

**MISR UNIVERSITY FOR SCIENCE AND TECHNOLOGY**  
**COLLEGE OF ENGINEERING**  
**MECHATRONICS DEPARTMENT**



# **MTE 405 SENSORS AND MEASUREMENTS**

**LAB 2 – SPRING 2020**

# Goals Of The Lab

A 3D illustration of a target with a red bullseye and concentric rings, with an arrow hitting the center. The target is shown from a slightly elevated, angled perspective, giving it a three-dimensional appearance. The bullseye is a small red circle in the center, surrounded by a white ring, then a red ring, and finally a white outer ring. An arrow with a green fletching and a grey shaft is shown hitting the bullseye. The target is set against a plain white background.



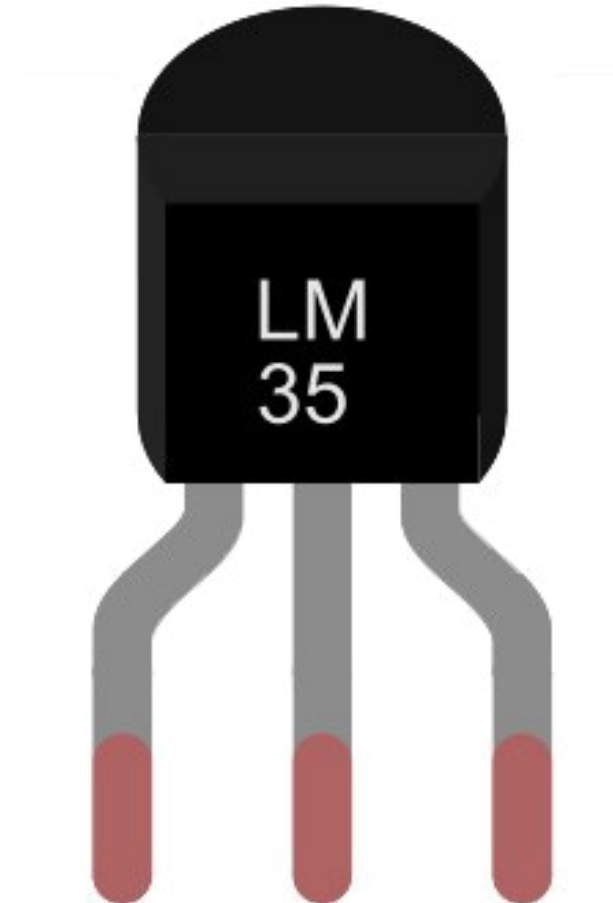
## Lab 2

# Sensing Temperature

Analog sensors

## Learning outcome

- LM35 characteristics.
- Simulation of LM35 on Proteus.
- Improving LM35 range.
- Practical implementation

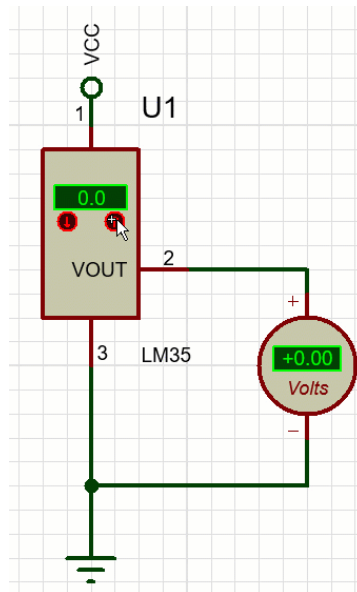


## Lab 2

# Sensing Temperature

LM35

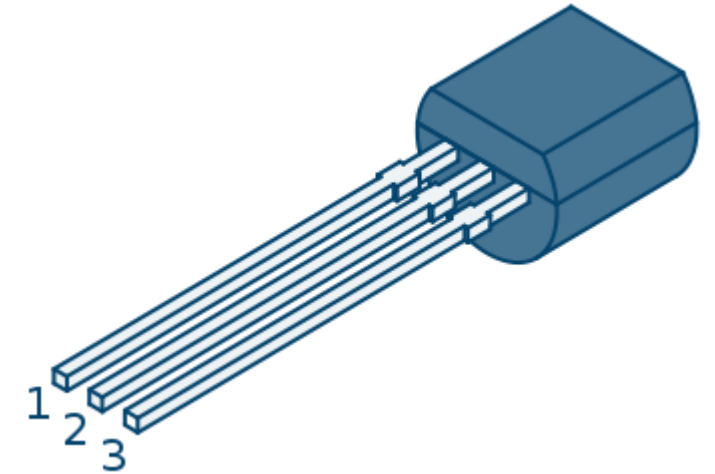
- ✓ Voltage supply : 4 – 30 V
- ✓ Sensitivity : 10 mV / °C
- ✓ Useful range : 2 – 150 °C
- ✓ Less than 50  $\mu$ A



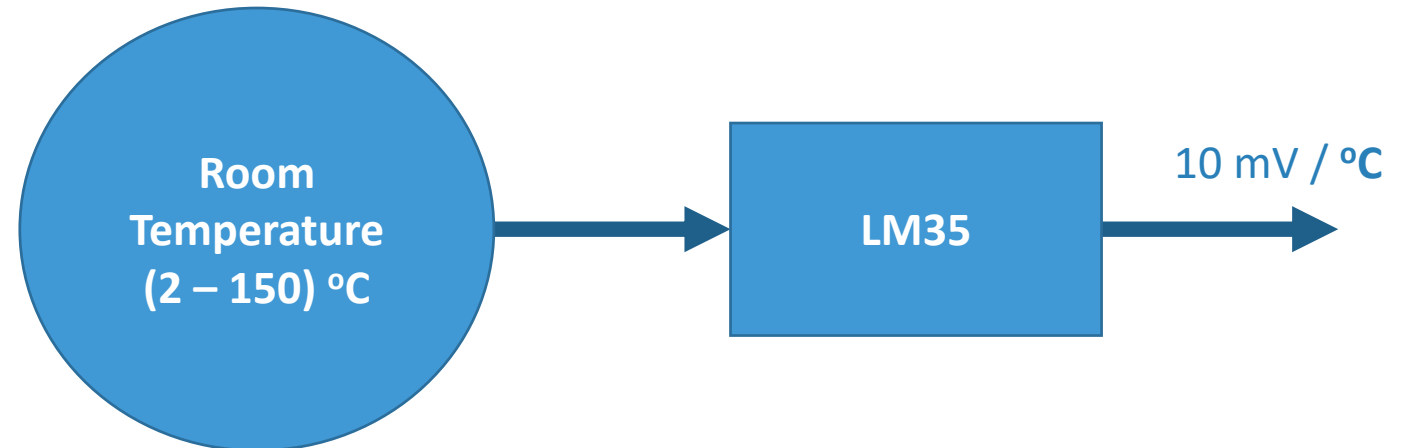
## LM35 Precision Centigrade

### 1 Features

- Calibrated Directly in Celsius (Centigrade)
- Linear + 10-mV/°C Scale Factor
- 0.5°C Ensured Accuracy (at 25°C)
- Rated for Full -55°C to 150°C Range
- Suitable for Remote Applications
- Low-Cost Due to Wafer-Level Trimming
- Operates From 4 V to 30 V
- Less Than 60- $\mu$ A Current Drain
- Low Self-Heating, 0.08°C in Still Air
- Non-Linearity Only  $\pm 1/4^\circ\text{C}$  Typical
- Low-Impedance Output, 0.1  $\Omega$  for 1-mA Load

