

# Streaming Hierarchical Clustering Based on Point-Set Kernel

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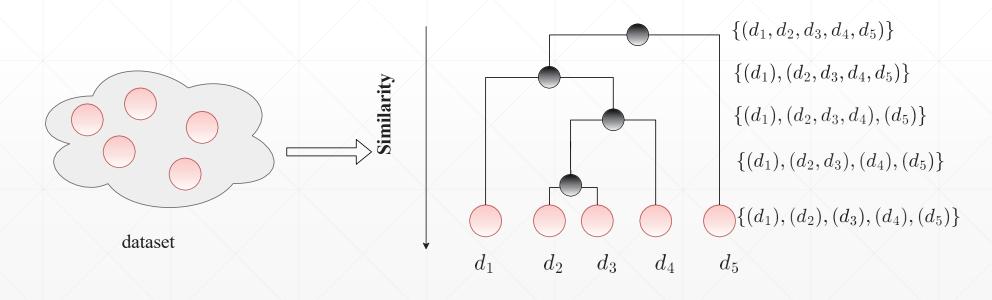






# **Hierarchical Clustering**

- Hierarchical clustering is one of the most popular clustering methods.
- It produces a cluster tree that each leaf contains a data point and each internal node represents a sub-cluster.



# **Existing Methods**

#### Classical AHC

- Single-linkage
- Average-linkage
- Complete-linkage

#### Disadvantages:

- They have at least computational complexity of  $O(n^2)$ .
- They cannot handle massive datasets and the cluster tree structure produced could not be changed easily.

#### Scalable AHC

- Sampling based.
- Mini-batches based.
- Approximations based.

#### Disadvantages:

These approaches trade off the clustering quality for fast linkage/similarity calculations.

## **Contributions**

- Proposing the first kernel-based incremental hierarchical clustering algorithm StreaKHC for clustering massive streaming data
- Developing an efficient tree updating strategy in real-time for StreaKHC.
  This updating strategy does not rely on any sampling, mini-batch or approximation method.
- Verifying the effectiveness and efficiency of StreaKHC on 17 synthetic and real-world datasets.



## **Isolation Kernel**

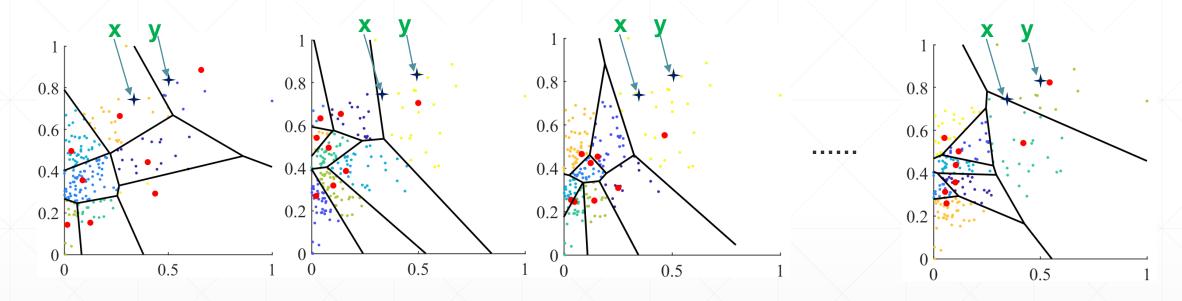
The key idea of the Isolation kernel [1] is using a space partitioning strategy to split the whole data space into  $\psi$  non-overlapping partitions based on a random sample of  $\psi$  points from a given dataset. The similarity between any two points is the expectation that these two points are found in the same partition.

$$K_{\psi}(\mathbf{x}, \mathbf{y}|D) = \mathbb{E}_{\mathcal{H}_{\psi}(D)}[\mathbb{I}(\mathbf{x}, \mathbf{y} \in \theta | \theta \in H)] \cong \frac{1}{t} \sum_{i=1}^{t} \mathbb{I}(\mathbf{x}, \mathbf{y} \in \theta | \theta \in H_i),$$

where  $H \in \mathcal{H}_{\psi}(D)$  is one partitioning based on a subsample with size  $\psi$ , and  $\mathbb{I}$  is an indicator function.



