MECHANISTIC INTERPRETABIL-

ITY ON (MULTI-TASK) IRRE-

DUCIBLE INTEGER IDENTIFIERS

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1 | Mechanistic Interpretability

2 | Modular Arithmetic

3 | Grokking on  $\mathcal{T}_{\text{miiii}}$ 

4 | Embeddings

5 | Neurons

"This disgusting pile of matrices is actually just an astoundingly poorly written, elegant and consice algorithm" — Neel Nanda¹

<sup>&</sup>lt;sup>1</sup>Not verbatim, but the gist of it

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- ▶ No obvious mapping from the weights of a trained model to math notation
- ▶ MI is about reverse engineering these models, and looking closely at them
- ▶ Many low hanging fruits / practical botany phase of the science
- ▶ How does a given model work? How can we train it faster? Is it safe?

#### 1.1 | Grokking

► Grokking [1] is "sudden generalization"

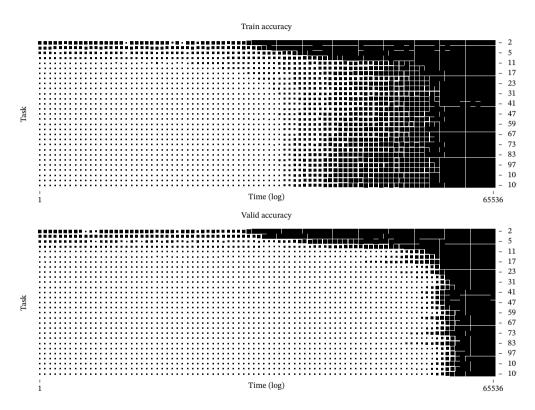


Figure 1: Grokking

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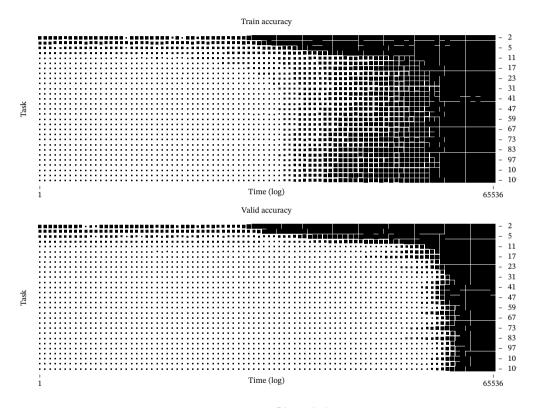


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## 1.1 | Grokking

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- ► MI (often) needs a mechanism
- ▶ Grokking is thus convenient for MI

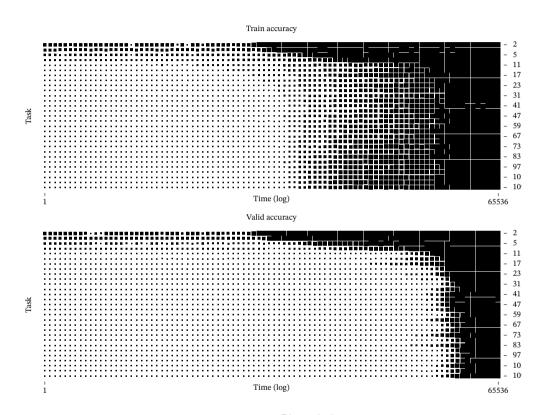


Figure 1: Grokking

#### 2 | Modular Arithmetic

- ▶ "Seminal" MI paper by Nanda et al. (2023) focuses on modular addition ( $\mathcal{T}_{nanda}$ )
- ▶ Their final setup trains on p = 113
- ► They train a one-layer transformer
- $\blacktriangleright$  We call their task  $\mathcal{T}_{\mathrm{nanda}}$

$$\mathcal{T}_{\mathrm{nanda}} = (x_0 + x_1) \operatorname{mod} p, \forall x_0, x_1 \quad (1.1)$$

$$\mathcal{T}_{\mathrm{miiii}} = \left(x_0 p^0 + x_1 p^1\right) \bmod q, \forall q < p(1.2)$$

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- $\blacktriangleright$  And ours we call  $\mathcal{T}_{\mathrm{miiii}}$

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# 2 | Modular Arithmetic

- $ightharpoonup \mathcal{T}_{\mathrm{miiii}}$  is non-commutative ...
- $\blacktriangleright$  ... and multi-task: q ranges from 2 to  $109^1$
- $ightharpoonup \mathcal{T}_{\mathrm{nanda}}$  use a single layer transformer
- ▶ Note that these tasks are synthetic and trivial to solve with conventional programming
- ▶ They are used in the MI literature to turn black boxes opaque

