

# Transductive Bounds for the Multi-class Majority Vote Classifier

**Vasilii Feofanov,** Emilie Devijver, Massih-Reza Amini

University Grenoble Alpes, Grenoble INP  
LIG, CNRS, Grenoble 38000, France  
(firstname.lastname@univ-grenoble-alpes.fr)

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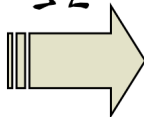
# Introduction

In many applications, labeling examples is prohibitive while huge number of unlabeled data are available.

$$Z_{\mathcal{L}} = \{(\mathbf{x}_i, y_i)\}_{i=1}^l$$



$$X_{\mathcal{U}} = \{\mathbf{x}_i\}_{i=l+1}^{l+u}$$



Classifier:  
 $\mathcal{X} \rightarrow \mathcal{Y}$

Goal:  
Small classification error



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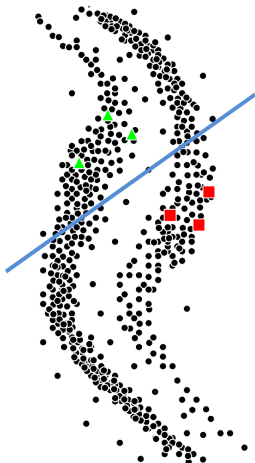
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# Introduction

Problem: Supervised learning is not efficient to use.



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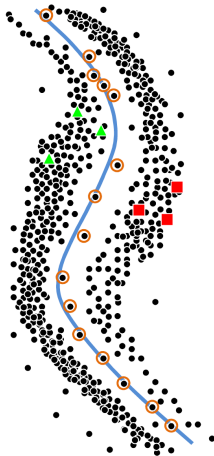
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Solution: Classifier that pass through the low density regions of **both** labeled and unlabeled examples.



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# Related Work and Motivation

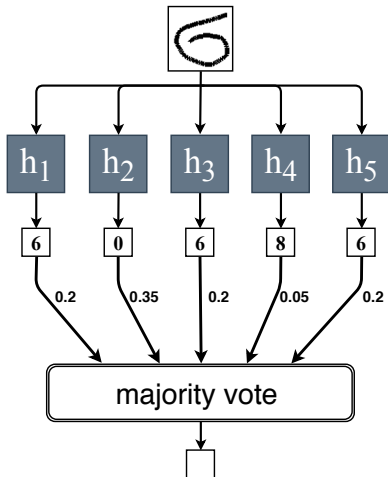
- We consider the transductive inference.  
The self-learning algorithm (SLA) is based on this paradigm. In [Amini et al., 2008] it was proposed to find a threshold for the **binary** SLA dynamically using a risk bound.
- PAC-Bayesian theorems [McAllester, 1999] bound risk of Gibbs and Bayes classifiers. Most of study is devoted to the binary framework.  
[Morvant et al., 2012] considers the multi-class case in the **supervised** setting.

In this work, we propose:

1. **Transductive** bounds of the Bayes classifier,
2. A **multi-class** extension of the self-learning algorithm.

# Bayes Classifier

$$B_Q(\mathbf{x}) := \operatorname{argmax}_{c \in \mathcal{Y}} [\mathbb{E}_{h \sim Q} \mathbb{1}_{h(\mathbf{x})=c}]$$



Input	$\mathbf{X}$
Hypothesis Space	$H$
Prediction	
Posterior	$Q$
Voting	
Output	$y$

