

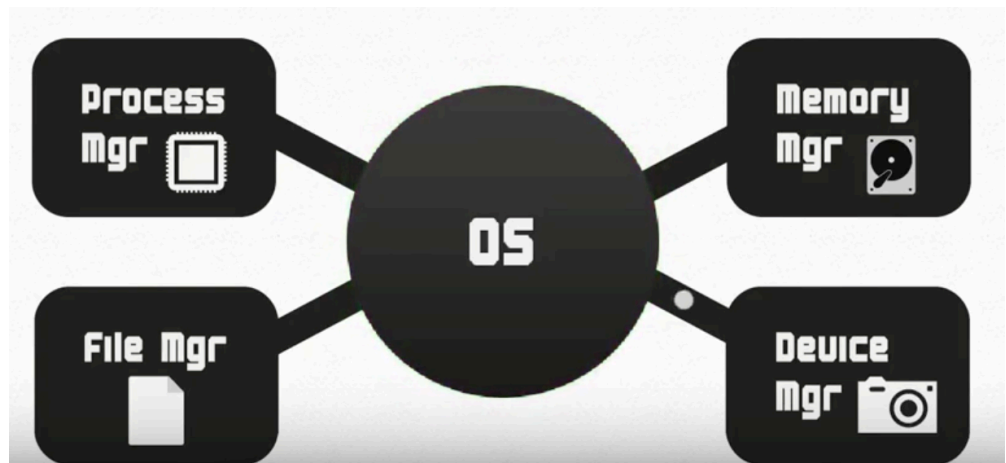
Operating systems

Essential skills 2016-2017

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content

- Introduction to Operating systems (OS)
- Process management
- Memory management
- File system
- Device management

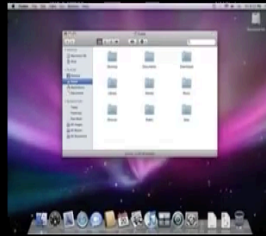


Most known Operating systems

Unix

(a family of OS's)

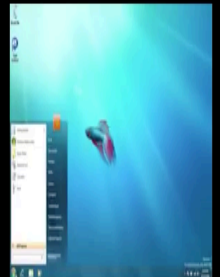
- Linux
- BSD
- OS X



Windows

(series of OS's from Microsoft)

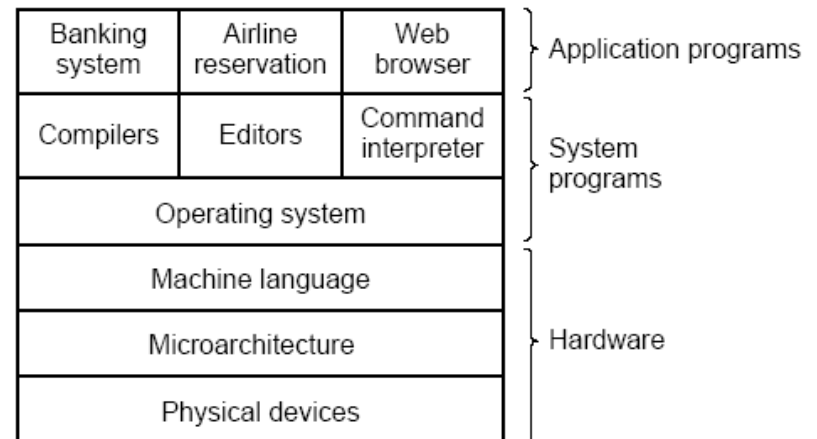
- Windows 8
- Windows Server 2012



ANDROID

Operating systems

- What do they do:
 - OS as a Virtual Machine
 - **Abstraction** → decouple applications from low level device details
 - OS as a Resource Manager
 - **Arbitration** → Fair sharing of **resources** (scheduling), protect against simultaneous usage of resources



Abstraction or Arbitration?

- Support both Intel and AMD processor
- Switching between Applications
- Separating memory Allocated to different applications
- Enabling video card software to use different camera devices
- Access two different hard disks
- Sending/receiving messages over the network

Hardware resources

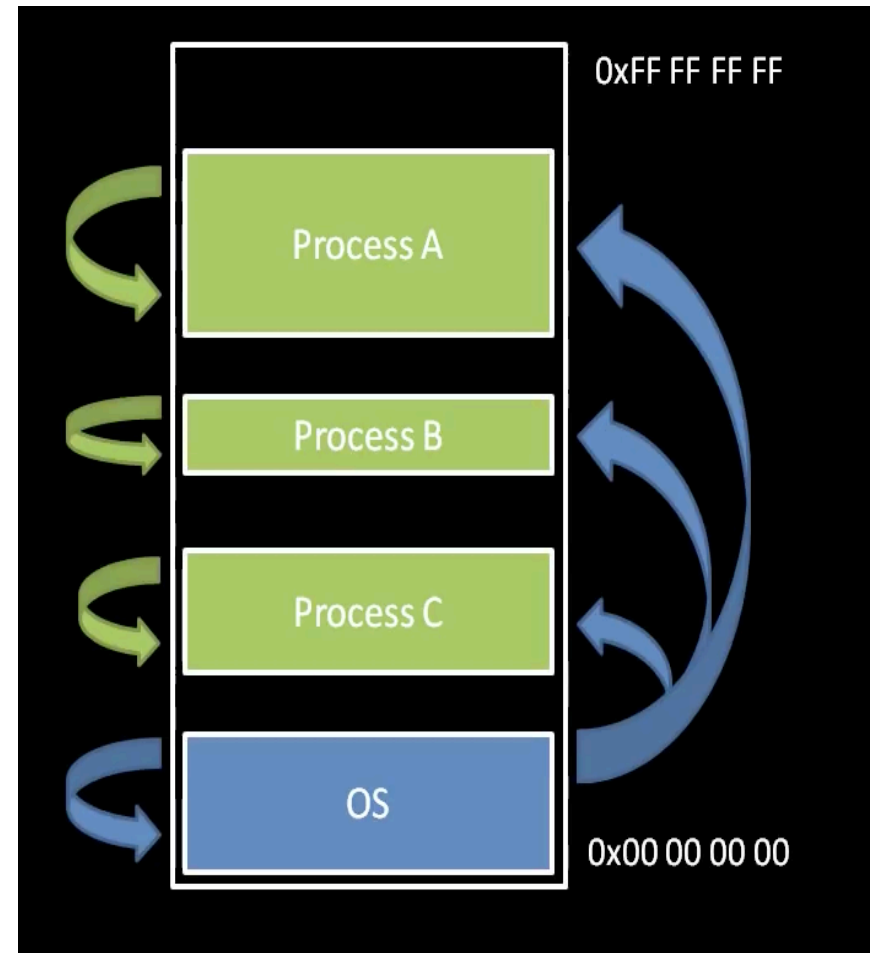
- Central Unit processing (CPU)
 - Execute program instructions
 - Multiple CPU cores execute instructions in parallel
- Memory
 - Hierarchy of different memory speeds
 - Fastest memory attached to CPU: registers and cache
 - Random Access memory (RAM) - Slower
 - Persistent memory (disk) – slowest
- Input/output (I/O) devices
 - Keyboard, mouse, Network Interface Card, Screen, printer, ...

How to view an OS

- From Application/user point of view
 - OS appears to the application and users as a **library of functions** → system calls
 - From OS point of view
 - A **process** represent a user or an application and executes a program.
 - Data needed for the processing is retrieved from and stored in **files**. Data in files are persistent over processes
- process = program in execution

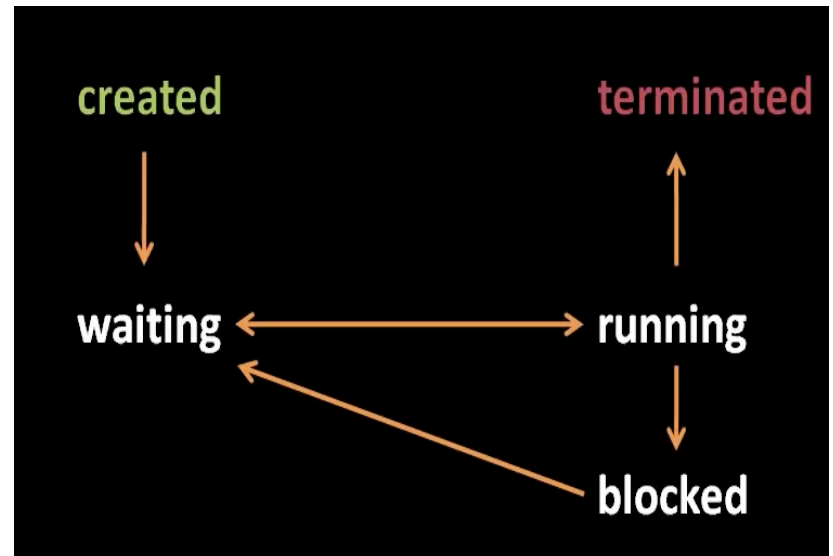
Process

- Each process has its **own memory** space
- A process is **not allowed to access** other processes memory space.

