

MATH223 - Linear Algebra (class notes)

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1 January 7th 2019

Should know how to solve a linear system and calculate a determinant... things like that.

- Written assignments (5) : 10%
- Webwork assignments (5) : 5%
- Midterm : 20%
- Final : 65%

Textbook: **Schaum's Outline - Linear Algebra.**

1.1 Motivation

We have linear systems, with two equations, like such:

$$\begin{aligned} 3x - 2y + z &= 2 \\ x - y + z &= 1 \end{aligned}$$

There is an algebraic way of seeing this, but we can also see this, from the geometric standpoint, as the intersection of the two planes in R^3 . Linear algebra has to do with things that are "flat", like a plane. As soon as we add in exponents to these equations, we get some curvature, and the techniques to solve these are different.

- Linear equations are the simplest kind, so you *must* understand them. Also, you *can* understand 'everything' about them.
- Theory used to describe solutions, etc.
- Linear equations are often used to approximate or model more complicated equations/situations.
- In applications, linear systems are often quite big (10000 equations/variables)

1.2 Complex numbers

Def: Let i be a symbol. We declare $i^2 = -1$.

Now, what we'd like to do is take this symbol i and combine it with the usual real numbers that we are familiar with. We set, for example,

$$\begin{aligned} 3i \\ i - 4 \\ 3i - \pi \\ \sqrt{i} + 21 \end{aligned}$$

Def: The field of complex numbers C consists of all expressions of the form $a + bi$, where $a, b \in R$.

Def: Addition (subtraction) and multiplication of complex numbers is defined by the following rules:

(i)

$$(a + bi) + (c + di) = (a + c) + (b + d)i$$

(ii)

$$\begin{aligned} (a + bi)(c + di) &= ac + adi + bci + bdi^2 \\ &= ac + adi + bci - bd \\ &= (ac - bd) + (ad + bc)i \end{aligned}$$

Notation:

- $0 + bi = bi$
- $a + 0i = a$ (a *real* number)
- $0 + 0i = 0$

Ex: If $z_1 = 2 - i$, $z_2 = 5i$, then

$$z_1 + z_2 = 2 + 4i$$

and

$$z_1 z_2 = (2 - i)(5i) = 10i - 5i^2 = 5 + 10i$$

Def: Let $z = a + bi \in C$

- (i) $\bar{z} = a - bi$, called the *complex conjugate* of z
- (ii) $|z| = \sqrt{a^2 + b^2}$, called the *absolute value* or *modulus*

Def: If $z = a + bi \in C$ and $z \neq 0$ (ie $z \neq 0 + 0i$), then the number

$$\begin{aligned} z^{-1} &= \frac{\bar{z}}{|z|^2} \\ &= \frac{a}{a^2 + b^2} - \frac{b}{a^2 + b^2}i \end{aligned}$$

is called the (multiplicative) inverse of z . It has the property $zz^{-1} = 1 = z^{-1}z$.

Proof. We have

$$\begin{aligned} zz^{-1} &= (a + bi)\left(\frac{a}{a^2 + b^2} - \frac{b}{a^2 + b^2}i\right) \\ &= \frac{a^2 - abi + abi - b^2i^2}{a^2 + b^2} \\ &= \frac{a^2 + 0 + b^2}{a^2 + b^2} \\ &= 1 \end{aligned}$$

Note: Since $z \neq 0 + 0i$, $a^2 + b^2 \neq 0$

□

Def: If $z, w \in C$ and $z \neq 0$ then

$$\frac{w}{z} = wz^{-1}$$

Ex: If $z = 1 + 2i, w = 3 - i$ then

$$\begin{aligned} \frac{w}{z} &= wz^{-1} \\ &= (3 - i)\left(\frac{1}{5} - \frac{2}{5}i\right) \\ &= \frac{3}{5} - \frac{6}{5}i - \frac{i}{5} + \frac{2}{5}i^2 \\ &= \frac{3}{5} - \frac{2}{5} - \frac{7}{5}i \\ &= \frac{1}{5} - \frac{7}{5}i \end{aligned}$$

Or,

$$\begin{aligned} \frac{3 - i}{1 + 2i} \cdot \frac{(1 - 2i)}{(1 - 2i)} &= \frac{3 - 6i - i + 2i^2}{1 - 2i + 2i - 4i^2} \\ &= \frac{1 - 7i}{5} \end{aligned}$$

2 January 9th 2019

2.1 Complex numbers as points in R^2

You can view $a + bi$ as a point $(a, b) \in R^2$. The usefulness of this is that we can consider, say, $(3 + 2i)$ and $(3 - i)$ as vectors in R^2 , and they will conserve the same properties (addition of complex numbers corresponds to vector addition in R^2). For the interpretation of multiplication to make sense, it's necessary to use polar coordinates.

2.2 Equations with complex numbers

Fact: Every real number $a \neq 0$ has two square roots:

- if $a > 0$, roots $\pm\sqrt{a}$
- if $a < 0$, two roots are $\pm i\sqrt{|a|}$, since:

$$\begin{aligned}(\pm i\sqrt{|a|}) &= i^2(\sqrt{|a|})^2 \\ &= -1 \cdot |a| \\ &= a\end{aligned}\quad (\text{since } a < 0)$$

Fact: Quadratic equation $ax^2 + bx + c = 0$ has solution

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

which may be in C .

Ex: Solve $x^2 - 2x + 3 = 0$, and factor $x^2 - 2x + 3$.

Sol:

$$\begin{aligned}x &= \frac{-2 \pm \sqrt{4 - 4(1)(3)}}{2} \\ &= \frac{2 \pm \sqrt{-8}}{2} \\ &= \frac{2 \pm i\sqrt{8}}{2} \\ &= \frac{2 \pm i2\sqrt{2}}{2} \\ &= 1 \pm i\sqrt{2}\end{aligned}$$

Note: If $ax^2 + bx + c$ has $a, b, c \in R$ has a non-real root, say z , its other root is \bar{z} ($z = a + bi$, $\bar{z} = a - bi$). This is not necessarily true if $a, b, c \in C$.

Back to problem. Factor $x^2 - 2x + 3 = (x - (1 + i\sqrt{2}))(x - (1 - i\sqrt{2}))$.

Caution: -1 has two roots, namely $\pm i$, so you may write $i = \sqrt{-1}$, but be careful:

$$\begin{aligned}
 -1 &= i^2 \\
 &= i \cdot i \\
 &= \sqrt{-1} \cdot \sqrt{-1} \\
 &= \sqrt{(-1)(-1)} && \text{(this step doesn't quite work)} \\
 &= \sqrt{1} \\
 &= 1
 \end{aligned}$$

Theorem: (Fundamental Theorem of Algebra) If

$$p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_0 x^0$$

is a polynomial with $a_n \neq 0$, and $a_n, a_{n-1}, \dots, a_0 \in C$, then $p(x)$ factors into linear factors,

$$p(x) = a_n \cdot (x - r_1) \cdot (x - r_2) \cdot \dots \cdot (x - r_n)$$

for some complex numbers r_1, r_2, \dots, r_n . Some r_i 's may be equal.

Corollary: Every such polynomial has at least one root, and at most n distinct roots.

Note: *Finding* the roots is, in general, quite difficult.

Ex: Factor $2x^3 + 2x$ (over C).

