1 Polynomials

1.1 Numeral Systems

A numeral system consists of a finite set of digits, D, and a base, b, for which b = |D|, *i.e.* b is the cardinality of D. The binary system, for instance, uses the digits $D = \{0, 1\}$. The cardinality of D in this case, hence, is 2. The decimal system uses the digits $D = \{0, ..., 9\}$ and, thus, has the base b = 10. The hexadecimal system uses the digits $D = \{0, ..., 15\}$, often given as $D = \{0, ..., 9, a, b, c, d, e, f\}$, and, therefore, has the base b = 16.

Numbers in any numeral system are usually represented as strings of digits. The string

10101010,

for instance, may represent a number in the binary system. (It could be a number in decimal format, too, though.) The string

170,

by contrast, cannot be a binary number, because it contains the digit 7, which is not element of D in the binary system. It can represent a decimal (or a hexadecimal number). The string

aa,

can represent a number in the hexadecimal system (but not one of in the binary or decimal system).

We interpret such a string, *i.e.* convert it to the decimal system, by rewriting it as a formula of the form:

$$a_n b^n + a_{n-1} b^{n-1} + \dots + a_0 b^0$$
,

where a_i are the digits that appear in the string, b is the base and n is position of the left-most digit starting to count with 0 on the right-hand side of the string. The string 10101010 in binary notation,hence, is interpreted as

$$1 \times 2^7 + 0 \times 2^6 + 1 \times 2^5 + 0 \times 2^4 + 1 \times 2^3 + 0 \times 2^2 + 1 \times 2^1 + 0 \times 2^0$$

which can be simplified to

$$2^7 + 2^5 + 2^3 + 2$$
.

which, in its turn, is

$$128 + 32 + 8 + 2 = 170.$$

The string 170 in decimal notation is interpreted as

$$10^2 + 7 \times 10 = 170.$$

Interpreting a string in the notation it is written in yields just that string. The string aa in hexadecimal notation is interpreted as

$$a \times 16 + a$$
.

The digit a, however, is just 10. We, hence, get the equation

$$10 \times 16 + 10 = 160 + 10 = 170.$$

What do we get, when we relax some of the constraints defining a numeral system? Instead of using a finite set of digits, we could use a number field, F, (finite or infinite) so that any member of that field qualifies as coefficient in the formulas we used above to interpret numbers in the decimal system. We would then relax the rule that the base must be the cardinality of the field. Instead, we allow any member x of the field to serve as a base. Formulas we get from those new rules would follow the recipe:

$$a_n x^n + a_{n-1} x^{n-1} + \dots + a_0 x^0$$

or shorter:

$$\sum_{i=0}^{n} a_i x^i$$

with $a_i, x \in F$.

Such beasts are indeed well-known. They are very prominent, in fact, and their name is polynomial.

The name *poly*nomial stems from the fact that polynomials may be composed of many terms; a monomial, by contrast, is a polynomial that consists of only one term. For instance,

$$5x^2$$

is a monomial. A binomial is a polynomial that consists of two terms. This is an example of a binomial:

$$x^5 + 2x$$
.

There is nothing special about monomials and binomials, at least nothing that would affect their definition as polynomials. Monomials and binomials are just polynomials that happen to have only one or, respectively, two terms.

Polynomials share many properties with numbers. Like numbers, arithmetic, including addition, subtraction, multiplication and division as well as exponentiation, can be defined over polynomials. In some cases, numbers reveal their close relation to polynomials. The binomial theorem states, for instance, that a product of the form

$$(a+b)(a+b)$$

translates to a formula involving binomial coefficients:

$$a^2 + 2ab + b^2$$
.

We can interpret this formula as the product of the polynomial x + a:

$$(x+a)(x+a),$$

which yields just another polynomial:

$$x^2 + 2ax + a^2$$

Let us replace a for the number 3 and fix x = 10. We get:

$$(10+3)(10+3) = 10^2 + 2 \times 3 \times 10 + 3^2 = 100 + 60 + 9 = 169, \tag{1.1}$$

which is just the result of the multiplication 13×13 . Usually, it is harder to recognise this kind of relations numbers have with the binomial theorem (and, hence, with polynomials), because most binomial coefficients are too big to be represented by a single-digit number. Already in the product 14×14 , the binomial coefficients are hidden. Let us look at this multiplication treated as the polynomial (x + a) with x = 10 and a = 4:

$$(10+4)(10+4) = 10^2 + 2 \times 4 \times 10 + 4^2 = 100 + 2 \times 40 + 16.$$

When we look at the resulting number, we do not recognise the binomial coefficient anymore – they are *carried* away: $100 + 2 \times 40 + 16 = 100 + 80 + 16 = 196$.

Indeed, polynomials are not numbers. Those are different concepts. Another important difference is that polynomials do not establish a clear order. For any two distinct numbers, we can clearly say which of the two is the greater and which is the smaller one. We cannot decide that based on the formula of the polynomial alone. One way to decide quickly which of two numbers is the grater one is to look at the number of their digits. The one with more digits is necessarily the greater one. In any numeral system it holds that:

$$a_3b^3 + a_2b^2 + a_1b + a_0 > c_2b^2 + c_1b + c_0$$

independent of the values of the as and the cs. For polynomials, this is not true. Consider the following example:

$$x^3 + x^2 + x + 1 > 100x^2$$
?

For x = 10, the left-hand side of the inequation is 1000 + 100 + 10 + 1 = 1111; the right-hand side, however, is $100 \times 100 = 10000$.

In spite of such differences, we can represent polynomials very similar to how we represented numbers, namely as a list of coefficients. This is a valid implementation in Haskell:

type
$$Poly \ a = P \ [a]$$

deriving $(Show)$

We add a safe constructor:

```
\begin{array}{l} poly:: (Eq\ a, Num\ a) \Rightarrow [\ a] \rightarrow Poly\ a \\ poly\ [\ ] = error\ "not\ a\ polynomial" \\ poly\ as = P\ (cleanz\ as) \\ cleanz:: (Eq\ a, Num\ a) \Rightarrow [\ a] \rightarrow [\ a] \\ cleanz\ xs = reverse\ \$\ go\ (reverse\ xs) \\ \textbf{where}\ go\ [\ ] \qquad = [\ ] \\ go\ [0] \qquad = [\ 0] \\ go\ (0:xs) = go\ xs \\ go\ xs \qquad = xs \end{array}
```

The constructor makes sure that the resulting polynomial has at least one coefficient and that all the coefficients are actually numbers and comparable for equality. The function cleanz called in the constructor removes leading zeros (which are redundant), just as we did when we defined natural numbers. But note that we reverse, first, the list of coefficients passed to go and, second, the result of go. This means that we store the coefficients from left to right in ascending order. Usually, we write polynomials out in descending order of their weight, i.e.

$$x^n + x^{n-1} + \dots + x^0.$$

But, here, we store them in the order:

$$x^0 + x^1 + \dots + x^{n-1} + x^n$$
.

The following function gets the list of coefficients back:

$$coeffs :: Poly \ a \rightarrow [a]$$

 $coeffs \ (P \ as) = as$

Here is a function to pretty-print polynomials:

```
pretty :: (Num \ a, Show \ a, Eq \ a) \Rightarrow Poly \ a \rightarrow String
pretty p = go (reverse \$ weigh p)
  where go[] = ""
            go((i,c):cs) = \mathbf{let} \ x \mid i \equiv 0
                                        i \equiv 1
                                                      = "x"
                                         otherwise = "x^" + show i
                                                      = x
                                     t \mid c \equiv 1
                                         otherwise = show \ c + x
                                      o \mid null \ cs
                                        | otherwise = " + "
                                 in if c \equiv 0 then qo cs else t + o + qo cs
weigh :: (Num \ a) \Rightarrow Poly \ a \rightarrow [(Integer, a)]
weigh (P []) = []
weigh (P \ as) = (zip \ [0..] \ as)
```

The function demonstrates how we actually interpret the list of coefficients. We first weigh them by zipping the list of coefficients with a list of integers starting at 0. One could say: we count the coefficients. Note that we start with 0, so that the first coefficient gets the weight 0, the second gets the weight 1 and so on. That, again, reflects our descending ordering of coefficients.

The reversed weighted list is then passed to go, which does the actual printing. We first determine the substring describing x: if i, the weight, is 0, we do not want to write the x, since $x^0 = 1$. If i = 1, we just write x. Otherwise we write x^i .

Then we determine the term composed of coefficient and x. If the coefficient, c is 1, we just write x; otherwise, we concatenate c with x. Note, however, that we later consider an additional case, namely, when c = 0. In this case, we ignore the whole term.

We still consider the operation. If the remainder of the list is null, *i.e.* we are now handling the last term, o is the empty string. Otherwise, it is the plus symbol. Here is room for improvement: when the coefficient is negative, we do not really need the operation, since we then write +-cx. Nicer would be to write only -cx.

Finally, we put everything together concatenating a string composed of term, operation and go applied on the remainder of the list.