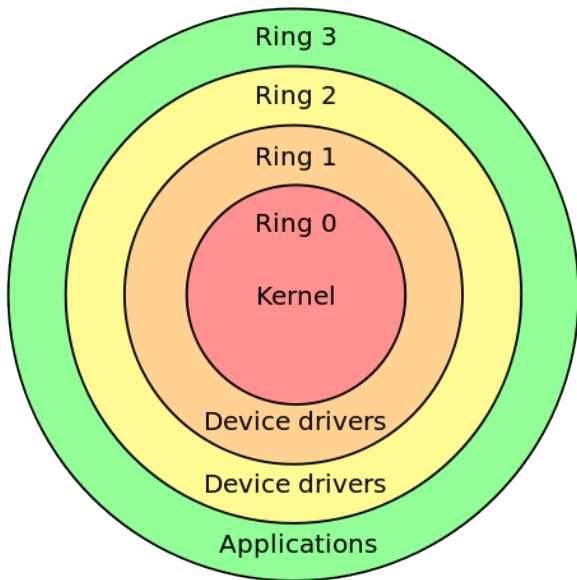


Process lifecycle

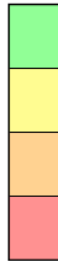
1. Process is first created
2. Then goes to the **waiting state** → for the OS (scheduler) to select the process
3. Then keep bouncing between two states: **running** and **waiting**
 - Can be interrupted
4. When the process request to resource or data not available it goes to the **blocked state**



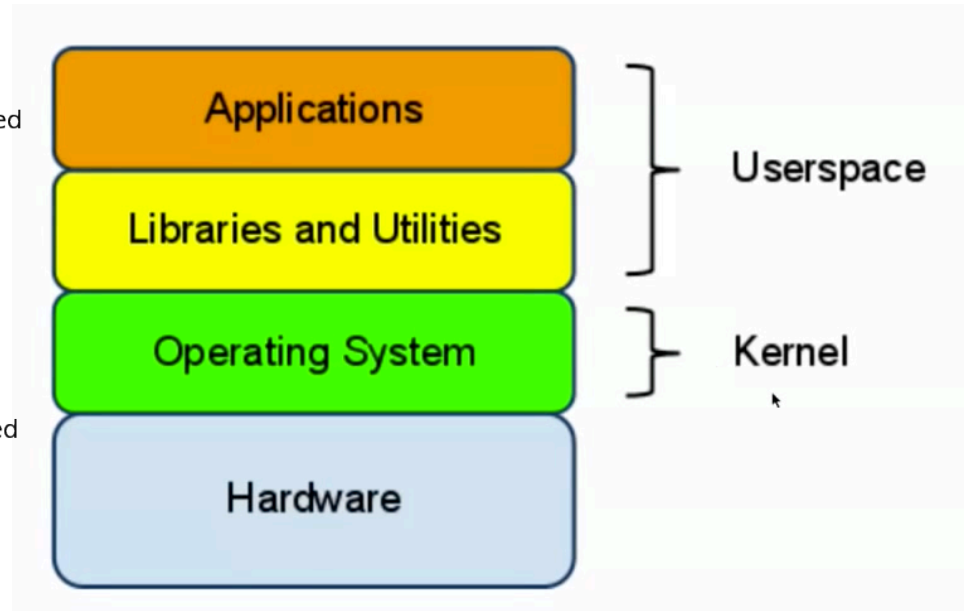
Kernel and user space



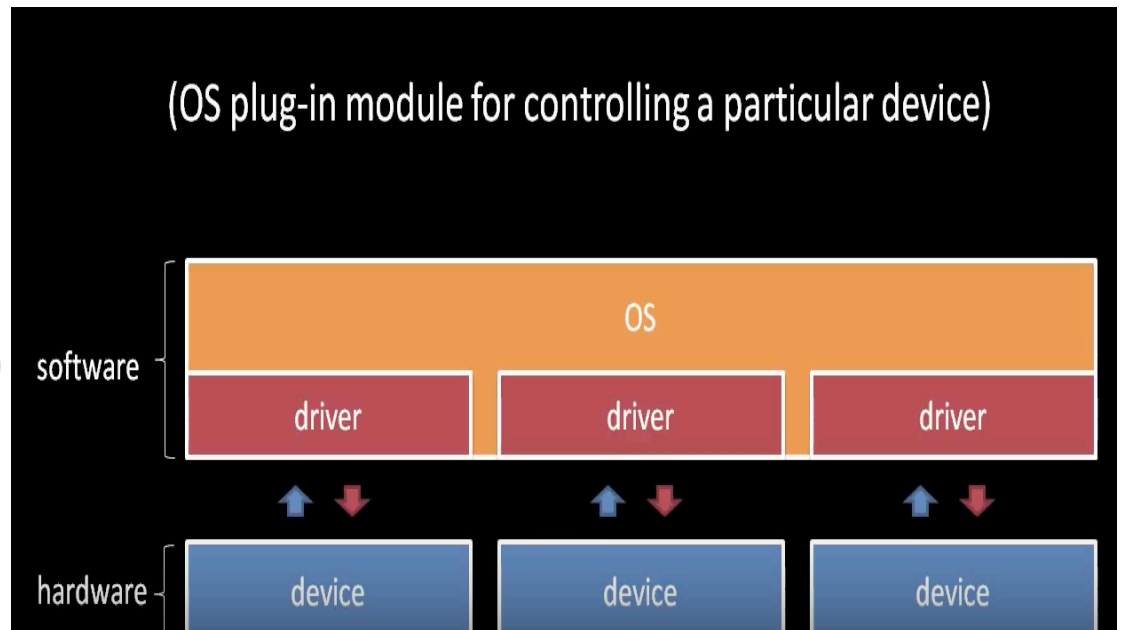
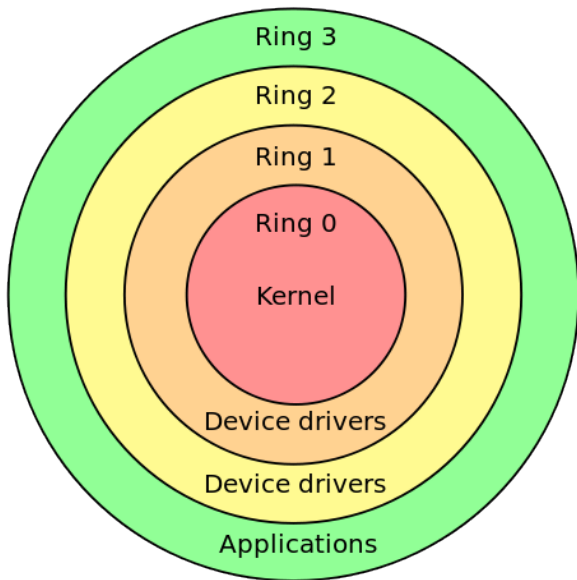
Least privileged



Most privileged



Device driver



Communicating with Hardware

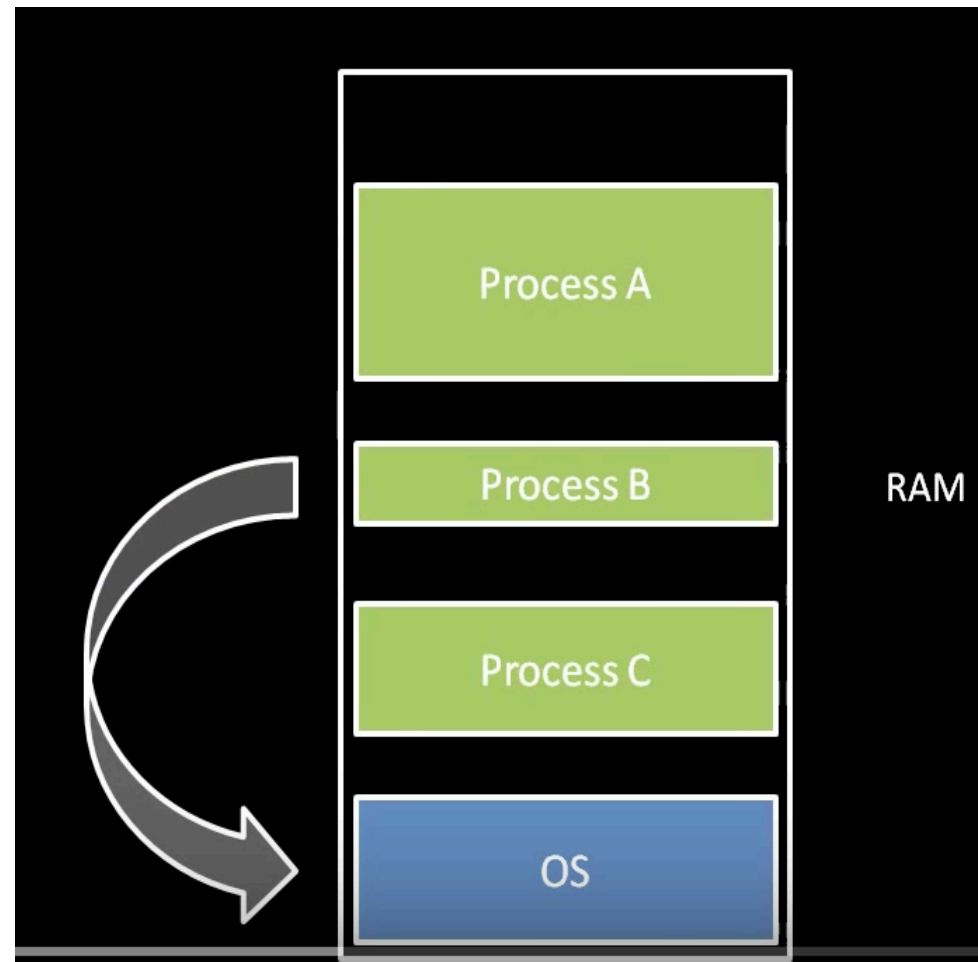
OS implement a common mechanism for allowing **applications** to access hardware (abstraction) and the way around

- Application make requests to the OS via **system calls**
- OS alert or terminate Applications via **signals**

System calls

A System call allow a process to access OS space

- Initiate request to the OS to open a file, send/receive data over the network etc.



