The Graph Algorithms Course

Pre-Requisite

- Basic Programming (we will code in C++)
- Basic - Intermediate Recursion
- Arrays, HM, LL, Trees

Outcome Expectation

- Course will be starting from very basics but we will cover adv CP topics
- Beneficial with Interview perspective too.

(21 classes)

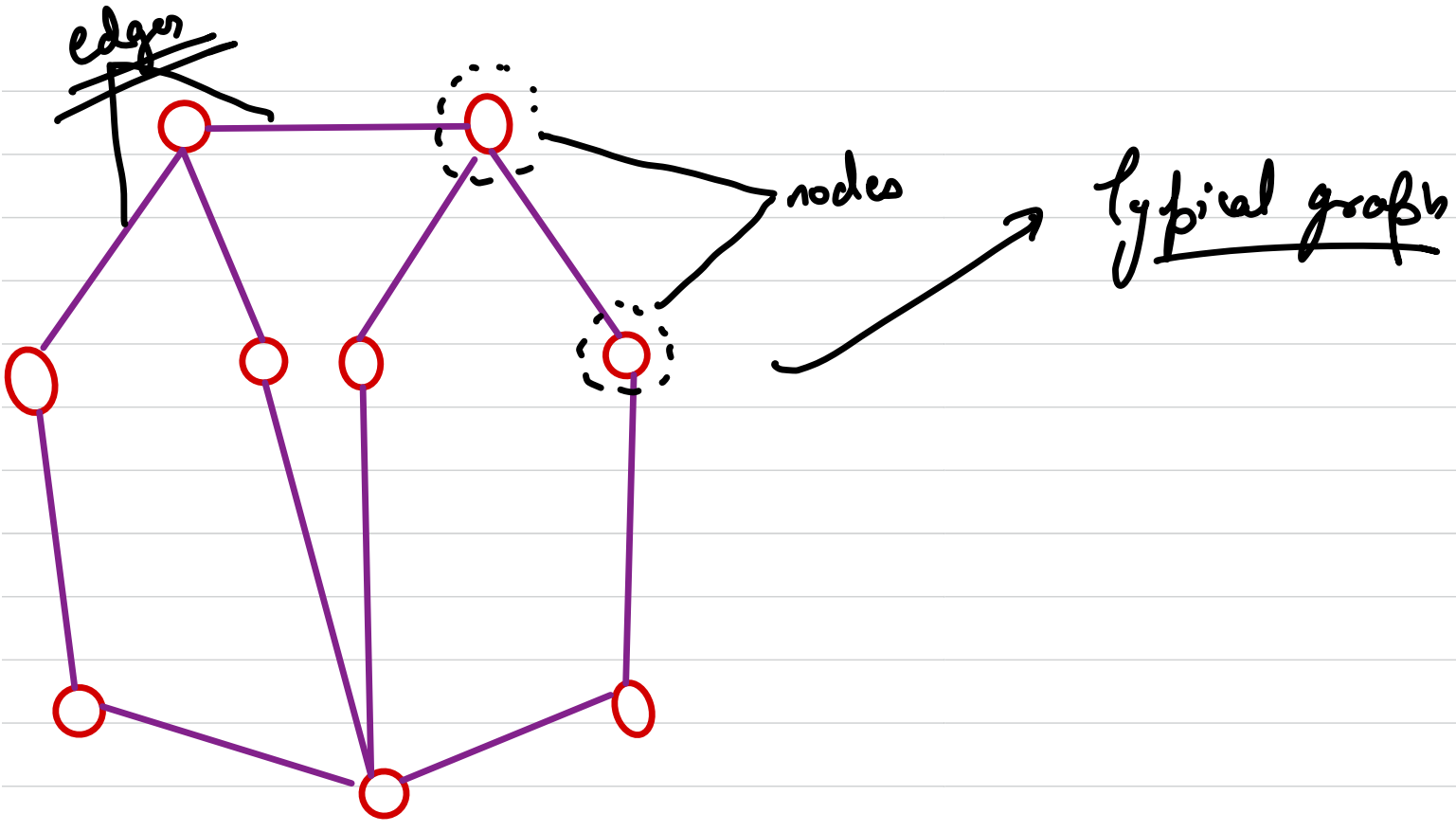
Topics

- Basic graphs & terminologies
- Traversal techniques BFS / DFS
- DP on graph (DP on DAGs)
- Matrix BFS / DFS , 0-1 BFS dc
- Trees (n-ary) , DP on trees
- Shortest path, MST
- DSU
- SCC , Bridges / articulation point

Graphs

Q⇒ What is a graph ??

Graph is a collection of nodes and edges where each node might point to / connected to other nodes. The nodes represent real life entities and are connected by edges representing relationship between the nodes.


edges
nodes
typical graph

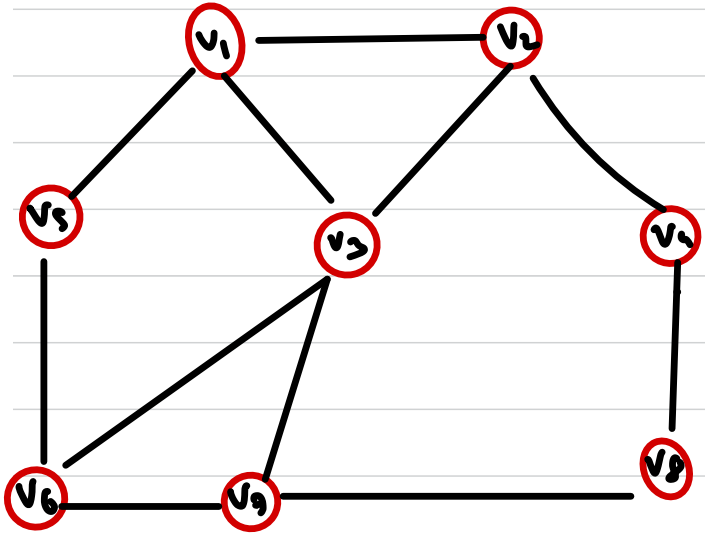
#Applications of graph

Biology → PPI graph
→ Metabolic network graph

Electrical → Circuit org graph

Computer Scene → Shortest path (ncp)
→ gsm frequency assignment
→ Routing mechanism
→ social media

formal definition of graph



V → set of vertices

$V = \{ v_1, v_2, v_3, \ldots\ldots, v_n \}$

Edge set

$E = \{ \{v_1, v_2\}$
$\{v_2, v_3\}$ → unordered set
$\vdots$
$\}$

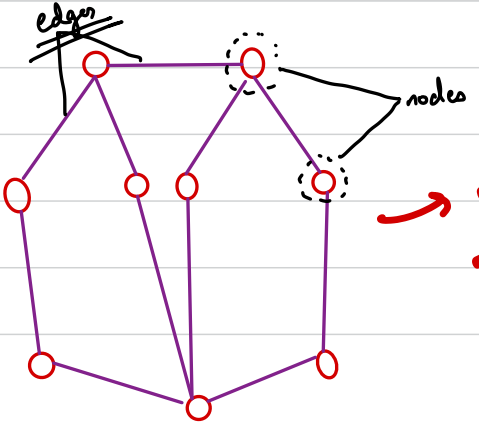
$G = (V, E)$ → mathematical notation of graph

A graph G is an ordered/unordered pair of a set V vertices & E, edges.

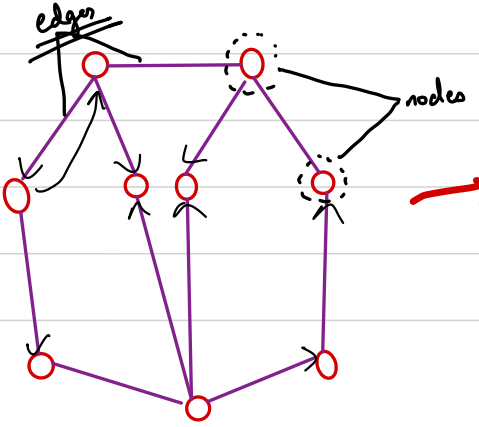
Types of graph

Based On direction

→ Directed → water flow, road network,
→ Undirected → facebook



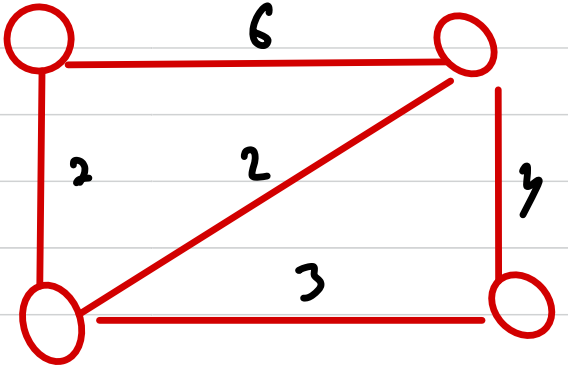
→ undirected



→ directed

Based on edge property

1. Weighted
2. Unweighted



Based on edge density

1) Sparse

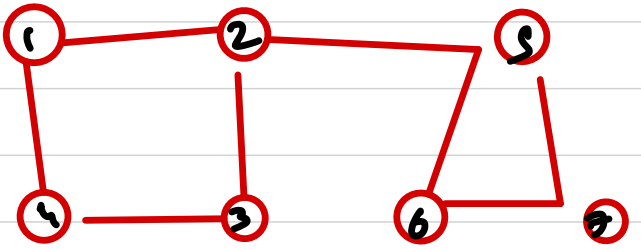
2) Dense

Representing graphs as a data structure

1) Adjacency Matrix
2) Adjacency List → adjacency set/map
   → edge list
3) Incidence Matrix

adjacency matrix

$A_{ij} = \begin{cases} 1 \rightarrow \text{if there is an edge from } i \text{ to } j \\ 0 \rightarrow \text{else} \end{cases}$



$A =$

	1	2	3	4	5	6	7
1	0	1	0	1	0	0	0
2	1	0	1	0	1	0	0
3	0	1	0	1	0	0	0
4	1	0	1	0	1	0	1
5	0	1	0	1	0	1	1
6	0	0	0	0	1	0	1
7	0	0	0	0	1	1	0

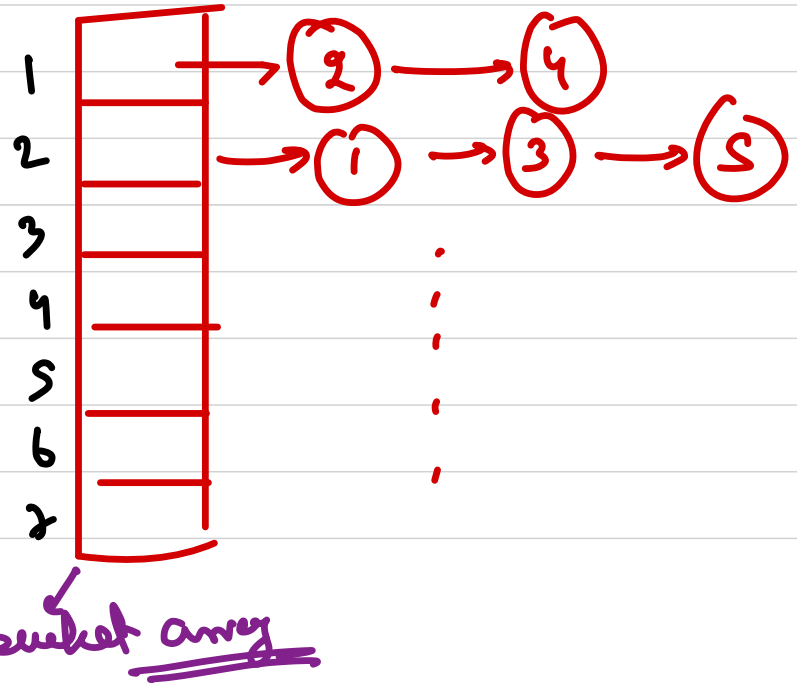
$\rightarrow O(V^2)$

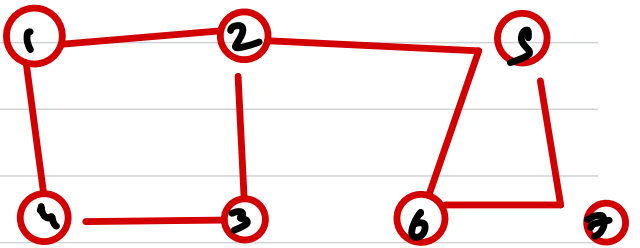
$N \times N$

adjacency List

{v, w}

Array of LL





O (V + E) → space

adjacency map/set

array of hashmap

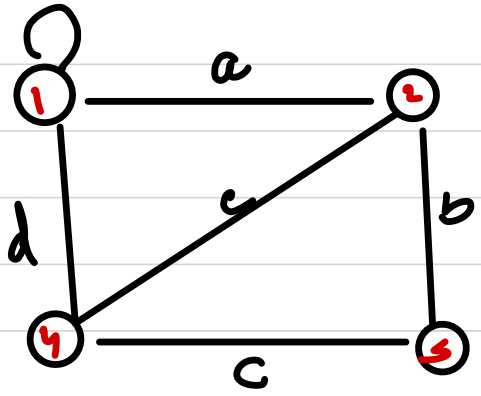
Incidence Matrix

Smia

M=

a	b	c	d	e	
1	0	0	1	0	1
1	1	0	0	1	2
0	1	1	0	0	3
0	0	1	1	1	4

(V*E)



col → edges
rows → vertex

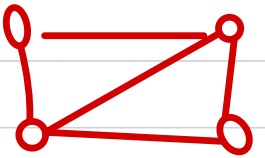
$$M_{ij} = \begin{cases} 1 & \text{if the } i^{th} \text{ vertex belongs to the } j^{th} \text{ edge} \\ 0 & \text{else} \end{cases}$$

col sum → 2

row sum → degree

Q. What is a degree ??

Degree of a vertex in a graph G, is the total no. of edges incident / associated with it.



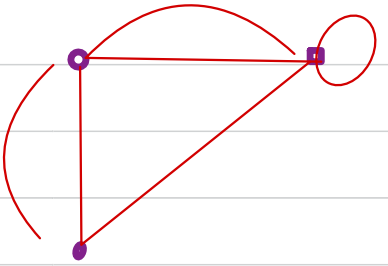
directed graph → indegree / outdegree

outdegree → no. of outgoing edges

indegree → no. of incoming edges

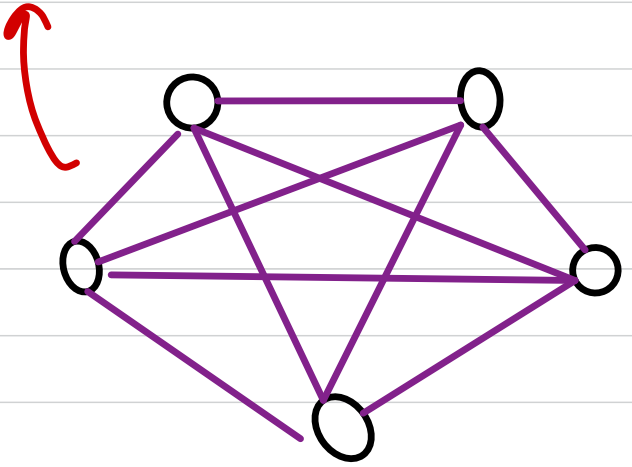
Multi graph → an undirected graph with multiple edges b/w two vertices & self loops allowed.

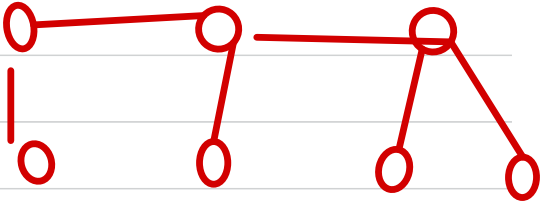
Multi graph



Simple graph → An undirected graph in which both multiple edges & loops are not allowed.

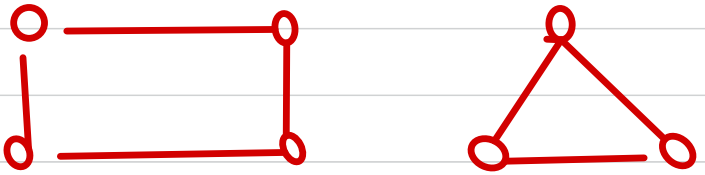
Complete graph → A graph in which every vertex is directly connected to every other vertex.





Connected graph → A graph in which there is some path between 2 vertices but not necessarily direct

Disconnected graph → atleast 2 vertices do not have a path to every other vertex.



Component → a subset of a disconnected/connected graph which is connected.