Here is a list of polynomials and how they are represented with our Haksell type:

$x^2 + x + 1$	poly [1, 1, 1]
$5x^5 + 4x^4 + 3x^3 + 2x^2 + x$	poly [0, 1, 2, 3, 4, 5]
$5x^4 + 4x^3 + 3x^2 + 2x + 1$	poly [1, 2, 3, 4, 5]
$5x^4 + 3x^2 + 1$	poly [1, 0, 3, 0, 5]

An important concept related to polynomials is the *degree*. The degree is a measurement of the *size* of the polynomial. In concrete terms, it is the greatest exponent in the polynomial. For us, it is the weight of the right-most element in the polynomial or, much simpler, the length of the list of coefficients minus one – since, we start with zero! The following function computes the degree of a given polynomial:

```
degree :: Poly \ a \rightarrow Int

degree \ (P \ as) = length \ as - 1
```

Note, by the way, that polynomials of degree 0, those with only one trivial term, are just constant numbers.

Finally, here is a useful function that creates random polynomials with *Natural* coefficients:

```
randomPoly::Natural \rightarrow Int \rightarrow IO \ (Poly \ Natural)
randomPoly \ n \ d = \mathbf{do}
cs \leftarrow cleanz < \$ > mapM \ (\setminus_{-} \rightarrow randomCoeff \ n) \ [1 \dots d]
\mathbf{if} \ length \ cs < d \ \mathbf{then} \ randomPoly \ n \ d
\mathbf{else} \ return \ (P \ cs)
randomCoeff :: Natural \rightarrow IO \ Natural
randomCoeff \ n = randomNatural \ (0, n-1)
```

The function receives a Natural and an Int. The Int indicates the degree of the polynomial we want to obtain. The Natural is used to restrict the size of the coefficients we want to see in the polynomial. In randomCoeff, we use the randomNatural defined in the previous chapter to generate a random number between 0 and n-1. You might suspect already where that will lead us: to polynomials modulo some number. But before we get there, we will study polynomial arithmetic.

1.2 Polynomial Arithmetic

We start with addition and subtraction, which, in German, are summarised by the beautiful word *strichrechnung* meaning literally "dash calculation" as opposed to *punkt-rechnung* or "dot calculation", which would be multiplication and division.

Polynomial strichrechnung is easy. Key is to realise that the structure of polynomials is already defined by strichrechnung: it is composed of terms each of which is a product of some number and a power of x. When we add (or subtract) two polynomials, we just sort them according to the exponents of their terms and add (or subtract) terms with equal exponents:

With our polynomial representation, it is easy to implement this kind of operation. One might think it was designed especially to support addition and subtraction. Here is a valid implementation:

```
add :: (Num \ a, Eq \ a) \Rightarrow Poly \ a \rightarrow Poly \ a \rightarrow Poly \ a
add = strich \ (+)
sub :: (Num \ a, Eq \ a) \Rightarrow Poly \ a \rightarrow Poly \ a \rightarrow Poly \ a
sub = strich \ (-)
sump :: (Num \ a, Eq \ a) \Rightarrow [Poly \ a] \rightarrow Poly \ a
sump = foldl' \ add \ (P \ [0])
strich :: (Num \ a, Eq \ a) \Rightarrow (a \rightarrow a \rightarrow a) \rightarrow Poly \ a \rightarrow Poly \ a \rightarrow Poly \ a
strich \ o \ (P \ x) \ (P \ y) = P \ (strichlist \ o \ x \ y)
strichlist :: (Num \ a, Eq \ a) \Rightarrow (a \rightarrow a \rightarrow a) \rightarrow [a] \rightarrow [a] \rightarrow [a]
strichlist \ o \ xs \ ys = cleanz \ (go \ xs \ ys)
\mathbf{where} \ go \ [] \ bs \qquad = bs
go \ as \ [] \qquad = as
go \ (a : as) \ (b : bs) = a \ `o` \ b : go \ as \ bs
```

Note that *sump* function, which implements *sum* for polynomials. Here is one more function that might be useful later on; it folds *strichlist* on a list of lists of coefficients:

```
strichf :: (Num \ a, Eq \ a) \Rightarrow (a \rightarrow a \rightarrow a) \rightarrow [[a]] \rightarrow [a]

strichf \ o = foldl' \ (strichlist \ o) \ []
```

Punktrechnung, *i.e.* multiplication and division, are a bit more complex – because of the distribution law. Let us start with the simple case where we distribute a monomial over a polynomial:

The function mul1 takes a single term (the monomial) and distributes it over the coefficients of a polynomial using the operation o. Each term in the polynomial is combined with the single term. This corresponds to the operation:

$$dx^{m} \times ax^{n} + bx^{n-1} + \dots + c = adx^{m+n} + bdx^{n-1+m} + \dots + cdx^{m}$$
(1.3)

The function mul1 receives on more parameter, namely the $Int\ i$ and uses it to generate a sequence of zeros that is put in front of the resulting coefficient list. As we will see shortly, the list of zeros reflects the weight of the single term. In fact, we do not implement the manipulation of the exponents we see in the abstract formula directly. Instead, the addition +m is implicitly handled by placing m zeros at the head of the list resulting in a new polynomial of degree m+d where d is the degree of the original polynomial. A simple example:

$$5x^2 \times (4x^3 + 3x^2 + 2x + 1) = 20x^5 + 15x^4 + 10x^3 + 5x^2$$

would be:

mul1 2 [1, 2, 3, 4] 5

which is:

zero
$$2 + (5 * [1, 2, 3, 4]) = [0, 0, 5, 10, 15, 20]$$

We, hence, would add 2 zeros, since 2 is the degree of the monomial.

Now, when we multiply two polynomials, we need to map all terms in one of the polynomials on the other polynomial using mul1. We further need to pass the weight of the individual terms of the first polynomial as the Int parameter of mul1. What we want to do is:

[
$$mul1$$
 (*) i ($coeffs$ $p1$) p | $(i, p) \leftarrow zip$ [$0..$] ($coeffs$ $p2$)].

What would we get applying this formula on the polynomials, say, [1, 2, 3, 4] and [5, 6, 7, 8]? Let us have a look:

[
$$mul1$$
 (*) i ([5, 6, 7, 8]) p | (i , p) $\leftarrow zip$ [0 . .] [1, 2, 3, 4]] [[5, 6, 7, 8], [0, 10, 12, 14, 16], [0, 0, 15, 18, 21, 24], [0, 0, 0, 20, 24, 28, 32]].

We see a list of four lists, one for each coefficient of [1,2,3,4]. The first list is the result of distributing 1 over all the coefficients in [5,6,7,8]. Since 1 is the first element, its weight is 0: no zeros are put before the resulting list. The second list results from distributing 2 over [5,6,7,8]. Since 2 is the second element, its weight is 1: we add one zero. The same process is repeated for 3 and 4 resulting in the third and fourth result list. Since 3 is the the third element, the third resulting list gets two zeros and, since 4 is the fourth element, the fourth list gets three zeros.

How do we transform this list of lists back into a single list of coefficients? Very easy: we add them together using strichf:

```
strichf (+) [[5, 6, 7, 8], [0, 10, 12, 14, 16], [0, 0, 15, 18, 21, 24], [0, 0, 0, 20, 24, 28, 32]] which is
```

This means that

$$(4x^3+3x^2+2x+1)\times(8x^3+7x^2+6x+5) = 32x^6+52x^5+61x^4+60x^3+34x^2+16x+5.$$
 (1.4)

Here is the whole algorithm:

```
mul :: (Show \ a, Num \ a, Eq \ a) \Rightarrow Poly \ a \rightarrow Poly \ a \rightarrow Poly \ a
mul \ p1 \ p2 \ | \ d2 > d1 = mul \ p2 \ p1
| \ otherwise = P \ (strichf \ (+) \ ms)
\mathbf{where} \ d1 = degree \ p1
d2 = degree \ p2
ms = [mul1 \ (*) \ i \ (coeffs \ p1) \ p \lor (i, p) \leftarrow zip \ [0 ...] \ (coeffs \ p2)]
```

On top of multiplication, we can implement power. We will, of course, not implement a naïve approach based on repeated multiplication alone. Instead, we will use the *square-and-multiply* approach we have already used before for numbers. Here is the code:

```
\begin{array}{l} powp:: (Show\ a,Num\ a,Eq\ a) \Rightarrow Natural \rightarrow Poly\ a \rightarrow Poly\ a \\ powp\ f\ poly = go\ f\ (P\ [1])\ poly \\ \textbf{where}\ go\ 0\ y\ \_ = y \\ go\ 1\ y\ x = mul\ y\ x \\ go\ n\ y\ x\ |\ even\ n\ = go\ (n\ `div\ 2)\ y \qquad (mul\ x\ x) \\ |\ otherwise = go\ ((n-1)\ `div\ 2)\ (mul\ y\ x) \end{array}
```

The function powp receives a natural number, that is the exponent, and a polynomial. We kick off by calling go with the exponent, f, a base polynomial P [1], i.e. unity, and the polynomial we want to raise to the power of f. If f = 0, we are done and return the base polynomial. This reflects the case $x^0 = 1$. If f = 1, we multiply the base polynomial by the input polynomial. Otherwise, if the exponent is even, we halve it, pass the base polynomial on and square the input. Otherwise, we pass the product of the base polynomial and the input on instead of the base polynomial as it is. This implementation differs a bit from the implementation we presented before for numbers, but it implements the same algorithm.

Here is a simple example: we raise the polynomial x + 1 to the power of 5. In the first round, we compute

which, since 5 is odd, results in

$$go\ 2\ (P\ [1,1])\ (P\ [1,2,1]).$$

This, in its turn, results in

go 1
$$(P[1,1])$$
 $(P[1,4,6,4,1])$.

