

# SM-2302: Software for Mathematicians

Matlab3: Numerical Techniques

Dr. Huda Ramli

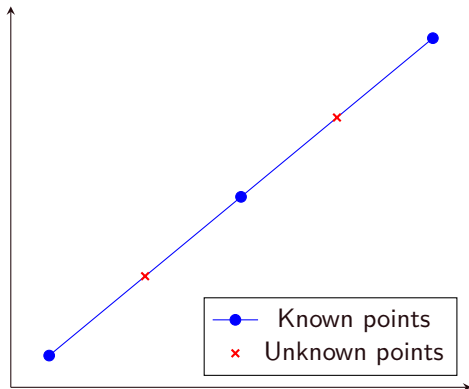
Mathematical Sciences, Faculty of Science, UBD

`huda.ramli@ubd.edu.bn`

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# Interpolation

Interpolation is used to estimate data points between two known points. The most common interpolation technique is linear interpolation.



- In MATLAB, we can use the `interp1()` function
- There are many options for interpolation methods, for e.g.
  - `linear` (default)
  - `nearest`,
  - `spline`,
  - `cubic`, etc.
- Refer to `help interp1` for more details

## Example 1

Given the following data points:

x	0	1	2	3	4	5
y	15	10	9	6	2	0

Find the interpolated value for  $x = 3.5$ .

Using the default linear interpolation, we get the answer 4.

```
x = 0:5;  
y = [15, 10, 9, 6, 2, 0];  
plot(x,y ,'-o')  
  
% Find interpolated value for x=3.5  
y_lin = interp1(x,y,3.5)
```

Using the `spline` interpolation on the same data results in the plotted interpolated points.

```
x = 0:5;  
y = [15, 10, 9, 6, 2, 0];  
new_x = 0:2.5:5;  
  
% Find interpolated values using spline:  
y_spline = interp1(x,y,new_x,'spline')  
  
% Original points and interpolated points in same graph:  
plot(x,y, new_x,y_spline, '-o')
```

# Curve Fitting

- It is often more convenient to model empirical data as a mathematical function:  $y = f(x)$ . Then, we can easily calculate any desired data based on this mathematical model.
- MATLAB's built-in curve fitting functions:

1. `>> p = polyfit(x,y,n)` finds coefficients of a polynomial  $p(x)$  of degree  $n$

2. `>> polyval(p,x)` returns the value of a polynomial  $p(x)$  evaluated at  $x$

These techniques use a polynomial of degree  $n$  that fits data  $y$  best in a least-squares sense.

- A **polynomial** is expressed as:

$$p(x) = p_1x^n + p_2x^{n-1} + \dots + p_nx + p_{n+1}$$

where  $p_1, p_2, \dots, p_{n+1}$  are the coefficients of the polynomial.

MATLAB represents  $p(x)$  as the vector:

$$p = [p_1; p_2; \dots p_n; p_{n+1}]$$

# Regression Models

- **Polynomial Regression:**  $y(x) = a_0x^n + a_1x^{n-1} + \dots + a_{n-1}x + a_n$
- **Linear Regression:**  $y(x) = ax + b$  is a polynomial of the first order.

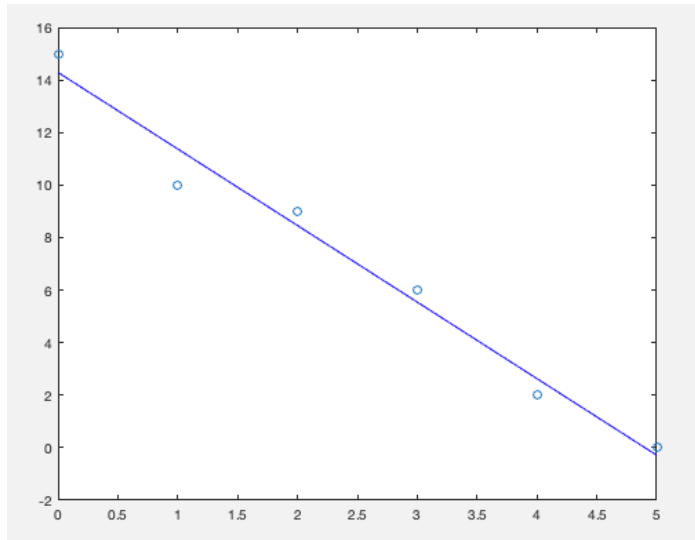
## Example 2 (Linear Regression)

Find the linear regression model of the data given in Example 1.

```
x = 0:5;  
y = [15, 10, 9, 6, 2, 0];  
n = 1; % first order polynomial  
p = polyfit(x,y,n)  
a = p(1); b = p(2);  
ymodel = a*x + b;  
plot(x,y, 'o', x,ymodel, 'b-')
```

The answer is  $\text{ans} = -2.9143 \quad 14.2857$

which gives the linear model:  $y = -2.9143c + 14.2857$  as shown in the resulting graph.



