

Lecture 3: Divide and Conquer Algorithms (II)

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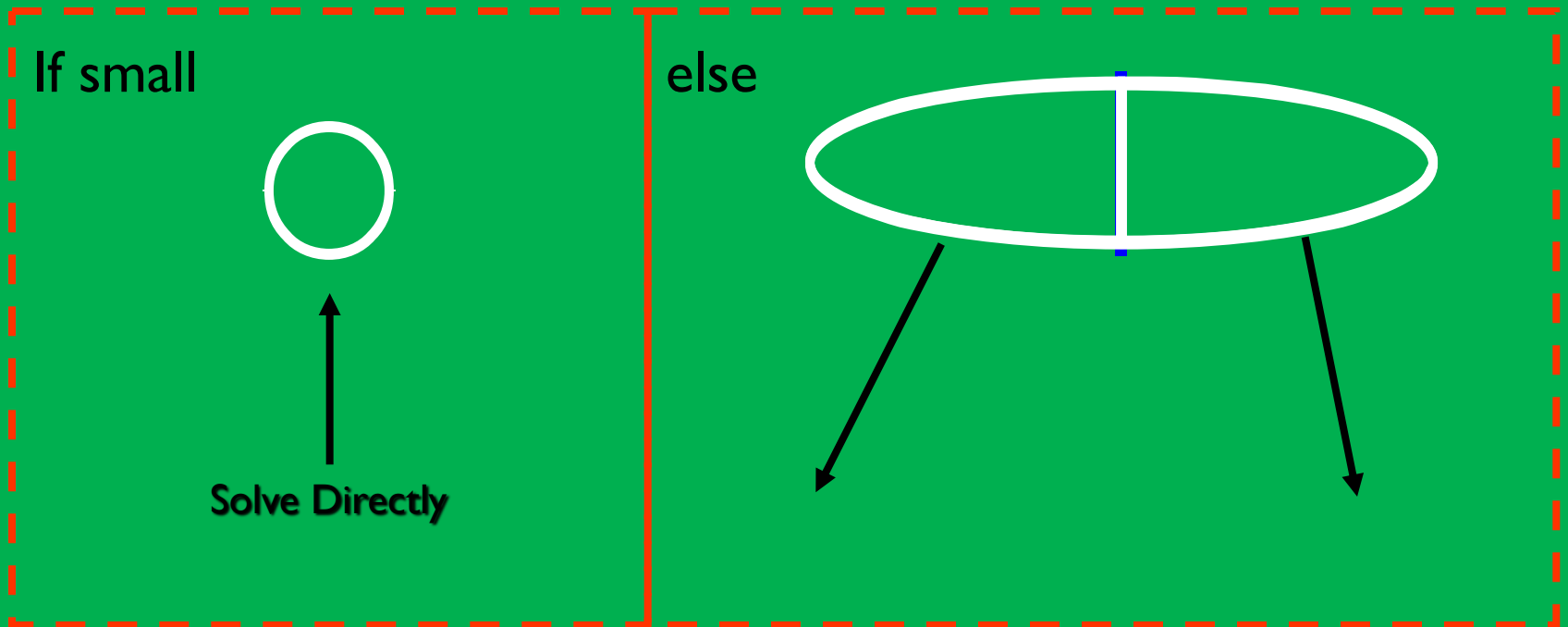


Divide and Conquer Recap

- ❑ **Divide and Conquer** is a recursive algorithm
- ❑ **Three essential steps:**
 - ❑ **Divide:** If the input size is too large to handle efficiently, divide the data into two or more disjoint subsets
 - ❑ **Recurse:** Keeps partitioning the data until a small size reasonable to solve
 - ❑ **Conquer:** Take the solutions from the subproblems and “merge” them to a solution from the division point