Sol:

$$\begin{aligned}
 2(x^3 + x) &= 2(x - 0)(x^2 + 1) \\
 &= 2(x - 0)(x^2 - i^2) \\
 &= 2(x - 0)(x - i)(x + i)
 \end{aligned}$$

Ex: Solve $x^2 - i = 0$

Sol: $x^2 = i$ so $x = \pm\sqrt{i}$. Want \sqrt{i} in format $a + bi$, $a, b \in R$.

$$\begin{aligned}\sqrt{i} &= a + bi \\ i &= (a + bi)^2 \\ &= a^2 + 2abi + b^2i^2 \\ 0 + i &= (a^2 - b^2) + 2abi\end{aligned}$$

$$0 = a^2 - b^2$$

$$1 = 2ab$$

$$a = \pm b$$

$$ab = \frac{1}{2}$$

(so $a=b$ both $+$ or both $-$)

$$a^2 = \frac{1}{2}$$

$$a = \pm \frac{1}{\sqrt{2}} = b$$

Two solutions, $\frac{1}{\sqrt{2}} + \frac{1}{\sqrt{2}}i$ and $-\frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}}i$.

2.3 Vector spaces (Ch 4)

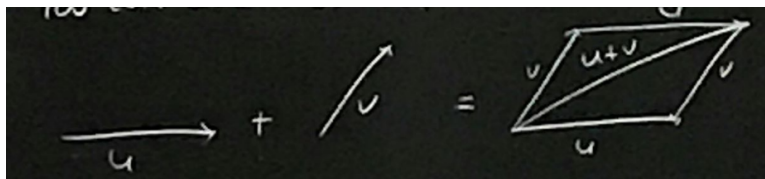
Def. The sets R and C (and also Q , rational numbers, although we won't go into details of this) are called *fields* (or *fields of scalars*). In this class, "a field of K " means that K is either R or C .

3 January 11th 2019

Last time: *Field* K is R or C (for this class).

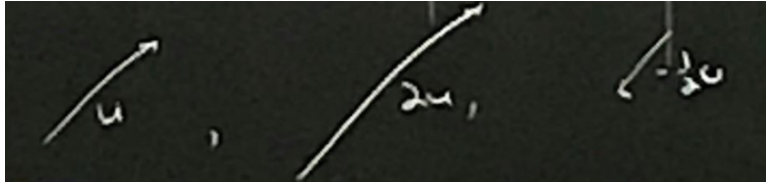
3.1 Geometric vectors ('arrows')

You can add two vectors (arrows).



Observation: $\vec{u} + \vec{v} = \vec{v} + \vec{u}$.

You can rescale a vector:



Observation: $a(b\vec{u}) = (ab)\vec{u}$.

Also: $1\vec{u} = \vec{u}$

Question: What properties are interesting? What other objects obey the same properties?

Abstraction: Focus on properties more than on the objects.

3.2 Definition of a vector space

Let V be a set, called set of "vectors", and let K be a field (R or C) (elements of K called *scalars*). Assume that we have already defined two operations:

- (1) One called *addition*, which takes two vectors $\vec{u}, \vec{v} \in V$ and produces another vector denoted $\vec{u} + \vec{v} \in V$.
- (2) One called *scalar multiplication* which takes a vector $\vec{u} \in V$ and a scalar $a \in K$ and produces another vector denoted $a\vec{u} \in V$

Then if, for all vectors $\vec{u}, \vec{v}, \vec{w} \in V$ and all scalars $a, b \in K$, the following 8 properties are true, then V is called a *vector space* (over K).

- (A1) $u + v = v + u$ (commutative laws)
- (A2) There exists a vector in V , named *zero vector* and denoted 0 (or $\vec{0}$) such that for all $u \in V$, $u + 0 = u$
- (A3) For each $u \in V$, there is a vector in V , called the (additive) inverse of u and denoted $-u$, having the property $u + (-u) = 0$ (where 0 is the zero vector defined in A2)
- (A4) $(u + v) + w = u + (v + w)$
- (SM1) $a(u + v) = au + av$ (distributive laws)
- (SM2) $(a + b)u = au + bu$
- (SM3) $a(bu) = (ab)u$
- (SM4) $1u = u$ ($1 \in R$ or C)

These are called the vector space *axioms*.

3.3 Examples of vector spaces

Some examples:

- (1) $K^n = \{(a_1, a_2, \dots, a_n) | a_1, a_2, \dots, a_n \in K\}$, with addition defined by

$$(a_1, a_2, \dots, a_n) + (b_1, b_2, \dots, b_n) = (a_1 + b_1, a_2 + b_2, \dots, a_n + b_n)$$

and scalar multiplication by

$$c(a_1, a_2, \dots, a_n) = (ca_1, ca_2, \dots, ca_n)$$

where $c \in K$ (and K = set of scalar).

Proof that K^n is a vector space

Need to prove all 8 properties. We will do 2, the rest are exercises.

- (A4) To prove for all $u, v \in V$, $u + v = v + u$.

Proof concept: To prove "for all $x \in A$, something", say "let $x \in A$ " (means x is an arbitrary element of A , ie you only know $x \in A$).

Then, prove something for that x .

Proof: Let $u, v \in K^n$. This means $u = (a_1, a_2, \dots, a_n)$, $v = (b_1, b_2, \dots, b_n)$ for some $a_1, a_2, \dots, a_n, b_1, b_2, \dots, b_n \in K$. Then

$$\begin{aligned} u + v &= (a_1, \dots, a_n) + (b_1, \dots, b_n) \\ &= (a_1 + b_1, \dots, a_n + b_n) && \text{(definition of addition in } K^n) \\ &= (b_1 + a_1, \dots, b_n + a_n) && \text{(since } a + b = b + a \text{ for } R \text{ and } C) \\ &= (b_1, \dots, b_n) + (a_1, \dots, a_n) && \text{(definition of addition in } K^n) \\ &= v + u \end{aligned}$$

- (A2) *Proof concept:* To prove "there exists" something, one method is to describe the thing directly.

Define $0 = (0, 0, \dots, 0)$ (which is in K^n). To prove for all $u \in K^n$, $u + 0 = u$, let $u \in K^n$. This means $u = (a_1, a_2, \dots, a_n)$, so

$$\begin{aligned} u + 0 &= (a_1, a_2, \dots, a_n) + (0, 0, \dots, 0) \\ &= (a_1 + 0, a_2 + 0, \dots, a_n + 0) \\ &= (a_1, a_2, \dots, a_n) \\ &= u \end{aligned}$$

- (2) In the vector space C^2 , $(2 + 3i, 5 - 7i) \in C^2$ is an example of a vector and $2i \in C$ is a scalar, so an example of scalar mult is :

$$\begin{aligned} 2i(u) &= 2i(2 + 3i, 5 - 7i) \\ &= (4i + 6i^2, 10i - 14i^2) \\ &= (-6 + 4i, 14 + 10i) \end{aligned}$$

4 January 14th 2019

Problem: Let $J = \{(x, y) | x \in R, y \in R\}$ but define addition by

$$(x_1, y_1) + (x_2, y_2) = (-x_1 - x_2, y_1 + y_2)$$

and scalar multiplication by

$$c(x, y) = (cx, cy)$$

Show that J is not a vector space.