#path → A path P_n is a graph whose vertices can be arranged in some sequence such that

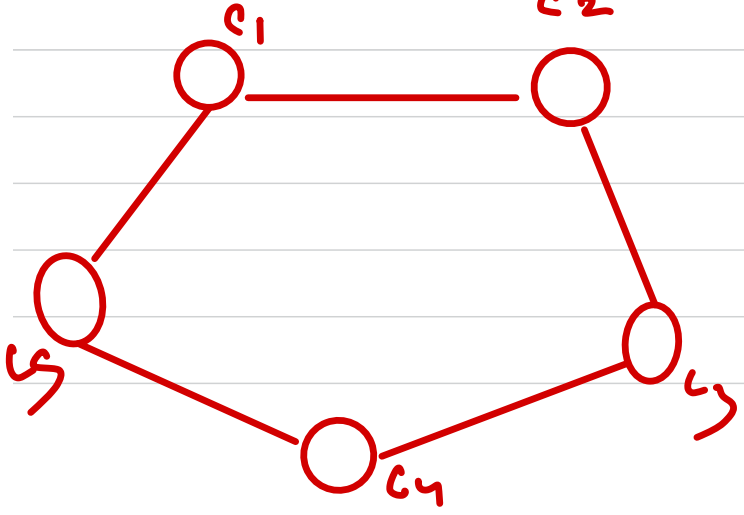
$V = \{v_1, v_2, v_3, v_4\}$

edge set of the graph is

$$E = \{ v_i v_{i+1} \quad \forall \; i \in [1, n-1] \}$$

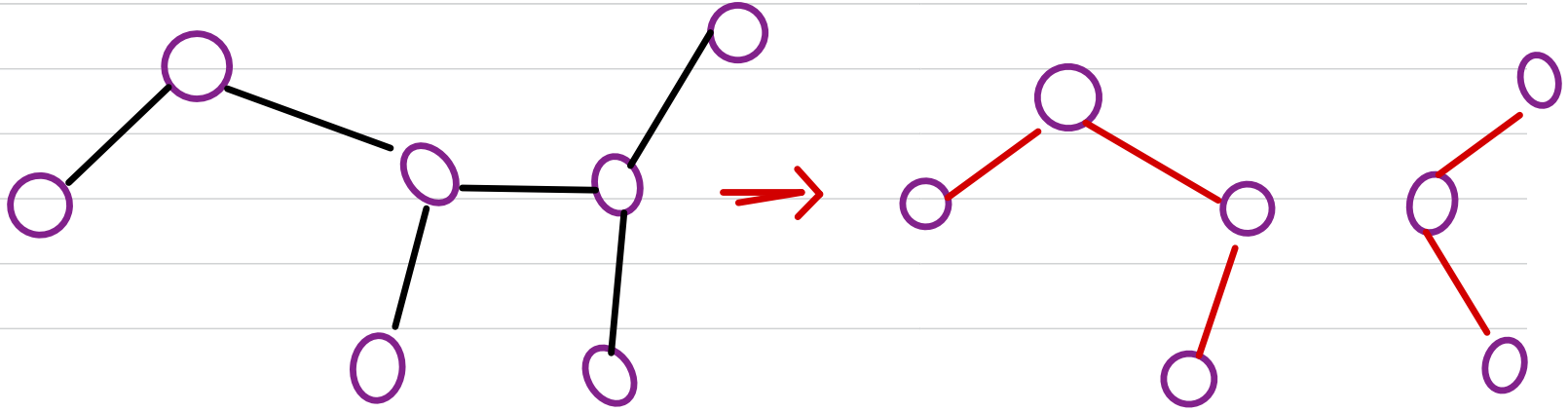
Cycle → A cycle C_n is a graph whose vertices can be arranged in a cyclic sequence. such that edge set is

$$E = \{v_i v_{i+1} \ \forall \ i \in [1, n-1]\} \cup \{v_1 v_n\}$$

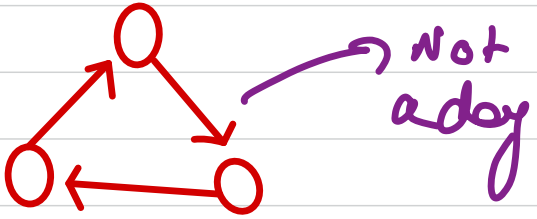


TREE → Tree is a connected graph with no cycles

forest → If we remove an edge from tree we get a forest which is collection of trees



DAGs (directed acyclic graphs) →



How to read graphs

As graphs are non-linear, we need some mechanism to read graphs.

Graph traversal

→ Depth first

→ Breadth first

Depth first search

TC
2
$O(V+E)$

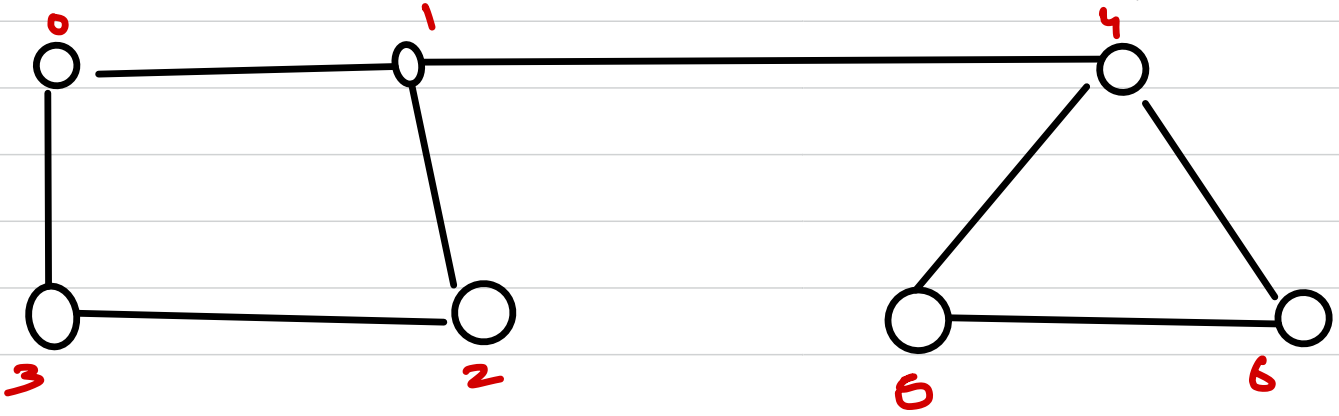
★ Motivation problem:

Q. Given a graph calc all paths between two vertices

OR

Q. Given a graph check whether there is a path between 2 vertices.

Last in → stack



is there a path from 0-5

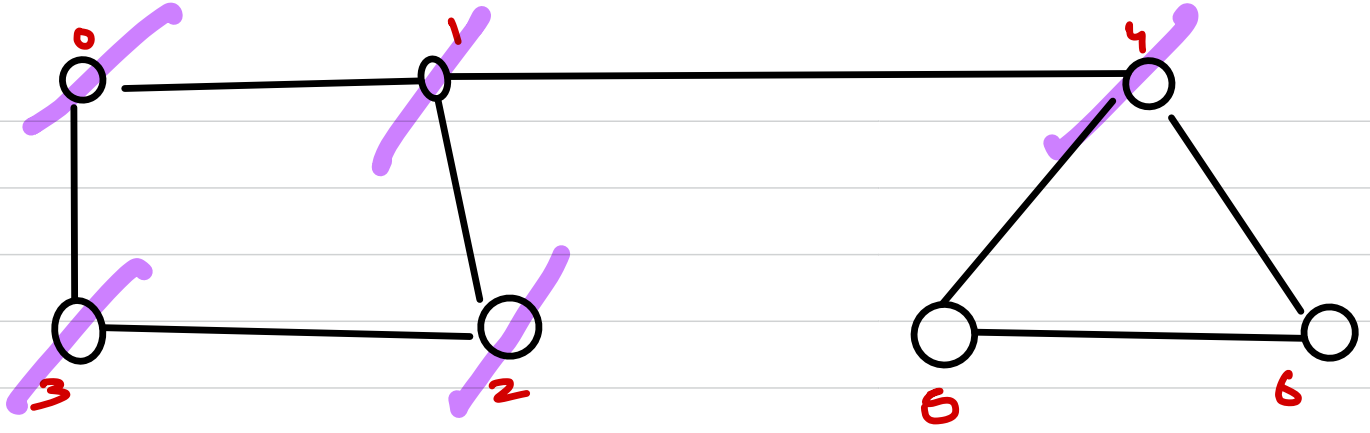
What is the most easiest query for this ??

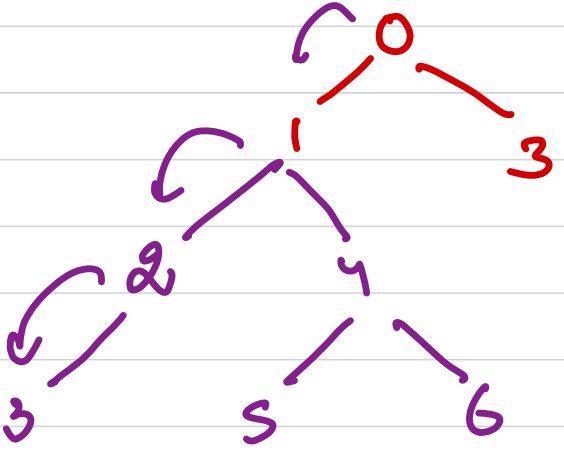
→ neighbours

$f(u,v)$ = whether there is a path from u to v.

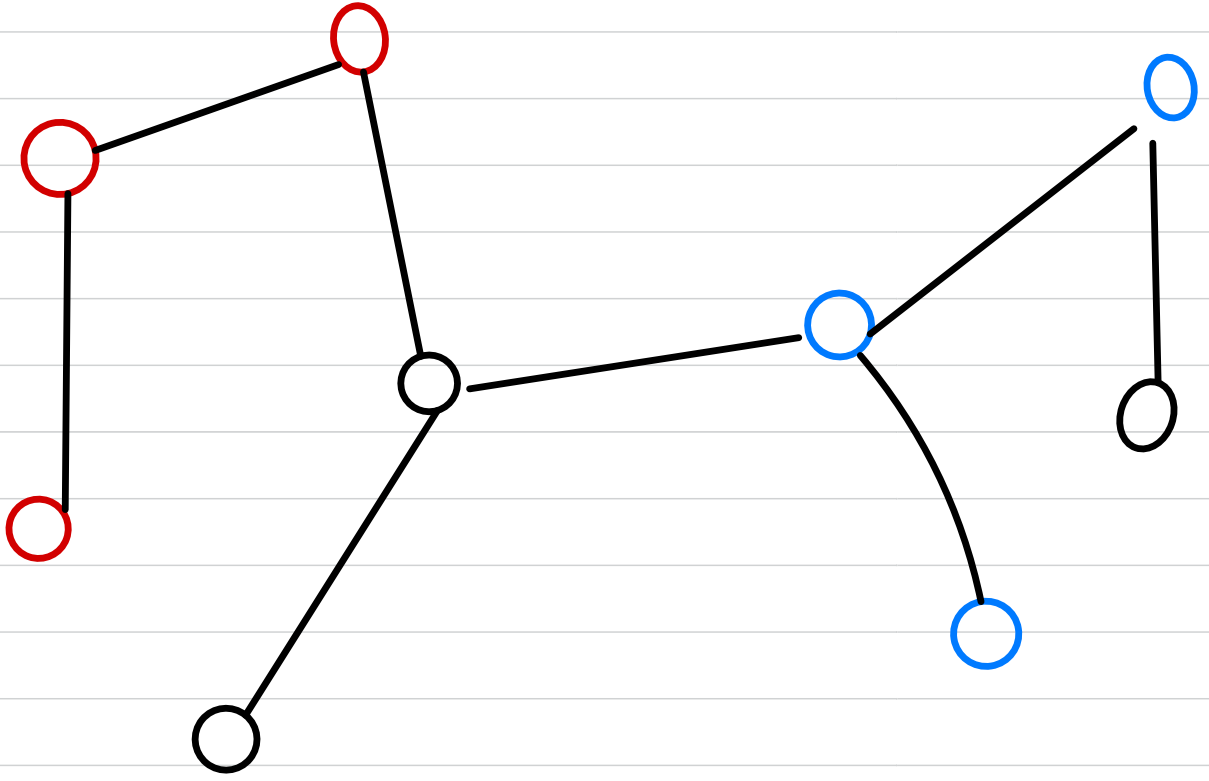
$$f(u,v) = \begin{cases} f(n_1, v) \\ \text{or} \\ f(n_2, v) \\ \text{or} \\ f(n_3, v) \\ \vdots \end{cases}$$

where $(n_1\ n_2\ n_3 \dots) \in$ neighbours of u.


0
1
4
3
2
6
6


0
1
3
2
4
3
5
6

→ total red
total blue]



Proof that a tree with n nodes has n-1 edges.

PMI → $f(n)$ → no. of edges for n nodes

$f(1) \rightarrow 0$

$f(2) \rightarrow 1$

To proove → $f(n+1)$

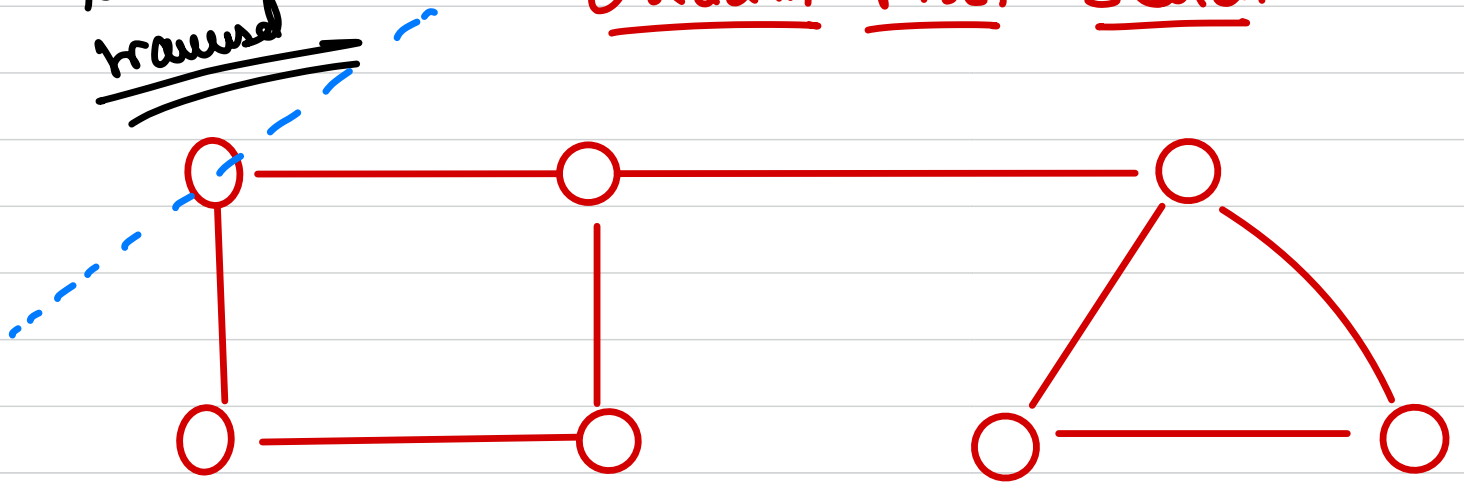
we assume function works for $f(n) \rightarrow n-1$

Total no. of edges → no. of edges required for $(n+1)^{th}$ node
+ $(n-1)$ edges

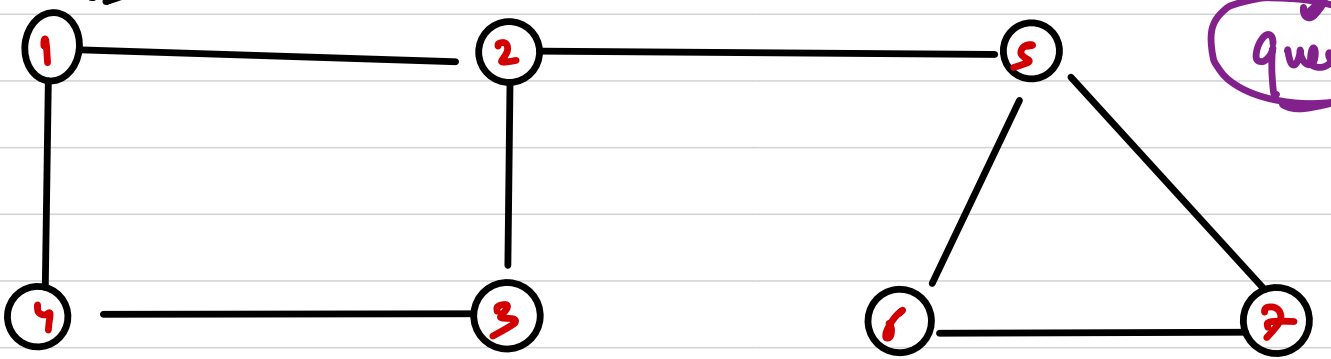
Every node that will be added to a tree requires only 1 node.