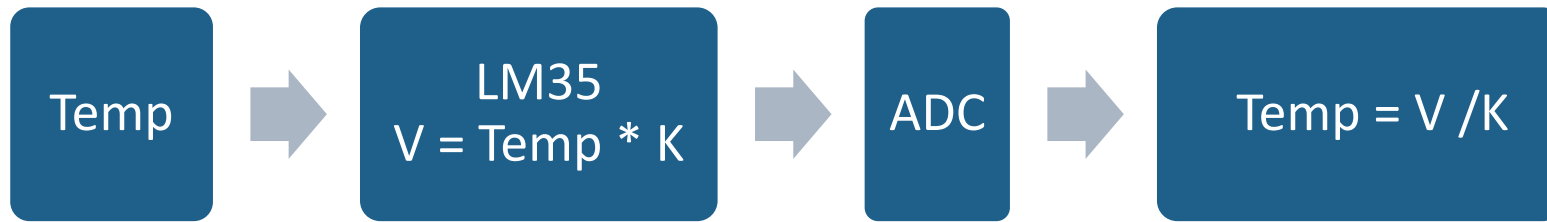


1. Vcc
2. Output
3. Gnd



# Sensing Temperature

LM35



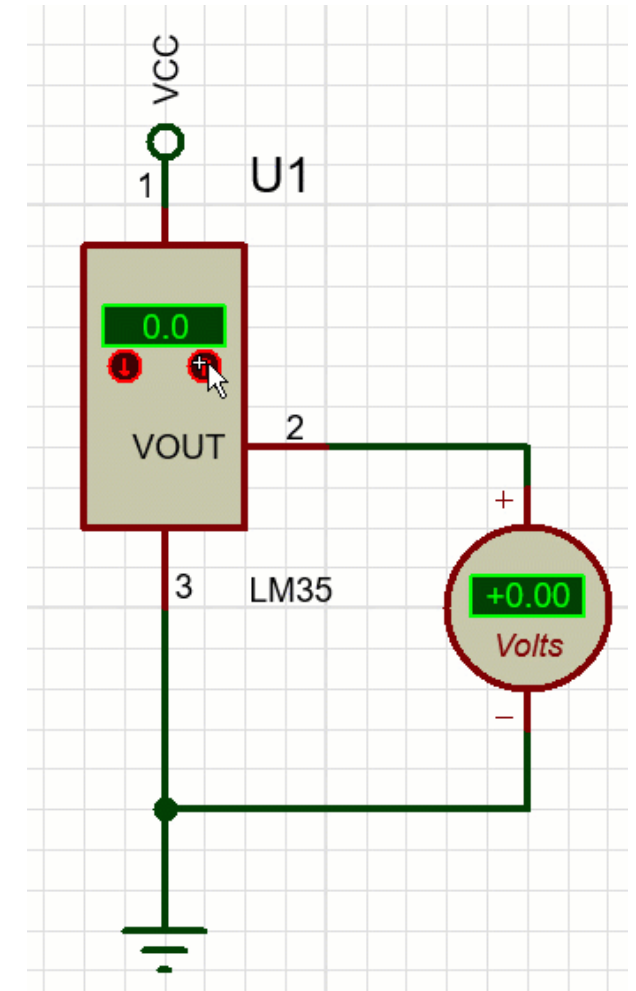
## Acquisition Transfer Function

Where

K .... Conversion factor

And

$$K = (10 \text{ mV} / 1000 \text{ mV})$$

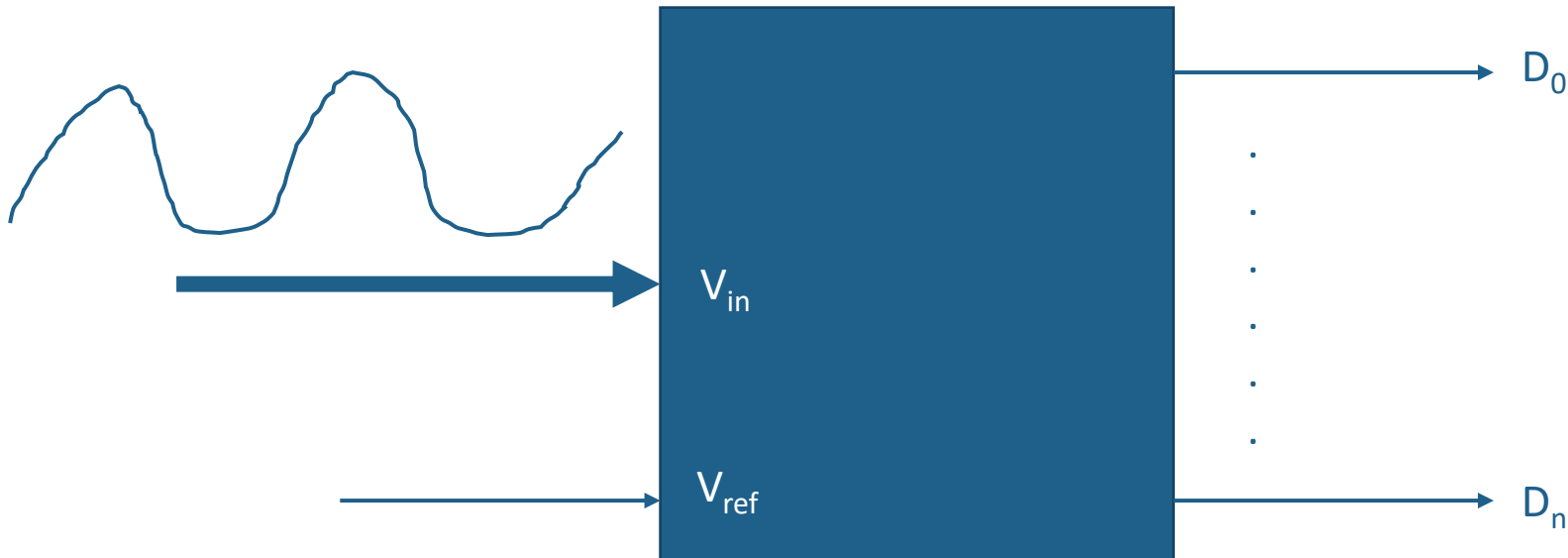


# Improving Sensor Range

Case Study

## PROBLEM DEFINITION

- You wish to build an embedded system for monitoring **temperature** using LM35.
- Your temperature **range** is expected to vary from **5 – 45 °C**
- You have **built-in 10-bit ADC** with **reference** voltage of **5V (resolution?)**.
- You are **assigned** to **improve the voltage range of LM35** to match ADC input voltage range for the input temperature range