Solution: Show *one* of the 8 vector space axioms is false. Consider (A1):

$$(x_2, y_2) + (x_1, y_1) = (-x_2 - x_1, y_2 + y_1)$$

This is actually ok! Now consider (A4):

$$\begin{aligned}(x_1, y_1) + ((x_2, y_2) + (x_3, y_3)) &= (x_1, y_1) + (-x_2 - x_3, y_2 + y_3) \\ &= (-x_1 - (-x_2 - x_3), y_1 + y_2 + y_3) \\ &= (-x_1 + x_2 + x_3, y_1 + y_2 + y_3)\end{aligned}$$

While

$$\begin{aligned}((x_1, y_1) + (x_2, y_2)) + (x_3, y_3) &= (-x_1 - x_2, y_1 + y_2) + (x_3, y_3) \\ &= (-(-x_1 - x_2) - x_3, y_1 + y_2 + y_3) \\ &= (x_1 + x_2 - x_3, y_1 + y_2 + y_3)\end{aligned}$$

This does not quite yet prove that the axiom is false. To do so, give *specific* case where the equation is false.

Actual proof: Let $u = (1, 1)$, $v = (2, 2)$ and $w = (3, 3)$. Then,

$$\begin{aligned}u + (v + w) &= (1, 1) + ((2, 2) + (3, 3)) \\ &= (1, 1) + (-2 - 3, 5) \\ &= (1, 1) + (-5, 5) \\ &= (-1 + 5, 6) \\ &= (4, 6)\end{aligned}$$

Whereas,

$$\begin{aligned}(u + v) + w &= ((1, 1) + (2, 2)) + (3, 3) \\ &= (-1 - 2, 3) + (3, 3) \\ &= (-3, 3) + (3, 3) \\ &= -(-3) - 3, 6) \\ &= (0, 6)\end{aligned}$$

Hence, the axiom does not hold.

4.1 More examples of vector spaces

- (1) K^n (ie R^n or C^n). See before
- (2) $P(K)$ = polynomials, where coefficients are in K . Addition, scalar multiplication are "as expected", ie for multiplication:

$$\begin{aligned} f(x) &= x^2 + 2ix - 4 \in P(C) \\ g(x) &= -x^2 + ix \in P(C) \end{aligned} \quad (\text{and also in } P(R))$$

For addition,

$$f(x) + g(x) = 3ix - 4$$

And for scalar multiplication,

$$\begin{aligned} 2if(x) &= 2ix^2 + 4i^2x - 8i \\ &= 2ix^2 - 4x - 8i \end{aligned}$$

- (3) $P_n(K)$ = polynomials of degree n or less, coefficient from K . For example,

$$\begin{aligned} x^2 - 2x + 2 &\in P_2(R) \\ x^2 - 2x + 2 &\in P_3(R) \\ x^2 - 2x + 2 &\in P_2(C) \\ x^2 - 2x + 2 &\notin P_1(R) \end{aligned}$$

Note: In $P(K)$, $P_n(K)$ the "vectors" are polynomials.

- (4) $M_{m \times n}(K)$ = $m \times n$ matrices with entries from K . Scalars are K , addition and scalar multiplication as expected.

$$\begin{aligned} A &= \begin{pmatrix} 2 & i \\ 0 & \pi \end{pmatrix} \in M_{2 \times 2}(C) \\ B &= \begin{pmatrix} -2 & 1 \\ 1+i & -\pi \end{pmatrix} \in M_{2 \times 2}(C) \\ A+B &= \begin{pmatrix} 0 & 1+i \\ 1+i & 0 \end{pmatrix} \\ 2iA &= \begin{pmatrix} 4i & 2i^2 \\ 0 & 2i\pi \end{pmatrix} \\ &= \begin{pmatrix} 4i & -2 \\ 0 & 2\pi i \end{pmatrix} \end{aligned}$$

The "zero vector" in $M_{m \times n}(K)$ is the $m \times n$ matrix with all entries 0.

- (5) Let X be any set (think $x = R$ or C , but not required). Define $F(X, K) = \{f : X \rightarrow K\}$ = all functions from X to K .

Ex: $f(x) = x^2 \in F(R, R)$.

Ex: Let $x = \{1, 2\}$. Then g defined by

$$\begin{aligned}g(1) &= 3 \\g(2) &= \sqrt{2}\end{aligned}$$

Addition in this space is defined by:

If $f, g \in F(X, K)$ then $f + g$ is the function defined by

$$(f + g)(x) = f(x) + g(x)$$

Note that $f(x) \in K$ and $g(x) \in K$, in other words they are *numbers* (scalars). The $+$ in $(f + g)$ is the addition of vectors f and g , while the other $+$ is scalar addition.

Scalar multiplication in this space is defined by: if $f \in F(X, K), c \in K$ then cf is the function defined by

$$(cf)(x) = cf(x)$$

Note that cf is the name of the function, that "multiplication" is scalar multiplication $F(X, K)$ and $cf(x)$ is the multiplication of two scalars (numbers).

The fact that $F(X, K)$ is a vector space and the axioms are followed is not so obvious.

Prove (A2) true for $F(X, K)$. Define $z \in F(X, K)$ by

$$z(x) = 0 \quad (\text{for all } x \in X)$$

Note that 0 here is a scalar. Then if $f \in F(X, K)$ is an arbitrary element, then we need to prove $f + z = f$. This is true since for all $x \in X$,

$$\begin{aligned}(f + z)(x) &= f(x) + z(x) \\&= f(x) + 0 \\&= f(x)\end{aligned}$$

Hence, $f + z, f$ have the same output (namely $f(x)$) for every input. Hence, $f + z = f$.

Exercise: Try (A3).

5 January 16th 2019

Theorem: ("Cancellation Law") Suppose v is a vector space over K . For all vectors $u, v, w \in V$, if $u + w = v + w$ then $u = v$.

Note: To prove "for all" you say let $u \in V$ (means u is an arbitrary vector).

To prove "if p then q ", denoted $p \rightarrow q$, assume p is true and use it to prove q .

Proof. Let $u, v, w \in V$. Assume $u + w = v + w$. By vector space axiom A3, there is a vector $(-w) \in V$. Add $(-w)$ to both sides:

$$\begin{aligned}(u + w) + (-w) &= (v + w) + (-w) \\ u + (w + (-w)) &= v + (w + (-w)) && \text{(by A1)} \\ u + \vec{0} &= v + \vec{0} && \text{(by A3)} \\ &= u = v && \text{(by A2)}\end{aligned}$$

□

Theorem:

1. The zero vector is unique
2. For each $u \in V$, $-u$ is unique

Note: To prove something is unique, suppose you have two of them and show they are the same.

Proof. 1) Assume 0 and z both satisfy the property (A2: $\forall u \in V, u + 0 = u$ (*) and $u + z = u$ (**)). Goal is to prove $0 = z$.

$$\begin{aligned}z &= z + 0 && \text{(by *, with } u = z) \\ &= 0 + z && \text{(by A4)} \\ z &= 0 && \text{(by **, with } u = 0)\end{aligned}$$

So the zero vector is unique.

- 2) Exercise.

□

Theorem: $\forall u \in V, c \in K$,

- 1) $c\vec{0} = \vec{0}$
- 2) $0u = \vec{0}$
- 3) $-(cu) = ((-c)u)$

Proof. Of 2). Let $u \in V$. Then,

$$\begin{aligned}0u + 0u &= (0 + 0)u && \text{(By SM2)} \\ 0u + 0u &= 0u && \text{(by R addition)} \\ 0u + 0u &= 0u + \vec{0} && \text{(by A2)} \\ 0u + 0u &= \vec{0} + 0u && \text{(by A4)} \\ 0u &= \vec{0} && \text{(by cancellation law)}\end{aligned}$$

□

Note: $0 + u = u$ is true for all $u \in V$ (same as $u + 0 = u$ then apply A4)

5.1 Linear combinations and spans

Def: Let $u, v_1, v_2, \dots, v_n \in V$. If there are scalars $a_1, a_2, \dots, a_n \in K$ such that $u = a_1v_1 + a_2v_2 + \dots + a_nv_n$ then u is said to be a linear combination of v_1, v_2, \dots, v_n .

