# Financial Time Series

Lecture 2

Multiple regression, Decomposition and Smoothing

# Multiple regression and forecasting

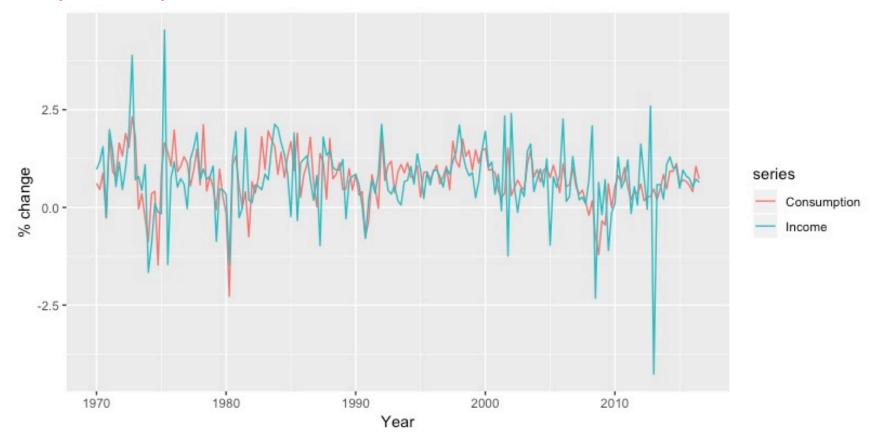
$$y_t = \beta_0 + \beta_1 x_{1,t} + \beta_2 x_{2,t} + \dots + \beta_k x_{k,t} + \varepsilon_t$$

- $y_t$  is the variable we want to predict: the "response" variable
- Each  $x_{j,t}$  is numerical and is called a "predictor". They are usually assumed to be known for all past and future times.
- The coefficients  $\beta_1, \ldots, \beta_k$  measure the effect of each predictor after taking account of the effect of all other predictors in the model.

That is, the coefficients measure the marginal effects.

•  $\varepsilon_t$  is a white noise error term

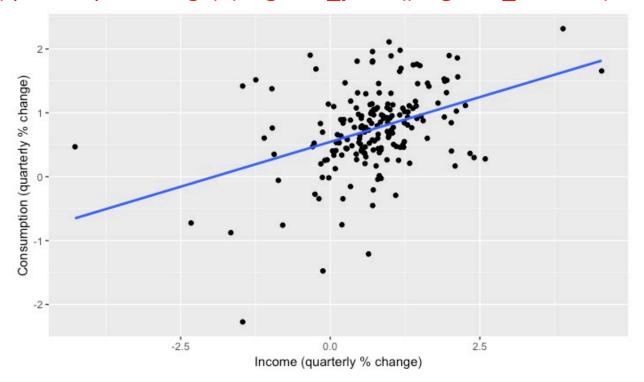
autoplot(uschange[,c("Consumption","Income")]) + ylab("% change")+ xlab("Year")



```
uschange %>%
```

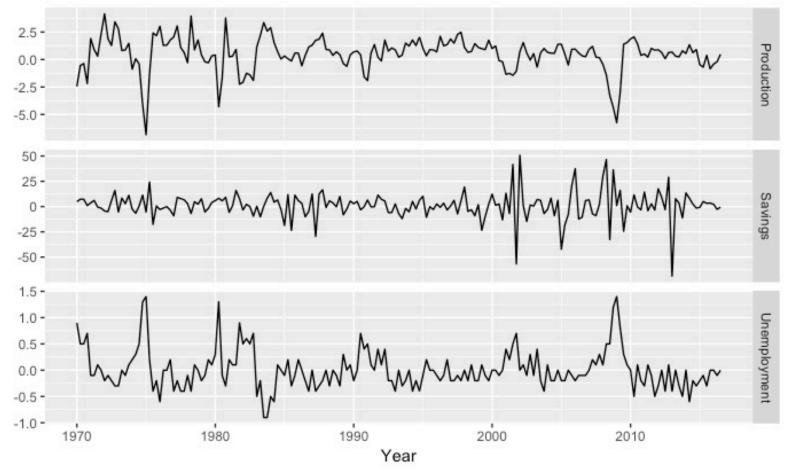
as.data.frame() %>%

ggplot(aes(x=Income, y=Consumption)) + ylab("Consumption (quarterly % change)") +
xlab("Income (quarterly % change)") + geom\_point() + geom\_smooth(method="Im", se=FALSE)