$$ADC \text{ Resolution} = \frac{V_{ref}}{2^n}$$

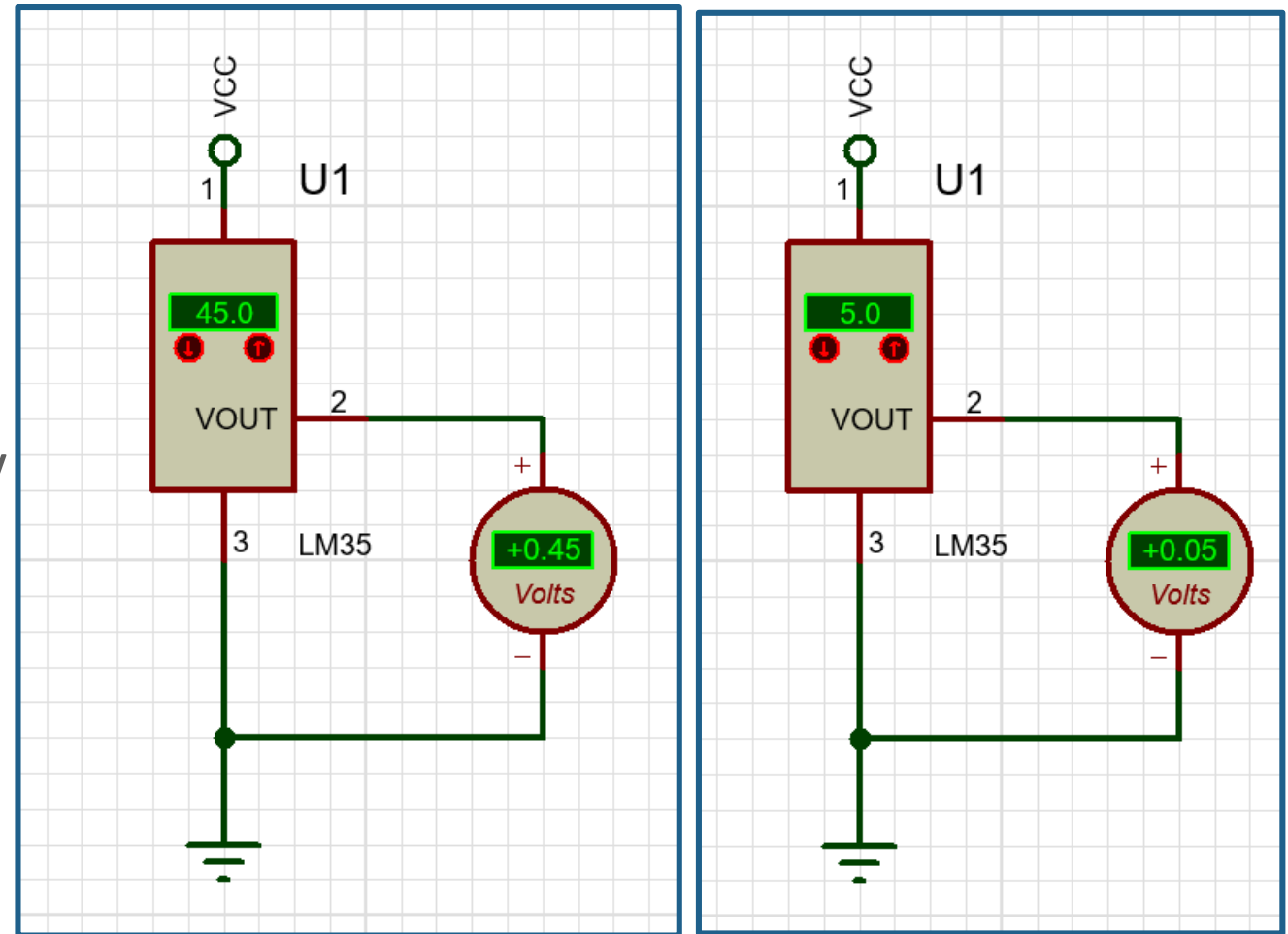
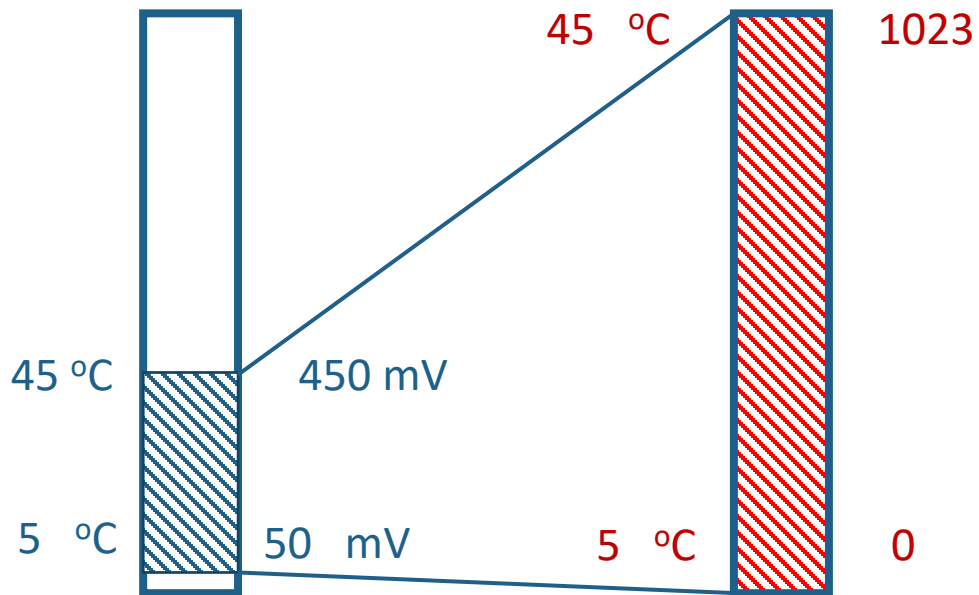
$$Digital \text{ Value} = \frac{V_{in}}{ADC \text{ Resolution} - \mathbf{1}}$$

# Improving Sensor Range

Case Study

## FOR LM35

- At 5 °C  $\rightarrow V_{lm35} = 5 \times 10\text{mV} = 50 \text{ mV}$
- At 45 °C  $\rightarrow V_{lm35} = 45 \times 10\text{mV} = 450 \text{ mV}$



What is the loss percentage in ADC range?

