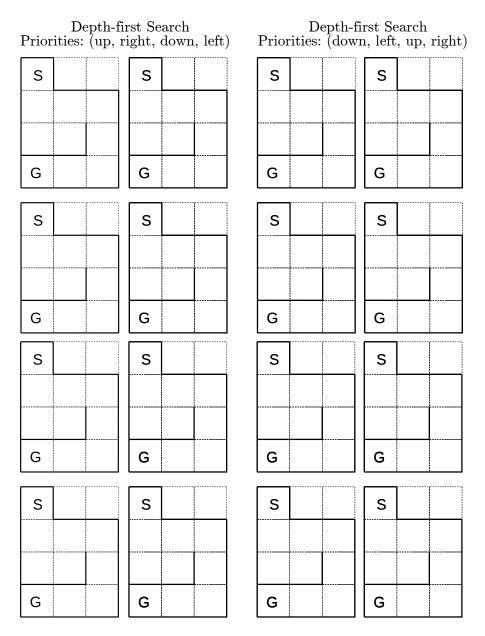
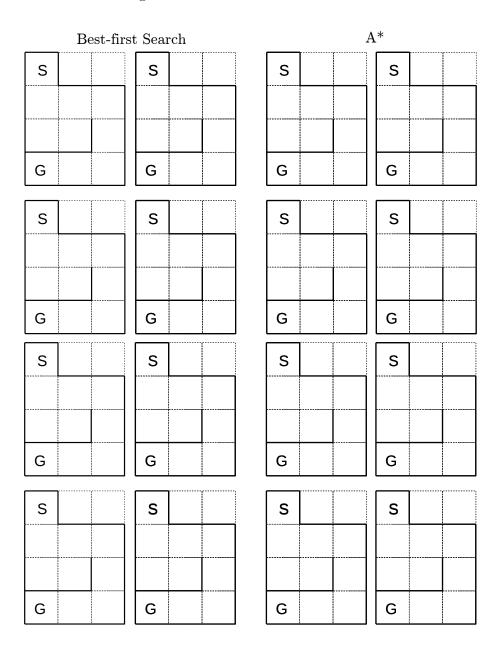
GWV – Grundlagen der Wissensverarbeitung Tutorial 4: Searching

Class Exercise 4.1: (Frontiers and Paths)

The grid below contains a small maze with a start and a goal. Suppose you use Depth-first search (different variants), Best-first search and A^* to find a path to the goal. For each search strategy, draw the frontier and the paths found so far in each search step. You have space for at most 8 search steps per search strategy. For Depth-first search, perform the search for two variants, the first one tries to search up first, then right etc. The other one starts with down, then left etc.



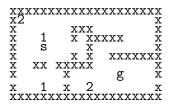


Exercise 4.2: (Heuristic Search)

Extend the program from last week to perform search in the maze:

of

- 1. Implement the blind search strategy "breadth first" to find a path for the robot. (3 Pt.)
- 2. Implement the blind search strategy "depth first" to find a path for the robot. (3 Pt.)
- 3. Provide example mazes that show the differences between and properties of the search strategies. Describe these properties. (2 Pt.)
- 4. Are there cases in which your program is unable to find a solution? Provide example mazes. (1 Pt.)



5. The Figure above shows a modified environment. There are mysterious portals that transport the robot from one field to a pre determined field far away. They are denoted with numbers, that is if the robot enters a field with a 1, it is automatically teleported to the other field with a 1 and so on. Modify your program to cope with this change.

(3 Pt.)

Version: November 6, 2016 Achievable score on this sheet: 12