

ST2334 Finals Cheatsheet

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definitions

sample space (S): set of all possible outcomes

- aka *sure event*

sample point: outcome in sample space, $p \in S$

event: subset of sample space, $E \subseteq S$

- no elements: *null event*, \emptyset

event operations & relationships

- * Applicable to n events

union: $A \cup B = \{x : x \in A \vee x \in B\}$

intersection: $A \cap B = \{x : x \in A \wedge x \in B\}$

complement: $A' = \{x : x \in S \wedge x \notin A\}$

mutually exclusive: $A \cap B = \emptyset$

contained: $A \subset B$

equivalent: $A \subset B \wedge B \subset A \Rightarrow A = B$

others:

- $A \cap A' = \emptyset$
- $A \cap \emptyset = \emptyset$
- $A \cup A' = S$
- $(A')' = A$
- $A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$
- $A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$
- $A \cup B = A \cup (B \cap A')$
- $A = (A \cap B) \cup (A \cap B')$
- $(A_1 \cup A_2 \cup \dots \cup A_n)' = A_1' \cap A_2' \cap \dots \cap A_n'$
- $(A_1 \cap A_2 \cap \dots \cap A_n)' = A_1' \cup A_2' \cup \dots \cup A_n'$

counting methods

multiplication principle: r different experiments performed sequentially, producing $n_1 \times n_2 \times \dots \times n_r$ outcomes

addition principle: r different procedures performed sequentially, producing $n_1 + n_2 + \dots + n_r$ ways (non-overlapping) to perform an experiment

permutation: selection and arrangement of r objects out of n where order matters (i.e. $\{a, b\} \neq \{b, a\}$)

$$P_r = nPr = \frac{n!}{(n-r)!} = n(n-1)(n-2)\dots(n-r+1)$$

combination: selection of r objects out of n where order does not matter

$$C_r^n = nCr = \binom{n}{r} = \frac{n!}{r!(n-r)!}$$

probability

$P(\cdot)$ is a function on the collection of events of the sample space S satisfying:

- axiom 1. For any event A , $0 \leq P(A) \leq 1$
- axiom 2. For the sample space, $P(S) = 1$
- axiom 3. For any two mutually exclusive events A and B , $A \cap B = \emptyset$ and $P(A \cup B) = P(A) + P(B)$

properties:

- $P(\emptyset) = 0$
- if A_1, A_2, \dots, A_n are mutually exclusive events, then $P(A_1 \cup A_2 \cup \dots \cup A_n) = P(A_1) + P(A_2) + \dots + P(A_n)$
- $P(A') = 1 - P(A)$
- $P(A) = P(A \cap B) + P(A \cap B')$
- inclusion-exclusion principle:** $P(A \cup B) = P(A) + P(B) - P(A \cap B)$
- $A \subset B \Rightarrow P(A) \leq P(B)$

finite sample space with equally likely outcomes: $S = \{a_1, a_2, \dots, a_k\}$ and all outcomes are equally likely, so any event occurring is where $A \subset S$

$$P(A) = \frac{|A|}{|S|}$$

probability of repeated event: if the outcome is always the same, then $P(K) = P(A)^n$

conditional probability

for any two events A and B with $P(A) > 0$, the conditional probability of B given that A has occurred is

$$P(B | A) = \frac{P(A \cap B)}{P(A)}$$

since A has occurred, A becomes the reduced sample space

multiplication rule: $P(A \cap B) = P(A)P(B | A)$ if $P(A) \neq 0$

inverse probability formula: $P(A | B) = \frac{P(A)P(B|A)}{P(B)}$

independence

events are independent ($A \perp B$) iff $P(A \cap B) = P(A)P(B)$

$$P(A) \neq 0 \Rightarrow P(A | B) = P(A)$$

$$P(B) \neq 0 \Rightarrow P(B | A) = P(B)$$

intuition: A and B if the knowledge of A does not change the probability of B

independence vs mutually exclusive:

- $P(A) > 0 \wedge P(B) > 0, A \perp B \Rightarrow$ not mutually exclusive
- $P(A) > 0 \wedge P(B) > 0, A, B$ not mutually exclusive $\Rightarrow A \nparallel B$
- S and \emptyset are independent of any other event
- $A \perp B \Rightarrow A \perp B', A' \perp B, A' \perp B'$

total probability

partition: if A_1, A_2, \dots, A_n are mutually exclusive events and $\bigcup_{i=1}^n A_i = S$, then A_1, A_2, \dots, A_n is a partition of S (i.e. how to split the sample space up into parts)

law of total probability: given a partition of S , for any event B ,

$$P(B) = \sum_{i=1}^n P(B \cap A_i) = \sum_{i=1}^n P(A_i)P(B | A_i)$$

applied to single event A and B :

$$P(B) = P(A)P(B | A) + P(A')P(B | A')$$

bayes' theorem

give a partition of S , then for any event B and $k = 1, 2, \dots, n$,

$$P(A_k | B) = \frac{P(A_k)P(B | A_k)}{\sum_{i=1}^n P(A_i)P(B | A_i)}$$

Applied to single event A and B :

$$P(A | B) = \frac{P(A)P(B | A)}{P(A)P(B | A) + P(A')P(B | A')}$$

random variables

a function X which assigns a real number to every $s \in S$ (mapping of values from sample space to some value representing a property of that value in the sample space)

$$X : S \mapsto \mathbb{R}$$

range space: set of real numbers produced by random variable X

$$R_X = \{x \mid x = X(s), s \in S\}$$

notations:

- $\{X = x\} = \{s \in S : X(s) = x\} \subset S$
- $\{X \in A\} = \{s \in S : X(s) \in A\} \subset S$
- $P(X = x) = P(\{s \in S : X(s) = x\})$
- $P(X \in A) = P(\{s \in S : X(s) \in A\})$

describing random variables: (1) range of inputs to outputs, (2) constructing a table/formula

probability distribution

probability distribution: $(x_i, f(x_i))$ where $f(x)$ is the probability function

discrete random variables

number of values in R_X is finite or countable

probability mass function: for a discrete random variable X , the probability (mass) function is:

$$f(x) = \{P(X = x), x \in R_X, 0, x \notin R_X\}$$

properties: $f(x)$ must satisfy the following

- $f(x_i) \geq 0 \forall x_i \in R_X$ (all fractional and ≤ 1)
- $f(x) = 0 \forall x \notin R_X$
- $\sum_{i=1}^{\infty} f(x_i) = \sum_{x_i \in R_X} f(x_i) = 1$

extension: for any set $B \subset \mathbb{R}$,

$$P(X \in B) = \sum_{x_i \in B \cap R_X} f(x_i)$$

continuous random variables

R_X is an interval or collection of intervals

probability density function: quantifies probability that X is in a certain range

properties: $f(x)$ must satisfy the following

- $f(x) \geq 0 \forall x \in R_X$
- $f(x) = 0 \forall x \notin R_X$
- $\int_{-\infty}^{\infty} f(x)dx = \int_{R_X} f(x)dx = 1$

extension 1: given that $a \leq b$,

$$\begin{aligned} P(a \leq X \leq b) &= P(a \leq X < b) \\ &= P(a < X \leq b) \\ &= P(a < X < b) \\ &= \int_a^b f(x)dx \\ P(X = x) &= 0 \end{aligned}$$

extension 2:

cumulative distribution function

probability distribution over a range (both discrete and continuous)

$$F(x) = P(X \leq x)$$

properties:

- $F(x)$ is always non-decreasing
- ranges of $F(x)$ and $f(x)$ satisfy
 - $0 \leq F(x) \leq 1$
 - for discrete distributions, $0 \leq f(x) \leq 1$
 - for continuous distributions, $f(x) \geq 0$ but not necessary that $f(x) \leq 1$

discrete random variables

$$\begin{aligned} F(x) &= \sum_{t \in R_X: t \leq x} f(t) \\ &= \sum_{t \in R_X: t \leq x} P(X = t) \end{aligned}$$

