Physics-Informed Neural Networks

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Group Exl at MMM (Uni Vie) "Math. Machine Learning"

- MMM: Development of innovative resource-saving / environmentally friendly (magnetic) materials and materials in biology/medicine. (4 Faculties involved)
- Synergy with FWF projects like P31140 and P35413
- Development of num. Methods in "Computational & Data Science"
- Esp. data-driven Reduced Order Approaches in Micromagnetism
- Efficient solution of PDEs (with ML)

Partial Differential Equations

- fluid dynamic
- heat diffusion
- electromagnetism
- celestial mechanics
- quantum mechanics
- etc.

$$\rho(\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u}) = \nabla p + \rho g + \mu \Delta \mathbf{u}$$

$$\frac{\partial \mathbf{u}}{\partial t} = c \Delta \mathbf{u}$$

$$\nabla \cdot \mathbf{D} = \rho_{v}$$

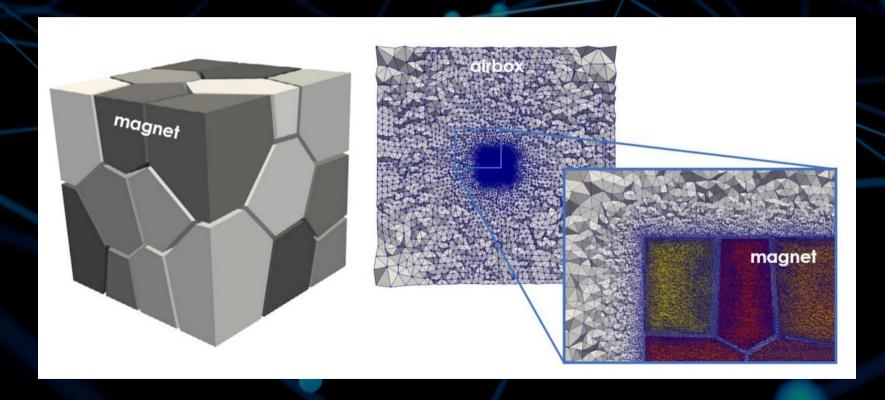
$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t} + \mathbf{J}$$

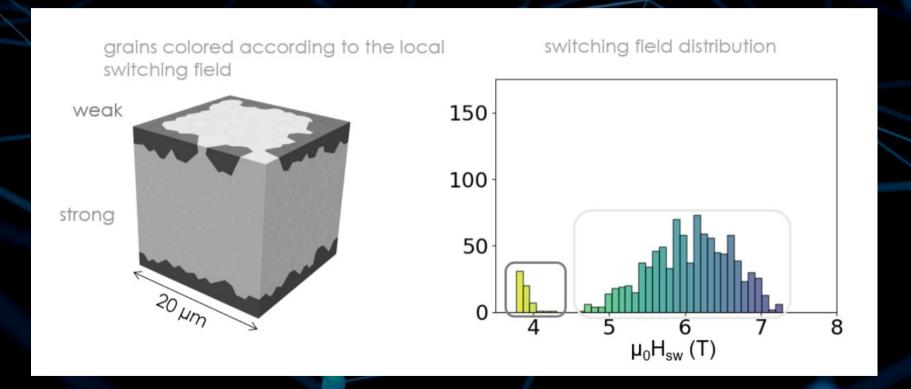
$$i\hbar \frac{\partial \Psi}{\partial t} = \hat{H}\Psi$$

