

Florent Fayollas

Antoine Vacher



TLS-SEC



DRONE PREDATOR

ONE DRONE TO RULE THEM ALL

Project overall goal

- **Take control of multiple drones**
 - Some existing military solutions
 - No civil solution

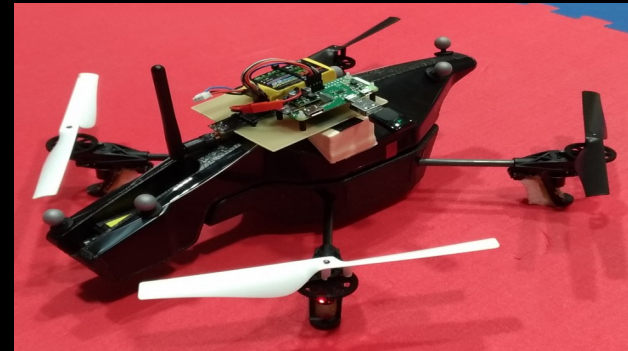


Project overall goal

- **Take control of multiple drones**
 - Some existing military solutions
 - No civil solution



- **Our goals:**
 - Reduced cost
 - No drone falling implied
 - High number of compatible drones
 - Usable on public events, by civilians



Syma – Introduction

The goal of the attack is to hijack a Syma X5C-1 Drone in flight



Documentation and markings tell us:

- Not WIFI
- Frequency band 2.4 GHz
- 4 Channels

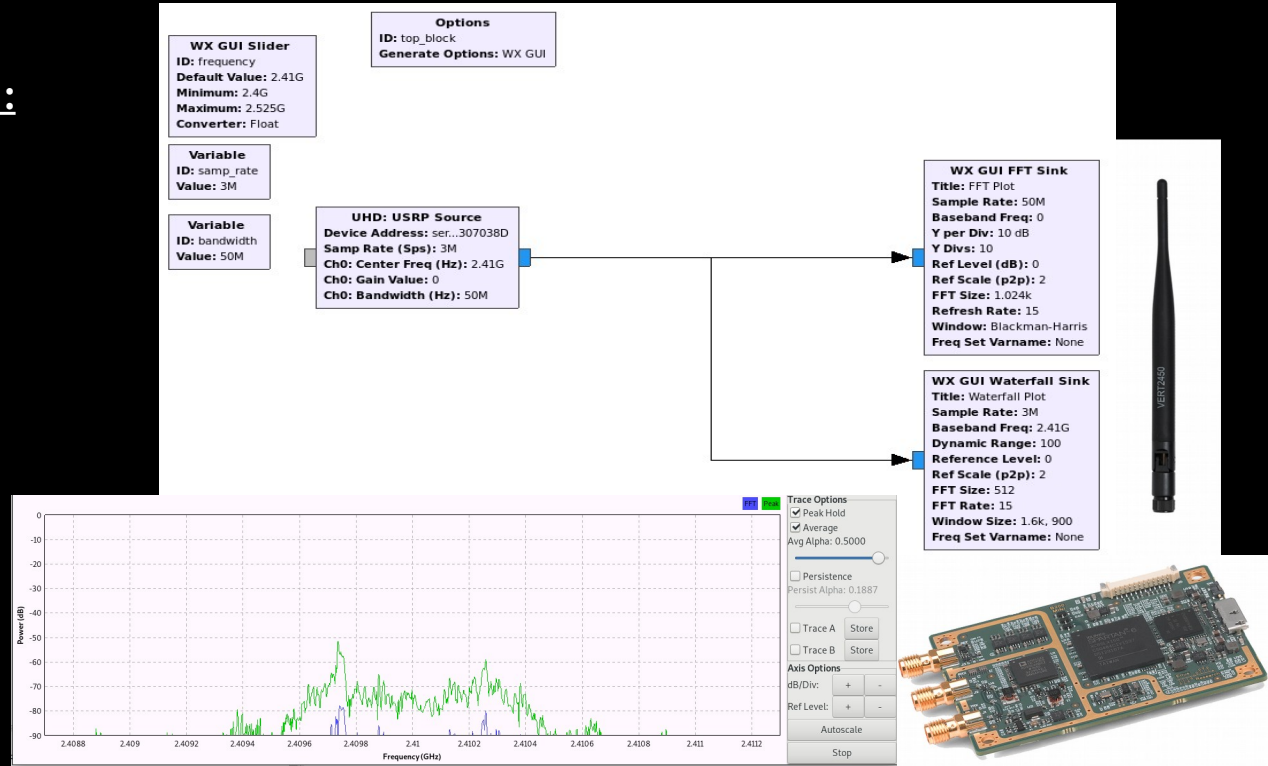
Syma – Step 1 – Finding Radio Channels

Using an USRP B200 SDR with GnuRadio :

- USRP Source
- FFT and Waterfall Sinks
- Browse all channels by 1MHz steps

→ Tx power received on channels :

