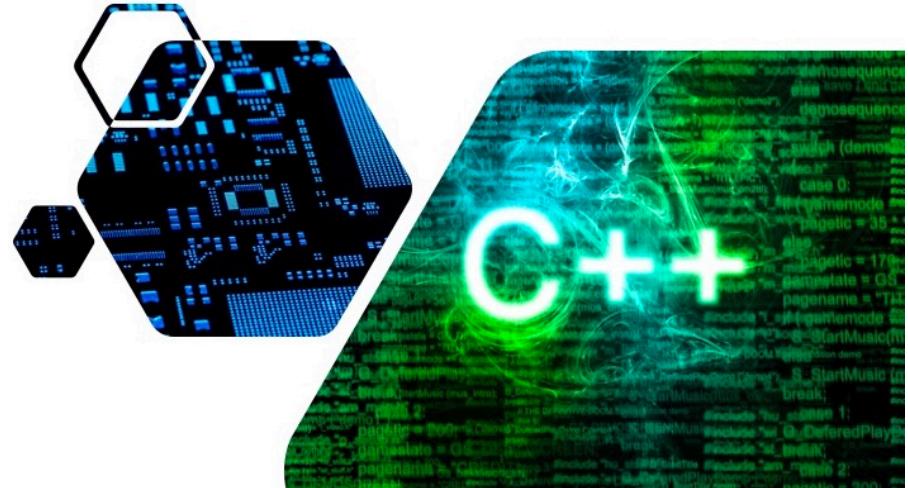


Lecture 2: Divide And Conquer (D&C) Algorithms

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University of Utah, Salt Lake City, UT



***For those who didn't
attend the course last
time ...***



***The course teaches you how to write “good”
programs with a specific focus on solving
computer design problems. You will gain
“hands-on” experience in writing C++/Python
code for implementing important data
structures and algorithms ...***

Design Automation is Driving Chip Evolution



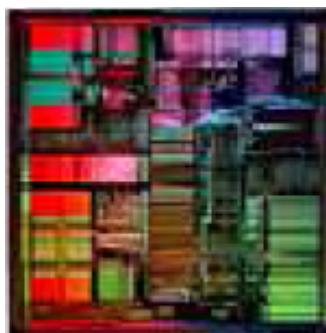
1982 – Intel 80286
134K transistors
12MHz; 68.7 mm²



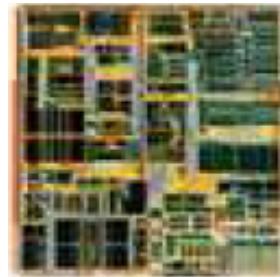
1985 – Intel 80386
275K transistors
33MHz; 104 mm²



1989 – Intel 80486
1.2M transistors
50MHz; 163 mm²



1993 – Intel Pentium
3.1M transistors
66MHz; 264 mm²



1997 – Intel Pentium II
7.5M transistors
300MHz; 209 mm²



1999 – Intel Pentium III
28M transistors
733MHz; 140 mm²



2000 – Intel Pentium4
42M transistors
1.5MHz; 224 mm²

~~Advanced~~ Applied Programming for Computer Design Problems

More information can be found in lecture 1

Some Questions about the Course

- ❑ How can I find more materials about C++ learning?
 - ❑ Cpp-now: <https://www.youtube.com/user/BoostCon>
 - ❑ Cpp-conf: <https://www.youtube.com/user/CppCon>
 - ❑ Cpp-reference: <https://en.cppreference.com/w/>
- ❑ How to know my code is good?
 - ❑ Ask experienced coder to read your code
 - ❑ Dive into the assembly: <https://godbolt.org/>
- ❑ What hardware knowledge do I need?
- ❑ How does this course help me find a job in AI?

Reflect on Big Mod Problem

❑ Naïve method

❑ $2^{16} = 2 * 2 * 2 * 2 * 2 * 2 * 2 * 2 * 2 * 2 * 2 * 2 * 2 * 2 * 2 * 2$ total 15 calculation

❑ Can we do better?

❑ $2^{16} = (2^8)^2$ total 1 calculation

❑ $2^8 = (2^4)^2$ total 1 calculation

❑ $2^4 = (2^2)^2$ total 1 calculation

❑ $2^2 = (2^1)^2$ total 1 calculation

❑ $2^1 = (2^0)^2$ total 1 calculation

Refined Solution

```
#include <iostream>
using namespace std;                                DO NOT globalize the namespace!!!

#define SQUARE(x) (x*x)
int bigmod(int a, int b, int c)
{
    if(b==0) return 1;

    else if(b%2==0)
        return SQUARE(bigmod(a,b/2,c)%c);

    else return ((a%c)*bigmod(a,b-1,c))%c;
}

int main()
{
    int a,b,c;

    while(std::cin >> a >> b >> c) std::cout<<bigmod(a,b,c)<<endl;
    return 0;
}
```

In fact, there is a name for the refined method:

Divide and Conquer algorithm

*(used to solve >50% computer design problems,
including Google's distributed system solutions,
e.g., MapReduce)*

An Iterative Version

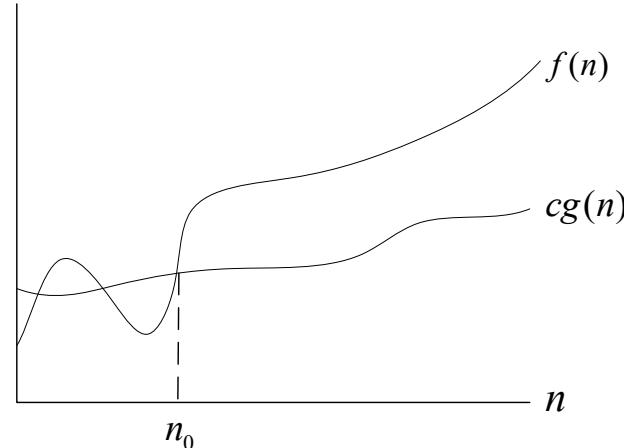
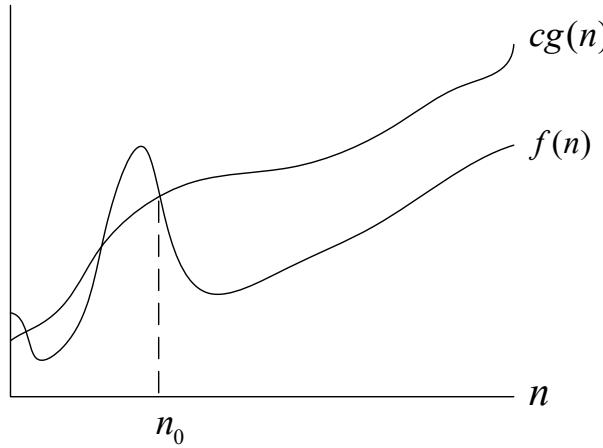
- All recursive problems can be rewritten iteratively

```
int64_t bigmod(int64_t a, int64_t b, int64_t c) {  
    int64_t result = 1;  
    while(b > 0) {  
        if(b & 1) {  
            result = (result * a) % c;  
        }  
        b = b >> 1;  
        a = a*a%c;  
    }  
    return result;  
}
```

See: <https://godbolt.org/z/RVxZRN>

Get a Sense of Runtime Performance

- Time complexity analysis
 - Runtime plays the most important role in performance
 - In algorithm theory, we use big O worst case analysis
 - Upper bound of the runtime with respect to input size N



In this course, we will use TW's empirical analysis as with modern computer architectures

Empirical Analysis

□ Technical Analysis (Input Data Size = N)

□ O(N)

- `for(int i=1; i<=N; i++) some_constant_work();`

□ O(N²)

- `for(int i=1; i<=N; i++)
 for(int j=1; j<=N; j++)
 some_constant_time_work();`

□ O(N³), O(N⁴)...

□ On modern computers, input Data Size = N

□ Timing Constraint

- $O(N) = 1000000 \sim 8000000$ equals to Run Time < 1s
- Generally true on modern PCs

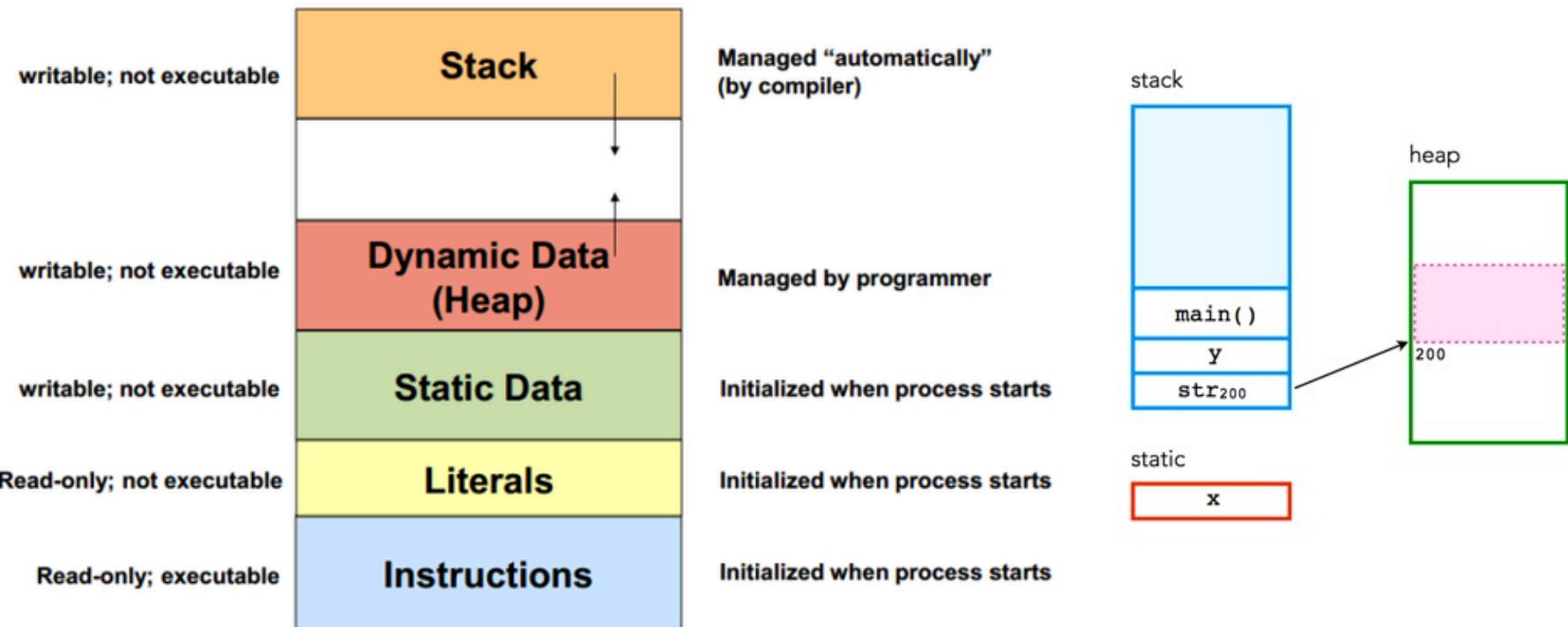
Empirical Analysis Examples

- A Problem with $N = 1000$, Time Limit = 1s**
 - Could a $O(N)$ algorithm pass the time limit constraint?
 - What about the $O(N \log N)$?
 - What about the $O(N^2)$?
 - What about the $O(N^2 \log N)$?
 - What about the $O(1)$ time ?

