# **CS324 - Large Language Models**

**Modeling, Training** 

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## Overview

## Modeling

- Tokenization: how a string is split into tokens
- Models: focus on the **Transformer** architecture, which is the key innovation that enabled large language models(LLMs).

## Training

- Objective functions
- BERT, T5, BART
- Optimization algorithms

## **Tokenization**

- Language models: Predict probabilities over token sequences.
- Natural language: Exists as strings of characters(e.g., the mouse ate the cheese)
- Tokenizer: Converts strings into token sequences.(e.g., [the, mouse, ate, the, cheese])
- →Importance: Tokenization significantly affects model performances.

- Tokenization methods:
  - Split by spaces
  - Byte pair encoding
  - Unigram model(SentencePiece)

# Tokenization - Split by spaces

- Simple tokenization: Splitting by spaces is insufficient for many languages
  - ex: Chinese, German, English(e.g., don't)
- Challenges with space-based splitting:
  - Doesn't account for linguistic nuances or complex word structures.
  - Requires more sophisticated tokenization methods.
- Good tokenization criteria:
  - Avoid too many tokens(e.g., characters or bytes).
  - Avoid too few tokens to ensure parameter sharing (e.g., similar structures like mother-in-law and father-in-law).
  - Tokens should represent meaningful linguistic or statistical units.

# Tokenization – Byte pair encoding(BPE)

### Key Idea

- Derived from data compression to tokenize text.
- Iteratively merges frequently co-occurring tokens.

#### Methods

- Input: Training corpus(character sequences).
- Initialize vocabulary with characters.
- Merge most frequent token pairs until desired vocabulary size.

# Tokenization – Byte pair encoding(BPE)

### Example

- Input: [t, h, e, \_, c, a, r], [t, h, e, \_, c, a, t], [t, h, e, \_, r, a, t]
- Merges: t, h  $\rightarrow$  th, th, e  $\rightarrow$  the, c, a  $\rightarrow$  ca
- Final Vocabulary: [a, c, e, h, t, r, ca, th, the]

## Unicode Challenge

- Vast Unicode space(144,697 characters).
- Solution: Run BPE on bytes to handle unseen characters.
- Example: "今天" → [x62, x11, 4e, ca].

# Tokenization – Unigram model(SentencePiece)

## • Key Idea:

- Tokenization T divides a sequences  $x_{1:L}$  into token spans.
- Likelihood:  $p(x_{1:L}) = \prod_{(i,j) \in T} P(x_{i:j})$

### • Example:

- Training string: a,ba,bc
- Tokenization:  $T = \{(1,2), (3,4), (5,5)\}, V = \{ab, c\}$
- Likelihood:  $p(x_{1:L}) = \frac{2}{3} \cdot \frac{2}{3} \cdot \frac{1}{3} = \frac{4}{9}$

# Tokenization – Unigram model(SentencePiece)

### Algorithm Steps:

- Start with a large seed vocabulary V.
- Iteratively optimize:
  - Optimize p(x) and T using the EM algorithm.
  - Compute loss(x) for each token  $x \in V$ :
  - Measure likelihood reduction if x is removed.
  - Sort tokens by loss and keep the top 80%.

#### Advantages:

- More structured and statistically principled compared to frequency-based methods.
- Allows for dynamic refinement of the token vocabulary.

# Models

#### Language Models:

- Represent sequences as probabilities  $(p(x_1, ..., x_L))$ .
- Versatile but inefficient for some tasks when modeling full sequences.

## Contextual Embeddings:

- Map token sequences to embeddings influenced by surrounding context.
- Example: [the, mouse, ate, the, cheese]  $\rightarrow \phi[(1, 0.1), (0, 1), (1, 1), (1, -0.1), (0, -1)].$

#### Core Idea:

- Embedding adapt based on the token's position and nearby words.
- Captures meaning dynamically for more task-specific efficiency.

# Models – Types of language models: Encoder-only

## • Encoder-only models:

- Examples: BERT, RoBERTa, etc.
- Generate contextual embeddings.
- Used primarily for classification tasks (e.g., sentiment analysis, natural language inference).