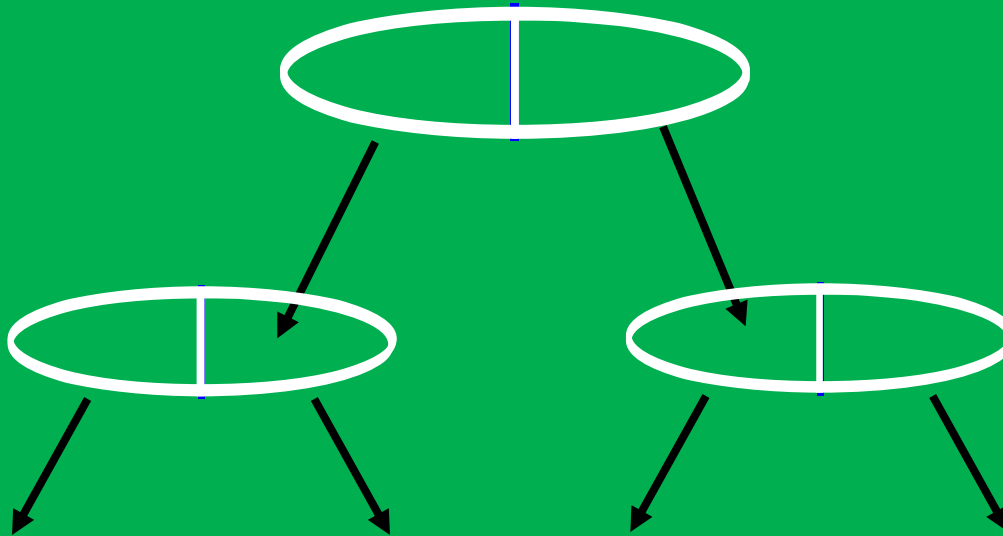
Visualization of Divide and Conquer

□ Divide



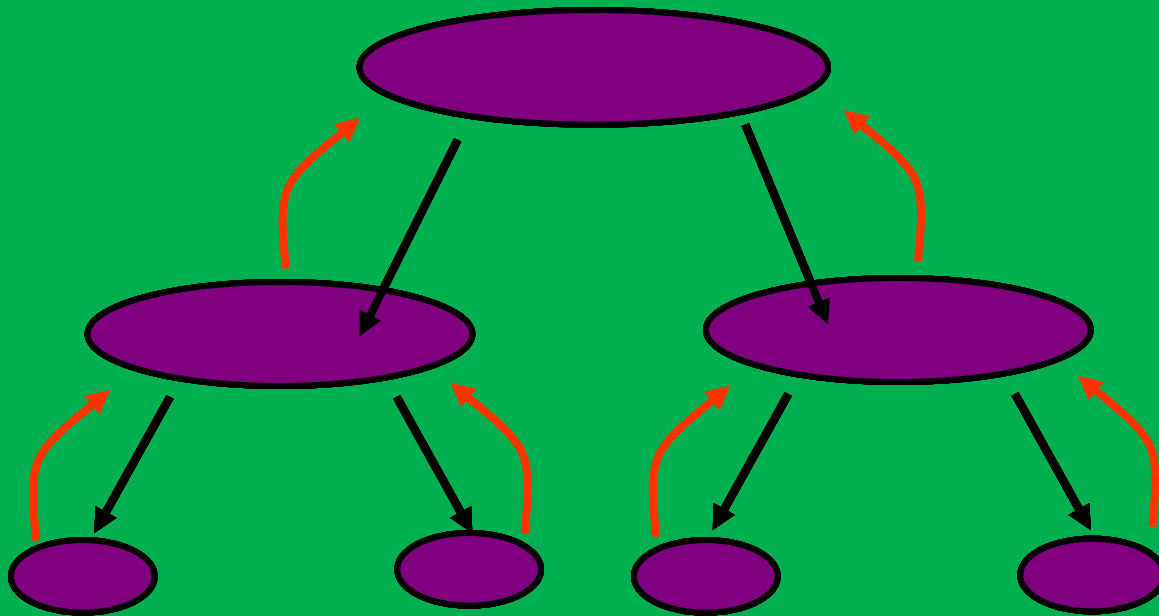
Visualization of Divide and Conquer

□ Recursive



Visualization of Divide and Conquer

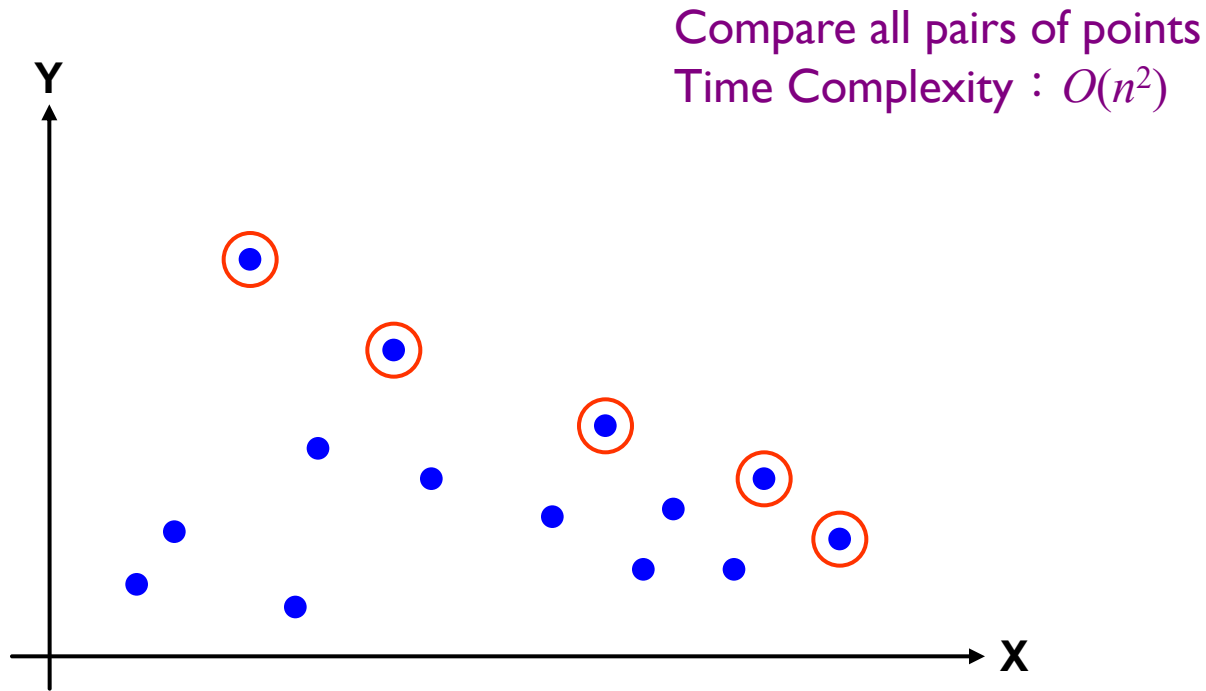
□ Solve and Conquer



Example: Find the 2D Maximal Points

❑ Brute-force method

- ❑ Write a two-level for-loop to compare all pair of points



Find 2D Maximal Points using Divide and Conquer

Input: A set S of n planar points (sorted along x).

Output: The maximal points of S .

Step 1: If S contains only one point, return it as the maxima. Otherwise, find a line L perpendicular to the X -axis which separates S into S_L and S_R , with equal sizes.

Step 2: Recursively find the maximal points of S_L and S_R .

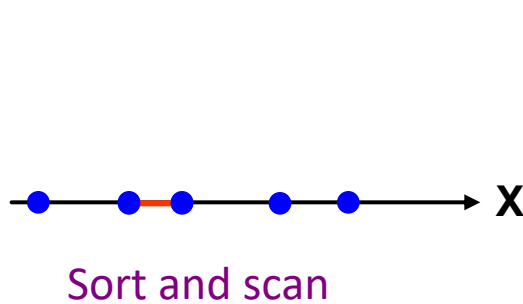
Step 3: Find the largest y -value in S_R , denoted as y_R . Discard each of the maximal points in S_L if its y -value is less than y_R .

```
std::vector<Point> dc(const std::vector<Point>& S, int beg, int end) {  
  
    if(!(beg < end)) return {};  
  
    // base case  
    if(end - beg == 1) return {S[beg]};  
  
    // recursion  
    int m = (beg + end + 1) / 2;  
    auto SL = dc(S, beg, m);  
    auto SR = dc(S, m, end);  
  
    // find the highest y in SR  
    int ymax = std::numeric_limits<int>::min();  
    for(const auto& p : SR) {  
        ymax = std::max(ymax, p.y);  
    }  
  
    // delete all points with y less than ymax from SL  
    for(const auto& p : SL) {  
        if(ymax > p.y) {  
            continue;  
        }  
        SR.push_back(p);  
    }  
  
    return SR;  
}
```