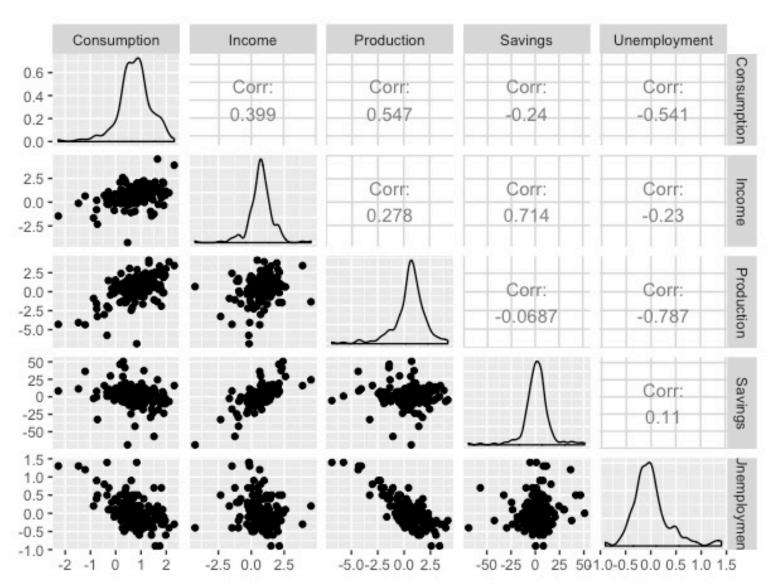


• tslm(Consumption ~ Income, data=uschange) %>% summary Call: tslm(formula = Consumption ~ Income, data = uschange) Residuals: Min 10 Median 30 Max -2.40845 -0.31816 0.02558 0.29978 1.45157 Coefficients: Estimate Std. Error t value Pr(>|t|) (Intercept) 0.54510 0.05569 9.789 < 2e-16 \*\*\* Income 0.28060 0.04744 5.915 1.58e-08 \*\*\* Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1 Residual standard error: 0.6026 on 185 degrees of freedom Multiple R-squared: 0.159, Adjusted R-squared: 0.1545 F-statistic: 34.98 on 1 and 185 DF, p-value: 1.577e-08

autoplot(uschange[,3:5], facets=TRUE) + xlab("Year")+ ylab("")



- install.packages("GGally")
- library("GGally")
- ggpairs(as.data.frame(usdata[,1:5]))

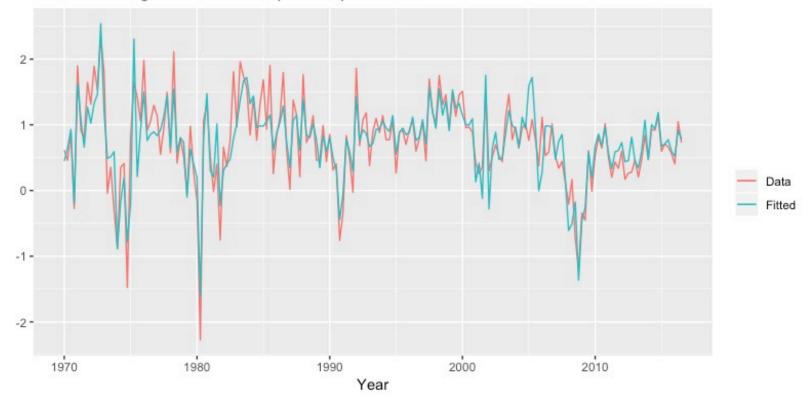


• fit.consMR <- tslm( Consumption ~ Income + Production + Unemployment + Savings, data=uschange) summary(fit.consMR) Call: tslm(formula = Consumption ~ Income + Production + Unemployment + Savings, data = uschange) Residuals: 10 Median 30 Max -0.88296 -0.17638 -0.03679 0.15251 1.20553 Coefficients: Estimate Std. Error t value Pr(>|t|) (Intercept) 0.26729 0.03721 7.184 1.68e-11 \*\*\* 0.71449 0.04219 16.934 < 2e-16 \*\*\* Income Production 0.04589 0.02588 1.773 0.0778. Savings -0.04527 0.00278 -16.287 < 2e-16 \*\*\* Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1 Residual standard error: 0.3286 on 182 degrees of freedom Multiple R-squared: 0.754, Adjusted R-squared: 0.7486

F-statistic: 139.5 on 4 and 182 DF, p-value: < 2.2e-16

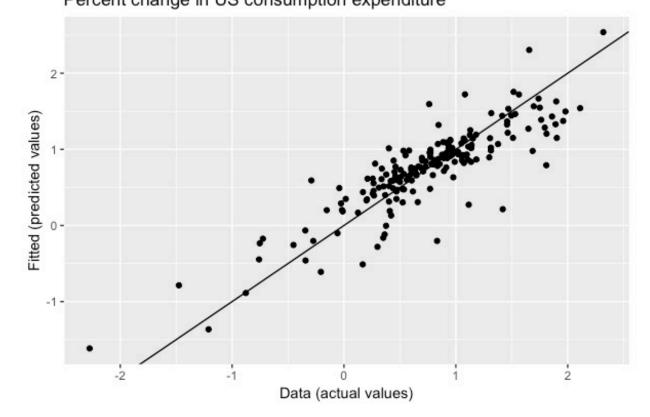
autoplot(uschange[,'Consumption'], series="Data") + autolayer(fitted(fit.consMR), series="Fitted") + xlab("Year") + ylab("") + ggtitle("Percent change in US consumption expenditure") + guides(colour=guide\_legend(title=" "))