# Improving Sensor Range

## Case Study

### FOR LM35

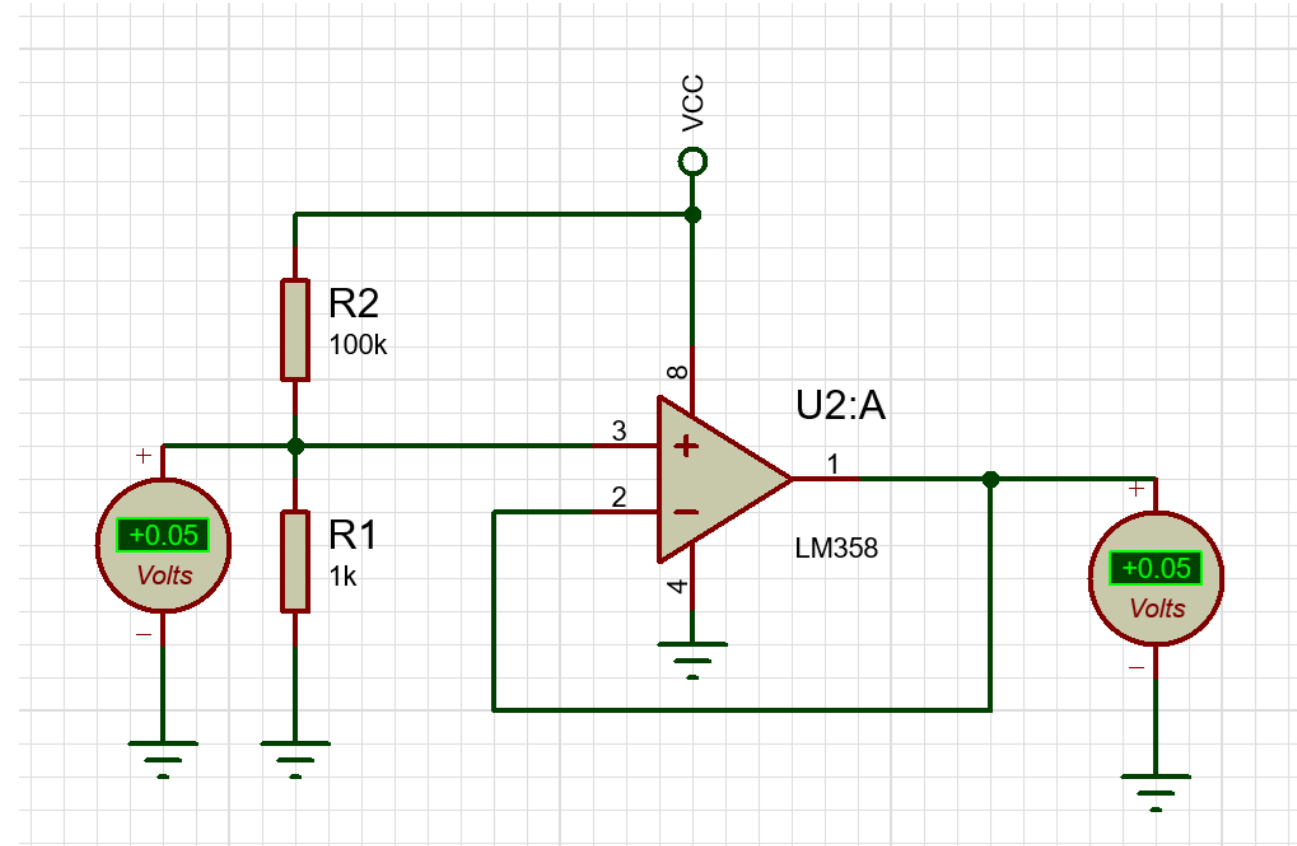
- At 5 °C  $\rightarrow V_{\text{lm35}} = 5 \cdot 10\text{mV} = 50 \text{ mV}$
- At 45 °C  $\rightarrow V_{\text{lm35}} = 45 \cdot 10\text{mV} = 450 \text{ mV}$

### STEP 1 ( Range Mapping)

- 50 mV  $\rightarrow 0\text{V}$  (ADC Vin min)
- 450 mV  $\rightarrow 5\text{V}$  (ADC Vin max) =  $V_{\text{ref}}$

### STEP 2 ( Shifting)

- 50 mV  $\rightarrow 0\text{V}$  (Voltage Divider + **Buffer** “why?”)