- A Problem with $N = 1000000$, Time Limit = 1s**
 - Could a $O(N)$ algorithm pass the time limit constraint?
 - What about the $O(\log N)$?
 - What about the $O(\log N \log N)$?
 - What about the $O(N^2)$?

What about Space Complexity?

- Same as the empirical runtime analysis
 - However, it depends on your RAM size
- Stack vs Heap



Before we talk about D&C ...

- Recursive program is the backbone of D&C
- Fibonacci number

1,1,2,3,5,8,13,21,34,55,89,144,233,377...

$$1+1=2$$

$$1+2=3$$

$$2+3=5$$

$$3+5=8$$

$$5+8=13$$

$$8+13=21$$

$$13+21=34$$

$$21+34=55$$

$$34+55=89$$

$$55+89=144$$

$$89+144=233$$

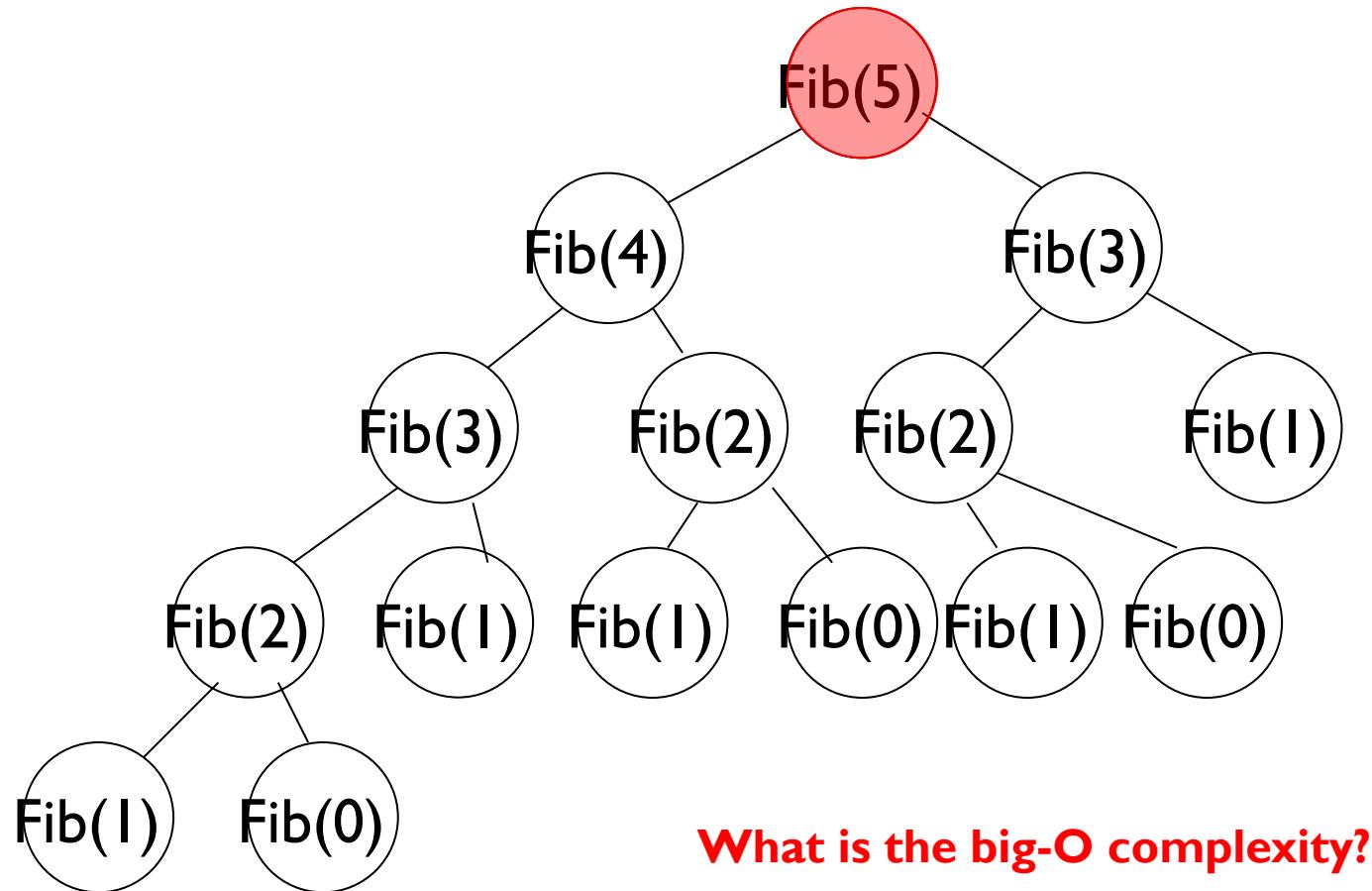
$$144+233=377$$

A Simple Recursive Solution

```
int fib_top_down(int n)
{
    if(n<=2) return 1;
    return fib_top_down(n-1)+fib_top_down(n-2);
}
```

What is the problem?

Duplicate Computations ...



What is the big-O complexity?

Tabular Method

❑ Problems

- ❑ Duplicate calculation
- ❑ $F(30)$ will blow up the runtime

❑ Solve by table Weapon

❑ Four Steps

- (1) Basic and Valid Condition
- (2) Is Found Condition
- (3) Recursive Part
- (4) Return Value Part

```
int fib_top_down(int n)
{
    if(n<=2) return 1;
    return fib_top_down(n-1)+fib_top_down(n-2);
}

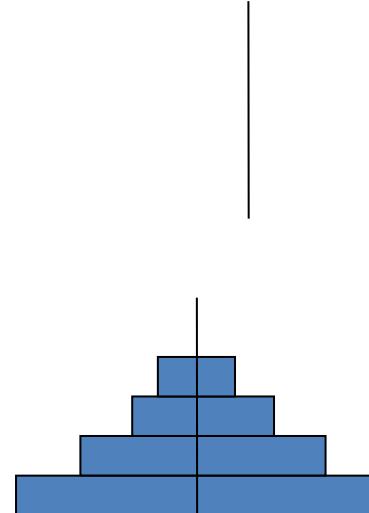
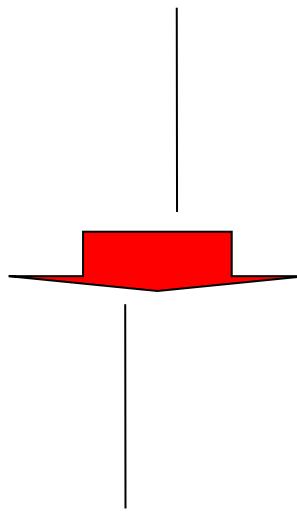
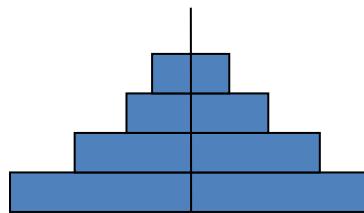
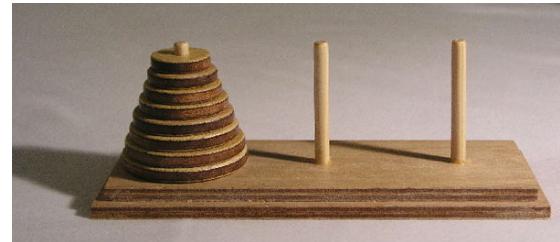
bool isfind[MAXN]; //all initialized to be false
int fib[MAXN]; //all initialized to be zero

int tabular(int n)
{
    if(n<=2) return 1;
    if(isfind[n]) return fib[n];
    fib[n] = tabular(n-1) + tabular(n-2);
    isfind[n] = true;
    return fib[n];
}
```

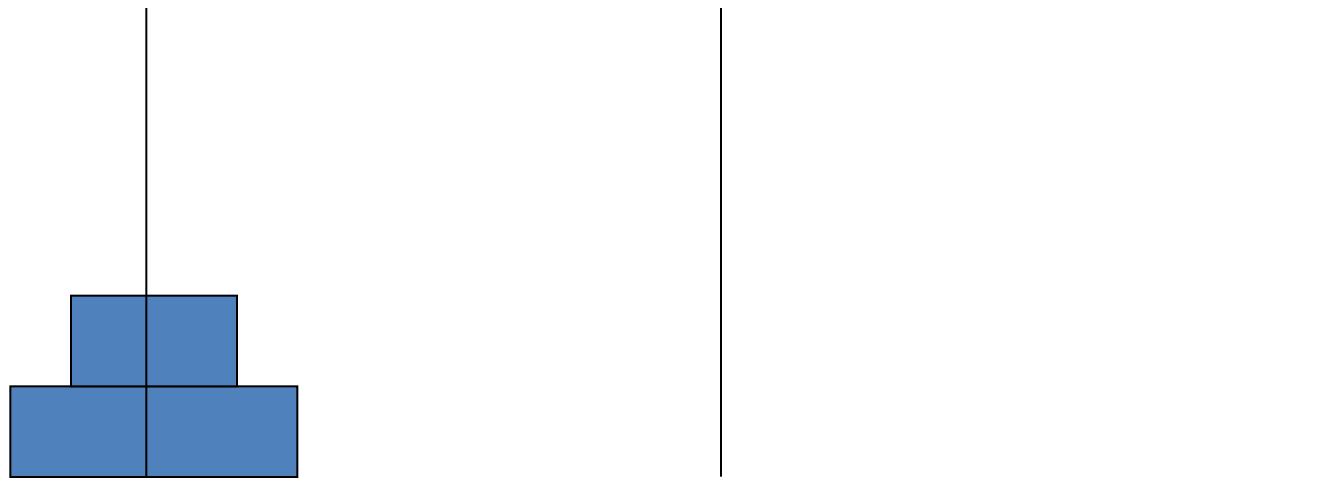


The Hanoi Problem

- Given three sticks, what's the number of steps required to move the tower of n blocks from the first peg to the last peg. You cannot put a large block on the small block

