

# Adaptive Targeted Machine Learning of ATE using Highly Adaptive Lasso

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March 2024

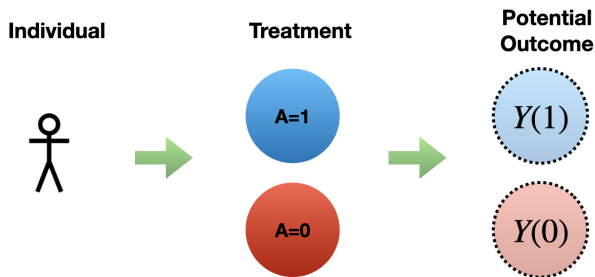
# Problem setup

- Consider an **observational study** of  $n$  *iid* individuals assigned to either *treatment* or *control*.
- We record **baseline covariates**  $W \in \mathbb{R}^d$ , treatment indicator  $A \in \{0, 1\}$ , and an **outcome**  $Y$ , where  $(W, A, Y) \sim P_0$ .

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- Is treatment  $A = 1$  better than control  $A = 0$ ?
- To answer this question, we want inference on the average treatment effect (ATE).

# Potential outcomes framework



What is  $\mathbb{E}[Y(1) - Y(0)]$ ?

# Identification of average treatment effect

- Assume:

- (i) *Consistency*:  $Y(A) = Y$ .
- (ii) *Randomization*:  $(Y(0), Y(1)) \perp\!\!\!\perp A \mid W$ .
- (iii) *Positivity*:  $1 > P_0(A = 1 \mid W) > 0$ .

# Identification of average treatment effect

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  - (iii) *Positivity*:  $1 > P_0(A = 1 \mid W) > 0$ .
- Then, the ATE is identified by a standardized difference in mean outcomes:

$$\mathbb{E}[Y(1) - Y(0)] = E_0 [E_0(Y \mid A = 1, W) - E_0(Y \mid A = 0, W)]$$

# Challenges in ATE estimation

- **Nonparametric** estimators require **strong positivity**:

$$1 - \delta > P_0(A = 1 \mid W) > \delta \text{ for } \delta > 0.$$

- Positivity **violations** are common and lead highly **variable** and **unstable** estimators.

# Challenges in ATE estimation

- However, positivity **assumptions can be relaxed** if we know the functional form of the CATE:

$$\tau_0(W) := E_0[Y \mid A = 1, W] - E_0[Y \mid A = 0, W].$$

- We can extrapolate to areas of limited treatment overlap if the CATE is constant, linear, additive, etc in  $W$ .



# Adaptive Targeted Machine Learning (ATMLE)

- Assuming a parametric model for the CATE *a priori* risks **misspecification bias**.
- Instead, we can be **data-adaptive** and learn a CATE model from data.
- **ATMLE**<sup>1</sup> is a framework that allows us to do adaptive model-selection, while still providing **valid inference** for the ATE.
- **How to learn model?** A HAL of the CATE intrinsically performs LASSO model selection over a rich spline basis.

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<sup>1</sup>L. van der Laan, M. Carone, A. Luedtke, M. van der Laan (2023)

# A risk function for the CATE

- Robinsons' transformation:

$$E_0[Y \mid A, W] = m_0(W) + (A - \pi_0(W))\tau_0(W),$$

with  $m_0(W) = E_0[Y \mid W]$ ,  $\pi_0(W) = P_0(A = 1 \mid W)$ .

- Implies CATE  $\tau_0$  minimizes risk function<sup>2</sup>:

$$\tau \mapsto E_0 \left[ \{Y - m_0(W) - (A - \pi_0(W))\tau(W)\}^2 \right].$$

- Rewrite the above as a weighted LS risk:

$$\tau \mapsto E_0 \left[ \omega_0(A, W) \left\{ \frac{Y - m_0(W)}{A - \pi_0(W)} - \tau(W) \right\}^2 \right],$$

where  $\omega_0(A, W) = \{A - \pi_0(W)\}^2$ .