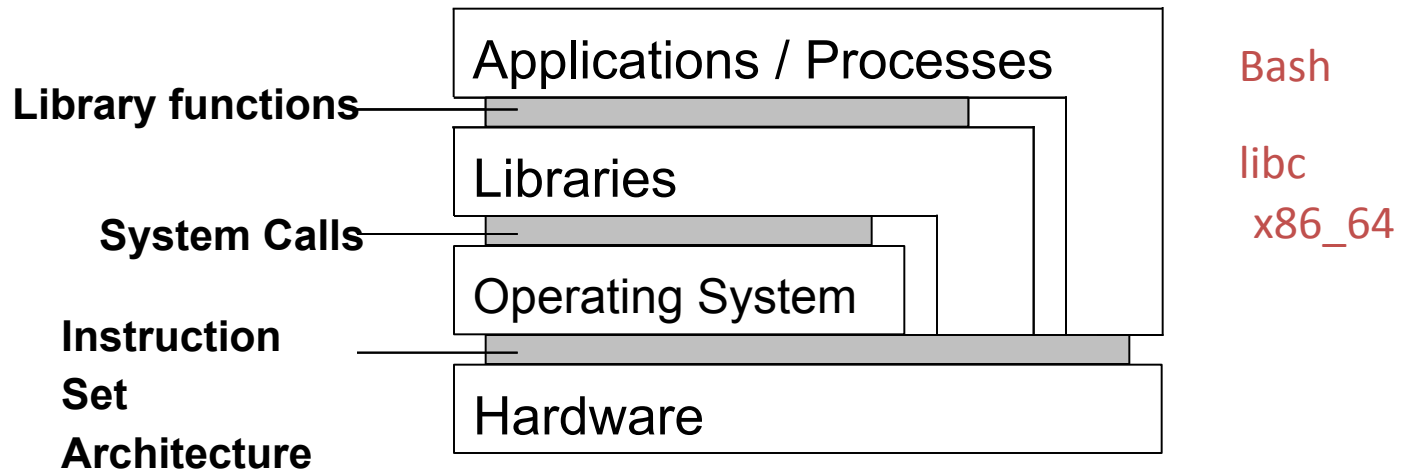
System call table

- In a system call the process specifies a **system call number**
- The CPU looks in the **system call table** for the address of the routine to be executed

...	...
system call 7	0xFF 31 01 11
system call 6	0xFF 90 44 44
system call 5	0xFF 31 01 11
system call 4	0xFF 31 21 14
system call 3	0xA2 22 00 10
system call 2	0x82 87 95 94
system call 1	0x20 15 10 00
system call 0	0x76 00 00 00

System calls

- **Problem:** Mechanics of issuing a system call are highly machine dependent
- **Solution:** Provide a library to allow system calls from C programs: `libc`



System calls: process Management

- Consider a very simple command shell
 1. Wait for the user to type in the command.
 2. Start the process that execute the program
 - Load the specified file into memory
 - And execute the program ➔ process
 3. Wait until the child process finishes

System calls: process Management

Needed: (1) **process creation**, (2) have process **execute a file**, (3) have a process **wait for a child** to finish.

```
while(TRUE){
    read_command(command, parameters);
    pid = fork();

    if( pid != 0 ){ /* parent process */
        waitpid( pid, &status, 0 );
    }
    else{ /* child process */
        execve(command, parameters, 0);
        exit(0);
    }
}
```

fork: Create a child process identical to the parent

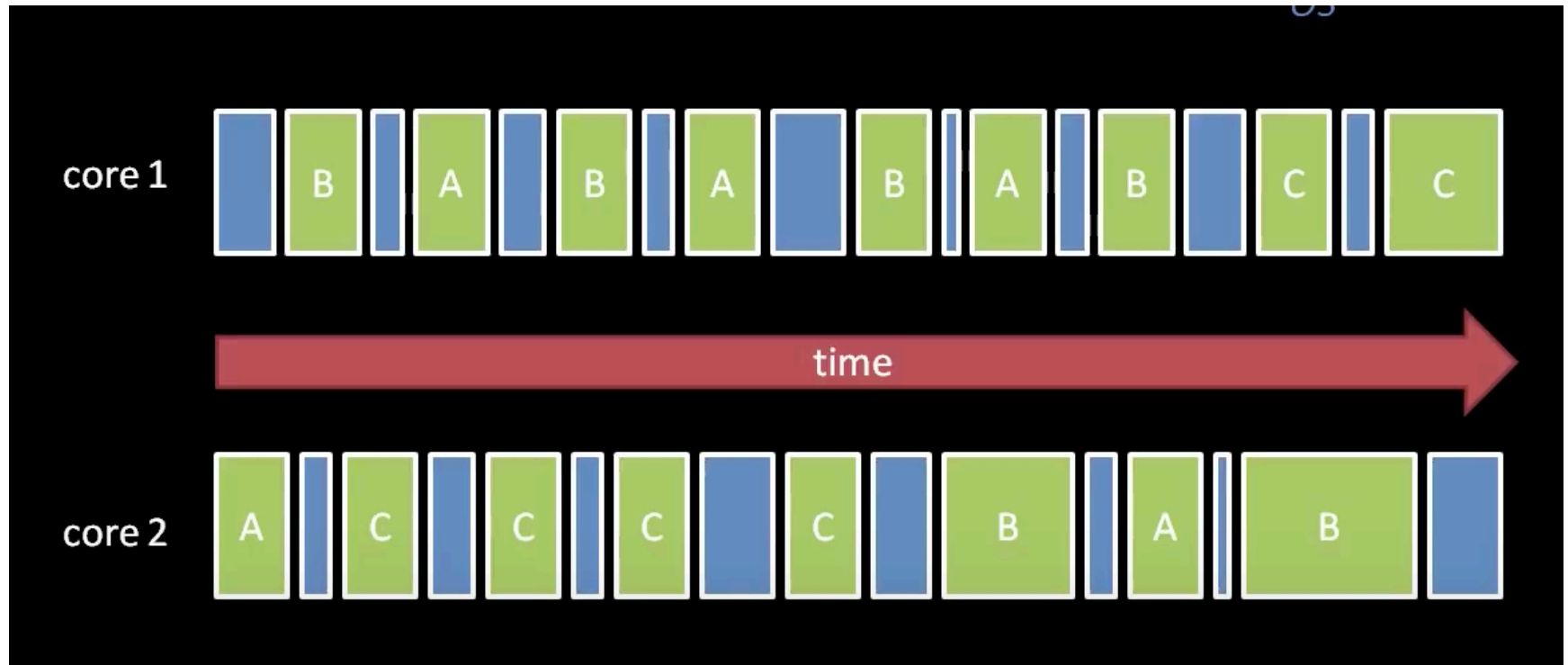
waitpid: Wait for a (specific) child to terminate

execve: Replace a process's core image

exit: Terminate process execution

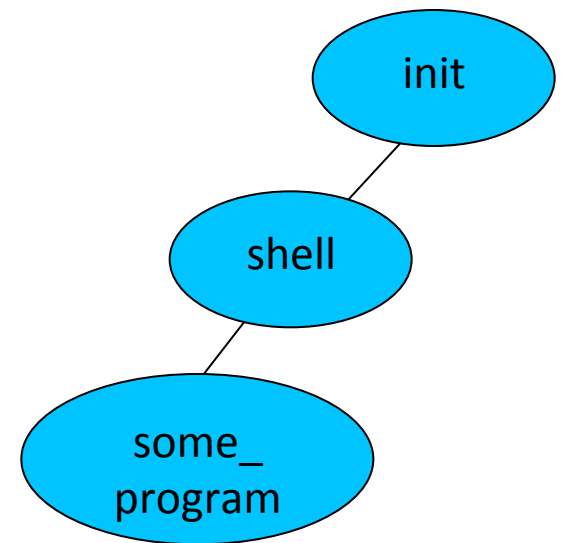
Multiple process

- Modern OS can execute more than one process at the time



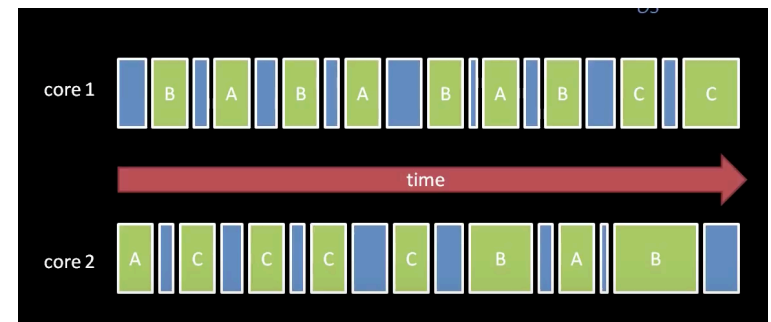
Multiple processes

- How do we get multiple processes in the first place?
 - Process can create other processes
 - Example: the command shell