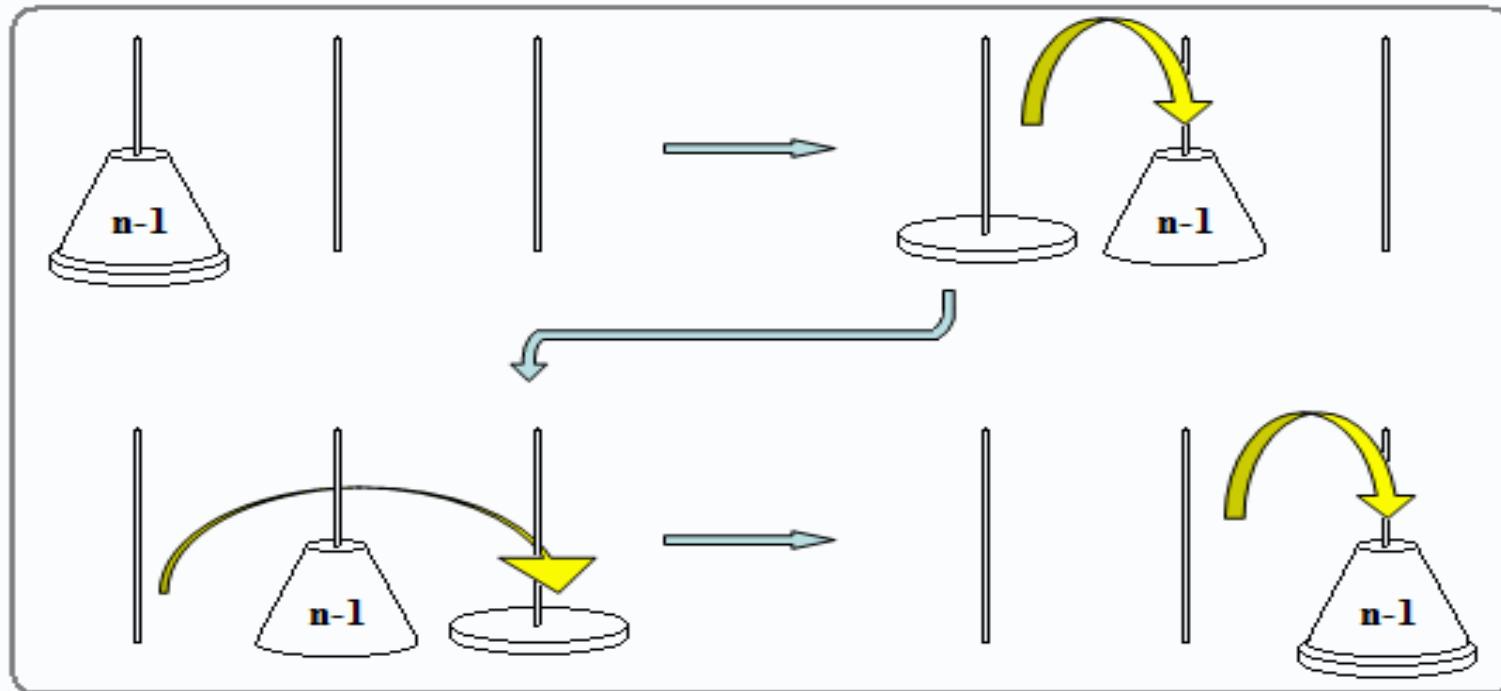


Example of Two Blocks



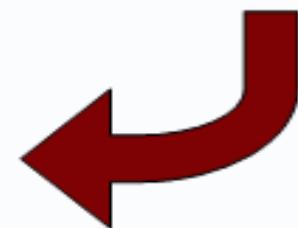
Example with a 2-block tower.

Recursion Formula



Tower of Hanoi
Counting the movements

$$\begin{aligned}f(n) &= f(n-1) + 1 + f(n-1) \\&= 2 * f(n-2) + 1\end{aligned}$$

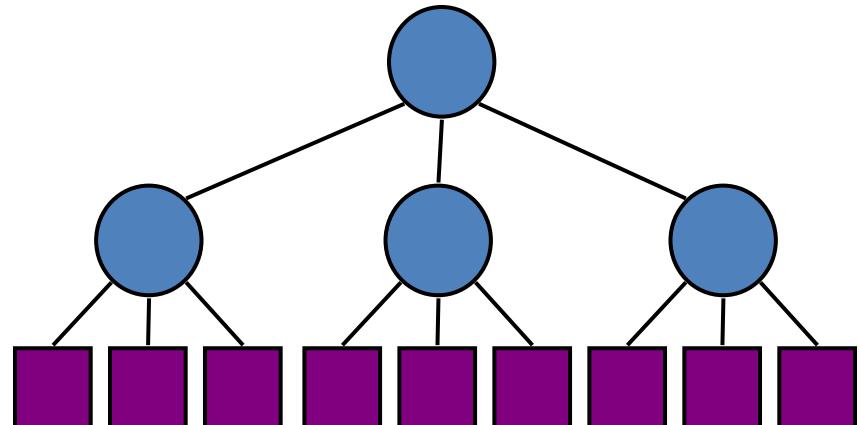
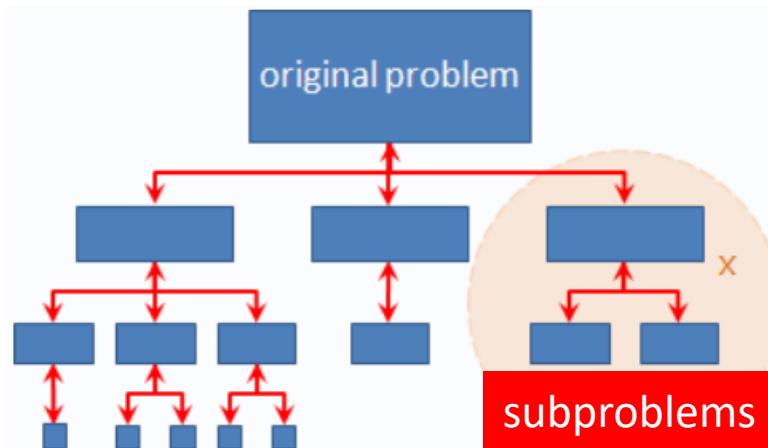


Divide and Conquer

❑ Divide & Conquer

- ❑ Divide: Divide the Original Problem Size into Small Problem Set
- ❑ Recursive: Solve the Problem Recursively
- ❑ Conquer: Combine these Problem Set

❑ Illustration



Time Complexity of Divide and Conquer

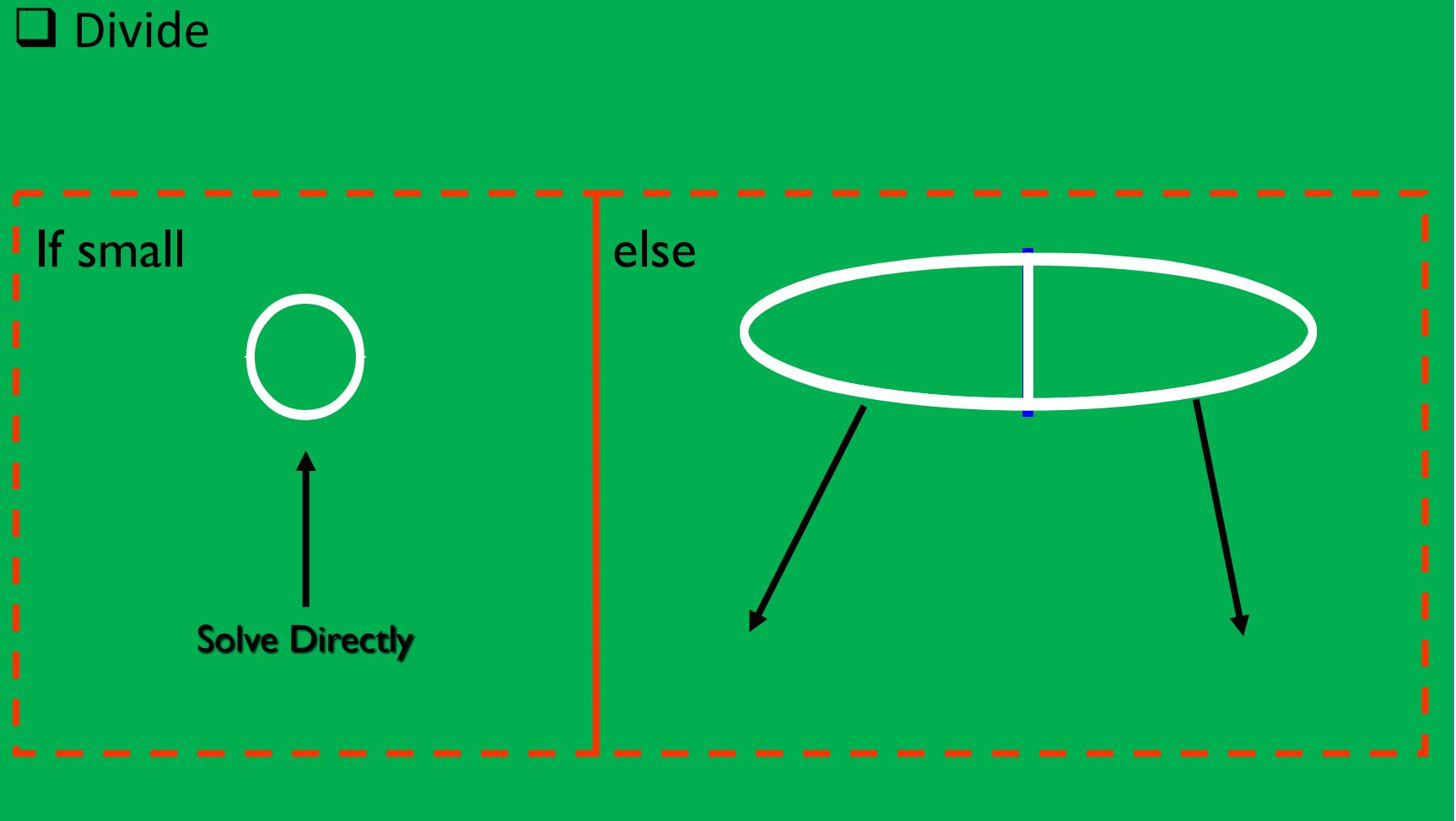
- Time Complexity Analysis of D&C

- Usually $N \log(N)$ time

$$T(n) = \begin{cases} k * T\left(\frac{n}{k}\right) + \text{time}(s) + \text{time}(m), & n > \text{given_size} \\ b, & n < \text{given_size} \end{cases}$$