This is the final step and results in

which is

the polynomial $x^5 + 5x^4 + 10x^3 + 10x^2 + 5x + 1$. You might have noticed that our Haskell notation shows the binomial coefficients $\binom{n}{k}$ for n=0, n=1, n=2, n=4 and n=5. We never see n=3, which would be $P\left[1,3,3,1\right]$, because we leave the multiplication $mul\left(P\left[1,1\right]\right)\left(P\left[1,2,1\right]\right)$ out. For this specific case with exponent 5, leaving out this step is where square-and-multiply is more efficient than multiplying five times. With growing exponents, the saving quickly grows to a significant order.

Division is, as usual, a bit more complicated than multiplication. But it is not too different from number division. First, we define polynomial division as Euclidean division, that is we search the solution for the equation

$$\frac{a}{b} = q + r \tag{1.5}$$

where r < b and bq + r = a.

The manual process is as follows: we divide the first term of a by the first term of b. The quotient goes to the result; then we multiply it by b and set a to a minus that result. Now we repeat the process until the degree of a is less than that of b.

Here is an example:

$$\frac{4x^5 - x^4 + 2x^3 + x^2 - 1}{x^2 + 1}.$$

We start by dividing $4x^5$ by x^2 . The quotient is $4x^3$, which we add to the result. We multiply: $4x^3 \times (x^2 + 1) = 4x^5 + 4x^3$ and subtract the result from a:

$$4x^{5} - x^{4} + 2x^{3} + x^{2} - 1
- 4x^{5} + 4x^{3}
= - x^{4} - 2x^{3} + x^{2} - 1$$
(1.6)

We continue with $-x^4$ and divide it by x^2 , which is $-x^2$. The overall result now is

 $4x^3 - x^2$. We multiply $-x^2 \times (x^2 + 1) = -x^4 - x^2$ and subtract that from what remains from a:

We continue with $-2x^3$, which, divided by x^2 is -2x. We multiply $-2x \times (x^2 + 1) = -2x^3 - 2x$ and subtract:

The result now is $4x^3 - x^2 - 2x$. We continue with $2x^2$, which, divided by x^2 is 2. We multiply $2 \times (x^2 + 1) = 2x^2 + 2$ and subtract:

$$\begin{array}{rcrcr}
2x^2 & + & 2x & - & 1 \\
- & 2x^2 & & + & 2 \\
& = & 2x & - & 3
\end{array} \tag{1.9}$$

The result now is $4x^3 - x^2 - 2x + 2$. We finally have 2x - 3, which is smaller in degree than b. The result, hence, is $(4x^3 - x^2 - 2x + 2, 2x - 3)$.

Here is an implementation of division in Haskell:

```
\begin{array}{ll} \textit{divp} :: & (\textit{Show } a, \textit{Num } a, \textit{Eq } a, \textit{Fractional } a, \textit{Ord } a) \Rightarrow \\ & \textit{Poly } a \rightarrow \textit{Poly } a \rightarrow (\textit{Poly } a, \textit{Poly } a) \\ \textit{divp } (\textit{P } as) (\textit{P } bs) = \textbf{let } (q,r) = \textit{go } [] \textit{ as } \textbf{in } (\textit{P } q, \textit{P } r) \\ \textbf{where } \textit{db} = \textit{degree } (\textit{P } bs) \\ \textit{go } \textit{q } r \mid \textit{degree } (\textit{P } r) < \textit{db} = (q,r) \\ \mid \textit{null } r \lor r \equiv [0] = (q,r) \\ \mid \textit{otherwise} = \\ \textbf{let } t = \textit{last } r / \textit{last } \textit{bs} \\ \textit{d } = \textit{degree } (\textit{P } r) - \textit{db} \\ \textit{ts} = \textit{zeros } \textit{d} + [t] \\ \textit{m } = \textit{mulist } \textit{ts } \textit{bs} \\ \textbf{in } \textit{go } (\textit{cleanz } \$ \textit{strichlist } (+) \textit{q } \textit{ts}) \\ \textit{(cleanz } \$ \textit{strichlist } (-) r \textit{m}) \\ \textit{mulist } :: (\textit{Show } a, \textit{Num } a, \textit{Eq } a) \Rightarrow [a] \rightarrow [a] \rightarrow [a] \\ \textit{mulist } \textit{c1 } \textit{c2} = \textit{coeffs } \$ \textit{mul } (\textit{P } \textit{c1}) (\textit{P } \textit{c2}) \\ \end{array}
```

First note that division expects its arguments to be polynomials over a *Fractional* data type. We do not allow polynomials over integers to be used with this implementation.

The reason is that we do not want to use Euclidean division on the coefficients. That could indeed be very confusing. Furthermore, polynomials are most often used with rational or real coefficients. Restricting division to integers (using Euclidean division) would, therefore, not make much sense.

Observe further that we call go with an empty set – that is the initial value of q, *i.e.* the final result – and as – that is initially the number to be divided, the number we called a above. The function go has two base cases: if the degree of r, the remainder and initially as, is less than the degree of the divisor b, we are done. The result is our current (q, r). The same is true if r is null or contains only the constant 0. In this case, there is no remainder: b divides a.

Otherwise, we divide the *last* of r by the *last* of b. Note that those are the term with the highest degree in each polynomial. This division is just a number division of the two coefficients. We still have to compute the new exponent, which is the exponent of *last* r minus the exponent of *last* b, *i.e.* their weight. We do this by subtracting their degrees and then inserting zeros at the head of the result ts. This result, ts, is then added to q. We further compute $ts \times bs$ and subtract the result from r. The function mulist we use for this purpose is just a wrapper around mul using lists of coefficients instead of Poly variables. With the resulting (q, r), we go into the next round.

Let us try this with our example from above:

$$\frac{4x^5 - x^4 + 2x^3 + x^2 - 1}{x^2 + 1}.$$

We call divp (P [-1,0,1,2,-1,4]) (P [1,0,1]) and get (P [2,-2,-1,4], P [-3,2]), which translates to the polynomials $4x^3 - x^2 - 2x + 2$ and 2x - 3. This is the same result we obtained above with the manual procedure.

From here on, we can implement functions based on division, such as divides:

$$divides :: (Show \ a, Num \ a, Eq \ a, Ord \ a) \Rightarrow$$

$$Poly \ a \rightarrow Poly \ a \rightarrow Bool$$

$$divides \ a \ b = \mathbf{case} \ b \ `divp` \ a \ \mathbf{of}$$

$$(_, P \ [0]) \rightarrow True$$

$$_ \qquad \to False$$

the remainder:

$$remp :: (Show \ a, Num \ a, Eq \ a, Ord \ a) \Rightarrow$$

$$Poly \ a \rightarrow Poly \ a \rightarrow Bool$$

$$remp \ a \ b = \mathbf{let} \ (_, r) = b \ 'd' \ a \ \mathbf{in} \ r$$

and, of course, the GCD:

```
gcdp :: (Show \ a, Num \ a, Eq \ a, Fractional \ a, Ord \ a) \Rightarrow Poly \ a \rightarrow Poly \ a \rightarrow Poly \ a
gcdp \ a \ b \ | \ degree \ b > degree \ a = gcdp \ b \ a
| \ zerop \ b = a
| \ otherwise = \mathbf{let} \ (\_, r) = divp \ a \ b \ \mathbf{in} \ gcdp \ b \ r
```

We use a simple function to check whether a polynomial is zero:

```
zerop :: (Num \ a, Eq \ a) \Rightarrow Poly \ a \rightarrow Bool

zerop \ (P \ [0]) = True

zerpo \ \_ = False
```

We can demonstrate gcdp nicely on binomial coefficients. For instance, the GCD of the polynomials $x^5 + 5x^4 + 10x^3 + 10x^2 + 5x + 1$ and $x^3 + 3x^2 + 3x + 1$, thus

```
gcdp \ (P \ [1,5,10,10,5,1]) \ (P \ [1,3,3,1]) is x^3 + 3x^2 + 3x + 1.
```

Since polynomials consisting of binomial coefficients of n, where n is the degree of the polynomial, are always a product of polynomials composed of smaller binomial coefficients in the same way, the GCD of two polynomials consisting only of binomial coefficients, is always the smaller of the two. In other cases, that is, when the smaller does not divide the greater, this implementation of the GCD can lead to confusing results. For instance, we multiply P [1, 2, 1] by another polynomial, say, P [1, 2, 3]. The result is P [1, 4, 8, 8, 3]. Now,

```
gcdp\ (P\ [1,5,10,10,5,1])\ (P\ [1,4,8,8,3])
```

does not yield the expected result P [1,2,1]. The reason is that the GCD is an operation defined on integers, but we implemented it on top of fractionals. That is often not what we want. Anyway, here, we will actually use the GCD only in finite fields. Until now, we have discussed polynomials in infinite fields. We now turn our attention to polynomial arithmetic in a finite field and, hence, to modular polynomial arithmetic.

With modular arithmetic, all coefficients in the polynomial are modulo n. That means we have to reduce those numbers. This, of course, does only make sense with integers. We first implement some helpers to reduce numbers modulo n reusing functions implemented in the previous chapter.