$f(n+1) = (n-1) + 1 \Rightarrow n$ H.P

Breadth First Search



Say we have an arbitrary src node then all the nodes with same shortest (by edges) distance from src node are said to be on the same level.



first in first out

queue

1, 2, 4, 3, 5, 6, 7 → Breadth first traversal

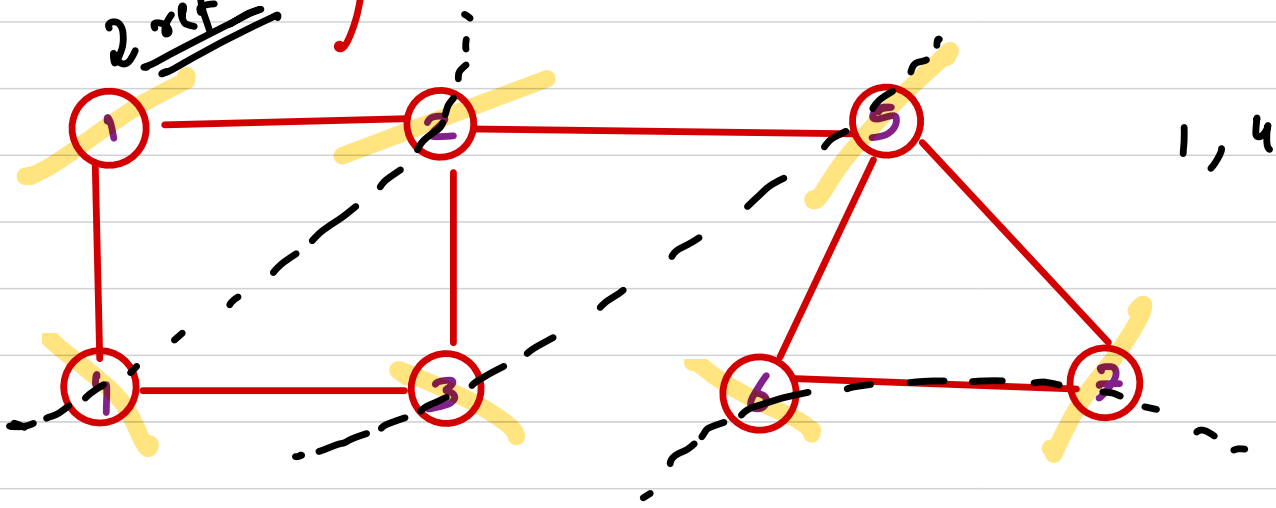
→ queue

Breadth First Search

FCFS

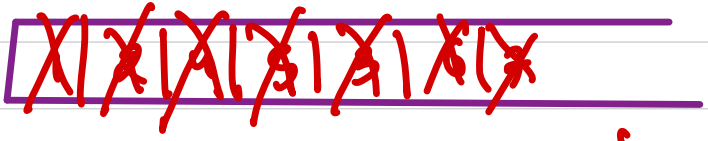
unvisited

2 ref



1, 4, 2, 3, 5, 6, 7

1, 2, 4, 5, 3, 6, 7



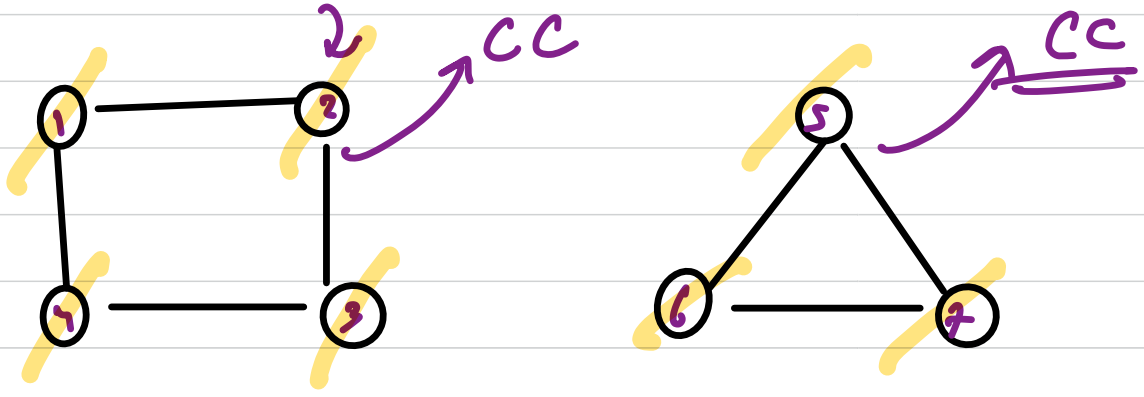
↳ queue

Time → O(V+E)

Space → O(V)

So in breadth first search, whenever we travel from src node → any node then it always considers shortest path.

Connected Components → DFS / BFS



Disconnected graph

vis = [ ]

Iterate on all possible vertices

```
for (i = 1; i <= n; i++)
    if (not vis[i])
        DFS(i)
```

So the no. of times we will call dfs will be the count of CC.

Journey to the moon

pair of astronaut id $< a_1, a_2 >$ then a_1, a_2 are from same country

Choose → 2

Say, total no. of ast = n

$nC_2 \rightarrow \frac{n!}{2!(n-2)!} \Rightarrow \frac{n(n-1)}{2}$

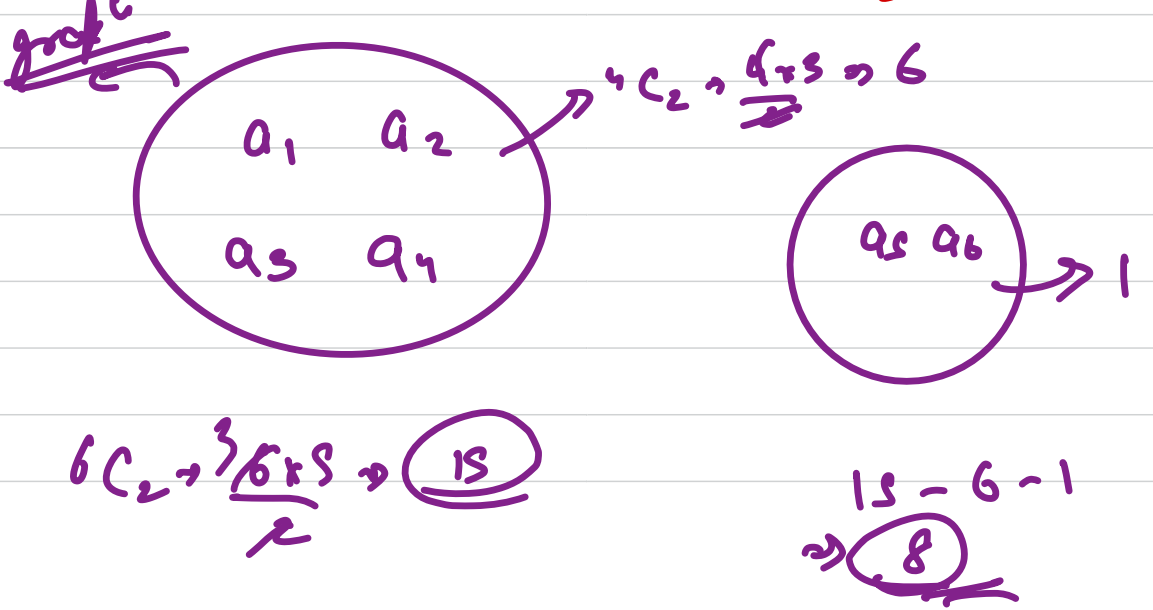
2 2

$\langle a_1\ a_2 \rangle$

$\langle a_2\ a_3 \rangle$

$\langle a_3\ a_4 \rangle$

$\langle a_5\ a_6 \rangle$

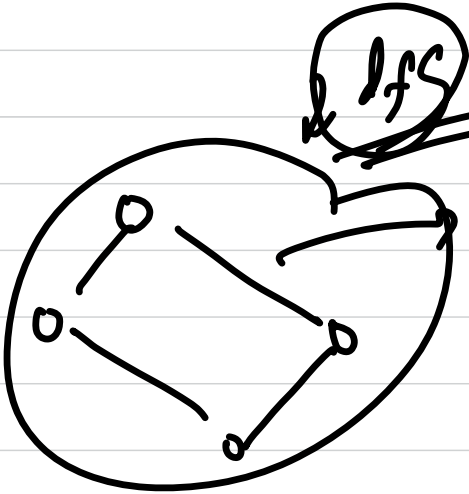


Permutation Swaps

id	1	2	3
A →	1	3	2
B →	1	4	2 3

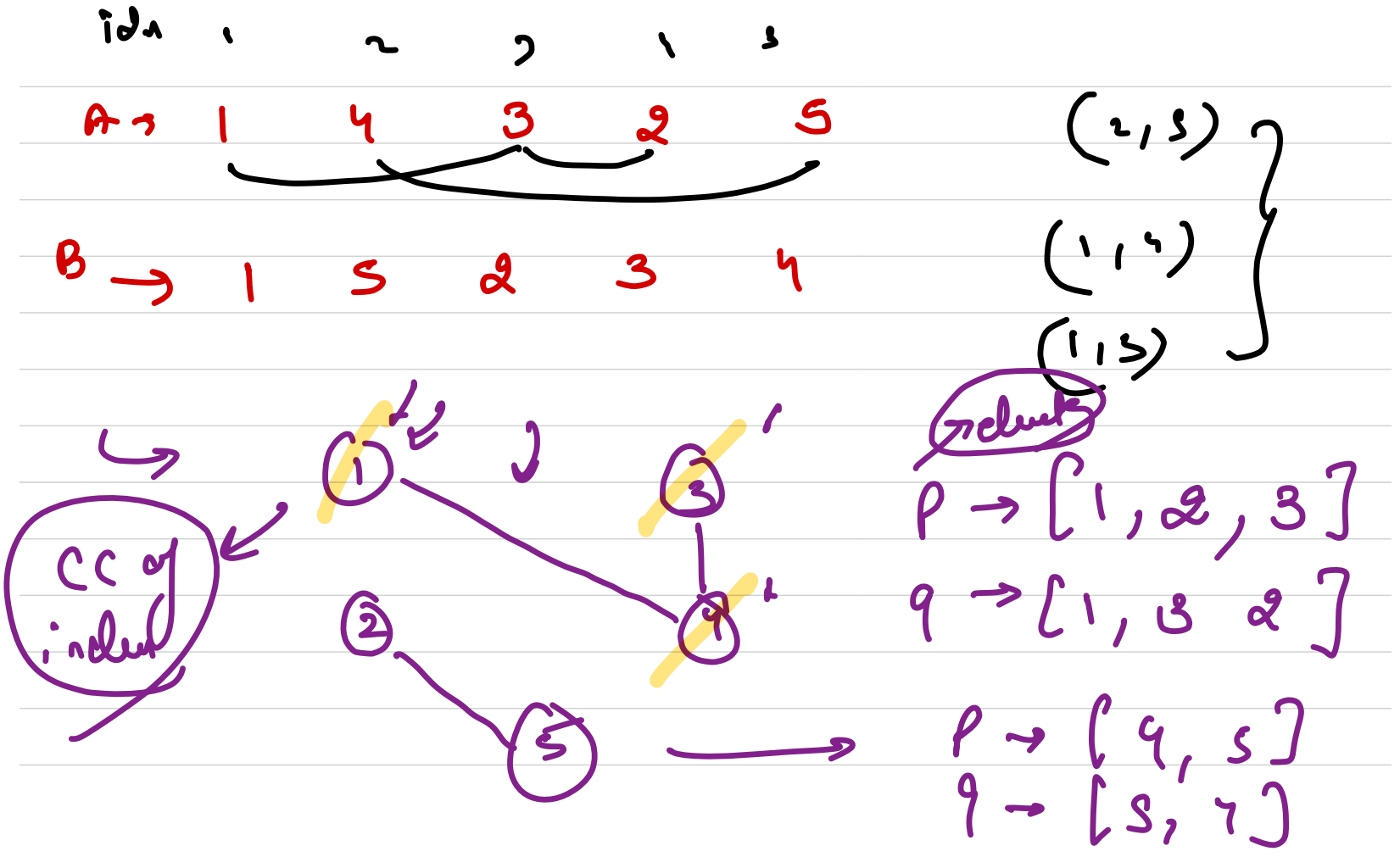
[11, 21, 31]
1 2 3

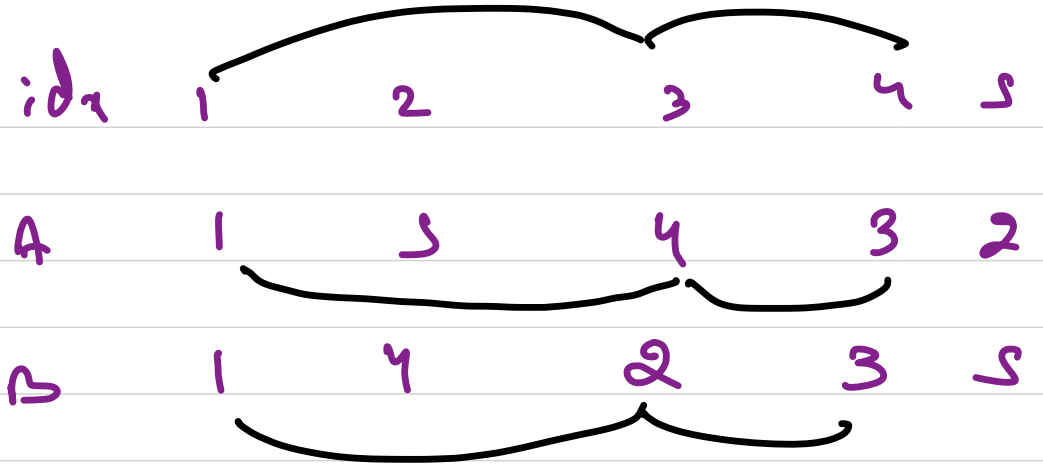
1, 2
2, 3



(3, 4) ← index

Those indexes are in the same connected component

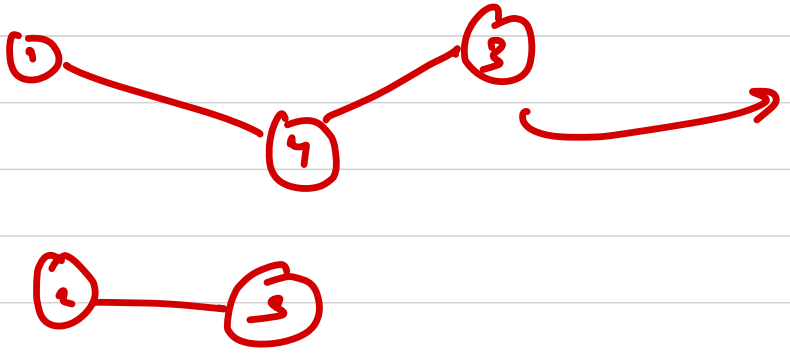

idx 1 2 3 4 5
A → 1 4 3 2 5
B → 1 5 2 3 4
(2,5)
(1,4)
(1,5)
redundant
CC of redundant
1
3
4
2
5
P → [1, 2, 3]
q → [1, 3 2]
P → [4, 5]
q → [5, 4]



(2, 5)

(3, 4)

(1, 4)

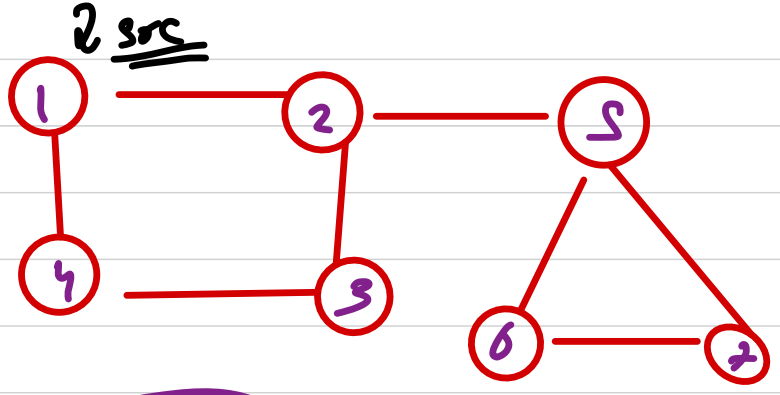


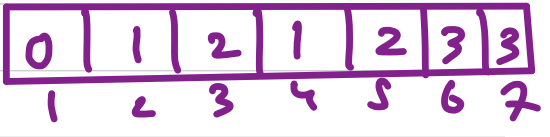
P → [1, 3, 4]

Q → [1, 2, 3]

unweighted undirected

Q⇒ Given an graph, and a source node calc the length of the shortest path to all the other nodes from the source node.





output

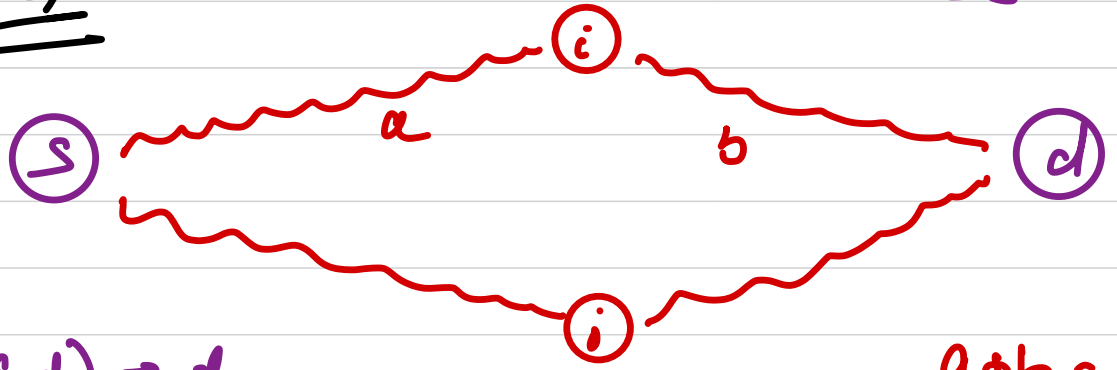
src=1

Bfs

Bfs traverse the nodes based on Shortest path

Q: Given a graph, a src and a destination, find all the nodes which are a part of atleast 1 shortest path.