- 10 : 2.410 GHz
- 31 : 2.431 GHz
- 42 : 2.442 GHz
- 66 : 2.466 GHz

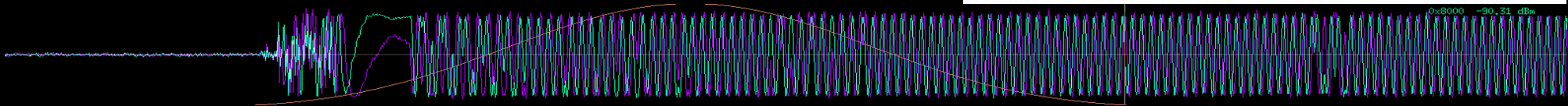
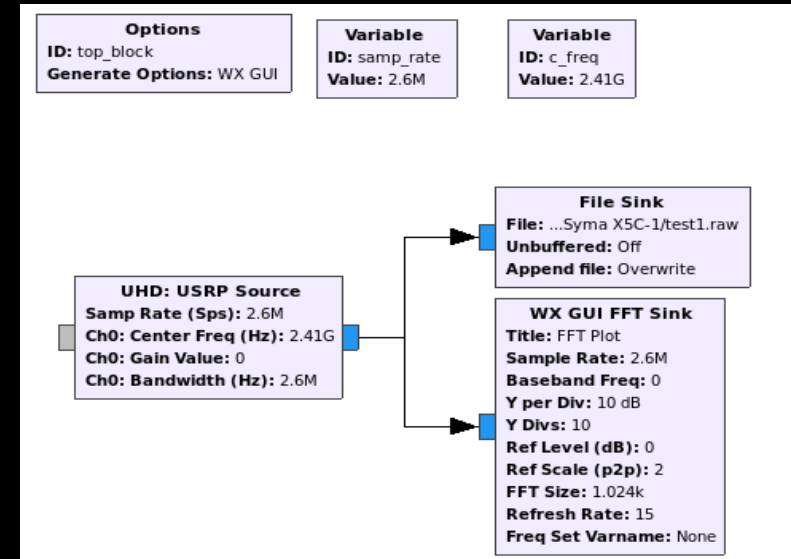


Syma – Step 2 – Finding Radio Modulation

Using an USRP B200 SDR with GnuRadio :

- USRP Source
- File Sink

Opening file with Baudline :



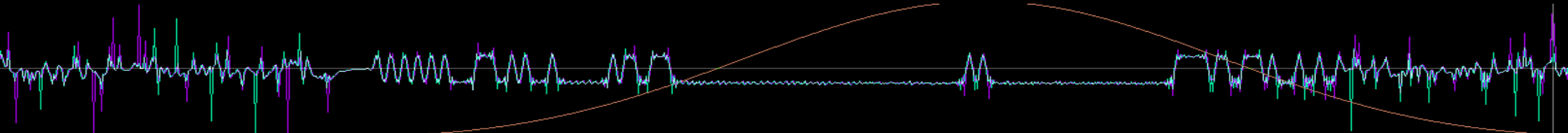
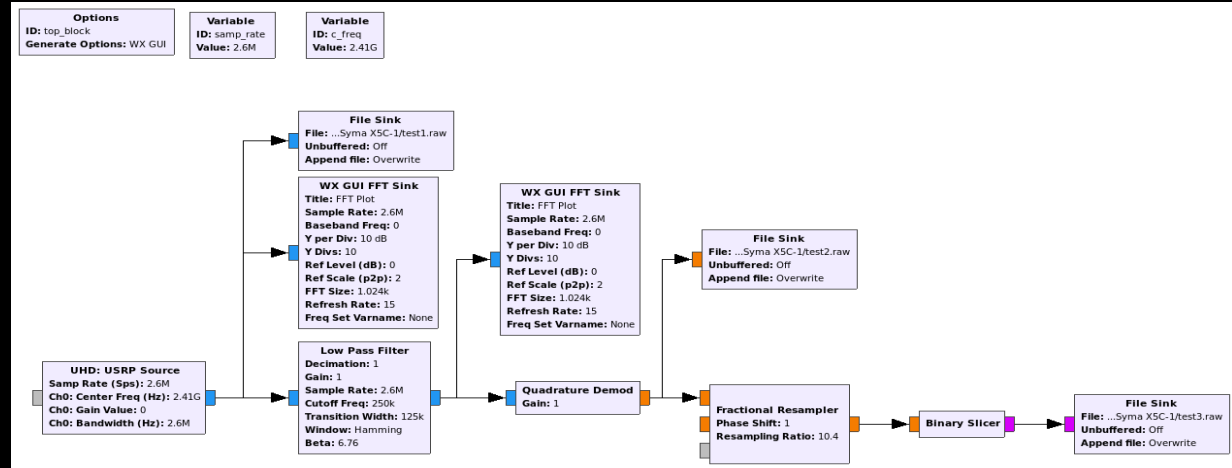
Constant amplitude → Not ASK. Could be (G)FSK or PSK

