RECURSION GDB BINARY SEARCH TREES

Problem Solving with Computers-II



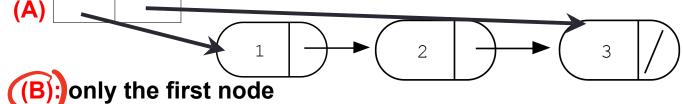
Concept Question

```
LinkedList::~LinkedList(){
   delete head;
}
```

class Node {
 public:
 int info;
 Node *next;
};

Which of the following objects are deleted when the destructor of Linked-list is called?

head tail



(C): A and B

(D): All the nodes of the linked list

(E): A and D

Concept question

```
LinkedList::~LinkedList(){
                                       Node::~Node(){
  delete head; This calls the
                                          delete next;
     destructor of Node for nocle 1
   head tail
```

Which of the following objects are deleted when the destructor of Linked-list is called? call's 2's destructor calls 3's destructor (B): All the nodes in the linked-list inder 15 deleted (C): A and B (D): Program crashes with a segmentation fault

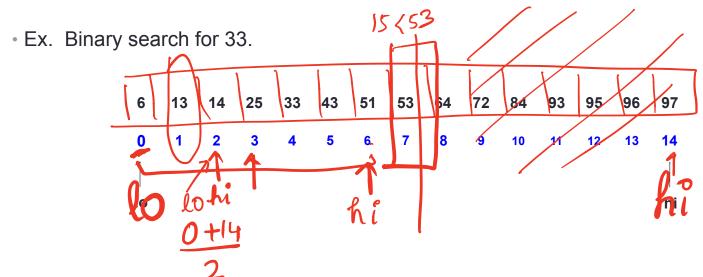
(E): None of the above

LinkedList::~LinkedList(){ Node::~Node(){ delete next; delete head; head tail what happens it we say
delete Pi

Part of the chain
starkingat node 2 is
deleted If you only want to delete node 2, first isolate it. (Set its next printer to null) then call delete.

Binary Search

- Binary search. Given value and sorted array a[], find index i such that a[i] = value, or report that no such index exists.
- Invariant. Algorithm maintains a [lo] ≤ value ≤ a [hi].



GDB: GNU Debugger

- To use gdb, compile with the -g flag
- Setting breakpoints (b)
- Running programs that take arguments within gdb (r arguments)
- Continue execution until breakpoint is reached (c)
- Stepping into functions with step (s)
- Stepping over functions with next (n)
- Re-running a program (r)
- Examining local variables (info locals)
- Printing the value of variables with print (p)
- Quitting gdb (q)
- Debugging segfaults with backtrace (bt)

Demo debugging using gdb.

* Refer to the gdb cheat sheet: https://ucsb-cs24.github.io/m19/lectures/GDB-cheatsheet.pdf

one field in a larger smuch (record)
one piece of data
hierarchy nodes

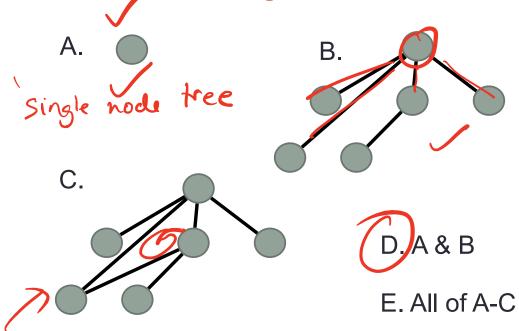
A tree has following general properties:

- One node is distinguished as a **root**;
- Every node (exclude a root) is connected by a directed edge *from* exactly one other node;

A direction is: *parent -> children*

• Leaf node: Node that has no children

Which of the following is/are a tree?



Binary Search Trees

• What are the operations supported?

Same as sorted away & fast insert & delete

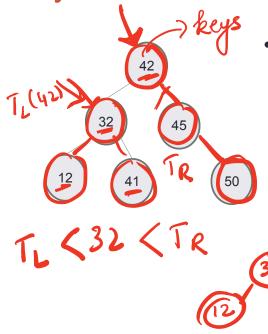
What are the running times of these operations?

This class we'll build some intuition, formalise next lecture

How do you implement the BST i.e. operations supported by it?

We'll go over the important operations. This exercise improvee your coding. exille

Binary Search Tree – What is it?

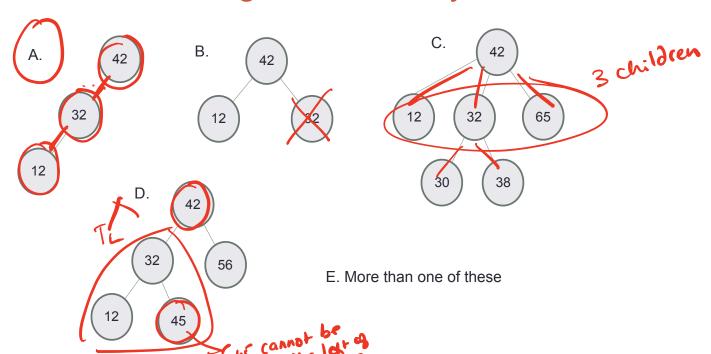


- Each node:
 - stores a key (k)
 - has a pointer to left child, right child and parent (optional)
 - Satisfies the Search Tree Property

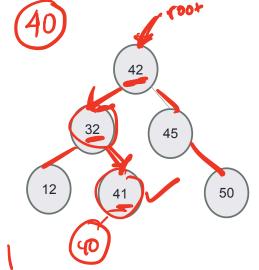
For any node, Keys in node's left subtree <= Node's key Node's key < Keys in node's right subtree

Do the keys have to be integers?

Which of the following is/are a binary search tree?



BSTs allow efficient search!



- Start at the root;
- Trace down a path by comparing **k** with the key of the current node x:
 - If the keys are equal: we have found the key
 - If $\mathbf{k} < \text{key}[\mathbf{x}]$ search in the left subtree of \mathbf{x}
 - If k > key[x] search in the right subtree of x



Search for 41, then search for 53

A node in a BST

```
class BSTNode {
public:
  BSTNode* left;
  BSTNode* right;
  BSTNode* parent;
  int const data;
  BSTNode (const int & d) : data(d) {
    left = right = parent = 0;
```

Define the BST ADT