#### Percent change in US consumption expenditure

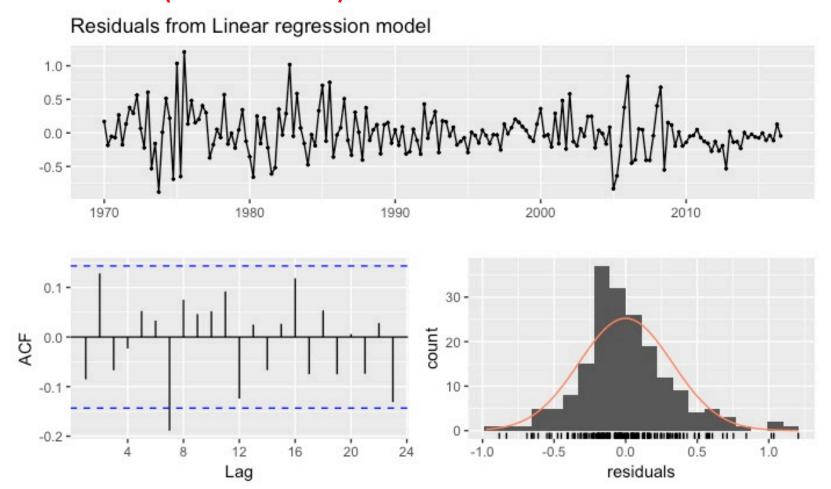


cbind(Data = uschange[,"Consumption"], Fitted = fitted(fit.consMR)) %>% as.data.frame() %>% ggplot(aes(x=Data, y=Fitted)) + geom\_point() + ylab("Fitted (predicted values)") + xlab("Data (actual values)") + ggtitle("Percent change in US consumption expenditure") + geom\_abline(intercept=0, slope=1)

Percent change in US consumption expenditure



checkresiduals(fit.consMR)



# Multiple regression and forecasting

For forecasting purposes, we require the following assumptions:

- $\varepsilon_t$  are uncorrelated and zero mean
- $\varepsilon_t$  are uncorrelated with each  $x_{i,t}$

It is useful to also have  $\varepsilon_t \sim N(0, \sigma^2)$  when producing prediction intervals or doing statistical tests.

# Trend and Dummy variables

Linear trend

$$x_t = t, \quad t = 1, 2, ..., T$$

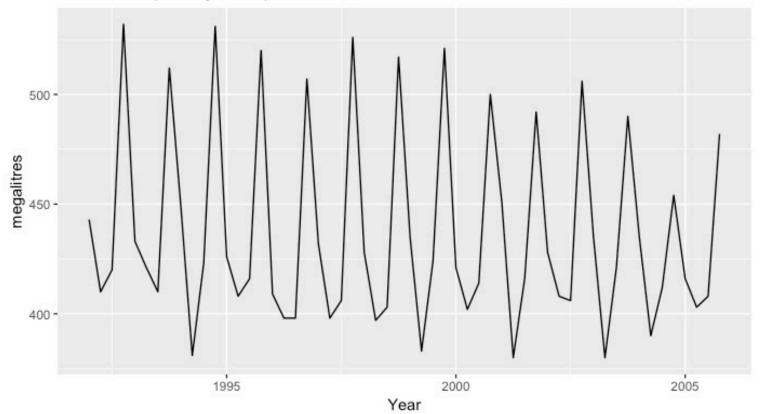
Strong assumption that trend will continue

• If a categorical variable takes only two values (e.g., 'Yes' or 'No'), then an equivalent numerical variable can be constructed taking value 1 if yes and 0 if no. This is called a dummy variable

### Example Beer Production

- beer2 <- window(ausbeer,start=1992,end=2006-.1)</li>
- autoplot(beer2) + labs(title="Australian quartely beer production",x="Year",y="megalitres")

Australian quartely beer production



### Example Beer Production

```
    fit <- tslm(beer2 ~ trend + season)</li>

summary(fit)
Call:
tslm(formula = beer2 ~ trend + season)
esiduals:
 Min 10 Median 30 Max
-44.024 -8.390 0.249 8.619 23.320
Coefficients:
     Estimate Std. Error t value Pr(>|t|)
(Intercept) 441.8141  4.5338 97.449 < 2e-16 ***
        trend
season2 -34.0466 4.9174 -6.924 7.18e-09 ***
season3 -18.0931 4.9209 -3.677 0.000568 ***
season4 76.0746 4.9268 15.441 < 2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
Residual standard error: 13.01 on 51 degrees of freedom
Multiple R-squared: 0.921, Adjusted R-squared: 0.9149
F-statistic: 148.7 on 4 and 51 DF, p-value: < 2.2e-16
```

### Example Beer Production

- x1=1:56
- x2=rep(c(0,1,0,0),14)
- x3=rep(c(0,0,1,0),14)
- x4=rep(c(0,0,0,1),14)
- f1=lm(beer2~x1+x2+x3+x4)
- summary(f1)
- Then we have the same result as in the previous slide.