Syma – Step 2 – Finding Radio Modulation

Trying GFSK as it is widely used for small electronics

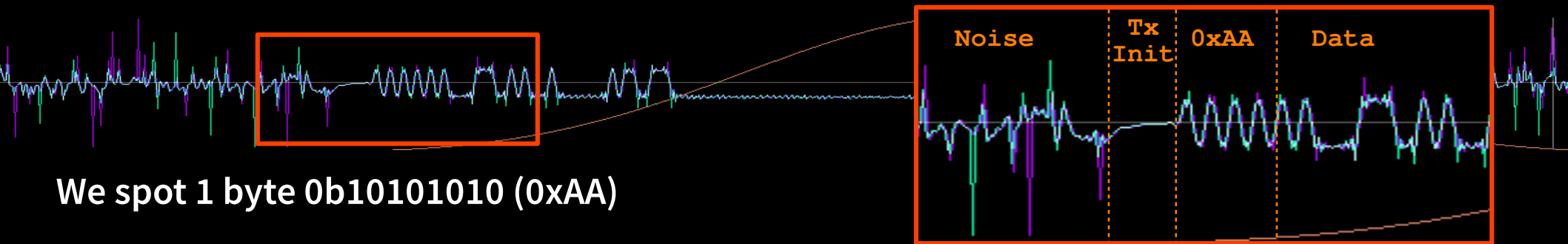
- USRP Source
- Low Pass Filter
- Quadrature Demod
- File Sink
- Save bit stream

Opening file with Baudline :



Signal looked clean. Demodulation seemed to be correct : GFSK 250 Kbit/s

Syma – Step 3 – Understanding Data Link Layer



We spot 1 byte 0b10101010 (0xAA)

→ This kind of preamble is mostly used for Rx synchronisation

Message is 18 bytes (including preamble)

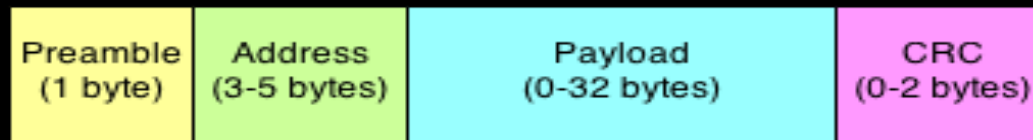
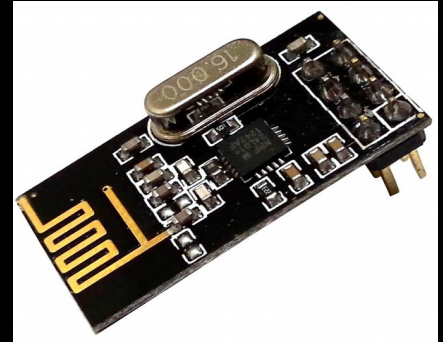
000007f0	00 00 00 01 01 01 00 00	01 00 01 00 01 00 01 00
00000800	01 01 01 01 00 00 00 00	01 01 00 00 00 00 01 00
00000810	00 00 00 01 00 00 01 01	01 00 00 01 01 00 00 01
00000820	01 00 00 01 00 01 00 00	00 00 00 01 00 01 01 00
00000830	01 01 00 00 01 01 01 01	00 00 00 00 01 00 01 00
00000840	00 00 00 00 01 01 00 00	00 01 01 01 00 01 01 01
00000850	01 01 00 00 00 01 00 01	01 00 01 00 01 01 00 00
00000860	00 00 01 01 01 01 00 00	00 01 00 00 00 01 00 00
00000870	01 01 01 01 01 01 00 00	01 00 01 01 00 01 01 01
00000880	01 01 01 00 01 00 00 01	00 00 01 01 01 01 01 00
00000890	01 01 01 01 01 01 00 01	00 01 00 00 01 00 00 00

hexdump -C test3.raw (recorded bit stream)

Syma – Step 3 – Understanding Data Link Layer

Introducing the nRF24l01+ module :

- Transceiver GFSK 2.4GHz on SPI bus
- Very popular module (on drones, RF mouses, DIY projects, ...)
- Come with 2 predefined packet based datalink layers (Basic or Enhanced Shockburst)
- Using 0xAA or 0x55 as preamble
- Using 3 to 5 bytes address
- Using variable payload length (up to 32 bytes in basic mode)
- Can use CRC on 1 or 2 bytes (optional)



Drone preamble is 0xAA which may mean that it is using a nR24l01+

→ Need to see if the rest of the frame matches

Syma – Step 3 – Understanding Data Link Layer

With the help of a python script, we guessed the field sizes from the bit stream recorded with GnuRadio

https://github.com/chopengauer/nrf_analyze/blob/master/nrf24_analyzer.py

```
[root@tigrou Syma X5C-1]# ../../nrf_analyze/nrf24_analyzer.py
Start
0Position 483 offset 483 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 9226 offset 8743 Address alca201670 Data 0000000002000000003 CRC da12 Len 10 preamb = aa
0Position 16875 offset 7649 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 17968 offset 1093 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 25617 offset 7649 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 26710 offset 1093 Address alca201670 Data 0000000002000000003 CRC da12 Len 10 preamb = aa
0Position 34359 offset 7649 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 35452 offset 1093 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 44195 offset 8743 Address alca201670 Data 0000000002000000003 CRC da12 Len 10 preamb = aa
0Position 51845 offset 7650 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 52937 offset 1092 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 60588 offset 7651 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 61681 offset 1093 Address alca201670 Data 0000000002000000003 CRC da12 Len 10 preamb = aa
0Position 69331 offset 7650 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
0Position 79166 offset 9835 Address alca201670 Data 0000000002000000003 CRC da12 Len 10 preamb = aa
0Position 87909 offset 8743 Address alca201670 Data 0000000002000000176 CRC c711 Len 10 preamb = aa
```

In a nutshell :

<u>Preamble</u> (1 byte)	<u>Address</u> (5 bytes)	<u>Syma Protocol</u> (10 bytes)	<u>DataLink CRC</u> (2 bytes)
0xaa	0xa1ca201670		

Note : If we would not have had a SDR, we could have used a pseudo-promiscuous mode of the nRF24l01+ by tuning the module out of its specification. This is quite tricky. Refer to the full report for more information.

