Compressed Sensing

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1 Preliminaries

We define useful mappings used in convex optimization, namely the proximal mapping

$$\operatorname{Prox}_{f}^{\lambda}(y) = \operatorname*{arg\,min}_{x} \left(f(x) + \frac{1}{2\lambda} ||x - y|| \right)$$

2 Overview

Short overwiew of matrix completion:

$$\min ||X||_* \quad s.t. \quad AX = B$$

We need to find the min rank X such that AX = B

3 Douglas- Rachford Splitting

In the noiseless case we can use DRS to solve this numerically via a fixed-point iteration:

$$z^{(k+1)} = z^{(k)} + \operatorname{Prox}_g^{\gamma} \left(2 \operatorname{Prox}_f^{\gamma}(z^{(k)}) - z^{(k)} \right) - \operatorname{Prox}_g^{\gamma}(z^{(k)})$$

To do this, we express our objective as a sum of two functions f + g where $f(X) = \delta_C(X)$ with $C = \{X | AX = B\}$ and $g(X) = ||X||_*$. We then obtain

$$Prox_f^{\gamma}(x) = \Pi_C(x) = x + A^+(b - Ax)$$

= $x + A^T(AA^T)^{-1}(b - Ax)$
= $x + A^T(b - Ax)$

To express the proximal mapping of the nuclear norm, we define the singular value thresholding operator \mathcal{D}_{γ} . For a matrix Y with the SVD $Y = U\Sigma V^T =$

 $U\operatorname{diag}(\sigma(Y))V^T$ it is expressed by $\mathcal{D}_{\gamma}(Y) = U\operatorname{diag}(\sigma(Y) - \lambda)_+V^T$. Thus we

$$\operatorname{Prox}_{g}^{\gamma}(x) = U(\sigma(x) - \gamma)_{+} V^{T}$$
$$= \mathcal{D}_{\gamma}(x)$$

FISTA 4

In the noisy case we are trying to minimize the following objective (in the Lagrangian formulation):

$$\min_{X} \lambda ||X||_* + \frac{1}{2} ||AX - B||_2^2 \tag{4.1}$$

For some $\lambda > 0$. The FISTA algorithm is formulated with respect to the following objective:

$$\min_{X} f(x) + g(x)$$

where we assume f and g to be sufficiently smooth, i.e. $f \in C^{1,1}(\mathbb{R}^n)$, which means

$$\exists L(f): ||\nabla f(x) - \nabla f(y)|| \le L(f)||x - y|| \forall x, y \in \mathbb{R}^n$$

In our case we have $f(x) = \frac{1}{2}||AX - B||_2^2 = \frac{1}{2}\langle AX - B, AX - B \rangle$ and $g(x) = \lambda ||X||_*$.By simple calculation we get

$$\nabla f(X) = A^T A X - A^T B = A^T (AX - B) \tag{4.2}$$

$$L(f) = 2\lambda_{\max}(A^T A) \tag{4.3}$$

Algorithm 1 FISTA with constant step size

Input Lipschitz- constant L(f) of ∇f , $y_1 = x_0 \in \mathbb{R}^n$, $t_1 = 1$

- 1: **for** k = 1, ... **do**
- $x_k = p_L(y_k)$
- $t_{k+1} = \frac{1+\sqrt{1+4*t_k^2}}{2}$ $y_{k+1} = x_k + \frac{t_k 1}{t_{k+1}}(x_k x_{k-1})$

In this algorithm we def.

$$\begin{aligned} Q_L(x,y) &= f(y) + \langle x - y, \nabla f(y) \rangle + \frac{L(f)}{2} ||x - y||^2 + g(x) \\ p_L(y) &= \operatorname*{arg\,min}_x Q_L(x,y) \\ &= \operatorname*{arg\,min}_x \left(g(x) + \frac{L(f)}{2} \left\| x - \left(y - \frac{1}{L} \nabla f(y) \right) \right\|^2 \right) \\ &= \operatorname*{arg\,min}_x \left(\frac{g(x)}{\lambda} + \frac{L(f)}{2\lambda} \left\| x - \left(y - \frac{1}{L} \nabla f(y) \right) \right\|^2 \right) \\ &= \operatorname*{Prox}_g^{\lambda/L} \left(y - \frac{1}{L} \nabla f(y) \right) \end{aligned}$$

Since we are trying to find the proximal mapping for the nuclear norm, we can apply the thresholding operator just like in our iteration step for DRS. We get

$$\operatorname{Prox}_{g}^{\lambda/L}\left(y - \frac{1}{L}\nabla f(y)\right) = U\operatorname{diag}\left(\sigma\left(y - \frac{1}{L}\nabla f(y)\right) - \frac{\lambda}{L}\right)_{+}V^{T}$$
$$= \mathcal{D}_{\lambda/L}\left(y - \frac{1}{L}\nabla f(y)\right)$$
$$= \mathcal{D}_{\lambda/L}\left(y - \frac{1}{L}A^{T}(Ay - B)\right)$$

I'm not sure if this is correct