### Selecting Predictors

- When there are many predictors, how should we choose which ones to use?
- We need a way of comparing two competing models.

#### What not to do!

- Plot y against a particular predictor  $(x_j)$  and if it shows no noticeable relationship, drop it.
- Do a multiple linear regression on all the predictors and disregard all variables whose p values are greater than 0.05.
- Maximize  $R^2$  or minimize MSE

# Adjusted $R^2$

$$\bar{R}^2 = 1 - (1 - R^2) \frac{T - 1}{T - k - 1}$$

• This is an improvement on  $R^2$ , as it will no longer increase with each added predictor. Using this measure, the best model will be the one with the largest value of  $\bar{R}^2$ . Maximizing  $\bar{R}^2$  is equivalent to minimizing the standard error  $\hat{\sigma}_{\epsilon}$ .

### Akaike's Information Criterion

$$AIC = -2 \log(L) + 2(k+2)$$

where L is the likelihood and k is the number of predictors in the model.

- This is a penalized likelihood approach.
- Minimizing the AIC gives the best model for prediction.
- AIC penalizes terms more heavily than  $\bar{R}^2$ .

### Bayesian Information Criterion

$$BIC = -2 \log(L) + (k + 2) \log(T)$$

where L is the likelihood and k is the number of predictors in the model.

- BIC penalizes terms more heavily than AIC
- Also called SBIC and SC.

### Choosing regression variables

#### Backwards stepwise regression

- Start with a model containing all variables.
- Try subtracting one variable at a time. Keep the model if it has lower AIC.
- Iterate until no further improvement.

#### Notes

- Stepwise regression is not guaranteed to lead to the best possible model.
- Inference on coefficients of final model will be wrong.

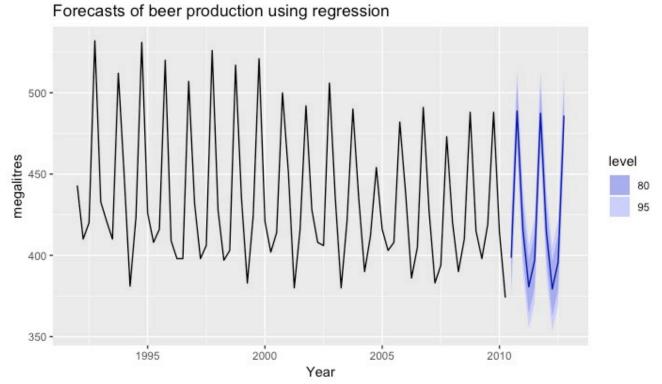
# How to know if the model is best fit for your data?

STATISTIC	CRITERION
R-Squared	Higher the better (> 0.70)
Adj R-Squared	Higher the better
F-Statistic	Higher the better
Std. Error	Closer to zero the better
t-statistic	Should be greater 1.96 for p-value to be less than 0.05
AIC	Lower the better
BIC	Lower the better

# Forecasting in Beer production example

- beer2 <- window(ausbeer, start=1992)</li>
- fit.beer <- tslm(beer2 ~ trend + season)</li>

fcast <- forecast(fit.beer) autoplot(fcast) + ggtitle("Forecasts of beer production using regression")</li>
 + xlab("Year") + ylab("megalitres")



### Time series components

#### Recall

- Trend pattern exists when there is a long-term increase or decrease in the data.
- Cyclic pattern exists when data exhibit rises and falls that are not of fixed period (duration usually of at least 2 years).
- Seasonal pattern exists when a series is influenced by seasonal factors (e.g., the quarter of the year, the month, or day of the week).

### Time series decomposition

$$y_t = S_t + T_t + R_t$$

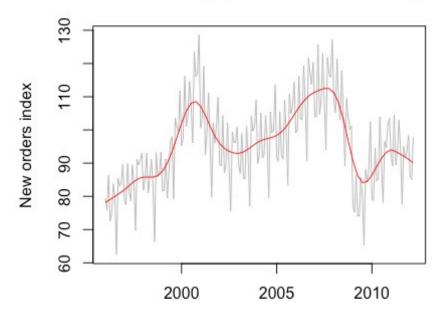
#### where

- $y_t$  = data at period t
- $T_t$  = trend-cycle component at period t
- $S_t$  = seasonal component at period t
- $R_t$  = remainder component at period t

