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AN OVERVIEW OF THE TRILINOS CORE PRODUCTS

Roger Pawlowski

HPSF Conference 2025

May 5-8, 2025, Chicago, IL



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CORE AREA PROVIDES FOUNDATIONAL CAPABILITIES FOR PACKAGES

- Performant data structures
- Abstraction layers (for linear algebra, linear solvers and nonlinear analysis)
- Utility libraries
- Common look and feel
- Includes “snapshotted” packages: Kokkos, Kokkos-Kernels and SEACAS

CORE AREA – PROVIDES BASIC CAPABILITIES



Roger Pawlowski

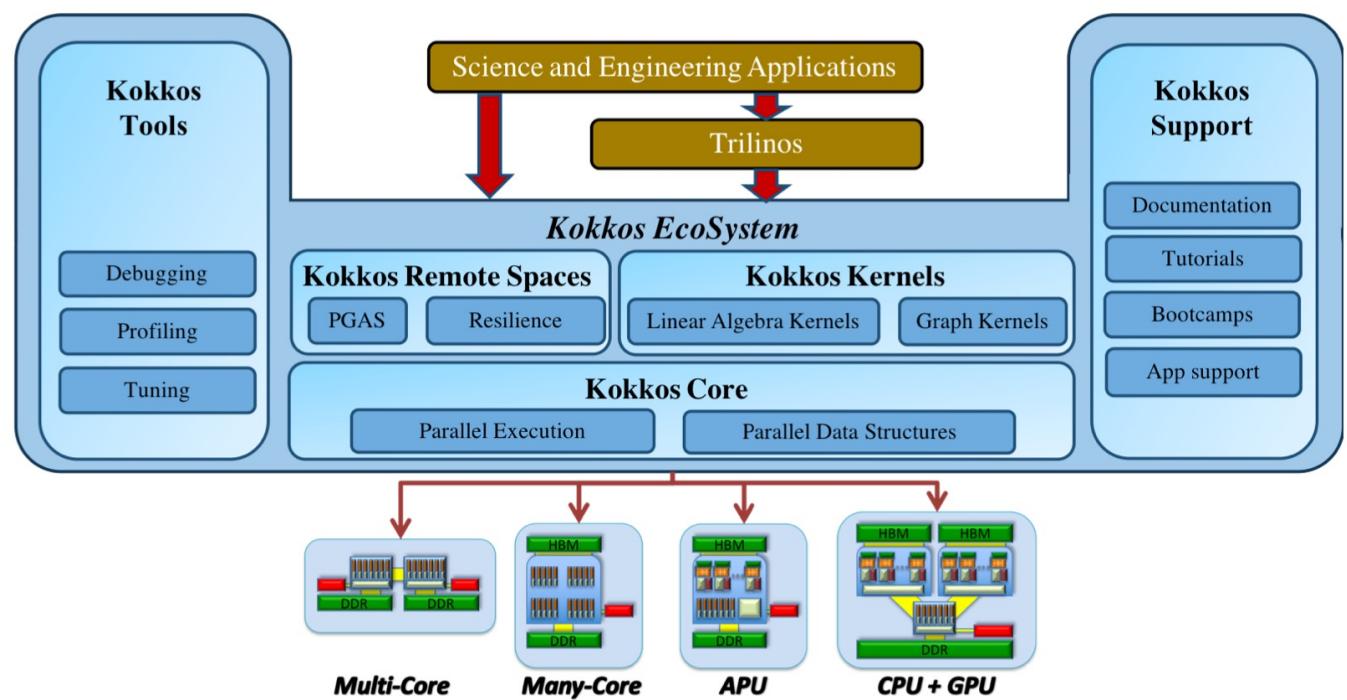
Alegbra/Numerics		
Kokkos (@kokkos)	Performance portability library	Christian Trott (@crtrott)
Kokkos Kernels (@kokkos-kernels)	Optimized math kernels for Kokkos library	Luc Berger-Vergiat (@lucbv)
RTOp (@rtop)	Vector Reduction/Transformation OPerators	Ross Bartlett (@bartlettroscoe)
Thyra (@thyra)	Abstract numerical algorithms and interfaces	Ross Bartlett (@bartlettroscoe)
Tpetra (@tpetra)	Distributed linear algebra objects	Chris Siefert (@csiefert2)
Utilities		
Galeri (@galeri)	Matrix generation tools	Jonathan Hu (@jhux2)
PyTrilinos2 (@pytrilinos2)	Python bindings for Trilinos packages	Christian Glusa (@cgcg)
SEACAS (@SEACAS)	Utilities supporting finite element analysis	Greg Sjaardema (@gsjaardema)
Teuchos (@teuchos)	Common tools (<i>smart pointers, parameter lists, ...</i>)	Roger Pawlowski (@rppawlo)
Meshing / Domain Decomposition		
Pamgen (@pamgen)	Mesh generation tools for simple shapes	Roger Pawlowski (@rppawlo)
Zoltan/Zoltan2 (@zoltan, @zoltan2)	Load balancing and partitioning	Erik Boman (@egboman)

PyTrilinos: Christian Glusa's talk @4:40pm

PERFORMANCE PORTABILITY: KOKKOS™



- Shared memory programming model in C++
- Write once, run on many architectures
- Thread scalable parallel patterns: for, reduce, scan, task
- Execution and Memory spaces
- Multidimensional array with compile-time polymorphic layouts
- Kokkos devs are on the c++ committee



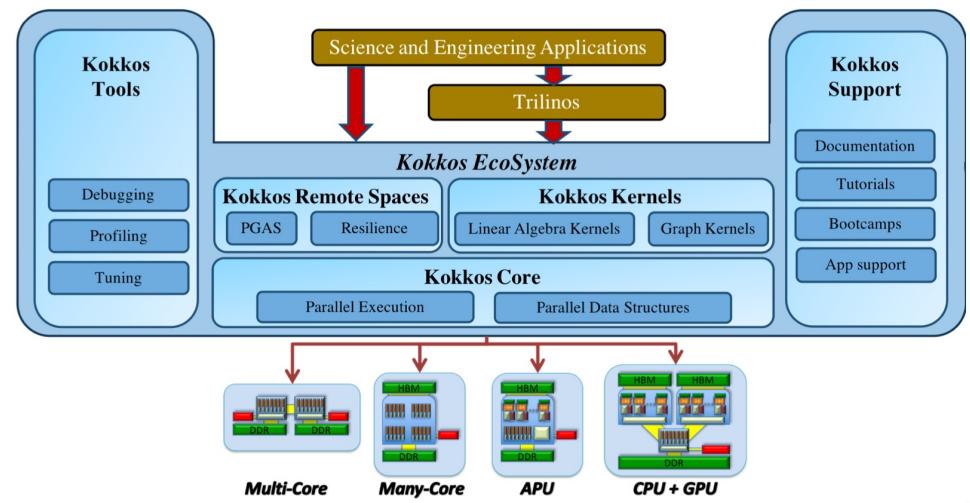
<https://github.com/kokkos/kokkos>

PERFORMANCE PORTABLE LINEAR ALGEBRA: KOKKOS-KERNELS



KokkosKernels provides math kernels for dense and sparse linear algebra as well as graph computations.