Numerical Magnetism

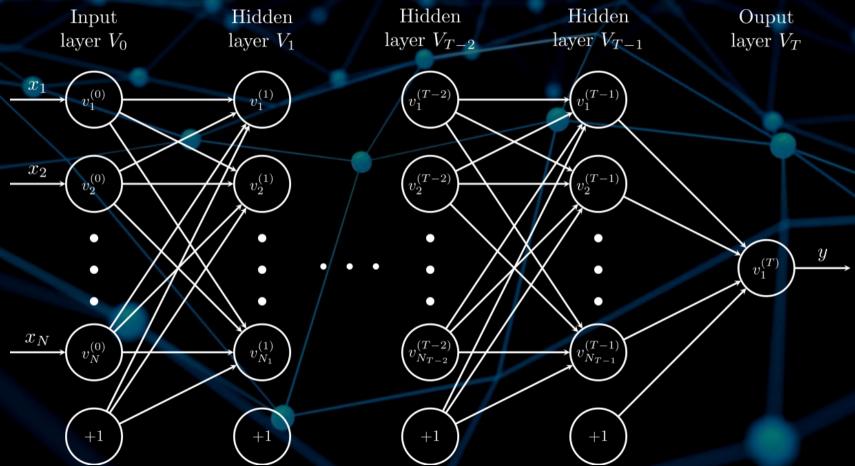


Exl, Lukas, et al. "Magnetic microstructure machine learning analysis." Journal of Physics: Materials 2.1 (2018): 014001.

Numerical Magnetism



Neural Networks



Supervised

Training samples

$$\{x_1,...,x_n\}$$
 $\{y_1,...,y_n\}$

Minimize objective

$$MSE(\omega) = \frac{1}{n} \sum_{i=1}^{n} (\mathcal{N}(\boldsymbol{x}_i; \omega) - y_i)^2 o min_{\omega}!$$

Physics-Informed (unsupervised)

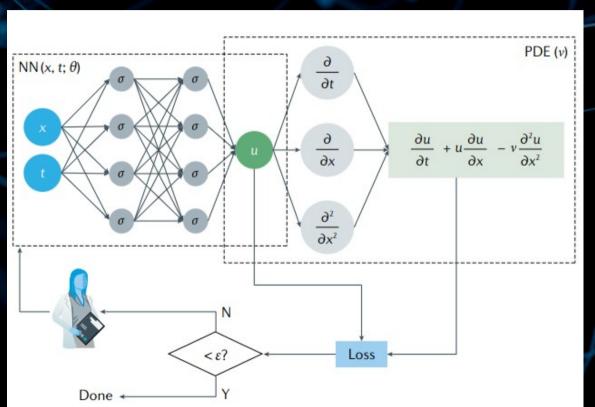
Training samples

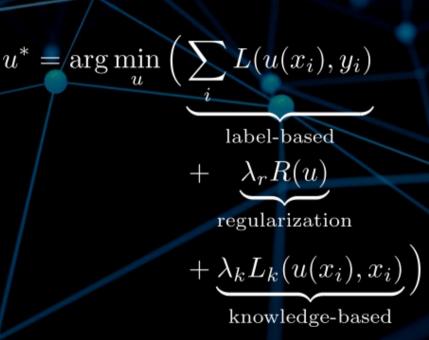
$$\{X_1,\ldots,X_n\}$$

 Minimize physics informed objective

$$MSE(\omega) = \frac{1}{n} \sum_{i=1}^{n} (\mathcal{N}(\boldsymbol{x}_i; \omega) - y_i)^2 \rightarrow min_{\omega}! \quad \frac{1}{n} \sum_{i=1}^{n} L(\mathcal{N}(\boldsymbol{x}_i; \omega)) + \text{Penalty}(\omega) \rightarrow min_{\omega}!$$

Physics-Informed Neural Networks





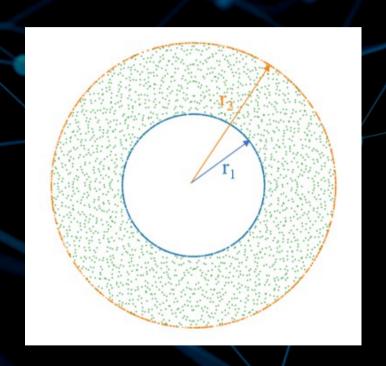
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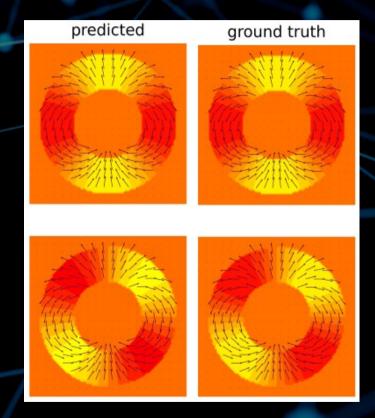
Stray Field Problem