$O(V+E)$



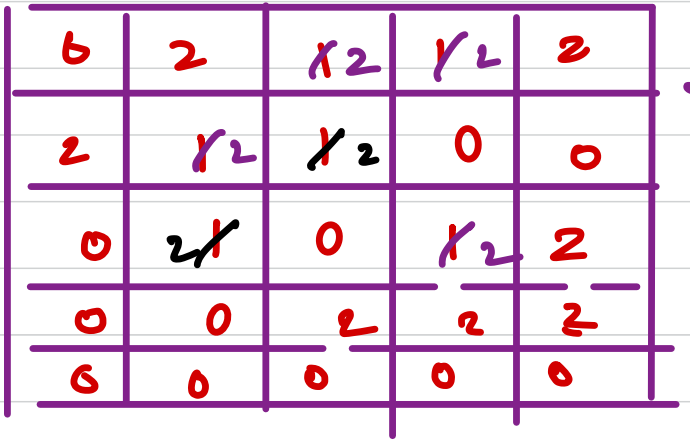
$s[i] + d[i] == x$

dist → (s, d) → x

$a + b = x$

$b = x - a$

Rotten Oranges

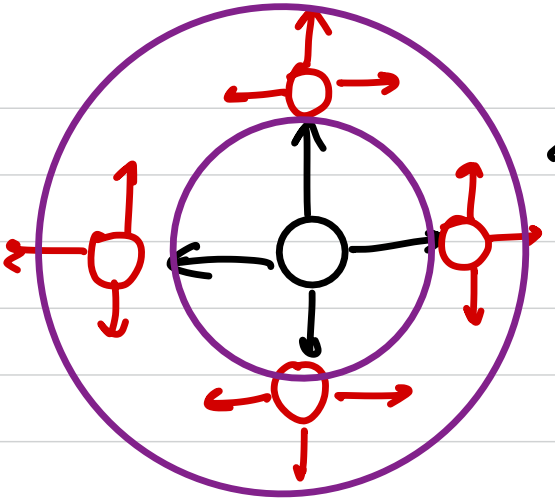


2D array

mxn

-1 → when no other oranges can not a orange

$t = t'$ → all oranges which are rotten until after their neighbours at same time



BFS

queue

vis

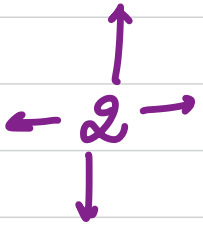
(i, j)

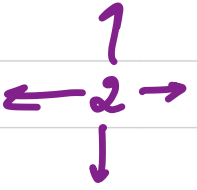
(i+1, j) | (i-1, j) | (i, j-1) | (i, j+1)

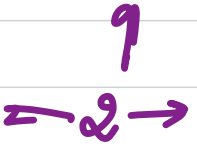
all this will be pushed if new is a fresh one

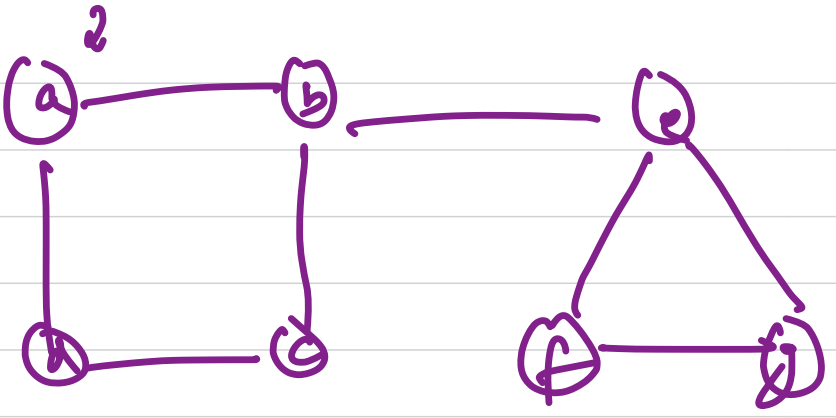
Multi source BFS

O(nm)


2

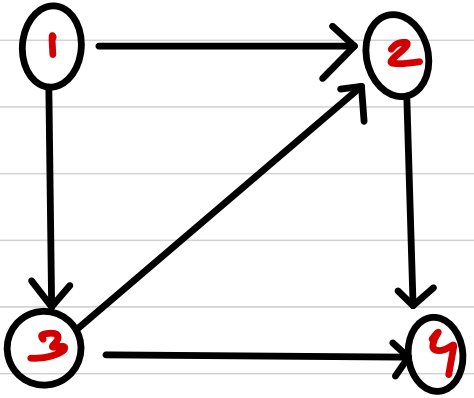

1
2


1
2


a
b
e
h
c
f
g

Longest Path

Dynamic Prog.



→ The longest directed path can start from any node.

IDK!

$f(v)$

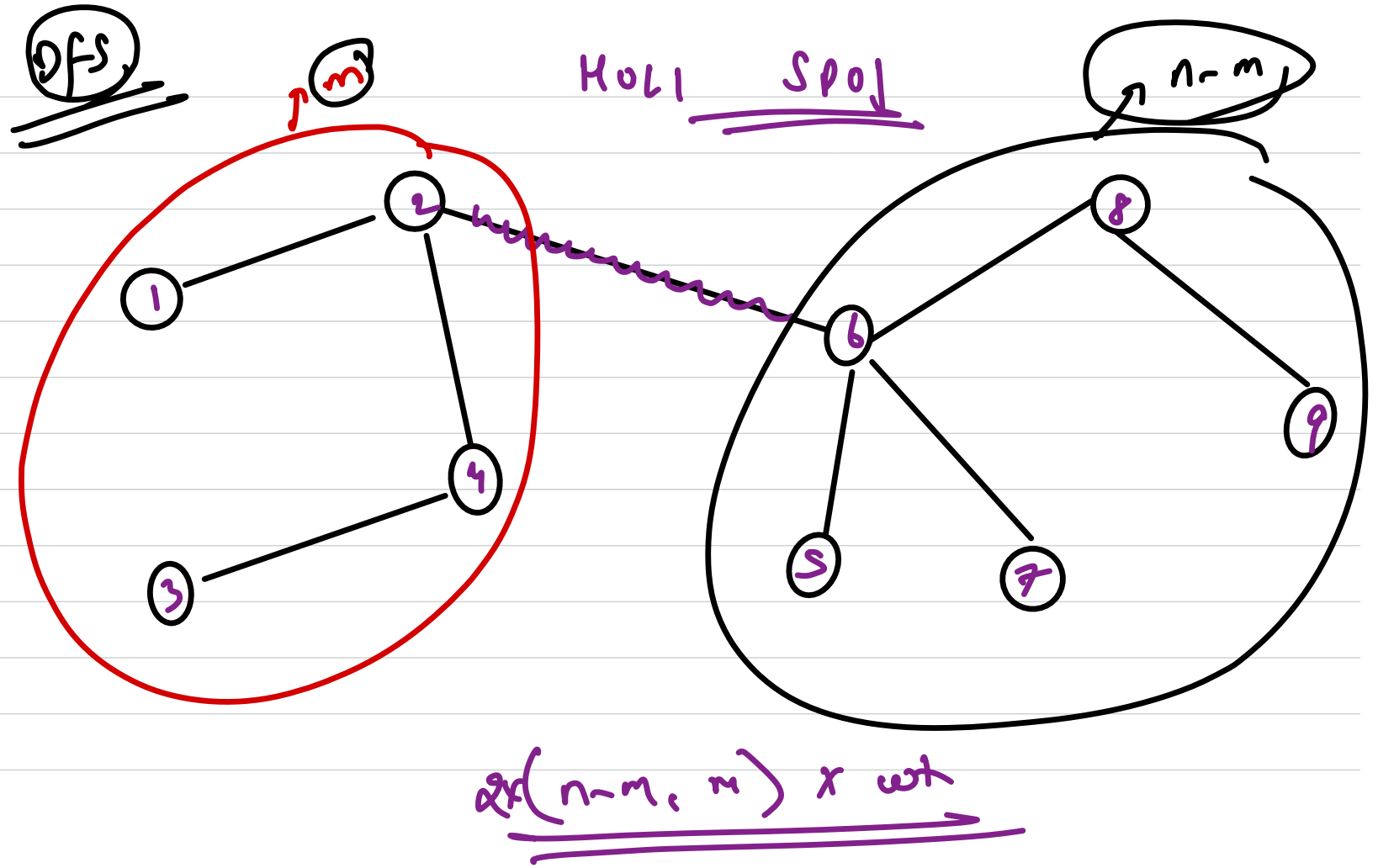
returns the length of the longest path that starts with v.

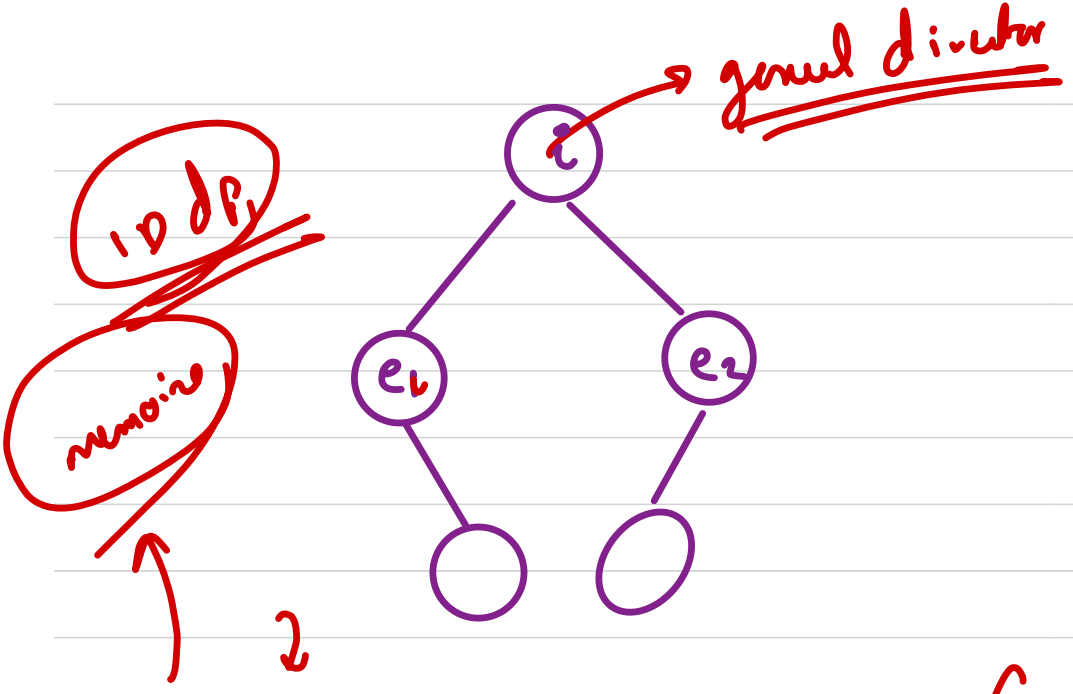
$1 + \max \begin{cases} f(n_1) \\ f(n_2) \\ f(n_3) \\ \vdots \\ f(n_m) \end{cases}$

Base → length → 0

where $n_1, n_2, n_3, \ldots, n_m$ are the neighbours of v.

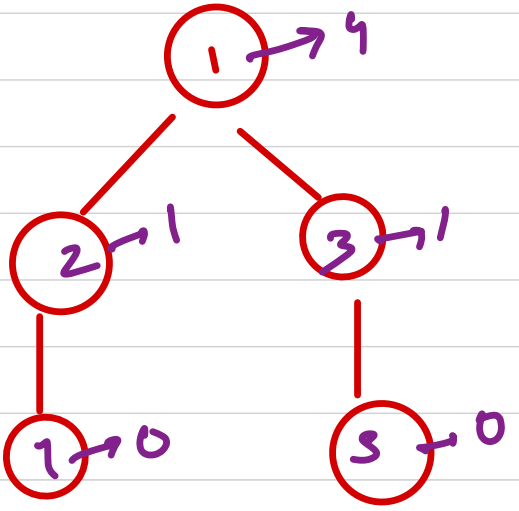
ans $\max(f(1), f(2), f(3) \ldots f(n))$

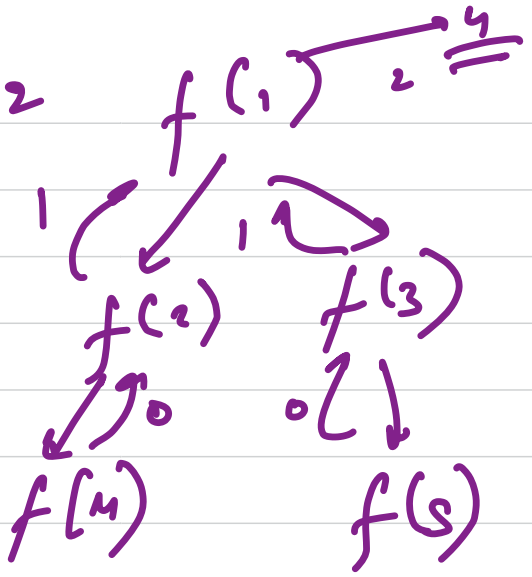

DFS
m
Holi Spot
n-m
1
2
3
4
5
6
7
8
9
2x(n-m, m) x wt



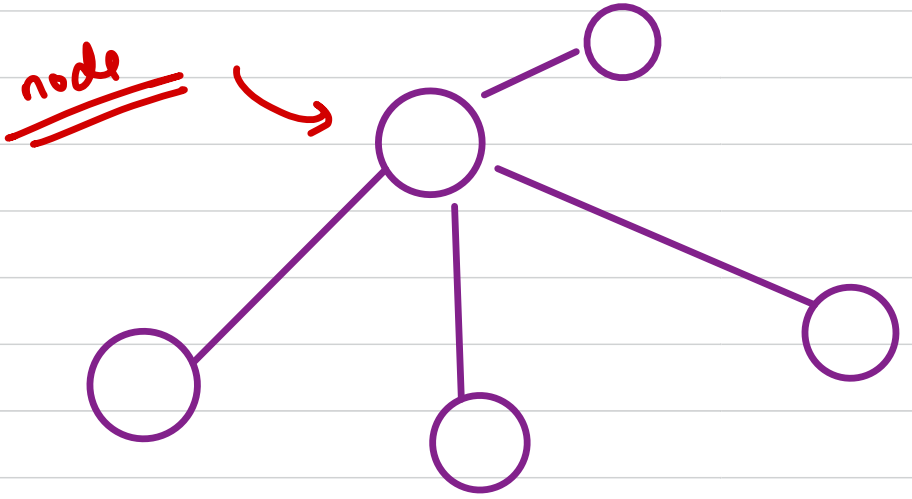
$f(i)$ = $\sum (1 + f(e_i))$

i : no. of subordinates under employee i


1
4
2
1
3
1
4
5
0
0


f(1)
4
2
2
1
1
f(2)
f(3)
0
0
f(4)
f(5)

Independent Set → Atcoder



color → B
W

Black → count
White → no count

No, two adjacent vertices should be Black

$f(node, c)$ → these two parameters can uniquely identify our state

c → constraint

$f(node, 0)$ → # of ways to color subtree rooted at node

as $c \to 0$ then node can be W or B

$f(node, 1)$ → # of ways to color subtree rooted at node and node is under constraint

$$\begin{cases} f(node, 0) = \pi f(child, 0) + \pi f(child, 1) \\ f(node, 1) = \pi f(child, 0) \end{cases}$$