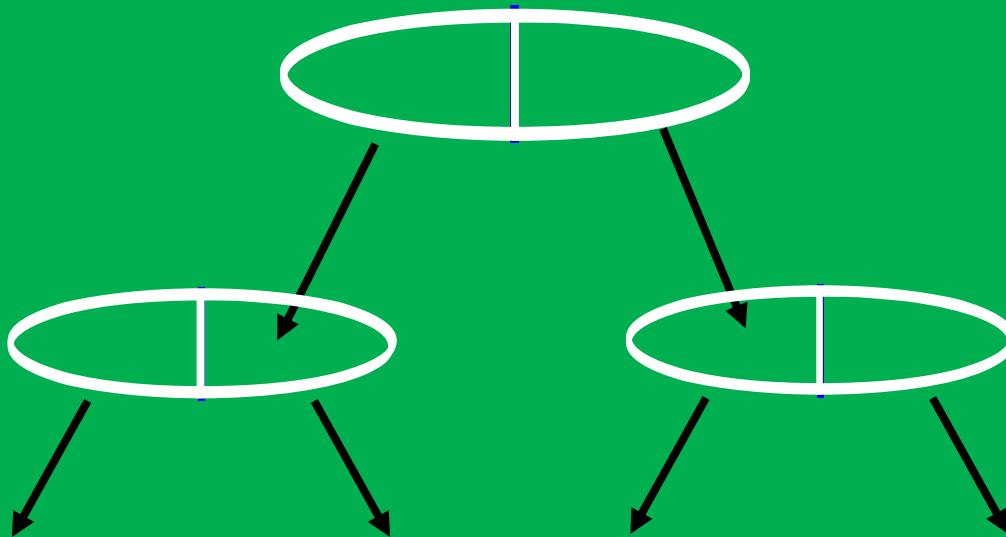
- k: the divided size
 - s: split
 - m: merge