- Portable BLAS, Sparse and Graph kernels
- Generic implementations for various scalar types and data layouts
- Access to major vendor optimized math libraries.
- Expand the scope of BLAS to hierarchical implementations.
- Batched BLAS



PARALLEL SPARSE LINEAR ALGEBRA: TPETRA

Basic building blocks for Trilinos solvers and preconditioners

- **Provides**

- Maps (distributed index array)
- Sparse graphs, (block) sparse matrices, & dense vectors/multivectors
- Norms, SpMV, SpGEMM, ...
- MPI communication & data (re)distribution
- Fill: {Create,modify} {graph,matrix,vector}

- **Key features**

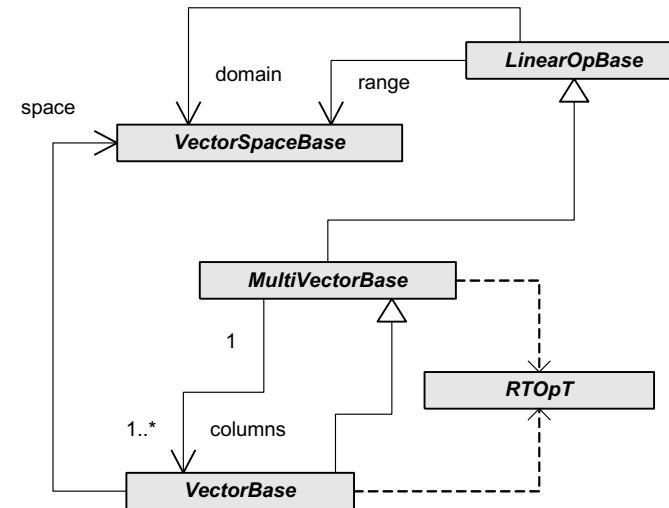
- Can pick type of values (real, complex, automatic differentiation, ensemble, ...)
- Detailed performance monitoring (**see Chris Siefert's talk @4:20pm**)



Image source:
https://en.wikipedia.org/wiki/Siq#/media/File:Petra_First_Glimpse.jpg

SOLVER ABSTRACTION LAYER: THYRA

- Abstractions for:
 - Vector/Operator (+Blocked wrappers)
 - Linear solvers/Preconditioners
 - Nonlinear solvers
 - Physics model interface (solver callback API)
- Matrix/Vector operations are handled in native data structures
 - Tpetra, Epetra, PETSC, ...
- Used to write higher level packages/algorithms
 - Wrapper to all linear solver/preconditioners (**Stratimikos**)
 - Physics-based block preconditioners (**TEKO**)
 - Nonlinear solver (**NOX**)
 - Time integration (**Tempus**)
 - Optimization (**ROL**)
 - Bifurcation/Stability Analysis (**LOCA**)



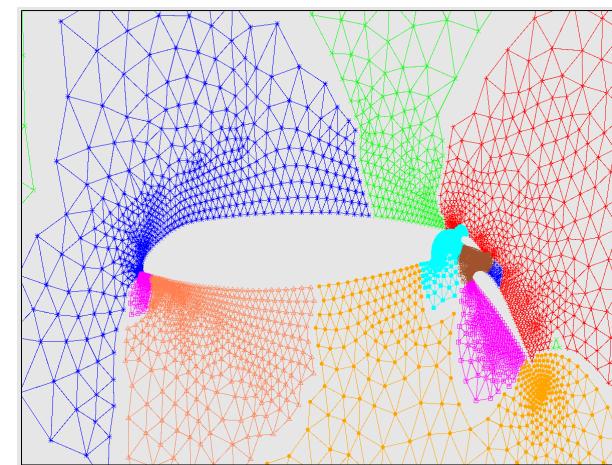
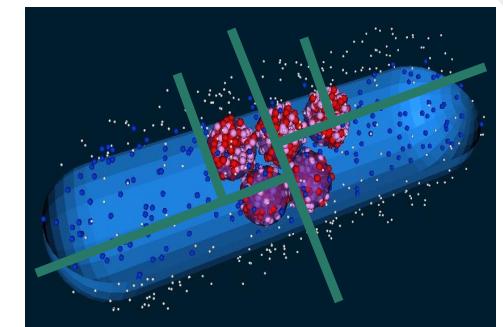
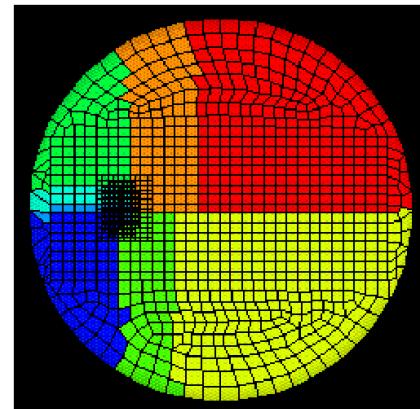
$$\begin{bmatrix} \mathbf{Q}_B & \mathbf{K}_E^B & 0 \\ \mathbf{K}_B^E & \mathbf{Q}_E & \mathbf{Q}_F^E \\ \mathbf{Q}_B^F & \mathbf{Q}_E^F & \mathbf{D}_F \end{bmatrix} \begin{bmatrix} \mathbf{B} \\ \mathbf{E} \\ \mathbf{F} \end{bmatrix}$$

See
Malachi
Phillips's
Talk
@4pm

PARALLEL PARTITIONING AND LOAD BALANCING: ZOLTAN/ZOLTAN2



- **Zoltan** and **Zoltan2** are packages for partitioning, load balancing, and combinatorial scientific computing
 - Both have a collection of algorithms (geometric partitioning, graph, hypergraph, etc.)
- Zoltan is quite old (~2000) and can be used stand-alone on CPUs
- Zoltan2 is fairly new and a tightly integrated Trilinos package
 - Supports Kokkos and GPUs
 - Works with Tpetra matrices and vectors
 - Currently depends on Zoltan (though some algorithms have been reimplemented)
 - Has similar features/functionality to Zoltan but not exactly the same