Ex: In $P(R)$, $x^2 + 2x - 4$ is a linear comb of $x^2, x, 1$.

Important problem: Given vectors u, v_1, v_2, \dots, v_n , determine if u is a linear combination of v_1, v_2, \dots, v_n and if so find a_1, a_2, \dots, a_n .

Ex: Determine if $f(x) = 2x^2 + 6x + 8$ is a linear combination of

$$\begin{aligned} g_1(x) &= x^2 + 2x + 1 \\ g_2(x) &= -2x^2 - 4x - 2 \\ g_3(x) &= 2x^2 - 3 \end{aligned}$$

Sol. Are there a_1, a_2, a_3 s.t.

$$\begin{aligned} 2x^2 + 6x + 8 &= a_1(x^2 + 2x + 1) + a_2(-2x^2 - 4x - 2) + a_3(2x^2 - 3) \\ &= (a_1 - 2a_2 + 2a_3)x^2 + (2a_1 - 4a_2)x + (a_1 - 2a_2 - 3a_3) \end{aligned}$$

Equating coefficients,

$$\begin{aligned} a_1 - 2a_2 + 2a_3 &= 2 \\ 2a_1 - 4a_2 &= 6 \\ a_1 - 2a_2 - 3a_3 &= 8 \end{aligned}$$

Solve the linear system:

$$\begin{aligned} &\left[\begin{array}{ccc|c} 1 & -2 & 2 & 2 \\ 2 & -4 & 0 & 6 \\ 1 & -2 & -3 & 8 \end{array} \right] \\ &\quad \downarrow \\ &\left[\begin{array}{ccc|c} 1 & -2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right] \quad (\text{row reduce}) \end{aligned}$$

\therefore No solution, because of the last row. f is not a linear combination of g_1, g_2, g_3 .

Def: Let $S \subseteq V$ (S is a subset of V) and assume $s \neq 0$. The span of s , denoted $\text{span}(s)$ is the set of all linear combinations of vectors from S , ie

$$\begin{aligned} \text{span}(s) &= \{u \in V \mid \exists v_1, v_2, \dots, v_n \in S \\ &\quad \text{and scalars } a_1, a_2, \dots, a_n \text{ s.t.} \\ &\quad u = a_1v_1 + a_2v_2 + \dots + a_nv_n\} \end{aligned}$$

6 January 18th 2019

6.1 Last class

$$\begin{aligned} S &\subseteq V \\ \text{span}(S) &= \{u \in V \mid \exists v_1, v_2, \dots, v_n \in S \\ &\quad \text{and scalars } a_1, a_2, \dots, a_n \text{ s.t.} \\ &\quad u = a_1 v_1 + a_2 v_2 + \dots + a_n v_n\} \end{aligned}$$

Ex: $S = \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix} \right\} \subseteq R^2$. Prove $\text{span}(S) = R^2$.

Note: $\begin{pmatrix} a \\ b \end{pmatrix}$ means (a, b) .

Proof note: To prove two sets A, B are equal, ie $A = B$, you can prove $A \subseteq B$ and $B \subseteq A$.

Sol:

- (1) Prove $\text{span}(S) \subseteq R^2$. Trivial, since any linear combination of vectors in R^2 is still in R^2 .
- (2) Prove $R^2 \subseteq \text{span}(S)$. Let $\begin{pmatrix} a \\ b \end{pmatrix} \in R^2$ (arbitrary). To prove that there exists scalars $x_1, x_2 \in K$ so that

$$\begin{pmatrix} a \\ b \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + x_2 \begin{pmatrix} 3 \\ 1 \end{pmatrix}$$

In other words,

$$\begin{aligned} a &= x_1 + 3x_2 \\ b &= 2x_1 + x_2 \end{aligned}$$

Want to show this has a solution (for all a, b). System is:

$$\begin{pmatrix} 1 & 3 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix}$$

But,

$$\begin{vmatrix} 1 & 3 \\ 2 & 1 \end{vmatrix} = 1 - 2(3) \neq 0$$

hence the system has (exactly one) solution. $\begin{pmatrix} a \\ b \end{pmatrix} \in \text{span}(S)$ so $R^2 \subseteq \text{span}(S)$. So by (1), (2), $\text{span}(S) = R^2$. \square

Note: $Ax = b$, $A_{n \times n}$ if A inv, $x = A^{-1}b$.

Theorem: Let $S \subseteq V$, $S \neq \emptyset$ (\emptyset = empty set). Then,

- (1) If $u, v \in \text{span}(S)$ then $u + v \in \text{span}(S)$
- (2) If $u \in \text{span}(S)$ and $c \in K$, then $cu \in \text{span}(S)$

$$(3) \vec{0} \in \text{span}(S)$$

Proof. By direct proof.

(1) (Note, "if $u, v \in \text{span}(S)$ " means for all $u, v \in \text{span}(S)$).

Let $u, v \in \text{span}(S)$. Then,

$$u = a_1u_1 + a_2u_2 + \dots + a_nu_n \text{ where } u_1, \dots, u_n \in S, a_1, \dots, a_n \in K$$

$$v = b_1v_1 + b_2v_2 + \dots + b_mv_m \text{ where } v_1, \dots, v_m \in S, b_1, \dots, b_m \in K$$

Then $u + v = a_1u_1 + \dots + a_nu_n + b_1v_1 + \dots + b_mv_m$ which is in $\text{span}(S)$ since $u_1, \dots, u_n, v_1, \dots, v_m \in S$.

(2) Let $u \in \text{span}(S), c \in K$. Then,

$$u = a_1u_1 + a_2u_2 + \dots + a_nu_n \text{ where } u_1, \dots, u_n \in S, a_1, \dots, a_n \in K$$

So,

$$\begin{aligned} cu &= c(a_1u_1) + c(a_2u_2) + \dots + c(a_nu_n) \\ &= (ca_1)u_1 + (ca_2)u_2 + \dots + (ca_n)u_n \end{aligned}$$

Note: If you want to be very formal, you need to write down all of the vector space axioms. Which is in $\text{span}(S)$ since it is a linear combination of a_1, \dots, a_n which are in S .

(3) (Prove $\vec{0} \in \text{span}(S)$) Let $u \in S$. **Note:** This is possible only because $S \neq \emptyset$.

Then $u = 1u$, so $u \in \text{span}(S)$. Then using $c = 0$ and (2) and fact that $u \in \text{span}(S)$,

$$cu = 0u = \vec{0}$$

is also in $\text{span}(S)$. **Note:** Since $u = 1u$, $S \subseteq \text{span}(S)$.

□

6.2 Subspaces

Def. Let V be a vector space and $W \subseteq V$ (subset). If W , using addition and scalar multiplication as defined in V , satisfies the definition of vector space, then W is called a subspace of V , denoted $W \leq V$ (less than equal sign, read as "subspace").

Note: Main issue is that addition and scalar multiplication with vector from W produce vectors which are still in W .

Theorem: Let $W \subseteq V$. Then, if the following three properties hold, then $W \leq V$ (subspace).

- (SS1) For all $w_1, w_2 \in W$, we have $w_1 + w_2 \in W$ ("closure under addition")
- (SS2) For all $w \in W$ and scalars $c \in K$, we have $cw \in W$ ("closure under scalar multiplication")
- (SS3) $\vec{0} \in W$.