# Electrical equipment manufacturing example

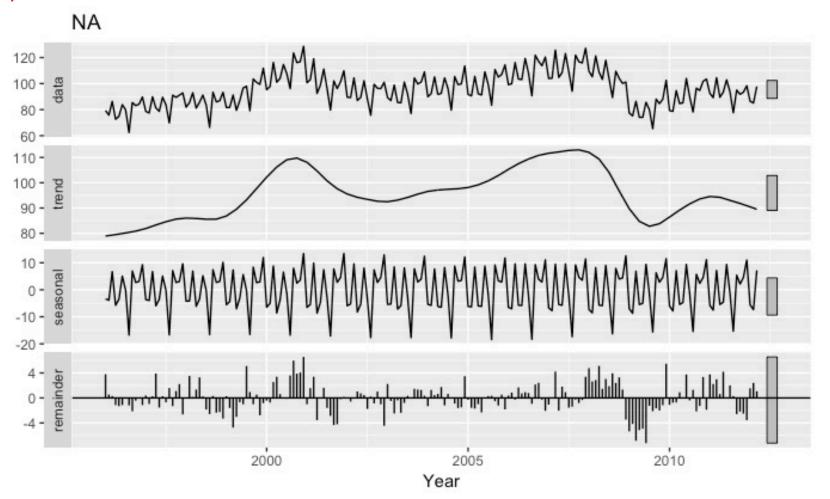
- fit <- stl(elecequip, s.window=5)</li>
- plot(elecequip, col="gray", main="Electrical equipment manufacturing", ylab="New orders index", xlab="") lines(fit\$time.series[,2],col="red",ylab="Trend")

#### Electrical equipment manufacturing



# Electrical equipment manufacturing example

- fit <- stl(elecequip, s.window=7)</li>
- autoplot(fit) + xlab("Year")



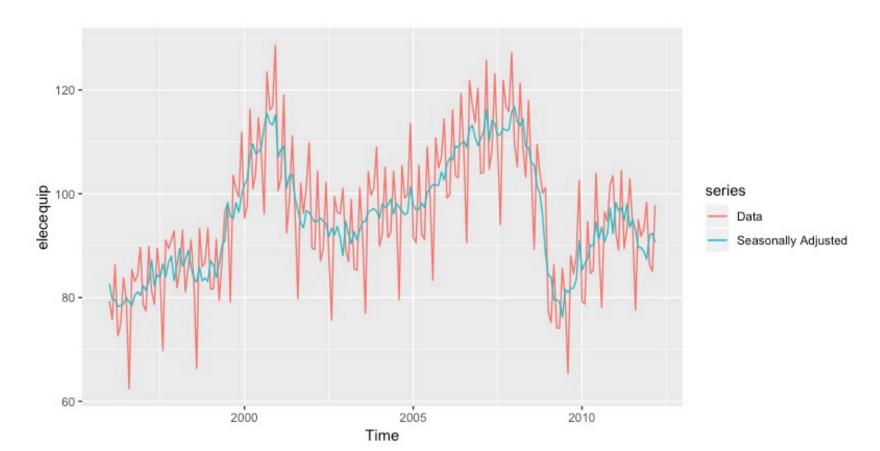
### Seasonal adjustment

- Useful by-product of decomposition: an easy way to calculate seasonally adjusted data.
- seasonally adjusted data given by

$$y_t - S_t = T_t + R_t$$

# Electrical equipment manufacturing example

- fit <- stl(elecequip, s.window=7)
- autoplot(elecequip, series="Data") + autolayer(seasadj(fit), series="Seasonally Adjusted")



### Forecast with decomposition

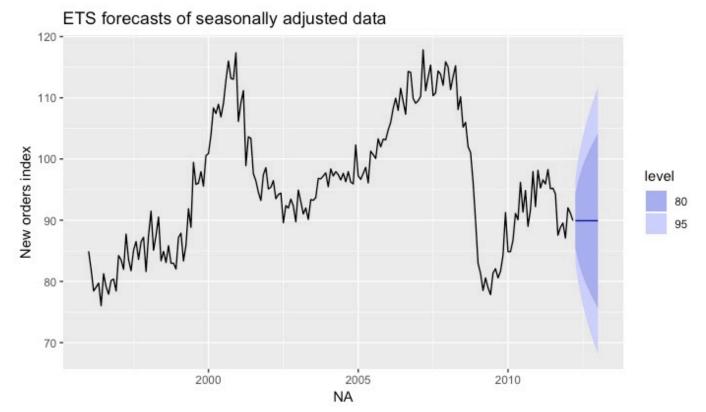
• Assuming an additive decomposition, the decomposed time series can be written as  $y_t = \hat{S}_t + \hat{A}_t$ ,

where  $\hat{A}_t = \hat{T}_t + \hat{R}_t$  is the seasonally adjusted component.