$$\begin{split} -\Delta\phi &= -\nabla \cdot \boldsymbol{m} \quad \text{in } \Omega \subset \mathbb{R}^3, \\ -\Delta\phi &= 0 \quad \text{in } \overline{\Omega}^c, \\ [\phi] &= 0 \quad \text{in } \partial\Omega, \\ \left[\frac{\partial\phi}{\partial\boldsymbol{n}}\right] &= -\boldsymbol{m} \cdot \boldsymbol{n} \quad \text{in } \partial\Omega, \\ \phi(\boldsymbol{x}) &= \mathcal{O}\left(\frac{1}{\|\boldsymbol{x}\|_2}\right) \quad \text{as } \|\boldsymbol{x}\|_2 \to \infty. \quad \phi_2^*(\boldsymbol{x}) = \int_{\partial\Omega} \left(\frac{(\boldsymbol{m} \cdot \boldsymbol{n} - \frac{\partial}{\partial_n}\phi_1)(\boldsymbol{y})}{4\pi \|\boldsymbol{x} - \boldsymbol{y}\|_2}\right) d\sigma(\boldsymbol{y}) \end{split}$$

Exl, Lukas, and Thomas Schrefl. "Non-uniform FFT for the finite element computation of the micromagnetic scalar potential." Journal of Computational Physics 270 (2014): 490-505.

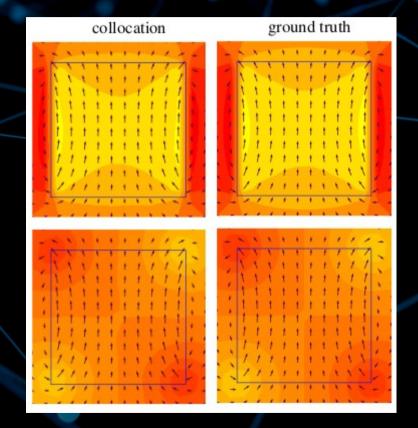
Physics-Informed Neural Networks





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Physics-Informed Neural Networks



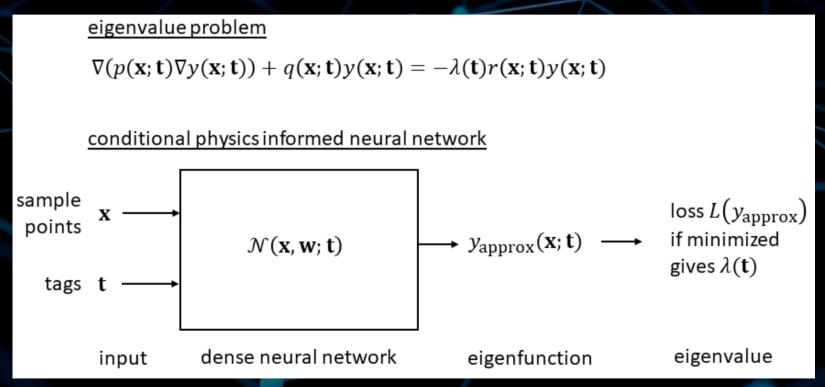
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Constraints

- Soft constraints
 - minimize the initial and/or boundary error of the model
- Hard constraints
 - initial/boundary conditions are enforced on the model