Syma – Step 4 – Understanding Syma Protocol

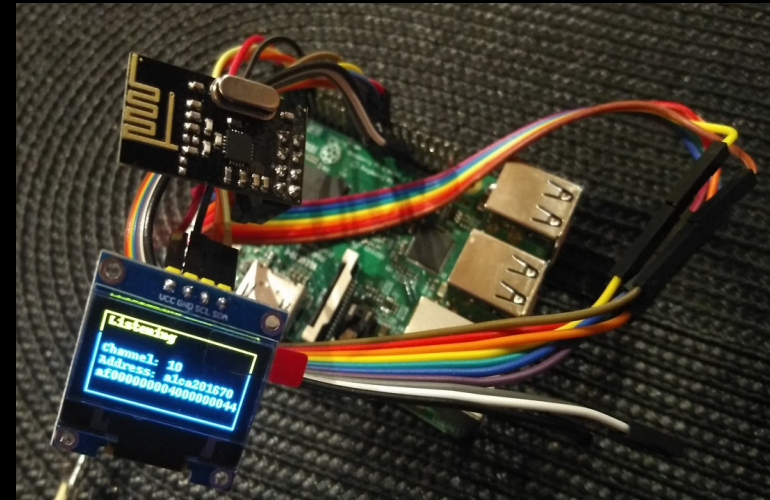
We built a live analyser

- With Raspberry PI and nRF24l01+
- OLED Screen added for THCon

→ By moving the RC controls, we could observe the payload.

Finally, Syma Protocol is quite simple...*

*Except Byte 10 : A pseudo CRC built as a XOR of bytes 1 to 9 and added to 0x55



<u>Preamble</u> (1 byte) 0xaa	<u>Address</u> (5 bytes) 0xa1ca201670	Altitude (1 byte)	Pitch (1 byte)	Roll (1 byte)	Yaw (1 byte)	<u>Other Stuff</u> (5 bytes)	<u>Syma « CRC »</u> (1 byte)	<u>DataLink CRC</u> (2 bytes)
-------------------------------------	---	----------------------	-------------------	------------------	-----------------	---------------------------------	---------------------------------	----------------------------------

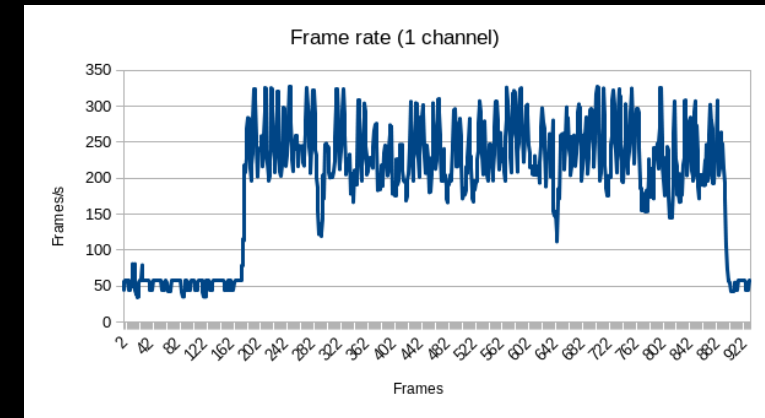
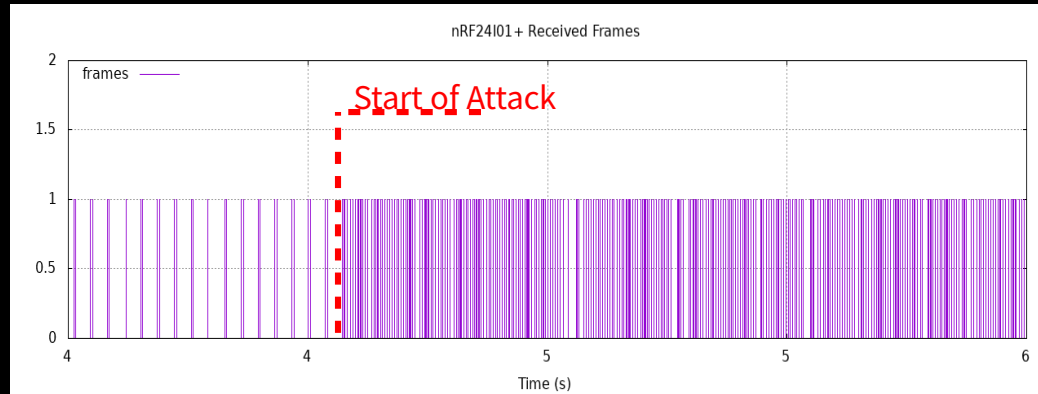
... Now we were ready to implement !

... so we added a USB Gamepad, tuned the code ...

... and finally attacked !