Visualization of Divide and Conquer



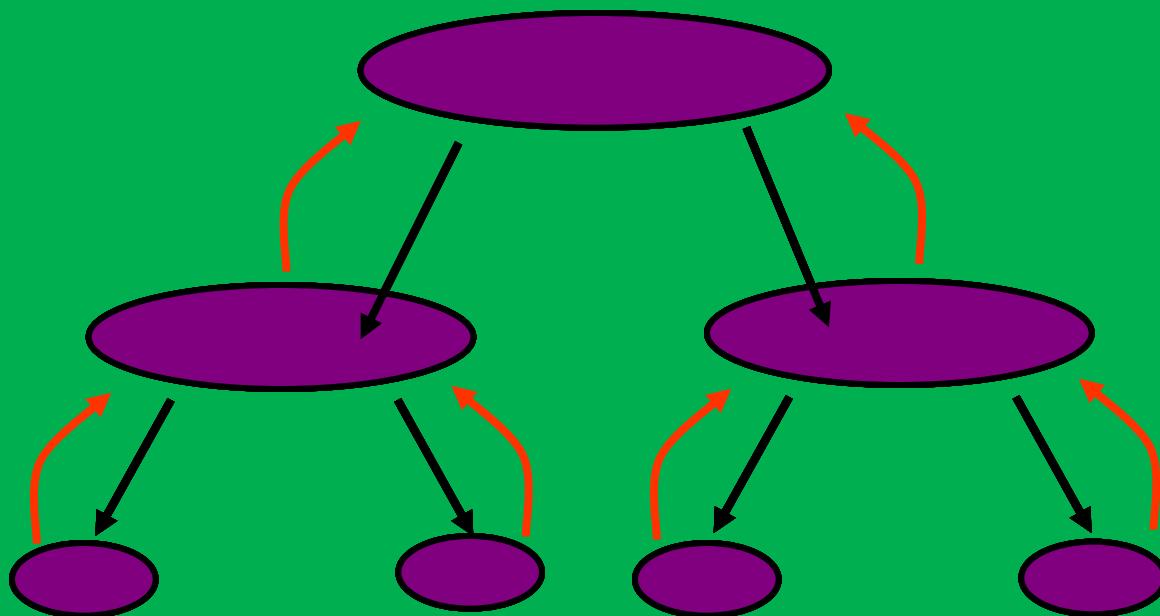
Visualization of Divide and Conquer

❑ Recursive



Visualization of Divide and Conquer

❑ Solve and Conquer

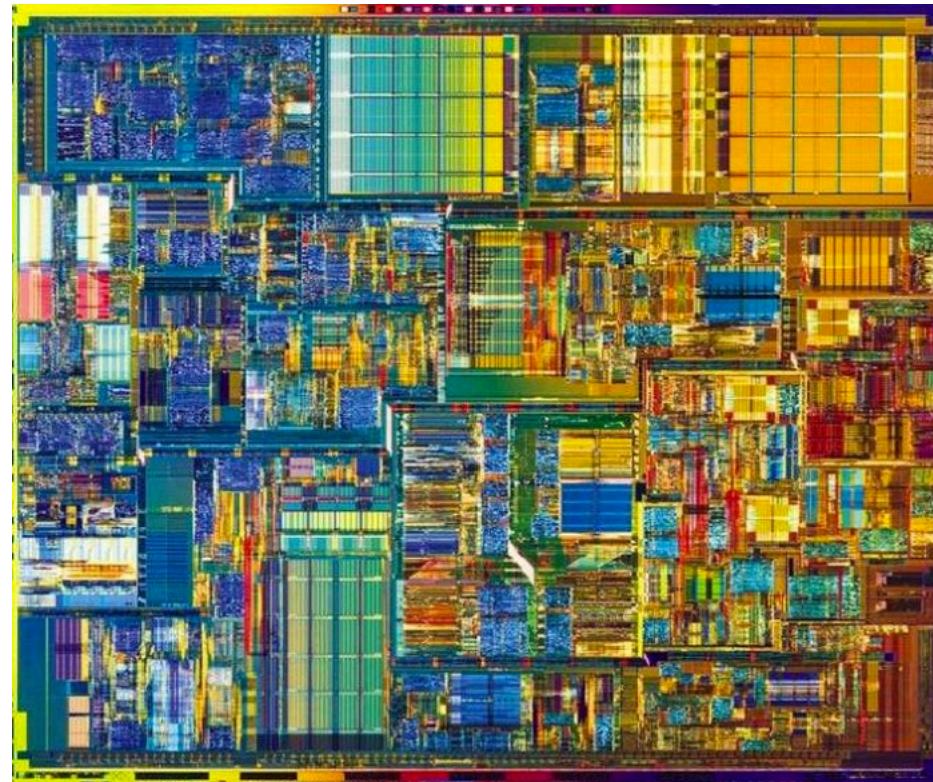


Divide and Conquer is Heavily used in CAD

- Modern circuits sizes are too large to handle in flat

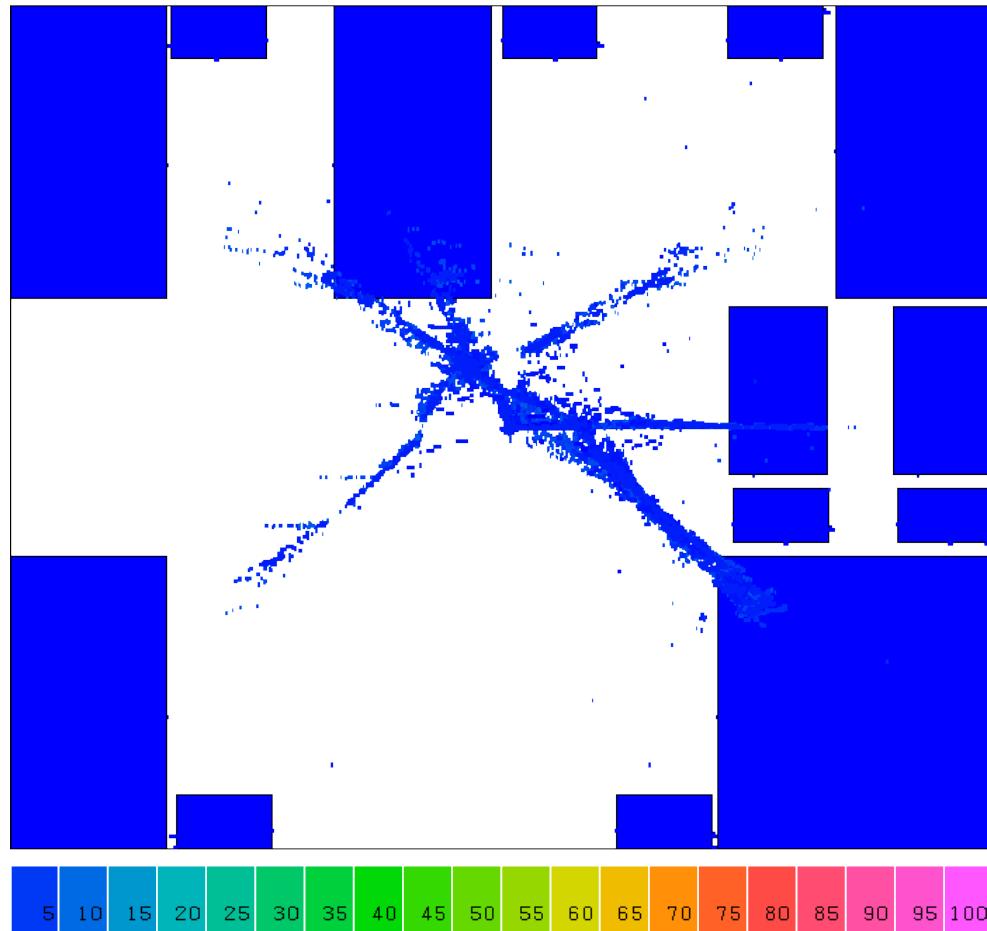


2000 – Intel Pentium4
42M transistors
1.5MHz; 224 mm²

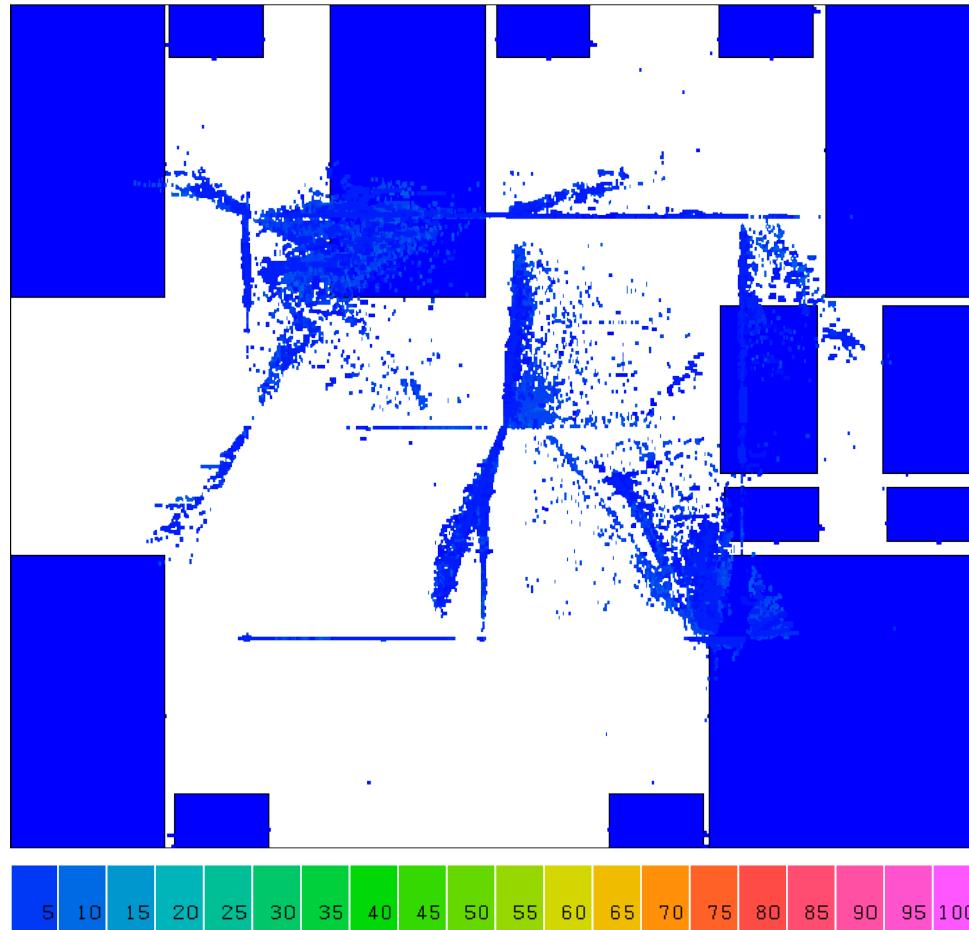


Directly solving the original problem takes forever to finish ...