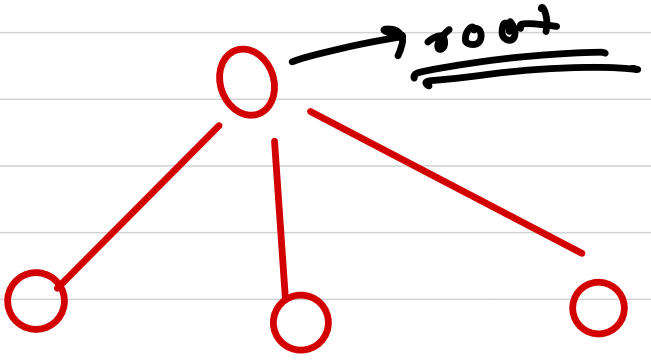
$\equiv$

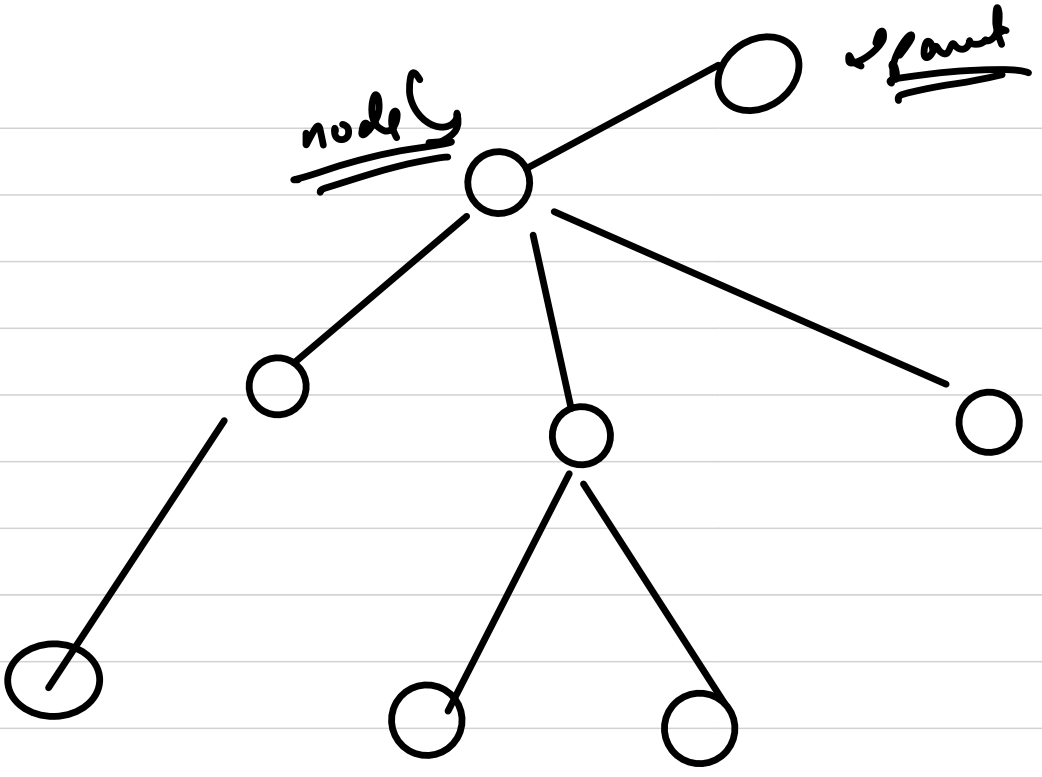
final ans $\rightarrow$ $f(root, 0)$

Leetcode

Binary Tree Cameras

Brute force




node
root

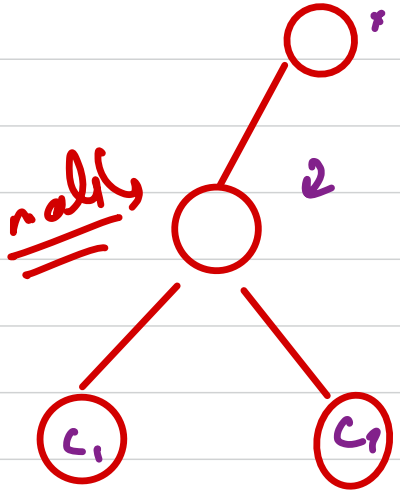
$f(node, cam, parcam)$

2

return the min number of cams to cover the subtree rooted at node.

final ans → $min(f(root, 1, 0), f(root, 0, 0))$

for current node, we decided whether a camera should be placed or not here

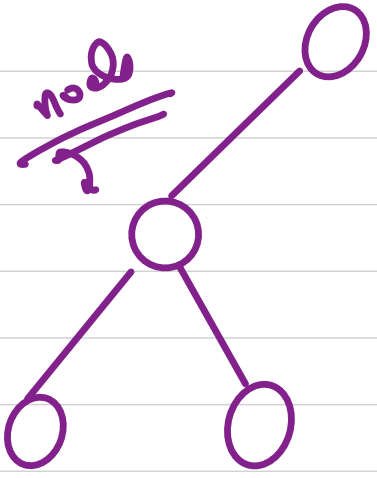


$f(node, 1, 0)$

for your cam

$$f(node, 1, 0) = 1 + \min(f(c_1, 1, 1), f(c_1, 0, 1)) + \min(f(c_2, 1, 1), f(c_2, 0, 1))$$

when node is not taken can but parent has it

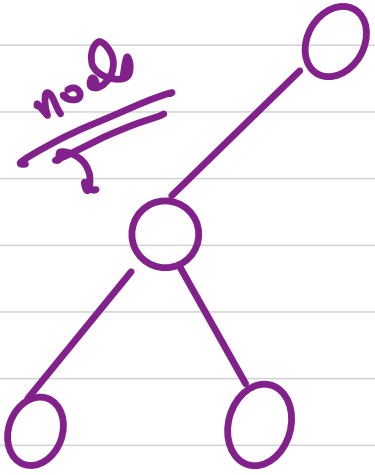


$f(node, 0, 1)$

$f(node, 0, 1) = \min(f(c_1, 0, 0), f(c_1, 1, 0)) +$

$\min(f(c_2, 0, 0), f(c_2, 1, 0)$

3D dp



$f(node, 0, 0)$

one of the children are bonded to node a car.

$f(node, 0, 0) =$ min

$f(c_1, 1, 0) + \min(f(c_2, 1, 0), f(c_2, 0, 0))$

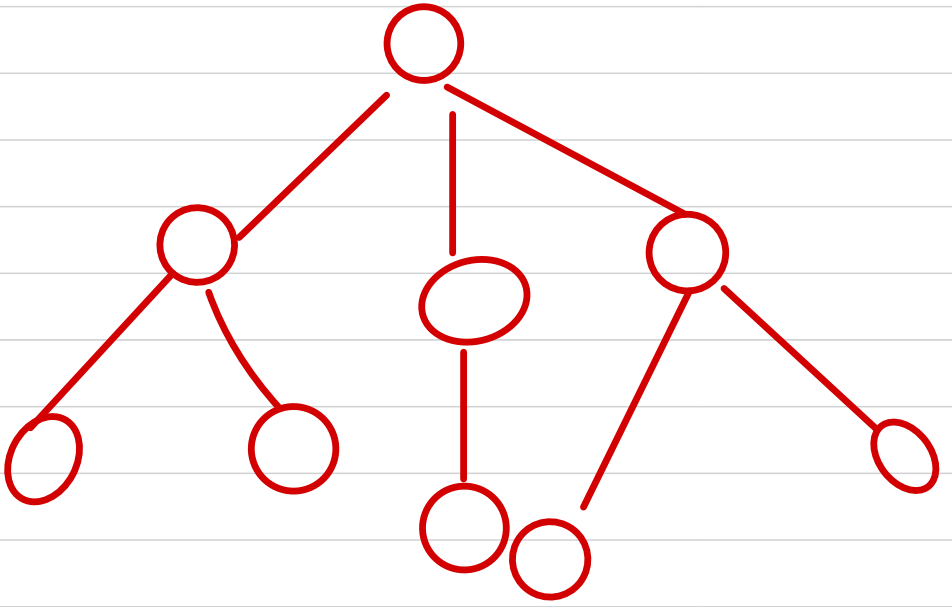
$f(c_2, 1, 0) + \min(f(c_1, 1, 0), f(c_1, 0, 0))$

gcd = $\frac{ab}{y}$

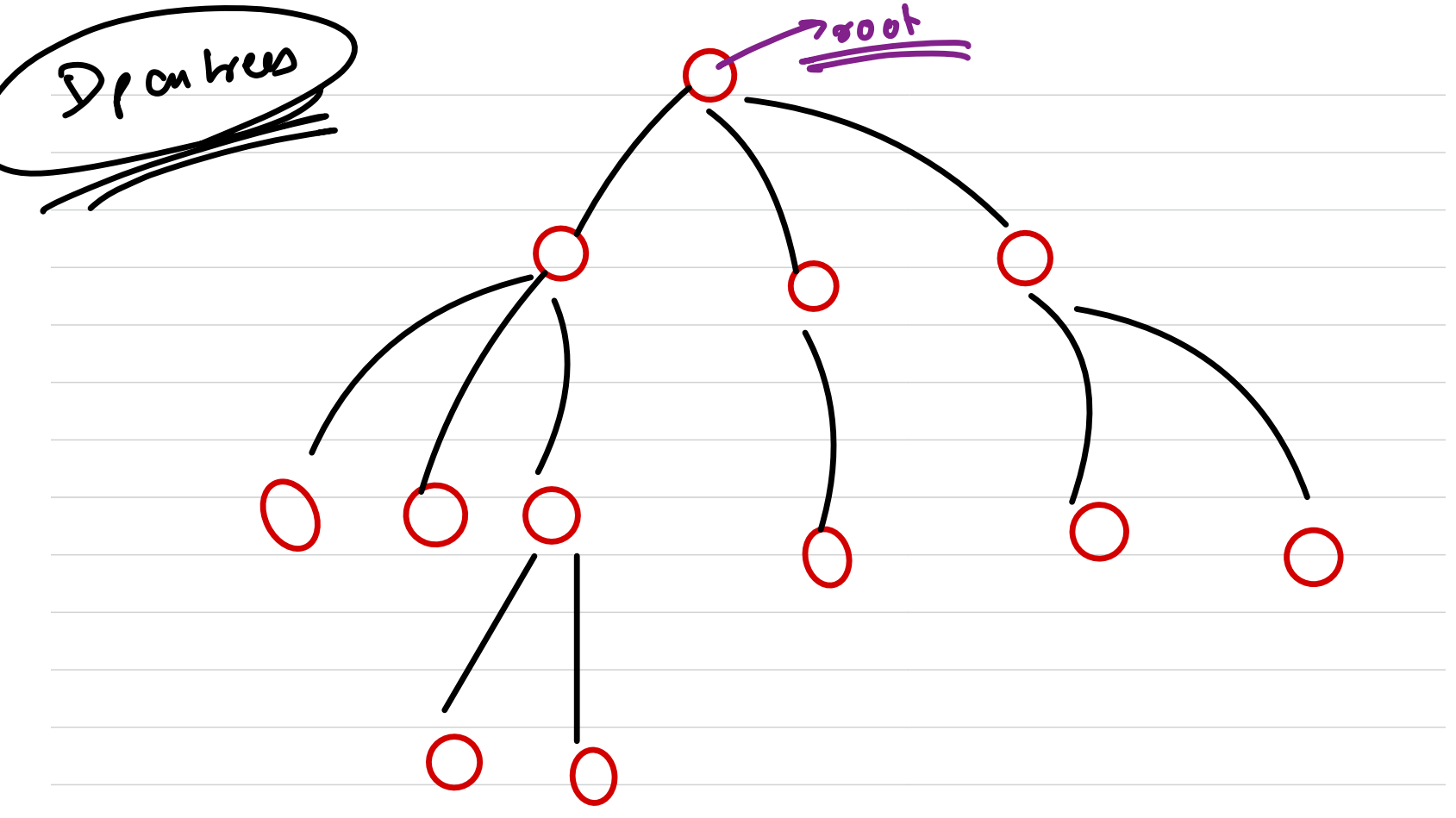
famtree (codechef)

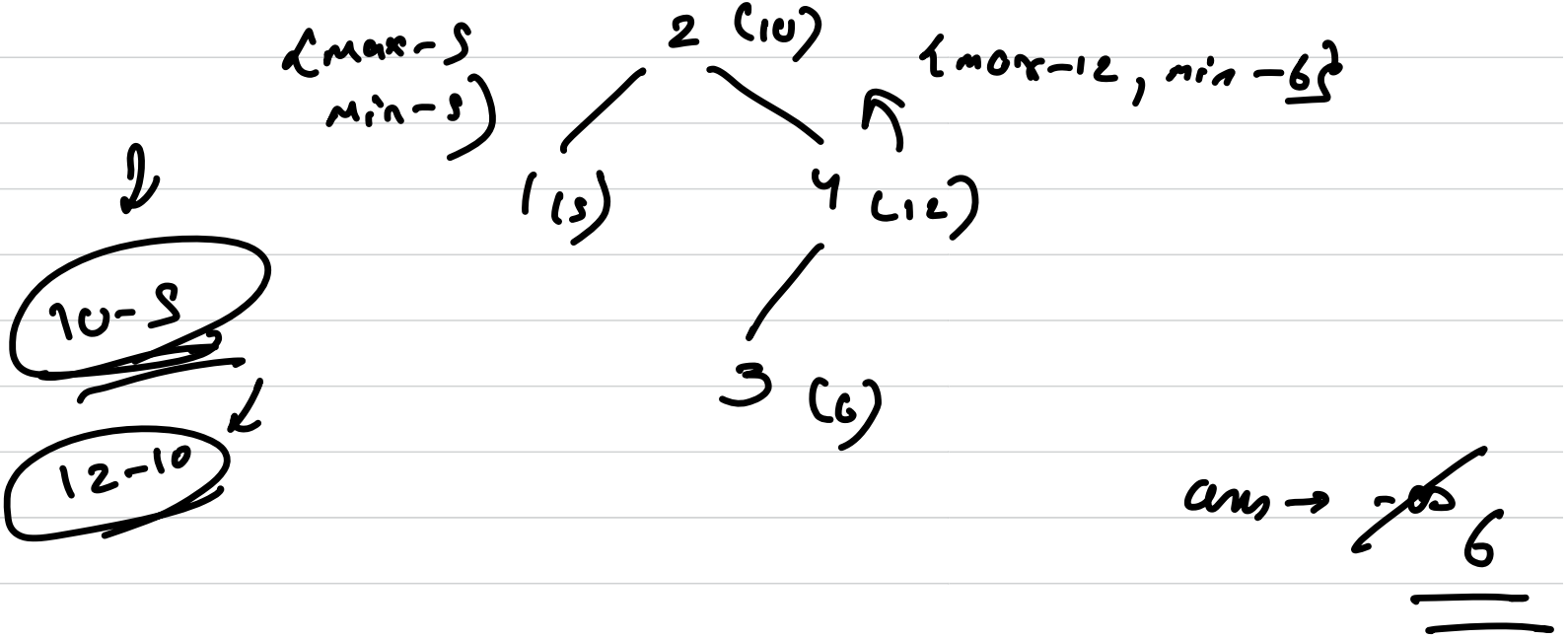
max

min



Dp on trees




{max-5
min-5}
2 (10)
{max-12, min-6}
1 (5)
4 (12)
3 (6)
10-5
12-10
ans → 6

#appleman and tree → codeforces

Divide this tree into arbitrary K components such that each component has exactly one black node.

$0 \le K < n$

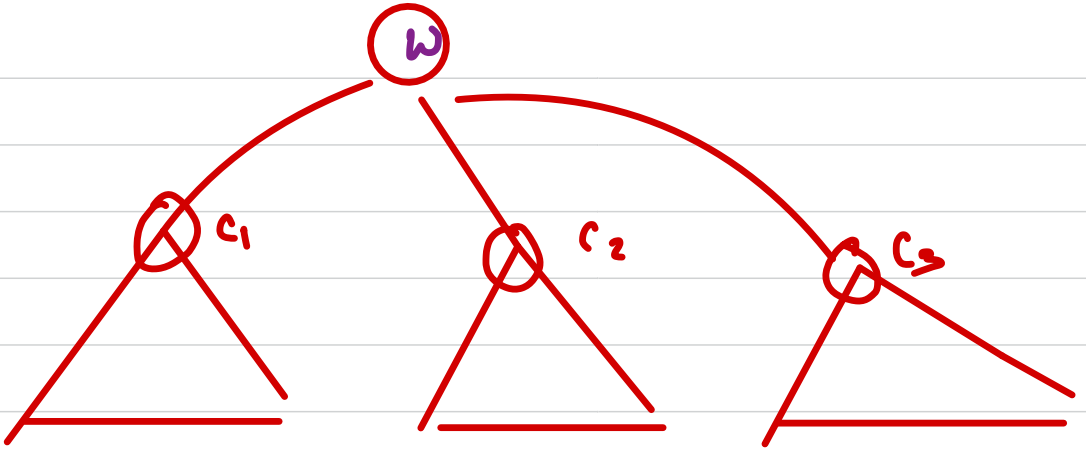
tree → $(n-1)$

every node will have different choices based on colors of node in subtree

$f(node, c)$ → count of black nodes

$f(node, 0)$ → # of ways subtree rooted at node has no black node vertex

$f(node, 1)$ → # of ways for subtree rooted at node & has 1 black vertex



block

$$f(node, 1) = \pi\left(f(c_1, 0) + f(c_1, 1)\right)$$

$$f(node, 0) = 0$$

$$f(node, 0) = \pi\left(f(c_1, 0) + f(c_1, 1)\right)$$

$$f(node, 1) = \Sigma f(c_1, 1) \times \frac{f(node, 0)}{f(c_1, 0) + f(c_1, 1)}$$

Q: You're given a set of inequalities.