<sup>&</sup>lt;sup>1</sup>Largest prime less than p = 113

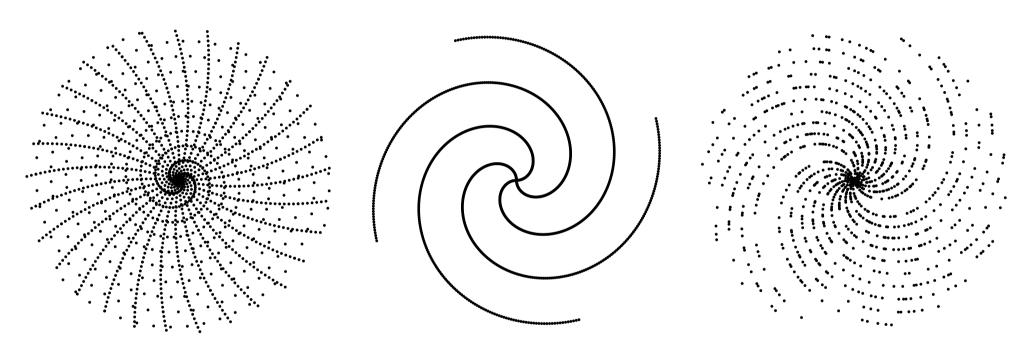
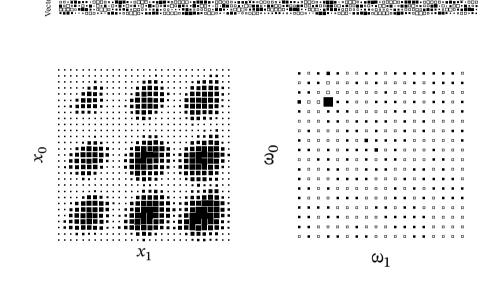


Figure 2:  $\mathbb{N} < p^2$  multiples of 13 or 27 (left) 11 (mid.) or primes (right)

# 3 | Grokking on $\mathcal{T}_{\text{miiii}}$

- ► For two-token samples, plot them varying one on each axis (Figure 3)
- ▶ When a matrix is periodic use Fourier
- ► Singular value decomposition



Left side singular value vectors capturing 50 % of the variance (nanda)

Figure 3: Top singular vectors of  $\mathbf{U}_{W_{E_{\mathcal{T}_{\mathrm{nanda}}}}}$  (top), varying  $x_0$  and  $x_1$  in sample (left) and freq. (right) space in  $W_{\mathrm{out}_{\mathcal{T}_{\mathrm{miiii}}}}$ 

# 3 | Grokking on $\mathcal{T}_{\text{miiii}}$

- ▶ The model groks on  $\mathcal{T}_{\text{miiii}}$  (Figure 4)
- ▶ Needed GrokFast [3] on compute budget
- ► Final hyperparams are seen in Table 1

| rate           | λ             | wd            | d   | lr               | heads |
|----------------|---------------|---------------|-----|------------------|-------|
| $\frac{1}{10}$ | $\frac{1}{2}$ | $\frac{1}{3}$ | 256 | $\frac{3}{10^4}$ | 4     |

Table 1: Hyperparams for  $\mathcal{T}_{\text{miiii}}$ 

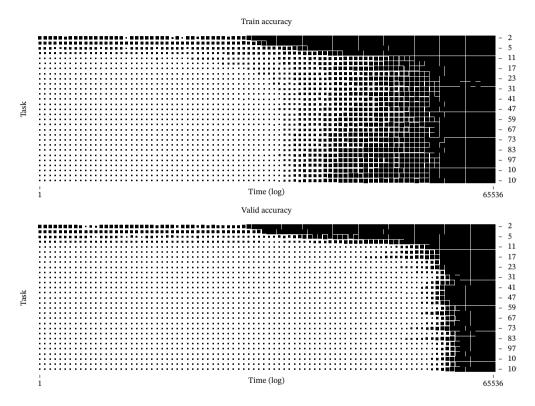


Figure 4: Training (top) and validation (bottom) accuracy during training on  $\mathcal{T}_{\text{miiii}}$ 

4 | Embeddings

How the embedding layer deals with the difference between  $\mathcal{T}_{\rm nanda}$  and  $\mathcal{T}_{\rm miiii}$ 

# 4.1 | Correcting for non-commutativity

▶ The position embs. of Figure 5 reflects that  $\mathcal{T}_{\text{nanda}}$  is commutative and  $\mathcal{T}_{\text{miiii}}$  is not

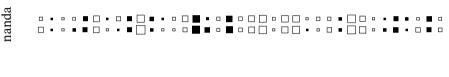


Positional embeddings

Figure 5: Positional embeddings for  $\mathcal{T}_{\text{nanda}}$  (top) and  $\mathcal{T}_{\text{miiii}}$  (bottom).

