# Compressed Sensing

May 7, 2020

#### 1 Overview

Short overwiew of matrix completion:

$$\min ||X||_* \quad s.t. \quad AX = B$$

We need to find the min rank X such that AX = B

## 2 Douglas- Rachford Splitting

In the noiseless case we can use DRS to solve this numerically via a fixed-point iteration:

$$z^{(k+1)} = z^{(k)} + Prox_{\gamma g} \Big( 2Prox_{\gamma f}(z^{(k)}) - z^{(k)} \Big) - Prox_{\gamma g}(z^{(k)})$$

We know that for  $f = \delta_C$  with  $C = \{X | AX = B\}$  we obtain

$$Prox_{\gamma f}(x) = \Pi_C(x) = x + A^+(b - Ax)$$
  
=  $x + A^T(AA^T)^{-1}(b - Ax)$   
=  $x + A^T(b - Ax)$ 

and via the SVD

$$Prox_{\gamma g}(x) = US_{\delta}(\sigma(x))V^{T}$$
$$= U(\sigma(x) - \gamma)_{+}V^{T}$$

## 3 FISTA

In the noisy case we are trying to minimize the following objective (in the Lagrangian formulation):

$$\min_{X} \lambda ||X||_* + \frac{1}{2} ||AX - B||_2^2$$

The FISTA algorithm is formulated with respect to the following objective:

$$\min_{X} f(x) + g(x)$$

where we assume f and g to be sufficiently smooth, i.e.  $f \in C^{1,1}(\mathbb{R}^n)$ , which means

$$\exists L(f): ||\nabla f(x) - \nabla f(y)|| \le ||x - y|| \forall x, y \in \mathbb{R}^n$$

In our case we have  $f(x)=\frac{1}{2}||AX-B||_2^2$  and  $g(x)=\lambda||X||_*$  and by simple calculation:  $L(f)=2\lambda_{max}(A^TA)$ 

## Algorithm 1 FISTA with constant step size

**Input** Lipschitz- constant L(f) of  $\nabla f$ ,  $y_1 = x_0 \in \mathbb{R}^n$ ,  $t_1 = 1$ 

- 1: **for** k = 1, ... **do**
- $x_k = p_L(y_k)$
- $t_{k+1} = \frac{1+\sqrt{1+4*t_k^2}}{2}$   $y_{k+1} = x_k + \frac{t_k-1}{t_{k+1}}(x_k x_{k-1})$

In this algorithm we def.

$$Q_L(x,y) = f(y) + \langle x - y, \nabla f(y) \rangle + \frac{L(f)}{2} ||x - y||^2 + g(x)$$

$$p_L(y) = \underset{x}{\operatorname{arg min}} Q_L(x,y)$$

$$= \underset{x}{\operatorname{arg min}} \left( g(x) + \frac{L(f)}{2} \left\| x - \left( y - \frac{1}{L} \right) \right\|^2 \right)$$

$$= Prox_{1/Lg}(y - \frac{1}{L} \nabla f(y))$$

To simplify this expression further, we examine the the SVD of the input matrix of  $p_L$ , which we call B for now. It turns out we arrive at a singular value thresholding step: Let  $B = U\Sigma V^T = Udiag(\sigma(b))V^T$  and

$$Prox_{\lambda g}(B) = Udiag(\sigma(B) - \lambda)_{+}V^{T}$$

which finally reveals  $Prox_{1/Lg}\Big(y-\frac{1}{L}\nabla f(y)\Big)=Udiag\Big(\sigma(y-\frac{1}{L}\nabla f(y))-\frac{1}{L}\Big)_{\perp}V^T$ 

I'm not sure if this is correct