

DISCRETE MORSE THEORY AND APPLICATIONS IN TDA

Sushovan “Sush” MAJHI

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I am a **fifth year** Math PhD student at Tulane University.

Thesis Advisor:

Carola Wenk, Computer Science, Tulane University

My Collaborators:

Rafal Komendarczyk, Mathematics, Tulane University

Brittany Terese Fasy, Computer Science, Montana State University

Yusu Wang, Computer Science, Ohio State University

WHAT IS TDA?

TDA is a subfield of applied mathematics. Topological tools and techniques are used to **Simplify**, **Analyze** and **Visualize** data.

TOPOLOGICAL DATA ANALYSIS (TDA)

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WHAT TOOLS ARE USED?

Simplicial Homology, Simple Homotopy Theory, Persistent Homology, Metric Geometry, Morse Theory etc.

data (dictionary.cambridge.org)

noun (U, sing/pl verb) • US /deɪ.tə/

information, especially facts or numbers, collected to be examined and considered and used to help decision-making, or information in an electronic form that can be stored and used by a computer.

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information, especially facts or numbers, collected to be examined and considered and used to help decision-making, or information in an electronic form that can be stored and used by a computer.

Data is an incomplete and **discrete** projection (sample) of a rather **continuous** object of interest.

UNIVERSAL TRUTH ABOUT DATA

- 1 full of noise/error/outliers
- 2 incomplete
- 3 high-dimensional

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Still we trust our data!



FIGURE: Joke from bigdata-madesimple.com

Extract info about the continuous object being sampled.

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- 1 Statistical Data Analysis (using hyperplanes, hypersurfaces, PDEs etc.)
- 2 Smooth Interpolation
- 3 Fractal Interpolation

WHY TDA?

Some data are very geometric in nature e.g. medical images, 3D printing.

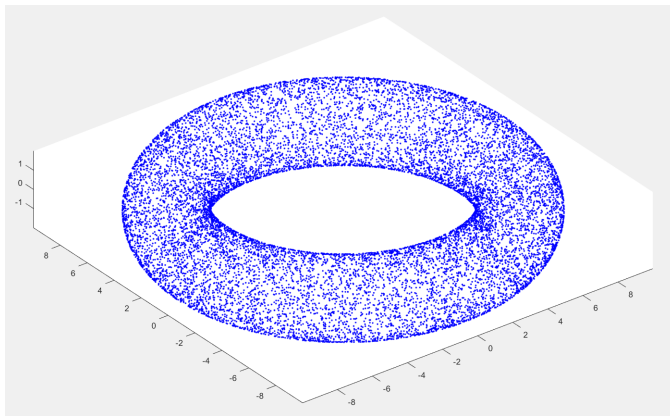


FIGURE: A sample from an embedded Torus (Matlab[®])

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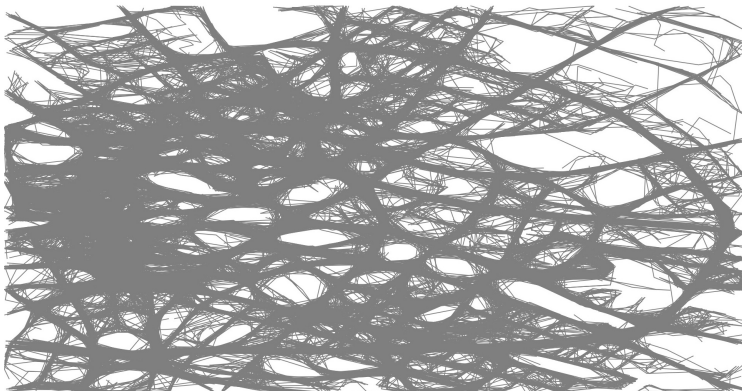


FIGURE: GPS traces of Berlin, Germany (www.mapconstruction.org)

WHY TDA?

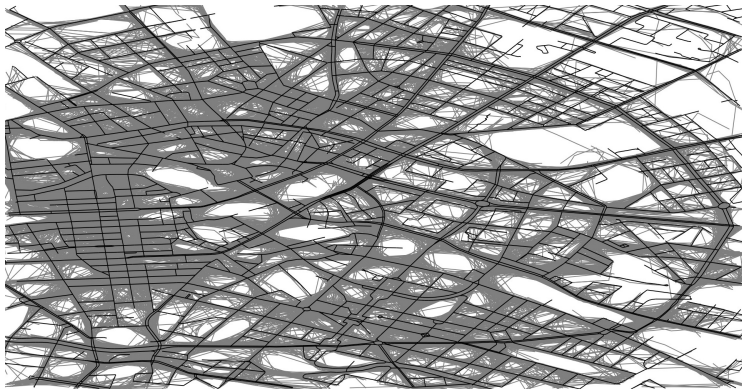


FIGURE: A possible reconstruction of road-network (www.mapconstruction.org)

PROBLEM OF MAP RECONSTRUCTION

APPLIED MATH IS ALSO CHALLENGING!