$$tu(x,t) = 0$$
 at $t = 0$

Conditional Physics-Informed Neural Networks

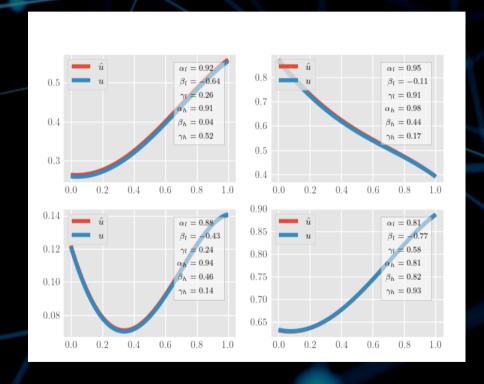


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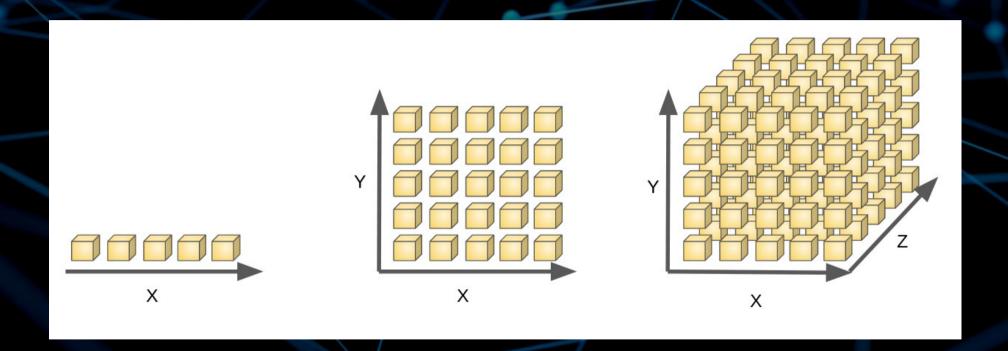
Conditional Physics-Informed Neural Networks

$$\begin{split} \frac{d^2u(x)}{dx^2} &= 1 - 2x^2\\ \alpha_l u(x) + \beta_l \frac{d^2u(x)}{dx^2} &= \gamma_l \quad \text{at } x = 0,\\ \alpha_h u(x) + \beta_h \frac{d^2u(x)}{dx^2} &= \gamma_h \quad \text{at } x = 1, \end{split}$$

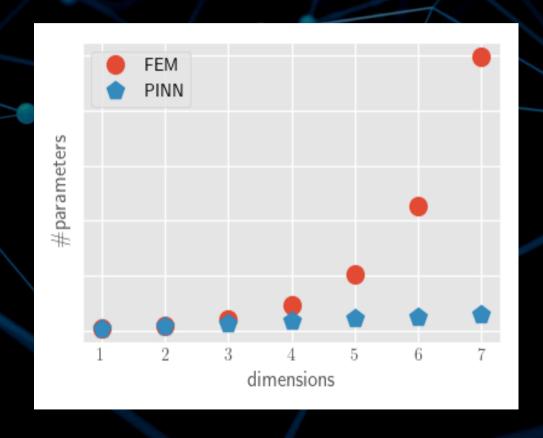
for $x \in [0, 1]$, $\alpha_l \in [0.8, 1]$, $\beta_l \in [-1, 0]$, $\gamma_l \in [0, 1]$, $\alpha_h \in [0.8, 1]$, $\beta_h \in [0, 1]$ and $\gamma_h \in [0, 1]$



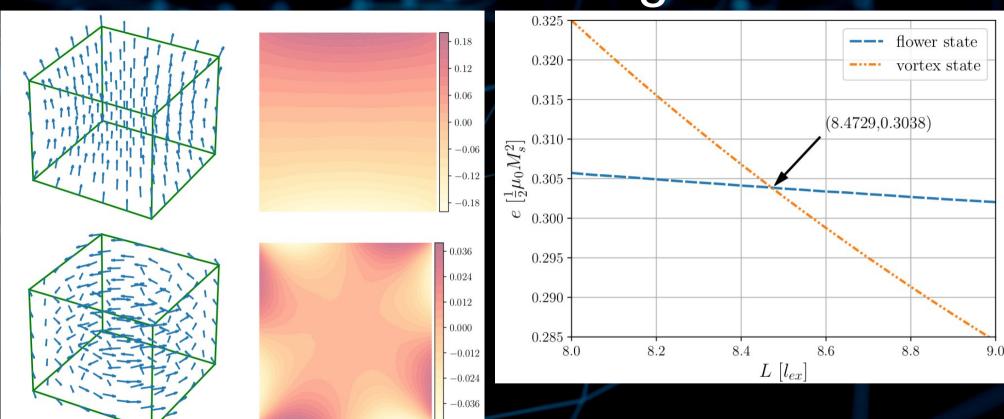
Curse of Dimensionality



Curse of Dimensionality

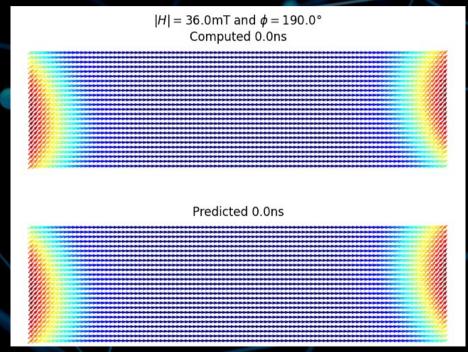


PINNs in Micromagnetism



Schaffer, Sebastian, et al. "Physics-informed machine learning and stray field computation with application to micromagnetic energy minimization." arXiv preprint arXiv:2301.13508 (2023).