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<sup>2</sup>Xie and Wager (2017)

## Step 1. Learn nuisance functions:

- 1 Regress  $\{Y_i\}_{i=1}^n$  on  $\{W_i\}_{i=1}^n$  using HAL to obtain estimate  $\hat{m}$  of  $m_0$ .
- 2 Regress  $\{A_i\}_{i=1}^n$  on  $\{W_i\}_{i=1}^n$  using HAL to obtain estimate  $\hat{\pi}$  of  $\pi_0$ .

## Step 2. Learn CATE:

- 1 Get *pseudo-outcomes*  $\{\hat{Z}_i\}_{i=1}^n$  and *pseudo-weights*  $\{\hat{\omega}_i\}_{i=1}^n$ :

$$\hat{Z}_i := \frac{Y_i - \hat{m}(W_i)}{A_i - \hat{\pi}(W_i)}; \quad \hat{\omega}_i := \{A_i - \hat{\pi}(W_i)\}^2.$$

- 2 Obtain estimate  $\hat{\tau}$  of  $\tau_0$  by regressing  $\{\hat{Z}_i\}_{i=1}^n$  on  $\{W_i\}_{i=1}^n$  with weights  $\{\hat{\omega}_i\}_{i=1}^n$  using (relaxed) HAL.

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Step 3. Plug-in to **learn ATE**:  $\psi_n := \frac{1}{n} \sum_{i=1}^n \hat{\tau}(W_i)$  and bootstrap with selected basis functions for confidence intervals.

# Simulation design: How does it perform?

- **Generating process:**

- $X \in \mathbb{R}^4$  and varying levels of treatment overlap.
- Normally distributed outcome with CATE piece-wise linear in some covariates:

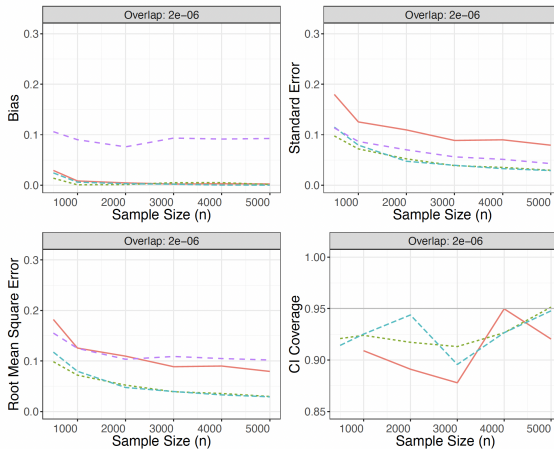
$$\tau_0(x) := 1 + x_1 + |x_2| + \cos(4x_3) + x_4$$

- **Model selection:**

- Specify additive basis for  $\tau_0$  using piece-wise linear hinge functions  $x \mapsto \max\{x - t, 0\}$  with knot  $t \in \mathbb{R}$ .
- CATE model  $\mathcal{T}_n$  is learned using lasso-regularized R-learner over basis (total variation denoising/HAL).

- **Compare:** ATML (2 types) vs AIPW and semiparametric (intercept).

# Simulation results: superefficiency



(a) Limited overlap ( $\alpha_0 \approx 10^{-6}$ )

— AIPW    - - - ADML-partially linear (\*)    - . - ADML-plugin (\*)    - - - semiparametric

**Figure 2:** Comparison of empirical bias, standard error and root mean squared error of estimator, and coverage of nominal 95% confidence interval across 5000 MCMC replications for partially linear and plug-in HAL-ADMLEs, prespecified semiparametric estimator (assuming constant CATE), and nonparametric AIPW estimator, under sampling from a fixed distribution *not* satisfying linearity and with varying degrees of treatment overlap.

# What is HAL-ATMLE estimating?

- Let  $\mathcal{T}_n$  be the linear span of the spline basis functions selected using the HAL estimator  $\hat{\tau}$  of the CATE.