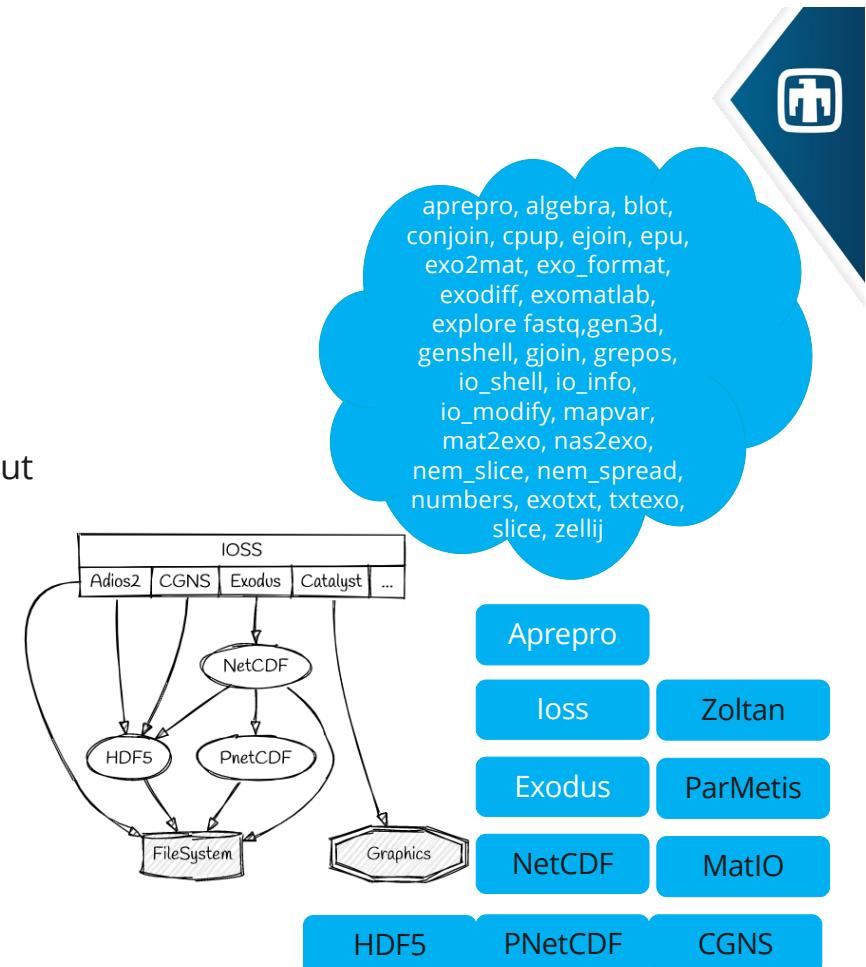
FINITE ELEMENT I/O TOOLS: SEACAS

- Provide IO for Sandia finite-element applications
- Provide applications and libraries for analyst workflow
- Support Production Analysts and Path-Forward Developers

SEACAS contains the **Exodus** and **IOSS** finite element input/output libraries; applications supporting meshing, preprocessing, postprocessing, graphics, database translation; and support libraries..

Exodus is a model developed to store and retrieve data for finite element analyses in a random access, machine independent, binary file that is written and read via C, C++, or Fortran APIs.

The **IO Subsystem** (IOSS) is a high-level database access API designed to give a format-agnostic interface to I/O capabilities with multiple backends outputting data to multiple formats. Supported input and output formats are **Exodus**, **CGNS**, HeartBeat, History, Generated, Pamgen, TextMesh, ADIOS2, FAODEL, Catalyst2, Null.



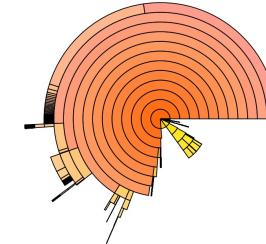
A supercomputer is a device for turning compute-bound problems into I/O-bound problems

TEUCHOS: COMMON PACKAGE UTILITIES (PRONOUNCED “TEFOS”)



- Provides a common look and feel
- Capabilities:
 - Reference counted smart pointer ([RCP](#))
 - **ParameterList**: runtime database (with yaml and xml I/O)
 - C++ Abstraction for an [MPI Communicator](#)
 - **Timers**
 - CPU BLAS/LAPACK wrappers
 - Scalar traits
 - Unit test harness
 - I/O Interface

```
NOX:  
  Direction:  
    Method: Newton  
  Newton:  
    Forcing Term Method: Constant  
    Rescue Bad Newton Solve: true  
    Stratimikos Linear Solver:  
      NOX Stratimikos Options: { }  
      Stratimikos:  
        Linear Solver Type: Belos
```



```
Panzer MixedPoisson Test: 4.39393 [1]  
| Mixed Poisson: 4.39382 - 99.9976% [1]  
| | panzer::CubeHexMeshFactory::buildUncommittedMesh(): 0.000528984 - 0.0120393% [1]  
| | panzer::CubeHexMeshFactory::completeMeshConstruction(): 0.765863 - 17.4305% [1]  
| | panzer::DOFManagerFactory::buildUniqueGlobalIndexer: 0.0451156 - 1.0268% [1]  
...  
| | Ifpack2::Relaxation::initialize: 4.403e-06 - 0.000100209% [1]  
| | Ifpack2::Relaxation::compute: 0.00249703 - 0.0568305% [1]  
| | Belos: Operation Op*x: 0.00338377 - 0.0770121% [1]  
| | Belos: PseudoBlockGmresSolMgr total solve time: 0.432027 - 9.83259% [1]  
| | | Belos: ICGS[2]: Orthogonalization: 0.0212883 - 4.92755% [31]  
| | | | Belos: ICGS[2]: Ortho (Norm): 0.000489003 - 2.29705% [31]  
| | | | Belos: ICGS[2]: Ortho (Inner Product): 0.00904903 - 42.507% [60]  
| | | | Belos: ICGS[2]: Ortho (Update): 0.00662776 - 31.1333% [60]  
| | | | Remainder: 0.00512255 - 24.0627%  
| | | Belos: Operation Prec*x: 0.0420421 - 9.73136% [31]  
| | | | Ifpack2::Relaxation::apply: 0.0418983 - 99.658% [31]  
| | | | Remainder: 0.000143774 - 0.341977%  
| | | Belos: Operation Op*x: 0.104452 - 24.1772% [31]  
| | | Remainder: 0.264244 - 61.1639%  
...
```