Multiple processes

- How the OS executes multiple processes on the same resources (CPU, memory , I/O devices) at the same time?
 - OS has to interrupt the processes while they are running
 1. OS send a **signal** to a process to interrupt it,
 2. Process **catch the signal** by executing a specific handler

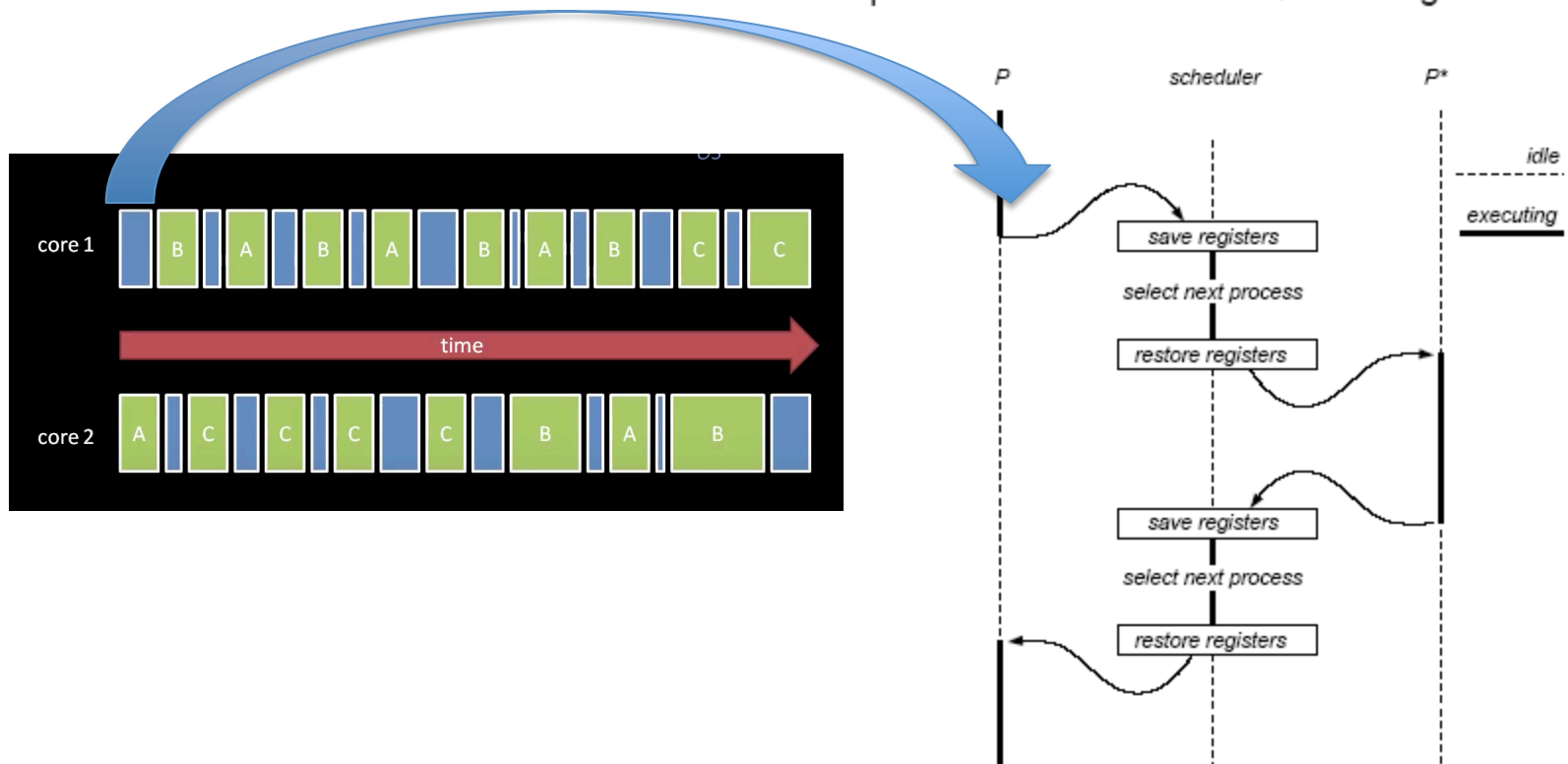


Pre-emptive multitasking

- CPU receives interrupts
- Interrupts stores Program Counter (PC)
- Interrupts invokes **handler**
- **Handler** save rest of state the CPU for the process
- **Handler** does its work
- **Handler** invokes the scheduler
- **Scheduler** selects a process to run
- **Scheduler** restores the state of the CPU that process
- **Scheduler** jumps execution to that process

Context switch

Problem: We have to change from one process to another. The stuff that is going to be used by another process should be saved \Rightarrow CPU registers.



Threads vs processes

- Thread fall under the regime of a **single process**, and thus reside in the **same address space**
 - Each thread has its **own stack**, processor **context**, and **state**;
 - Threads synchronise through simple primitives (**semaphores** and **monitors**)
 - Each thread may call upon any service provides by the OS, it does it on behalf of the process to which belongs.

Threads –Some Problems

- Does the OS keep an administration of threads (kernel threads), or not (user threads)?
- What happens if a user thread does a blocking system call?
- when process is cloned does the new process get all the threads as well? What about the threads currently blocking on a system call?
- When the OS send a signal, how can you related the signal to a thread should you relate it to a thread?

Mutual Exclusion

- Critical Region: is a part of a **multi-process** program (piece of code) that **may not be concurrently** executed by more than one of the program's processes/threads
- Solutions
 - Semaphores
 - Monitors

Semaphores

- Semaphores are **data structure** that provides mutual exclusion to critical sections:
- Semaphores support two operations
 - Wait (Sem): block until semaphore is open
 - P(), after the Dutch word test (proberen)
 - Signal (sem): allow another thread to enter
 - V() after the Dutch word increment (verhogen)

Semaphore types

- **Mutex** Semaphore
 - Represent a **single access** to a resource
 - Guarantees a mutual exclusion to a CS
- **Counting** semaphore
 - Represent a **resource with many units** available
 - Multiple threads can pass the semaphore

Semaphore in use

```
struct Semaphore {  
    int value;  
    Queue q;  
} S;  
  
withdraw (account, amount) {  
    wait(S);  
    balance = get_balance(account);  
    balance = balance - amount;  
    put_balance(account, balance);  
    signal(S);  
    return balance;  
}
```

Threads
block

```
wait(S);  
balance = get_balance(account);  
balance = balance - amount;
```

```
wait(S);
```

```
wait(S);
```

```
put_balance(account, balance);  
signal(S);
```

```
...  
signal(S);
```

```
...  
signal(S);
```

It is undefined which
thread runs after a signal



Monitors

- A monitor is a **programming language construct** that controls access to the shared data
 - Synchronise code added by the compiler, enforced at runtime
- A monitor is a module that encapsulates
 - Shared data structures
 - Synchronisation Procedures
- A monitor **protects** its data from **unstructured access**
 - It guarantees that threads accessing its data through its procedures interact only in well defined way

Condition variables

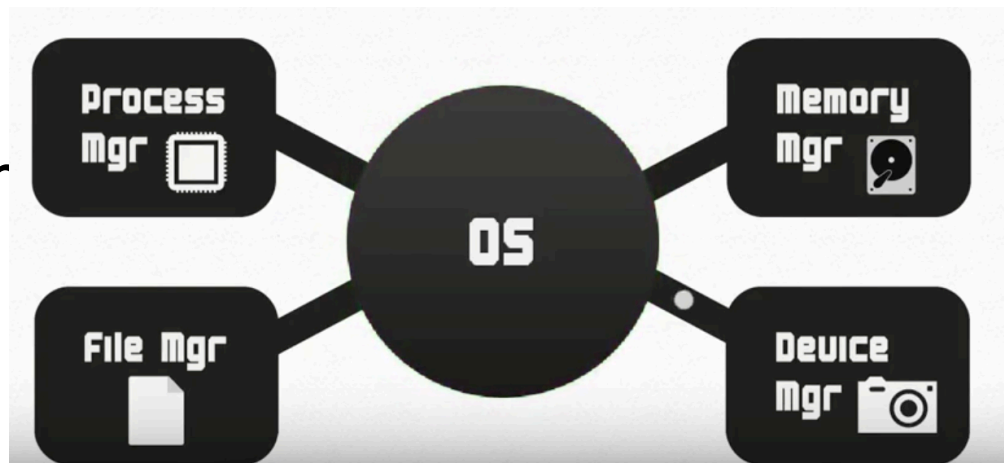
- Condition variables provide a mechanism to **wait for events** (a “rendezvous point”)
- Condition variables support three operations:
 - **Wait** – release monitor lock, wait for C/V to be signaled
 - So condition variables have wait queues, too
 - **Signal** – wakeup one waiting thread
 - **Broadcast** – wakeup all waiting threads

