KU LEUVEN

Faculteit Industriële Ingenieurswetenschappen / Elektronica - ICT

Dries Kennes <ceo@marsrover.space> Laurens Van de Walle<cco@> Christophe Bulcke<christophe@> Jonas Michiels<jonas@> Robbe Goovaerts<robbe@>

Turtlebot: Mars rover

https://marsrover.space

Mission

1) Scan 360º for POIs

2) Drive to selected POI

   • Map environment

3) "Collect" sample

4) Back to 1)

Design

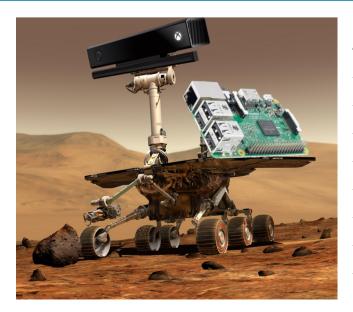| Perception	Decision	Actuation
• 3D camera	• Raspberry PI	• Motor: Control wheels • Gripper

Timeline

	20/2	27/2	6/3	13/3	20/3	27/3	3/4	Easter	24/4	1/5
Task management	▓									
Hardware introduction	▓	▓								
Motor actuation		▓	▓	▓						
Gripper actuation		▓	▓							
Acquire image stream			▓	▓						
Detecting POIs				▓	▓	▓				
Pathfinding						▓	▓	▓		
Terrain mapping							▓	▓	▓	
Integration								▓	▓	▓