## Lab 2

# Improving Sensor Range

Case Study

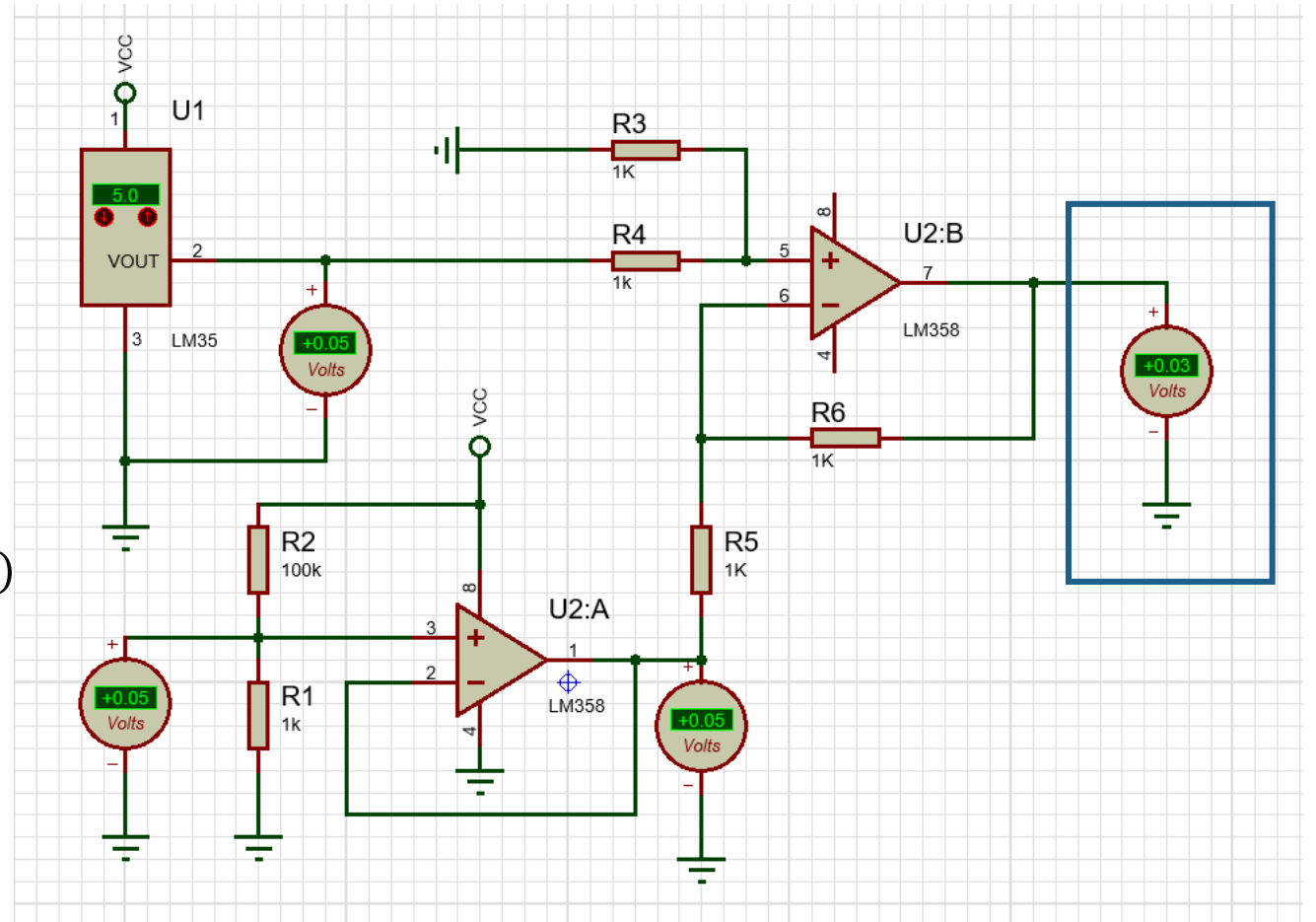
$$V(offset) = 5 * \frac{100k}{1k} = 50 \text{ mV}$$

$$V(out) = V_{LM \rightarrow 50^{\circ}C} - V(offset) = 0V(\text{Theoretical})$$

$$V(out) = 0.05 - 0.05 = 0V + \text{Amplifier DC offset}$$

## STEP 2 ( Shifting)

- 50 mV → 0V (Voltage Divider + Buffer  
“why?”)