A real-world problem does not directly inform us about the math behind it.

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GPS traces \rightarrow road-network

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OUR PROBLEM

GPS traces \rightarrow road-network

EXPECTATIONS

- 1 The output is homotopy equivalent to the actual road-network i.e. **same homology, homotopy groups**.
- 2 output has a very small Hausdorff distance to the ground truth i.e. **close geometric features as well**.

OUR FIRST APPROACH

TOOLS USED

Metric Geometry (geodesic space, Gromov distortion, convexity radius)

Algebraic Topology (Cech and Vietoris-Rips complexes, Simplicial Homology, Simplicial Shadow).

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THEOREM (SUBMITTED TO SOCG'19)

Let X be a compact subset of \mathbb{R}^N with a positive convexity radius ρ and finite distortion δ . And, let $S \subseteq \mathbb{R}^n$ such that $d_H(S, X) < \epsilon < \frac{\rho}{4\delta(2\delta+1)}$. Then, for any non-negative integer k , $H_k(X)$ is isomorphic to the image of the homomorphism induced by the following simplicial inclusion map

$$j : \mathcal{C}_\epsilon(S) \rightarrow \mathcal{C}_{(4\delta+1)\epsilon}(S).$$

THE SHORTCOMINGS

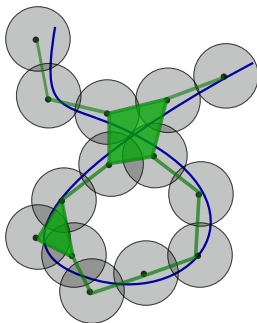


FIGURE: Reconstruction of a planar graph

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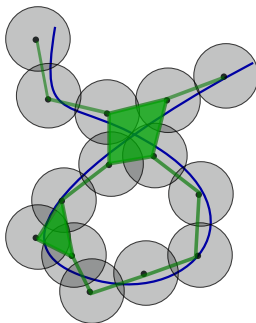


FIGURE: Reconstruction of a planar graph

- 1 the output (green) does not look like a graph
- 2 the method does not like outliers

MOTIVATION

A reasonably “good” smooth function reveals the **Combinatorial Description** of a smooth manifold.

CLASSICAL MORSE THEORY

Let M^n be a smooth manifold and $f : M \rightarrow \mathbb{R}$ be a smooth function.

CRITICAL POINT

A point $p \in M$ is called a **critical point** of f if $Df = 0$.

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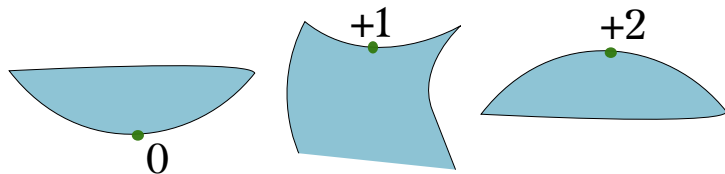


FIGURE: critical points with index

CLASSICAL MORSE THEORY

MORSE FUNCTION

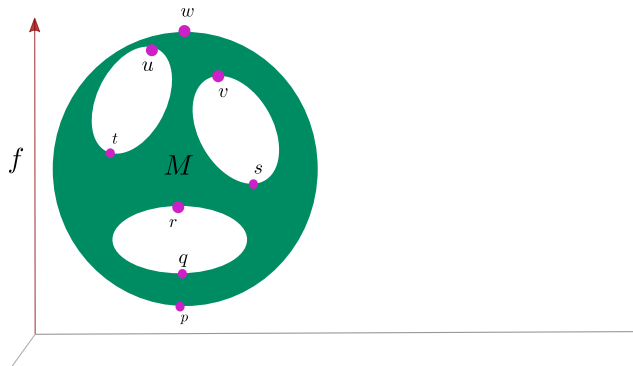
A smooth function $f : M^n \rightarrow \mathbb{R}$ is called a **Morse function** if all its critical points are non-degenerate.

CLASSICAL MORSE THEORY

MORSE FUNCTION

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p has index 0. w has index +2. Others have index +1.