Access to the monitor is controlled by a **lock**

Monitor	semaphore
<p>Wait()</p> <ul style="list-style-type: none">• blocks the calling thread on the queue,• and gives up the lock <p>To call wait, the thread has to be in the monitor (hence has lock)</p>	<p>Wait() or P()</p> <ul style="list-style-type: none">• blocks calling thread on the queue
<p>Signal ()</p> <ul style="list-style-type: none">• causes a waiting thread to wake up <p>If there is no waiting thread, the signal is lost.</p> <p>→ Condition variables have no history</p>	<p>Signal () or V()</p> <ul style="list-style-type: none">• increases the semaphore count, allowing future entry even if no thread is waiting

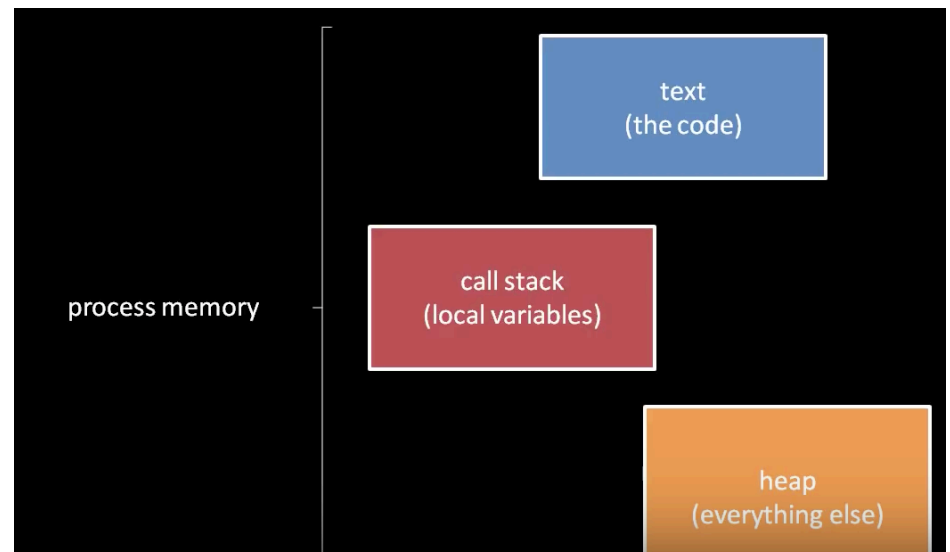
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- Process management
 - Single process management
 - Multi process management
- Memory management
- File system
- Device management



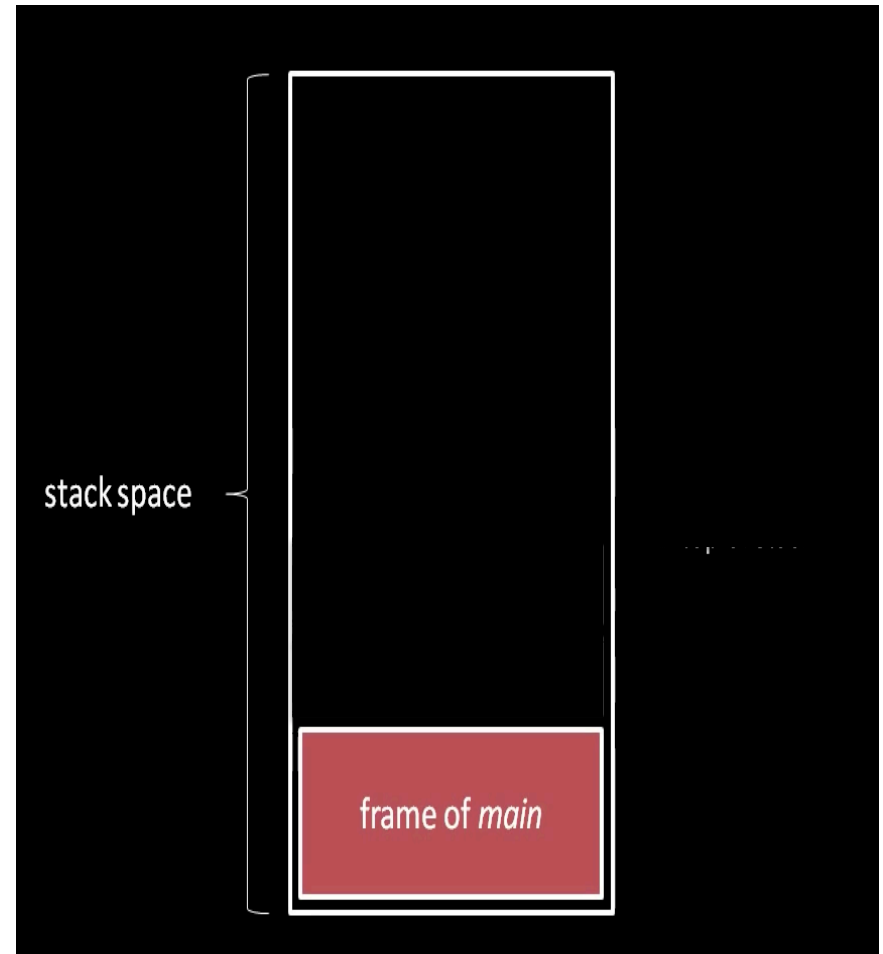
Process Memory organization

- Process code (text)
 - Never modified during execution except of dynamic linking with shared library
- Process **stack** (local variables)
- Process **heap** (for anything else)



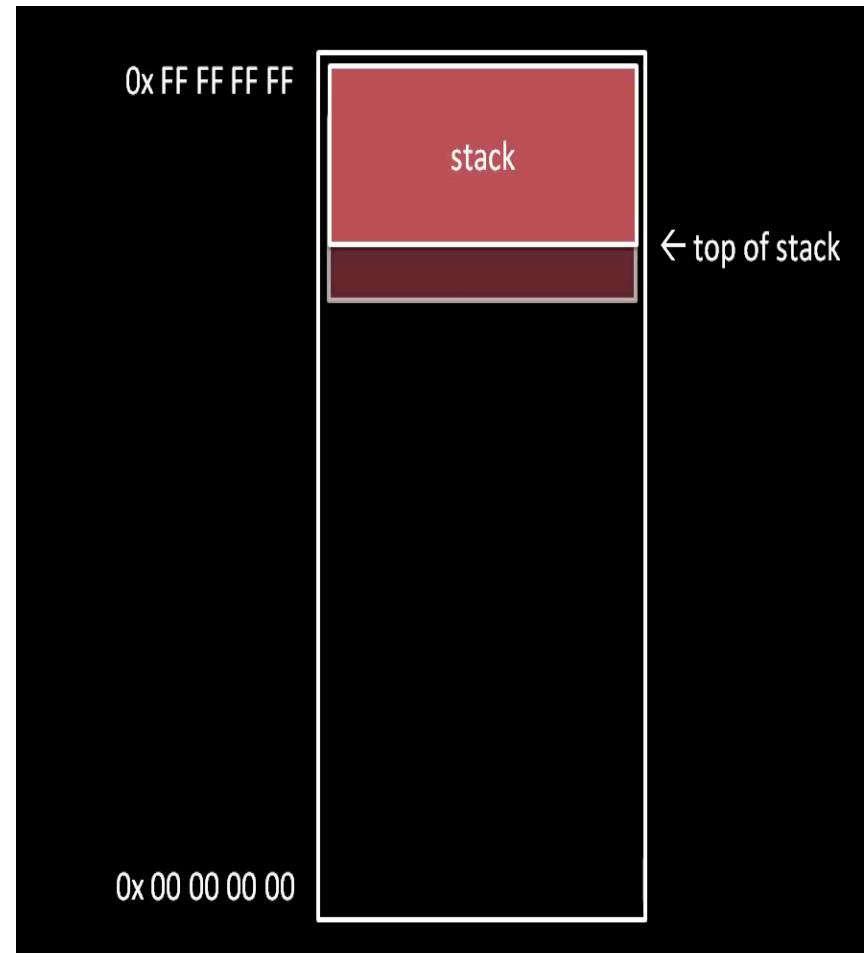
Stack management 1/2

- Start unused **when functions** are called address space is reserved for the function to save:
 - Local variable of the called function
 - Return address
 - Size of the frame
- Top of the stack is keep in a special register called **the stack pointer**