Eg ($a<b$ $c>d$ $b<d$ .....)

You've to find that whether for any set of int values for the variables, can be solve the inequality.

Dependency Resolution

↳ $a < b$, $c > d$, $b < d$

↳ packages of a software

↳ Course Structure

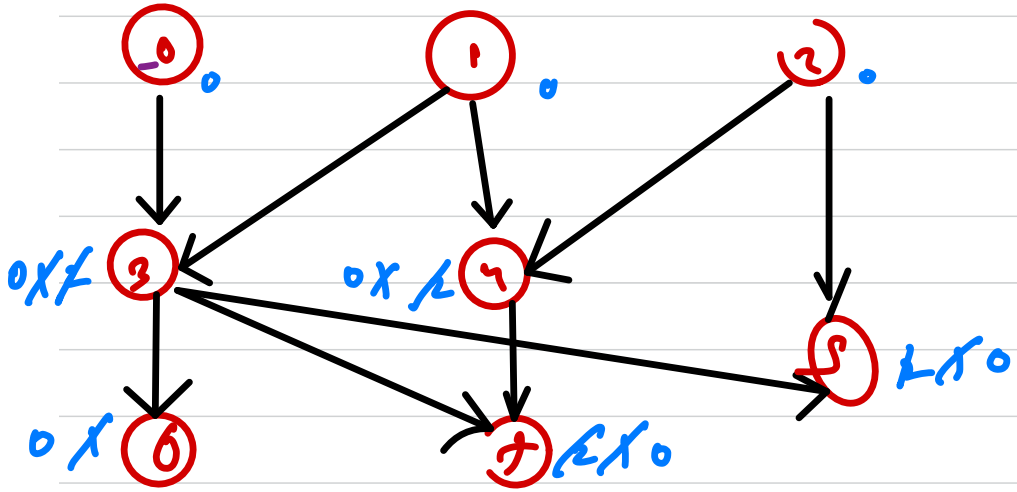
} can be visualized in the form of a graph.

↗ directed graphs

In order to resolve the dependency graph we can use an algorithm called as Topological Sorting

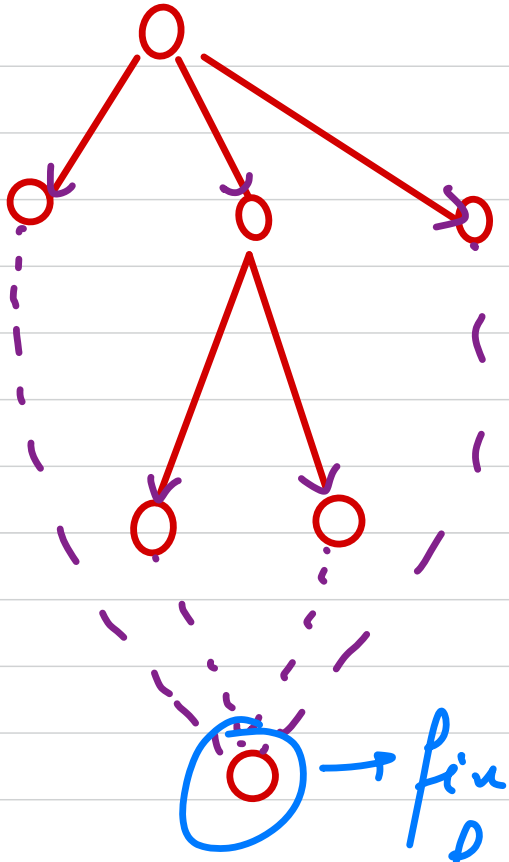
Kahn's algorithm → BFS based topological sort

queue



5, 7, 3, 11, 8, 2, 9, 10

0, 1, 2, 3, 4, 5, 6, 7



0, 1, 2, 3

→ find the value here i.e Node N. 0, 1, 2, 3

f (node, xor)

Q→ Given a grid with chars [L, R, U, D] on each cell of grid. You're standing at top left of the grid. From each cell you can go in the direction written on the cell for e.g L → Left. Detect if it is possible to reach the bottom right corner or not.

Dimension → $m \times n$

Expected Space → $O(1)$

$m, n \leq 10^3$

↳ There is only one case for not reaching the bottom right.

↳ if there exist a cycle-

cycle detection

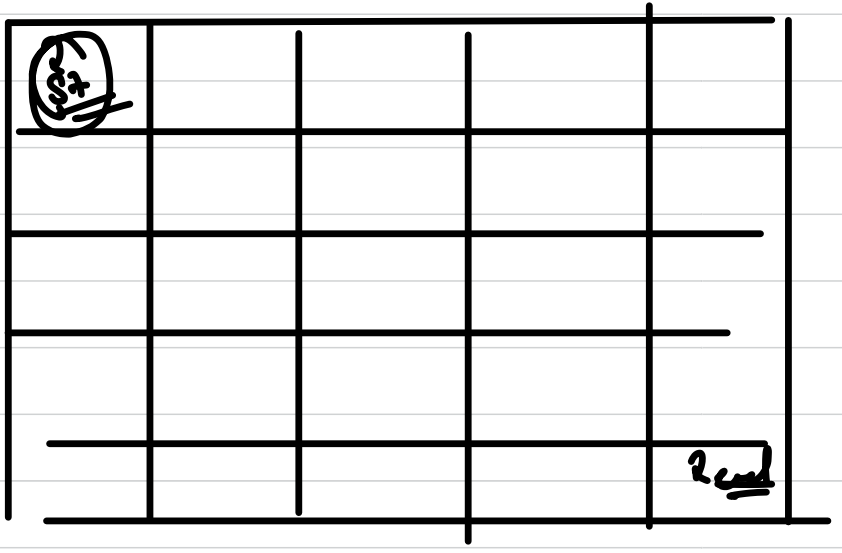
1 ⟶ 1x

2 ⟶ 2x

Say we can swap the character of the cell with any other char we need. Cost of changing char is 1 unit.

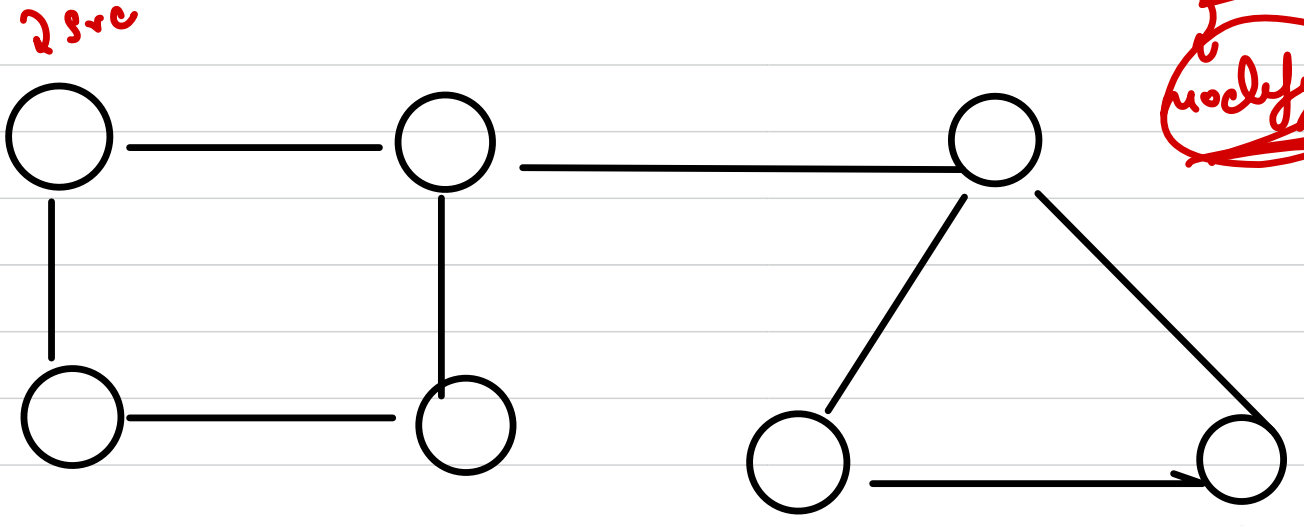
Calc the min cost to reach bottom right.

1 cent



On this weighted graph Calc the shortest path

Given a graph & a src and a dest cole the shortest path from src → dest

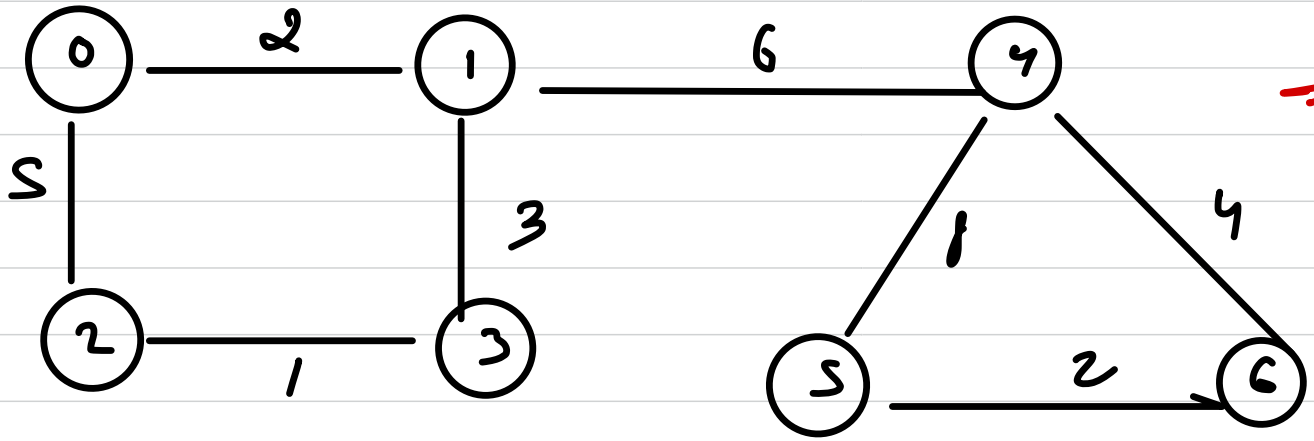


BFS

modify

Dijkstra's

Priority queue



Adj list

pq

node	parent	wt
0	-1	0
1	0	2
2	0	5
3	1	5
4	5	14
5	6	12
6		

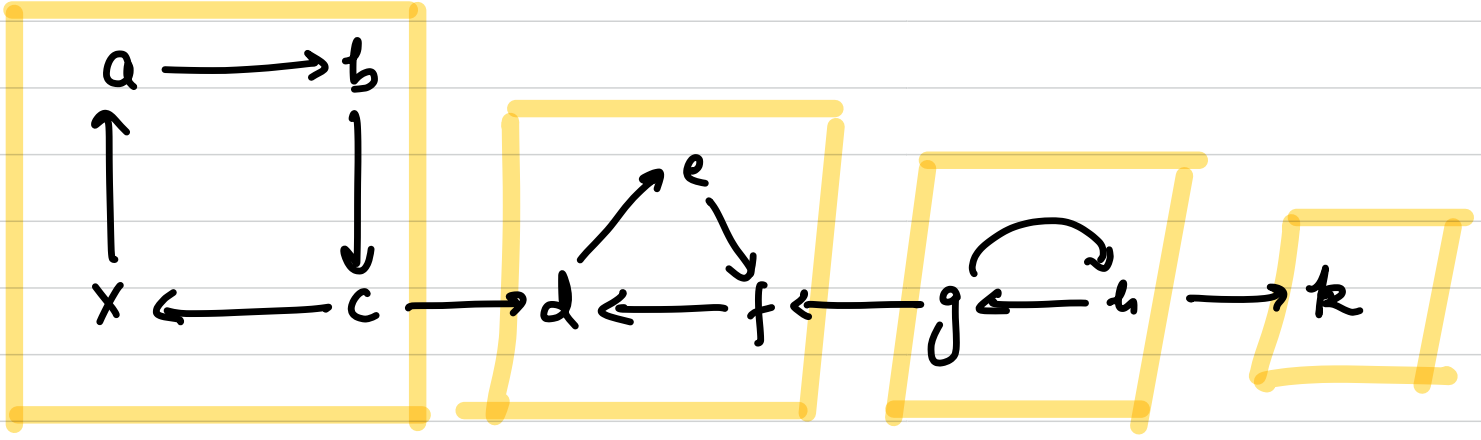
0	2	1	3	4	5	6

Strongly Connected Components

directed graph

We have a path from a to b but not vice-versa

Within a component in a SCC every vertex should have a path to other vertex in a directed graph



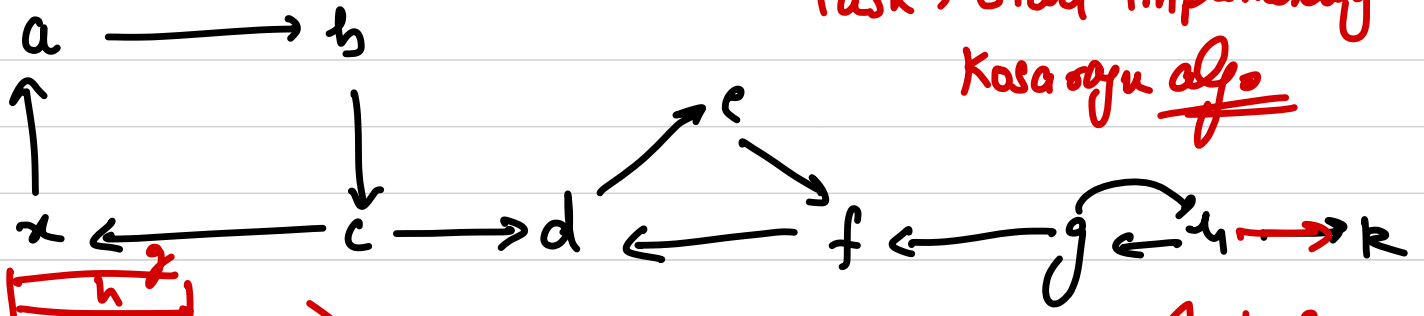
How can we find SCC??

for finding normal cc in an undirected graph, we used to take help of dfs / BFS

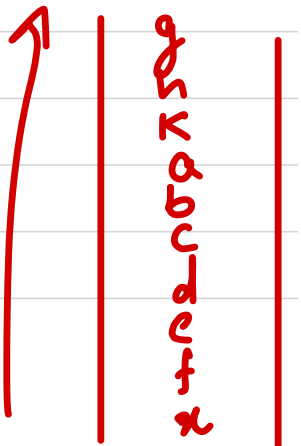
Kosaraju's Algorithm

Visited
a, b, c, x, d, e, f
g, h, k

Task → Start Implementing Kosaraju algo



→ Stack



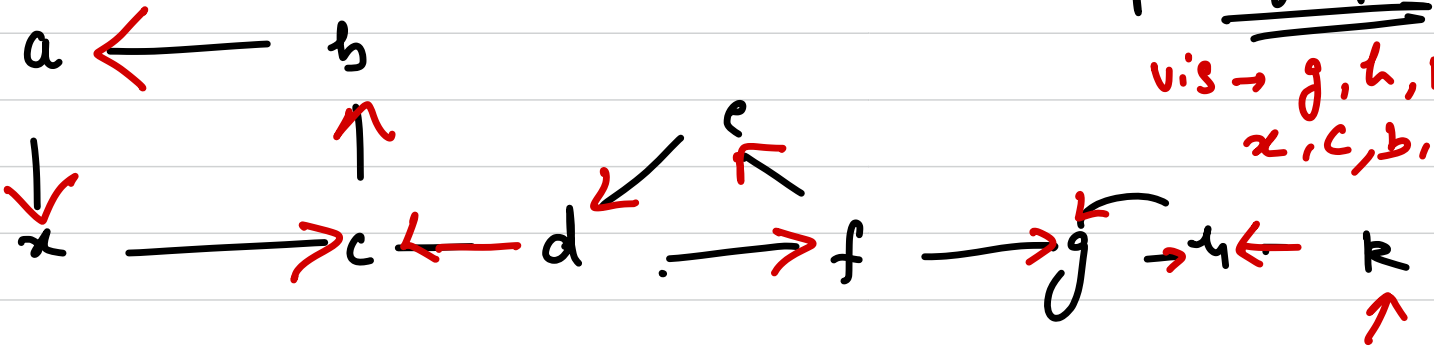
We will start bfs/dfs from an unvisited node.
If we have touched all possible nodes in one go
then we restart with any other unvisited if
it is left.