CLASSICAL MORSE THEORY

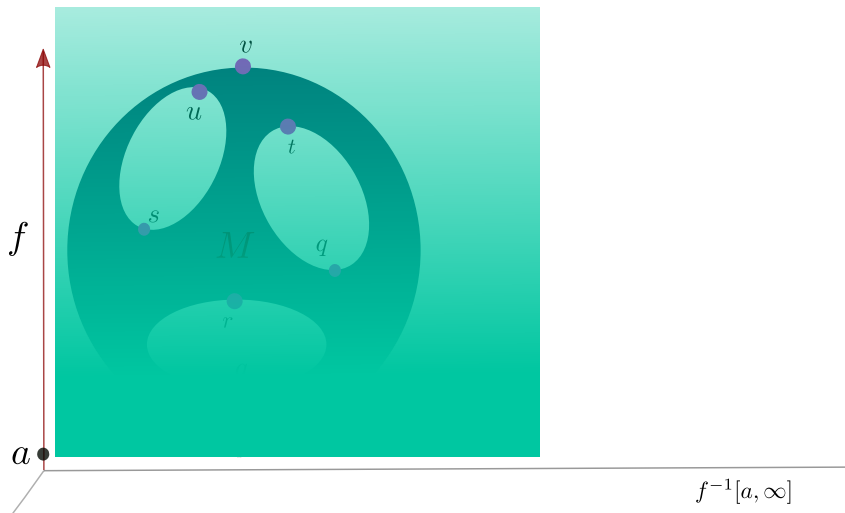


FIGURE: Sub-level Set

CLASSICAL MORSE THEORY

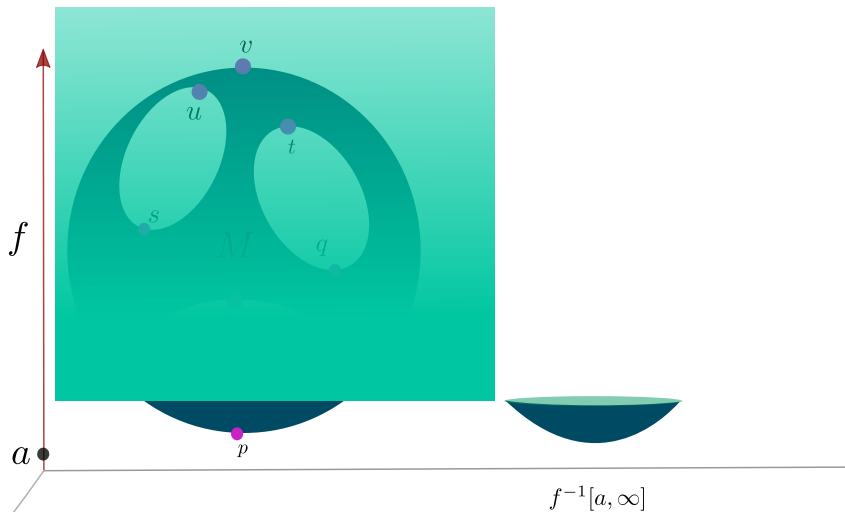


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CLASSICAL MORSE THEORY

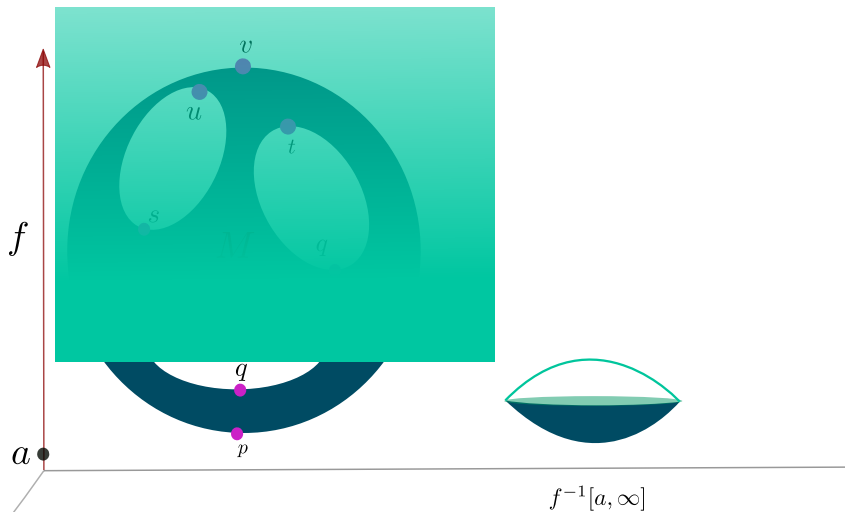


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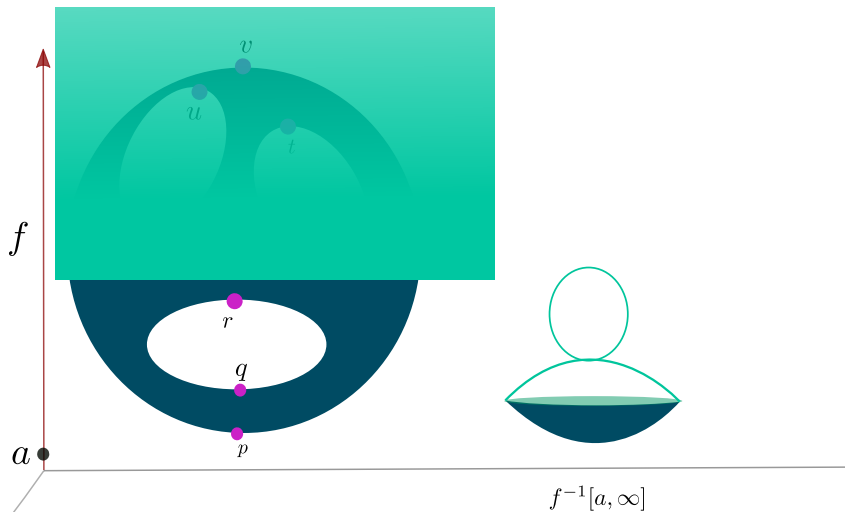


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CLASSICAL MORSE THEORY

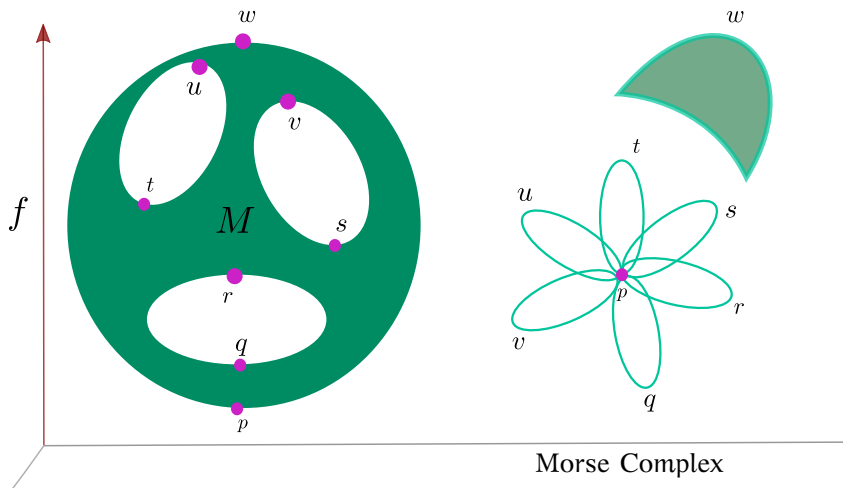


FIGURE: Morse Complex

MORSE THEOREM

If f is Morse on M , then M is *homotopy equivalent* to a CW-complex having a d -cell for each critical point of f of index d .

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MORSE INEQUALITY

critical d -index critical points $\geq H_d(M)$.

DYNAMICS OF MORSE FUNCTIONS

GRADIENT OF MORSE FUNCTION

The gradient vector field of a smooth function f

$$\langle \nabla f, V \rangle := -Df(V),$$