CDF is a step function and can be represented as such (note that probability is cumulative to reach 1):

$$\begin{aligned} F(x) &= \{0, x < 0 \\ 1/4, 0 \leq x < 1 \\ 3/4, 1 \leq x < 2 \\ 1, x \geq 2 \end{aligned}$$

for any two numbers $a < b$,

$$P(a \leq X \leq b) = P(X \leq b) - P(X < a) = F(b) - F(a-)$$

$F(a-)$ is the largest value in R_X that is smaller than a

continuous random variable

$$F(x) = \int_{-\infty}^x f(t)dt$$

$$f(x) = \frac{dF(x)}{dx}$$

for any two numbers $a < b$,

$$P(a \leq X \leq b) = P(a < X < b) = F(b) - F(a)$$

note that if there are multiple functions per interval and a, b run across multiple intervals, separately integrate each interval with the functions for each interval

expectation

expectation, also known as mean, of random variable is the average value of X after repeating the experiment many times. This value may not be a possible value of X

discrete random variable:

$$\mu_X = E(X) = \sum_{x_i \in R_X} x_i f(x_i)$$

continuous random variable:

$$E(X) = \int_{-\infty}^{\infty} x f(x)dx = \int_{x \in R_X} x f(x)dx$$

properties:

- $E(aX + b) = aE(X) + b$
- $E(X + Y) = E(X) + E(Y)$
- let $g(\cdot)$ be an arbitrary function,

$$E(g(X)) = \sum_{x \in R_X} g(x)f(x)$$

or

$$E(g(X)) = \int_{R_X} g(x)f(x)dx$$

variance

calculates the deviation of X from its mean (expectation)

$$\sigma_X^2 = V(X) = E(X - \mu_X)^2 = E(X^2) - E(X)^2$$

applicable regardless of discrete/continuous random variable.

$$V(X) = \sum_{x \in R_X} (x - \mu_X)^2 f(x)$$

or

$$V(X) = \int_{-\infty}^{\infty} (x - \mu_X)^2 f(x)dx$$

properties:

- $V(X) \geq 0$ if $P(X = E(X)) = 1$ where X is a constant
- $V(aX + b) = a^2 V(X)$
- standard deviation of X : $\sigma_X = \sqrt{V(X)}$

joint distributions

(X, Y) is a two-dimensional random vector/random variable

range space: $R_{X,Y} = \{(x, y) \mid x = X(s), y = Y(s), s \in S\}$ (effectively looking at all pairs of (x, y) ; generalizable to n dimensions)

discrete two-dimensional random variable: number of possible values of $(X(s), Y(s))$ is finite or countable (both X and Y are discrete)

continuous two-dimensional random variable: number of possible values of $(X(s), Y(s))$ can assume any value in some region of the Euclidean space \mathbb{R}^2 (both X and Y are continuous)

joint probability function

discrete joint probability function

$$f_{X,Y}(x, y) = P(X = x, Y = y)$$

properties:

- $f_{X,Y}(x, y) \geq 0 \forall (x, y) \in R_{X,Y}$
- $f_{X,Y}(x, y) = 0 \forall (x, y) \notin R_{X,Y}$
- $\sum_{i=1}^{\infty} \sum_{j=1}^{\infty} f_{X,Y}(x_i, y_j) = \sum_{i=1}^{\infty} \sum_{j=1}^{\infty} P(X = x_i, Y = y_j) = 1$
- above is the same as $\sum \sum_{(x,y) \in R_{X,Y}} f(x, y) = 1$

let $A \subset R_{X,Y}$,

$$P((X, Y) \in A) = \sum_{(x,y) \in A} f_{X,Y}(x, y)$$

continuous joint probability function

$$\begin{aligned} P((X, Y) \in D) &= P(a \leq X \leq b, c \leq Y \leq d) \\ &= \int_a^b \int_c^d f_{X,Y}(x, y)dydx \end{aligned}$$

*the order of integration does not matter

properties:

- $f_{X,Y}(x, y) \geq 0 \forall (x, y) \in R_{X,Y}$
- $f_{X,Y}(x, y) = 0 \forall (x, y) \notin R_{X,Y}$
- $\int \int_{(x,y) \in R_{X,Y}} f_{X,Y}(x, y)dydx = 1$

*focus of this module is ranges where x and y do not depend on each other (not the same as independence)

marginal probability distribution

isolating X or Y from a joint probability distribution (projection of joint distribution to univariate distribution). To find X , use Y , and vice versa

$$P(X = x) = f_X(x) = \sum_y f_{X,Y}(x, y)$$

or

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, y)dy$$

marginal probability distributions are probability functions.