These are the same properties we just proved for spans; in other words, we proved earlier that $\text{span}(S)$ is a subspace.

Proof. For W to have operations addition, scalar multiplication, just means (SS1) and (SS2) are true. So now, check (A1) - (SM4). Most of them are true because they are true in a larger vector space.

- (A1) Let $u, v, w \in W$. Then since $u, v, w \in V$, and (A1) holds in V , $u + (v + w) = (u + v) + w$.
- (A2) This is (SS3).
- (A3) This is the one we have to do a bit more work for. Let $w \in W$. Want to show $-w \in W$. Then, using (SS2) with $c = -1$ gives

$$-1(w) = -w \quad (\text{thm from last class})$$

is in W , as needed.

- (A4) Still true because it is true in V .

(SM1-SM4) All hold because they hold in V .

□

7 January 21st 2019

7.1 A note on logic

Let P, Q be statements that are true or false.

- (1) "If P then Q ", also written symbolically as " $P \Rightarrow Q$ " (P implies Q) means if P is true, then Q is also true. To *prove* " $P \Rightarrow Q$ ", assume P and prove Q is true. If you *know* that " $P \Rightarrow Q$ " is true, you can *use it*: if you can establish that P is true, you may conclude Q is true.

Ex: Let A be an $n \times n$ matrix:

$$P : \det(A) = 1 \quad Q : "A \text{ is invertible}"$$

Thm: $P \Rightarrow Q$

- (2) The *converse* of " $P \Rightarrow Q$ " is " $Q \Rightarrow P$ ". This is a (logically) different statement.

Ex: With P and Q as above, " $Q \Rightarrow P$ " is not true because $A_{\text{inv}} \not\Rightarrow \det(A) = 1$.

- (3) The *contrapositive* of “ $P \Rightarrow Q$ ” is “ $\neg Q \Rightarrow \neg P$ ” ie “if Q false, then P also false”. Logically, this is the same as “ $P \Rightarrow Q$ ”.
- (4) The *equivalence* “ P if and only if Q ”, written “ $P \iff Q$ ” means “ $P \Rightarrow Q$ and also $Q \Rightarrow P$ ” is true. Also means that either both P and Q are true or both are false.

Ex: $\det(A) \neq 0 \iff A$ is invertible.

To prove “ $P \iff Q$ ”, need to prove “ $P \Rightarrow Q$ ” and “ $Q \Rightarrow P$ ”.

Note: $\neg P \Rightarrow \neg Q$ is the same as $Q \Rightarrow P$.

7.2 Subspaces (cont'd)

Thm (last class): Let $W \subseteq V$ (*subset*). If

1. For all $u, v \in W$, $u + v \in W$
2. For all $u \in W$, $c \in K$, $cu \in W$
3. $\vec{0} \in W$

then $W \leq V$ (*subspace*). (ie: (1), (2), (3) are true $\Rightarrow W \leq V$)

Thm. Let $W \subseteq V$. Then

$$W \leq V \Rightarrow (1), (2), (3) \text{ are true}$$

(ie the converse of last theorem is true).

Proof. Exercise.

Thm. Let $W \subseteq V$. Then

$$W \leq V \iff (1), (2), (3) \text{ are true}$$

7.3 Examples of subspaces and non-subspaces

Is each subset a subspace?

- (a) $W = \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix} \right\} \subseteq R^2$. Not a subspace, since the zero vector is not in W . The others are also false, but it's enough to prove that one of the statements does not hold. But $\text{span}(W) = R^2$ (so $\text{span}(W) \leq R^2$)

- (b) $W = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in R^3 \mid x + y - z = 0 \right\}$. Need to check (1), (2), (3):

- (1) Let $\begin{pmatrix} x \\ y \\ z \end{pmatrix}, \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} \in W$. Then we know $x + y - z = 0$ and $x' + y' - z' = 0$.

Check:

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} x + x' \\ y + y' \\ z + z' \end{pmatrix}$$

Verify

$$\begin{aligned}(x + x') + (y + y') - (z + z') &= (x + y - z) + (x' + y' - z') \\ &= 0 + 0 \\ &= 0\end{aligned}$$

So yes, it is in W .

(2) Let $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \in W$ (means $x + y - z = 0$), let $c \in K$. To prove

$$c \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} cx \\ cy \\ cz \end{pmatrix} \in W$$

Here, $cx + cy - cz = c(x + y - z) = c(0) = 0$. So $c \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in W$

(3) $\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \in W$, since $0 + 0 - 0 = 0$

Since (1), (2), (3) true, $W \leq R^2$ (subspace)

(c) $W = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in R^3 \mid x + y - z = 1 \right\}$. This is *not* a subspace. (3) is false.

(d) $W = \{A \in M_{2 \times 2} \mid A_{ij} \geq 0 \forall i, j\}$, where A_{ij} is the entry of A in row i , column j . (1) and (3) are true:

(1) Add two matrices with non-negatives entries, result has non-negative entries.

(2) $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \in W$

Note, we wrote these out very informally. Now, (2) is false since, for example $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \in W$ but

$$(-1) \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \notin W$$

7.4 Two special subspaces

Let V be a vector space.

(1) $V \leq V$ is true

(2) $\{\vec{0}\} \leq V$ is true ("zero subspace")

7.5 A refinement on the definition of span

Def. If $S = \emptyset$ (emptyset), define $\text{span}(S) = \{\vec{0}\}$ (if $S \neq \emptyset$, $\text{span}(S)$ defined as before).

Thm. $\text{span}(S) \leq V$.

Proof Two cases :

1. If $S = \emptyset$, $\text{span}(S) = \{\vec{0}\} \leq V$
2. If $S \neq \emptyset$, you already proved $\text{span}(S)$ satisfies (1), (2), (3).
So $\text{span}(S) \leq V$.

Thm. (improved version of subspace conditions) Let $W \subseteq V$. Then

$$W \leq V \iff W \neq \emptyset \text{ and } \forall w_1, w_2 \in W \text{ and } c \in K \text{ we have } cw_1 + w_2 \in W$$

Proof We will actually prove $(1), (2), (3) \iff RHS$ (right-hand side). Two parts to proof.

- (1) “(1), (2), (3) $\Rightarrow RHS$ ” or “ \Rightarrow ”

8 January 23rd 2019

Recap:

- (1) If $u, v \in W$ then $u + v \in W$
- (2) if $u \in W, c \in K$ then $cu \in W$
- (3) $\vec{0} \in W$

Theorem: Let $W \subseteq V$. Then

$$W \leq V \iff W \neq \emptyset \text{ and } \forall u, v \in W, c \in K \text{ we have } cu + v \in W$$

Proof: Suffices to prove $(1), (2), (3) \iff RHS$.

1. \Rightarrow Assume (1), (2), (3) (prove right-hand side). Two things to prove:
 - (1) Since $\vec{0} \in W$ (by (3)), $W \neq \emptyset$
 - (2) Let $u, v \in W$ and $c \in K$. Since (2) holds, $cu \in W$. Since (1) holds, $cu \in W$ and $v \in W$, so $cu + v \in W$.
2. \Leftarrow Assume RHS, prove (1), (2), (3).
 - (1) Let $u, v \in W$. Apply RHS with \Leftarrow to get

$$cu + v = 1u + v = u + v \in W$$

- (2) (Prove $\vec{0} \in W$) Since $W \neq \emptyset$, there is a vector $w \in W$. Apply right-hand side with $u = w, v = w, c = -1$. So $cu + v = (-1)w + w = -w + w = \vec{0} \in W$.
- (3) Let $u \in W, c \in K$. Apply RHS ($cu + v \in W$) with $u = u, c = c, v = \vec{0}$ (note: $\vec{0} \in W$ by (3) above). Then $cu + v = cu + \vec{0} = cu \in W$ \square

Ex: In $F(R, R) = V$ (functions $f : R \rightarrow R$), prove that

$$W = \{f \in V \mid f(3) = 0\}$$

is a subspace. Eg: $f(x) = (x - 3)e^x \in W$.