## Advantages:

Contextual embeddings account for bidirectional context(left and right).

#### • Limitations:

- Can not generate text or completions naturally.
- Require ad-hoc training objectives(e.g., masked language modeling).

# Models – Types of language models: Decoder-only

#### Decoder-only models:

- Examples: GPT-2, GPT-3, etc.
- Operate autoregressively: given a prompt  $x_{1:i}$ , they provide
  - Contextual embeddings  $\phi(x_{1:i})$
  - Next-token distribution  $p(x_{i+1}|x_{1:i})$
- Enables text generation (e.g., autocomplete).

### Advantages:

- Naturally generate completions.
- Simple training objective: maximum likelihood.

#### • Limitation:

• Contextual embeddings for each token only use unidirectional (left-to-right) context.

# Models – Types of language models : Encoder-Decoder

#### Encoder-Decoder models:

- Examples: BART, T5, etc.
- Encoder produces bidirectional contextual embeddings from input  $x_{1:L}(\phi(x_{1:L}))$ .
- Decoder generates output  $y_{1:L}$  conditioned on those embeddings  $(p(y_{1:L}|\phi(x_{1:L})))$ .

## Advantages:

- Bidirectional context in the encoder for richer embeddings.
- Natural text generation from the decoder.

#### Limitation

Requires more complex training objectives(e.g., denoising or other recontruction tasks).

## Models - Architecture

- Token-to-Vector Conversion
  - EmbedToken: Maps each token  $x_i$  to a vector using an embedding matrix  $E \in \mathbb{R}^{[V] \times d}$ .
  - Output: A sequence of context-independent embeddings  $[Ex_1, ..., Ex_L]$ .
- Abstract SequenceModel
  - Transforms context-independent embeddings into contextual embeddings.
  - Examples of specific implements include:
    - FeedForwardSequenceModel, SequenceRNN, TransformerBlock

# Models - Architecture

- FeedForwardSequenceModel
  - Uses a fixed-length context(like an n-gram model).
  - For each position *i* in [1, ..., L]:
    - 1. Collect the last n embeddings:  $(x_{i-n+1}, ..., x_i)$ .
    - 2. Apply a feedforward network to produce  $h_i$ .
  - Returns the updated sequence  $[h_1, ..., h_L]$ .

# Models – Recurrent Neural Networks

#### SequenceRNN:

- Processes sequences from  $x_1$  to  $x_L$  recursively to compute vectors  $h_1$  to  $h_L$ .
- Updates hidden states:  $h_i = RNN(h_{i-1}, x_i)$ .

## RNN Module Functionality

- Takes the current state h and a new observation x, returning an updated state.
- Implementations include SimpleRNN, LSTM, and GRU.

## SimpleRNN

Updates the hidden state h by applying a linear transformation followed by a non-linear function(e. g., logistic or ReLU).

# Models – Recurrent Neural Networks

#### Bidirectional RNN

- Enhances sequence processing by running RNNs in both forward and reverse directions.
- Combine forward and backward states to capture dependencies from both past and future context.

## Challenges and Advancements

- Simple RNNs are difficult to train due to vanishing gradients.
- LSTM and GRU were developed to better capture long-term dependencies and mitigate training issues.
- Despite potential, practical dependencies on distant tokens may not be robust
- LSTMs significantly advanced deep learning's impact in NLP.

#### Overview & Context

- Transformers power major NLP models (GPT, BERT, T5).
- Core mechanism: attention, originally used in machine translation.

#### Attention Mechanism

• Concept: A "soft" lookup for matching a query y against key-value pairs from each token  $x_i$ .

- Implementation:
  - 1. Transform  $x_i$  into keys  $(W_{key}x_i)$  and values  $(W_{value}x_i)$ .
  - 2. Transform y into a query ( $W_{query}y$ ).
  - 3. Compute scores (dot products of query and keys).
  - 4. Normalize scores with softmax to form weights  $\alpha_i$ .
  - 5. Weighted sum of the values yields the attention output.
- Multi-Headed Attention: Multiple parallel attention heads capture different "aspects".

#### Self-Attention

- Each token  $x_i$  serves as the query y when comparing with every other token in the sequence.
- Produces a contextualized vector for each position that reflects all other positions in the sequence.