The first function takes an integer modulo n:

```
\begin{array}{ll} mmod:: Zahl \rightarrow Zahl \\ mmod \ n \ p \mid n < 0 \land (-n) > p = mmod \ (-(mmod \ (-n)) \ p) \ p \\ \mid n < 0 \qquad \qquad = mmod \ (p+n) \ p \\ \mid otherwise \qquad = n \ `rem' \ p \end{array}
```

Equipped with this function, we can easily implement multiplication:

```
modmul :: Zahl \rightarrow Zahl \rightarrow Zahl \rightarrow Zahl

modmul \ p \ f1 \ f2 = (f1 * f2) \ `mmod` \ p
```

For division, we reuse the *inverse* function:

```
modiv :: Zahl \rightarrow Zahl \rightarrow Zahl \rightarrow Zahl

modiv \ p \ n \ d = modmul \ p \ n \ d'

\mathbf{where} \ d' = M.inverse \ d \ p
```

Now, we turn to polynomials. Here is, first, a function that transforms a polynomial into one modulo n:

```
pmod :: Poly \ Zahl \rightarrow Zahl \rightarrow Poly \ Zahl

pmod \ (P \ cs) \ p = P \ [c \ `mmod \ `p \ | \ c \leftarrow cs]
```

In other words, we just map mmod on all coefficients. Let us look at some polynomials modulo a number, say, 7. The polynomial P[1,2,3,4] we already used above is just the same modulo 7. The polynomial P[5,6,7,8], however, changes:

```
P[5, 6, 7, 8] 'pmod' 7
```

```
is P[5, 6, 0, 1] or, in other words, 8x^3 + 7x^2 + 6x + 5 turns, modulo 7, into x^3 + 6x + 5.
```

The polynomial x+1 raised to the power of 5 is $x^5 + 5x^4 + 10x^3 + 10x^2 + 5x + 1$. Modulo 7, this reduces to $x^5 + 5x^4 + 3x^3 + 3x^3 + 5x + 1$. That is: the binomial coefficients modulo n change. For instance,

```
map\ (choose2\ 6)\ [0..6]
```

is

1,6,15,20,15,6,1.

Modulo 7, we get

1,6,1,6,1,6,1.

 $map\ (choose2\ 7)\ [0..7]$

is

1,7,21,35,35,21,7,1.

Without big surprise, we see this modulo 7 drastically simplified:

1,0,0,0,0,0,0,1.

Here are addition and subtraction, which are very easy to convert to modular arithmetic:

```
addmp: Zahl \rightarrow Poly\ Zahl \rightarrow Poly\ Zahl \rightarrow Poly\ Zahl addmp\ n\ p1\ p2 = strich\ (+)\ p1\ p2\ `pmod`\ n submp: Zahl \rightarrow Poly\ Zahl \rightarrow Poly\ Zahl \rightarrow Poly\ Zahl \rightarrow Poly\ Zahl submp\ n\ p1\ p2 = strich\ (-)\ p1\ p2\ `pmod`\ n
```

Multiplication:

```
\begin{array}{lll} \textit{mulmp} :: \textit{Zahl} \rightarrow \textit{Poly} \; \textit{Zahl} \rightarrow \textit{Poly} \; \textit{Zahl} \rightarrow \textit{Poly} \; \textit{Zahl} \\ \textit{mulmp} \; p \; p1 \; p2 \; | \; d2 > d1 & = \textit{mulmp} \; p \; p2 \; p1 \\ & | \; \textit{otherwise} = P \; [\textit{m 'mmod'} \; p \; | \; \textit{m} \leftarrow \textit{strichf} \; (+) \; \textit{ms}] \\ \textbf{where} \; \textit{ms} = [\textit{mul1} \; o \; i \; (\textit{coeffs} \; p1) \; c \; | \; (i, c) \leftarrow \textit{zip} \; [0 \ldots] \; (\textit{coeffs} \; p2)] \\ & d1 \; = \; \textit{degree} \; p1 \\ & d2 \; = \; \textit{degree} \; p2 \\ & o \; = \; \textit{modmul} \; p \end{array}
```

We repeat the multiplication from above

$$mul\ (P\ [1,2,3,4])\ (P\ [5,6,7,8])$$

which was

Modulo 7, this result is

The modulo multiplication

$$mulmp \ 7 \ (P \ [1,2,3,4]) \ (P \ [5,6,0,1])$$

yields the same result:

Division:

```
\begin{array}{l} \textit{divmp} :: \textit{Zahl} \rightarrow \textit{Poly Zahl} \rightarrow \textit{Poly Zahl} \rightarrow (\textit{Poly Zahl}, \textit{Poly Zahl}) \\ \textit{divmp p } (\textit{P as}) \; (\textit{P bs}) = \mathbf{let} \; (\textit{q}, \textit{r}) = \textit{go} \; [0] \; \textit{as in} \; (\textit{P q}, \textit{P r}) \\ \textbf{where } \textit{db} = \textit{degree} \; (\textit{P bs}) \\ \textit{go q r} \; | \; \textit{degree} \; (\textit{P r}) < \textit{db} = (\textit{q}, \textit{r}) \\ | \; \textit{null } \; r \lor r \equiv [0] \; = (\textit{q}, \textit{r}) \\ | \; \textit{otherwise} \; = \\ \textbf{let} \; t \; = \; \textit{modiv p } (\textit{last r}) \; (\textit{last bs}) \\ \textit{d} \; = \; \textit{degree} \; (\textit{P r}) - \textit{db} \\ \textit{ts} \; = \; \textit{zeros} \; \textit{d} \; + [t] \\ \textit{m} \; = \; \textit{mulmlist p ts bs} \\ \textbf{in } \; \textit{go} \; [\textit{c `mmod`p} \; | \; \textit{c} \leftarrow \; \textit{cleanz} \; \$ \; \textit{strichlist } (+) \; \textit{q ts}] \\ | \; [\textit{c `mmod`p} \; | \; \textit{c} \leftarrow \; \textit{cleanz} \; \$ \; \textit{strichlist } (-) \; \textit{r m}] \end{array}
```

GCD:

$$\begin{array}{l} gcdmp :: Zahl \rightarrow Poly \ Zahl \rightarrow Poly \ Zahl \rightarrow Poly \ Zahl \\ gcdmp \ p \ a \ b \ | \ degree \ b > degree \ a = gcdmp \ p \ b \ a \\ | \ zerop \ b = a \\ | \ otherwise = \mathbf{let} \ (_, r) = divmp \ p \ a \ b \ \mathbf{in} \ gcdmp \ p \ b \ r \end{array}$$

Let us try gcdmp on the variation we already tested above. We multiply the polynomial $x^2 + 2x + 1$ by $3x^2 + 2x + 1$ modulo 7:

```
mulmp \ 7 \ (P \ [1,2,1]) \ (P \ [1,2,3]).
```

The result is P[1, 4, 1, 1, 3].

Now, we compute the GCD with P[1, 5, 10, 10, 5, 1] modulo 7:

```
gcdmp \ 7 \ (P \ [1,5,3,3,5,1]) \ (P \ [1,4,1,1,3]).
```

The result is P[1,2,1], as expected.

Finally, power:

```
\begin{array}{l} powmp:: Zahl \rightarrow Zahl \rightarrow Poly \ Zahl \rightarrow Poly \ Zahl \\ powmp \ p \ f \ poly = go \ f \ (P \ [1]) \ poly \\ \textbf{where} \ go \ 0 \ y \ \_ = y \\ go \ 1 \ y \ x = mulmp \ p \ y \ x \\ go \ n \ y \ x \mid even \ n \ = go \ (n \ `div `2) \ y \qquad (mulmp \ p \ x \ x) \\ \mid otherwise = go \ ((n-1) \ `div `2) \ (mulmp \ p \ x \ x) \\ (mulmp \ p \ x \ x) \end{array}
```

Here is a nice variant of Pascal's triangle generated by map $(\lambda x \to powmp \ 7 \ x \ (P \ [1,1]) \ [1..14]:$

```
P \begin{bmatrix} 1,1 \\ P \begin{bmatrix} 1,2,1 \end{bmatrix} \\ P \begin{bmatrix} 1,3,3,1 \end{bmatrix} \\ P \begin{bmatrix} 1,4,6,4,1 \end{bmatrix} \\ P \begin{bmatrix} 1,5,3,3,5,1 \end{bmatrix} \\ P \begin{bmatrix} 1,6,1,6,1,6,1 \end{bmatrix} \\ P \begin{bmatrix} 1,0,0,0,0,0,0,1 \end{bmatrix} \\ P \begin{bmatrix} 1,1,0,0,0,0,0,1 \end{bmatrix} \\ P \begin{bmatrix} 1,2,1,0,0,0,0,1,2,1 \end{bmatrix} \\ P \begin{bmatrix} 1,2,1,0,0,0,1,2,1 \end{bmatrix} \\ P \begin{bmatrix} 1,3,3,1,0,0,0,1,3,3,1 \end{bmatrix} \\ P \begin{bmatrix} 1,4,6,4,1,0,0,1,4,6,4,1 \end{bmatrix} \\ P \begin{bmatrix} 1,5,3,3,5,1,0,1,5,3,3,5,1 \end{bmatrix} \\ P \begin{bmatrix} 1,6,1,6,1,6,1,6,1,6,1,6,1,6,1 \end{bmatrix} \\ P \begin{bmatrix} 1,0,0,0,0,0,0,0,2,0,0,0,0,0,0,1 \end{bmatrix}
```

It is especially interesting to look at greater powers using exponents that are multiples of 7. Before we continue with modular arithmetic, which we need indeed to understand some of the deeper problems related to polynomials, we will investigate the application of polynomials using a famous device: Babbage's difference engine.