Solution: (1), (2) together (by last thm). Let $f, g \in W, c \in R$ (prove $cf + g \in W$). We know $f(3) = 0$ and $g(3) = 0$. Then, check $(cf + g)(3) = cf(3) + g(3) = 0 + 0 = 0$. So $cf + g \in W$.

Also, prove $W \neq \emptyset$. $f(x) = x - 3 \in W$, since $f(3) = 0$ (or, $z(3) = 0$ satisfies $z(3) = 0$ so $z \in W$. Note that z is the zero vector of $F(R, R)$).

Theorem: Let $A \in M_{m \times n}(K), b \in K^m$. Define

$$S = \{x \in K^n \mid Ax = b\}$$

ie S = solution set to linear system $Ax = b$. Then,

$$S \leq K^n \iff b = \vec{0} \text{ (ie system is homogeneous)}$$

Proof

- (i) \Rightarrow Assume $S \leq K^n$. Then $\vec{0}_n \in S$ (by (3)). So $A\vec{0} = b$ but $A\vec{0}_n = \vec{0}_m$ so $\vec{0} = b$.
- (ii) \Leftarrow Assume $b = \vec{0}_m$ (prove $S \leq K^n$). Then $A\vec{0}_n = \vec{0}_m$, so $\vec{0}_n \in S$. Next, let $u, v \in S, c \in K$. So $u, v \in K^n$ and $Au = b, Av = b$. Verify $cu + v$ is a solution.

$$\begin{aligned} A(cu + v) &= A(cu) + Av && \text{(prop of matrix multiplication)} \\ &= c(Au) + Av && \text{(prop of matrix multiplication)} \\ &= cb + b \\ &= c\vec{0} + \vec{0} \\ &= \vec{0} \\ &= b \quad \square \end{aligned}$$

Ex: Equation $ax + by + cz = d$ describes a plane in R^3 (eg $x + y + z = 1$) (and also, every plane can be described this way). That is,

$$\{(x, y, z) \in R^3 \mid ax + by + cz = d\}$$

is a plane.

By last thm,

$$\begin{aligned}
 P \text{ is a subspace} &\iff ax + by + cz = d \text{ is a homogeneous system} \\
 &\iff d = 0 \\
 &\iff P \text{ passes through origin } (0, 0, 0)
 \end{aligned}$$

Theorem: Let $S \subseteq V$. Then,

- (1) $\text{span}(S) \leq V$ and $S \subseteq \text{span}(S)$
- (2) If $S \subseteq W$, and $W \leq V$ (subspace) then $\text{span}(S) \subseteq W$ (actually, $\text{span}(S) \leq W$, subspace by (1))

Proof:

- (1) \leq We know already. Let $u \in S$. Then $u = 1u$, so $u \in \text{span}(S)$
- (2) Assume $S \subseteq W$, and $W \leq V$. Let $v \in \text{span}(S)$. Then $v = a_1u_1 + a_2u_2 + \dots + a_nu_n$ for some scalars and vectors $u_1, u_2, \dots, u_n \in S$. Since $S \subseteq W$, $u_1, u_2, \dots, u_n \in W$. But W subspace. So $a_1u_1, a_2u_2, \dots, a_nu_n \in W$ (by prop (2) subspace) then $a_1u_1 + a_2u_2 \in W$ (by prop (1) of subspaces). So then $(a_1u_1 + a_2u_2) + a_3u_3 \in W$ (etc). So $a_1u_1 + a_2u_2 + \dots + a_nu_n \in W$. **Note:** "etc" here is actually a proof by mathematical induction. Omit for now.

9 January 25th 2019

9.1 Interlude : Symbolic logic (briefly)

Let P, Q be statements that could be true (T) or false (F). Define:

- (1) $\neg P$, "not P ", is F when P is T , T when P is F
- (2) $P \wedge Q$, " P and Q ", is T exactly when P, Q both T
- (3) $P \vee Q$, " P or Q " is T when P, Q both F
- (4) $P \Rightarrow Q$, " P implies Q ", is T *unless* P is T and Q is F . Hence, $P \Rightarrow Q$ is *equivalent to* $\neg P \vee Q$. We will write $P \Rightarrow Q \equiv \neg P \vee Q$.
- (5) $P \iff Q$, " P if and only if Q ", is T if both T or both F .

9.1.1 De Morgan's Laws

- $\neg(P \wedge Q) \equiv \neg P \vee \neg Q$
- $\neg(P \vee Q) \equiv \neg P \wedge \neg Q$

9.1.2 Quantifiers

- \forall means "for all"
- \exists means "there exists"

Ex. (A4) (commutativity) $\forall u, v \in V \quad u + v = v + u$.

Ex. 2 (A2) (zero vector) $\exists z \in V \quad \forall u \in V \quad (u + z = u) \wedge (z + u = u)$ (textbook version)

9.1.3 Negating quantifiers

- $\neg \forall u \in V P(u) \equiv \exists u \in V \neg P(u)$
- $\neg \exists u \in V P(u) \equiv \forall u \in V \neg P(u)$

Ex.

$$\begin{aligned} \neg(A2) &\equiv \neg \exists z \in V \forall u \in V \quad u + z = u \wedge z + u = u \\ &\equiv \forall z \in V \neg \forall u \in V \quad u + z = u \wedge z + u = u \\ &\equiv \forall z \in V \exists u \in V \quad \neg(u + z = u \wedge z + u = u) \\ &\equiv \forall z \in V \exists u \in V \quad (u + z \neq u \vee z + u \neq u) \end{aligned}$$

9.1.4 Proof by contradiction

You want to prove some statement P . Proof by contradiction works this way:

- (1) Assume $\neg P$
- (2) Derive a contradiction (hard part)
- (3) Conclude P is true

Ex. Outline of how to prove (A2) *does not hold* in some vector space. You want to prove $\neg(A2)$.

$$\begin{aligned} \neg(A2) &\equiv \neg \exists z \in V \forall u \in V \quad u + z = u \wedge z + u = u \\ &\equiv \forall z \in V \neg \forall u \in V \quad u + z = u \wedge z + u = u \end{aligned}$$

Let $z \in V$. Prove the right-hand part ($\neg \forall u \in V \quad u + z = u \wedge z + u = u$) by contradiction. Assume (for contradiction) that

$$\forall u \in V \quad u + z = u \wedge z + u = u \tag{1}$$

Use (1) by substituting $u =$ some specific vector (derive a contradiction). Conclude that ($\neg \forall u \in V \quad u + z = u \wedge z + u = u$) is true.

9.2 Last time

Thm. If $S \subseteq W$, $W \leq V$ then $\text{span}(S) \subseteq W$.

Note. This means if you "promote" a subset to a subspace, adding in only what's necessary, what you get is $\text{span}(S)$. Or, $\text{span}(S)$ is the "smallest" subspace containing S .