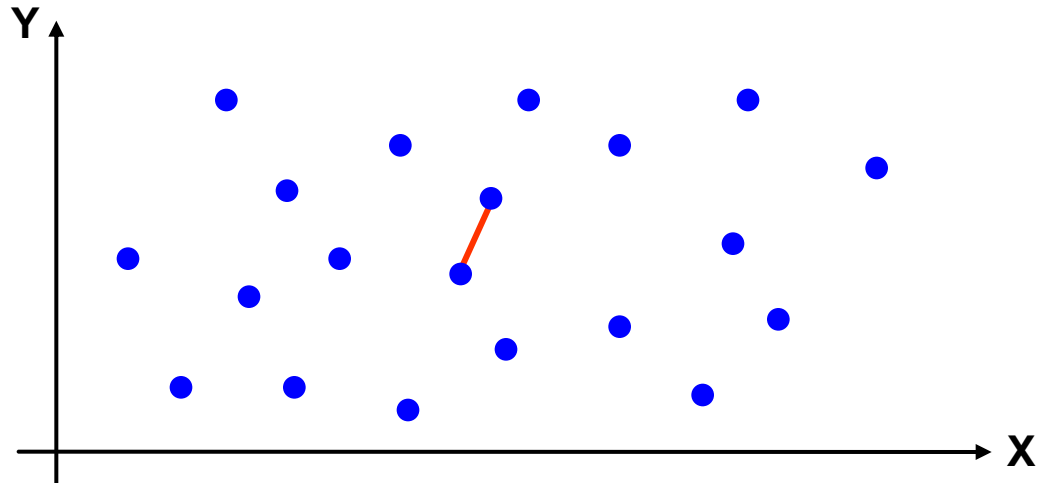

The 2D Closest Pair Problem

- Given a point set at a 2D plane, find a pair of points with the *minimum* distance

1-D version:



2-D version:



Divide and Conquer Algorithm

Input: A set S of n planar points.

Output: The distance between two closest points.

Step 1: Sort S in increasing order of x values

Step 2: If S contains only one point, return infinity as its distance.

Step 3: Find a median line L perpendicular to the x -axis and divide S into S_L and S_R with equal sizes.

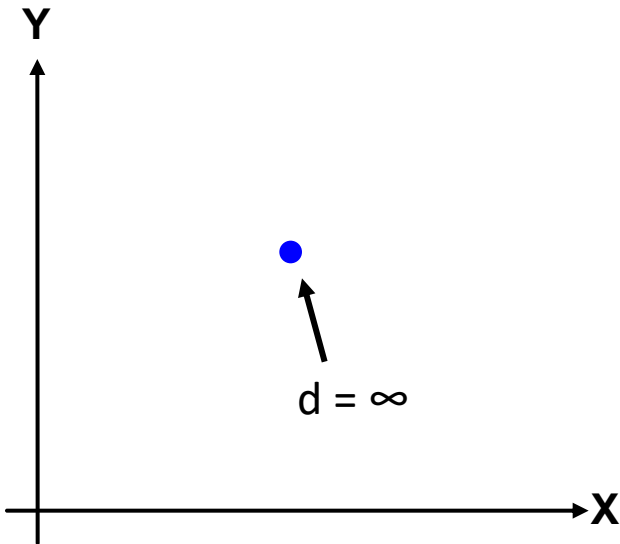
Step 4: Recursively apply Steps 2 and 3 to solve the closest pair problems of S_L and S_R . Let $d_L(d_R)$ denote the distance between the closest pair in S_L (S_R). Let $d = \min(d_L, d_R)$; Find a stripe of $+d/-d$ from the mid point and search the minimum distance within the stripe; return the minimum