1.3 The Difference Engine

Polynomial arithmetic, as we have seen, is very similar to number arithmetic. What is the correspondent of interpreting a number in a given numeral system in the domain of polynomials? Well, that is the *application* of the polynomial to a given number. We would substitute x for a number in the Field in which we are working and just compute the formula. For instance, the polynomial

$$x^2 + x + 1$$

can be applied to, say, 2. Then we get the formula

$$2^2 + 2 + 1$$
,

which is 4 + 2 + 1 = 7.

For other values of x, it would of course generate other values. For x = 0, for instance, it would give $0^2 + 0 + 1 = 1$; for x = 1, it is $1^2 + 1 + 1 = 3$; for x = 3, it yields $3^2 + 3 + 1 = 13$.

How would we apply a polynomial represented by our Haskell type? We would need to go through the list of coefficients, raise x to the power of the weight of each particular coefficient, multiply it by the coefficient and, finally, add all the values together. Here is an implementation:

```
apply :: Num \ a \Rightarrow Poly \ a \rightarrow a \rightarrow a

apply \ (P \ cs) \ x = sum \ [c * x \uparrow i \mid (i, c) \leftarrow zip \ [0 ...] \ cs]
```

Let us try with a very simple polynomial, x + 1:

```
apply (P [1,1]) 0 \text{ gives } 1.

apply (P [1,1]) 1 \text{ gives } 2.

apply (P [1,1]) 2 \text{ gives } 3.

apply (P [1,1]) 3 \text{ gives } 4.
```

This polynomial, apparently, just counts the integers adding one to the value to which we apply it. It implements i++.

On the first sight, this result appears to be boring. However, after a quick thought, there is a lesson to learn: we get to know the polynomial, when we look at the *sequence* it produces. So, let us implement a function that maps *apply* to lists of numbers:

```
mapply :: Num \ a \Rightarrow Poly \ a \rightarrow [a] \rightarrow [a]

mapply \ p = map \ (apply \ p)
```

For simple polynomials, the sequences are predictable. x^2 , obviously, just produces the squares; x^3 produces the cubes and so on. Sequences created by powers of the simple

```
polynomial x + 1, still, are quite predictable, e.g.
```

```
\begin{array}{l} mapply \; (P\;[1,2,1]) \; [0\ldots 10] \colon \; 1,4,9,16,25,36,49,64,81,100,121 \\ mapply \; (P\;[1,3,3,1]) \; [0\ldots 10] \colon \; 1,8,27,64,125,216,343,512,729,1000,1331 \\ mapply \; (P\;[1,4,6,4,1]) \; [0\ldots 10] \colon \; 1,16,81,256,625,1296,2401,4096,6561,10000,14641 \\ mapply \; (P\;[1,5,10,10,5,1]) \; [0\ldots 10] \colon \; 1,32,243,1024,3125,7776,16807,32768,59049,100000,161051 \end{array}
```

The first line, easy to recognise, is the squares, but pushed one up, *i.e.* the application to 0 yields the value for 1^2 , the application to 1 yields the value for 2^2 and so on. The second, still easy to recognise, is the cubes – again pushed up by one. The third line is the powers of four and the fourth line is the powers of five, both pushed up by one.

That is not too surprising at the end, since P [1,2,1] is the result of squaring P [1,1], which generates the integers pushed one up; P [1,3,3,1] is the result of raising P [1,1] to the third power and so on.

Things become more interesting, when we deviate from the binomial coefficients. The sequence produced by mappy (P [1,2,3,4]) [1..10], for instance, does not resemble such a simple sequence: 1, 10, 49, 142, 313, 586, 985, 1534, 2257, 3178, 4321. Even the Online Encyclopedia has nothing interesting to say about it. The same is true for mappy (P [5,6,7,8]) [1..10], which is 5, 26, 109, 302, 653, 1210, 2021, 3134, 4597, 6458, 8765.

This raises another interesting question: given a sequence, is there a method by which we can we recognise the polynomial that created it? Yes, there is. In fact, there are. There was even a machine that helped in guessing polynomials from sequences. It was built in the early 19th century by Charles Babbage (1791 – 1871), an English polymath, mathematician, philosopher, economist and inventor.

Babbage stands in the tradition of designers and constructors of early computing machinery; predecessors of his in this tradition were, for instance, Blaise Pascal (1623 - 1662) and Gottfried Wilhelm Leibniz (1646 - 1716). Babbage designed two series of machines, first, the difference engines and, later, the analytical engines.

The analytical engine, unfortunately, was not built in his lifetime. The final collapse of the project came in 1878, after Babbage's death in 1871, due to lack of finance. The analytical engine would have been a universal (Turing-complete) computer very similar to our computers today, but not working on electricity, but on steam. It would have been programmed by punch cards that, in Babbage's time, were used for controlling looms. Programs would have resembled modern assembly languages allowing control structures like selection and iteration. In the context of a description of the analytical engine, Ada Lovelace (1815 – 1852), a friend of Babbage and daughter of Lord Byron, described how to compute Bernoulli numbers with the machine. She is, therefore, considered the first computer programmer in history.

The difference engine, at which we will look here, is much simpler. It was designed to analyse polynomials and what it did was, according to Babbage, "computing differences". During Babbage's lifetime, a first version was built and successfully demonstrated. The construction of a second, much more powerful version which was financially backed by the government, failed due to disputes between Babbage and his engineers. This machine was finally built by the London Science Museum in 1991 using material and engineering techniques available in the 19^{th} century proving this way that it was actually possible for Babbage and his engineers to build such a machine.

The difference engine, as Babbage put it, computes differences, namely the differences in a sequence of numbers. It would take as input a sequence of the form

0,1,16,81,256,625,1296,2401,4096,6561,10000

and compute the differences between the single numbers:

$$\begin{array}{rcl}
1 & - & 0 & = & 1 \\
16 & - & 1 & = & 15 \\
81 & - & 16 & = & 65 \\
256 & - & 81 & = & 175
\end{array} \tag{1.10}$$

Here is a simple function that does this job for us:

```
\begin{array}{ll} \textit{diffs} :: [\textit{Zahl}] \rightarrow [\textit{Zahl}] \\ \textit{diffs} [] &= [] \\ \textit{diffs} [\_] &= [] \\ \textit{diffs} (a:b:cs) = (b-a): \textit{diffs} (b:cs) \end{array}
```

Applied on the sequence above, diffs yields:

1,15,65,175,369,671,1105,1695,2465,3439

What is so special about it? Perhaps, nothing. But let us repeat the process using this sequence. It yields:

14,50,110,194,302,434,590,770,974

And once again:

36,60,84,108,132,156,180,204

And one more time:

24,24,24,24,24,24

Suddenly, we have constant list. How often did we apply diffs? Four times – and, as you may have realised, the original sequence was generated by the polynomial x^4 , a polynomial of degree 4. Is that coincidence?

For further investigation, we implement the complete difference machine, which takes differences, until it reaches a constant sequence.

```
dengine :: [Zahl] \rightarrow [[Zahl]]

dengine cs \mid constant \ cs = []

\mid otherwise = ds : dengine \ ds

where ds = diffs \ cs

constant \ [] = True

constant \ [\_] = True

constant \ (x : xs) = all \ (\equiv x) \ xs
```

Note that we restrict coefficients to integers. This is just for clearness. Polynomials are usually defined over a field, such as the rational or the real numbers!

To confirm our suspicion that the difference engine creates n difference sequences for a polynomial of degree n, we apply the engine on x, x^2 , x^3 , x^4 and x^5 and count the sequences it creates:

```
\begin{array}{l} length \; (dengine \; (mapply \; (P \; [0,1]) \; [0 \ldots 32])) \colon 1 \\ length \; (dengine \; (mapply \; (P \; [0,0,1]) \; [0 \ldots 32])) \colon 2 \\ length \; (dengine \; (mapply \; (P \; [0,0,0,1]) \; [0 \ldots 32])) \colon 3 \\ length \; (dengine \; (mapply \; (P \; [0,0,0,0,1]) \; [0 \ldots 32])) \colon 4 \\ length \; (dengine \; (mapply \; (P \; [0,0,0,0,0,1]) \; [0 \ldots 32])) \colon 5 \end{array}
```

The engine already has a purpose: it tells us the degree of the polynomial that generates a given sequence. It can do much more, though. For instance, it lets us predict the next value in the sequence. To do so, we take the constant difference from the last sequence and add it to the last difference of the previous sequence; we take that result and add it to the previous sequence and so on, until we reach the first sequence. Consider the sequence and its differences from above:

```
0,1,16,81,256,625,1296,2401,4096,6561,10000\\1,15,65,175,369,671,1105,1695,2465,3439\\14,50,110,194,302,434,590,770,974\\36,60,84,108,132,156,180,204\\24,24,24,24,24,24,24
```

We start at the bottom and compute 204 + 24 = 228. This is the next difference of the previous sequence. We compute 974 + 228 = 1202. We go one line up and compute 3439 + 1202 = 4641. This, finally, is the difference to the next value in the input sequence, which, hence, is 10000 + 4641 = 14641 and, indeed, 11^4 . Even without knowing the polynomial that actually generates the sequence, we are now able to continue this sequence. Here is a function that does that for us:

```
predict :: [[Zahl]] \rightarrow [Zahl] \rightarrow Maybe\ Zahl
predict\ ds\ xs = \mathbf{case}\ go\ (reverse\ ds)\ \mathbf{of}
0 \rightarrow Nothing
d \rightarrow Just\ (d + (last\ xs))
\mathbf{where}\ go\ [] = 0
go\ (a:cs) = last\ a + go\ cs
```

The function takes two arguments: the first is the list of difference sequences and the second is the original sequence. We apply go on the reverse of the sequences (because we are working backwards). For each sequence in this list, we get the last and add it to the last of the previous until we have exhausted the list. If go yields 0, we assume that something went wrong. The list of sequences may have been empty in the first place. Otherwise, we add the result to the last of the original list.