Syma – Attack Characteristics

- Attack is only working when the drone is already paired with a controller
 - Some binding protocol exists (out of scope)
- Drone receives orders both from legit pilot and from predator
 - Attack succeeds because the predator emits a lot more frames than the official remote
- We created a logger with RPI and nRF24l01+ to visualize the difference



Syma – Conclusion

- Syma Protocol quite simple (1 byte per command, no encryption, ...)
- Highjacking a Syma X5C-1 requires very few ressources :
 - 1 Raspberry Pi Zero W (~10€)
 - 1 nRF24l01+ (~0.5€)
 - A few cables
 - 1 USB Gamepad (~5€)
- **Attack is :**
 - Hard to detect by the pilot
 - Easy to detect by an engineer (SDR, ...)
 - Almost impossible to stop without jamming and thus loosing the drone

The Parrot AR.Drone 2.0

- Developed by a French company
- Released in 2012
- Features:
 - OS: Linux 2.6.32
 - CPU: ARM Cortex A8
 - Autonomy: 12"
 - Optional GPS
- Controlled by WiFi
 - Opened WiFi network
 - iOS/Android app



The Parrot AR.Drone 2.0

- Developed by a French company
- Released in 2012
- Features:
 - OS: Linux 2.6.32
 - CPU: ARM Cortex A8
 - Autonomy: 12"
 - Optional GPS
- **Controlled by WiFi**
 - Opened WiFi network
 - iOS/Android app



Vulnerable!



Parrot – Attack principle

- Based on a existing attack (Samy Kamkar)

- Discover drones' WiFi network and clients

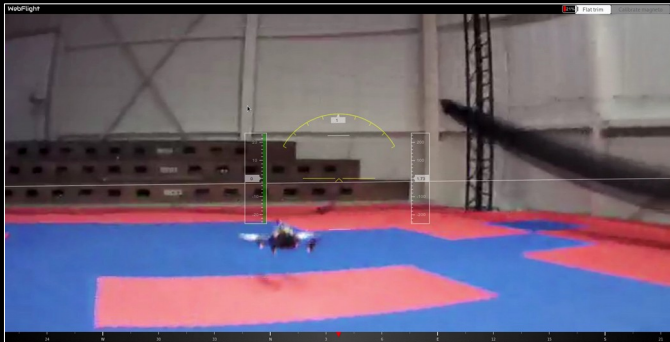
Scapy `sniff` instead of `airodump-ng`

- Disconnect client from network

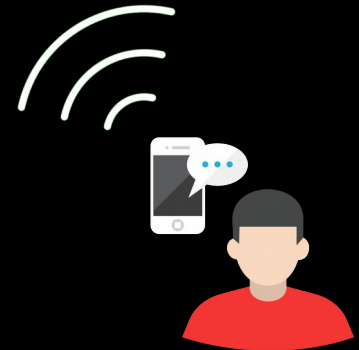
`aireplay-ng`

- Connect to network and control the drone

`ardrone-webflight`



Real connection



Parrot – Attack principle

- Based on a existing attack (Samy Kamkar)

- Discover drones' WiFi network and clients

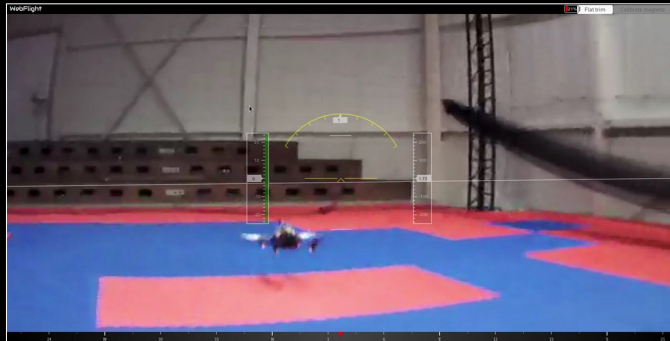
Scapy `sniff` instead of `airodump-ng`

- Disconnect client from network

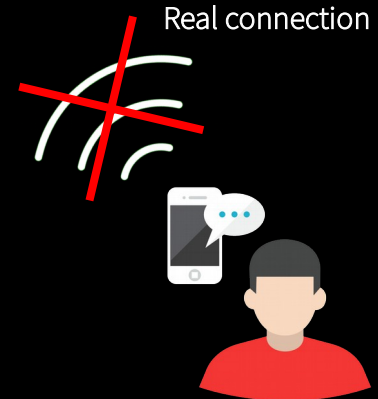
`aireplay-ng`

- Connect to network and control the drone

`ardrone-webflight`



Deauth. attack



Parrot – Attack principle

- Based on a existing attack (Samy Kamkar)