## Feedforward Layer

- Applies a simple, per-token transformation:  $y_i = W_2 \max(0, W_1 x_i + b_1) + b_2$ .
- Complements self-attention by introducing additional nonlinear processing.

- Improving Trainability
  - Residual Connections: Add the original input back to the function output (x + f(x)) to ensure grad ients can flow even if f becomes difficult to train.
  - Layer Normalization: Normalizes each token's embedding to avoid overly large or small values.
  - AddNorm encapsulates residual addition plus layer norm.
  - Stacking multiple TransformerBlocks leads to large-scale models (e.g., GPT-3).

## Positional Embeddings

- Transformers lack inherent sequence order; positional embeddings inject location information.
- Common approach uses sinusoidal functions sin for even dimensions, cos for odd).
- Result: each token embedding is enriched with its positional signal in the sequence.

### Key Takeaways

- Attention is the centerpiece, enabling global context capture.
- Residual/LayerNorm ensure deep stacking is feasible.
- Positional Encodings provide ordering cues in an otherwise order-agnostic architecture.
- Transformers' flexibility and scalability underpin modern large language models.

# Models – GPT-3

- GPT-3 Architecture
  - $GPT 3(x_{1:L}) = TransformerBlock^{96}(EmbedTokenWithPosition(x_{1:L}))$
- Variants in Transformer Implementations
  - 1. Layer Normalization: "Post-norm" (original Transformer) vs. "pre-norm" (GPT-2), affecting training s tability.
  - 2. Dropout: Applied throughout to mitigate overfitting.
  - 3. Sparse Transformer (GPT-3):Interleaves sparse and dense layers to reduce parameters.
  - 4. Masking Schemes: Differ among encoder-only, decoder-only, and encoder-decoder models.

# Objective functions

- Decoder-Only (GPT-Style)
  - Autoregressive LM:  $p(x_i|x_{1:i-1})$
  - Training Objective: Maximum Likelihood (NLL)
- Encoder-Only (BERT-Style)
  - Bidirectional embeddings (no need to generate text).
  - Masked Language Modeling (MLM):
    - Randomly mask ~15% of tokens, predict them from context.
    - Use partial replacement with real words to avoid test-train mismatch.
  - Next Sentence Prediction (NSP):
    - Predict whether the second sentence truly follows the first.

# Objective functions

- Encoder-Decoder (T5 / BART-Style)
  - Bidirectional encoder (like BERT) + autoregressive decoder (like GPT).
  - Often trained with denoising tasks (e.g., masked spans, permuted sentences).

## **BERT**

- Architecture: 24 Transformer layers,  $d_{model}$ =1024, 16 attention heads( $\approx$ 355M params)
- Key Tokens:
  - [CLS] for classification embedding.
  - [SEP] to divide sequences.
- Improvements (RoBERTa):
  - Removed NSP, used more data (160GB), trained longer → better benchmarks.

# **T5 & BART**

- T5 (Text-to-Text)
  - Everything cast as text-to-text (including classification).
  - Trained on replacing masked spans → "i.i.d. noise."
  - Large version ~11B parameters.

#### BART

- RoBERTa-like encoder, GPT-like decoder.
- Denosing tasks (mask 30% tokens, permute sentences).
- Strong on both classification & generation.

# Optimization

- Core Objective:
  - $O(\theta) = \sum_{x \in D} -log p_{\theta}(x)$
- Adam Optimizer
  - Momentum + Adaptive Learning Rates.
  - Increases memory from storing  $(m_t, v_t)$ .
  - AdaFactor reduces memory usage by storing row/column stats instead of full moments.

# Optimization

- Mixed-Precision Training (FP16)
  - Master weights in FP32, everything else in FP16.
  - Loss scaling to avoid underflow.
- Learning Rate Schedules
  - Warmup then decay (common in Transformers).
  - Cosine decay, etc.
- Initialization Tricks
  - Xavier for most layers.
  - Additional scaling (e.g.,  $1/\sqrt{N}$  for GPT, or  $1/\sqrt{d}$  for T5 attention matrices).