Illustration

Step 1: sort by the x and y coordinate

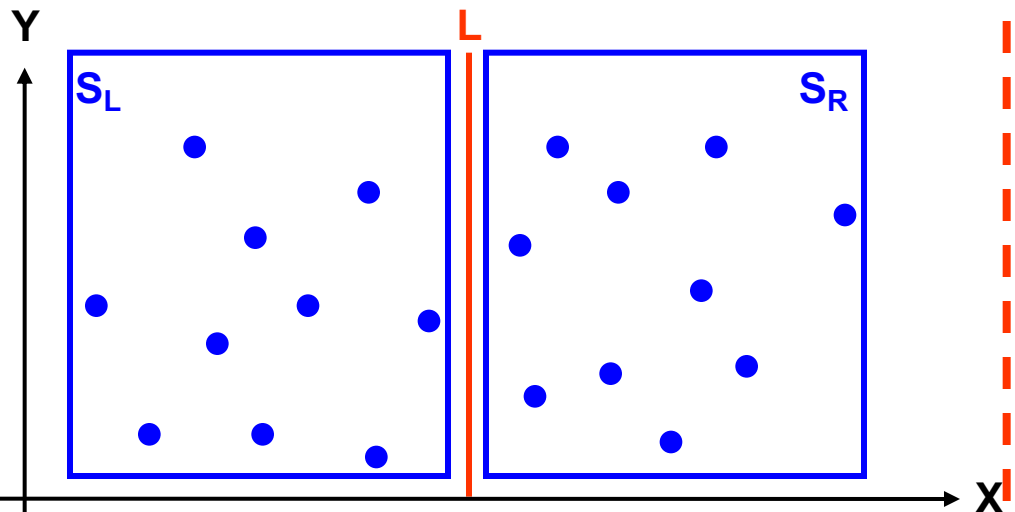
Step 2

If only one point



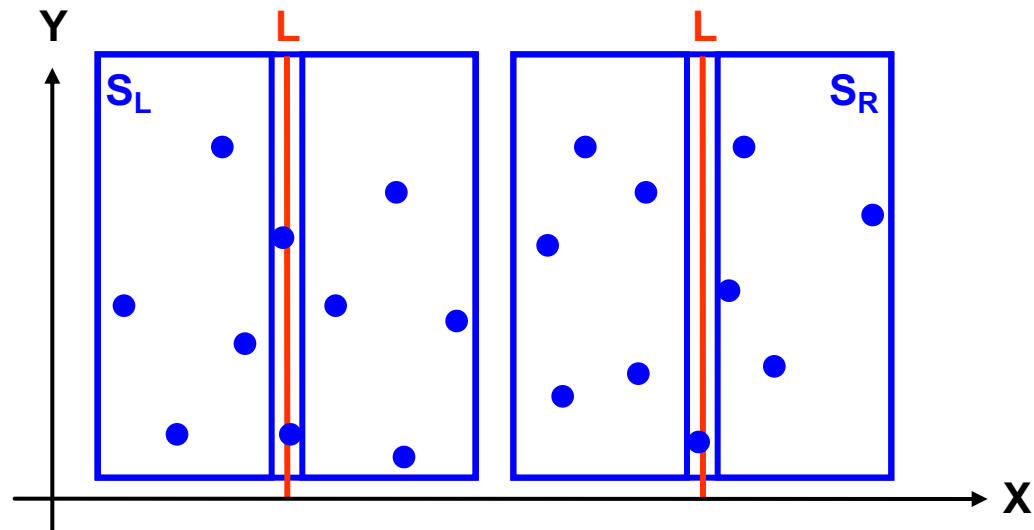
Step 3

Divide by the mid-x point



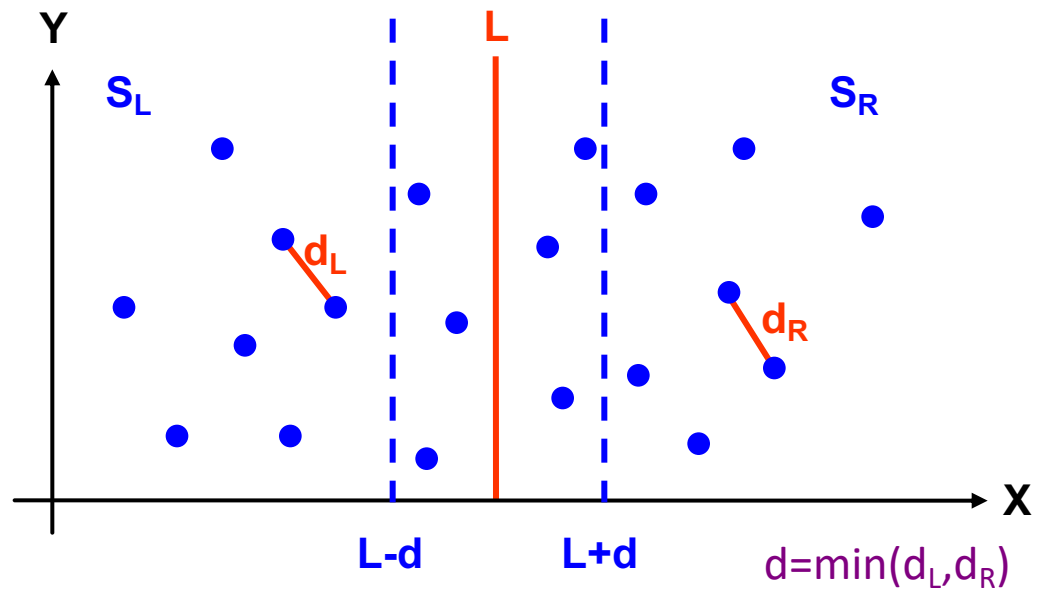
Illustration

Step 4



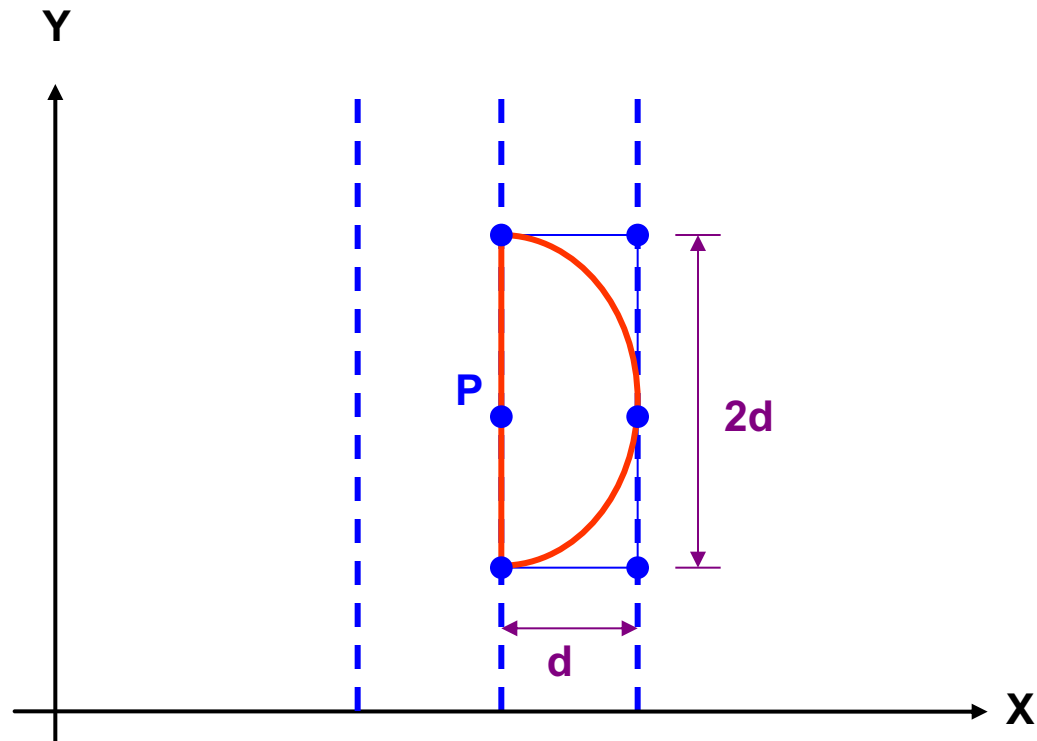
Illustration

Step 5



Illustration

- ❑ You will not search too many points in the strip



Maximum Subarray Sum Problem

- ❑ Given a sequence of integer number, find the largest sum of contiguous array numbers

-2	-3	4	-1	-2	1	5	-3
0	1	2	3	4	5	6	7

$$4 + (-1) + (-2) + 1 + 5 = 7$$

Maximum Contiguous Array Sum is 7

Brute Force?