Do dfs & store vertices in the stack as per their finish
order.

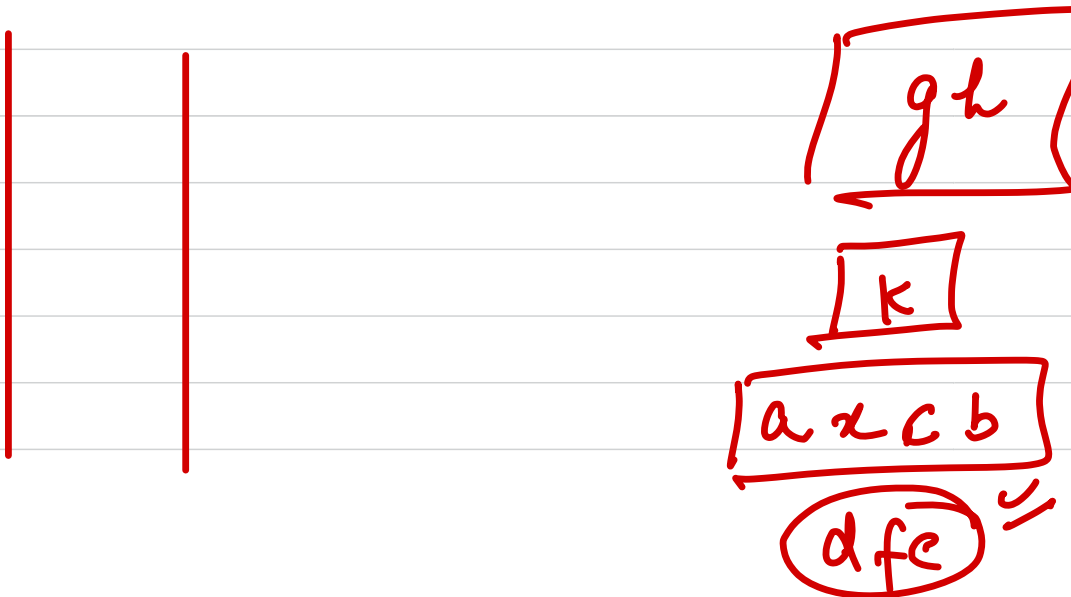
In the phase 2, take transpose of the graph

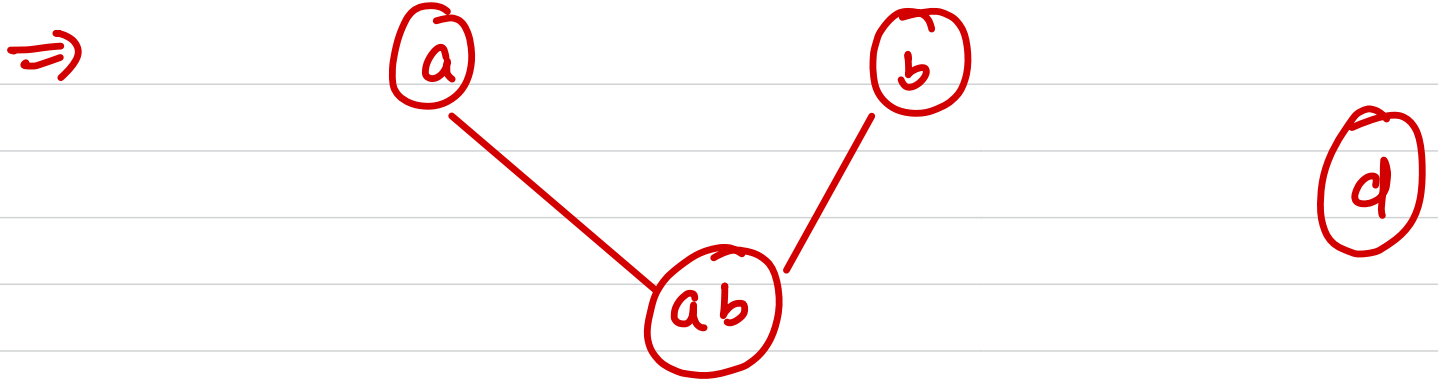
Start dfs on the transposed graph from the node at the top of Stack.

2 transposed graphs



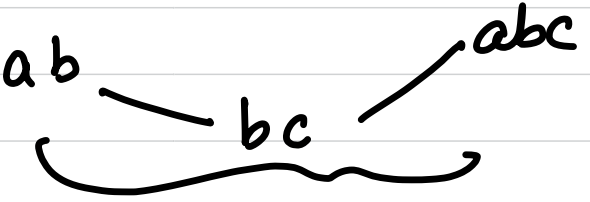
vis → g, h, k, a
x, c, b, d, f, e

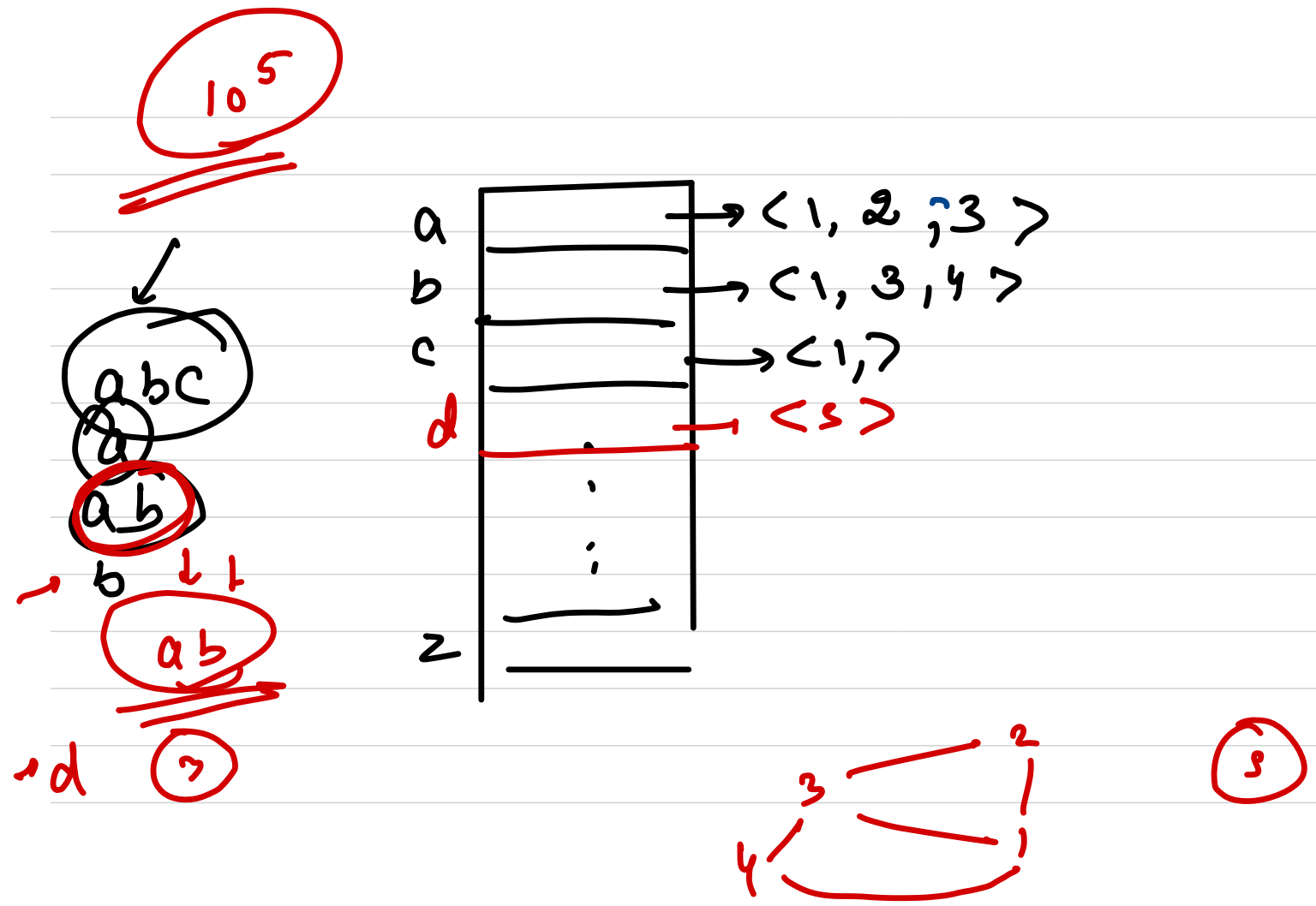




Same component

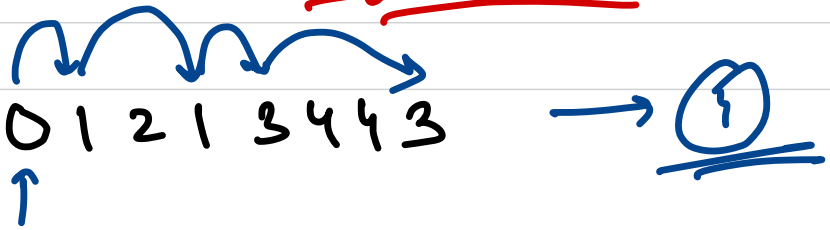
2. Dfs / Bfs / DSU




10^5
abc
a
ab
b
ab
d
3
a
b
c
d
z
<1, 2, 3>
<1, 3, 4>
<1, 7>
<s>
2
3
4
1
3

Q. Given a string of digits of length N. ($N \leq 10^5$) You're standing at 0^{th} index & want to reach $(N-1)^{th}$ index. For each jump you take a cost of 1 unit. and from any i^{th} digit, you can go to $i-1$ or $i+1$ or any other digit S_j such that $S_i == S_j$

Find the min jumps.



0 1 2 1 3 4 4 3

worst case → you need to touch every digit only twice

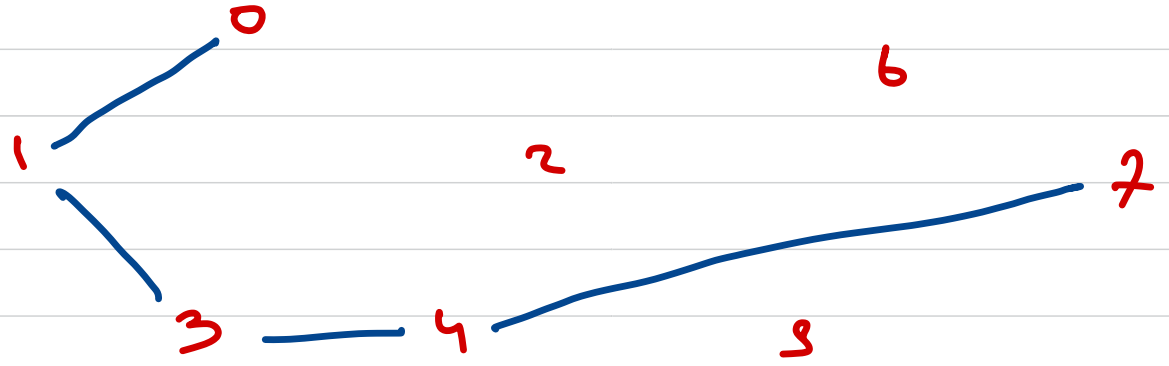
→ 19

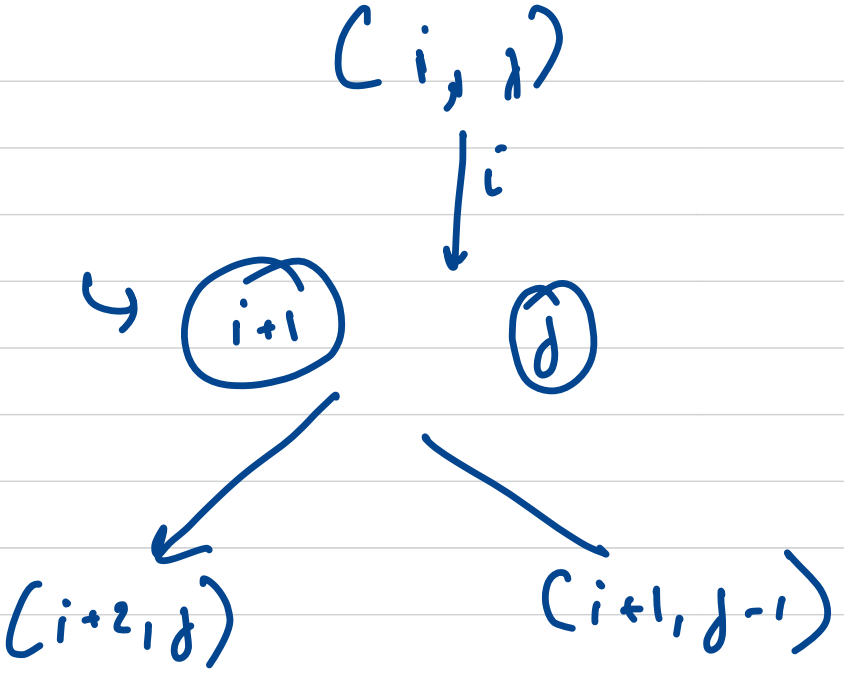
0 0 1 0 0 2 2 2 3 3 4 5 6 6 6 0 2 5 6 8 9

0 1 2 1 3 4 4 3

0 1 2 3 4 5 6 7

0 → 1 → 2




(i, j)
i
i+1
j
(i+2, j)
(i+1, j-1)

Disjoint Set Union

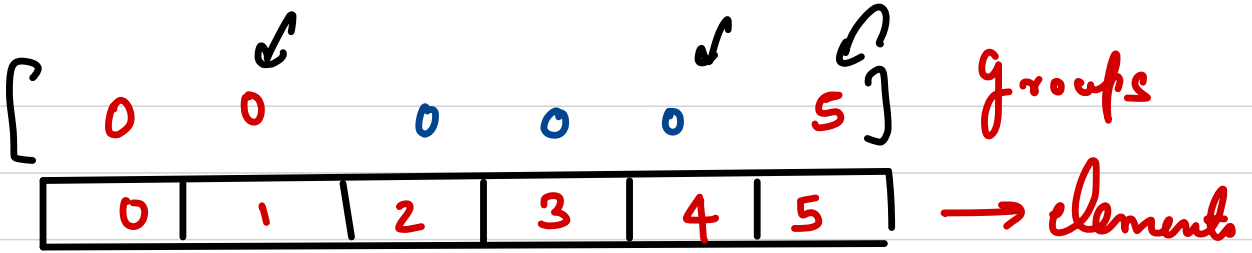
Ex Lets say we want to create clusters

We have a set of elements and we need to group them. Sometimes you might be asked to return the group of any element belongs to.

To uniquely identify a group, we will pick any element of the group & name it the leader/ representative / parent of the group.

union (a, b) → Adds b to the group of a or vice-a-versa.

get(x) / find(x) → To what group the element x belongs to.



union (0,1)

union (2,3)

union (3,4)

union (1,3)

fund(1) → 0

fund(5) → 5

fund(4) → 0

```
int find(x){
    return par[x];
}
```

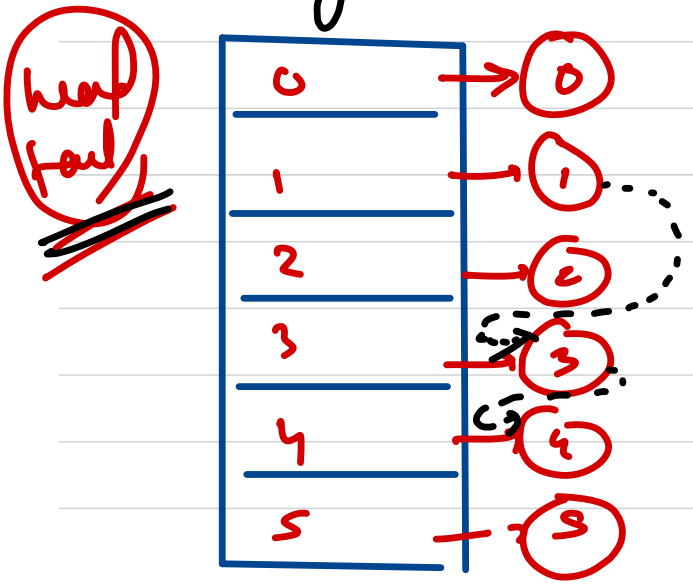
O(1)

Can we optimize?

```
void union(a,b){
    a = find(a);
    b = find(b);
    for i in 1..n {
        if par[i] == b
            par[i] = a
    }
}
```

O(n)

How about storing the grouping mechanism such that we represent it as vector of vector or vector of ll



union(1,3)

doubly list

find / get → O(n)

union → O(1)

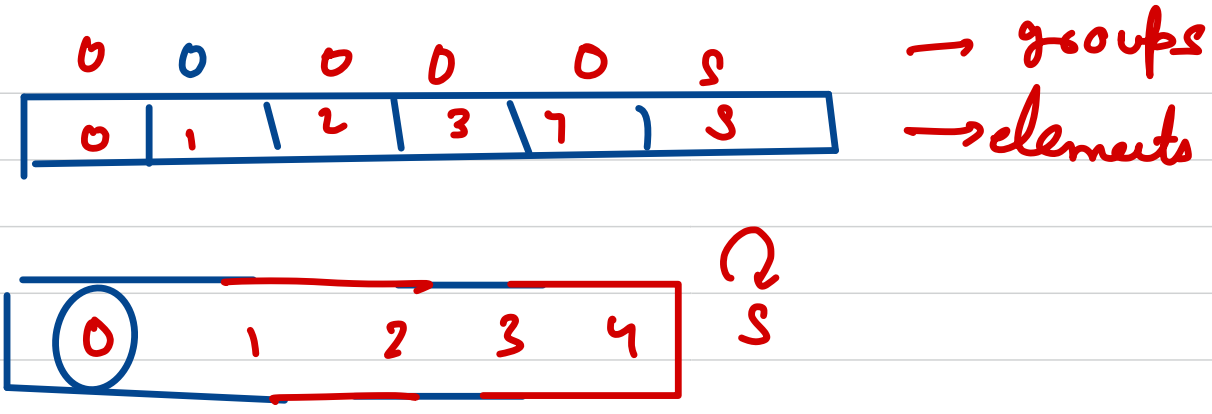
The core problem is, if we add n elements then the operation of updating parent array for each element is $O(n)$

amortized $\quad \frac{n \times O(n)}{n} \rightarrow O(n)$

Somehow optimize updating the parent.