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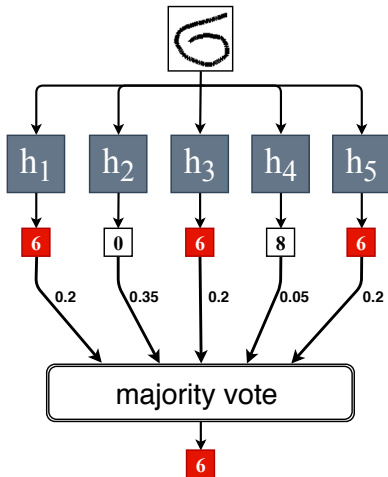
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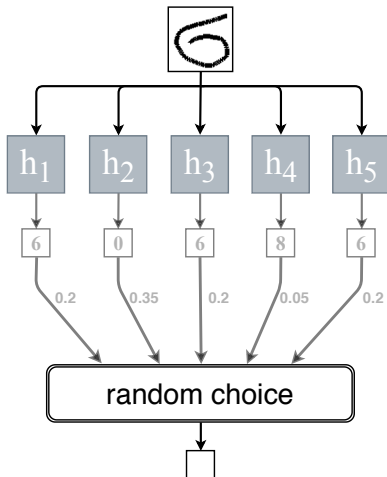
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# Gibbs Classifier

$$G_Q(\mathbf{x}) := \text{rand}_{h \sim Q} h(\mathbf{x})$$



Input	$\mathbf{X}$
Hypothesis Space	$H$
Prediction	
Posterior	$Q$
Rand Choice Acc. to $Q$	
Output	$y$

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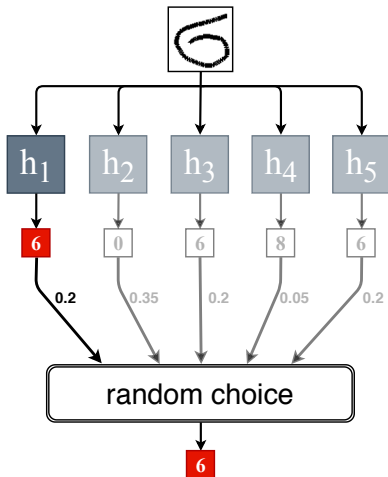
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# Gibbs Classifier

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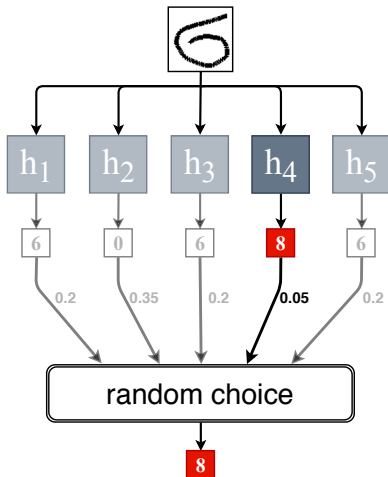
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# Gibbs Classifier

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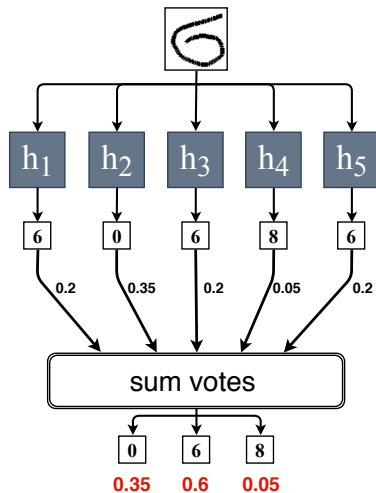
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# Margin: Indicator of Confidence

$$m_Q(\mathbf{x}, c) = \mathbb{E}_{h \sim Q} \mathbb{1}_{h(\mathbf{x})=c}$$



Input
$\mathbf{X}$
Hypothesis Space
$H$
Prediction
Posterior
$Q$
Voting
Margin
$\mathbf{m}_Q$

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# Error Measures

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- $R_{\mathcal{U}}(B_Q, i, j) := \frac{1}{u_i} \sum_{\mathbf{x}' \in X_{\mathcal{U}}} \mathbb{1}_{B_Q(\mathbf{x}')=j} \mathbb{1}_{y'=i},$
- $R_{\mathcal{U}}(G_Q, i, j) := \frac{1}{u_i} \sum_{\mathbf{x}' \in X_{\mathcal{U}}} \mathbb{E}_{h \sim Q} \mathbb{1}_{h(\mathbf{x}')=j} \mathbb{1}_{y'=i},$