EXAMPLE APPLICATION

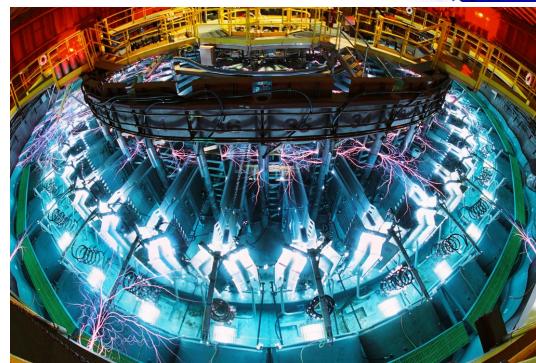
EMPIRE MODELS PLASMA EFFECTS IN HOSTILE NUCLEAR ENVIRONMENTS

- Empire is a plasma physics code used in weapon modernization work for hostile nuclear environments
- Simulation is necessary - test facilities can only access parts of parameter space
- Used extensively in conjunction with experimental facilities

EMPIRE



Z: World's most powerful pulsed-power facility and x-ray generator



SATURN: World's brightest x-ray generator, tests electronics



HERMES-III: World's most powerful gamma simulator, for testing electronics and military systems

EMPIRE'S NUMERICAL APPROACH: FEM-PIC



Empire's Particle-in-Cell (PIC) scheme¹ solves the equations of motion

$$\frac{dx_p(t)}{dt} = v_p(t),$$

$$\frac{dv_p(t)}{dt} \equiv a_p(t) = \frac{q_p}{m_p} [E(t, x_p(t)) + v_p(t) \times B(t, x_p(t))]$$

encoded by the *plasma kinetic equation* for each particle (p):

$$\frac{df(t, x, v)}{dt} \equiv \frac{\partial f}{\partial t} + v \cdot \frac{\partial f}{\partial x} + a \cdot \frac{\partial f}{\partial v} = \left(\frac{\partial f}{\partial t} \right)_{coll}$$

with fields evolved according to the Maxwell curl equations:

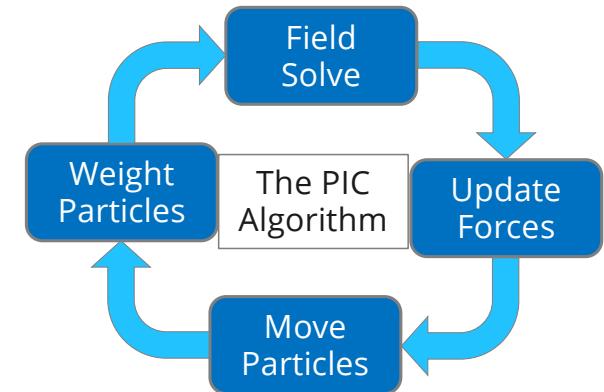
$$\frac{\partial B}{\partial t} = -\nabla \times E$$

$$\frac{\partial E}{\partial t} = \frac{1}{\epsilon\mu} \nabla \times B - \frac{1}{\epsilon} J$$

solved in strong form

solved in weak form

Using compatible discretization decisions^{2,3} ensures the Maxwell divergence constraints are satisfied for all time



Flow diagram showing a pure PIC timestep

$$\begin{pmatrix} \Delta t^{-1} \mathbb{I}_{\mathcal{F}} & \mathbb{K}_h \\ -\mathbb{K}_h^T \mathbb{M}_{\mathcal{F}}(\mu^{-1}) & \Delta t^{-1} \mathbb{M}_{\mathcal{E}}(\epsilon) \end{pmatrix} \begin{pmatrix} \Delta B \\ \Delta E \end{pmatrix} = - \begin{pmatrix} r_B \\ r_E \end{pmatrix}$$

where \mathbb{K} = discrete curl operator, \mathbb{M} = mass matrix, \mathbb{I} = identity matrix, \mathcal{F} and \mathcal{E} label operators acting on face and edge spaces, h is the characteristic mesh dimension which labels quantities as spatially discretized versions of their continuum counterparts, Δt = timestep width, r = residuals

¹Bettencourt, et. al., *EMPIRE-PIC: A Performance Portable Unstructured Particle-in-Cell Code*, 2021

²Nédélec J-C. *Mixed finite elements in \mathbb{R}^3* . Numerische Mathematik, 35(3):315–341, 1980.

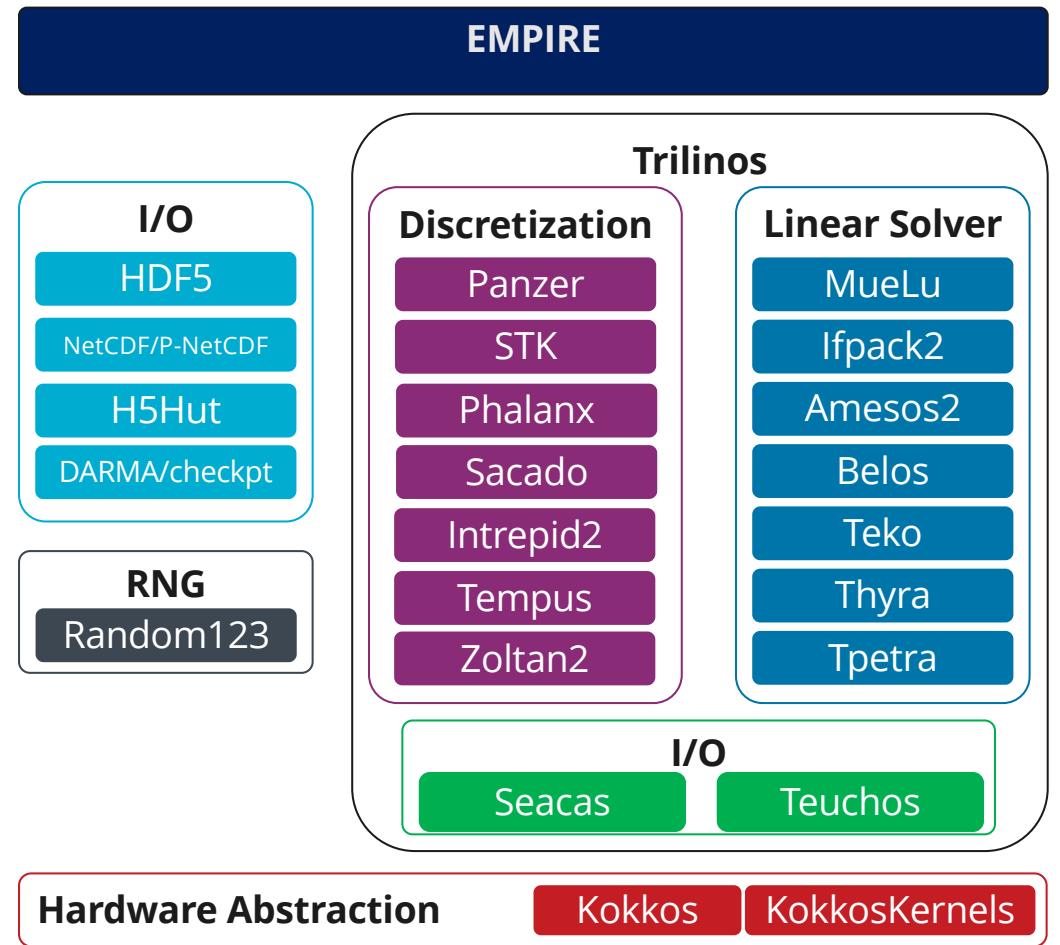
³Raviart P-A. and Thomas, J. T. *A mixed finite element method for 2nd order elliptic problems*. Mathematical aspects of finite element methods, volume 606, pages 292–315. 1977