- ❑ Run two loops

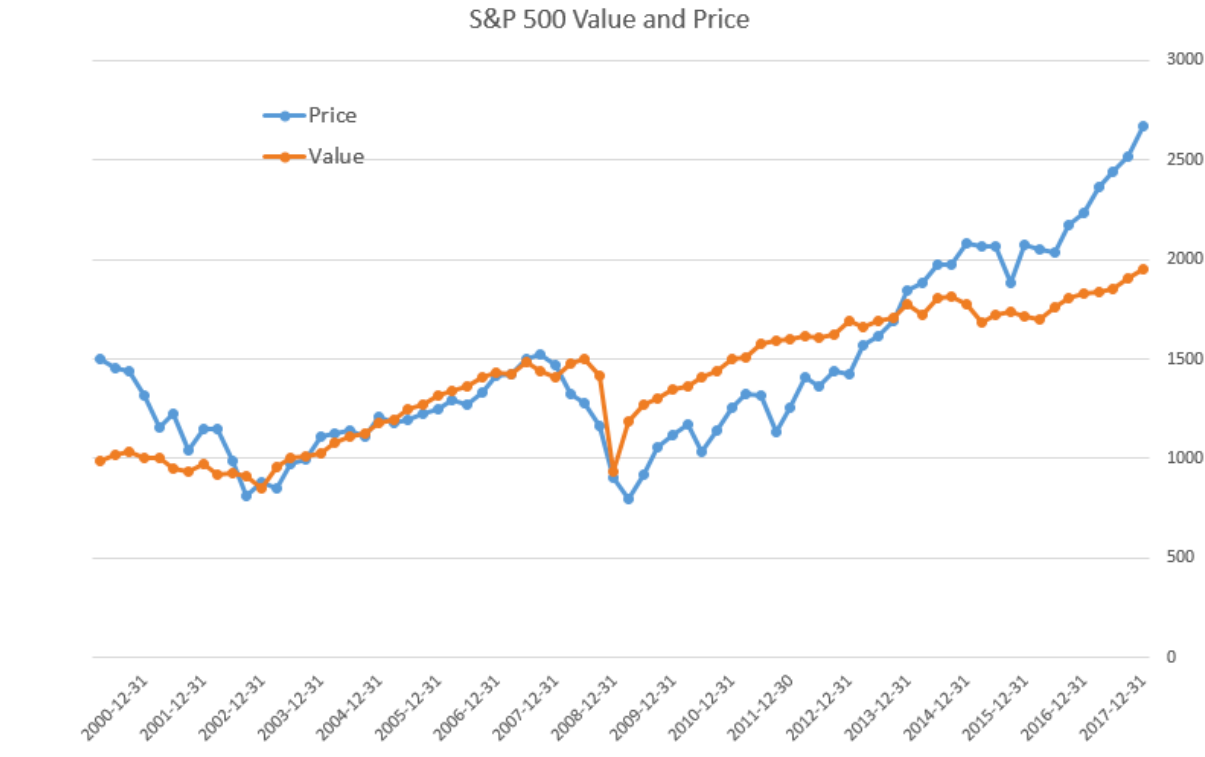
```
int brute_force(const std::vector<int>& D, int beg, int end) {  
    int max = std::numeric_limits<int>::min();  
    for (int i = beg; i < end; ++i) {  
        int sum = 0;  
        for (int j = i; j < end; ++j) {  
            sum += D[j];  
            max = std::max(sum, max);  
        }  
    }  
    return max;  
}
```


Divide and Conquer

- Step 1:** If the array has fewer than 3 elements, go brute force
- Step 2:** Partition the array into two halves of equal size. Recursively find the maximum subarray sum of S_L and S_R .
- Step 3:** Merge two sums from S_L and S_R . Find the maximum subarray sum across the mid point. Return the overall minimum

Practical Application I

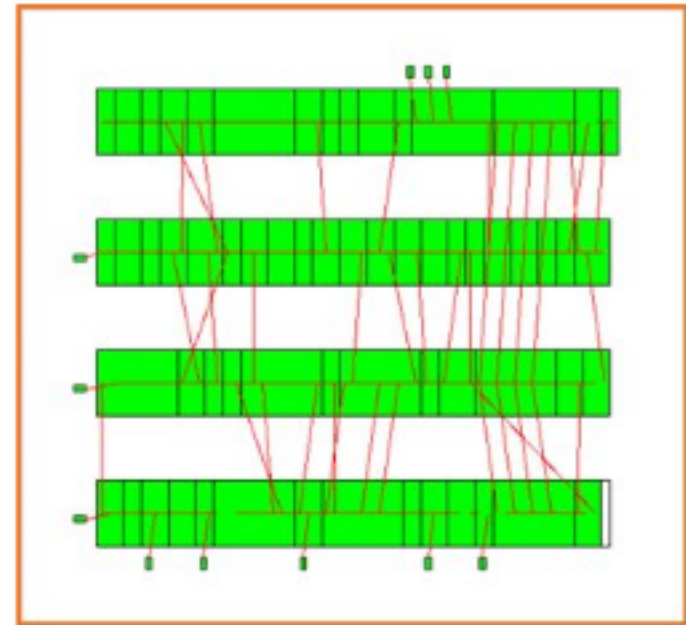
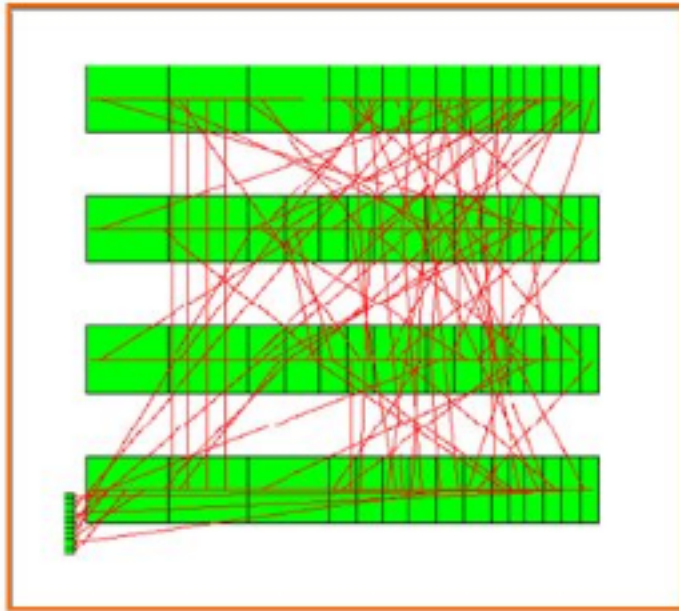
□ A basic routine of financial computing



