

Anxing Xiao

Adaptive Computing Laboratory

School of Computing

National University of Singapore, Singapore 117417

✉ anxingx@comp.nus.edu.sg

🏠 anxingxiao.com

🎓 [Google Scholar](#)

RESEARCH INTERESTS

My research topics cover reasoning, motion planning, and assistive robotics. My long-term research goal is to advance the capability of various service robots to adapt to unforeseen objects and tasks in diverse human-centric environments.

EDUCATION

National University of Singapore

Jan 2023 - present

Ph.D. student in Computer Science

Advisors: [Prof. David Hsu](#)

Harbin Institute of Technology

Aug 2017 - Jun 2021

B.Eng. in Automation (Shenzhen Campus), GPA: 93.08/100 (Ranking 1/70)

Visiting Student at UC Berkeley (2019 Fall - 2020 Spring)

EXPERIENCE

Robotic Perception and Intelligence Lab, SUSTech & CUHK

Aug 2021 - Jun 2022

Research Assistant with [Prof. Max Q.-H. Meng](#)

Shenzhen, China

Worked on autonomous trolley collection robots and fast Generalized Voronoi Diagrams generation.

Hybrid Robotics Lab, UC Berkeley

Mar 2020 - Mar 2021

Undergraduate Research Assistant with [Prof. Koushil Sreenath](#)

Berkeley, CA, USA

Worked on robotic guide dog and quadrupedal autonomous navigation with optimized jumping.

PUBLICATIONS

Preprint:

* denotes equal contribution, † denotes mentorship

- [1] **A. Xiao**, A. Gupta, Y. Deng, K. Li, D. Hsu, "Robi Butler: Remote Multimodal Interactions with Household Robot Assistant", *In submission*. [\[Paper\]](#) [\[Video\]](#) [\[Website\]](#)
- [2] S. Luo, J. Zhu, P. Sun, Y. Deng, C. Yu, **A. Xiao**[†], X. Wang, "GSON: A Group-based Social Navigation Framework with Large Multimodal Model", *In submission*. [\[Paper\]](#) [\[Video\]](#)
- [3] S. Chen, **A. Xiao**, D. Hsu, "LLM-State: Expandable State Representation for Long-horizon Task Planning in the Open World", [\[Paper\]](#) [\[Video\]](#)

Conference:

- [1] S. Yu, K. Lin, **A. Xiao**, J. Duan, H. Soh, "Octopi: Object Property Reasoning with Large Tactile-Vision-Language Models", *Robotics: Science and Systems (RSS)*, 2024. [\[Paper\]](#) [\[Website\]](#) [\[Code\]](#)
- [2] B. Xia, H. Luan, Z. Zhao, X. Gao, P. Xie, **A. Xiao**[†], J. Wang, and M. Q.-H. Meng, "Collaborative Trolley Transportation System with Autonomous Nonholonomic Robots", *International Conference on Intelligent Robots and Systems (IROS)*, 2023. [\[Paper\]](#) [\[Video\]](#)
- [3] Y. Chen, Z. Xu, Z. Jian, G. Tang, Y. Yangli, **A. Xiao**[†], X. Wang, and B. Liang, "Quadruped Guidance Robot for the Visually Impaired: A Comfort-Based Approach", *International Conference on Robotics and Automation (ICRA)*, 2023. [\[Paper\]](#) [\[Video\]](#)
- [4] **A. Xiao**^{*}, H. Luan^{*}, Z. Zhao^{*}, Y. Hong, J. Zhao, J. Wang, and M. Q.-H. Meng, "Robotic Autonomous Trolley Collection with Progressive Perception and Nonlinear Model Predictive Control", *International Conference on Robotics and Automation (ICRA)*, 2022. [\[Paper\]](#) [\[Video\]](#)
- [5] Z. Jian, Z. Lu, X. Zhou, B. Lan, **A. Xiao**[†], X. Wang, and B. Liang, "PUTN: A Plane-fitting based Uneven Terrain Navigation Framework", *International Conference on Intelligent Robots and Systems (IROS)*, 2022. [\[Paper\]](#) [\[Code\]](#)
- [6] **A. Xiao**^{*}, W. Tong^{*}, L. Yang^{*}, J. Zeng, Z. Li, and K. Sreenath, "Robotic Guide Dog: Leading a Human with Leash-Guided Hybrid Physical Interactions", *International Conference on Robotics and Automation (ICRA)*, 2021. **Best Service Robot Paper Finalist**. [\[Paper\]](#) [\[Video\]](#) Media coverage: [\[Daily Mail\]](#) [\[New Scientist\]](#) [\[Tech Xplore\]](#) [\[Daily Californian\]](#) [\[Independent\]](#) [\[Futurism\]](#) [\[China Daily\]](#) [\[DeepTech \(Chinese\)\]](#)
- [7] S. Gilroy, D. Lau, L. Yang, E. Izaguirre, K. Biermayer, **A. Xiao**, M. Sun, A. Agrawal, J. Zeng, Z. Li, and K. Sreenath, "Autonomous Navigation with Optimized Jumping through Constrained Obstacles on Quadrupeds", *International Conference on Automation Science and Engineering (CASE)*, 2021. [\[Paper\]](#) [\[Video\]](#) Media coverage [\[Video Friday\]](#)