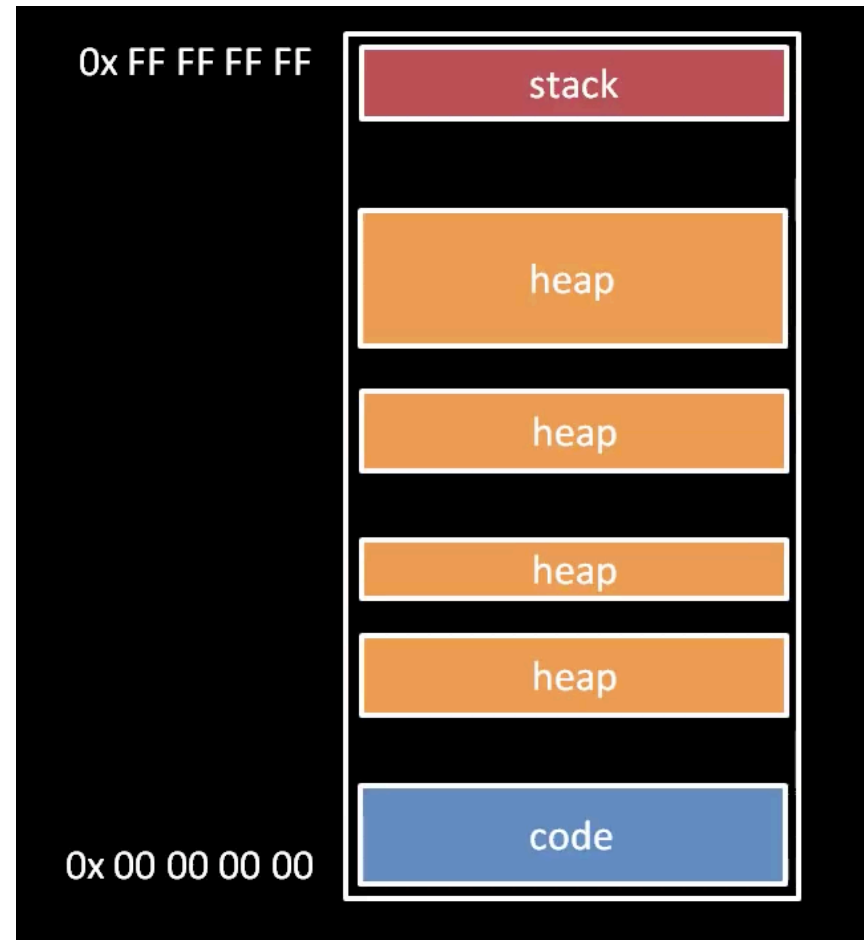
Stack management 2/2

- The **size** of the stack is kept in another register
- When stack pointer reaches this stack boundary → it triggers an exception
 - Increase the size of the stack
 - terminate the process if the stack is too big
- Problem: When a program exceeds its stack space → stack overflow



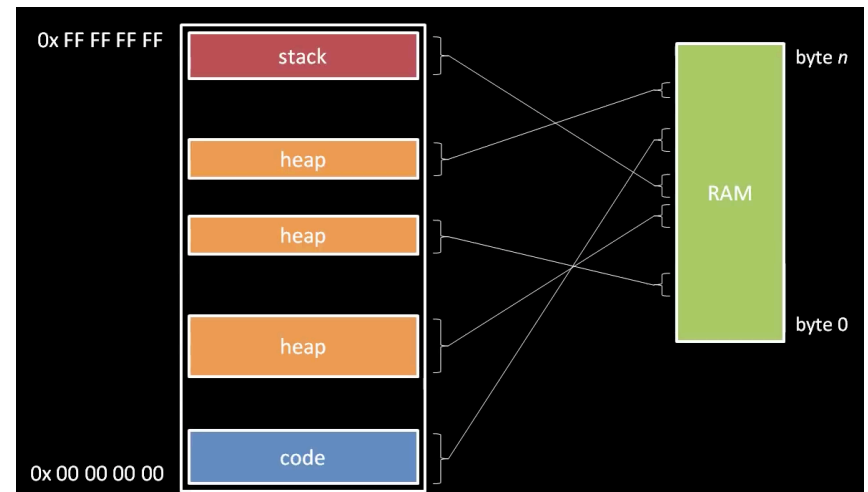
Heap management 1/2

- Memory space between the stack and the code of the process
 1. **Process requests** allocation of heap space from the OS
 2. **OS allocates** a piece of adjacent space
 3. **de-allocation** is the responsibility of the **process**
- Problems
 - Run out of heap space
 - Fragmentation of the heap space



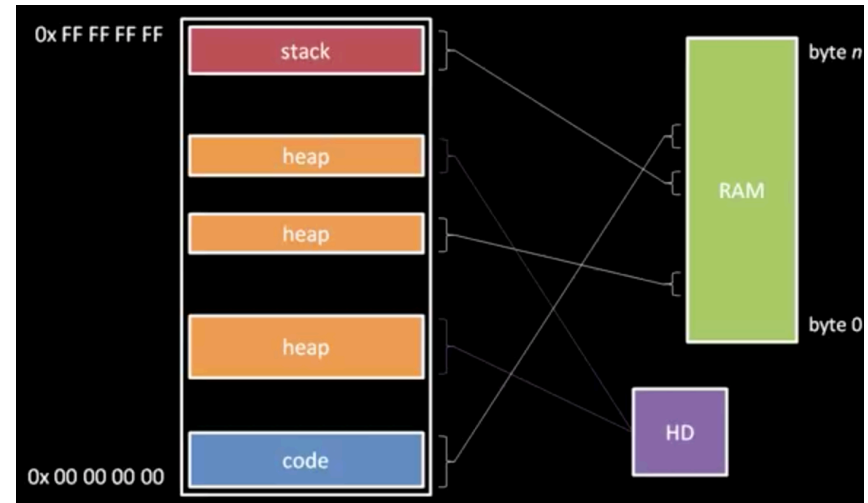
Heap management 2/2

- The memory address of a process do not refer to actual byte in the system memory (RAM)
- Instead chunks of the process address space are mapped by the OS to chunks of the byte in the system memory
 - Not contiguous
 - Or in a particular order



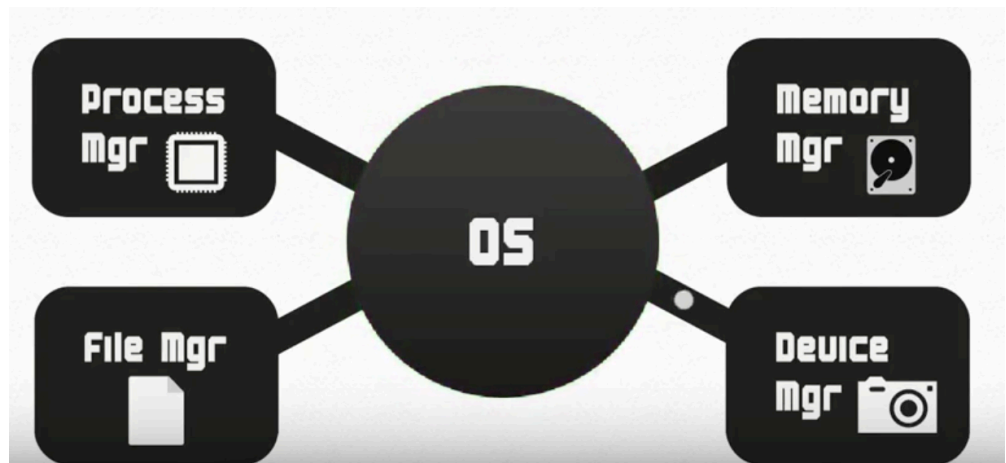
Heap management: SWAP

- To free up valuable system memory (RAM), the OS may decide to **swap out pages** of a process to a Hard drive
- Heap data that are not mapped to any part of the RAM and are marked the **process memory table** as **SWAPPED**
- If a process tries to access SWAPPED pages an exception is generated
 1. Copy back data to RAM
 2. Adjust the process mem table



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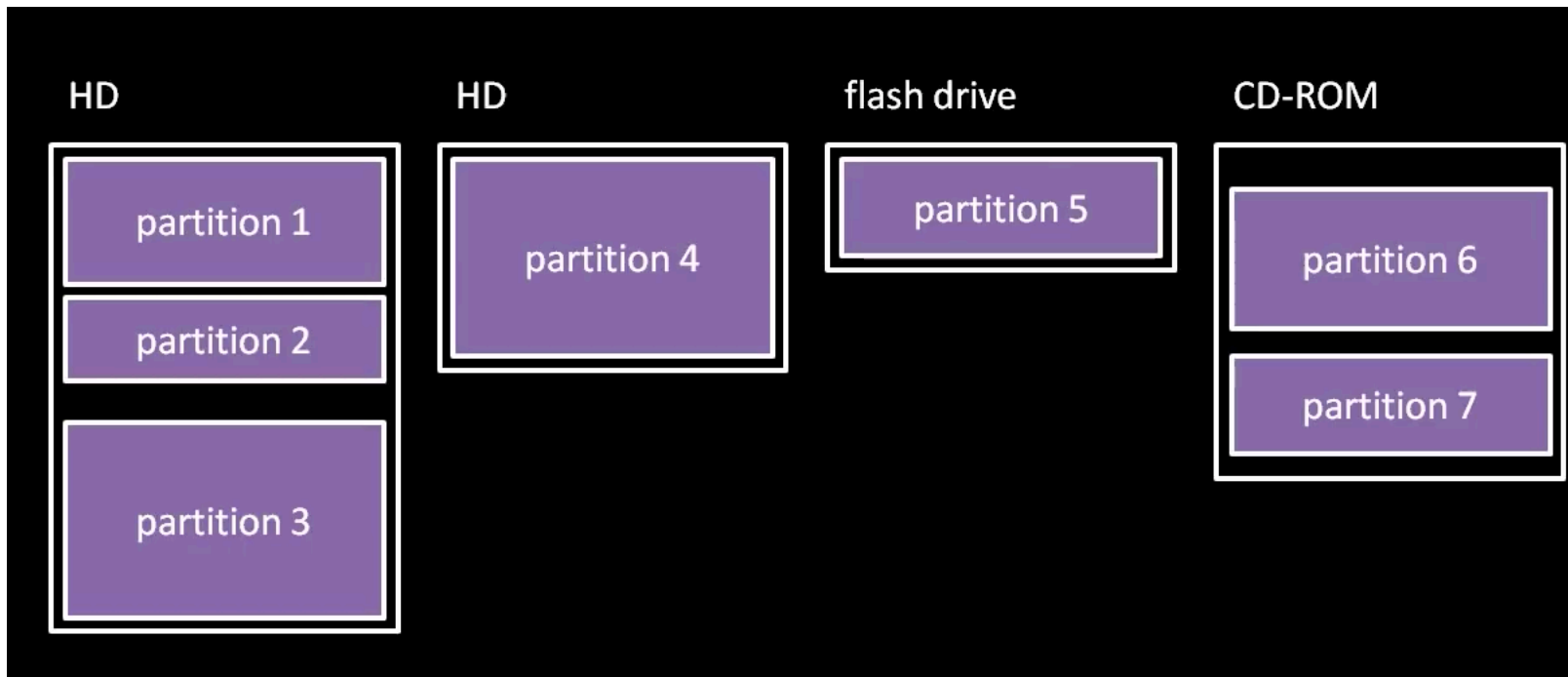