### Example 3 (Polynomial Regression)

Use `polyfit` and `polyval` functions to compare different orders of the polynomial regression models for the same data given in Example 1:

x	0	1	2	3	4	5
y	15	10	9	6	2	0

Since we only have 6 data points, we will study models up to the 5th order polynomial.

```
x=[0, 1, 2, 3, 4, 5];  
y=[15, 10, 9, 6, 2, 0];  
for n=2:5 % From orders 2 to 5  
    p=polyfit(x,y,n)  
    ymodel=polyval(p,x);  
    subplot(2,2,n-1)  
    plot(x,y,'o',x,ymodel)  
    title(sprintf('Model of order %d', n));  
end
```



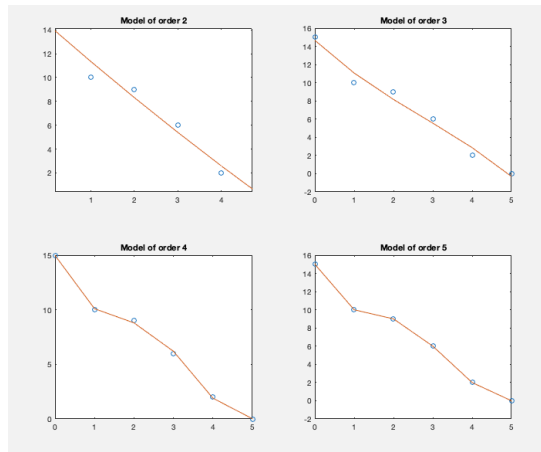
The resulting polynomial regression models are

$$y_2(x) \approx 0.05x^2 - 3.2x + 14.5$$

$$y_3(x) \approx -0.065x^3 + 0.5x^2 - 4x + 14.7$$

$$y_4(x) \approx 0.2x^4 - 1.9x^3 + 6.3x^2 - 9.4x + 15$$

$$y_5(x) \approx -0.04x^5 + 0.7x^4 - 4.2x^3 + 10.3x^2 - 11.8x + 15$$



## Example 4 (Model fitting)

Given the following data:

Height, $h(\text{ft})$	0	1.7	1.95	2.60	2.92	4.04	5.24
Flow, $f(\text{ft}^3/\text{s})$	0	2.6	3.6	4.03	6.45	11.22	30.61

Create polynomial regression models of the following order:

- (i) linear
- (ii) quadratic
- (iii) cubic

Which gives the best model? Plot the result in the same plot and compare them. Add `xlabel`, `ylabel`, `title` and a `legend` to the plot and use different line styles so the user can easily see the comparison.

```
1 %% Script to plot polynomial regression models
2 clear, clc
3
4 % Real Data:
5 height = [0, 1.7, 1.95, 2.60, 2.92, 4.04, 5.24];
6 flow = [0, 2.6, 3.6, 4.03, 6.45, 11.22, 30.61];
7 new_height = 0:0.5:6; % generate new height values used to test the model
8
9 polyorder = 1; % linear
10 p1 = polyfit(height, flow, polyorder) % first order model
11 new_flow1 = polyval(p1,new_height); % use the model to find new flow values
12
13 polyorder = 2; % quadratic
14 p2 = polyfit(height, flow, polyorder) % second order model
15 new_flow2 = polyval(p2,new_height);
16
17 polyorder = 3; % cubic
18 p3 = polyfit(height, flow, polyorder) % third order model
19 new_flow3 = polyval(p3,new_height);
```

```
20
21 % plot the original data together with the model found for comparison
22 plot(height, flow, 'bo', new_height, new_flow1, new_height, new_flow2, ...
        new_height, new_flow3)
23 title('Model fitting')
24 xlabel('height')
25 ylabel('flow')
26 legend('real data', 'linear model', 'quadratic model', 'cubic model')
```

# Numerical differentiation

The derivative of a function  $y = f(x)$  is a measure of how  $y$  changes with  $x$ :

$$f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

A numerical approach to the derivative of a function  $y = f(x)$  is

$$\frac{dy}{dx} = \frac{\Delta y}{\Delta x} = \frac{y_2 - y_1}{x_2 - x_1}$$

MATLAB offers functions for numerical differentiation:

- `diff(x)`: Difference and approximate derivative for a vector **x**
- `polyder(p)`: Differentiate polynomial, returns the derivative of the polynomial whose coefficients are the elements of vector **p**

## Example 5

Use numerical differentiation to find  $\frac{dy}{dx}$  on the function  $y = x^2$ , based on the data points:

x	-2	-1	0	1	2
y	4	1	0	1	4

We know that the exact solution is:  $\frac{dy}{dx} = 2x$ .

We will compare the results from the numerical differentiation with the exact solution.

```
x = -2:2; y = x.^2;  
dydx_num = diff(y)./diff(x);  
dydx_exact = 2*x;  
dydx = [[dydx_num, NaN] ', dydx_exact'] % NaN is added to the vector to get ...  
      same length of vectors  
plot(x,[dydx_num, NaN], 'b', x, dydx_exact, 'g') % Plot the derivatives
```

This yields the following results:

dydx =	
-3	-4
-1	-2
1	0
3	2
NaN	4

How can we get a better approximation result?

