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```
%Tyler Matthews
%System Simulation Project
```

```
disp('Decided to simulate two different systems using various values for the timestep and AB2
as the integrator')
```

Decided to simulate two different systems using various values for the timestep and AB2 as the integrator

SYSTEM 1

```
%{
dx/dt = y
dy/dt = (1 - x^2 - y^2)y - x
%}

clc; close all; clear all; %clear console, clear workspace, close figures
figure;
for j = 1:10

    startTime = 0;
    stopTime = 2*j;
    steps = 50000;

    T = (stopTime - startTime)/50;
    t = linspace(startTime, stopTime, steps);

    x = zeros(1, length(t));
    y = zeros(1, length(t));
    fx = zeros(1, length(t));
    fy = zeros(1, length(t));

    x(1) = 0.1;
    y(1) = 0.005;

    fx(1) = y(1);
    fy(1) = y(1)*(1 - x(1)^2 - y(1)^2) - x(1);

    x(2) = x(1) + T*fx(1);%Euler
    y(2) = y(1) + T*fy(1);

    for k=3 : steps
        fx(k-1) = y(k-2);
        fy(k-1) = y(k-2)*(1 - x(k-2)^2 - y(k-2)^2) - x(k-2);
        x(k) = x(k-1) + (3*T)./(2)*fx(k-1) - (T/2)*fx(k-2);%AB2
        y(k) = y(k-1) + (3*T)./(2)*fy(k-1) - (T/2)*fy(k-2);
```

```
end
```

```
%PLOTTING
```

```
subplot(5,2,j)
```

```
t1 = sprintf("T = %0.2f & StopTime = %i", T, stopTime);
```

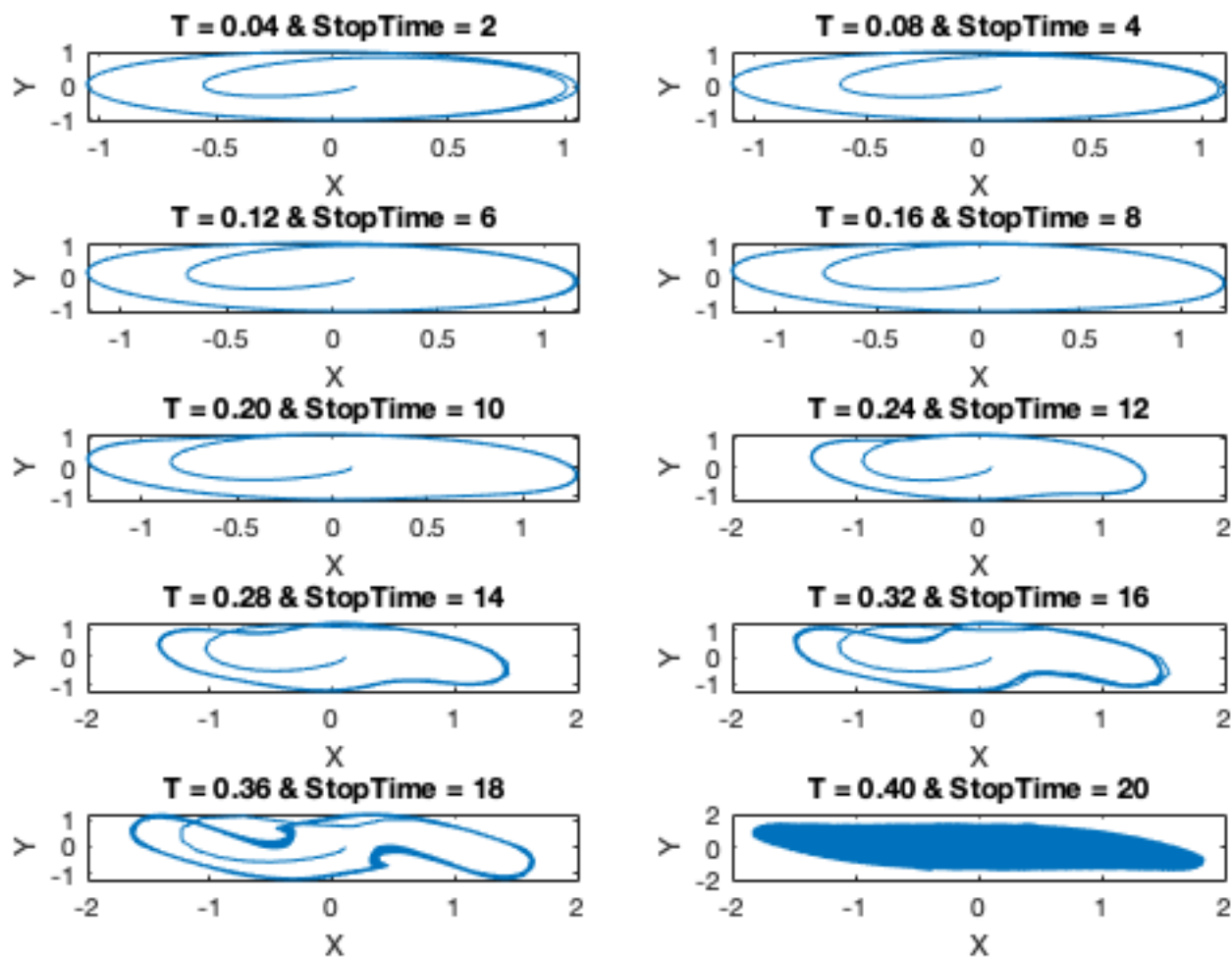
```
plot(x, y)
```

```
xlabel('X')
```

```
ylabel('Y')
```

```
title(t1)
```

```
end
```



System 2

```
%{  
dx/dt = y  
dy/dt = -x  
%}  
stopTimeArr = [1, 5, 10];  
  
figure;  
for j = 1:3  
  
    startTime = 0;  
    stopTime = stopTimeArr(j);  
    steps = 20000;  
  
    T = (stopTime - startTime)/50;  
    t = linspace(startTime, stopTime, steps);
```

```

x = zeros(1, length(t));
y = zeros(1, length(t));
fx = zeros(1, length(t));
fy = zeros(1, length(t));

x(1) = 20;
y(1) = 10;

fx(1) = y(1);
fy(1) = -x(1);

x(2) = x(1) + T*fx(1);
y(2) = y(1) + T*fy(1);

for k=3 : steps
    fx(k-1) = y(k-2);
    fy(k-1) = -x(k-2);
    x(k) = x(k-1) + (3*T)./(2)*fx(k-1) - (T/2)*fx(k-2);
    y(k) = y(k-1) + (3*T)./(2)*fy(k-1) - (T/2)*fy(k-2);
end

%PLOTTING
subplot(3,1,j)
t1 = sprintf("T = %0.2f", T);
plot(x, y)
xlabel('X')
ylabel('Y')
title(t1)
end

```