Here are some more examples:

```
let s = mapply \ (P \ [0,1]) \ [0..10] in predict (dengine s) s: 11
let s = mapply \ (P \ [0,0,1]) \ [0..10] in predict (dengine s) s: 121
let s = mapply \ (P \ [0,0,0,1]) \ [0..10] in predict (dengine s) s: 1331
let s = mapply \ (P \ [0,0,0,0,1]) \ [0..10] in predict (dengine s) s: 14641
let s = mapply \ (P \ [0,0,0,0,0,1]) \ [0..10] in predict (dengine s) s: 161051
```

Let us go back to the question of how to find the polynomial given the sequence that this polynomial generates. With the help of the difference engine, we already know the degree of the polynomial. Supposed, we know that the first element in the sequence was generated applying 0 to the unknown polynomial and the second one was generated applying 1, the third by applying 2 and so on, we have all information we need.

From the degree, we know the form of the polynomial. A polynomial of degree 1 has the form $a_1x + a_2$; a polynomial of degree 2 has the form $a_1x^2 + a_2x + a_3$; a polynomial of degree 3 has the form $a_1x^3 + a_2x^2 + a_3x + a_4$ and so on.

Since we know the values to which the polynomial is applied, we can easily compute the value of the x-part of the terms. They are that value raised to the power of the weight. The challenge, then, is to find the coefficient by which that value is multiplied.

The first element in the sequence is just the last coefficient, the one "without" an x, since the other terms "disappear", when we apply 0. Consider for example a polynomial of the form $x^2 + x + a$, we get $0^2 + 0 + a = c$, where c is the first value in the sequence. Thus, a = c.

The second element is 1 applied to the formula and, therefore, all terms equal their coefficients, since cx^n , for x = 1, is just c. The third element results from applying 2 to the polynomial, it hence adheres to a formula where unknown values (the coefficients) are multiplied by 2, $2^2 = 4$, $2^3 = 8$ and so on.

In other words, for a polynomial of degree n, we can devise a system of linear equations with n+1 unknowns and the n+1 first elements of the sequence as constant values. A

polynomial of degree 2, for instance, yields the system

$$\begin{array}{rcl}
a & = & a_1 \\
a & + & b & + & c & = & a_2 \\
a & + & 2b & + & 4c & = & a_3
\end{array} \tag{1.11}$$

where the constant numbers a_1 , a_2 and a_3 are the first three elements of the sequence. A polynomial of degree 3 would generate the system

$$\begin{array}{rcl}
 a & = & a_1 \\
 a & + & b & + & c & + & d & = & a_2 \\
 a & + & 2b & + & 4c & + & 8d & = & a_3 \\
 a & + & 3b & + & 9c & + & 27d & = & a_4
 \end{array} \tag{1.12}$$

We have already learnt how to solve such systems: we can apply Gaussian elimination. The result of the elminiation is the coefficients of the generating polynomial, which are the unknowns in the linear equations. The known values (which we would call the coefficients in a linear equation) are the values obtained by computing x^i where i is the weight of the coefficient. Here is a function to extract the known values, the xes raised to the weight from a given sequence with a given degree:

```
genCoeff :: Zahl \rightarrow Zahl \rightarrow Zahl \rightarrow [Zahl]

genCoeff \ d \ n \ x = go \ 0 \ x

where go \ i \ x \mid i > d = [x]

\mid otherwise = n \uparrow i : go \ (i + 1) \ x
```

Here, d is the degree of the polynomial, n is the value to which the polynomial is applied and x is the result, i.e. the value from the sequence. The local function go repeats from 0 to d, raising n, the input value, to the current weight and adding it to the resulting list. At the end, when we have reached a value greater than the degree, we add the value from the sequence as known constant yielding one line of the system of linear equations.

When we apply genCoeff on the sequence generated by x^4 , we would have:

```
genCoeff \ 4\ 0\ 0 resulting in [1,0,0,0,0,0] genCoeff \ 4\ 1\ 1 resulting in [1,1,1,1,1,1] genCoeff \ 4\ 2\ 16 resulting in [1,2,4,8,16,16] genCoeff \ 4\ 3\ 81 resulting in [1,3,9,27,81,81] genCoeff \ 4\ 2\ 56 resulting in [1,4,16,64,256,256]
```

Note that the results are very regular: we see constant 1 in the first column, the natural numbers in the first column, the squares in the third, the cubes in the fourth and the powers in the fifth and sixth column. This are just the values for x^i , for $i \in \{0...4$. Since the value in the sixth column, the one we took from the sequence, equals the value in the fifth column, we can already guess that the polynomial is simply x^4 . Here is another sequence, generated by a secret polynomial:

We compute the difference lists using dengine as ds and compute the degree of the polynomial using length ds. The result is 4. Now we call genCoeff on the first four elements of the sequence:

```
\begin{array}{l} \textit{genCoeff} \ 4\ 0\ 14\ \text{resulting in}\ [1,0,0,0,0,14]\\ \textit{genCoeff}\ 4\ 1\ 62\ \text{resulting in}\ [1,1,1,1,1,62]\\ \textit{genCoeff}\ 4\ 2\ 396\ \text{resulting in}\ [1,2,4,8,16,396]\\ \textit{genCoeff}\ 4\ 3\ 1544\ \text{resulting in}\ [1,3,9,27,81,1544]\\ \textit{genCoeff}\ 4\ 4\ 4322\ \text{resulting in}\ [1,4,16,64,256,4322] \end{array}
```

We use genCoeff to create a matrix representing the entire system of equations:

```
\begin{array}{l} \mathit{findCoeffs} :: [[\mathit{Zahl}]] \to [\mathit{Zahl}] \to \mathit{L.Matrix} \; \mathit{Zahl} \\ \mathit{findCoeffs} \; \mathit{ds} \; \mathit{seq} = \mathit{L.M} \; (\mathit{go} \; 0 \; \mathit{seq}) \\ \mathbf{where} \; \mathit{d} = \mathit{fromIntegral} \; (\mathit{length} \; \mathit{ds}) \\ \mathit{go} \; _{-}[] = [] \\ \mathit{go} \; \mathit{n} \; (\mathit{x} : \mathit{xs}) \; | \; \mathit{n} > \mathit{d} \; = [] \\ | \; \mathit{otherwise} = \mathit{genCoeff} \; \mathit{d} \; \mathit{n} \; \mathit{x} : \mathit{go} \; (\mathit{n} + 1) \; \mathit{xs} \end{array}
```

The function findCoeffs receives the list of difference sequences created by dengine and the original sequence. It computes the degree of the generating polynomial as $length\ ds$ and, then, it goes through the first d elements of the sequence calling genCoeff with d, the known input value n and x, the element of the sequence. For the sequence generated by x^4 , we obtain M [[1,0,0,0,0,0],[1,1,1,1,1,1],[1,2,4,8,16,16], [1,3,9,27,81,81],[1,4,16,64,256,256]], which corresponds to the matrix

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 2 & 4 & 8 & 16 & 16 \\ 1 & 3 & 9 & 27 & 81 & 81 \\ 1 & 4 & 16 & 64 & 256 & 256 \end{pmatrix}$$

For the sequence of the unknown polynomial, we obtain M [[1,0,0,0,0,14], | [1,1,1,1,1,62], [1,2,4,8,16,396], [1,3,9,27,81,1544], [1,4,16,64,256,4322]], which corresponds to the matrix:

$$\begin{pmatrix}
1 & 0 & 0 & 0 & 0 & 14 \\
1 & 1 & 1 & 1 & 1 & 62 \\
1 & 2 & 4 & 8 & 16 & 396 \\
1 & 3 & 9 & 27 & 81 & 1544 \\
1 & 4 & 16 & 64 & 256 & 4322
\end{pmatrix}$$

The next steps are simple. We create the echelon form and solve by back-substitution. The following function puts all the bits together to find the generating polynomial:

```
findGen :: [[Zahl]] \rightarrow [Zahl] \rightarrow [Quoz]
findGen \ ds = L.backsub \circ L.echelon \circ findCoeffs \ ds
```

Applied on the difference list and the sequence generated by x^4 , find Gen yields: [0%1, 0%1, 0%1, 1%1], which indeed corresponds to the polynomial x^4 . For the sequence generated by the unknown polynomial, we get: [14%1, 9%1, 11%1, 16%1, 12%1], which corresponds to the polynomial $12x^4 + 16x^3 + 11x^2 + 9x + 14$. Let us test:

```
mapply (P [14, 9, 11, 16, 12]) [0...10] yields:
```

14,62,396,1544,4322,9834,19472,34916,58134,91382,137204,

which indeed is the same sequence we saw above!