File systems 1/2

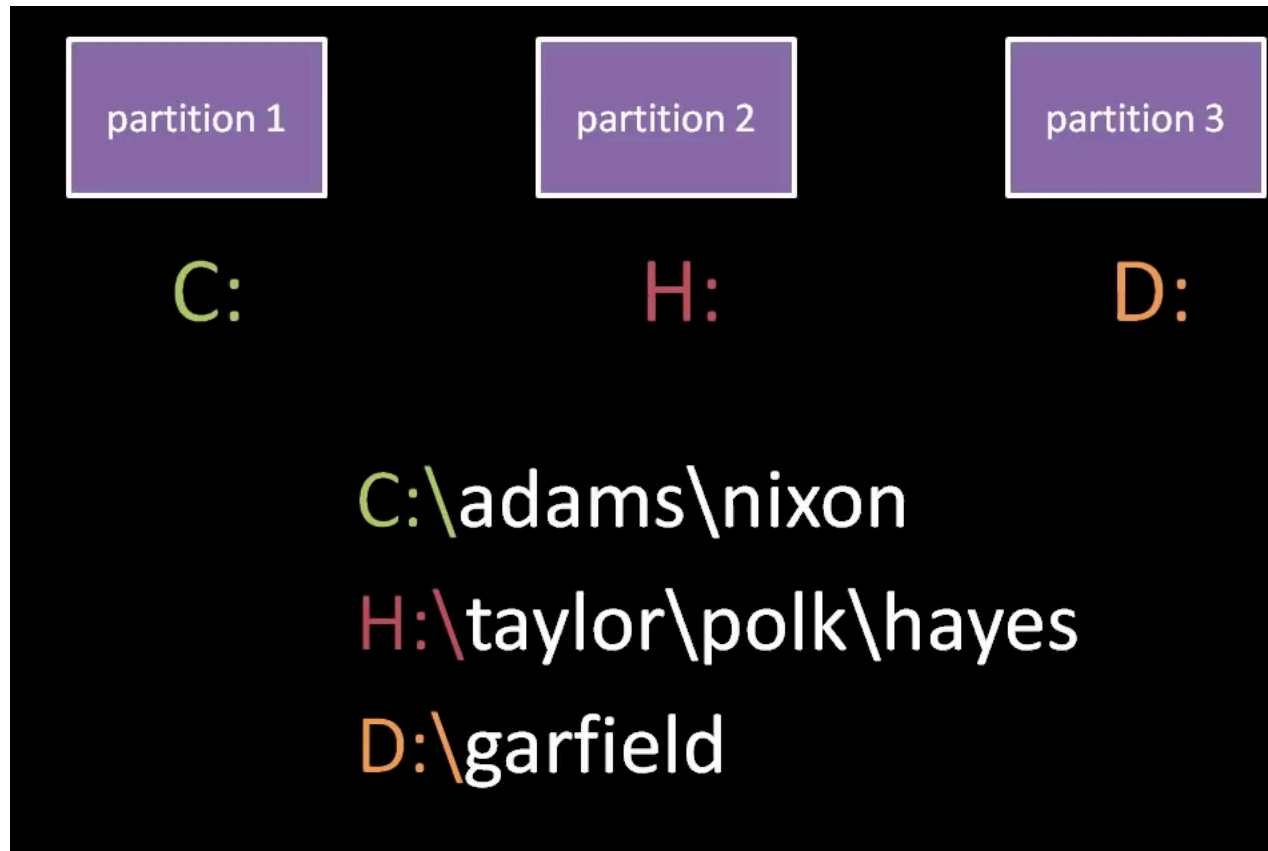
- OS provide an useful **abstraction** of the **storage system** known as file system
- File systems presents storage devices as **hierarchy of directories** and files stored in these directories
- Processes can read/write data from/to **logically contiguous** memory space called file, which can be accessed by a logical name

Partitions

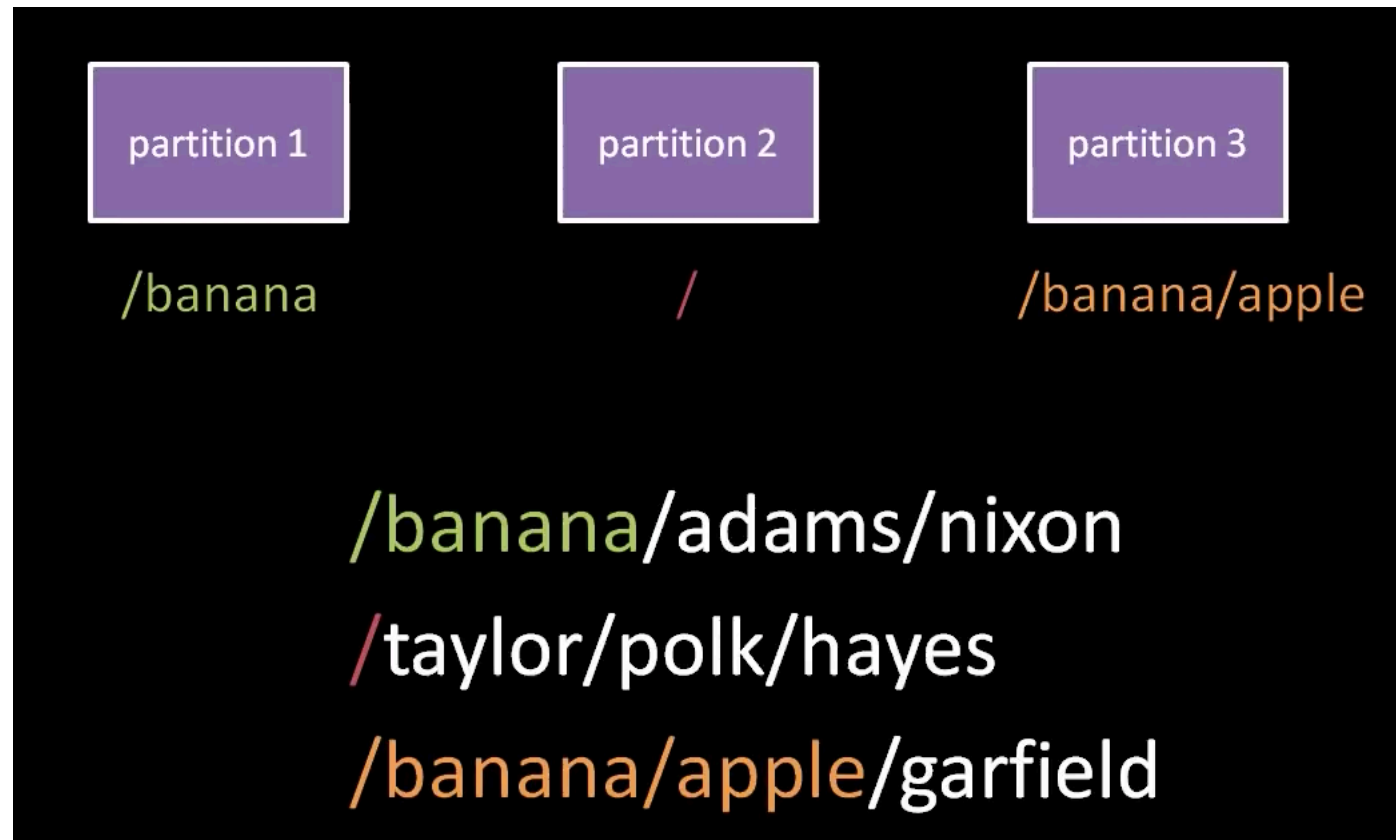
- Storage devices are composed of one or more partitions