Fact. Subspaces are "closed under taking linear combinations". Ie if $W \leq V$, $w_1, \dots, w_n \in W$ and $a_1, \dots, a_n \in K$ then

$$a_1 w_1 + a_2 w_2 + \dots + a_n w_n \in W$$

Caution. Linear combinations are *finite* sums by definition. So you can't sum up infinitely many vectors.

9.3 Illustration of this theorem

Let $S = \left\{ \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 4 \\ 0 \end{pmatrix} \right\} \subseteq W = \left\{ \begin{pmatrix} x \\ y \\ 0 \end{pmatrix} \mid x, y \in R \right\}$. Then $\text{span}(S) \subseteq W$ ie $\text{span}(S)$ is in xy plan. In fact, $\text{span}(S) = W$.

Def. If $W = \text{span}(S)$, we say that S spans W or is a spanning set for W .

Ex. $S = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$, $\text{span}(S) = xy\text{-plane in } R^3$. So S spans the xy -plane.

Ex. 2. $S = \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \right\}$, $\text{span}(S) = \left\{ \begin{pmatrix} x \\ x \\ 0 \end{pmatrix} \mid x \in R \right\} = \text{line}$.

9.4 Intersection of two subspaces

Theorem Let $W_1 \leq V, W_2 \leq V$. Then $W_1 \cap W_2 \leq V$ (ie intersection of two subspaces is a subspace).

Proof. $W_1 \cap W_2 = \{w \in V \mid w \in W_1 \wedge w \in W_2\}$.

- (1) $\vec{0} \in W_1, \vec{0} \in W_2$ (because subspace). So $\vec{0} \in W_1 \cap W_2$.
- (2) Let $u, v \in W_1 \cap W_2, c \in K$. So $u, v \in W_1$ and $W_1 \leq V$ so $cu + v \in W_1$ and $u, v \in W_2$ and $W_2 \leq V$ so $cu + v \in W_2$. Hence $cu + v \in W_1 \cap W_2$. \square

10 January 28th 2019

Last time: $W_1 \leq V$ and $W_2 \leq V \Rightarrow W_1 \cap W_2 \leq V$.

Corollary: The intersection of any number of subspaces is a subspace.

Problem. Prove that $W = \{f : \mathbb{R} \rightarrow \mathbb{R} \mid f(1) = 0 \wedge f(2) = 0\}$ is a subspace of $F(\mathbb{R}, \mathbb{R})$.

Sol #1: Directly from subspace properties (omit)

Sol #2: We saw an example proving that $\{f : \mathbb{R} \rightarrow \mathbb{R} | f(3) = 0\}$ is a subspace. The "3" is not important, so similarly:

$$\begin{aligned}W_1 &= \{f : \mathbb{R} \rightarrow \mathbb{R} | f(1) = 0\} \\W_2 &= \{f : \mathbb{R} \rightarrow \mathbb{R} | f(2) = 0\}\end{aligned}$$

both subspaces of $F(\mathbb{R}, \mathbb{R})$. Then $W_1 \cap W_2 = \{f : \mathbb{R} \rightarrow \mathbb{R} | f(1) = 0 \wedge f(2) = 0\}$ is a subspace.

Q: Is union of two subspaces also a subspace?

A: Not in general.

Eg: $W_1 = \text{x-axis} = \left\{ \begin{pmatrix} x \\ 0 \end{pmatrix} | x \in \mathbb{R} \right\} \leq \mathbb{R}^2$

$W_2 = \text{y-axis} = \left\{ \begin{pmatrix} 0 \\ y \end{pmatrix} | y \in \mathbb{R} \right\} \leq \mathbb{R}^2$

$W_1 \cup W_2 = \text{xy-axis} = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} | x = 0 \vee y = 0 \right\}$, which, importantly, is not \mathbb{R}^2 . *Not* a subspace, since $\begin{pmatrix} 1 \\ 0 \end{pmatrix} \in W_1 \cup W_2$, $\begin{pmatrix} 0 \\ 1 \end{pmatrix} \in W_1 \cup W_2$, but $\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \notin W_1 \cup W_2$.

Note: To promote $W_1 \cup W_2$ to a subspace, you form $\text{span}(W_1 \cup W_2)$.

Def: Let $W_1 \leq V$ and $W_2 \leq V$. The *sum* of W_1 and W_2 is

$$W_1 + W_2 = \{v \in V | \exists w_1 \in W_1, w_2 \in W_2, \text{ such that } v = w_1 + w_2\}$$

Ex:

$$\begin{aligned}W_1 &= \{ax^2 | a \in \mathbb{R}\} \leq P(\mathbb{R}) \\W_2 &= \{ax | a \in \mathbb{R}\} \leq P(\mathbb{R})\end{aligned}$$

We have,

$$W_1 + W_2 = \{ax^2 + bx | a, b \in \mathbb{R}\}$$

Theorem: Let $W_1 \leq V$, $W_2 \leq V$. Then

- (a) $W_1 + W_2 = \text{span}(W_1 \cup W_2)$ (hence $W_1 + W_2$ is a subspace)
- (b) $W_1 \leq W_1 + W_2$, $W_2 \leq W_1 + W_2$

Proof:

- (a) (1) Prove $W_1 + W_2 \subseteq \text{span}(W_1 \cup W_2)$. Let $v \in W_1 + W_2$, so $v = w_1 + w_2$ where $w_1 \in W_1$ and $w_2 \in W_2$. Then $w_1, w_2 \in W_1 \cup W_2$ so $v \in \text{span}(W_1 \cup W_2)$
- (2) " \supseteq ". Let $v \in \text{span}(W_1 \cup W_2)$. Means $v = a_1 u_1 + a_2 u_2 + \dots + a_n u_n$, $u_1, u_2, \dots, u_n \in W_1 \cup W_2$ and $a_1, a_2, \dots, a_n \in K$. Each u_i is in $W_1 \cup W_2$. Separate into two groups and relabel, so that:

- Those in W_1 , call these

$$u_1, u_2, \dots, u_l$$

So $0 \leq l \leq n$, $l = 0$ means *none* in W_1 .

- Those in $W_2 \setminus W_1 = \{w \in W_2 | w \notin W_1\}$ ("set difference"), call these

$$u_{l+1}, \dots, u_n$$

So $l = 0$ means all in $W_2 \setminus W_1$, $l = n$ means all in W_1 .

Then, let $w_1 = a_1u_1 + a_2u_2 + \dots + a_lu_l$ (or $w_1 = \vec{0}$ if $l = 0$), $w_2 = a_{l+1}u_{l+1} + \dots + a_nu_n$ (or $w_2 = \vec{0}$ if $l = n$).

Then $w_1 \in W_1$ since W_1 is a subspace, similarly $w_2 \in W_2$. So

$$\begin{aligned} v &= a_1u_1 + \dots + a_nu_n \\ &= w_1 + w_2 \in W_1 + W_2 \text{ as required} \end{aligned}$$

(b) $W_1 \leq W_1 + W_2$, $W_2 \leq W_1 + W_2$. Follows from (a), since $S \subseteq \text{span}(S)$ \square .

10.1 Linear independence

Def: Vectors $u_1, u_2, \dots, u_n \in V$ (all distinct) are said to be *linearly dependent* if \exists scalars $a_1, a_2, \dots, a_n \in K$ *not all 0* such that

$$a_1u_1 + a_2u_2 + \dots + a_nu_n = \vec{0}$$

Above equation called a *dependence relation*.

Note: If $a_1u_1 + a_2u_2 + \dots + a_nu_n = \vec{0}$ and $a_1 \neq 0$, then you can solve for u_1 :

$$u_1 = \frac{-a_2}{a_1}u_2 - \frac{a_3}{a_1}u_3 - \dots - \frac{a_n}{a_1}u_n$$

ie u_1 = linear combination of others, "depends on" others.