Now, what about the differences generated by the difference engine? Those, too, are sequences of numbers. Are there polynomials that generate those sequences? The first difference sequence of our formerly unknown polynomial is

```
48,334,1148,2778,5512,9638,15444,23218,33248,45822
```

The next three difference sequences could be derived from this sequence – so, we can assume that this sequence is generated by a polynomial of degree 3. Let us see what $findGen\ (tail\ ds)\ (head\ ds)$ yields with ds being the list of difference sequences of that polynomial: [48 % 1,118 % 1,120 % 1,48 % 1], which corresponds to the polynomial $48x^3 + 120x^2 + 118x + 48$. Let us test again:

mapply (P [48, 118, 120, 48]) [0..10] yields:

48,334,1148,2778,5512,9638,15444,23218,33248,45822,61228

The next difference sequence should then be generated by a polynomial of degree 2. We try with **let** $ds' = tail \ ds$ **in** $findGen \ (tail \ ds') \ (head \ ds')$ and get $[286\% \ 1,384\% \ 1,144\% \ 1]$, which corresponds to the polynomial $144x^2 + 384x + 286$.

mapply (P [286, 384, 144]) [0..10] yields:

286,814,1630,2734,4126,5806,7774,10030,12574,15406,18526

which, indeed, is the third difference sequence.

Finally, the last but one sequence, the last that is not constant, should be generated by a polynomial of degree 1. We try with let $ds'' = tail\ (tail\ ds)$ in $findGen\ (tail\ ds'')\ (head\ ds'')$ and get $528\ \%\ 1,288\ \%\ 1$ which corresponds to the polynomial 288x+528.

mapply (P [528, 288]) [0..10] yields:

528,816,1104,1392,1680,1968,2256,2544,2832,3120,3408

which, again is the expected difference sequence.

The differences are closely related to the tremendously important concept of the deriva-

tive of a function. The derivative of a polynomial Π of degree n is a polynomial Π' of degree n-1 that measures the rate of change or slope of Π . The derivative expresses the rate of change precisely for any point in Π . We will look at this with much more attention in the next chapter; the third part will then be dedicated to derivatives and related concepts.

The difference sequences and the polynomials that generate them are also a measurement of the rate of change. Actually, the difference between two points is the rate of change of that polynomial between those two points. The difference, however, is a sloppy measure.

Without going into too many details here, we can quickly look at how the derivative of a polynomial is computed, which, in fact, is very easy. For a polynomial of the form

$$ax^n + bx^m + \dots + cx + d$$
,

the derivative is

$$nax^{n-1} + mbx^{m-1} + \dots + c.$$

In other words, we drop the last term (which is the first term in our Haskell representation of polynomials) and, for all other terms, we multiply the term by the exponent and reduce the exponent by one.

The derivative of the polynomial, x^4 , for instance, is $4x^3$; in the notation of our polynomial type, we have P[0,0,0,0,1] and its derivative P[0,0,0,4]. The derivative of $4x^3$ is $12x^2$, whose derivative then is 24x, whose derivative is just 24. The derivative of our polynomial

$$12x^4 + 16x^3 + 11x^2 + 9x + 14$$

is

$$48x^3 + 48x^2 + 22x + 9$$
.

Note that the first term equals the first term of the polynomial that we identified as the generator of the first difference sequence. Indeed, the differences are sloppy as a measure for the rate of change – but they are not completely wrong!

Here is a function to compute the derivative:

derivative ::
$$(Eq\ a, Num\ a, Enum\ a) \Rightarrow Poly\ a \rightarrow Poly\ a$$

derivative $(P\ as) = P\ (cleanz\ (go\ \$\ zip\ [1\mathinner{\ldotp\ldotp}]\ (drop\ 1\ as)))$
where $go\ []\ = []$
 $go\ ((x,c):cs) = (x*c):go\ cs$

What is the sequence generated by the derivative of our polynomial? Well, we define the derivative as **let** p' = derivative (P [14, 9, 11, 16, 12]), which is P [9, 22, 48, 48], apply it using $mapply \ p'$ [0...10] and see:

9, 127, 629, 1803, 3937, 7319, 12237, 18979, 27833, 39087, 53029

Quite different from the first difference sequence we saw above!

What about the second derivative? we define as **let** p'' = derivative p' and get P[22, 96, 144]. This polynomial creates the sequence

22,262,790,1606,2710,4102,5782,7750,10006,12550,15382

The next derivative, let p''' = derivative p'', is P[96, 288] and generates the sequence 96,384,672,960,1248,1536,1824,2112,2400,2688,2976.

You can already predict the next derivative, which is a polynomial of degree 0: it is P [288]. This is a constant polynomial and will generate a constant sequence, namely the sequence 288. That, however, was also the constant sequence generated by the difference engine. Of course, when the rate of change is the same everywhere in the original polynomial, then precision does not make any difference anymore. The two methods shall come to the same result.

Consider the simple polynomial x^2 . It generates the sequence

$$0, 1, 4, 9, 16, 25, 36, 49, \dots$$

The differences are

$$1, 3, 5, 7, 9, 11, 13, \dots$$

The differences of this list are all 2.

The derivative of x^2 is 2x. It would generate the sequence

$$0, 2, 4, 6, 8, 10, 12, 14, \dots$$

which does not equal the differences. However, we can already see that the derivative of 2x, 2, is constant and generates the constant sequence

$$2, 2, 2, 2, 2, 2, 2, 2, \ldots$$

1.4 Differences and Binomial Coefficients

How are the values appearing in the sequence and the values appearing in the difference sequences related? There must be a relation, since the distance between the values in the sequence is expressed by the values appearing in the difference sequences.

The ingenious Isaac Newton has studied this relation intensely and came up with a formula. Before we go right to the formula, let us observe on our own. The following table shows, in the first line, the value of n, *i.e.* the value to which the polynomial is applied; in the second line, we see the result for this n; in the first column we have the first value from the sequence and from the difference lists:

	0	1	2	3	4
	14	62	396	1544	4322
14	1	1	1	1	1
48	0	1	2	3	4
286	0	0	1	3	6
528	0	0	0	1	4
288	0	0	0	0	1

What is the meaning then of the numbers in the cells of the table? Well, those are factors. We can compute the values of the sequence by formulas derived from this table:

The next question would then be: what are those numbers? But, here, I have to ask you to look a bit more closely at the table. What we see is left-to-right:

Those are binomial coefficients! We could rewrite the table as

	0	1	2	3	4
	14	62	396	1544	4322
14	$\begin{pmatrix} 0 \\ 0 \end{pmatrix}$	$\binom{1}{0}$	$\binom{2}{0}$	$\binom{3}{0}$	$\binom{4}{0}$
48	$\binom{0}{1}$	$\binom{1}{1}$	$\binom{2}{1}$	$\binom{3}{1}$	$\binom{4}{1}$
286	$\binom{0}{2}$	$\binom{1}{2}$	$\binom{2}{2}$	$\binom{3}{2}$	$\binom{4}{2}$
528	$\binom{0}{3}$	$\binom{1}{3}$	$\binom{2}{3}$	$\binom{3}{3}$	$\binom{4}{3}$
288	$\binom{0}{3}$	$\binom{1}{4}$	$\binom{2}{4}$	$\binom{3}{4}$	$\binom{4}{4}$

If this were universally true, we could devise a much better prediction function. The one we wrote in the previous section has the disadvantage that we can only predict the next number in the sequence. To predict a value way ahead we need to generate number by number before we are there. With Newton's trick, we could compute any number in the sequence in one step.

All we have to do is to get the *heads* of the sequences and to calculate the formula:

$$\sum_{k=0}^{d} h_k \binom{n}{k}$$

where d is the degree of the polynomial, n the position in the sequence, *i.e.* the number to which we apply the polynomial, and h_k the head of the sequence starting to count with the original sequence as k = 0, the first difference list as k = 1 and so on. The sixth value (n = 5) of the sequence would then be

$$14 \times {5 \choose 0} + 48 \times {5 \choose 1} + 286 \times {5 \choose 2} + 528 \times {5 \choose 3} + 288 \times {5 \choose 4},$$

which is

$$14 + 48 \times 5 + 286 \times 10 + 528 \times 10 + 288 \times 5$$
,

which, in its turn, is

$$14 + 240 + 2860 + 5280 + 1440 = 9834$$

which is indeed the next value in the sequence.

Here is an implementation:

```
newton :: Zahl \rightarrow [[Zahl]] \rightarrow [Zahl] \rightarrow Zahl
newton \ n \ ds \ seq = sum \ ts
\mathbf{where} \ hs = getHeads \ seq \ ds
ts = [h*(choose \ n \ k) \mid (h, k) \leftarrow zip \ hs \ [0 \dots n]]
getHeads :: [Zahl] \rightarrow [[Zahl]] \rightarrow [Zahl]
getHeads \ seq \ ds = map \ head \ (seq : ds)
```

To perform some experiments, here, as a reminder, are the first 14 numbers of the sequence generated by our polynomial P [14, 9, 11, 16, 12]:

```
14,62,396,1544,4322,9834,19472,34916,58134,91382,137204,198432,278186,379874
```

We set $s = mapply \ P \ [14, 9, 11, 16, 12] \ [0..10]$ and $d = dengine \ s$. Now we perform some tests:

```
newton 0 d s gives 14.

newton 1 d s gives 62.

newton 5 d s gives 9834.

newton 11 d s gives 198432.

newton 13 d s gives 379874.
```

The approach, hence, seems to work. But there is more. The function *newton* gives us a closed form to compute any number in the sequence, given that we have the beginning of that sequence and its difference lists. A closed form, however, is a generating formula – it is the polynomial that generates the entire sequence. We just need a way to make the formula implicit in *newton* explicit.