Maximum subarray sum to find the optimal long-term investment

Practical Application II

❑ Row-based VLSI detailed placement



Maximum/minimum subarray sum to find per-row wirelength

Sorting

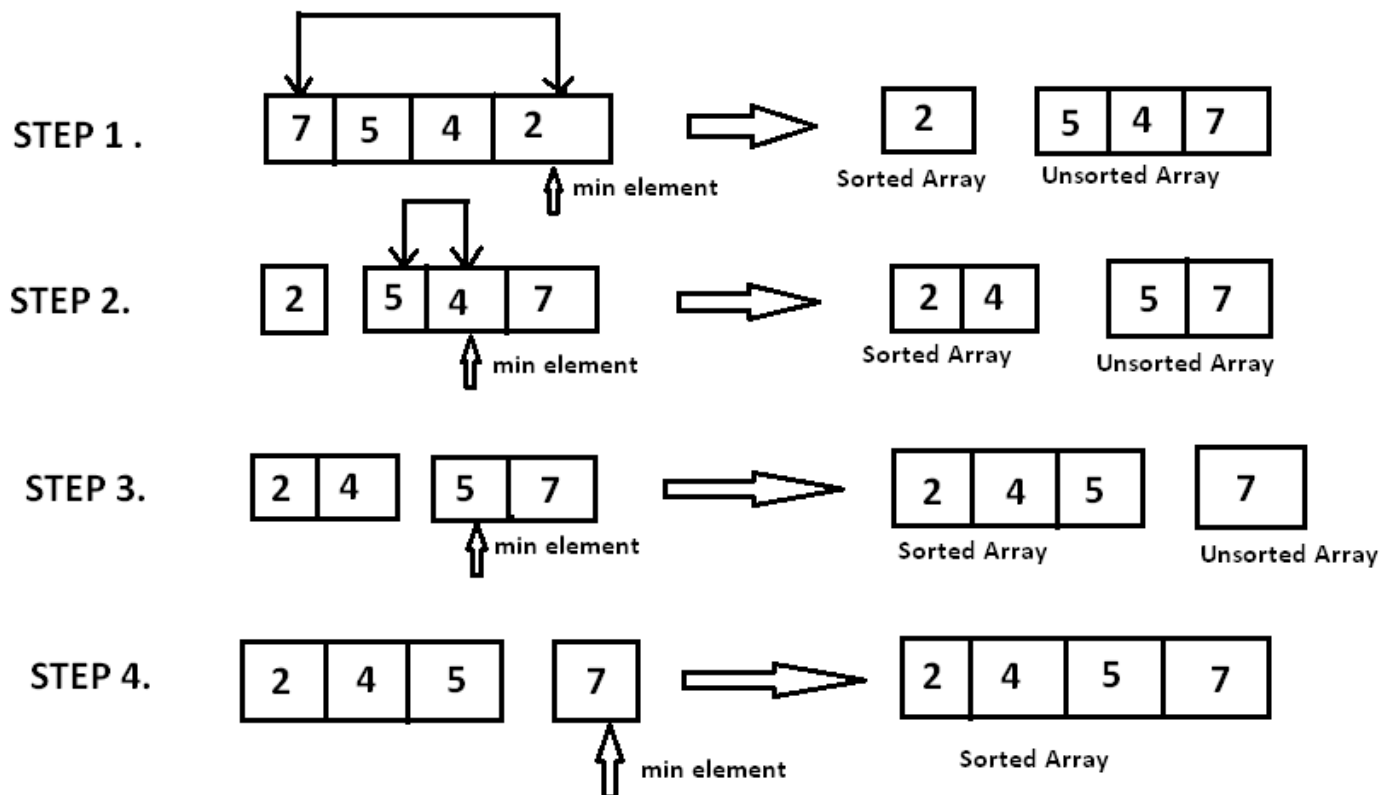
- ❑ **The most fundamental algorithm in all subjects ...**
- ❑ **Goal: puts elements in a certain order**
 - ❑ Increasing order: 1, 2, 5, 6, 8, 90, 123
 - ❑ Decreasing order: 123, 90, 8, 6, 5, 2, 1
- ❑ **Many algorithm paradigms**
 - ❑ Bubble sort
 - ❑ Selection sort
 - ❑ Merge sort
 - ❑ Qsort
 - ❑ ...
- ❑ **Today, new sorting algorithms are being invented**

Selection Sort

❑ Two loops

❑ Outer loop to repeat $n-1$ times

❑ Inner loop to find the minimum element



Selection Sort Implementation

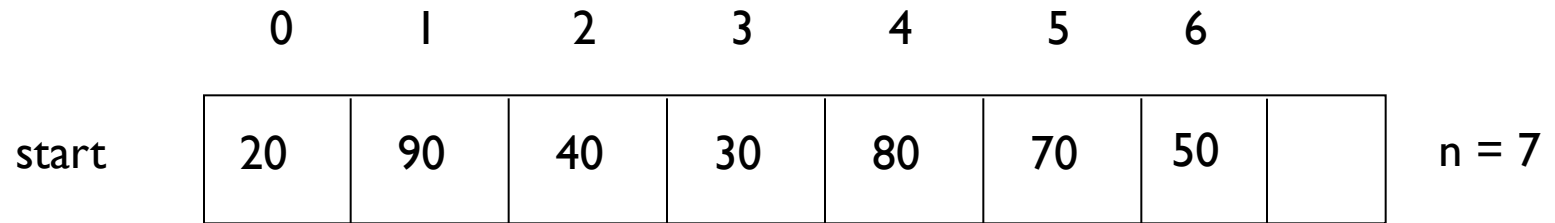
```
void brute_force(std::vector<int>& D, int beg, int end) {
    int max = std::numeric_limits<int>::min();
    for (int i = beg; i < end; ++i) {
        int min_v = D[i];
        int min_j = i;
        for (int j = i+1; j < end; ++j) {
            if(D[j] < min_v) {
                min_v = D[j];
                min_j = j;
            }
        }
        std::swap(D[i], D[min_j]);
    }
}
```