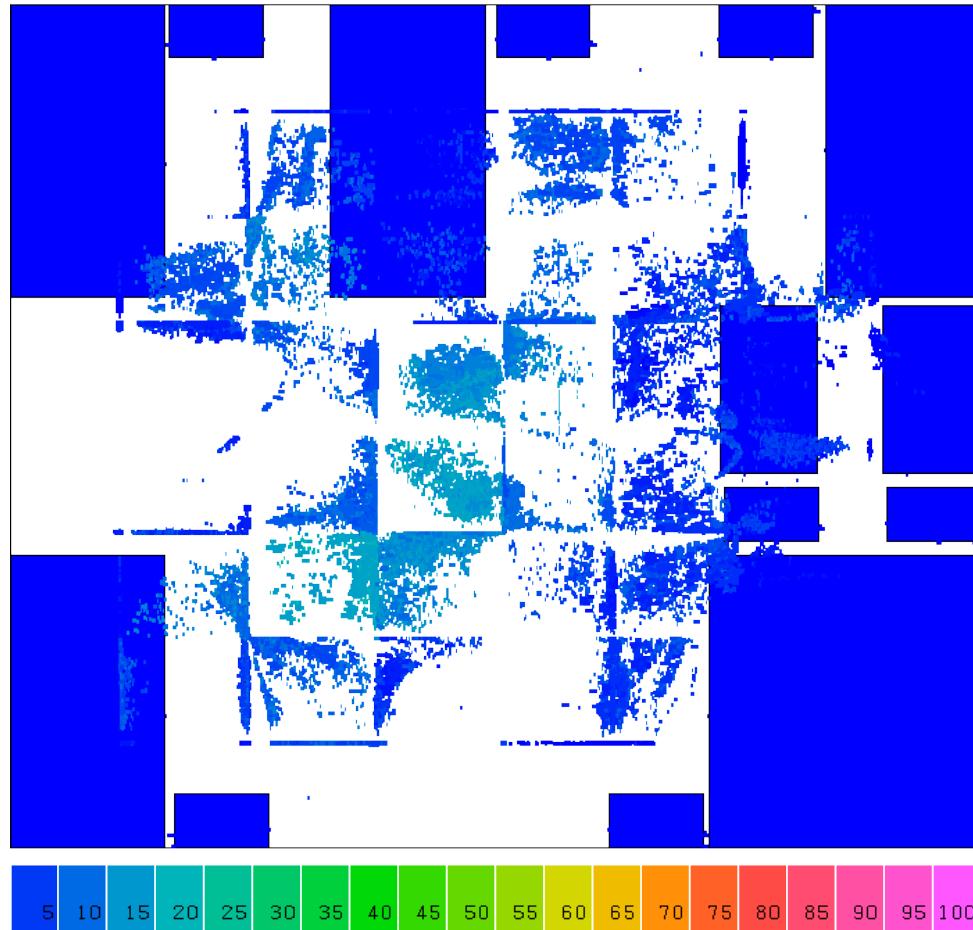
Example: Placement



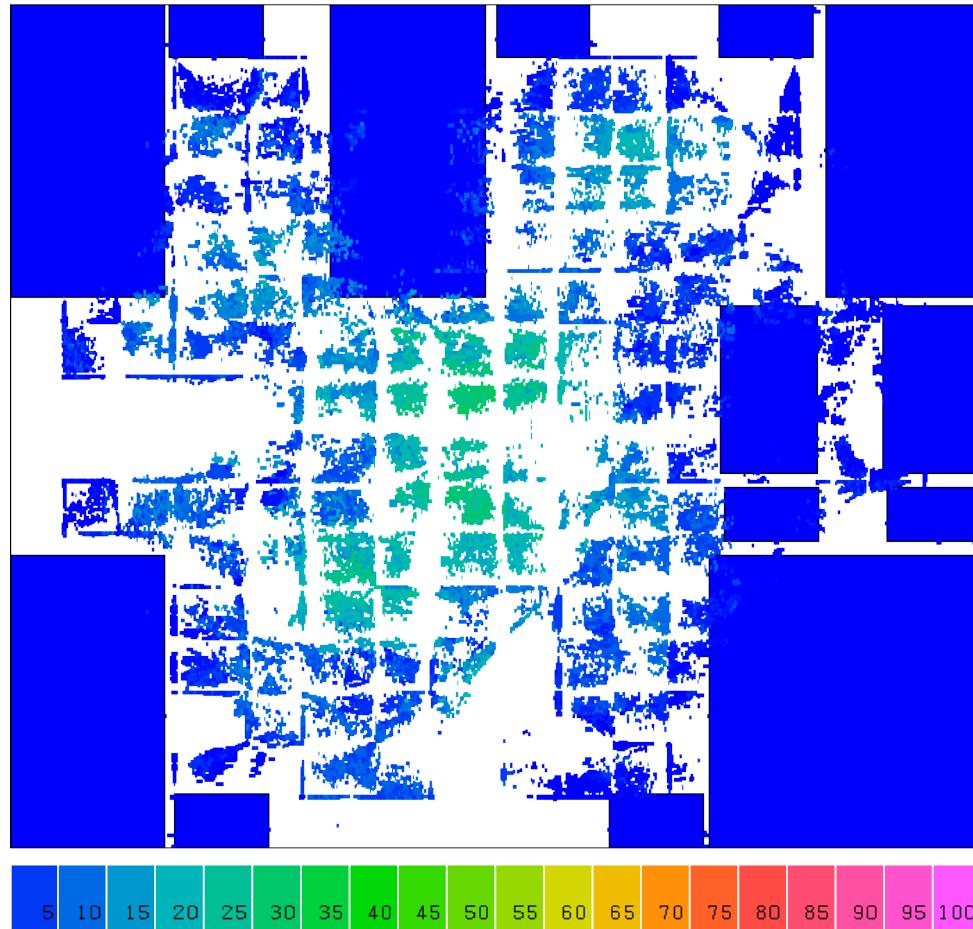
Example: Placement



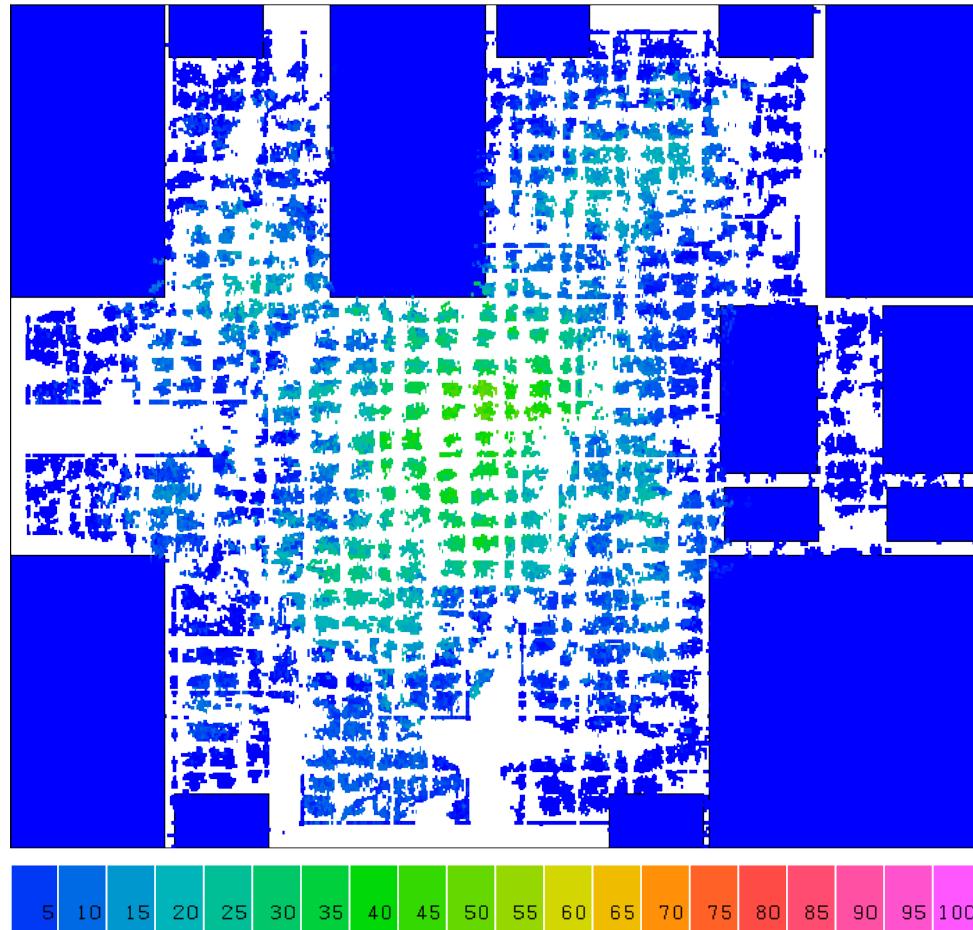
Example: Placement



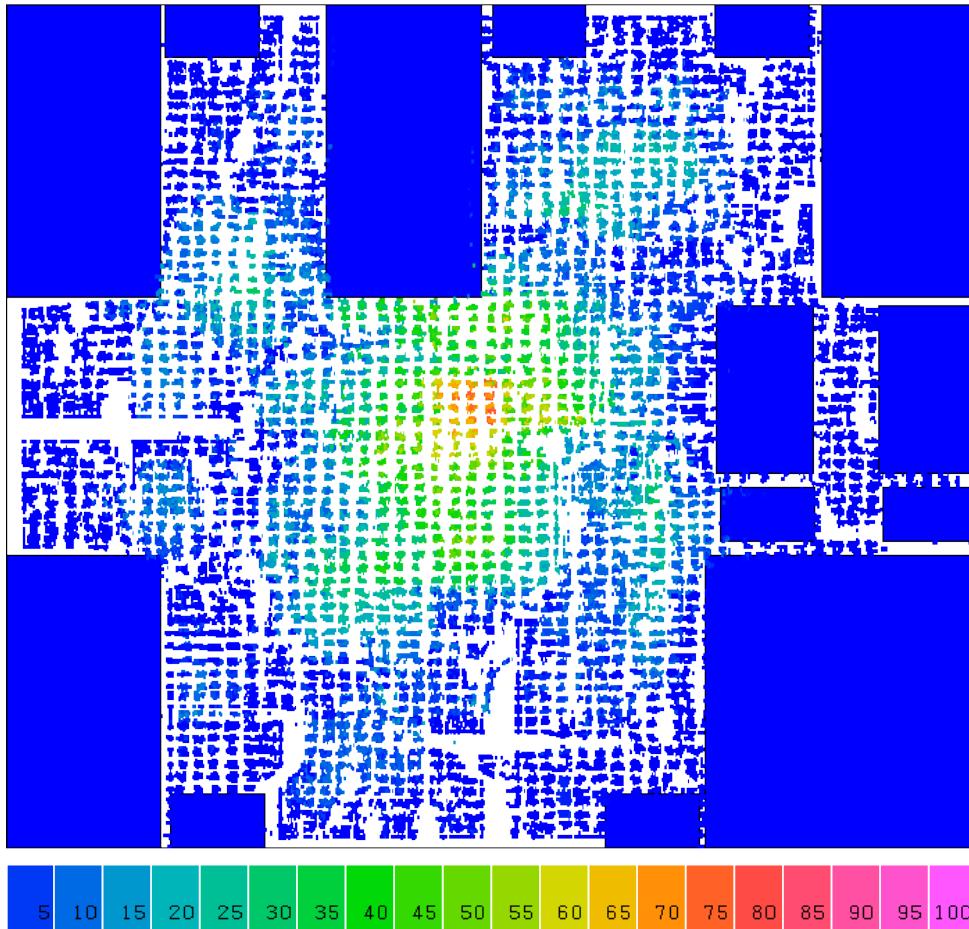
Example: Placement



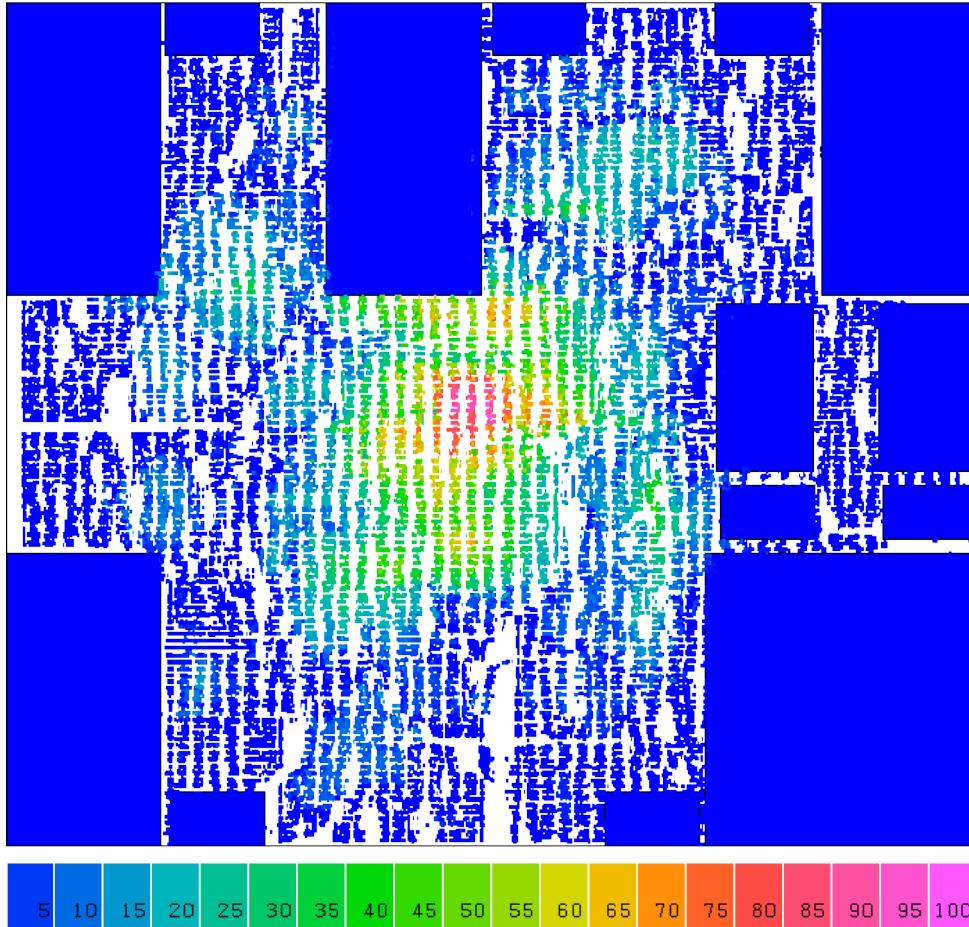
Example: Placement



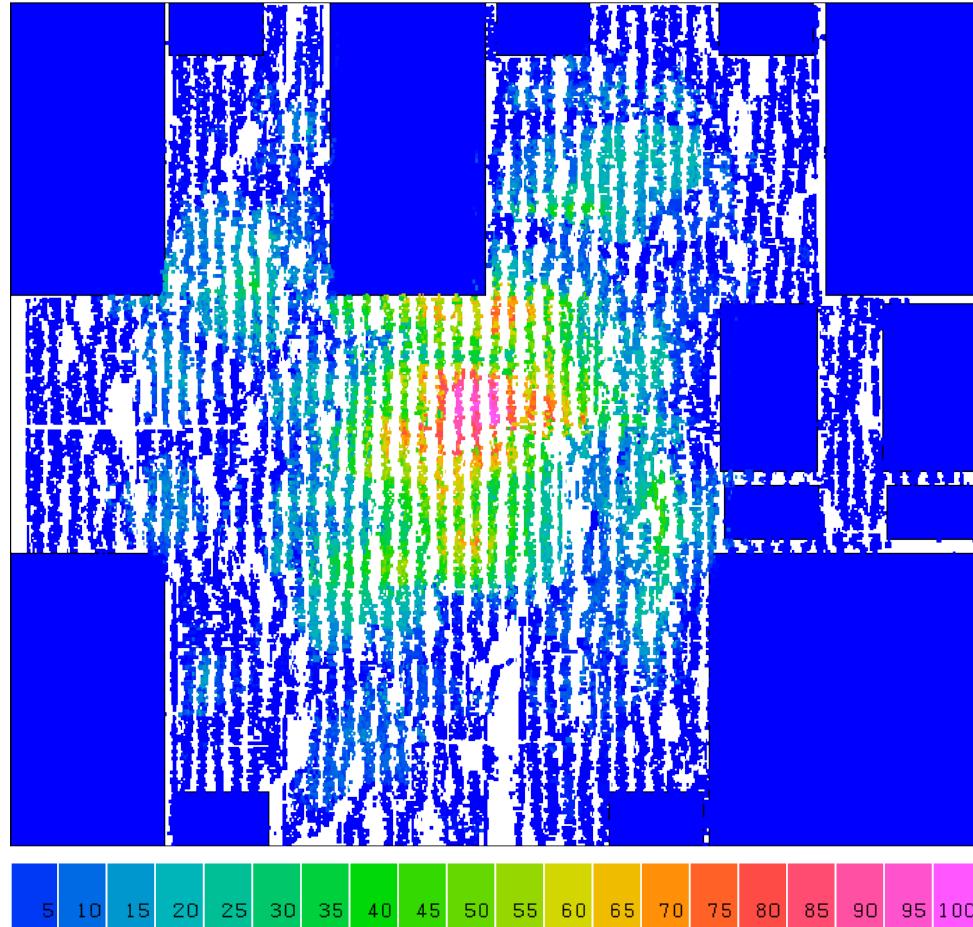
Example: Placement



Example: Placement