## **Isolation Kernel Calculation**

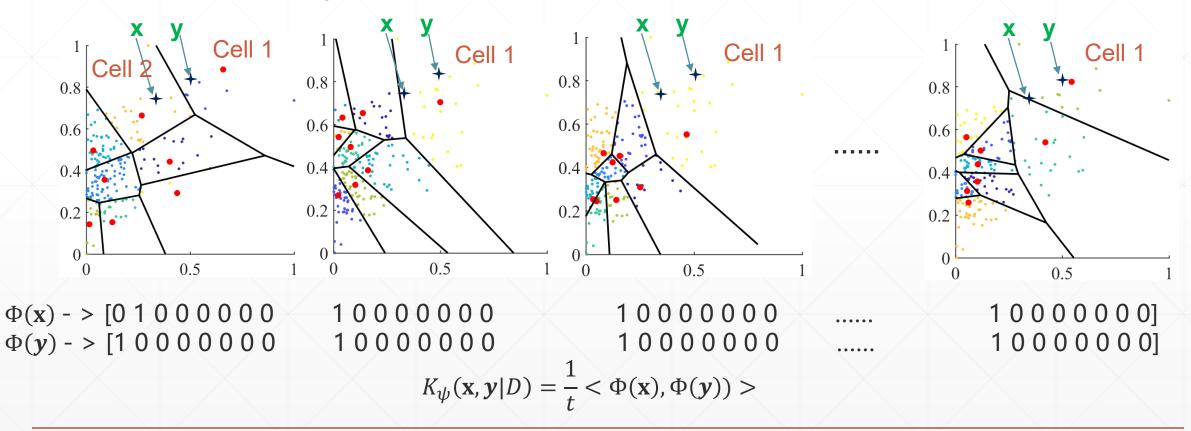


We can use a nearest neighbour method to split a data space into 8 non-overlapping partitions, and independently conduct this partitioning strategy for t=100 trials. If two points  $\mathbf{x}$  and  $\mathbf{y}$  are located in the same partition (sharing the same nearest subsample point) in 25 out of 100 trials, then the similarity between  $\mathbf{x}$  and  $\mathbf{y}$  is estimated as 0.25, i.e.,  $K_8(\mathbf{x}, \mathbf{y}|D) = 0.25$ .



# **Isolation Kernel Feature Map**

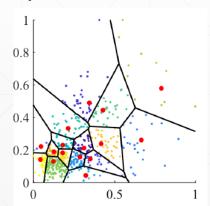
 $\Phi(\mathbf{x})$  is a binary vector that represents the partitions in all the partitionings, where  $\mathbf{x}$  falls in to only one of  $\psi$  cells in each partitioning.

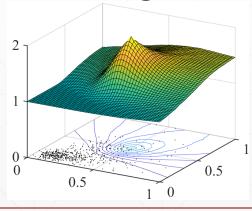




# **Isolation Kernel Properties**

- Isolation kernel adapts to local density distribution. The isolation mechanism of IK produces large partitions in sparse regions and small partitions in dense regions, based on the random subsamples.
- The probability of two points from the dense cluster falling into the same isolating partition is lower than two points of equal inter-point distance from the sparse cluster, i.e., two points in a sparse region are more similar than two points of equal inter-point distance in a dense region.





Contours with reference to point (0.5, 0.5).

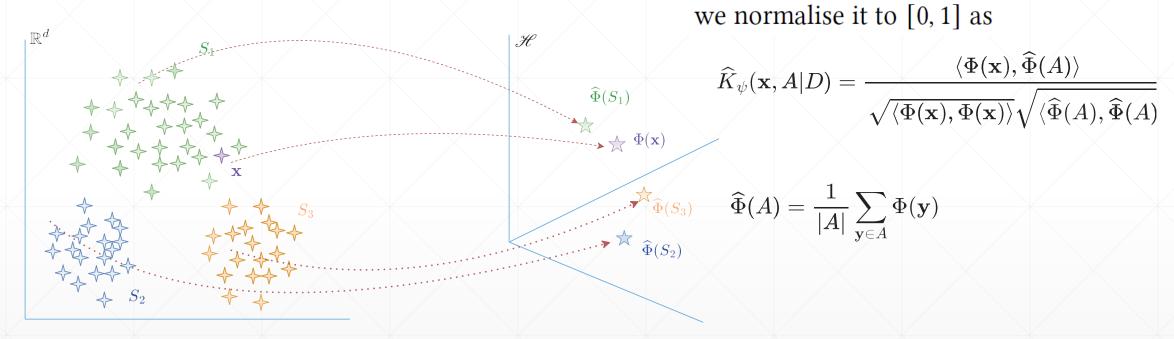
## **Point-Set Kernel**

Given a point x and a set  $A = \{y_i\}_{i=1}^p$ , and  $x, y_i \in R^d$ , the point-set similarity between x and A is the average pairwise similarity between x and every point in A, defined as follows:

$$\widehat{K}_{\psi}(\mathbf{x}, \mathbf{A}|D) = \frac{1}{|\mathbf{A}|} \sum_{\mathbf{y} \in A} K_{\psi}(\mathbf{x}, \mathbf{y}|D) = \frac{1}{t} < \Phi(\mathbf{x}), \widehat{\Phi}(A) >$$

Where  $\widehat{\Phi}(A) = \frac{1}{|A|} \sum_{\mathbf{y}} \Phi(\mathbf{y})$  is the kernel mean map of  $K_{\psi}$ .

## Point-Set Kernel (cont.)



Because  $\widehat{\Phi}(A)$  can be pre-calculated, estimating the similarity between a point and a set points costs constant time O(1).

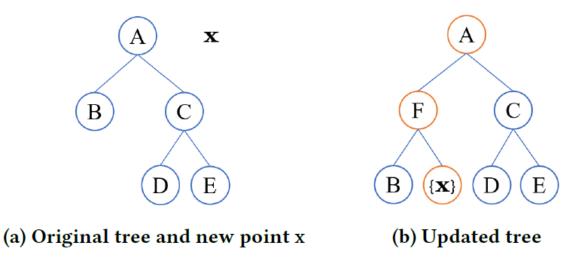
## **StreaKHC**

StreaKHC is a kernel-based incremental hierarchical clustering algorithm.

- Building an Isolation kernel and mapping points to its feature space.
- Employing a top-down search strategy to grow a tree with a new point, i.e., it recursively add the new point x with x's most similar node at each level long the path from the root to a leaf node  $\eta$ .
- Pruning the existing leaf to control the size of the hierarchical cluster tree, i.e., it stores the most recent *l* points only to reduce the over-size hierarchical tree to a pre-set size limit.

# StreakHC - Example of Adding a Point

- 1. Add x into the root
- 2. Find  $\widehat{K}_{\psi}(\mathbf{x}, S_B) \geq \widehat{K}_{\psi}(\mathbf{x}, S_C)$
- 3. Replace B with a subtree having a new parent node containing  $F = B \cup \{x\}$



The time and space complexity of StreaKHC are O(n) and  $O(l\psi t)$ , respectively.

The distance version StreaKHC-D uses the average-linkage function for point-set dissimilarity calculation as  $D(\mathbf{x}, S) = \sum_{\mathbf{y} \in S} \left| |\mathbf{x} - \mathbf{y}| \right|_2 / |S|$ .

# **Empirical Evaluation - Baselines**

#### 1. Batch Hierarchical Clustering:

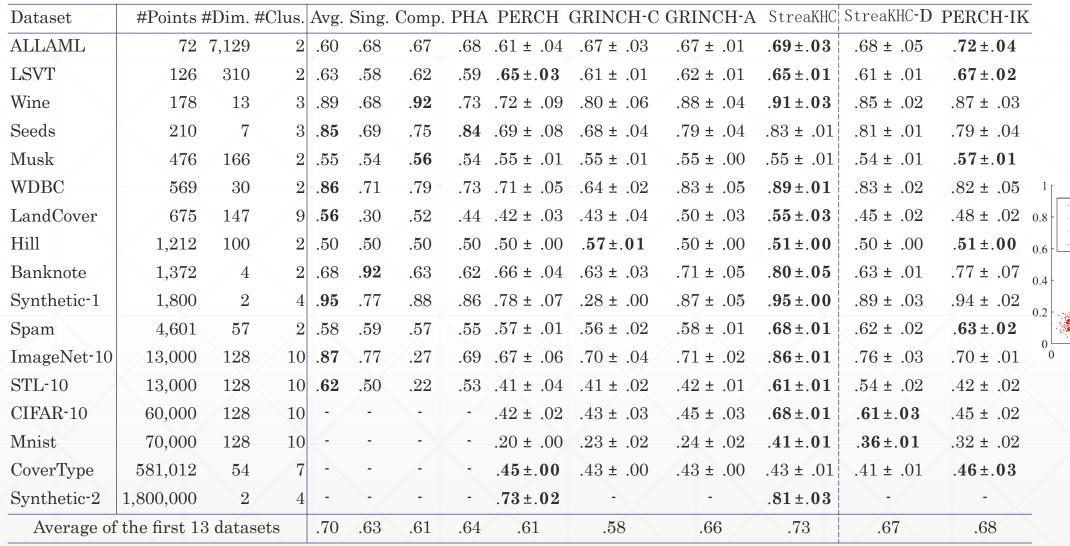
- AHC with average-linkage (Avg.).
- AHC with single-linkage (Sing.).
- AHC with complete-linkage (Comp.)
- PHA. It uses a potential-based linkage function.