Time complexity $O(N^2)$

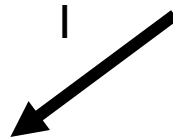
Using Divide and Conquer: Merge Sort

- ❑ **Divide**: If S has at least two elements (nothing needs to be done if S has zero or one elements), remove all the elements from S and put them into two sequences, S_1 and S_2 , each containing about half of the elements of S . (i.e. S_1 contains the first $\lceil n/2 \rceil$ elements and S_2 contains the remaining $\lfloor n/2 \rfloor$ elements).
- ❑ **Recurse**: Recursively sort sequences S_1 and S_2 .
- ❑ **Conquer**: Put back the elements into S by merging the sorted sequences S_1 and S_2 into a unique sorted sequence.

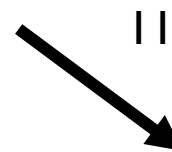
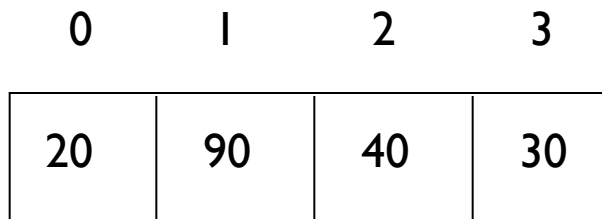
Illustration



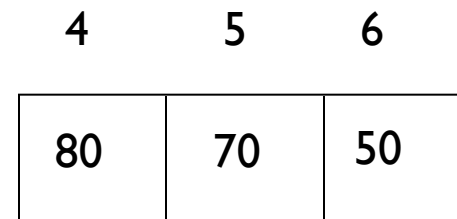
mergesort(a, 0, 6)



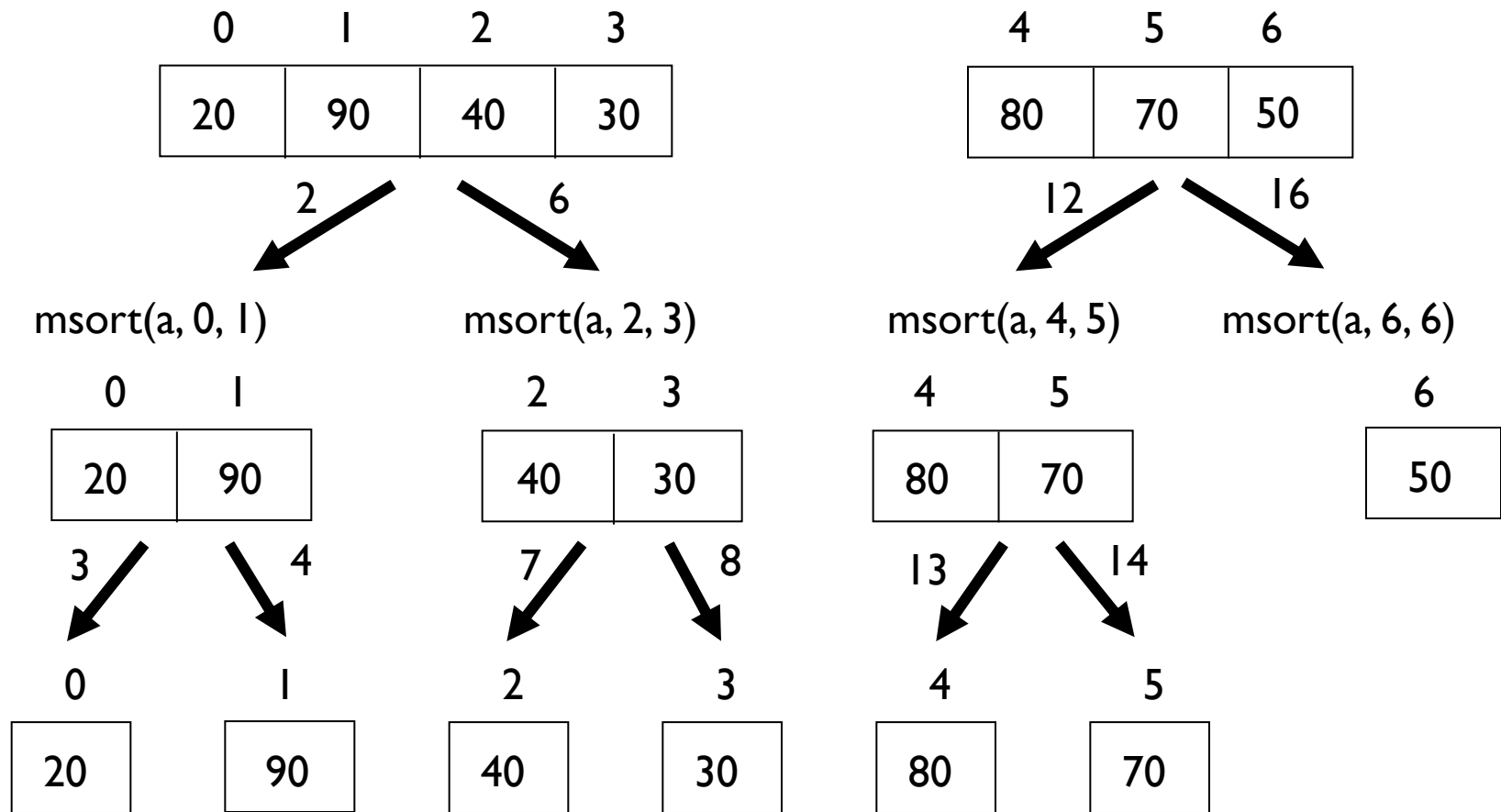
mergesort(a, 0, 3)