- Discover drones' WiFi network and clients

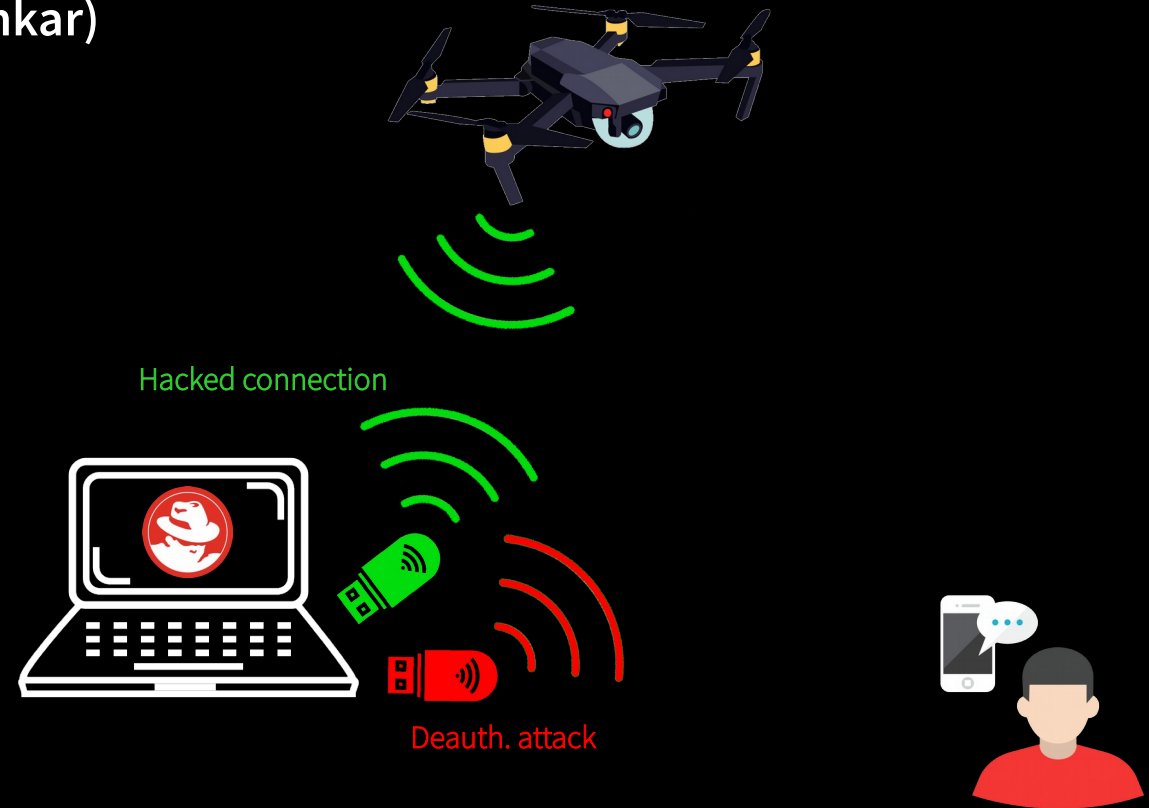
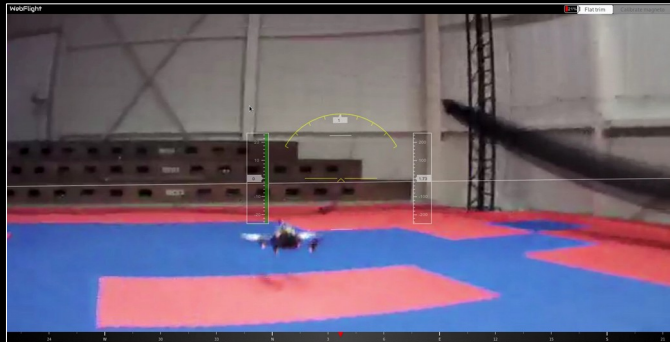
Scapy `sniff` instead of `airodump-ng`