conditional distribution

distribution of Y given that the random variable X is observed to take the value x

conditional probability function of Y given that $X = x$:

$$f_{Y \mid X}(y \mid x) = \frac{f_{X,Y}(x, y)}{f_X(x)}$$

when given values, it finds $P(Y \mid X = x)$

only defined for x such that $f_X(x) > 0$ (same for y)

$f_{Y \mid X}(y \mid x)$ is not a probability function of x : the requirements of probability functions do not need to hold

applications: you can also use summation for discrete joint random variables

$$P(Y \leq y \mid X = x) = \sum_{i=1}^y f_{Y \mid X}(y_i \mid x)$$

$$E(Y \mid X = x) = \sum_{i=1}^{\infty} y_i f_{Y \mid X}(y_i \mid x)$$

reading discrete joint probability tables

$x \backslash y$	y_1	y_2	y_3	$f_X(x)$
x_1	a	b	c	$a + b + c$
x_2	d	e	f	$d + e + f$
x_3	g	h	i	$g + h + i$
$f_Y(y)$	$a + d + g$	$b + e + h$	$c + f + i$	1

$E(Y \mid X = x)$ (same steps for $E(X \mid Y = y)$) (using $x = x_1$):

- sum of probability given $X = x_1 = f_X(x_1)$, $a + b + c = K$
 - divide each value in $X = x_1$ by K , a/K , b/K , c/K
 - multiply each by the corresponding Y value, $\frac{ay_1}{K}$, $\frac{by_2}{K}$, $\frac{cy_3}{K}$
 - sum the values: $E(Y \mid X = x_1) = \frac{ay_1 + by_2 + cy_3}{K}$
- $E(X)$ (same steps for $E(Y)$): $x_1 \cdot (a + b + c) + x_2 \cdot (d + e + f) + x_3 \cdot (g + h + i)$
- simplified $E(X)$ (same steps for $E(Y)$): $x_1 \cdot f_X(x_1) + x_2 \cdot f_X(x_2) + x_3 \cdot f_X(x_3)$

independent random variables

X does not decide Y and vice versa

X and Y are independent iff for any x and y (all pairs),

$$f_{X,Y}(x, y) = f_X(x)f_Y(y)$$

*must manually check all combinations

product feature: necessary condition for independence: $R_{X,Y}$ needs to be a product space

$$\begin{aligned} f_{X,Y}(x, y) &= f_X(x)f_Y(y) > 0 \\ \Rightarrow R_{X,Y} &= \{(x, y) \mid x \in R_X, y \in R_Y\} = R_X \times R_Y \end{aligned}$$

if $R_{X,Y}$ is not a product space, then X and Y are not independent (visually, it's a rectangular space)

properties:

- if $A \subset \mathbb{R} \wedge B \subset \mathbb{R}$, the events $X \in A$ and $Y \in B$ are independent events in S

$$P(X \in A; Y \in B) = P(X \in A)P(Y \in B)$$

$$P(X \leq x; Y \leq y) = P(X \leq x)P(Y \leq y)$$

- for arbitrary functions $g_1(\cdot)$ and $g_2(\cdot)$, $g_1(X) \perp g_2(Y)$
- $f_X(x) > 0 \Rightarrow f_{Y \mid X}(y \mid x) = f_Y(y)$
- $f_Y(y) > 0 \Rightarrow f_{X \mid Y}(x \mid y) = f_X(x)$

checking independence

given a joint probability table (for discrete variables), if there are 0 entries in the table, then $R_{X,Y}$ is not a product space, hence $X \nparallel Y$

more generally, both conditions must hold:

- $R_{X,Y}$ is positive and is a product space
- for any $(x, y) \in R_{X,Y}$, $f_{X,Y}(x, y) = C \times g_1(x) \times g_2(y)$ (can be decomposed into parts that all do not depend on each other)
 - * $g_1(X)$ and $g_2(Y)$ do not need to be probability functions

joint expectation

$$E(g(X, Y)) = \sum_x \sum_y g(x, y)f_{X,Y}(x, y)$$

or

$$E(g(X, Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y)f_{X,Y}(x, y)dydx$$

covariance

$$\begin{aligned} \text{cov}(X, Y) &= E[(X - E(X))(Y - E(Y))] \\ &= \sum_x \sum_y (x - \mu_X)(y - \mu_Y)f_{X,Y}(x, y) \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x - \mu_X)(y - \mu_Y)f_{X,Y}(x, y)dydx \end{aligned}$$

properties:

- $\text{cov}(X, Y) = E(XY) - E(X)E(Y)$
- if $X \perp Y$, $\text{cov}(X, Y) = 0$ (but converse is not true)
- $X \perp Y \Rightarrow E(XY) = E(X)E(Y)$
- $\text{cov}(aX + b, c$

- $\lim_{p \rightarrow 0, n \rightarrow \infty} P(X = x) = \frac{e^{-np}(np)^x}{x!}$
- recommended values: n big, p small
 - $n \geq 20 \wedge p \leq 0.05$, OR
 - $n \geq 100 \wedge np \leq 10$

continuous distributions

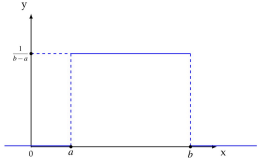
continuous random variable X follows the following distributions if they have the following probability density function

continuous uniform distribution

over interval (a, b)

$$f_X(x) = \begin{cases} \frac{1}{b-a} & \text{if } a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$$

- $X \sim U(a, b)$
- $E(X) = \frac{a+b}{2}$, $V(X) = \frac{(b-a)^2}{12}$



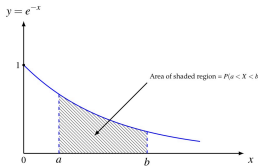
$$F_X(x) = \begin{cases} 0 & \text{if } x < a \\ \frac{x-a}{b-a} & \text{if } a \leq x \leq b \\ 1 & \text{if } x > b \end{cases}$$

exponential distribution

parameter $\lambda > 0$

$$f_X(x) = \begin{cases} \lambda e^{-\lambda x} & \text{if } x \geq 0 \\ 0 & \text{if } x < 0 \end{cases}$$

- $X \sim \text{Exp}(\lambda)$
- $E(X) = \frac{1}{\lambda}$, $V(X) = \frac{1}{\lambda^2}$
- can be written with μ if $\mu = 1/\lambda$



$$F_X(x) = P(X \leq x) = \int_0^x \lambda e^{-\lambda t} dt = [-e^{-\lambda t}]_0^x = 1 - e^{-\lambda x}$$

- if $x \geq 0$, else $F_X(x) = 0$

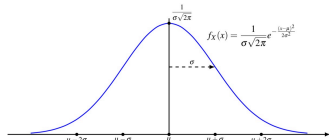
memory-less property: if $X \sim \text{Bin}(\lambda)$, then $P(X > s + t \mid X > s) = P(X > t)$

normal distribution

parameter μ and σ^2

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/2\sigma^2}$$

- $X \sim N(\mu, \sigma^2)$
- $E(X) = \mu$, $V(X) = \sigma^2$



- properties:**
- same σ_2 but different $\mu \rightarrow$ same shape, different center
 - as σ_2 increases \rightarrow curve flattens

approximation to binomial: let $X \sim \text{Bin}(n, p)$; $n \rightarrow \infty$

- then $X \sim N(0, 1)$
- $Z = \frac{X - E(X)}{\sqrt{V(X)}} = \frac{X - np}{\sqrt{np(1-p)}}$
- recommended values: $np > 5$ and $n(1-p) > 5$
- continuity correction: adjusting ranges by $\pm 1/2$

- $a \leq X \Rightarrow -1/2$
- $a < X \Rightarrow +1/2$
- $X \leq b \Rightarrow +1/2$
- $X < b \Rightarrow -1/2$

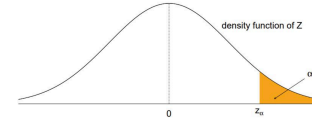
standard normal

given $X \sim N(\mu, \sigma^2)$, let $Z = \frac{X-\mu}{\sigma}$, $Z \sim N(0, 1)$

- $\varphi(\cdot) = f_Z(z) = \frac{1}{\sqrt{2\pi}} e^{-z^2/2}$; pdf
- $\Phi(\cdot) = \int_{-\infty}^z \varphi(t) dt = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^z e^{-t^2/2} dt$: cumulative function
- $P(x_1 < X < x_2) \Rightarrow P(z_1 < Z < z_2) \Rightarrow \Phi\left(\frac{x_2-\mu}{\sigma}\right) - \Phi\left(\frac{x_1-\mu}{\sigma}\right)$

properties:

- $P(Z \geq 0) = P(Z \leq 0) = \Phi(0) = 0.5$
- $\forall z, \Phi(z) = P(Z \leq z) = P(Z \geq -z) = 1 - \Phi(-z)$
- $Z \sim N(0, 1) \Rightarrow -Z \sim N(0, 1)$
- $Z \sim N(0, 1) \Rightarrow \sigma Z + \mu \sim N(\mu, \sigma^2)$
- $P(Z > z_\alpha) = \alpha$



quantile: upper (α th) quantile where $0 \leq \alpha \leq 1$ is x_α that satisfies $P(X \geq x_\alpha) = \alpha$

- common z_α values:
 - $z_{0.05} = 1.645$
 - $z_{0.01} = 2.326$
- symmetrical about 0, so $P(Z \geq z_\alpha) = P(Z \leq -z_\alpha) = \alpha$

population

population: all possible outcomes/observations of a survey/experiment; size is N

- population mean: μ_X
- population variance: σ_X^2

sample: subset of population; size is n

finite population: finite number of elements

infinite population: infinitely large number of elements

random sampling

sample of n members taken from a given population: $\binom{N}{n}$

- every member has the same probability of being selected
- yields sample that resembles the population; reducing chance that sample is seriously biased

sampling infinite population: let X be a random variable with pdf $f_X(x)$

- let X_1, X_2, \dots, X_n be independent random variables with the same distribution as X
- (X_1, X_2, \dots, X_n) is a random sample of size n
- $f_{X_1, X_2, \dots, X_n} = f_{X_1}(x_1) f_{X_2}(x_2) \dots f_{X_n}(x_n)$
- sampling from a finite population with replacement \Rightarrow sampling from an infinite population

sampling distribution: probability distribution of a statistic

statistics

function of n observations in sample; statistics are samples

sample mean:

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

- $\mu_{\bar{X}} = E(\bar{X}) = \mu_X$
- in the "long run"
- $\sigma_{\bar{X}}^2 = V(\bar{X}) = \sigma_X^2/n$

sample variance:

$$S^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$$

standard error: spread of sampling distribution (standard deviation): SE or $\sigma_{\bar{X}}$

- how much \bar{X} tends to vary from sample to sample of size n

law of large numbers: if X_1, X_2, \dots, X_n are independent random variables with the same mean μ and variance σ^2 , then for any $\varepsilon \in \mathbb{R}$,

$$n \rightarrow \infty \Rightarrow P(|\bar{X} - \mu| > \varepsilon) \rightarrow 0$$

- i.e. as sample size increases, the probability that sample mean differs from population mean goes to 0
- central limit theorem:** if \bar{X} is a mean of random sample size n from population with mean μ and finite variance σ^2 , then

$$n \rightarrow \infty \Rightarrow \frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \rightarrow Z \sim N(0, 1)$$

$$\Rightarrow \bar{X} \rightarrow N\left(\mu, \frac{\sigma^2}{n}\right)$$

- i.e. for large n , sums and means of random samples drawn from a population follow the normal distribution closely
- if sample comes from normal population, then \bar{X} is normally distributed as well
- rule of thumb:
 - symmetric population: $n = 15 - 20$
 - moderately skewed: $n = 30 - 50$
 - extremely skewed: $n = 1000$
- convergence in distribution: for any x

$$\lim_{n \rightarrow \infty} P\left(\frac{\bar{X} - \mu}{\sigma/\sqrt{n}} \leq x\right) = \Phi(x)$$

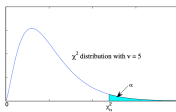
sampling distributions

chi-squared (χ^2) distribution

let Z_1, Z_2, \dots, Z_n be n independent and identically distributed standard normal random variables

- a random variable with the same distribution as $Z_1^2 + Z_2^2 + \dots + Z_n^2$ is a χ^2 random variable with n degree of freedom
- $\chi^2(n)$

$$P(Y > \chi^2(n; \alpha)) = \alpha.$$



properties:

- $Y \sim \chi^2(n) \Rightarrow E(Y) = n$; $V(Y) = 2n$
- for large n , $\chi^2(n) \approx N(n, 2n)$
- if Y_1 and Y_2 are independent χ^2 random variable with m, n degrees of freedom, then $Y_1 + Y_2$ is $\chi^2(m+n)$
- has a long right tail

distribution of $\frac{(n-1)S^2}{\sigma^2}$: where $X_i \sim N(\mu, \sigma^2)$ has $\chi^2(n-1)$

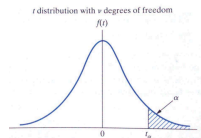
$$\frac{(n-1)S^2}{\sigma^2} = \frac{\sum_{i=1}^n (X_i - \bar{X})^2}{\sigma^2}$$

t-distribution

suppose $Z \sim N(0, 1)$ and $U \sim \chi^2(n)$ and $Z \perp U$:

$$T = \frac{Z}{\sqrt{U/n}} \sim t(n)$$

$$P(T > t_{n, \alpha}) = \alpha.$$



properties:

- $n \rightarrow \infty \Rightarrow t(n) \rightarrow N(0, 1)$ (when $n \geq 30$, replace with $N(0, 1)$)
- $T \sim t(n) \Rightarrow E(T) = 0$; $V(T) = n/(n-2)$, $n > 2$
- graph: symmetric about vertical axis and resembles graph of standard normal (but flatter)
- used if σ (stdev) is unknown and sample size is small
 - otherwise, if sample size is large, use z but continue using S instead of σ

relation to normal distribution: if X_1, \dots, X_n are independent and identically distributed normal random variables with mean μ and variance σ^2

$$\frac{\bar{X} - \mu}{S/\sqrt{n}} \sim t(n-1)$$

F-distribution

suppose $U \sim \chi^2(m)$ and $V \sim \chi^2(n)$ are independent

$$F = \frac{U/m}{V/n} \sim F(m, n)$$

properties:

- $X \sim F(m, n) \Rightarrow E(X) = \frac{n}{n-2}$, $n > 2$; $V(X) = \frac{2n^2(m+n-2)}{m(n-2)^2(n-4)}$, $n > 4$
- $F \sim F(n, m) \Rightarrow \frac{1}{F} \sim F(m, n)$
- $F(m, n; \alpha) \Rightarrow P(F > F(m, n; \alpha)) = \alpha$
- $F(m, n; 1 - \alpha) = 1/F(n, m; \alpha)$

estimator

rule about how to calculate an estimate based on information in the sample

unbiased estimator: let $\hat{\theta}$ be the estimator of θ

$$E(\hat{\theta}) = \theta$$

- $E(S^2) = \sigma^2$

maximum error of estimate: replace σ with S if necessary and $z_{\alpha/2}$ with $t_{n-1, \alpha/2}$ if variance not known or sample size too small

$$E = z_{\alpha/2} \frac{\sigma}{\sqrt{n}}$$

reversing the formula:

$$n \geq \left(\frac{z_{\alpha/2} \sigma}{E}\right)^2$$

confidence intervals

interval estimator: rule for calculating, from a sample, an interval (a, b) with some level of certainty that the parameter of interest lies in

- quantified as degree of confidence/confidence level $(1 - \alpha)$
- (a, b) is the $(1 - \alpha)$ confidence interval

$$P(a < \mu < b) = 1 - \alpha$$

$$\bar{X} \pm E$$

- written as

interpretation: given some sample statistic, the population parameter is either contained within (or not) the confidence interval

- when repeated over many samples, about 100(1 - α)% of the confidence intervals will contain the population parameter

2 populations

independent samples

usually focused on $\mu_1 - \mu_2 = \delta$

known and unequal variance

populations are normal OR both samples are large

$$Z = \frac{(\bar{X} - \bar{Y}) - (\mu_1 - \mu_2)}{\sqrt{\frac{\sigma_1^2}{n_1} + \frac{\sigma_2^2}{n_2}}} \approx N(0, 1)$$

confidence interval:

$$(\bar{X} - \bar{Y}) \pm z_{\alpha/2} \sqrt{\frac{\sigma_1^2}{n_1} + \frac{\sigma_2^2}{n_2}}$$

large and unknown variance

$$Z = \frac{(\bar{X} - \bar{Y}) - (\mu_1 - \mu_2)}{\sqrt{\frac{S_1^2}{n_1} + \frac{S_2^2}{n_2}}} \approx N(0, 1)$$

