

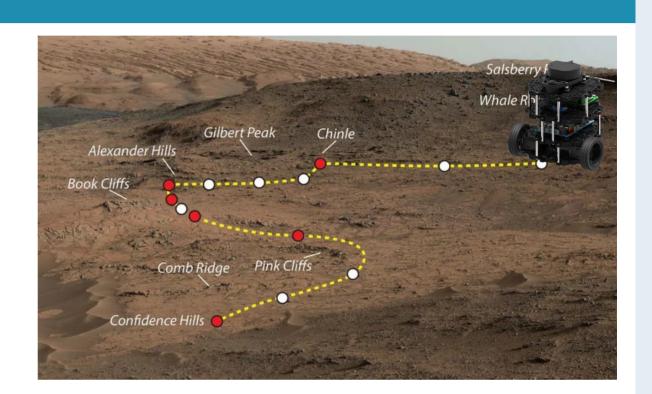
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Turtlebot: Mars rover

https://marsrover.space

Mission

- 1) Scan 360° for POIs
- 2) Drive to selected POI
 - Map environment
- 3) "Collect" sample
- 4) Back to 1)



Design

Perception

• 3D camera

Decision

Raspberry Pl

Actuation

- Motor: Control wheels
- Gripper

Timeline



	20/2	27/2	6/3	13/3	20/3	27/3	3/4	Pasen	24/4	1/5
Task management										
Hardware introduction										
Motor actuation										
Gripper actuation										
Acquire image stream										
Detecting POIs										
Pathfinding										
Terrain mapping										
Integration										