• To forecast a decomposed time series, we forecast the seasonal component,  $\hat{S}_t$ , and the seasonally adjusted component  $\hat{A}_t$ , separately.

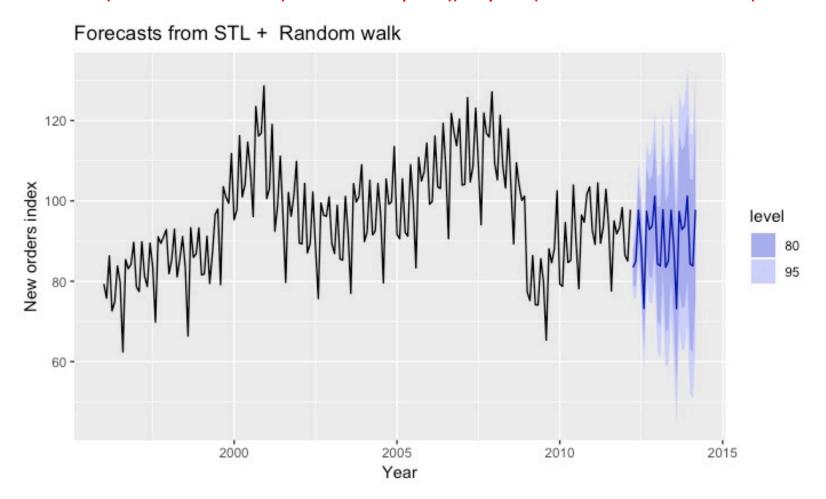
### Forecast with decomposition

- fit <- stl(elecequip, t.window=13, s.window="periodic")</li>
- fit %>% seasadj() %>% naive() %>%
- autoplot() + ylab("New orders index") + ggtitle("ETS forecasts of seasonally adjusted data")



### Forecast with decomposition

fit %>% forecast(method='naive') %>% autoplot() + ylab("New orders index") + xlab("Year")



# Moving average smoothing

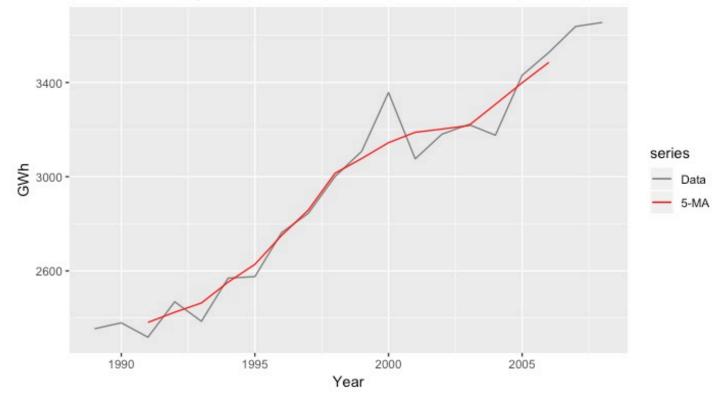
A moving average of order m can be written as

$$\widehat{T}_t = \frac{1}{m} \sum_{j=-k}^{k} y_{t+j}, \qquad m = 2k+1$$

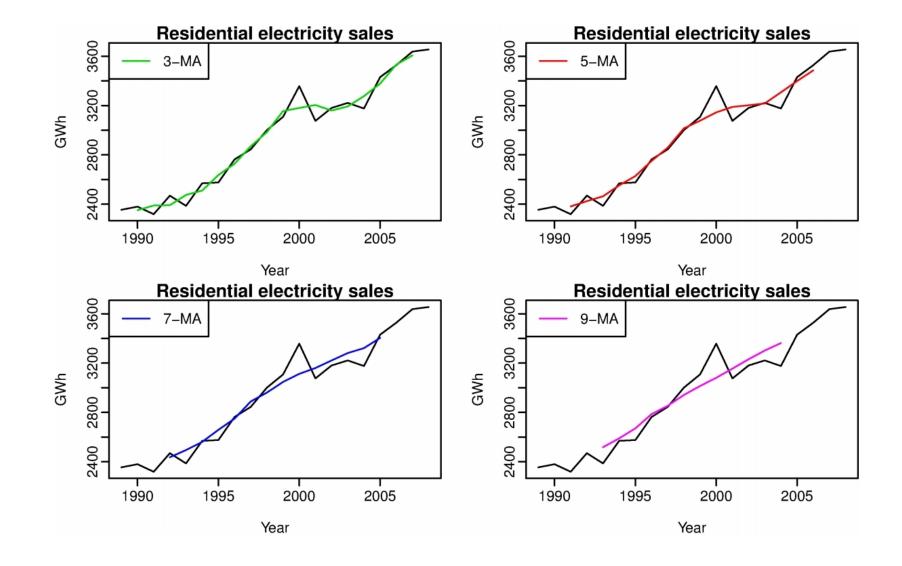
### Moving average smoothing

autoplot(elecsales, series="Data") + autolayer(ma(elecsales,5), series="5-MA") + xlab("Year") + ylab("GWh") + ggtitle("Annual electricity sales: South Australia") + scale\_colour\_manual(values=c("Data"="grey50","5-MA"="red"), breaks=c("Data","5-MA"))