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# Error Measures

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- $E_{\mathcal{U}}(h) := \frac{1}{u} \sum_{\mathbf{x}' \in X_{\mathcal{U}}} \mathbb{1}_{h(\mathbf{x}') \neq y'},$  – error rate
- $\mathbf{C}_h^{\mathcal{U}} := (R_{\mathcal{U}}(h, i, j))_{i,j=\{1,\dots,K\}^2, i \neq j},$  – [Morvant et al., 2012]

- $R_{\mathcal{U}}(B_Q, i, j) := \frac{1}{u_i} \sum_{\mathbf{x}' \in X_{\mathcal{U}}} \mathbb{1}_{B_Q(\mathbf{x}')=j} \mathbb{1}_{y'=i},$
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- $E_{\mathcal{U}}(h) := \frac{1}{u} \sum_{\mathbf{x}' \in X_{\mathcal{U}}} \mathbb{1}_{h(\mathbf{x}') \neq y'},$
- $\mathbf{C}_h^{\mathcal{U}} := (R_{\mathcal{U}}(h, i, j))_{i, j = \{1, \dots, K\}^2, i \neq j},$
- $R_{\mathcal{U} \wedge \theta}(B_Q, i, j) := \frac{1}{u_i} \sum_{\mathbf{x}' \in X_{\mathcal{U}}} \mathbb{1}_{B_Q(\mathbf{x}')=j} \mathbb{1}_{y'=i} \mathbb{1}_{m_Q(\mathbf{x}', j) \geq \theta_j},$ 
  - risk to have the conditional error and the margin above  $\theta_j$

# A Transductive Bound for the Conditional Risk

## Theorem

$\forall Q$  and  $\forall \delta \in (0, 1]$ ,  $\forall \theta \in [0, 1]^K$  with prob. at least  $1 - \delta$ :

$$R_{\mathcal{U} \wedge \theta}(B_Q, i, j) \leq \inf_{\gamma \in [\theta_j, 1]} \left\{ I_{i,j}^{(\leq, <)}(\theta_j, \gamma) + \frac{1}{\gamma} \left[ (K_{i,j}^\delta - M_{i,j}^{<}(\gamma) + M_{i,j}^{<}(\theta_j)) \right]_+ \right\},$$

where

- $K_{i,j}^\delta = R_u^\delta(G_Q, i, j) - \varepsilon_{i,j}$ ,
- $R_u^\delta(G_Q, i, j)$  is an upper bound that holds with prob. at least  $1 - \delta$ .
- $\varepsilon_{i,j}$  is the average of  $j$ -margins in class  $i$  and class  $j$  is not predicted,
- $I_{i,j}^{(\leq, <)}(\theta_j, \gamma)$  is proportion of obs. from  $i$  with margin in interval  $[\theta_j, \gamma)$ ,
- $M_{i,j}^{<}(t)$  is the average of  $j$ -margins in class  $i$  that less than  $t$ .



# A Transductive Bound for the Conditional Risk

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## Proof

- Bound derived from a solution of a linear program where the error is maximized.
- Constraint: connection between  $R_{\mathcal{U} \wedge \theta}(B_Q, i, j)$  and  $R_u(G_Q, i, j)$ .
- The solution of linear program is explicit and is computed in practice.

## Theorem: Remarks

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## Proposition

*Suppose*

- The Gibbs conditional risk bound is tight,
- The Bayes classifier makes its mistakes mostly on examples with low margins

$\Rightarrow$  the bound is **tight**.



# Conditional Bayes Error

We look for  $\theta$  that minimizes:

$$E_{\mathcal{U}|\theta}(B_Q) := \frac{E_{\mathcal{U} \wedge \theta}(B_Q)}{\pi(m_Q(\mathbf{x}', B_Q(\mathbf{x}')) \geq \theta_{B_Q(\mathbf{x}')})}.$$

A **trade-off** between:

- Transductive error on pseudo-labeled examples (estimated using **Theorem**),
- Proportion of pseudo-labeled examples in  $X_{\mathcal{U}}$ .