for any other vector field V on M .

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The **stable manifold**

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UNSTABLE MANIFOLD

The **unstable manifold**

$$W_u(p) = \{x \in M \mid \lim_{t \rightarrow -\infty} \Phi_t(x) = p\}$$

OBSERVATIONS

For a Morse function f on a compact manifold M ,

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For a Morse function f on a compact manifold M ,

- ① critical points are the equilibrium points of ∇f .
- ② f (strictly) decreases along the flow-lines.
- ③ no limit cycles.

BACK TO OUR PROBLEM

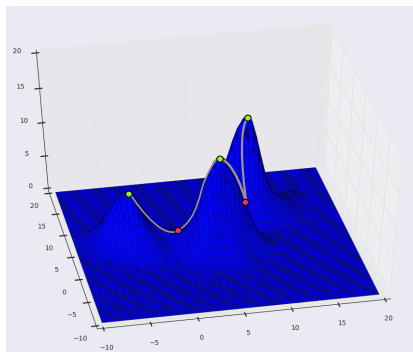


FIGURE: KDE

If the samples are concentrated around a graph, then the mountain ridges on the graph of the density function are expected to capture it.

CONCLUSION

- 1 our project is ongoing.
- 2 there is a reading group in mathematics department meeting weekly to discuss Morse theory.

Thanks