EMPIRE WAS DESIGNED ON A “COMPONENT” STRATEGY

- Directly depends on 21 Trilinos packages
- 38 total Trilinos packages with indirect dependencies
- Empire is built from the ground up for performance portability
- Requires large-scale iterative linear solve for electromagnetics

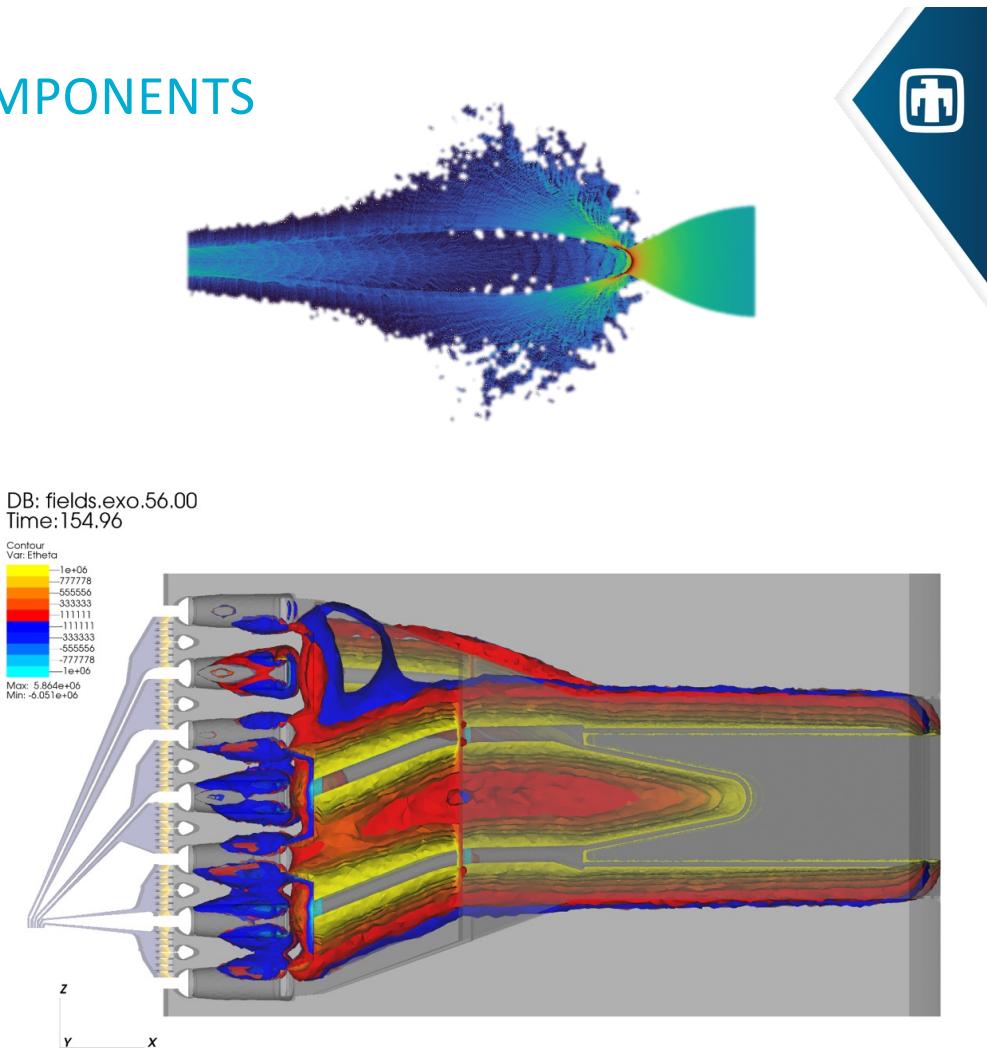
Linear Solvers: See Jonathan Hu’s Talk @2:15pm

Discretization: See Mauro Perego’s Talk @2:35pm



USE OF CORE AND DISCRETIZATION COMPONENTS

- **Kokkos** for underlying data structures of the entire code
- **Tpetra** for parallel distributed linear algebra
- Empire's (yaml) input file uses **Teuchos::ParameterList** for parsing and validation
- **SEACAS** is used to read and write mesh data
- **Zoltan** used to load balance the finite element mesh for parallel simulations
- **Thyra** used for blocked linear solves and coupling to circuits
- **Shards** for cell topology
- **Intrepid2** for finite element (FE) bases
- **Phalanx** for performance portability tools (view-of-views, virtual-function-on-device, ...)
- **Panzer** for mesh tools, periodic bcs and FE assembly
- **STK** for runtime mesh database
- **Percept** for uniform mesh refinement



ELECTROMAGNETIC SOLVER USING COMPATIBLE FINITE ELEMENTS



$$\begin{pmatrix} \Delta t^{-1} \mathbb{I}_{\mathcal{F}} & \mathbb{K}_h \\ -\mathbb{K}_h^T \mathbb{M}_{\mathcal{F}}(\mu^{-1}) & \Delta t^{-1} \mathbb{M}_{\mathcal{E}}(\epsilon) \end{pmatrix} \begin{pmatrix} \Delta \mathbf{B} \\ \Delta \mathbf{E} \end{pmatrix} = - \begin{pmatrix} \mathbf{r}_B \\ \mathbf{r}_E \end{pmatrix} \quad \begin{aligned} \mathbf{B} &\in \mathbf{H}_{\nabla \cdot}(\Omega) \\ \mathbf{E} &\in \mathbf{H}_{\nabla \times}(\Omega) \end{aligned}$$