#### Annual electricity sales: South Australia



# Moving average at different orders



### Moving average of moving average

- One reason for doing this is to make an even-order moving average symmetric.
- A 2x4-MA can be written as

$$\frac{1}{2} \left[ \frac{1}{4} (y_{t-2} + y_{t-1} + y_t + y_{t+1}) + \frac{1}{4} (y_{t-1} + y_t + y_{t+1} + y_{t+2}) \right] 
= \frac{1}{8} y_{t-2} + \frac{1}{4} y_{t-1} + \frac{1}{4} y_t + \frac{1}{4} y_{t+1} + \frac{1}{8} y_{t+2}.$$

 In general, an even order MA should be followed by an even order MA to make it symmetric. Similarly, an odd order MA should be followed by an odd order MA.

# Estimating trend cycle with seasonal data

- The  $2 \times 4$ -MA can be used to estimate quarterly data.
- 2×m-MA v.s. m+1-MA.
- If the seasonal period is even and of order m, use 2 × m-MA to estimate the trend cycle.
- If it's odd, then use m-MA to estimate the trend cycle.
- Thus 2 × 12-MA for monthly trend, and 7-MA for daily trend.

# Electrical equipment manufacturing

autoplot(elecequip, series="Data") + autolayer(ma(elecequip, 12), series="12-MA") + xlab("Year") + ylab("New orders index") + ggtitle("Electrical equipment manufacturing (Euro area)") + scale\_colour\_manual(values=c("Data"="grey","12-MA"="red"), breaks=c("Data","12-MA"))

Electrical equipment manufacturing (Euro area) 120 -New orders index series 100 -Data 12-MA 80 -60 -

2005

Year

2010

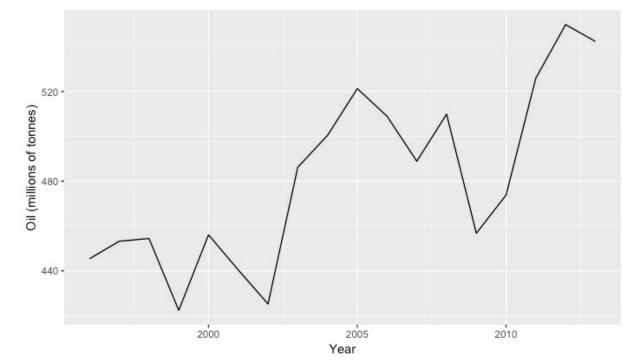
2000

# Smoothing

• The simplest of the exponentially smoothing methods is naturally called **simple exponential smoothing** (SES). This method is suitable for forecasting data with no clear trend or seasonal pattern.

• oildata <- window(oil, start=1996) autoplot(oildata) + ylab("Oil (millions of tonnes)") +

xlab("Year")



#### Models

Previously we discussed the naive method:

$$\hat{y}_{T+h} = y_T$$
 for all h

Thus the most recent obs. is the only important one for prediction purposes.

• The other method we mentioned, the average method:

$$\hat{y}_{T+h} = \frac{1}{T} \sum_{t=1}^{I} y_t$$

Thus all obs. are of equal importance for forecasting.

 Naturally, intuition tells us that a better forecasting method should lie in between these two extremes. More recent obs. should be more important and assigned more weights.

#### SES model

 Forecasts are calculated using weighted averages with exponential decaying weights.

$$\hat{y}_{T+1|T} = \alpha y_T + \alpha (1-\alpha) y_{T-1} + \alpha (1-\alpha)^2 y_{T-2} + \dots + (1-\alpha)^T y_{1|0}$$

 $\alpha$  is a smoothing parameter.

Obs.	$\alpha = 0.2$	$\alpha = 0.4$	$\alpha = 0.6$	$\alpha = 0.8$
УТ	0.2	0.4	0.6	0.8
$y_{T-1}$	0.16	0.24	0.24	0.16
<i>УТ</i> -2	0.128	0.144	0.096	0.032
<i>УТ</i> -3	0.1024	0.0864	0.0384	0.0064

• The weight goes down exponentially. When  $\alpha = 1$ , this reduces to the naive estimate.