#### 4.1 | Correcting for non-commutativity

- ▶ The position embs. of Figure 5 reflects that  $\mathcal{T}_{\text{nanda}}$  is commutative and  $\mathcal{T}_{\text{miiii}}$  is not
- ▶ Maybe: this corrects non-comm. of  $\mathcal{T}_{\text{miiii}}$ ?
- $\blacktriangleright$  Corr. is 0.95 for  $\mathcal{T}_{\mathrm{nanda}}$  and -0.64 for  $\mathcal{T}_{\mathrm{miiii}}$



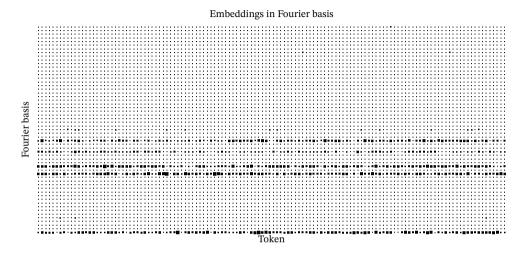
Positional embeddings



Figure 5: Positional embeddings for  $\mathcal{T}_{\text{nanda}}$  (top) and  $\mathcal{T}_{\text{miiii}}$  (bottom).

## 4.2 | Correcting for multi-tasking

- ▶ For  $\mathcal{T}_{\text{nanda}}$  token embs. are essentially linear combinations of 5 frequencies ( $\omega$ )
- $\blacktriangleright$  For  $\mathcal{T}_{\mathrm{miiii}}$  more frequencies are in play
- $\blacktriangleright$  Each  $\mathcal{T}_{\mathrm{miiii}}$  subtask targets unique prime
- ▶ Possibility: One basis per prime task



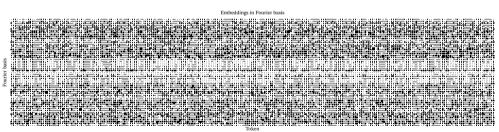


Figure 6:  $\mathcal{T}_{\text{nanda}}$  (top) and  $\mathcal{T}_{\text{miiii}}$  (bottom) token embeddings in Fourier basis

# 4.3 | Sanity-check and task-mask

- ▶ Masking  $q \in \{2, 3, 5, 7\}$  yields we see a slight decrease in token emb. freqs.
- $\blacktriangleright$  Sanity check:  $\mathcal{T}_{\text{baseline}}$  has no periodicity
- ▶ The tok. embs. encode a basis per subtask?

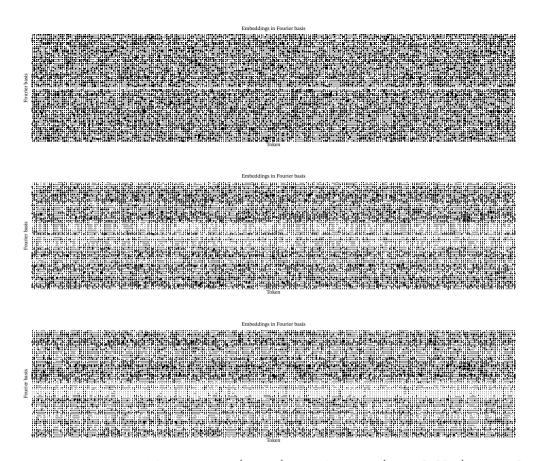


Figure 7:  $\mathcal{T}_{\text{baseline}}$  (top),  $\mathcal{T}_{\text{miiii}}$  (middle) and  $\mathcal{T}_{\text{masked}}$  (bottom) token embeddings in Fourier basis  $_{10 \text{ of } 19}$ 