Windows Partitions

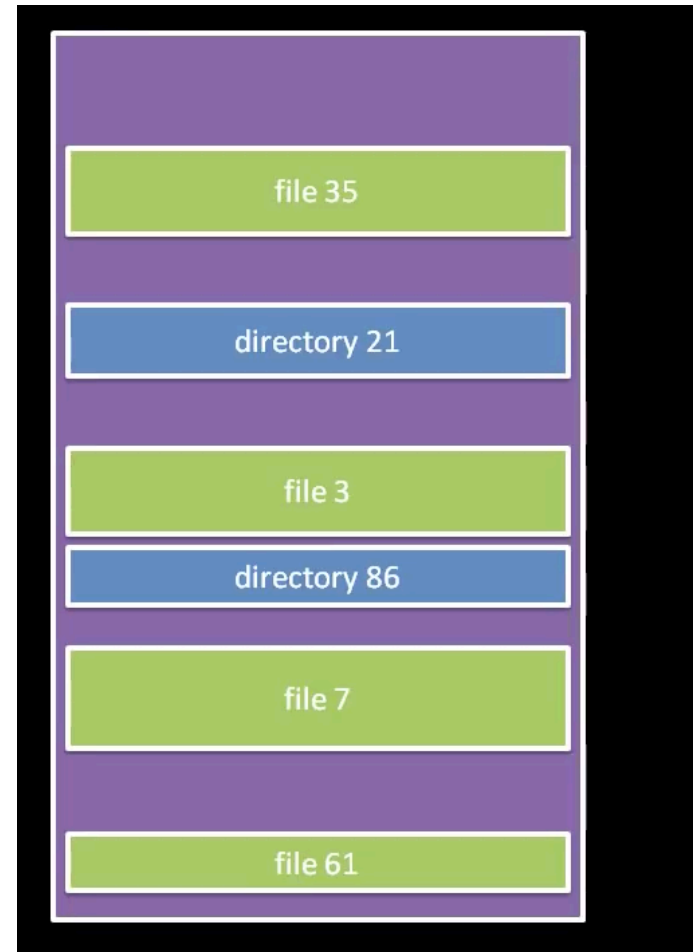


Unix-like Partitions



Partitions

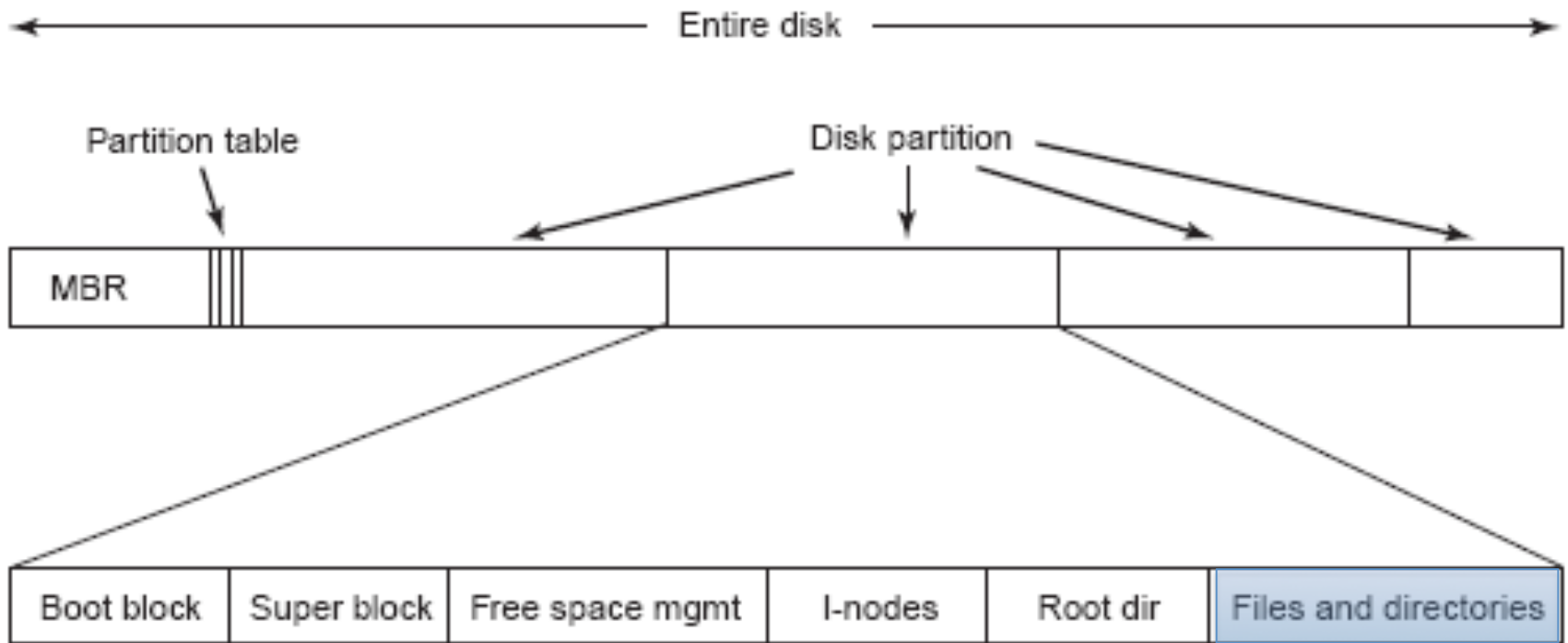
- Each partition is organized as a **hierarchy of files** and **directories**
- Each file and directory is known by a **unique identifier**
 - File Attributes



File system design

- File storage
- Directory implementation
- Disk space management
- Consistency

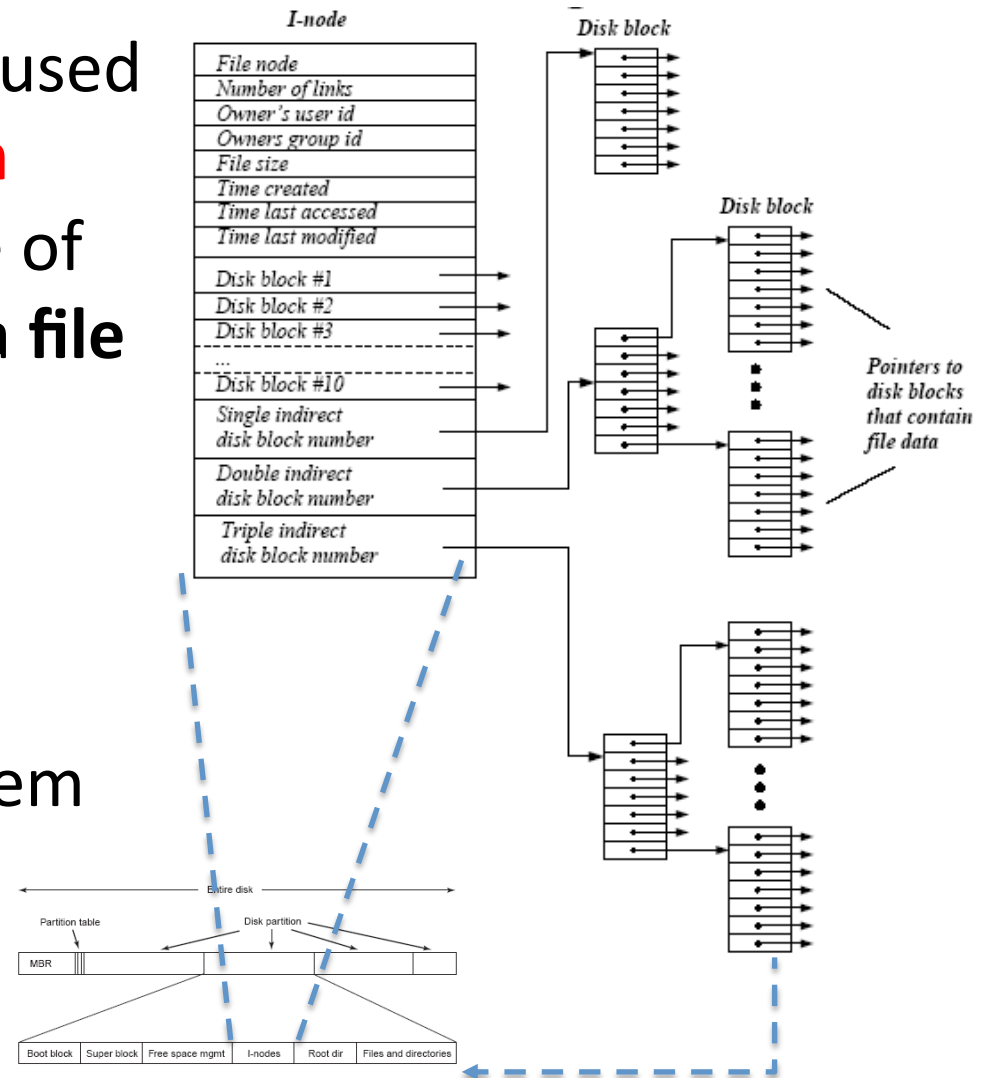
File storage: Disk Layout



File storage - Inode

inode is a data structure used to represent **a filesystem object**, which can be one of various things including a **file** or a **directory**.

Each inode stores the attributes and disk block location(s) of the filesystem object's data



File storage –name resolution