- $\psi_n$  is an efficient estimator of the **data-adaptive parameter**:

$$\Psi_n(P) = E_P[\Pi_n \tau_P(W)]$$

$$\Pi_n \tau_P := \operatorname{argmin}_{\tau \in \mathcal{T}_n} E_P \left[ \pi_P(X) \{1 - \pi_P(X)\} \{\tau_P(X) - \tau(X)\}^2 \right].$$

- We can show  $\sqrt{n}(\psi_n - \Psi_n(P_0)) \rightarrow N(0, \sigma_0^2)$ .
- What about the ATE  $\Psi(P_0) = E_0[\tau_0(W)]$ ?

# Oracle bias due to model approximation

- Under  $P_0$ , assume  $\mathcal{T}_n$  asymptotically **approaches** some limiting **oracle model**  $\mathcal{T}_0$  containing  $\tau_0$ .

- If  $\mathcal{T}_n \subseteq \mathcal{T}_0$ , there exists a function  $\gamma_0 \in \mathcal{T}_0$  such that

$$|\Psi_n(P_0) - \Psi(P_0)| \leq \|\gamma_0 - \Pi_n \gamma_0\| \|\tau_0 - \Pi_n \tau_0\|.$$

- If  $\gamma_0$  and  $\tau_0$  have bounded sectional variation norm, then

$$\|\gamma_0 - \Pi_n \gamma_0\| \|\tau_0 - \Pi_n \tau_0\| = o_p(n^{-1/2});$$

$$\sqrt{n}(\psi_n - \Psi(P_0)) \rightarrow N(0, \sigma_0^2).$$



# What else is HAL-ATMLE estimating?

- Under  $P_0$ , assume  $\mathcal{T}_n$  asymptotically **approaches** some limiting **oracle model**  $\mathcal{T}_0$  containing  $\tau_0$ .
- Then,  $\psi_n$  is an efficient estimator of the **oracle parameter**:

$$\Psi_0(P) := E_P [\Pi_{0\mathcal{T}_P}(X)]$$

$$\Pi_{0\mathcal{T}_P} := \operatorname{argmin}_{\tau \in \mathcal{T}_0} E_P \left[ \pi_P(X) \{1 - \pi_P(X)\} \{\tau_P(X) - \tau(X)\}^2 \right].$$

## Note:

- **Same estimand:** If  $\tau_0 \in \mathcal{T}_0$ , then  $\Psi(P_0) = \Psi_0(P_0)$ .
- **Different efficiency bound:** Efficiency bound of  $\Psi_0$  driven by size of  $\mathcal{T}_0$ .

# Concluding remarks

ATML is a general framework for adaptive and superefficient inference using data-driven model selection.

- ATML shows superefficiency is a continuum — not a dichotomy.
- ATML includes nonparametric regular and efficient estimators as a special case.
- ATML provides a means for nonparametric inference when regular estimators do not exist or behave poorly.
- ATML can beat any prespecified (semi)parametric estimator by learning a working model containing their model.

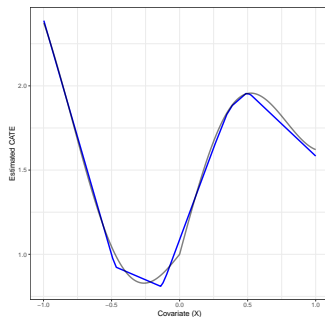
# Setup and Data Generation

```
# Install causalHAL branch of hal9001 Github package
devtools::install_github("tlverse/hal9001@causalHAL")
library(hal9001)

# Generate data
n <- 1000
X <- runif(n, -1, 1)
pi.true <- plogis(-1 + abs(X) + X^2 + 0.5*sin(4*X))
A <- rbinom(n, 1, pi.true)
m.true <- 2*X^2 + pi.true * (1 + abs(X) + 0.5*sin(4*X))
cate.true <- (1 + abs(X) + 0.5*sin(4*X))
mu.true <- m.true + (A - pi.true) * cate.true
Y <- rnorm(n, mu.true, 0.2)
```

# Estimate CATE using HAL

```
# HAL model fitting
cate_fit <- fit_hal_cate(X, Y, A,
  smoothness_orders = 1,
  num_knots = 100,
  max_degree = 1)
cate.hat <- predict(cate_fit, X)
```