## Example 6

Consider the equation  $y = x^3 + 2x^2 - x + 3$ .

- (a) Find  $\frac{dy}{dx}$  analytically.
- (b) Taking  $x = [-5, 5]$ , use `diff` function to approximate the derivative  $\Delta y / \Delta x$ .
- (c) Compare the data in 2D array and compare the graphs of the exact value of  $\frac{dy}{dx}$  and the numerical approximation in the same plot.
- (d) Increase the number of data points and compare.

The exact solution is

$$\frac{dy}{dx} = 3x^2 + 4x - 1.$$



```
x = -5:1:5;  
y = x.^3 + 2*x.^2 - x + 3; % Define the function y(x)  
  
% Plot the function y(x)  
plot(x,y)  
title('y')  
  
% Find numerical solution to dy/dx  
dydx_num = diff(y)./diff(x);  
dydx_exact = 3*x.^2 + 4.*x -1;  
dydx = [[dydx_num, NaN] ', dydx_exact ']  
  
% Plot numerical vs analytical solution to dy/dx  
figure(2)  
plot(x,[dydx_num, NaN], x, dydx_exact)  
title('dy/dx')  
legend('numerical solution', 'analytical solution')
```

# Differentiation on Polynomials

A polynomial can be expressed in the general form:

$$y(x) = a_0x^n + a_1x^{n-1} + \dots + a_{n-1}x + a_n$$

and its derivative is  $y'(x) = a_0nx^{n-1} + a_1(n-1)x^{n-2} + \dots + a_{n-1}$ .

In Example 6,

- The equation  $y = x^3 + 2x^2 - x + 3$  can be defined as a polynomial using the function:

`>> p = [1 2 -1 3]` where  $n = 3$ .

- Then

`polyder(p)`

`ans =`

`3 4 -1`

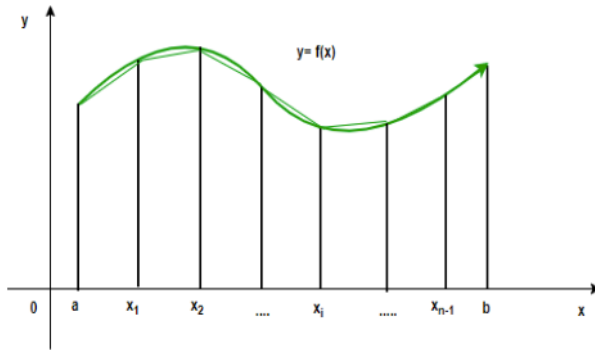
which agrees with our analytical derivative  $\frac{dy}{dx} = 3x^2 + 4x - 1$ .

# Numerical integration

- The integral of a function  $f(x)$  is denoted as:  $\int_a^b f(x) dx$ .
- An integral can be seen as the area under a curve. Given  $y = f(x)$  the area  $A$  under the curve can be approximated by dividing the area between the limits into trapezoids:

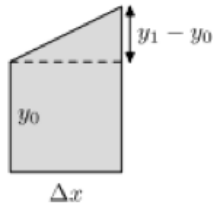
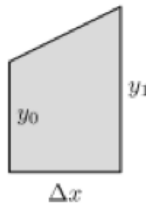
$$A = \sum_{i=1}^n \frac{f(x_i) + f(x_{i-1})}{2} \Delta x \quad \text{where} \quad \Delta x = x_i - x_{i-1}$$

This is known as the **trapezoid rule**.



The area of a trapezoid is obtained by adding the area of a rectangle and a triangle:

$$A_1 = y_0 \Delta x + \frac{1}{2}(y_1 - y_0) \Delta x = \frac{(y_0 + y_1) \Delta x}{2}$$



# Numerical integral functions

Function	Description	Example
diff	Difference and approximate derivative diff(x): $[x_2 - x_1, x_3 - x_2, \dots, x_n - x_{n-1}]$	dydx = diff(y)./ diff (x)
trapz	Computes the approximate integral using the trapezoidal method	trapz(x,y)
quad	Numerically evaluate integral, adaptive Simpson quadrature method	quad(func,a,b)
quadl	Same as quad but uses adaptive Labatto quadrature	quadl(func,a,b)
polyint	Integrate polynomial analytically	polyint (p)
integral	Numerically integrates function func from xmin to xmax	integral (func,xmin,xmax)

func is a scalar-valued function from a to b.

## Example 7

Use the trapezoid rule and `diff` function to solve the numerical integral of  $x^2$  from 0 to 1.

```
1 x = 0:0.1:1;
2 func = @(x) x.^2;
3 y = func(x);
4 plot(x,y)
5
6 % Calculate the Integral (Trapezoid method):
7 avg_y = y(1:length(x)-1) + diff(y)/2;
8 A = sum(diff(x).*avg_y)
9
10 % Use built-in trapz function:
11 A_trapz = trapz(x,y)
12
13 % Calculate the Integral (Simpson method):
14 A_simp = quad('x.^2', 0,1)
15
16 % Calculate the Integral (Lobatto method):
17 A_lab = quadl(@(x) func(x), 0,1)
```