PINNs in Micromagnetism

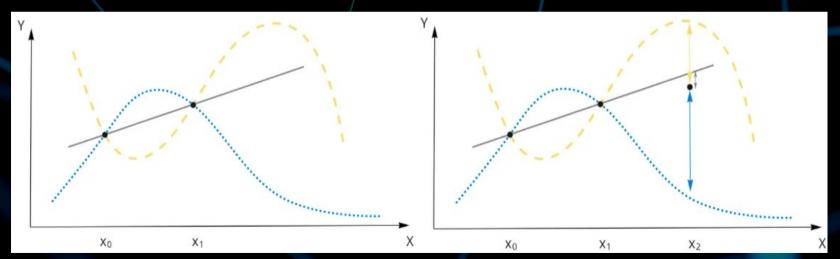


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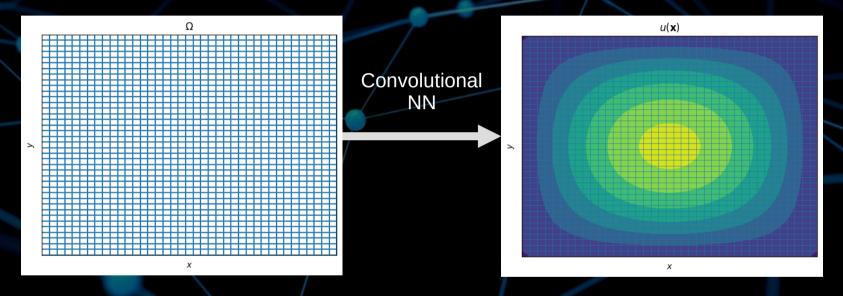
Inductive Bias

- Inductive reasoning refers to generalization from specific observations to a conclusion.
- The less training data we have, the stronger inductive bias should be to help the model to generalize well.
- Choosing a model with the right bias boosts chances of finding a better generalization with less data



https://towardsdatascience.com/the-inductive-bias-of-ml-models-and-why-you-should-care-about-it-979fe02a1a56