confidence interval:

$$(\bar{X} - \bar{Y}) \pm z_{\alpha/2} \sqrt{\frac{S_1^2}{n_1} + \frac{S_2^2}{n_2}}$$

small, equal, unknown variance

equal variance assumption: if $1/2 \leq S_1/S_2 \leq 2$

pooled estimator: estimates σ^2 ; follows $t_{n_1+n_2-2}$ distribution

$$S_P^2 = \frac{(n_1-1)S_1^2 + (n_2-1)S_2^2}{n_1 + n_2 - 2}$$

$$Z = \frac{(\bar{X} - \bar{Y}) - (\mu_1 - \mu_2)}{\sigma \sqrt{\frac{1}{n_1} + \frac{1}{n_2}}} \approx N(0, 1)$$

confidence interval:

$$(\bar{X} - \bar{Y}) \pm t_{n_1+n_2-2, \alpha/2} S_P \sqrt{\frac{1}{n_1} + \frac{1}{n_2}}$$

large and equal variance

$$(\bar{X} - \bar{Y}) \pm z_{\alpha/2} S_P \sqrt{\frac{1}{n_1} + \frac{1}{n_2}}$$

dependent samples/paired data

each pair is independent from each other; let $D_i = X_i - Y_i$ and $\mu_D = \mu_1 - \mu_2$

- treat D_1, D_2, \dots, D_n as random sample with mean μ_D and variance σ_D^2

$$T = \frac{\bar{D} - \mu_D}{S_D/\sqrt{n}}$$

$$\bar{D} = \frac{\sum_{i=1}^n D_i}{n}$$

$$S_D^2 = \frac{\sum_{i=1}^n (D_i - \bar{D})^2}{n-1}$$

- $n < 30$ and population normally distributed: $T \sim t_{n-1}$

- $n \geq 30$: $T \sim N(0, 1)$

confidence interval:

$$\bar{D} \pm t_{n-1, \alpha/2} \frac{S_D}{\sqrt{n}}$$

- replace $t_{n-1, \alpha/2}$ with $z_{\alpha/2}$ if $n \geq 30$

hypothesis testing

- set competing hypotheses: null and alternative
- set level of significance
- identify test statistic, distribution, and rejection criteria
- compute the observed test statistic value
- conclusion

null vs alternative hypothesis

looking for ways to reject that there is no change and show that there is significance

null hypothesis (H_0): assumed truth (i.e. no change)

alternative hypothesis (H_1): contrasting hypothesis; what we want to prove

outcome: reject or fail to reject hypothesis

one-sided hypothesis test: $H_1: \mu > \bar{x}$ or $H_1: \mu < \bar{x}$ (right or left leaning hypothesis test)

two-sided hypothesis test: $H_1: \mu \neq \bar{x}$ (both sides)

level of significance

conclusions:

- reject H_0 and conclude H_1
- do not reject H_0 and conclude H_0

	Do not reject H_0	Reject H_0
H_0 is true	Correct decision	Type 1 error
H_0 is false	Type 2 error	Correct decision

level of significance α : probability of making a type 1 error

- more serious so control this

power of test $1 - \beta$: probability of making type 2 error

test statistic, distribution, and rejection region

quantifies how unlikely it is to observe the sample assuming the null hypothesis is true



calculation & conclusion

check if sample statistic falls within rejection region

- if so, sample is improbable, so reject H_0
- else, failed to reject H_0

hypothesis testing with mean

population distribution is normal or n is sufficient large

use $Z = \frac{\bar{X} - \mu_0}{\sigma/\sqrt{n}} \sim N(0, 1)$ as test statistic and rejection region is $P(|Z| > z_{\alpha/2}) = \alpha$

- if two-tailed test: $Z < -z_{\alpha/2}$ or $Z > z_{\alpha/2}$
- if one-tailed test: $Z < -z_{\alpha/2}$ (for left tail) or $Z > z_{\alpha/2}$ (for right tail)

unknown variance: use t -distribution instead with $n - 1$ degree of freedom with S replacing σ ; use standard normal distribution iff $n \geq 30$

- swap Z check with t check

p-value

probability of obtaining a test statistic at least as extreme than the observed sample value, given that H_0