# Customize HAL nuisance estimators

```
fit_hal_cate(X, Y, A,  
             smoothness_orders = 1,  
             num_knots = 100,  
             max_degree = 1,  
             A_fit_params = list(smoothness_orders = 1,  
                                  num_knots = 100,  
                                  max_degree = 1),  
             Y_fit_params = list(smoothness_orders = 1,  
                                  num_knots = 100,  
                                  max_degree = 1))
```

## Specify custom nuisance estimates

```
# Estimate  $E[Y|X]$ 
A_fit <- fit_hal(X, A, smoothness_orders = 1,
                num_knots = 100, max_degree = 1,
                return_cv_predictions = TRUE)
A.hat <- A_fit$cv_predictions

# Estimate  $E[Y|X]$ 
Y_fit <- fit_hal(X, Y, smoothness_orders = 1,
                num_knots = 100, max_degree = 1,
                return_cv_predictions = TRUE)
Y.hat <- Y_fit$cv_predictions

# Pass in custom nuisance estimates.
cate_fit <- fit_hal_cate(X, Y, A, smoothness_orders = 1,
                        num_knots = 100, max_degree = 1
                        A.hat = A.hat, Y.hat = Y.hat)
```

# Bootstrap-assisted Inference for CATE and ATE

```
# Bootstrap the HAL fit
bootstrapped_cate_fit <- bootstrap_hal(cate_fit)

# Pointwise inference on new data
out <- inference_pointwise(bootstrapped_cate_fit,
                           new_data = X)
```

prediction <dbl>	CI_lower <dbl>	CI_right <dbl>
1.7722840	1.7165366	1.8261782
1.8839604	1.8154606	1.9537709
1.2509638	1.1762711	1.3141461
0.8408733	0.7752579	0.9203952
1.2511315	1.1764752	1.3143329
2.1626062	2.0774746	2.2412668

# Inference for Functionals of CATE

```
# Functional inference for ATE
functional_mean <- function(hal_fit, X, ...) {
  mean(predict(hal_fit, X))
}
out <- inference_delta_method(
  bootstrapped_cate_fit,
  functional = functional_mean)
```

estimate <dbl>	CI_lower <dbl>	CI_right <dbl>
1.492985	1.449743	1.529833



# Outline of general framework

- **Pathwise differentiable parameter**  $\Psi : \mathcal{M}_{np} \rightarrow \mathbb{R}$  on nonparametric model  $\mathcal{M}_{np}$ .
- **Learn from data** a working model  $\mathcal{M}_n \subset \mathcal{M}_{np}$ .
- Let  $\mathcal{M}_n$  **stabilize** appropriately to an *oracle model*  $\mathcal{M}_0$ .
- Define projection-based **working parameter** and **oracle parameter**:

$$\Psi_n := \Psi \circ \Pi_n \text{ for } \Pi_n : \mathcal{M}_{np} \rightarrow \mathcal{M}_n;$$

$$\Psi_0 := \Psi \circ \Pi_0 \text{ for } \Pi_0 : \mathcal{M}_{np} \rightarrow \mathcal{M}_0$$

- **Oracle bias** is second order:

$$\Psi_n(P_0) - \Psi_0(P_0) = (\Pi_n P_0 - P_0)\{D_{\Psi_0, P_0} - \Pi_n D_{\Psi_0, P_0}\} + \text{Rem}_n.$$

- Construct **debiased** estimator  $\psi_n$  of  $\Psi_n(P_0)$  using DML/TML.
- Under conditions,  $\psi_n$  is locally RAL and efficient for  $\Psi_0$ .

- Robinson, Peter M. "Root-N-consistent semiparametric regression." *Econometrica: Journal of the Econometric Society* (1988): 931-954.
- van der Laan, Lars, Marco Carone, Alex Luedtke, and Mark van der Laan. "Adaptive debiased machine learning using data-driven model selection techniques." *arXiv preprint arXiv:2307.12544* (2023).