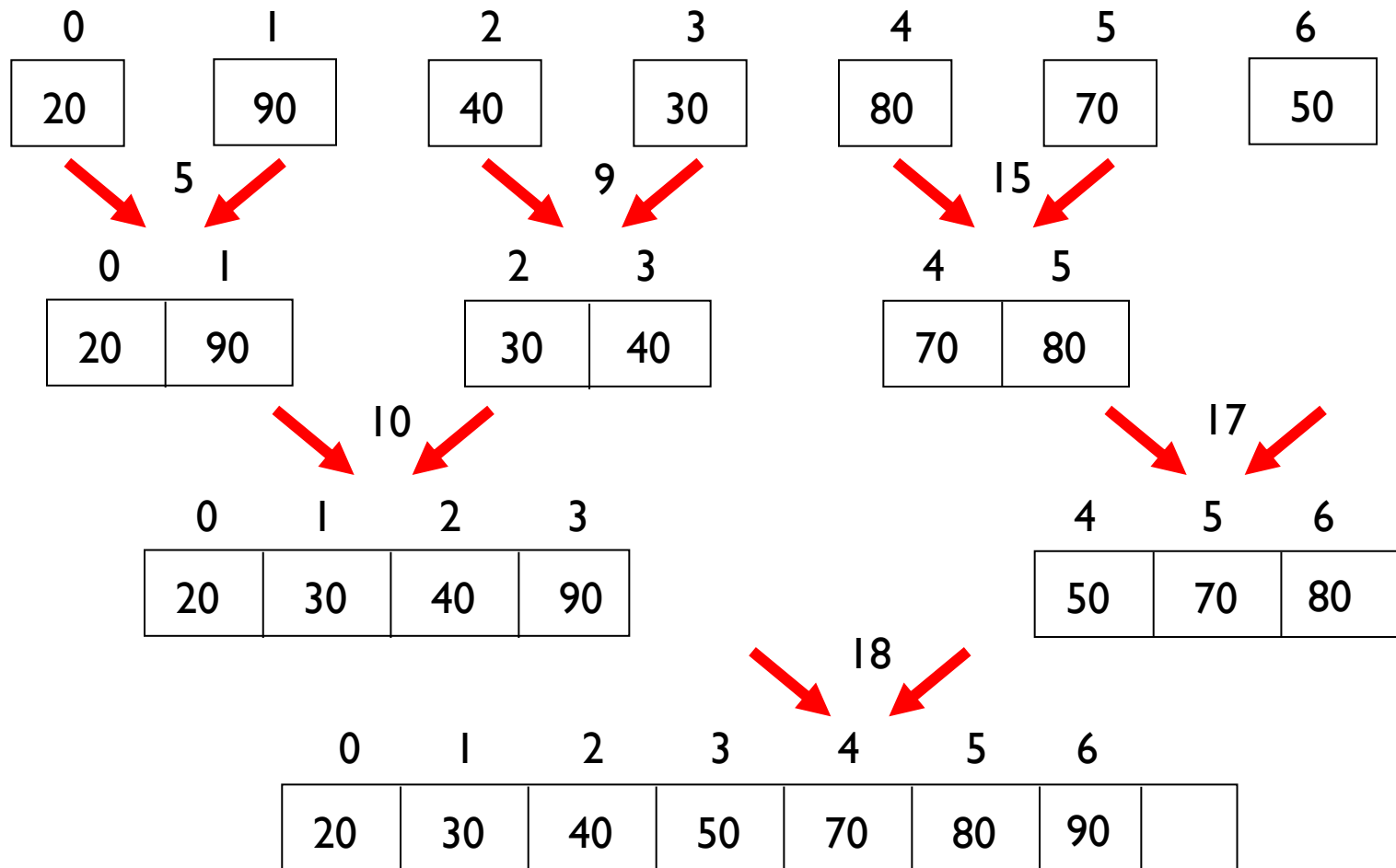
mergesort(a, 4, 6)



Illustration



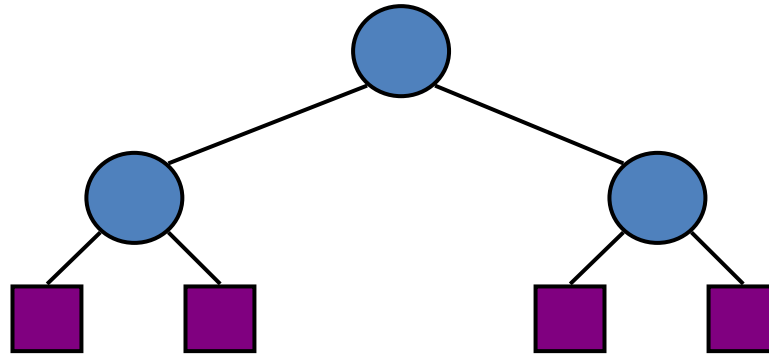
Illustration



Merge Sort Complexity

❑ Run Time Analysis

- ❑ At each level in the binary tree created for Merge Sort, there are n elements, with $O(1)$ time spent at each element
- ❑ $O(n)$ running time for processing one level
- ❑ The height of the tree is $O(\log n)$



- ❑ Therefore, the time complexity is **$O(n \log n)$**

Summary

- ❑ **2D closest pair of points finding**
 - ❑ Commonly used in computational geometry
- ❑ **Maximum subarray sum**
 - ❑ Commonly used in financial computing and VLSI designs
- ❑ **Sorting**
 - ❑ Insertion sort (kinda brute force: $O(N^2)$)
 - ❑ Merge sort (divide and conquer: $O(n \log n)$)

Note

- ❑ **To compile a “test.cpp” program to a binary “test”**
 - ❑ `g++ test.cpp -O2 -o test`
- ❑ **To feed a program with a test file from the standard output:**
 - ❑ `./simple < test.txt`
- ❑ **To measure the runtime of the above program:**
 - ❑ `time -p ./simple < test.txt`