FreeBSD package management system

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- Binary packages management
- Replaces old pkg_* tools
- Uses central sqlite3 based storage
- Provides the comprehensive toolset for binary packages management

The main goal of pkg is to simplify system management tasks.

▶ Easy install, remove and upgrade of binary packages

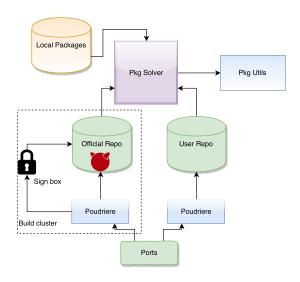
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- Integration with the **ports** (easily adopted for other source management systems, e.g. pkgsrc)
- Automatic resolving of dependencies and conflicts
- Encourage users to install software from binary packages
- ...but do not prevent users from building custom packages using the **ports**

Ports management using pkg



 Dependencies and conflicts solver that can automatically resolve complex upgrade or install scenarios

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- Improved security by sandboxing (Capsicum) untrusted operations:



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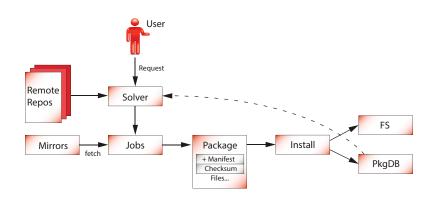


Sandboxing:

- archives extracting
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- repositories signatures checking and public keys extracting
- Concurrent locking system



Pkg architecture





The problems of the old solver in pkg

Absence of conflicts resolving



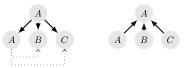
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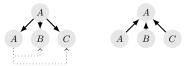
The problems of the old solver in pkg

- Absence of conflicts resolving
- No alternatives support (plain dependencies only)
- Can perform merely a single task: either install or upgrade or remove

- Ports renaming:
 - ▶ simple: racket-textual → racket-minimal
 - splitting/merging:



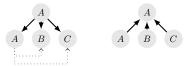
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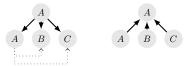


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- Ports reorganising:
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 - adding or removing new conflicts



There are another issues to be resolved:

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- Set jobs priorities using the following rules:
 - ▶ install **dependencies** first



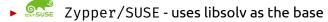
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 - deal with conflicts using the same priority
 - packages removing reverses the priority order

Existing systems

There are many examples of solvers used in different package management systems, for example:



Yum/RedHat - migrating to libsolv

OpenBSD/pkg_add - uses internal solver

Apt/Debian - uses internal solver

Pacman/Archlinux - uses internal solver



External solvers

To interact with an external solver we have chosen the CUDF format used in the Mancoosi research project http://mancoosi.org:

```
^^Ipackage: devel/libblah
```

^^Iversion: 1

^^Idepends: x11/libfoo

```
^^Ipackage: security/blah
```

^^Iversion: 2

^^Idepends: devel/libblah

^^Iconflicts: security/blah-devel

^^I



Interaction with external solver

There are some limitations and incompatibilities with CUDF.

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There are some limitations and incompatibilities with CUDF.

- CUDF supports plain integers as versions and we need to convert versions twice
- ▶ There is no support of options in CUDF packages formulas
- External solvers are often too complicated and large

We need an internal solver!

Alternatives:

Write own logic of dependencies and conflicts resolution?