- Disconnect client from network

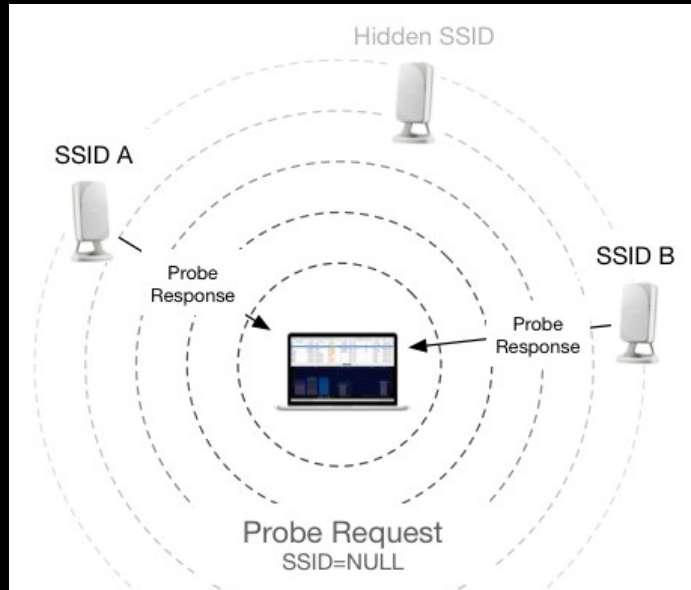
`aireplay-ng`

- Connect to network and control the drone

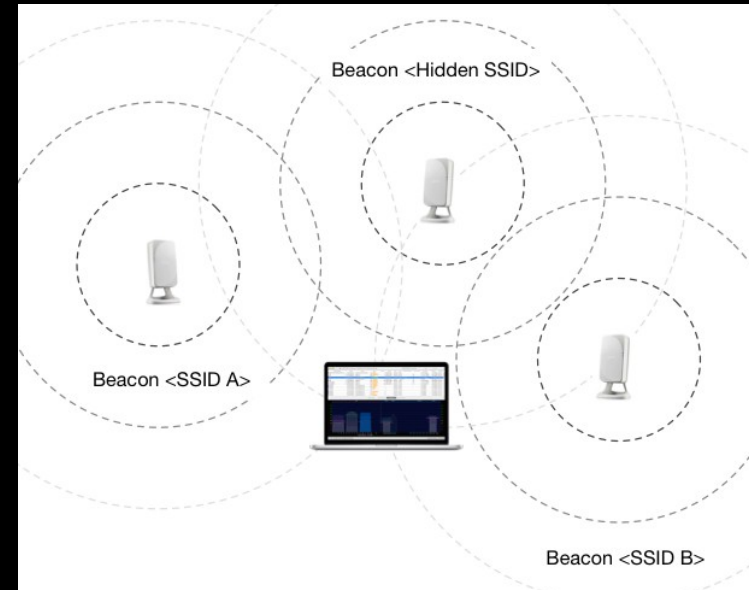
`ardrone-webflight`



Parrot – WiFi network discovering with Scapy

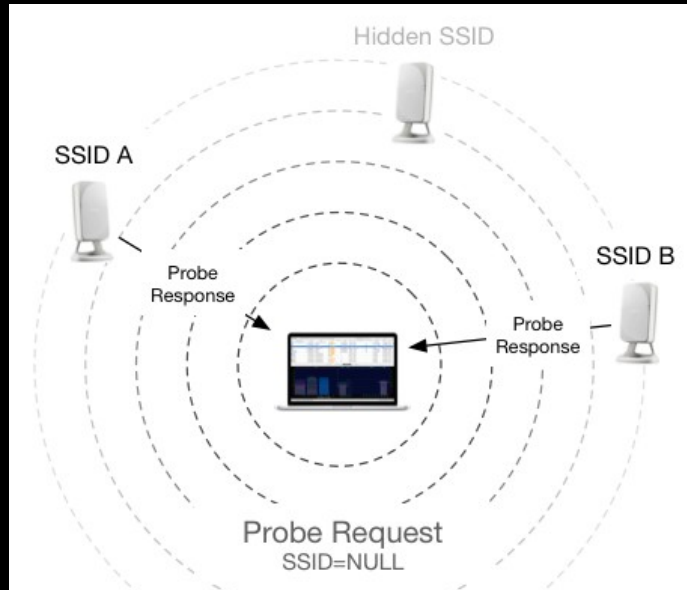


Active scan

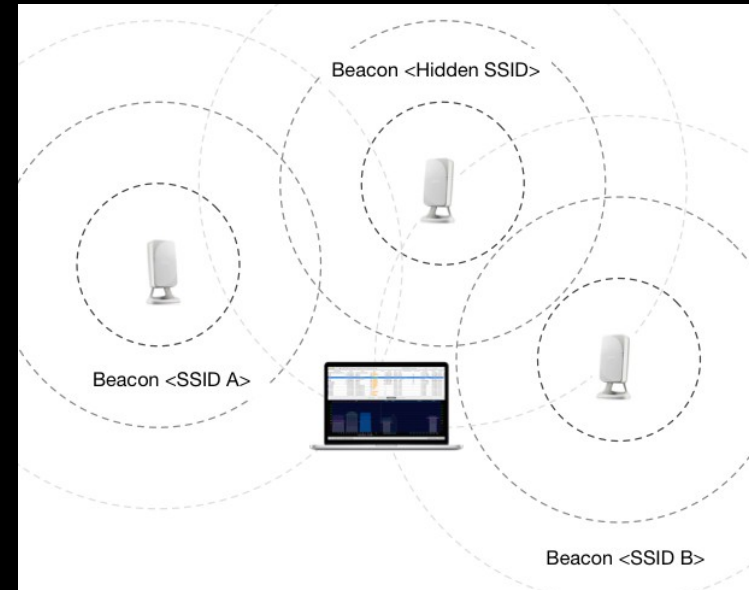


Passive scan

Parrot – WiFi network discovering with Scapy



Active scan



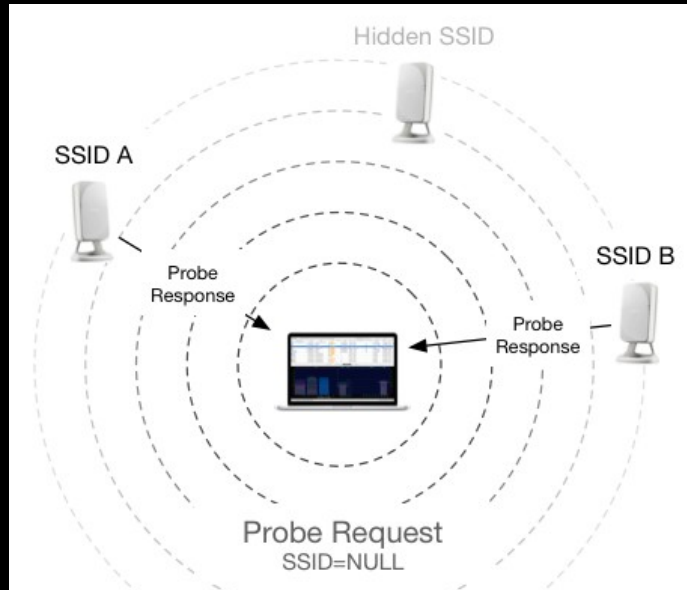
Passive scan

90:03:b7:c8:68:d0

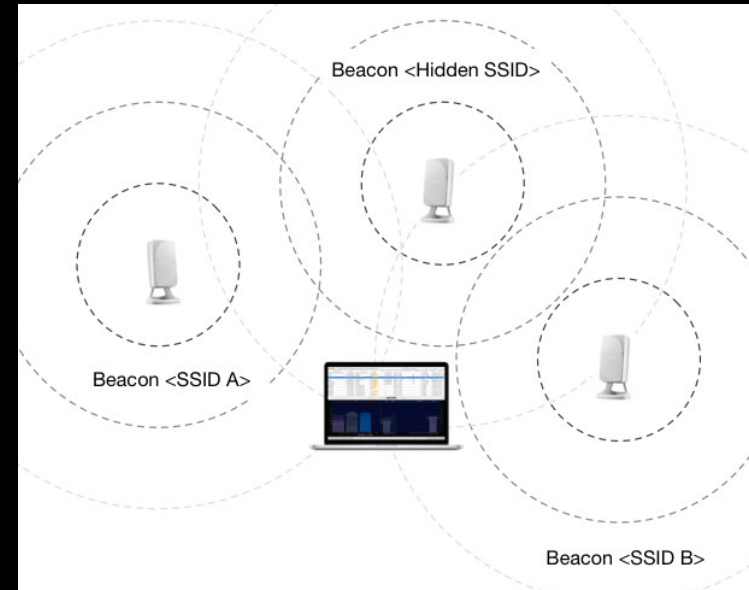
Organisationally Unique
Identifier (OUI)

Network Interface
Controller (NIC) specific

Parrot – WiFi network discovering with Scapy



Active scan



Passive scan

Manufacturer filtering ← 90:03:b7:c8:68:d0

Organisationally Unique Identifier (OUI)	Network Interface Controller (NIC) specific
--	---

Parrot – Embedding tool on a predator drone

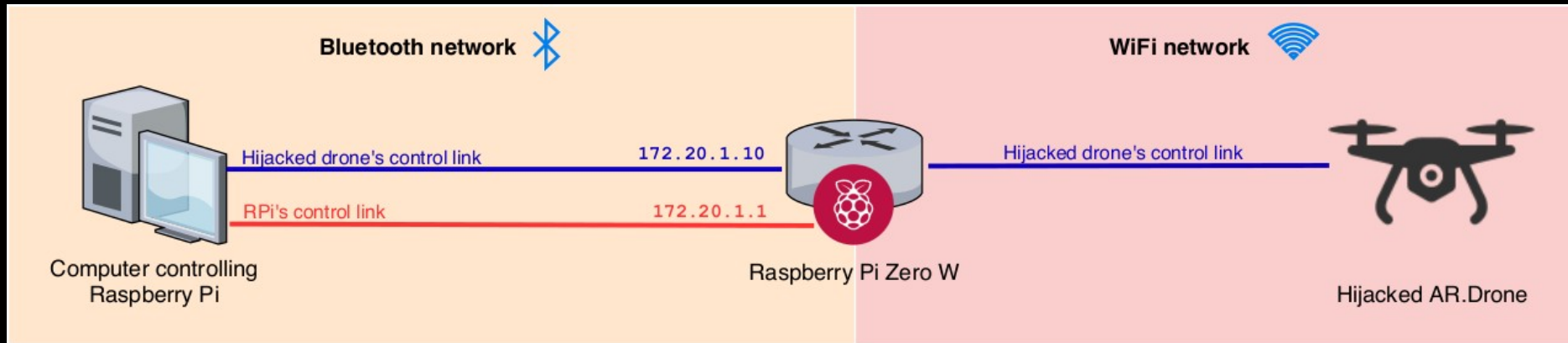
- Embedded tool on a Raspberry Pi Zero W
- Tried reducing network adapter
 - 3 USB WiFi dongles tested
 - Blacklisted driver

Parrot – Embedding tool on a predator drone

- Embedded tool on a Raspberry Pi Zero W
- Tried reducing network adapter
 - 3 USB WiFi dongles tested
 - Blacklisted driver
- Network to control board:
 - Bluetooth PAN
 - SSH connection

Parrot – Embedding tool on a predator drone

- Embedded tool on a Raspberry Pi Zero W
- Tried reducing network adapter
 - 3 USB WiFi dongles tested
 - Blacklisted driver
- Network to control board:
 - Bluetooth PAN
 - SSH connection
- **ardrone-webflight moved to attacker's computer**



Parrot – Protection means

- **Use Parrot's solution**
 - Associate MAC address of real pilot
 - Bypassed by MAC spoofing
- **Do not send beacon frames**
 - Active search of WiFi networks
 - Eventually brute-force searching
- **Encrypt WiFi traffic**
 - Using WPA
 - Parrot Bepop example



Parrot Bepop

Drone-predator hacking Parrot – Demo