Read about **amplifier DC offset**

## Lab 2

# Improving Sensor Range

Case Study

*After min voltage removal*

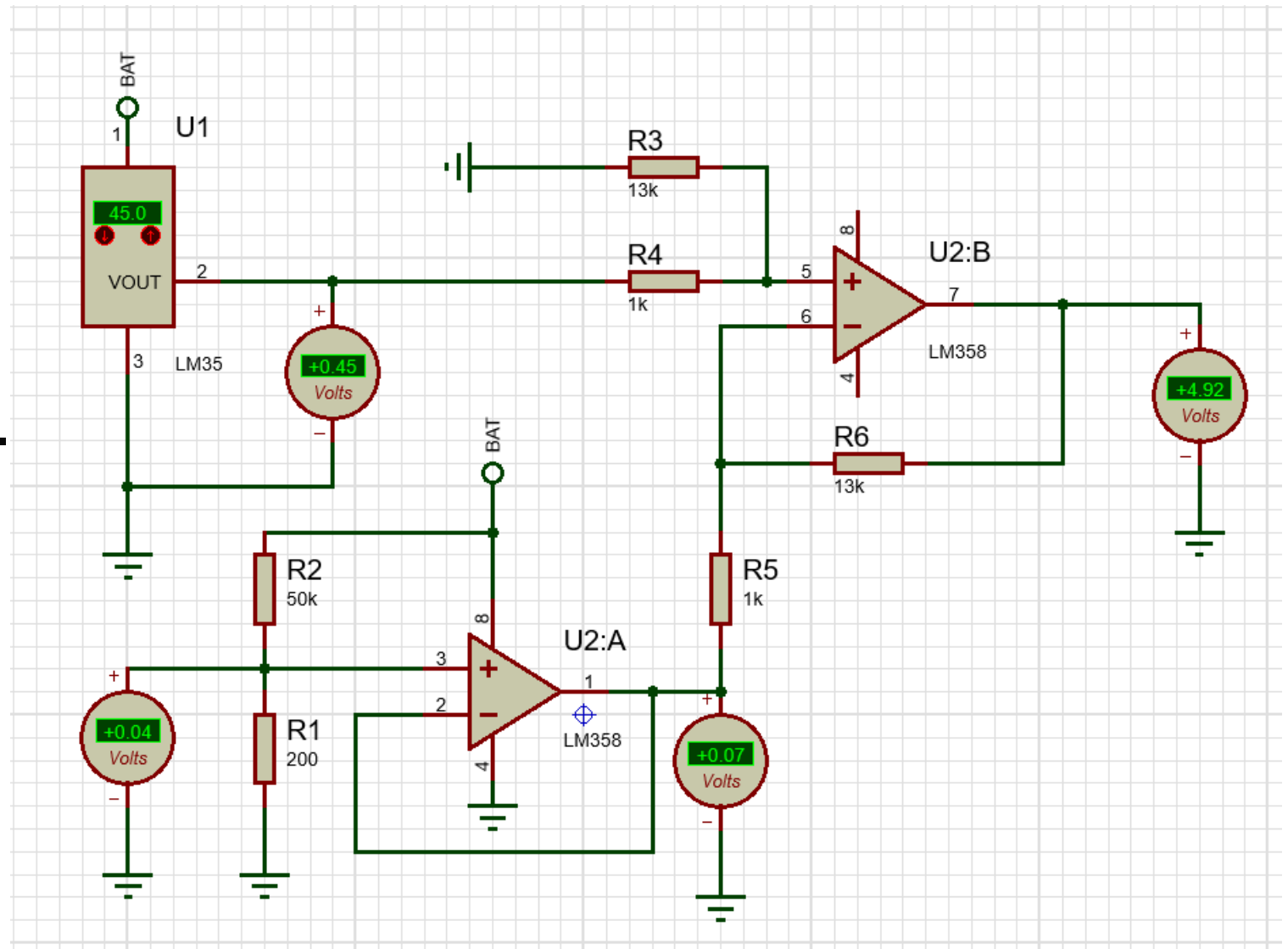
$$V(450) = 0.45 - 0.05 = 0.$$

*Gain*

$$G = \frac{5}{0.4} = 12.5$$

## STEP 3 ( Amplification)

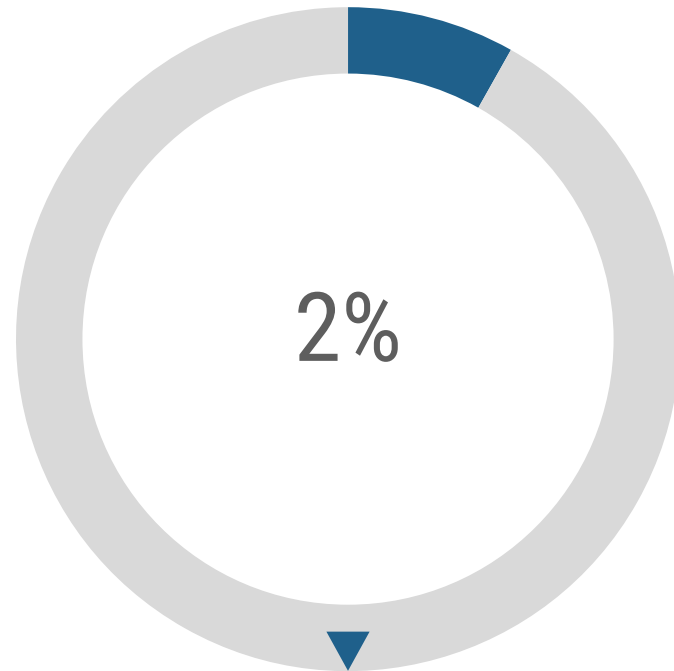
- 450 mV → 5V (Gain of differential amplifier)



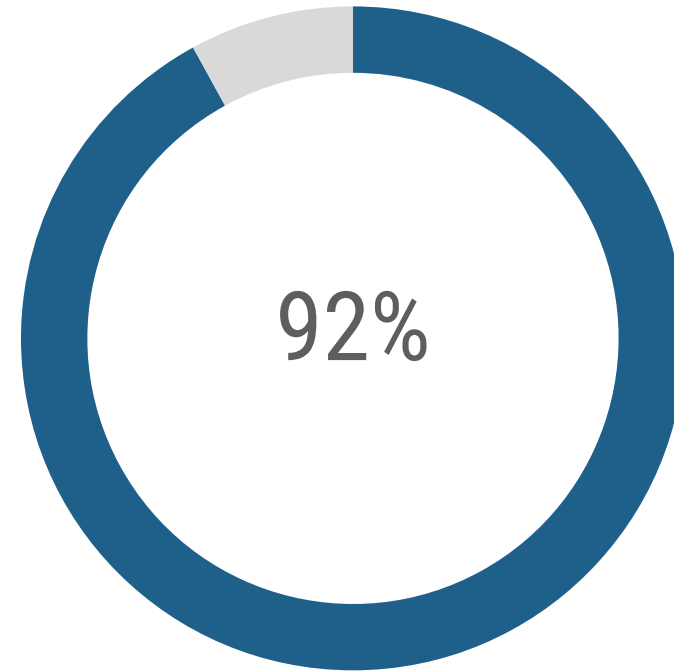
$$V_{\text{bat}} = 12\text{V} \text{ (why changed?)}$$

# Improving Sensor Range

Case Study



BEFORE



AFTER

# Improving Sensor Range

Case Study

## PROBLEM DEFINITION

- You wish to build an embedded system for monitoring **temperature** using LM35.
- Your temperature **range** is expected to vary from **10 – 100 °C**
- You have **built-in 10-bit ADC** with **reference** voltage of **5V**.
- You are **assigned** to **improve the voltage range of LM35** to match ADC input voltage range for the input temperature range

APPLY THE DESIGN IN SIMULATION AND  
PRACTICAL CIRCUIT

# Improving Sensor Range

Case Study

## SOLUTION Steps

1. Get sensor minimum and maximum voltages corresponding to given range

$$T_{min} = 10^{\circ} \rightarrow V_{min} = T * \text{sensor sensitivity} = 10^{\circ} * \frac{10mV}{C} = 0.1 V$$

$$T_{max} = 100^{\circ} \rightarrow V_{max} = T * \text{sensor sensitivity} = 100^{\circ} * \frac{10mV}{C} = 1.0 V$$

$$V_{min} = 0.1 V \quad V_{max} = 1.0 V$$

# Improving Sensor Range

Case Study

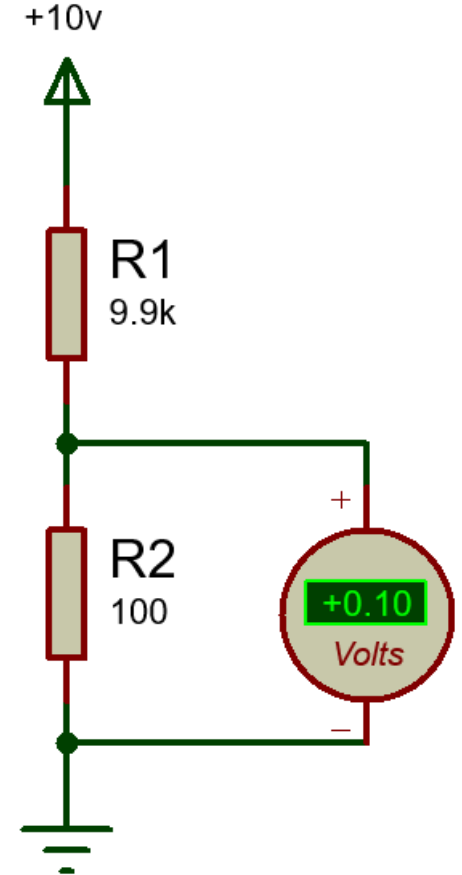
## SOLUTION Steps

2. Remove min voltage offset  $V_{\min}$  by subtracting it from the same voltage created by a voltage divider

*Desired voltage divider output =  $V_{\min} = 0.1\text{ V}$*

$$V_o = V_s \frac{R_2}{R_1 + R_2} \rightarrow R_1 = R_2 \left( \frac{V_s}{V_o} - 1 \right) \text{ (Derive it if you like)}$$

$$\text{Assuming } V_s = 10\text{V}, R_2 = 100 \rightarrow R_1 = 100 \left( \frac{10}{0.1} - 1 \right) = 9.9\text{k}$$