Ex: $\{x^2 + x, 2x^2, \frac{x}{10}\}$ is a dependent set of vectors in $P(\mathbb{R})$ since

$$(x^2 + x) - \frac{1}{2}(2x^2) - 10(\frac{x}{10}) = 0$$

Def: A set of vectors $S \subseteq V$ (possibly infinite) is dependent if \exists a finite subset $\{v_1, v_2, \dots, v_n\} \subseteq S$ of it which is dependent.

Def: Vectors v_1, v_2, \dots, v_n are linearly independent if they are *not* dependent. That is,

$$\begin{aligned} \neg \exists a_1, \dots, a_n \in K \quad (a_1u_1 + \dots + a_nu_n = \vec{0} \wedge \neg(a_1 = 0 \wedge a_2 = 0 \wedge \dots \wedge a_n = 0)) \\ \forall a_1, \dots, a_n \in K \quad \neg(a_1u_1 + \dots + a_nu_n = \vec{0} \wedge \neg(a_1 = 0 \wedge a_2 = 0 \wedge \dots \wedge a_n = 0)) \\ \forall a_1, \dots, a_n \in K \quad (\neg(a_1u_1 + \dots + a_nu_n = \vec{0}) \vee (a_1 = 0 \wedge a_2 = 0 \wedge \dots \wedge a_n = 0)) \end{aligned}$$

Note that $P \implies Q \equiv \neg P \vee Q$. In other words, u_1, u_2, \dots, u_n are linearly independent if

$$\forall a_1, \dots, a_n \in K (a_1 u_1 + \dots + a_n u_n = \vec{0} \implies a_1 = 0 \wedge \dots \wedge a_n = 0)$$

Which is to say that the only solution to $a_1 u_1 + \dots + a_n u_n = \vec{0}$ is the trivial solution $a_1 = 0, a_2 = 0, \dots, a_n = 0$.

11 January 30th 2019

11.1 Last class

v_1, v_2, \dots, v_n *independent* if $x_1 v_1 + \dots + x_n v_n = \vec{0}$ has only trivial solution $x_1 = x_2 = \dots = x_n = 0$.

Ex: Prove that $\{1 + x^2, x + x^2, 1 + x + x^2\}$ is independent.

Solution: Consider equation

$$a(1 + x^2) + b(x + x^2) + c(1 + x + x^2) = 0 = 0(1) + 0x + 0x^2$$

Want to show $a = b = c = 0$ is the only solution.

Equation means for all $x \in K$ (\mathbb{R} or \mathbb{C}),

$$a(1 + x^2) + b(x + x^2) + c(1 + x + x^2) = 0$$

So, substitute any scalar for x :

$$x = 0 \quad a + c = 0$$

$$x = 1 \quad 2a + 2b + 2c = 0$$

$$x = -1 \quad 2a + 0b + c = 0$$

Can translate into linear system:

$$\begin{pmatrix} 1 & 0 & 1 & 0 \\ 2 & 2 & 3 & 0 \\ 2 & 0 & 1 & 0 \end{pmatrix}$$

Row-reduce:

$$\begin{pmatrix} 1 & 0 & 1 & 0 \\ 2 & 2 & 3 & 0 \\ 2 & 0 & 1 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & -1 & 0 \end{pmatrix} \\ \rightarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

Only solution is $a = 0, b = 0, c = 0$ so vectors are independent. If we obtain infinitely many, then you can find dependent set so dependent.

11.2 Some important cases

- (i) $S = \emptyset$ is linearly independent since there are no vectors with which to form a dep. relation.
- (ii) If $\vec{0} \in S$, then dependent (since $1\vec{0} = \vec{0}$ is a dep. relation)
- (iii) $\{u\}$ is independent $\iff u \neq \vec{0}$.
Note: $u + (-1)u = \vec{0}$ is *not* a dep. relation, since u is repeated. But, $\{u, -u\}$ is dependent since

$$u + (-u) = \vec{0}$$

is a dep. relation.

Proposition: Let $A, B \subseteq V$ where $A \subseteq B$.

- (i) If A is dependent, B is also dependent
- (ii) If B is independent, A is also independent (contrapositive)

Proof:

- (i) If A dep, we have a dep relation

$$a_1v_1 + a_2v_2 + \dots + a_nv_n = \vec{0} \quad (\text{not all scalars } 0, v_1, \dots, v_n \in A)$$

which is also a dependence relation in B since $v_1, \dots, v_n \in B$.

- (ii) This is the contrapositive of (i). \square

Note: Converse is false, $B \text{ dep} \not\rightarrow A \text{ dep}$.

11.3 Extending an independent set

Theorem: Let $S \subseteq V$ be linearly independent and suppose $u \notin S$. Then, $S \cup \{u\}$ independent $\iff u \notin \text{span}(S)$.

Proof:

- (i) “ \rightarrow ” We will prove this as the contrapositive, ie $u \in \text{span}(S) \rightarrow \text{dep}$. Assume $u \in \text{span}(S)$. So,

$$\begin{aligned} u &= a_1v_1 + \dots + a_nv_n \quad \text{where } v_1, v_2, \dots, v_n \in S \\ \vec{0} &= (-1)u + a_1v_1 + \dots + a_nv_n \end{aligned}$$

Which is a linear combination of vectors from $S \cup \{u\}$, not all coefficients 0 since first is -1 . Also, the vectors u, v_1, v_2, \dots, v_n are all distinct, since $u \notin S$. So this is a dependence relation on $S \cup \{u\}$, so the set is dependent.

- (ii) “ \leftarrow ” Also by contrapositive. Assume $S \cup \{u\}$ dep, want to show that $u \in \text{span}(S)$. So there is a dependence relation on $S \cup \{u\}$. Two cases:

- **Case 1:** Dependence relation does not involve u (or, involves u but with coefficient 0), ie we have

$$a_1v_1 + \dots + a_nv_n = \vec{0} \quad (\text{not all scalars } 0, v_1, \dots, v_n \in S)$$

But this contradicts independence of S , so case 1 does not occur.

- **Case 2:** Dependence relation involves u (with coeff *not* 0), so

$$au + a_1v_1 + \dots + a_nv_n = \vec{0} \quad v_1, \dots, v_n \in S$$

and $a \neq 0$. Rewrite:

$$u = \frac{-a_1}{a}v_1 - \frac{a_2}{a}v_2 - \dots - \frac{a_n}{a}v_n \quad (a \neq 0)$$

Hence $u \in \text{span}(S)$. \square

Note: Conclusion can be restated as

$$S \cup \{u\} \text{ dependent} \iff u \in \text{span}(S)$$

11.4 Basis and dimension

Fact: If W is subspace, then $\text{span}(W) = W$. (Exercise)

So every subspace *is* a span. But thinking of W as $\text{span}(W)$ is excessive. Would like to find the *smallest* S such that

$$\text{span}(S) = W$$

Def: Let $W \leq V$. A *basis* of W is a set $B \subseteq W$ such that

- $\text{span}(B) = W$ (“enough vectors to produce W ”)
- B is linearly independent (“no extra vectors in B ”)

Examples:

$$(i) \text{ Let } e_i = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \leftarrow (\text{row } i) . \text{ Then,}$$

$$\{e_1, e_2, \dots, e_n\}$$

is a basis for K^n . For example,

$$\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

is a basis for K^3 .

More next class.