Now let's say we will not union $b \to a$ directly

We can maintain sizes of the groups, and we will always add smaller group to the bigger one.



ops → 1

union (0,1)

union (2,3)
union (4,0)
union (2,4)

what is the benefit

union by size

$\frac{n \times (\log n)}{n} \rightarrow O(\log n)$

1
2
4
8
.
.
.
2^k

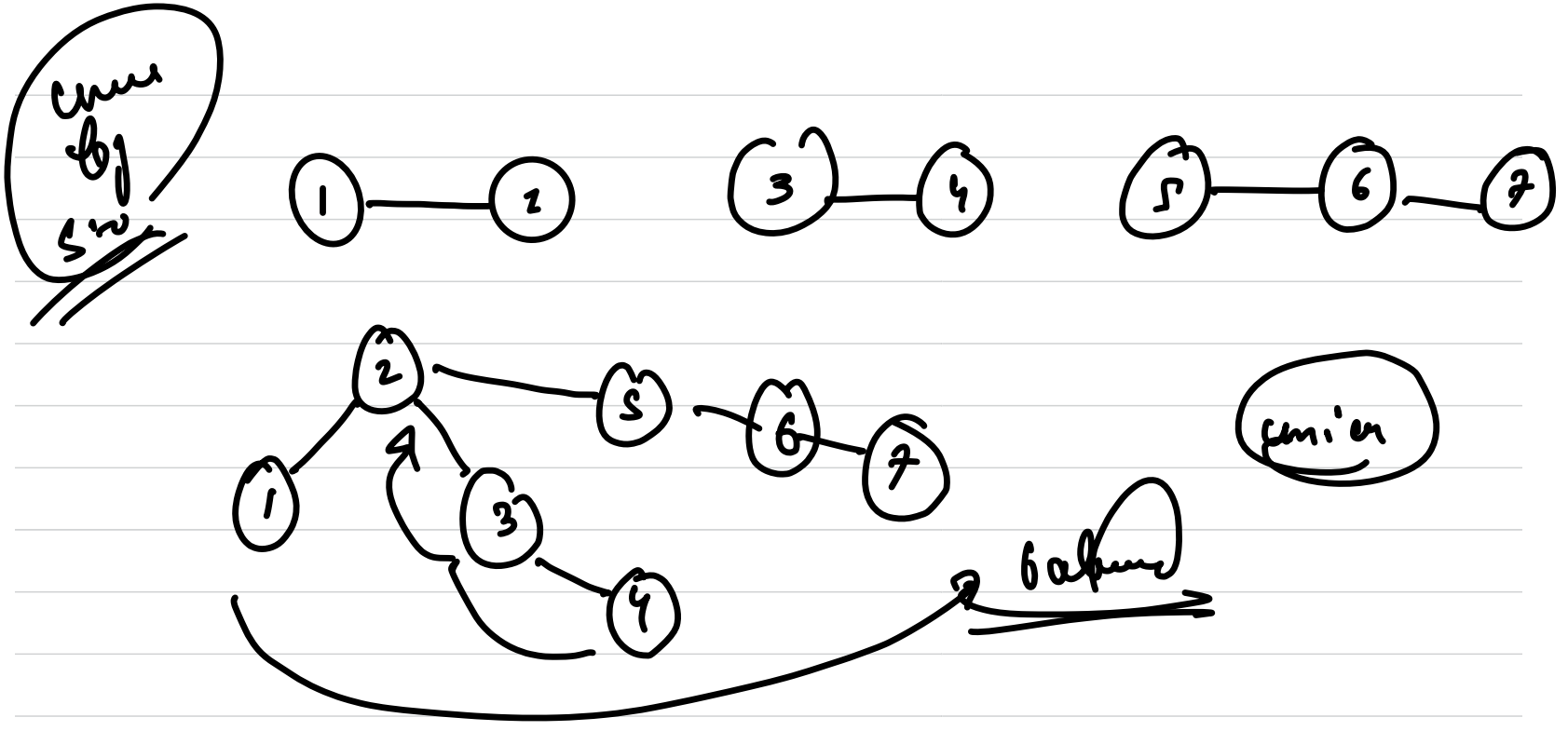
$k \rightarrow \log n$

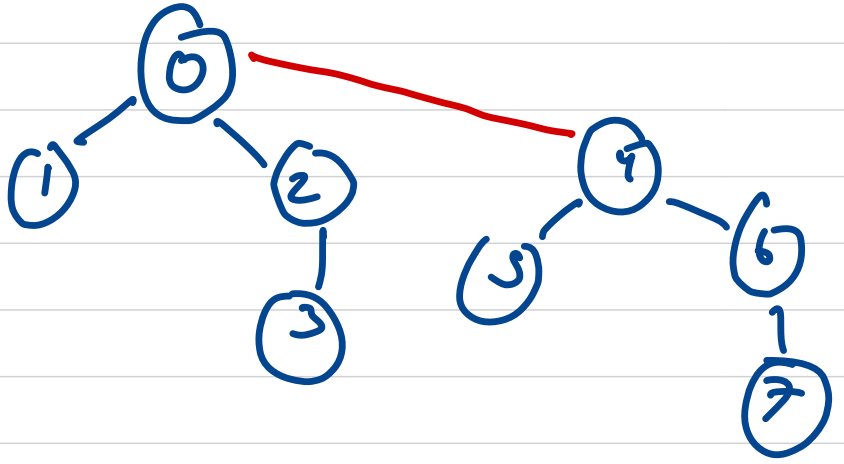
$1 \times \frac{n}{2} + 2 \times \frac{n}{4} + 4 \times \frac{n}{8} \ldots\ldots$

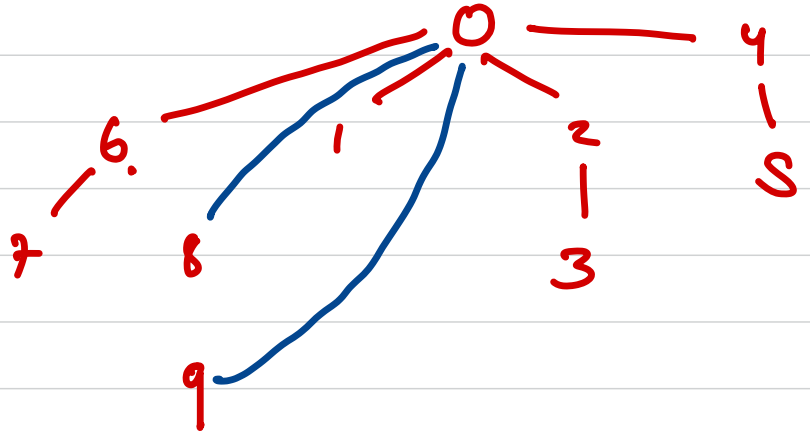
n

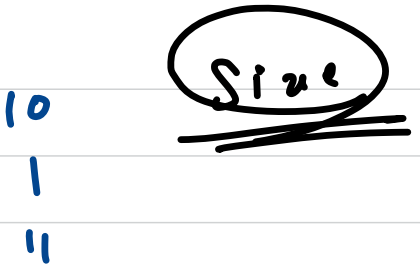
→ union → $\log n$

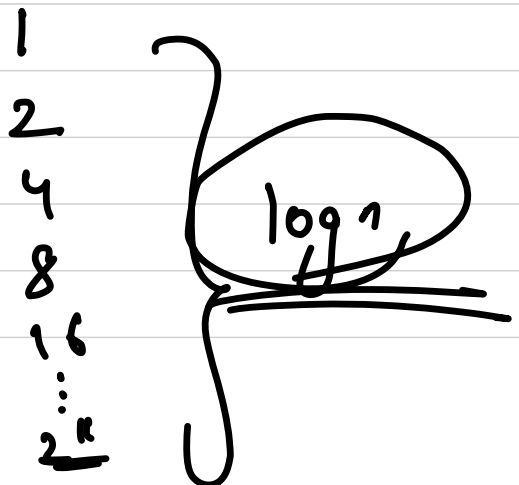
get → $\log n$

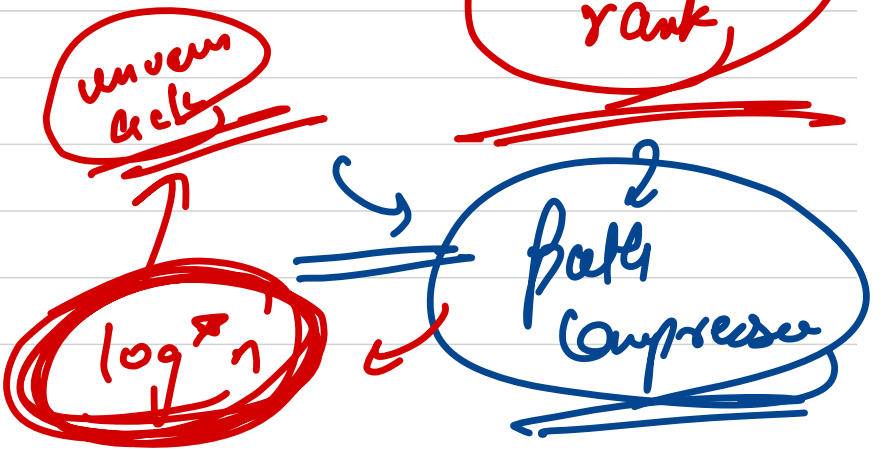

1
2
3
4
5
6
7
union


0
1
2
3
4
5
6
7


0
4
5
6
7
8
1
2
3
9


10
11
Size


1
2
4
8
16
2^k
log n


union by rank
union by rank
log* n
Path Compression

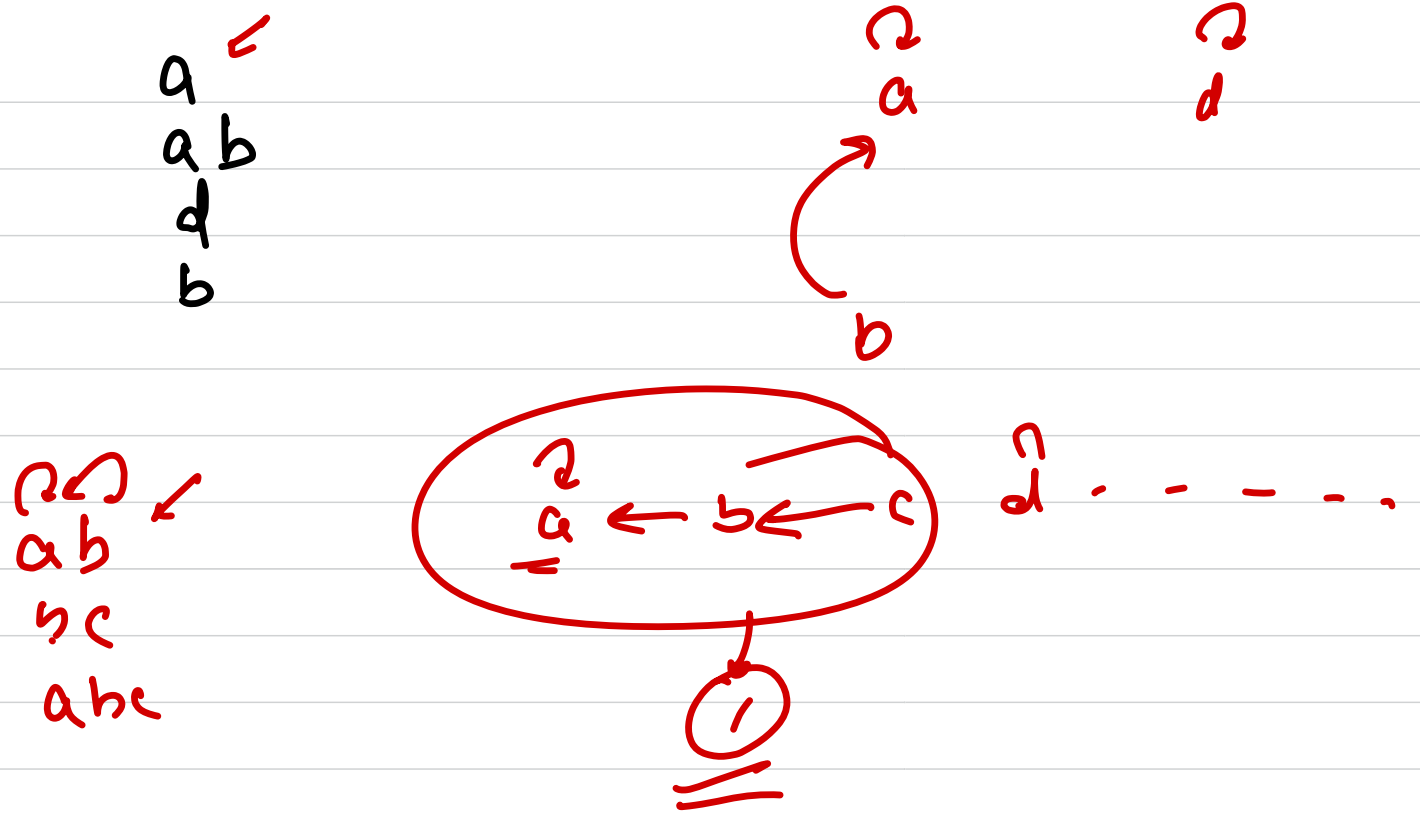
$\log^* n \rightarrow$ extremely slow growing func^n

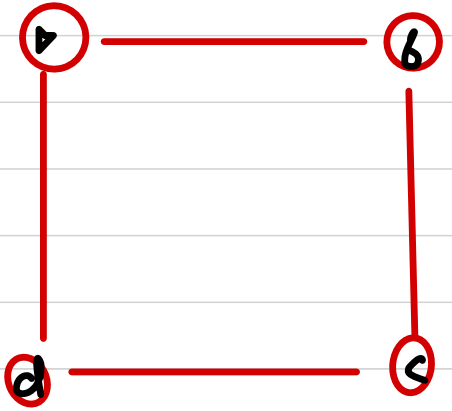
$\log^* n$ no. of steps we need to take $\log_2 n$ on the value of n to make it smaller than 1.

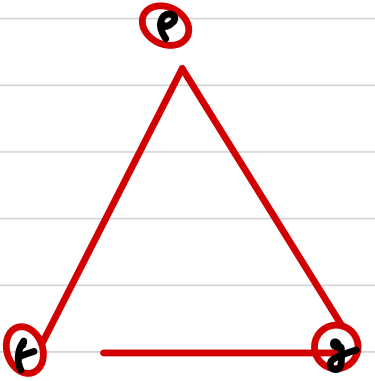
$n \rightarrow 2^{16}$

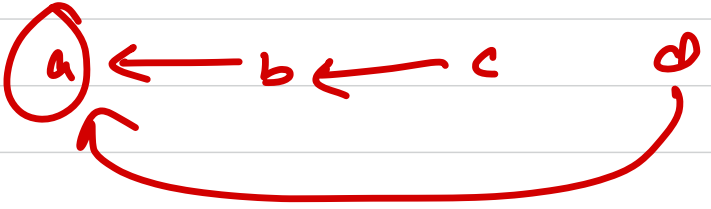
$\log 2^{16} \longrightarrow \log(16) \rightarrow \log(4) \log(2)$

$\rightarrow 1$


a
a b
d
b
a
b
d
a b
b c
a b c
a ← b ← c
d . . . . .
1


a
b
d
c


e
f
g


a
b
c
d


e
f
g