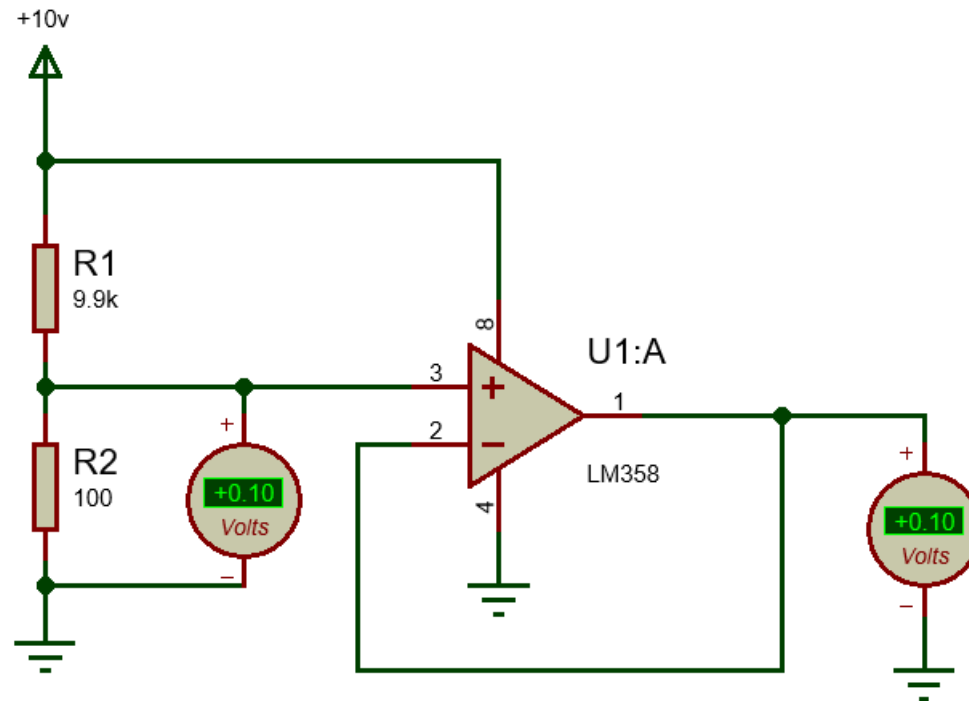
## Lab 2

# Improving Sensor Range

Case Study

## SOLUTION Steps

3. Apply buffering stage (*as discussed in the lab*)



# Improving Sensor Range

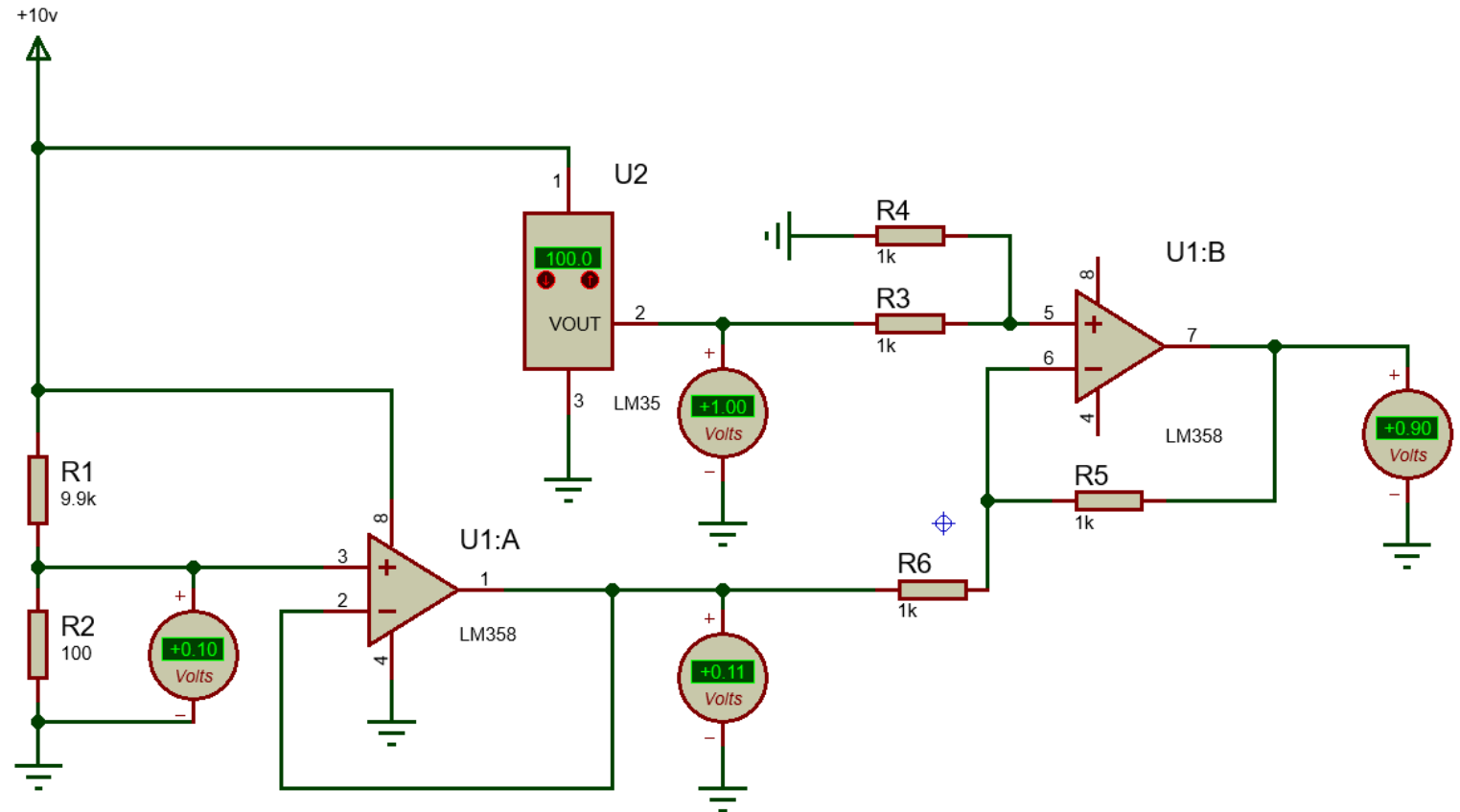
Case Study

## SOLUTION Steps

- Subtract sensor min and max output voltage from buffer and check new  $V_{\min}$  and  $V_{\max}$  after subtraction. (use differential amplifier for subtraction with  $G = 1$ )