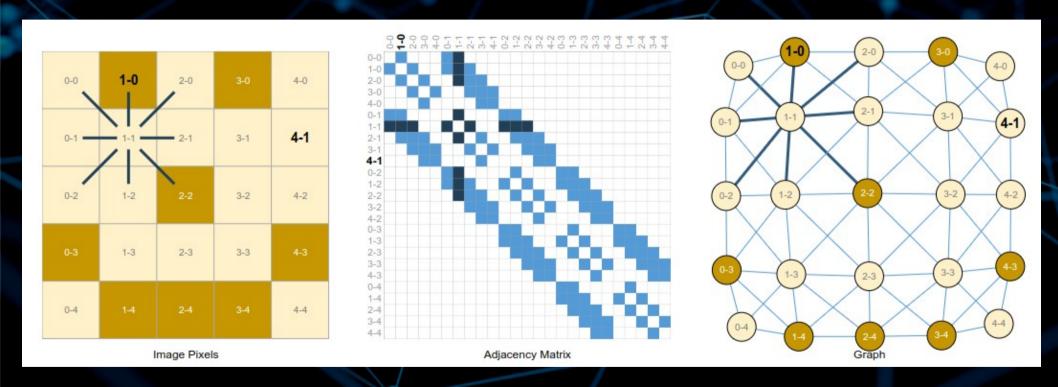
Physics-Informed Convolutional Networks



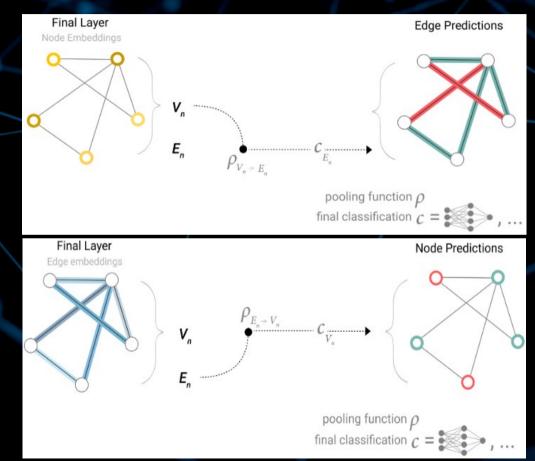
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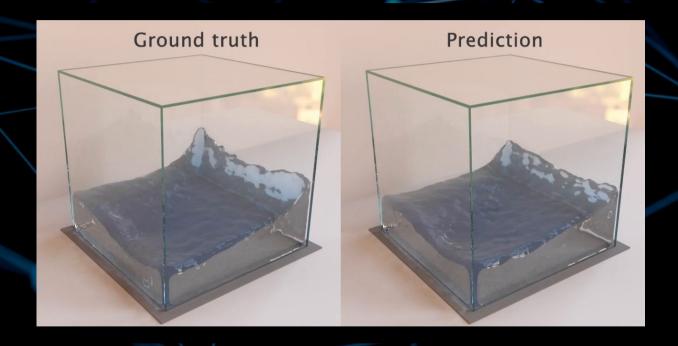
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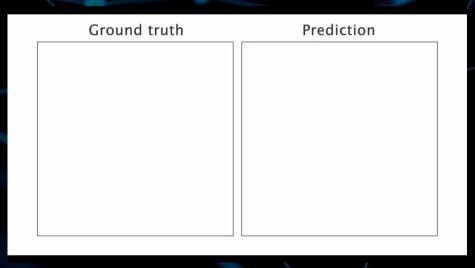


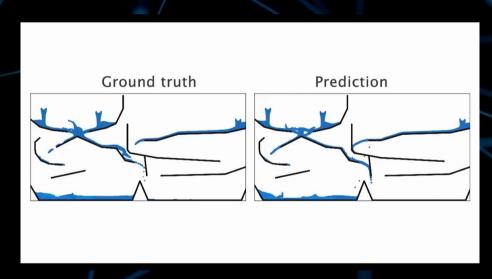
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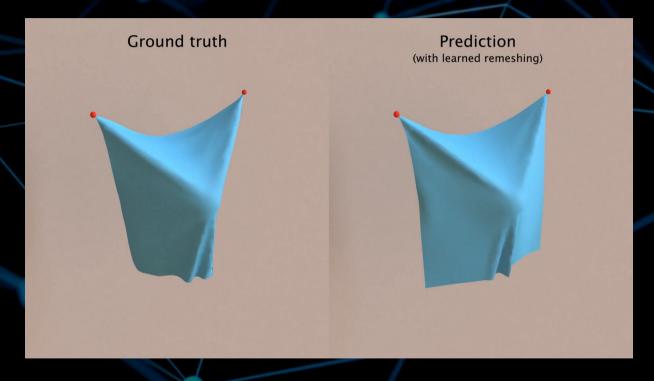




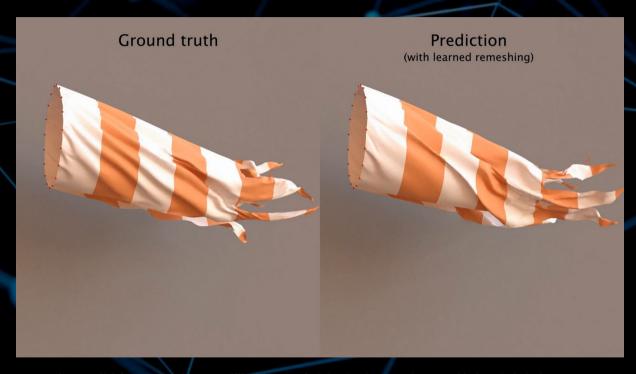
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Current Research

- Domain Decomposition
- Importance sampling
- Optimization method in PINN training (e.g. stoch.)
 Versions of trust region methods and L-BFGS)
- Conditional PINNs in Micromagnetism
- Time-dependent PDEs

Acknowledgements

- Austrian Science Fund (FWF) via project
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