#### 5 | Neurons

- Figure 8 shows transformer MLP neuron activations as  $x_0$ ,  $x_1$  vary on each axis
- $\blacktriangleright$  Inspite of the dense Fourier basis of  $W_{E_{\mathcal{T}_{\mathrm{miiii}}}}$  the periodicity is clear

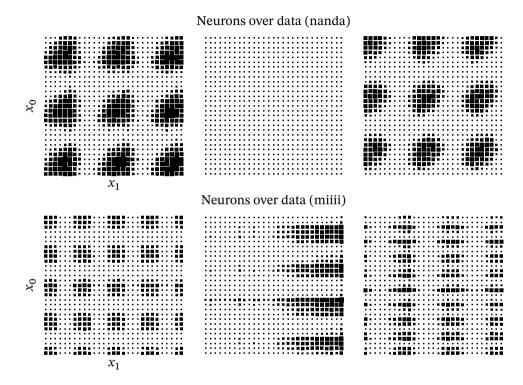


Figure 8: Activations of first three neurons for  $\mathcal{T}_{\text{nanda}}$  (top) and  $\mathcal{T}_{\text{miiii}}$  (bottom)

#### 5 | Neurons

- ► (Probably redundant) sanity check: Figure 9 confirms neurons are periodic
- $\blacktriangleright$  See some freqs.  $\omega$  rise into significance
- ▶ Lets log  $|\omega > \mu_{\omega} + 2\sigma_{\omega}|$  while training

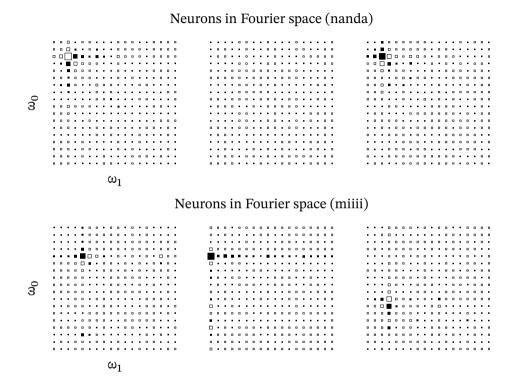


Figure 9: FFT of Activations of first three neurons for  $\mathcal{T}_{\text{nanda}}$  (top) and  $\mathcal{T}_{\text{miiii}}$  (bottom)