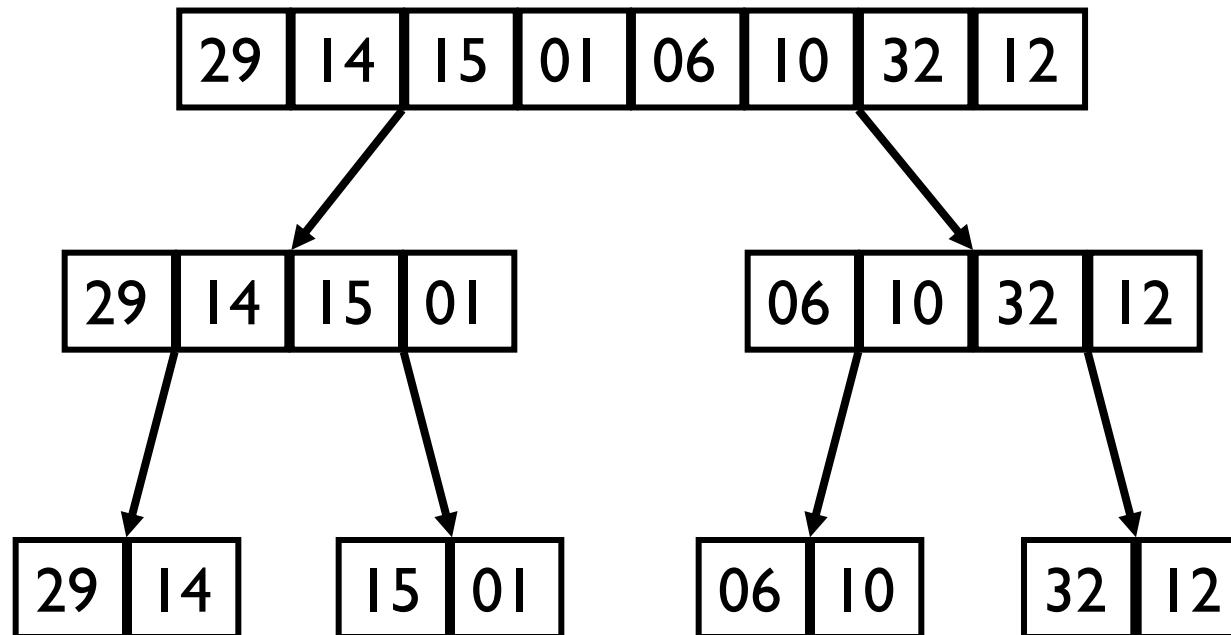


Example: Placement



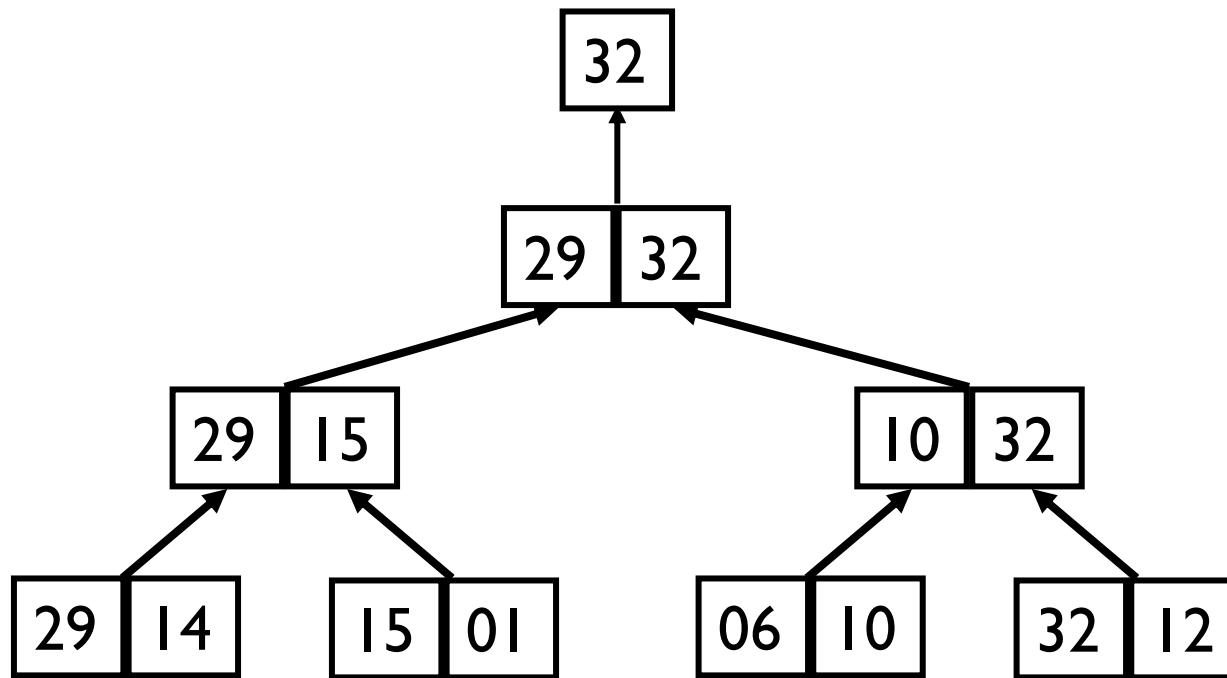
Example: Find the Minimum Value

□ Divide



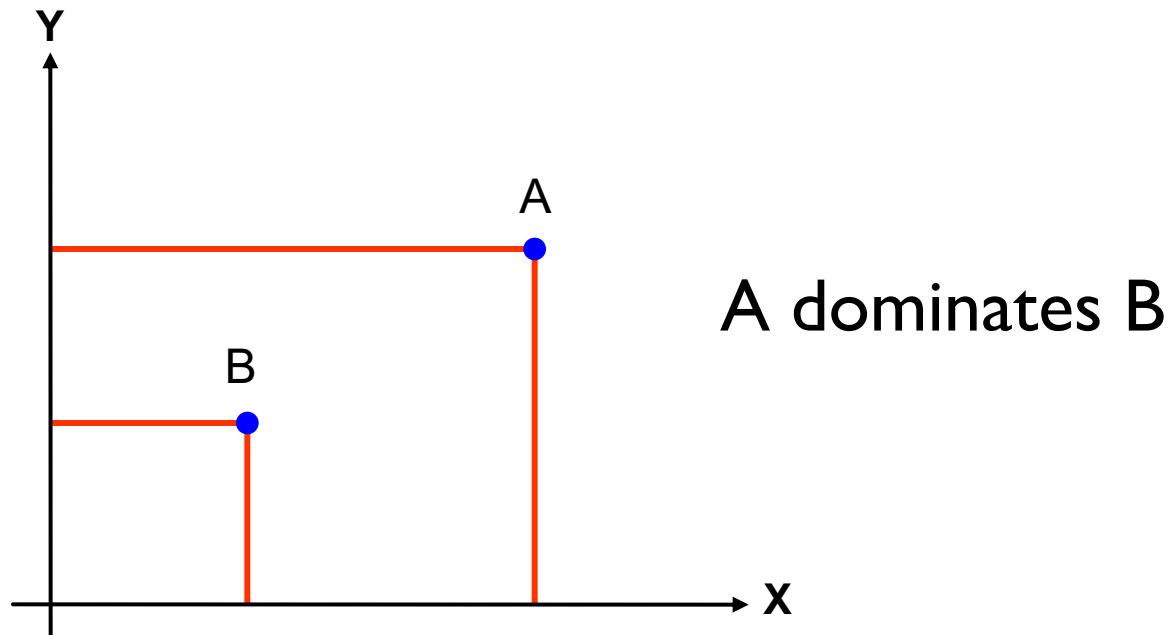
Example: Find the Minimum Value

□ Conquer



Example: Find the 2D Maxima Points

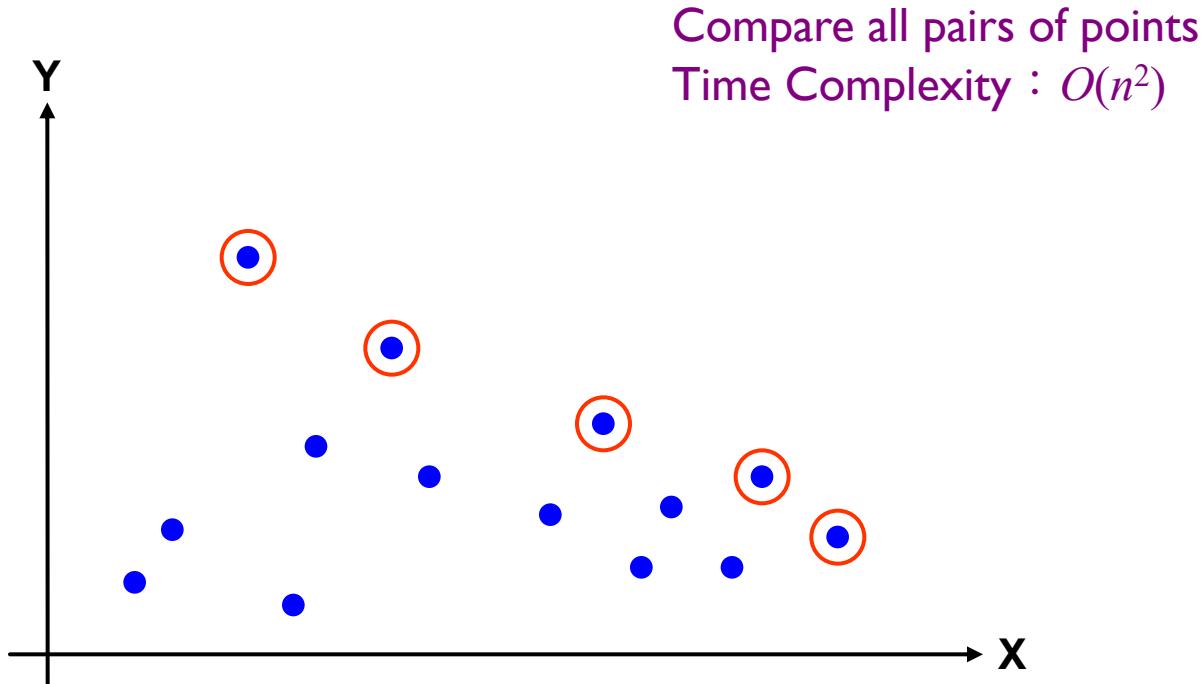
A point (x_1, y_1) dominates (x_2, y_2) if $x_1 > x_2$ and $y_1 > y_2$.