Block LU Decomposition

$$\begin{pmatrix} \Delta t^{-1} \mathbb{I}_{\mathcal{F}} & \mathbb{K}_h \\ -\mathbb{K}_h^T \mathbb{M}_{\mathcal{F}}(\mu^{-1}) & \Delta t^{-1} \mathbb{M}_{\mathcal{E}}(\epsilon) \end{pmatrix} = \begin{pmatrix} \mathbb{I}_{\mathcal{F}} & 0 \\ -\Delta t \mathbb{K}^T \mathbb{M}(\mu^{-1}) & \mathbb{I}_{\mathcal{E}} \end{pmatrix} \begin{pmatrix} \Delta t^{-1} \mathbb{I}_{\mathcal{E}} & \mathbb{K}_h \\ 0 & \mathbb{S}_{\mathcal{E}} \end{pmatrix}$$

Assemble Schur Compliment $\mathbb{S}_{\mathcal{E}} = \Delta t^{-1} \mathbb{M}_{\mathcal{E}}(\epsilon) + \Delta t \mathbb{K}_h^T \mathbb{M}(\mu^{-1}) \mathbb{K}_h$
as monolithic matrix

Solve for dE with PCG:

$$\mathbb{S}_{\mathcal{E}} \Delta \mathbf{E} = -\mathbf{r}_E + \Delta t \mathbb{K}_h^T \mathbb{M}(\mu^{-1}) \mathbf{r}_B$$

Explicit back solve for dB:

$$\Delta \mathbf{B} = -\Delta t \mathbb{K}_h \Delta \mathbf{E} - \Delta t \mathbf{r}_B$$

Bettencourt, et. al., *EMPIRE-PIC: A Performance Portable Unstructured Particle-in-Cell Code*, 2021

Lourenco Beirao de Veiga, Konstantin Lipnikov, and Marco Manzini, *Mimetic Finite Difference Method for Elliptic Problems*.

Bochev et al., *An algebraic multigrid approach based on a compatible gauge reformulation of Maxwell's equations*, 2008.

Meshing:
STK, Percept,
SEACAS, Panzer

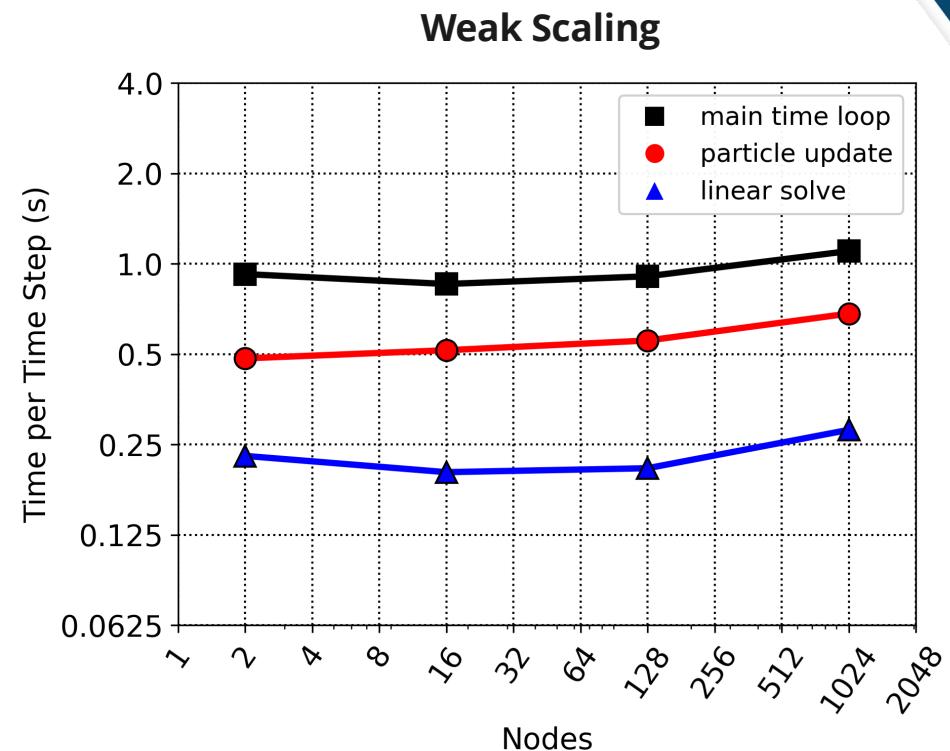
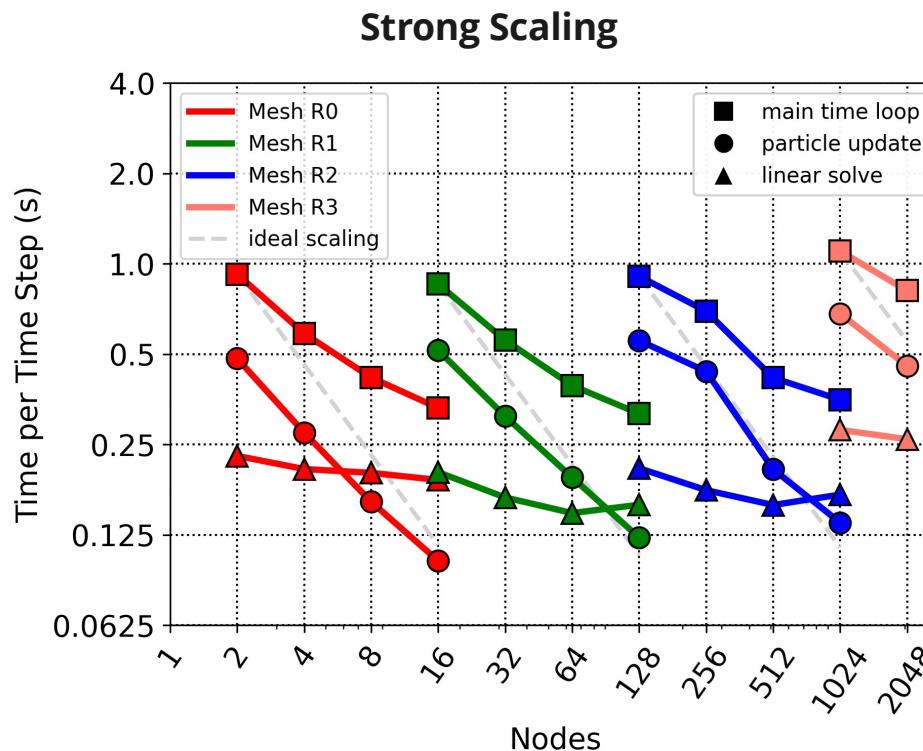
Data Structures:
Kokkos,
KokkosKernels,
Tpeta

FE Assembly:
Shards, Intrepid2,
Panzer, Thyra

Linear Solve:

- Uses RefMaxwell AMG with Conjugate Gradient
- Chebyshev smoother
- Prec setup done once
- Belos, Teko, MueLu, Ifpack2, Amesos2, KokkosKernels, Zoltan2

