Using a Cartesian Vector Class

Out[3]: True

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https://github.com/t-o-k/scikit-vectors (https://github.com/t-o-k/scikit-vectors)

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In [1]: from skvectors import create class Cartesian Vector
In [2]: # Create a 4-dimensional cartesian vector class
        CVC = create class Cartesian Vector('CVC', 'ABCD')
        # Explicit alternative:
        \# CVC = 1
              create class Cartesian Vector(
                  name = 'CVC',
                  component_names = [ 'A', 'B', 'C', 'D' ],
                  brackets = [ '<', '>' ],
                  sep = ', ',
                  cnull = 0,
                  cunit = 1.
                  functions = None
In [3]: # Check if a vector is the zero vector (i.e. its length is equal to cnull)
        u = CVC(0, 0, 0, 0)
        u.is zero vector()
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In [4]: # Check if a vector is the zero vector
        u = CVC(0, 0, 1, 0)
        u.is_zero_vector()
Out[4]: False
In [5]: # Check if a vector is a unit vector (i.e. its length is equal to cunit)
        u = CVC(0.6, 0.0, -0.8, 0.0)
        u.is unit vector()
Out[5]: True
In [6]: # Check if a vector is a unit vector
        u = CVC(-0.1, 0.5, 0.0, 0.8)
        u.is unit vector()
Out[6]: False
In [7]: # Check if a vector is equal to another
        u = CVC(-3, -1, 4, 2)
        v = CVC(-3, 1, 4, 2)
        U == V
Out[7]: False
In [8]: # Check if a vector is not equal to another
        u = CVC(-3, -1, 4, 2)
        v = CVC(-3, 1, 4, 2)
        u != v
Out[8]: True
In [9]: # Check if a vector is orthogonal to another
        u = CVC(3, 2, -1, 4)
        v = CVC(0, 3, 6, 0)
        u.are orthogonal(v)
Out[9]: True
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In [10]: # Check if a vector is orthogonal to another
         u = CVC(3, 2, -1, 4)
         v = CVC(0, 3, 6, 4)
         u.are orthogonal(v)
Out[10]: False
In [11]: # NB: All vectors are orthogonal to the zero vector
         u = CVC(3, 2, -1, 4)
         V = CVC(0, 0, 0, 0)
         u.are orthogonal(v)
Out[11]: True
In [12]: # NB: The zero vector is orthogonal to all vectors
         u = CVC(0, 0, 0, 0)
         v = CVC(3, 2, -1, 4)
         u.are orthogonal(v)
Out[12]: True
In [13]: # Check if the length of a vector is equal to the length of another
         u = CVC(-4, -2, 4, 1)
         v = CVC(5, 1, 1, -3)
         u.equal lengths(v)
Out[13]: False
In [14]: # Check if the length of a vector is equal to the length of another
         (2 * CVC(-2, -1, 2, 0)).equal lengths(CVC(15, 3, 3, -9) / 3)
Out[14]: True
In [15]: # Check if a vector is shorter than another
         u = CVC(1, 3, -5, 1)
         v = CVC(-4, 0, 4, -2)
         u.shorter(v)
Out[15]: False
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In [16]: # Check if a vector is shorter than another
         u = CVC(5, -3, -1, -1)
         v = CVC(2, -5, 4, 2)
         u.shorter(v)
Out[16]: True
In [17]: # Check if a vector is longer than another
         u = CVC(1, 3, -5, 1)
         V = CVC(-4, 0, 4, -2)
         u.longer(v)
Out[17]: False
In [18]: # Check if a vector is longer than another
         u = CVC(-2, 2, 4, 5)
         v = CVC(1, -5, -1, 3)
         u.longer(v)
Out[18]: True
In [19]: # Calculate the dot product of a vector and another
         u = CVC(-2, 1, -1, 3)
         v = CVC(2, 3, 0, -4)
         u.dot(v)
Out[19]: -13
In [20]: # Calculate the dot product of a vector and another
         (CVC(-4, -1, -3, 1) + 2).dot(CVC(3, 4, 1, -3) - 1)
Out[20]: -13
In [21]: # Calculate the length (magnitude) of a vector
         u = CVC(-2, -5, 4, 2)
         u.length()
Out[21]: 7.0
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In [22]: # Calculate the length of a vector
         (CVC(3, -2, -3, 7) - CVC(2, -7, -2, 4)).length()
Out[22]: 6.0
In [23]: # Calculate the distance between a position vector and another
         u = CVC(3, -2, -3, 7)
         v = CVC(2, -7, -2, 4)
         u.distance(v)
Out[23]: 6.0
In [24]: # Create a vector from the normalization of a vector
         # (i.e. a vector in the same direction with length equal cunit)
         u = CVC(-4, 0, 0, 3)
         u.normalize()
Out[24]: CVC(A=-0.8, B=0.0, C=0.0, D=0.6)
In [25]: # Create a vector by projecting a vector onto another
         u = CVC(9, -9, 0, 6)
         v = CVC(0, 2, 1, -4)
         w = u.project(v)
Out[25]: CVC(A=-0.0, B=-4.0, C=-2.0, D=8.0)
In [26]: | # Create a vector from the inverse of the projection of a vector onto another
         W = CVC(-0, -4, -2, 8)
         v = CVC(-3, 3, 0, -2)
         u = w.inv project(v)
         u
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Out[26]: CVC(A=9.0, B=-9.0, C=-0.0, D=6.0)

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In [27]: # Create a vector by rejecting a vector from another
         u = CVC(9, -9, 0, 6)
         v = CVC(0, 2, 1, -4)
         u.reject(v)
Out[27]: CVC(A=9.0, B=-5.0, C=2.0, D=-2.0)
In [28]: # Calculate the scalar projection of a vector onto another
         u = CVC(3, 0, 4, -1)
         V = CVC(-6, 0, -8, 0)
         u.scalar project(v)
Out[28]: -5.0
In [29]: # Calculate the smallest angle in radians between a vector and another
         u = CVC(4.5, -3.0, 0.0, -1.5)
         W = CVC(-3.0, -3.0, 0.0, -3.0)
         u.angle(w) \# = pi/2
Out[29]: 1.5707963267948963
In [30]: # Calculate the cosine of the smallest angle between a vector and another
         u = CVC(-1, 0, 0, -1)
         V = CVC(2, 0, -2, 2)
         u.cos(v) # = -(2/3)**0.5
Out[30]: -0.8164965809277259
In [31]: # Limit the resulting value to be greater than or equal to s*cunit and smaller than or equal to t*cunit
         s = -1
         t = 2
             CVC.clip(i, s, t)
             for i in [ -3, -2, -1, 0, 1, 2, 3, 4]
Out[31]: [-1, -1, -1, 0, 1, 2, 2, 2]
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