Example: Find the 2D Maximal Points

- Brute-force method

- Write a two-level for-loop to compare all pair of points



Solve the 2D Maximal Points Problem

Input: A set S of n planar points.

Output: The maximal points of S .

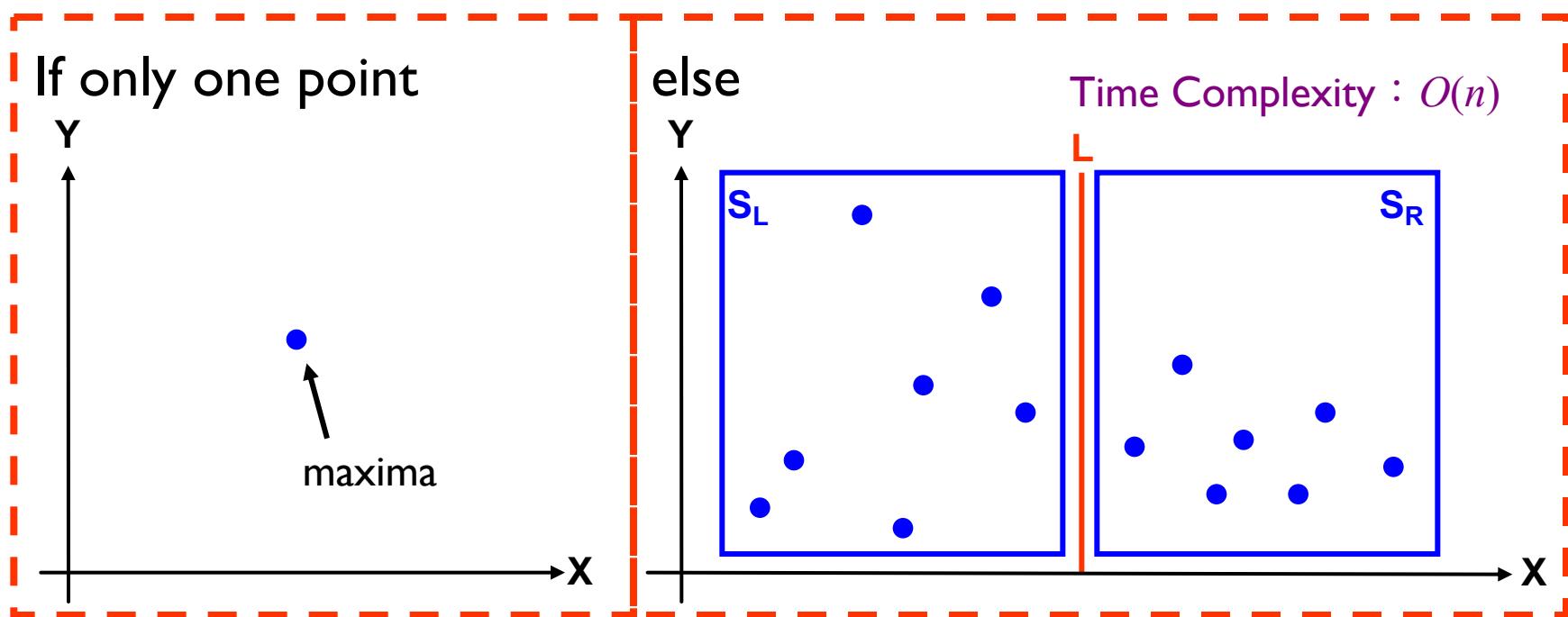
Step 1: If S contains only one point, return it as the maxima. Otherwise, find a line L perpendicular to the X-axis which separates S into S_L and S_R , with equal sizes.

Step 2: Recursively find the maximal points of S_L and S_R .

Step 3: Find the largest y -value in S_R , denoted as y_R . Discard each of the maximal points in S_L if its y -value is less than y_R .

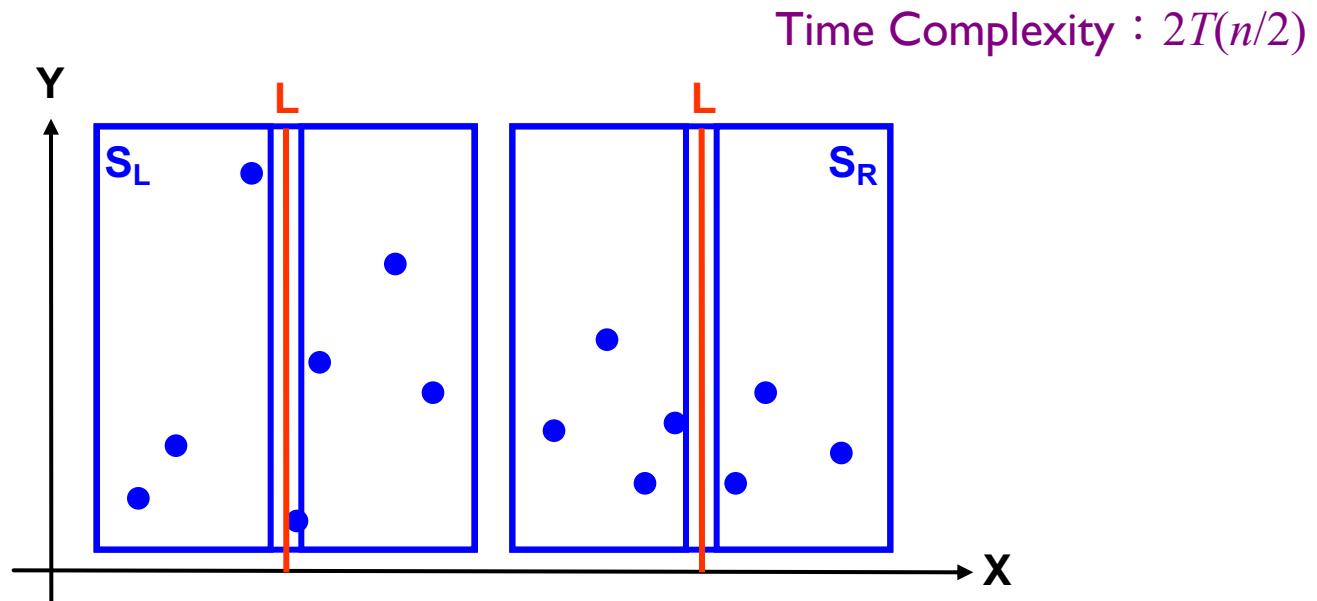
Algorithm Illustration

□ Step 1



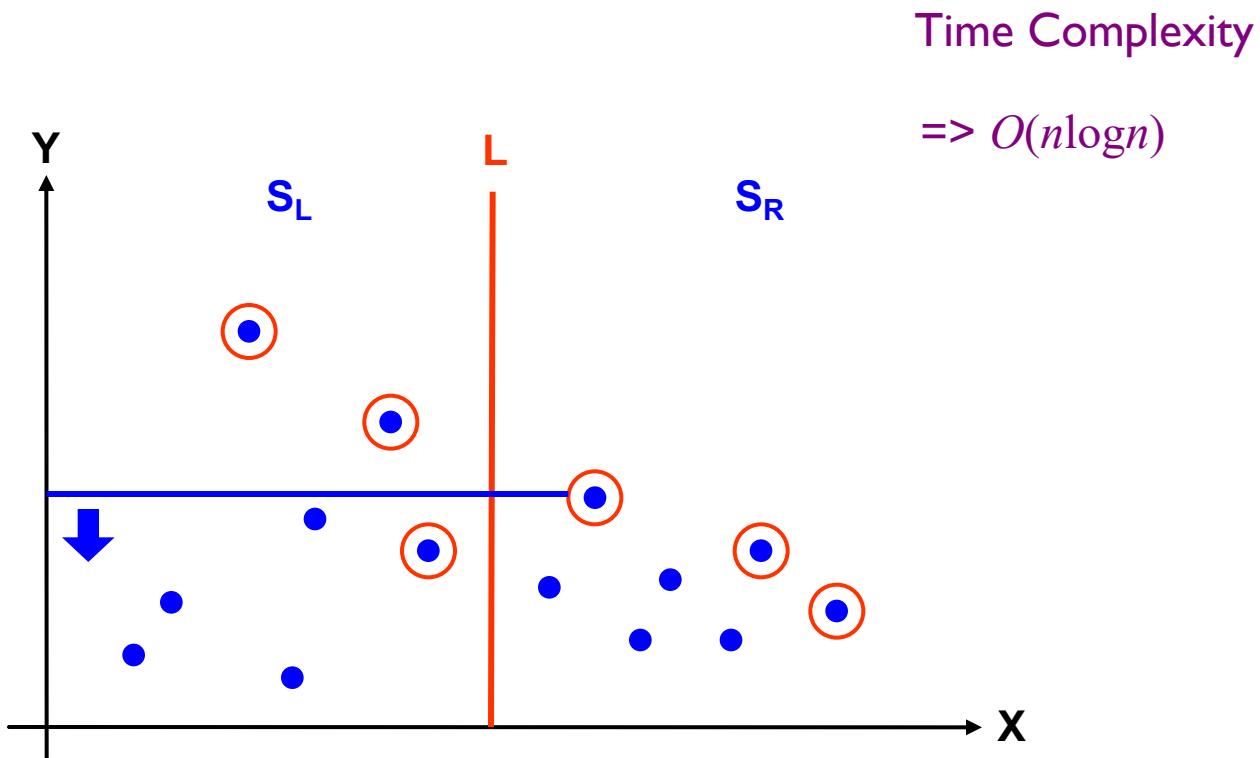
Algorithm Illustration

□ Step 2



Algorithm Illustration

□ Step 3



Summary

- **Divide and Conquer is a recursive algorithm**
- **Three essential steps:**
 - **Divide**: If the input size is too large to deal with in a straightforward manner, divide the data into two or more disjoint subsets.
 - **Recur**: Use divide and conquer to solve the subproblems associated with the sub datasets.
 - **Conquer**: Take the solutions from the subproblems and “merge” them to a solution from the division point.

Note

- To compile a “test.cpp” program to a binary “test”
 - g++ test.cpp -O2 -o test
- To feed a program with a test file from the standard output:
 - ./simple < test.txt
- To measure the runtime of the above program:
 - time –p ./simple < test.txt