# Multi-class Self-learning Algorithm

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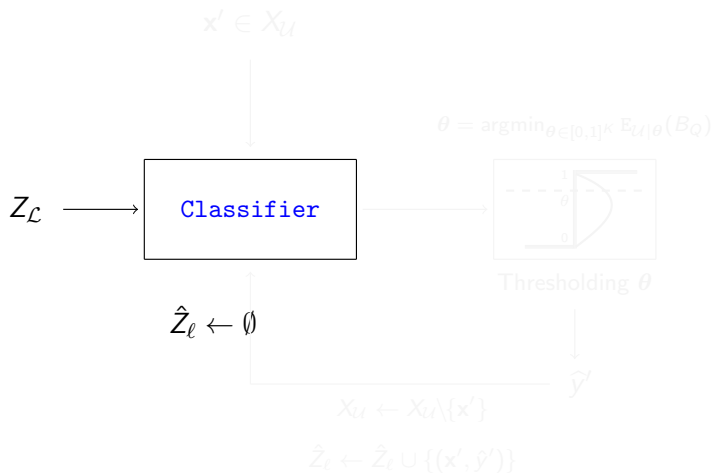
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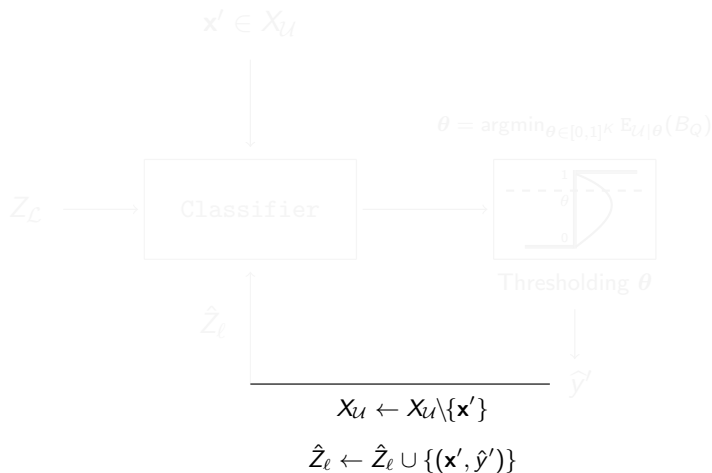


## Multi-class Self-learning Algorithm

## Transductive Bounds for the Multi-class Majority Vote Classifier

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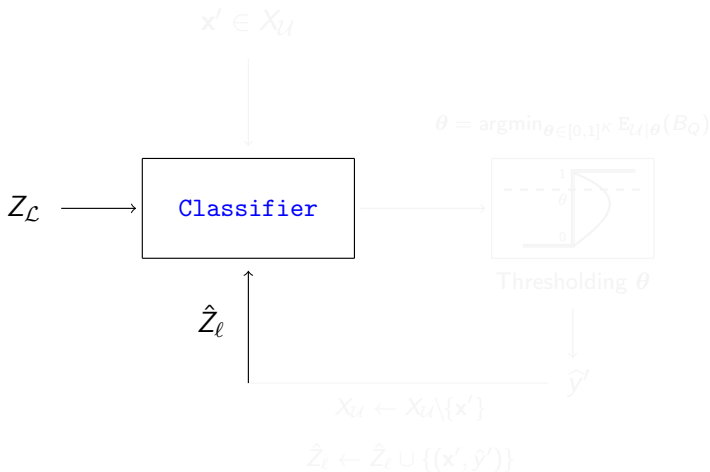
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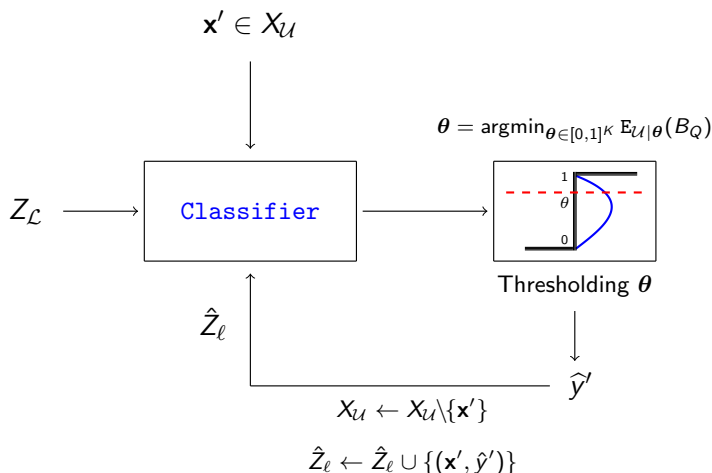
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## Experiment Results on Different Data Sets