We can do that using our polynomial data type. When we can express the binomial coefficients in terms of polynomials and apply them to the formula used above, we will get the polynomial out that generates this sequence. Here is a function that does it:

```
\begin{array}{ll} bin2poly::Zahl \rightarrow Zahl \rightarrow Poly\ Quoz\\ bin2poly\ f\ 0 &= P\ [f\ \%\ 1]\\ bin2poly\ f\ 1 &= P\ [0,f\ \%\ 1]\\ bin2poly\ f\ k &= P\ [f\ \%\ (B.fac\ k)]\ `mul`\ go\ (k\ \%\ 1)\\ \textbf{where}\ go\ 1 &= P\ [0,1]\\ go\ i &= P\ [-(i-1),1]\ `mul`\ (go\ (i-1)) \end{array}
```

The function receives two integers: the first one is a factor (the head) by which we multiply the resulting binomial polynomial and the second one is k in $\binom{n}{k}$. Note that we do not need n, since n is the unknown, the x, the base of our polynomial.

If k = 0, the binomial is 1, since for all binomials: $\binom{n}{0} = 1$. We, hence, return a constant polynomial consisting of the factor. This corresponds to $h_0 \times \binom{n}{0}$. The result is just h. Note that we convert the coefficients to rational numbers, since that is the type the function is supposed to yield.

If k = 1, the binomial is n, since for all binomials: $\binom{n}{1} = n$. Since, n is the base of the polynomial, it is expressed by the polynomial P[0,1]. This is just n (or, if you are more used to it: x). Since we multiply with f, the result in this case is $f \times n = fn$, or, in the language of our Haskell polynomials P[0,f].

Otherwise, we go into the recursive go function. The function receives one rational number, namely k (which, de facto, is an integer) The base case is k = 1. In that case we yield P[0,1], hence, n. Otherwise, we create the polynomial P[-(i-1),1], that is n-(k-1) and multiply with the result of go applied to i-1. This function, hence, creates the numerator of the fraction formula of the binomial coefficient:

$$n(n-1)(n-2)\dots(n-k+1).$$

The result of the function is then multiplied by f divided by k!. The former, still, is some head from the difference sequences and the latter is the denominator of the fraction formula. We, thus, compute:

$$\frac{fn(n-1)(n-2)\dots(n-k+1)}{k!}.$$

Now, we can use this formula represented by a polynomial to compute the generating polynomial. The function that does so has exactly the same structure as the newton function. The difference is just that it expresses binomial coefficients as polynomials and that it does not receive a concrete number n for which we want to compute the corresponding value (because we want to compute the formula generating all the values):

```
newtonGen :: [[Zahl]] \rightarrow [Zahl] \rightarrow Poly \ [Quoz]
newtonGen \ ds \ seq = sump \ ts
\mathbf{where} \ hs = getHeads \ seq \ ds
ts = [bin2poly \ h \ k \mid (h,k) \leftarrow zip \ hs \ [0 \dots n]]
n = fromIntegral \ (length \ seq \ ds)
```

When we call $newtonGen\ ds\ s$, ds still being the difference lists and s the sequence in question, we see:

```
P [14\%1,9\%1,11\%1,16\%1,12\%1],
```

which we immediately recognise as our polynomial $12x^4 + 16x^3 + 11x^2 + 9x + 14$.

For another test, we apply the monomial x^5 as

let $s = mapply \ (P \ [0,0,0,0,0,1]) \ [0..10]$ in $newtonGen \ (dengine \ s) \ s$ and see

$$P [0\% 1, 0\% 1, 0\% 1, 0\% 1, 0\% 1, 1\% 1],$$

which is indeed the polynomial x^5 .

But now comes the hard question: why does that work at all???

To answer this question, we should make sure to understand how Newton's formula basically works. The point is that we restrict ourselves to the heads of the sequences as building blocks. When we compute some value x_n in the sequence, we need to compute x_{n-1} and the difference between x_{n-1} and x_n and add those together. Let us build a model that simulates this approach, so we can reason about it more easily.

We use as a model a polynomial of degree 3; that model is sufficiently complex to simulate the problem completely and is, on the other hand, a bit simpler than a model based on a polynomial of degree 4, like the one we have studied above.

The model consists of a data type:

```
data Newton = H \mid X \mid Y \mid Z
deriving (Show, Eq)
```

The *Newton* type has four constructors: H represents the head of the original sequence; X is the head of the first difference list; Y is the head of the second difference list and Z is the constant element repeated in the last difference list. (Remember that a polynomial of degree 3 generates 3 difference lists.)

The model also contains a function to compute positions in the sequence. This function, called cn (for "computeNewton"), takes two arguments: a *Newton* constructor and an integer. The integer tells us the position we want to compute starting with the head = 0:

```
\begin{array}{l} cn:: Newton \rightarrow Natural \rightarrow [Newton] \\ cn \ H \ 0 = [H] \\ cn \ H \ n = cn \ H \ (n-1) + cn \ X \ (n-1) \end{array}
```

When we want to compute the first element in the sequence, $cn\ H\ 0$, we just return [H]. When we want to compute any other numbers, we recursively call $cn\ H\ (n-1)$, which computes the previous data point and add $cn\ X\ (n-1)$, which computes the difference between the previous data point the one we want to compute. Here is how we compute the difference:

$$cn \ X \ 0 = [X]$$

 $cn \ X \ n = cn \ X \ (n-1) + cn \ Y \ (n-1)$

If we need the first difference, $cn\ X\ 0$, we just return [X]. Otherwise, we call $cn\ X\ (n-1)$, this computes the previous difference, and compute $cn\ Y\ (n-1)$, the difference between the previous and the current difference. Here is how we compute the difference of the difference:

$$cn \ Y \ 0 = [Y]$$

 $cn \ Y \ n = Z : cn \ Y \ (n-1)$

If we need the first difference, $cn \ Y \ 0$, we just return [Y]. Otherwise, we compute the previous difference $cn \ Y \ (n-1)$ adding Z, the constant difference, to the result.

The output looks somewhat weird. When we call, for instance, cn H 5, we see

$$[H, X, X, Y, X, Y, Z, Y, X, Y, Z, Y, Z, Z, Y, X, Y, Z, Y, Z, Z, Y, Z, Z, Y, Z, Z, Y],$$

which is somewhat confusing. We, therefore implement one more function: *ccn*, for "count cn":

```
 \begin{split} ccn :: [\mathit{Newton}] &\rightarrow (\mathit{Int}, \mathit{Int}, \mathit{Int}, \mathit{Int}) \\ ccn \ ls &= (\mathit{length} \ (\mathit{filter} \ (\equiv H) \ ls), \\ & \mathit{length} \ (\mathit{filter} \ (\equiv X) \ ls), \\ & \mathit{length} \ (\mathit{filter} \ (\equiv Y) \ ls), \\ & \mathit{length} \ (\mathit{filter} \ (\equiv Z) \ ls)) \end{split}
```

When we apply this function, e.g. ccn (cn H 5), we see:

```
(1, 5, 10, 10)
```

The binomial coefficients $\binom{5}{k}$, for $k \in \{0...3\}$. To see some more examples we call $map\ (\lambda n \to ccn\ (cn\ H\ n))\ [0..10]$ and get

```
[(1,0,0,0),\\(1,1,0,0),\\(1,2,1,0),\\(1,3,3,1),\\(1,4,6,4),\\(1,5,10,10),\\(1,6,15,20),\\(1,7,21,35),\\(1,8,28,56),\\(1,9,36,84),\\(1,10,45,120)]
```

1.5 Roots

1.6 Vieta's Formula

1.7 The Method of partial Fractions

1.8 Generationfunctionology 1

1.9 The closed Form of the Fibonacci Sequence

$$G(x) = F_0 + F_1 x + F_2 x^2 + F_3 x^3 + \dots$$
 (1.14)

$$G(x) = 0 + x + x^{2} + 2x^{3} + 3x^{4} + 5x^{5} + 8x^{6} + \dots$$
(1.15)

$$xG(x) = F_0x + F_1x^2 + F_2x^3 + F_3x^4 + \dots$$
(1.16)

$$x^{2}G(x) = F_{0}x^{2} + F_{1}x^{3} + F_{2}x^{4} + F_{3}x^{5} + \dots$$
(1.17)

$$G(x) - xG(x) - x^{2}G(x) = (1 - x - x^{2})G(x).$$
(1.18)

$$(1 - x - x^{2})G(x) = (F_{0} + F_{1}x + F_{2}x^{2} + F_{3}x^{3} + \dots) - (F_{0}x + F_{1}x^{2} + F_{2}x^{3} + \dots) - (F_{0}x^{2} + F_{1}x^{3} + \dots)$$

$$(1 - x - x^{2})G(x) = F_{0} + (F_{1} - F_{0})x$$

$$+ (F_{2} - F_{1} - F_{0})x^{2}$$

$$+ (F_{3} - F_{2} - F_{1})x^{3}$$

$$+ \dots$$

$$(1 - x - x^2)G(x) = x. (1.19)$$

$$G(x) = \frac{x}{1 - x - x^2}. (1.20)$$

1.10 Factoring Polynomials