# Weighted average form

• By definition, the forecast at t+1 equals to a weighted average between the most recent obs.  $y_t$  and the most recent forecast:

$$\hat{y}_{t+1|t} = \alpha y_t + (1-\alpha)\hat{y}_{t|t-1}.$$

$$\hat{y}_{2|1} = \alpha y_1 + (1 - \alpha)\ell_0$$

$$\hat{y}_{3|2} = \alpha y_2 + (1 - \alpha)\hat{y}_{2|1}$$

$$\hat{y}_{4|3} = \alpha y_3 + (1 - \alpha)\hat{y}_{3|2}$$

$$\vdots$$

$$\hat{y}_{T+1|T} = \alpha y_T + (1 - \alpha)\hat{y}_{T|T-1}$$

# Weighted average form

By substitution we have

$$\hat{y}_{3|2} = \alpha y_2 + (1 - \alpha) \left[ \alpha y_1 + (1 - \alpha) \ell_0 \right]$$

$$= \alpha y_2 + \alpha (1 - \alpha) y_1 + (1 - \alpha)^2 \ell_0$$

$$\hat{y}_{4|3} = \alpha y_3 + (1 - \alpha) \left[ \alpha y_2 + \alpha (1 - \alpha) y_1 + (1 - \alpha)^2 \ell_0 \right]$$

$$= \alpha y_3 + \alpha (1 - \alpha) y_2 + \alpha (1 - \alpha)^2 y_1 + (1 - \alpha)^3 \ell_0$$

$$\vdots$$

$$\hat{y}_{T+1|T} = \sum_{j=0}^{T-1} \alpha (1 - \alpha)^j y_{T-j} + (1 - \alpha)^T \ell_0.$$

#### Component form

- Time series components consist of level, trend, and seasonal component.
- ullet For simple exponential smoothing, only level  $I_t$  is needed

Forecast equation 
$$\hat{y}_{t+1|t} = I_t$$
  
Smoothing equation  $I_t = \alpha y_t + (1 - \alpha)I_{t-1}$ ,

where  $I_t$  is the level of the time series at time t.

#### Error correction form

• We can rearrange the component form to get the following, where  $e_t$  is the one step within-sample forecast error at time t.

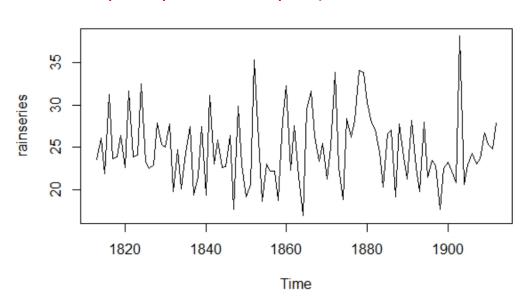
$$I_t = I_{t-1} + \alpha (y_t - I_{t-1})$$
  
=  $I_{t-1} + \alpha e_t$ 

where 
$$e_t = y_t - I_{t-1} = y_t - \hat{y}_{t|t-1}$$
 for  $t = 1, \dots, T$ .

- If the error at time t is negative, then the level at t 1 is overestimated. The new level is then the previous level adjusted downwards.
- $\bullet$   $\alpha$  controls the smoothness of the level forecast, smaller implies smoother.
- We can obtain the optimal  $\alpha$  via minimizing the SSE

#### Simple exponential smoothing example

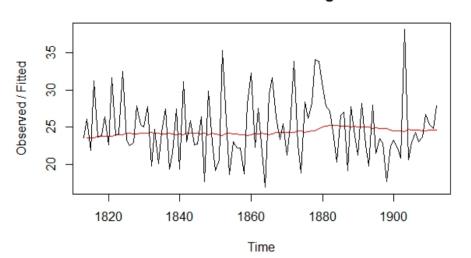
- If the time series contains no trend and seasonality, then we can use simple linear smoothing to make short term forecast.
- Degree of smoothing is controlled by alpha.
- The following figure shows the annual rainfall by inches for London.
- rain= scan("http://robjhyndman.com/tsdldata/hurst/precip1.dat",skip=1)
- rainseries <- ts(rain,start=c(1813))</li>
- plot.ts(rainseries)



# Simple exponential smoothing example

- From this plot, the mean stays at constant level, and doesn't have much seasonality.
- Use function HoltWinters(). For simple exponential smoothing, we set the parameters beta=FALSE and gamma=FALSE.
- The following figure shows the fitted line over original data.
- rainseriesforecasts <- HoltWinters(rainseries, beta=FALSE, gamma=FALSE)</li>





# Simple exponential smoothing example

- For each year, we can compute the error between the observed value and fitted value, thus the in sample sum of square errors(for all the years we have data with)
- rainseriesforecasts\$SSE
- [1] 1828.855
- For simple exponential smoothing, we use the first value (23.56) as the initial value. This can be specified in HoltWinters using "l.start" option.
- rainseriesforecasts2<-HoltWinters(rainseries, beta=FALSE, gamma=FALSE, l.start=23.56)
- forecast(rainseriesforecasts2, h=2)

```
Point Forecast Lo 80 Hi 80 Lo 95 Hi 95

1913 24.67819 19.17493 30.18145 16.26169 33.09470

1914 24.67819 19.17333 30.18305 16.25924 33.09715
```