## Transductive Bounds for the Multi-class Majority Vote Classifier

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Data set	Info	Score	RF	LP	OVA-TSVM	FSLA $\theta=0.7$	MSLA
Vowel	$l = 99$	ACC	$.583 \pm .026$	$.577 \pm .027$	NA	$.516^{\downarrow} \pm .043$	$.592 \pm .027$
	$u = 891$ $d = 10$ $K = 11$	F1	$.572 \pm .028$	$.568 \pm .026$	NA	$.493^{\downarrow} \pm .046$	$.580 \pm .030$
DNA	$l = 31$	ACC	$.693^{\downarrow} \pm .072$	$.538^{\downarrow} \pm .039$	$.812 \pm .039$	$.516^{\downarrow} \pm .09$	$.706^{\downarrow} \pm .083$
	$u = 3155$ $d = 180$ $K = 3$	F1	$.65^{\downarrow} \pm .109$	$.535^{\downarrow} \pm .044$	$.812 \pm .038$	$.372^{\downarrow} \pm .096$	$.663^{\downarrow} \pm .118$
Pendigits	$l = 109$	ACC	$.864^{\downarrow} \pm .022$	$.777^{\downarrow} \pm .052$	$.667^{\downarrow} \pm .023$	$.847^{\downarrow} \pm .035$	$.887 \pm .019$
	$u = 10883$ $d = 16$ $K = 10$	F1	$.861^{\downarrow} \pm .025$	$.756^{\downarrow} \pm .069$	$.656^{\downarrow} \pm .021$	$.842^{\downarrow} \pm .042$	$.885 \pm .02$
MNIST	$l = 175$	ACC	$.865^{\downarrow} \pm .018$	NA	NA	$.8^{\downarrow} \pm .059$	$.909 \pm .018$
	$u = 69825$ $d = 900$ $K = 10$	F1	$.863^{\downarrow} \pm .019$	NA	NA	$.774^{\downarrow} \pm .077$	$.909 \pm .018$
SensIT	$l = 49$	ACC	$.67 \pm .0291$	NA	NA	$.619^{\downarrow} \pm .037$	$.675 \pm .029$
	$u = 98479$ $d = 100$ $K = 3$	F1	$.654 \pm .045$	NA	NA	$.578^{\downarrow} \pm .068$	$.66 \pm .042$

## Application

**Table:** Classification performance on 5 data sets.

↓: the performance is statistically worse than the best result on the level 0.01 of significance.

NA: the algorithm does not converge.

- Proposed transductive bounds for the Bayes classifier, which are tight under certain conditions.
- Self-learning with automatic threshold finding shows promising results for semi-supervised tasks.
- Future perspective: self-learning with semi-supervised feature selection.

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## Conclusion and Perspectives

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The source code:

[github.com/vfeofanov/trans-bounds-maj-vote](https://github.com/vfeofanov/trans-bounds-maj-vote)

# Conclusion and Perspectives

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