$$V_{\min-\text{new}} = 0.1 - 0.1 = 0V$$

$$V_{\max-\text{new}} = 1.0 - 0.1 = 0.9V$$





# Improving Sensor Range

Case Study

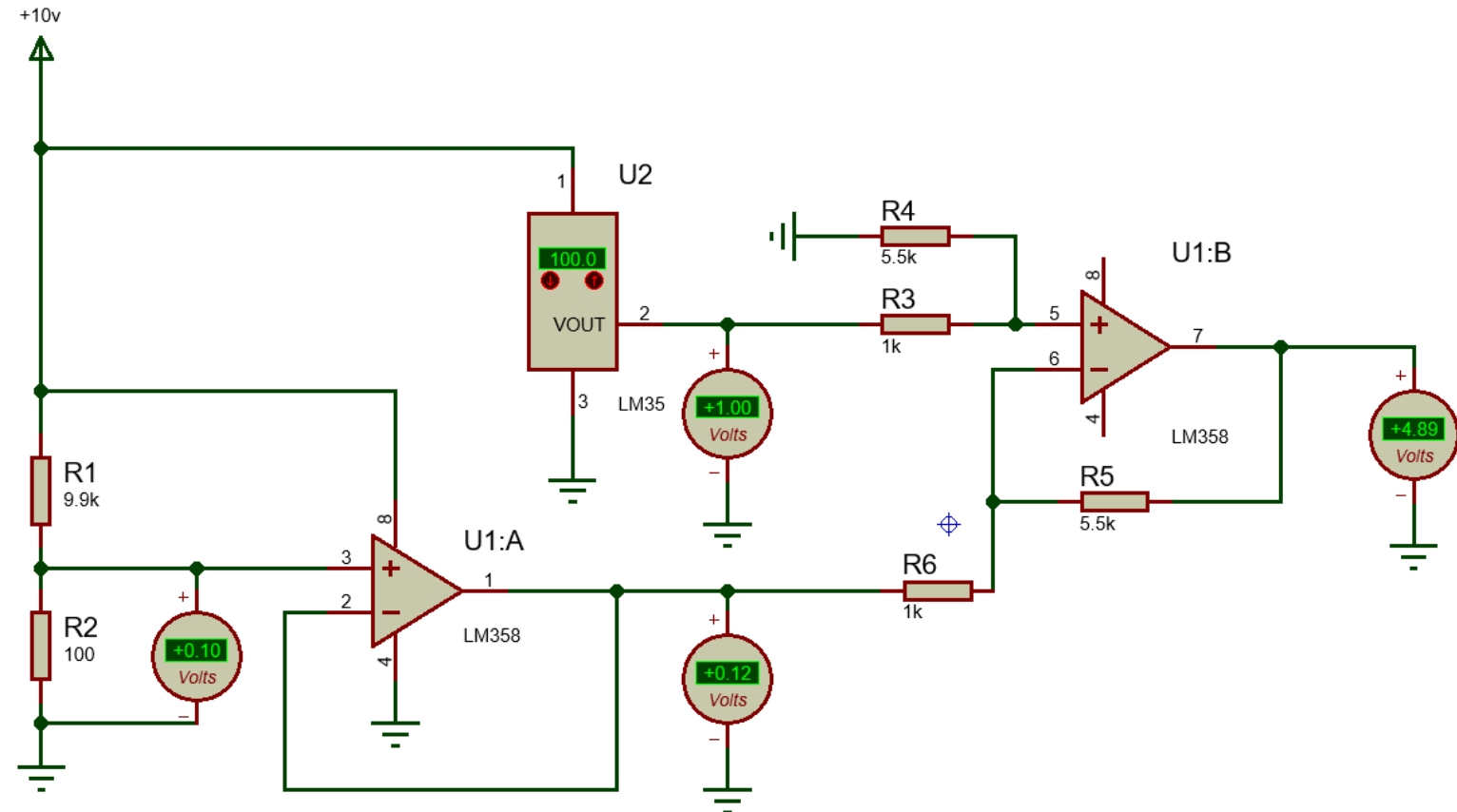
## SOLUTION Steps

5. To maximize the sensor voltage to ADC  $V_{ref}$ , the amplifier gain is set to:

$$G = \frac{V_{ref(ADC)}}{V_{max-new(sensor)}}$$

$$= \frac{5.0}{0.9} = 5.56 \cong 5.5$$

If  $R_f$  is  $5.5k \rightarrow R_1 = 1k$



$\therefore @ T = 10^{\circ}C \rightarrow V = (0.1 - 0.1) * 5.5 = 0V$  and  $@ T = 100^{\circ}C \rightarrow V = (1.0 - 0.1) * 5.5 = 4.95V$

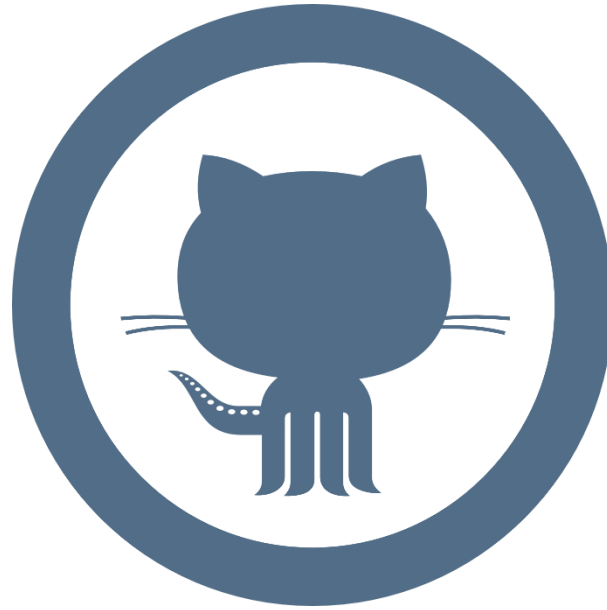
# SENSITIVITY IMPROVEMENT

Before and After

$$\text{Sensor sensitivity} = \frac{10\text{mV}}{^{\circ}\text{C}} \text{ (before signal conditioning)}$$

$$\text{Sensor sensitivity} = \frac{10\text{mV}}{^{\circ}\text{C}} * 5.5 = \frac{55.5\text{mv}}{^{\circ}\text{C}} \text{ (After)}$$

*Sensor sensitivity is improved 5.5 times  
the original sensitivity*



Don't forget to pull the lab update from.

<http://github.com/wbadry/mte405>

**END OF LAB 2**