SCALABILITY ON CAVITY PROBLEM ON ATS-2 SIERRA (4 NVIDIA V100 GPUS/NODE)

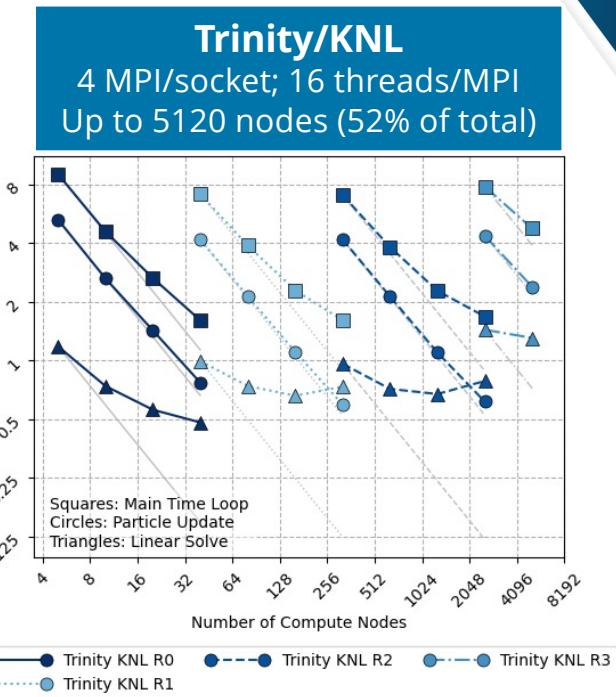
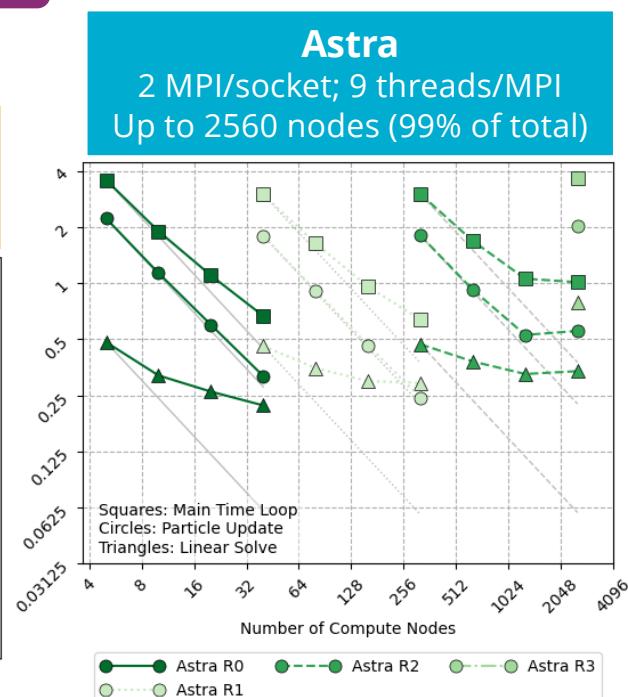
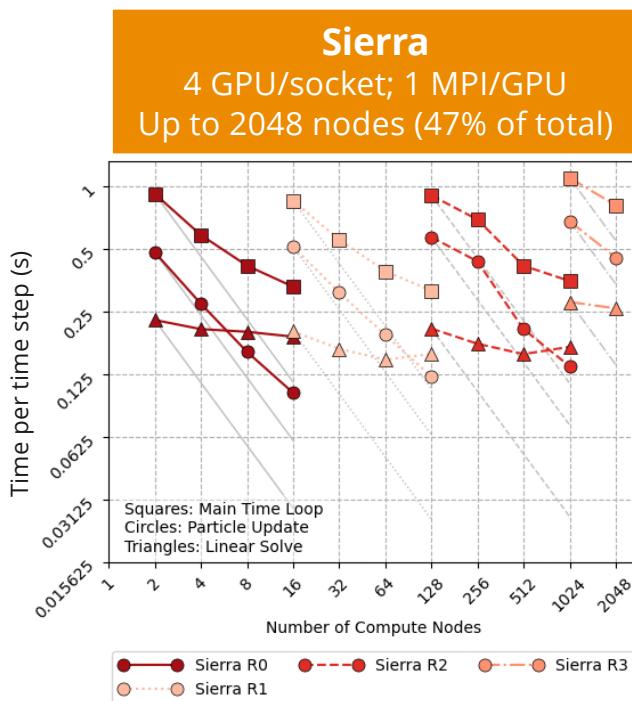


- Largest Simulations: 1.6B Elements and 160B particles!

PERFORMANCE RESULTS FOR GENERIC CAVITY



Single platform scaling results



PERFORMANCE RESULTS ON AMD GPUS (MI250X)



EAS3: 36 nodes available, will show results up to 32 nodes

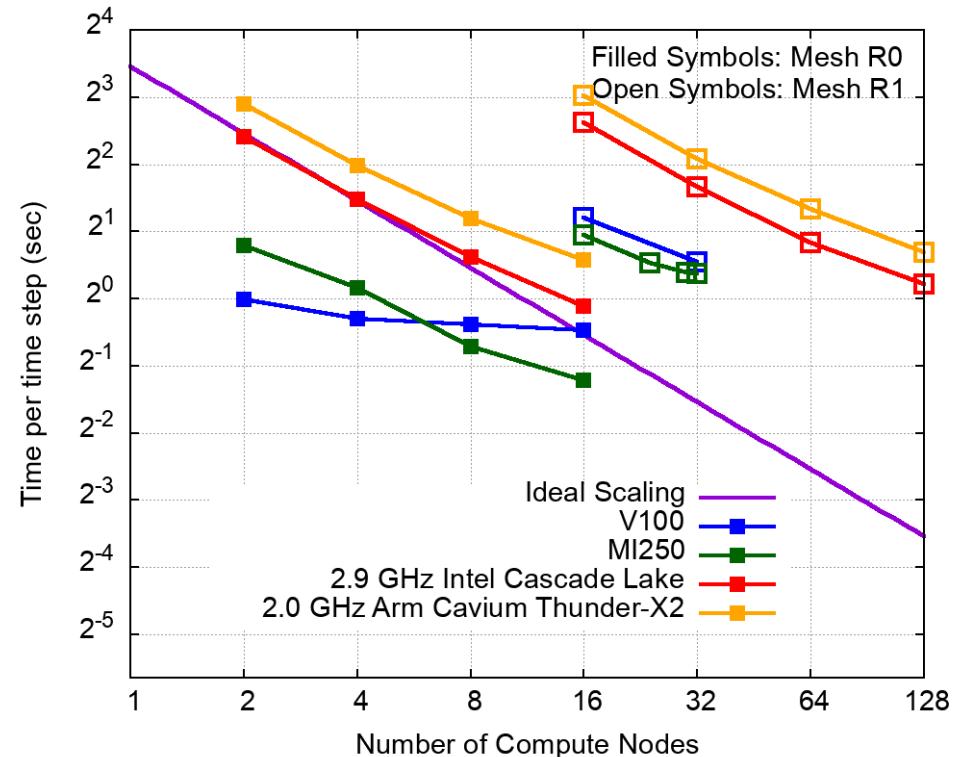
Machines:

- **EAS3:** 4 AMD MI250x GPUs per node
- **CTS-1:** Intel Cascade Lake 48 cores per node
- **ATS-2:** 4 NVIDIA V100 GPUs per node
- **Vanguard:** 2.0 GHz ARM Cavium Thunder-X2, 56 cores per node

System	Peak FLOPs	STREAM Bandwidth
Single MI250x	48 TF	2.68 TB/s
Single V100	7 TF	855 GB/s
Intel Cascade Lake node	4.45 TF	208 GB/s
Arm Cavium Thunder X2 node	896 GF	250 GB/s

Two meshes, uniformly refined:

Mesh	Elements	Nodes	Edges	Particles
R0	4.6M	791K	220K	170M
R1	36.8M	6.2M	883K	1.35B

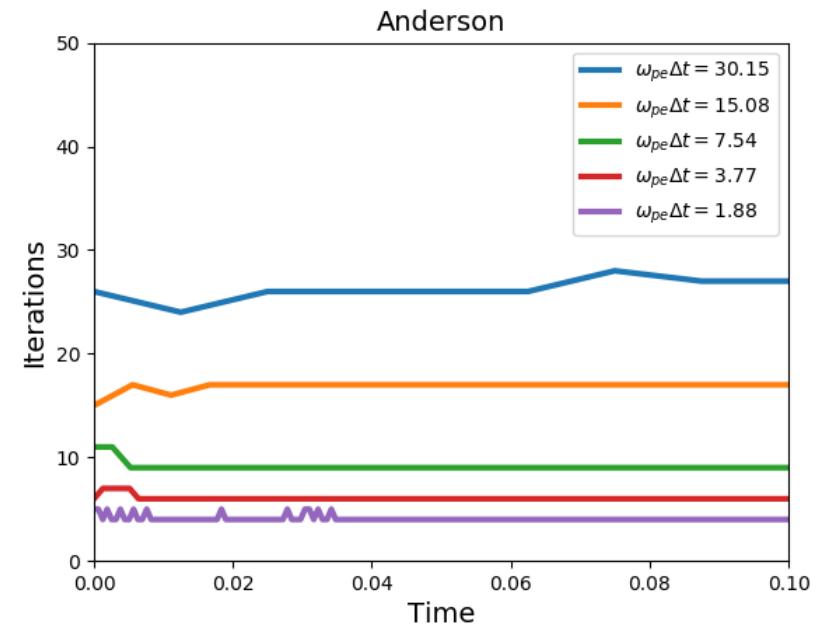
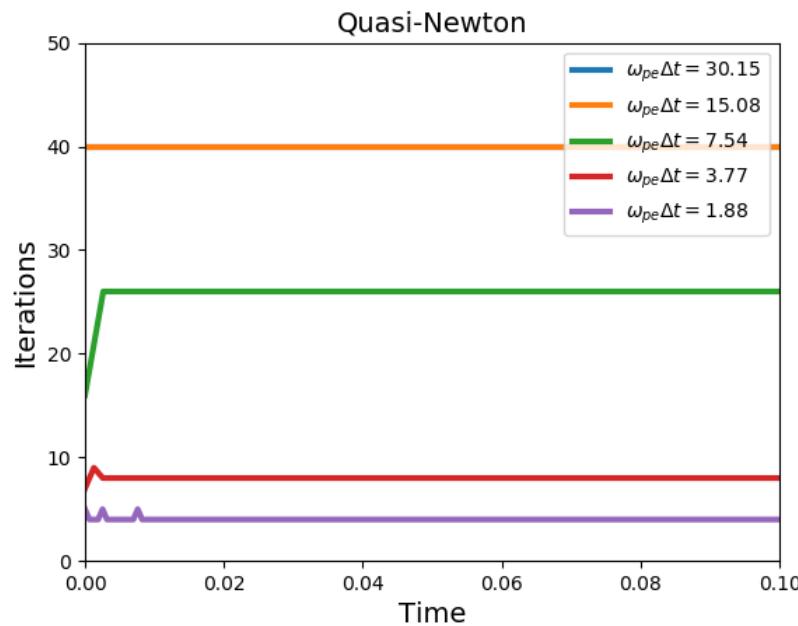


- **Default linear solve used on EAS3. No work to date on optimizing the linear solve on EAS3!**
- Other platforms all have linear solves that were hand tuned/optimized for the hardware.

ANDERSON ACCELERATION IMPROVES PERFORMANCE

- Hybrid Two fluid plasma vortex in MHD limit
- IMEX time discretization, DG fluid discretization, coupled to CG Maxwell discretization
- Using Schur-Complement in all simulations

- Fluid block diagonal solver: **KokkosKernels**: KokkosBatched_LU and KokkosBatched_Trsrm
- Coupled outer solve: **NOX** for Anderson Acceleration



AN INCOMPLETE LIST OF CONTRIBUTORS



Trilinos Core Area

- Chris Baker
- Ross Bartlett
- Erik Boman
- Karen Devine
- Christian Glusa
- Roger Pawlowski
- Chris Siefert
- Greg Sjaardema
- Heidi Thornquist
- Jonathan Hu
- Michael Heroux
- Daniel Ibanez
- Mark Hoemmen
- Kevin Long
- Christian Trott
- Damien Lebrun-Grandie
- Siva Rajamanikan
- Luc Berger-Vergiat

Empire

- Matt Bettencourt
- Keith Cartwright
- Eric Cyr
- Adam Darr
- James Elliott
- Daniel Jensen
- Todd Kordenbrock
- Richard Kramer
- Caleb Logeman
- Ed Love
- William McDoniel
- Duncan McGregor
- Logan Meredith
- Chris Moore
- Roger Pawlowski
- Edward Phillips
- Bryan Reuter
- Sid Shields
- David Sirajuddin
- Shane Stafford
- Scot Swan

And many more...

SUMMARY

- Trilinos provides powerful tools for modeling complex physical systems
- The “Core” product area supplies foundational building blocks for other packages
- Trilinos enables scalable large-scale simulations on multiple architectures



EXASCALE
COMPUTING
PROJECT



U.S. DEPARTMENT OF
ENERGY

Office of
Science