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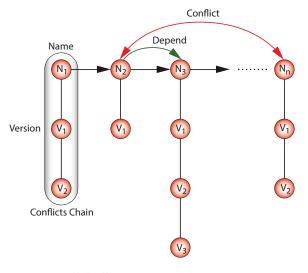
Use SAT solver for packages management

$$\underbrace{\underbrace{(x_1 \| \neg x_2 \| x_3)}_{\text{Clause}} \& (x_3 \| \neg x_1) \& (x_2)}^{\text{SAT expression}}$$



Packages universe

We convert all packages involved to a packages universe of the following structure:



Making a SAT problem

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 - ▶ Install/Upgrade package A \rightarrow (a_1)
 - ▶ Delete package B $\rightarrow (\neg b_1)$
- Convert dependencies and conflicts to disjuncted clauses

Converting dependencies and conflicts

If package A depends on package B (versions B₁ and B₂), then we can either have package A not installed or any of B installed:

$$(\neg A \|B_1\|B_2)$$

Converting dependencies and conflicts

▶ If package A depends on package B (versions B₁ and B₂), then we can either have package A not installed or any of B installed:

$$(\neg A \| B_1 \| B_2)$$

▶ If we have a conflict between versions of B (B_1 , B_2 and B_3) then we ensure that merely one version is installed:

$$\underbrace{(\neg B_1 \| \neg B_2) \& (\neg B_1 \| \neg B_3) \& (\neg B_2 \| \neg B_3)}_{\text{Conflicts chain}}$$



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- Unit propagation solve clauses with only a single unsolved variable
- DPLL algorithm backtracking (conflict driven resolution is used now)
- Package specific assumptions.

SAT problem propagation

Trivial propagation - direct install or delete rules

$$(\neg A \parallel B) \& \underbrace{(A)}_{true} \& \underbrace{(\neg C)}_{false} \& (\neg A \parallel \neg D)$$

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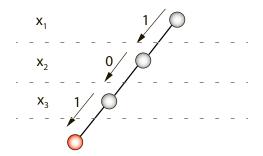
Unit propagation - simple depends and conflicts

$$\underbrace{ \begin{pmatrix} \neg A \| B \end{pmatrix}}_{B \to true} \& \underbrace{ \begin{pmatrix} A \end{pmatrix}}_{CA} \& \underbrace{ \begin{pmatrix} \neg C \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{CA} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{CA} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{ \begin{pmatrix} \neg A \| \neg D \end{pmatrix}}_{D \to false} & \underbrace{$$



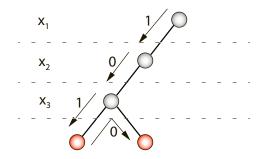
DPLL algorithm

DPLL is proved to be one of the efficient algorithms to solve SAT problem (not the fastest but more simple than alternatives).



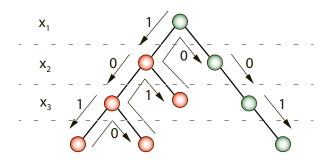
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- Additional logic when dealing with multi-repo

Solvers and Pkg

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 - parse output

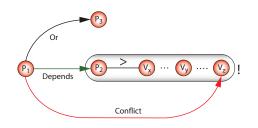
Solvers and Pkg

- Pkg may pass the formed universe to an external CUDF solver:
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 - parse output
- Alternatively the internal SAT solver may be used:
 - convert the universe to SAT problem
 - formulate request
 - ▶ ???
 - PROFIT



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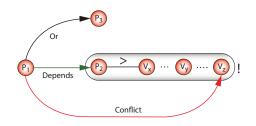
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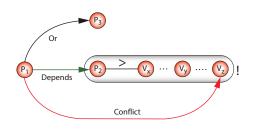
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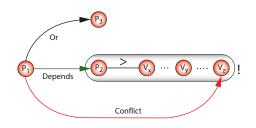
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- Alternative dependencies





Packages format

Uses xz format:

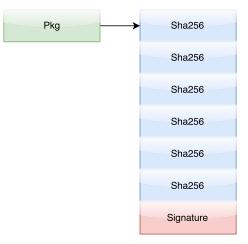
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- Metadata is compressed together with payload (slow index)

Signatures now



Repo





Ed25519 via asignify

For faster index

Plain tar + zstd compression

 Uses zstd compression: very fast and good compressin rate (faster and better than gz)

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- No direct support of libarchive (yet)



Questions?

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