- [8] Y. Wu, **A. Xiao**, H. Chen, S. Zhang, Y. Liu, "Amphibious Robot's Trajectory Tracking with DNN-Based Nonlinear Model Predictive Control", *International Conference on Advanced Intelligent Mechatronics (AIM)*, 2020. [\[Paper\]](#)

SELECTED AWARDS AND HONORS

- NUS Research Scholarship 2023
- Best Paper Award Finalist for Service Robotics at **ICRA '21** 2021
- Dean's Award. 2021
- First-class Undergraduate Academic Scholarship 2018-2021
- Provincial-Level Merit Student. 2019
- National Scholarship. 2018

PROFESSIONAL RESPONSIBILITIES

- *Journal Reviewing*: IEEE T-RO, IEEE RA-L, IEEE T-IE, IEEE T-ASE.
- *Conference Reviewing*: ICRA '22 '23 '24 '25, IROS '22 '24.
- *Mentorship*
 - Students
 - * Bingyi Xia [C.2], MS Student @ SUSTech 2022 - 2023
 - * Xuheng Gao [C.2], MS Student @ SUSTech 2022 - 2023
 - * Zhengzhe Xu [C.3], Undergrad @ HITsz → PhD @ HKU 2021 - 2022
 - * Yanbo Chen [C.3], Undergrad @ HITsz → MS @ Tsinghua Univ. 2021 - 2022
 - * Xiao Zhou [C.5], Undergrad @ HITsz → MPhil. @ HKUST 2021 - 2022

REFERENCES

- **Prof. David Hsu (IEEE Fellow).**
 Provost's Chair Professor.
 Department of Computer Science. National University of Singapore.
 Relationship: PhD supervisor.
 Email: dyhsu@comp.nus.edu.sg
- **Prof. Max Q.-H. Meng (IEEE Fellow).**
 Department head, Chair Professor.
 Department of Electrical and Electronic Engineering, Southern University of Science and Technology
 Relationship: RA supervisor.
 Email: max.meng@ieee.org
- **Prof. Koushil Sreenath.**
 Associate Professor.
 Department of Mechanical Engineering, University of California, Berkeley.
 Relationship: RA supervisor.
 Email: koushils@berkeley.edu

SKILLS

- **Programming**: Python, C/C++, MATLAB, HTML
- **Softwares & Tools**: ROS, PyTorch, OpenCV, CasADi, LCM, Solidworks, Gazebo, Isaac Sim, Git, LaTeX
- **Hardware**: Multiple Motors and Sensors, Arduino, Raspberry Pi, Basic Mechanical Design
- **Sports**: Table Tennis, Basketball, Soccer