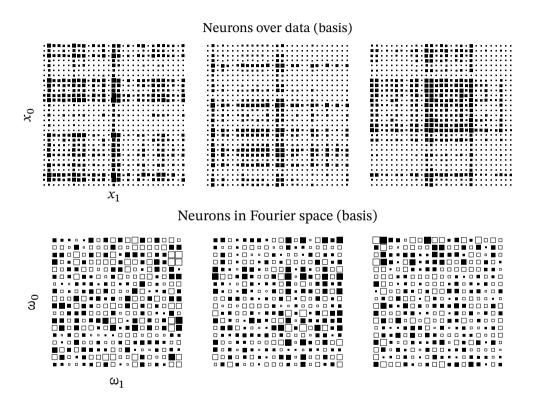


Figure 10: Neurons as archive for  $\mathcal{T}_{\text{basline}}$ 

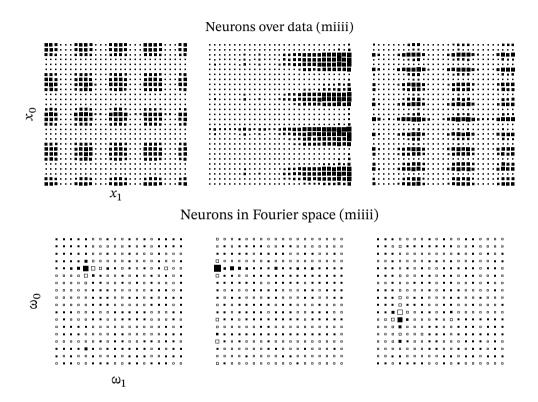


Figure 11: Neurons as algorithm  $\mathcal{T}_{\text{miiii}}$ 

#### Evolution of active frequencies ( $\omega$ ) through time (log)

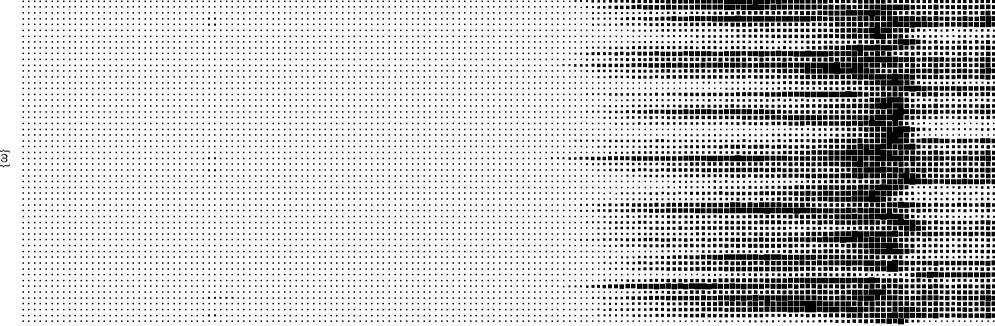


Figure 12: Number of neurons with frequency  $\omega$  above the theshold  $\mu_{\omega} + 2\sigma_{\omega}$ 

- ▶ Neurs. periodic on solving  $q \in \{2, 3, 5, 7\}$
- ▶ When we generalize to the reamining tasks, many frequencies activate (64-sample)
- ▶ Those  $\omega$ 's are not useful for memory and not useful after generalization

| time       | 256 | 1024 | 4096 | 16384 | 65536 |
|------------|-----|------|------|-------|-------|
| $ \omega $ | 0   | 0    | 10   | 18    | 10    |

Table 2: active  $\omega$ 's through training

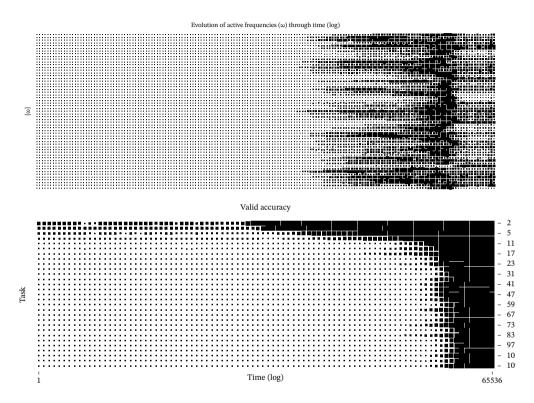


Figure 13: Figure 12 (top) and validation accuracy from Figure 4 (bottom)

- ▶ GrokFast [3] shows time gradient sequences is (arguably) a stocastical signal with:
  - ► A fast varying overfitting component
  - ► A slow varying generealizing component
- $\blacktriangleright$  My work confirms this to be true for  $\mathcal{T}_{\text{miiii}}$  ...
- ... and observes a structure that seems to fit *neither* of the two

- ► Future work:
  - ▶ Modify GrokFast to assume a third stochastic component
  - ▶ Relate to signal processing literature
  - ▶ Can more depth make tok-embedding sparse?



#### References

- [1] A. Power, Y. Burda, H. Edwards, I. Babuschkin, and V. Misra, "Grokking: Generalization Beyond Overfitting on Small Algorithmic Datasets," no. arXiv:2201.02177. arXiv, Jan. 2022. doi: 10.48550/arXiv.2201.02177.
- [2] N. Nanda, L. Chan, T. Lieberum, J. Smith, and J. Steinhardt, "Progress Measures for Grokking via Mechanistic Interpretability," no. arXiv:2301.05217. arXiv, Oct. 2023.
- [3] J. Lee, B. G. Kang, K. Kim, and K. M. Lee, "Grokfast: Accelerated Grokking by Amplifying Slow Gradients," no. arXiv:2405.20233. Jun. 2024.

#### A | Stochastic Signal Processing

We denote the weights of a model as  $\theta$ . The gradient of  $\theta$  with respect to our loss function at time t we denote g(t). As we train the model, g(t) varies, going up and down. This can be thought of as a stocastic signal. We can represent this signal with a Fourier basis. GrokFast posits that the slow varying frequencies contribute to grokking. Higer frequencies are then muted, and grokking is indeed accelerated.

## B | Discrete Fourier Transform

Function can be expressed as a linear combination of cosine and sine waves. A similar thing can be done for data / vectors.

## C | Singular Value Decomposition

An  $n \times m$  matrix M can be represented as a  $U\Sigma V^*$ , where U is an  $m \times m$  complex unitary matrix,  $\Sigma$  a rectangular  $m \times n$  diagonal matrix (padded with zeros), and V an  $n \times n$  complex unitary matrix. Multiplying by M can thus be viewed as first rotating in the m-space with U, then scaling by  $\Sigma$  and then rotating by V in the n-space.