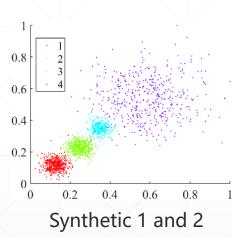
#### 2. Online Hierarchical Clustering:

- PERCH. It adds a new point to the nearest leaf node of an existing cluster tree and then rearrange/rotate the tree once detecting a masking situation.
- GRINCH. It is similar to PERCH with an additional grafting subroutine. Two versions of GRINCH are used: approximate average-linkage (GRINCH-A) and cosine similarity linkage (GRINCH-C).



# **Clustering Results in Dendrogram Purity**

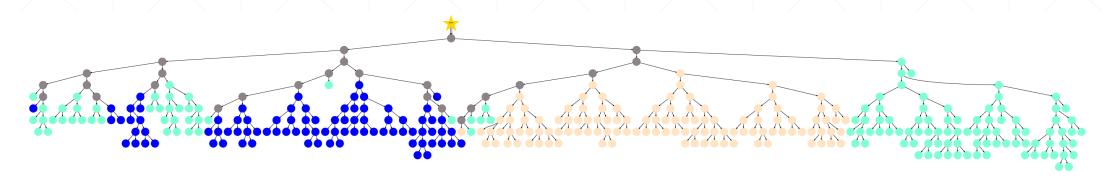




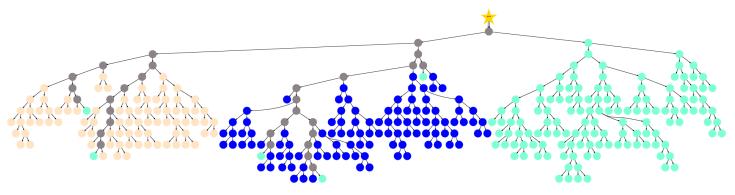
- StreaKHC-D is StreaKHC using Euclidean distance only.
- PERCH-IK: The same PERCH algorithm running on Isolation kernel space.



## **Visualisation on Wine Dataset**



(a) PERCH with Dendrogram Purity of 0.80.

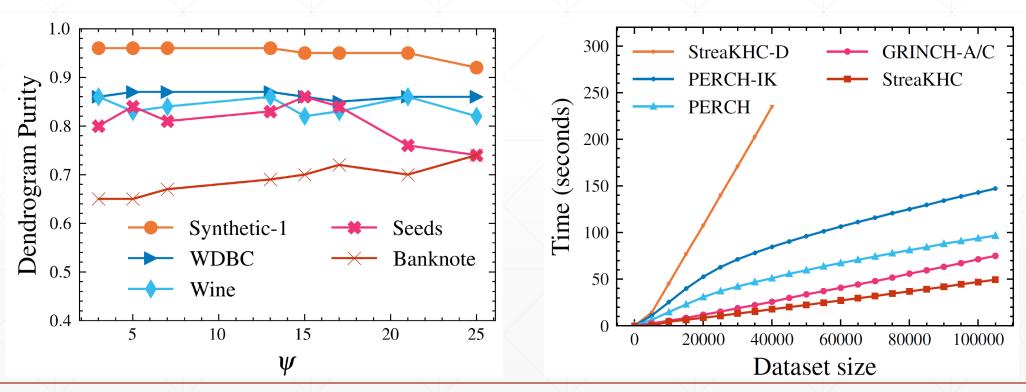


(b) StreaKHC with *Dendrogram Purity* of 0.95.

Figure 4: Clustering dendrograms (cluster trees) on the Wine dataset. Each leaf node contains a data point, and each colour represents a ground-truth label of a node if all the points in it belong to the same label, otherwise, the node is coloured grey.

# **Sensitivity and Scalability Test**

- Maintains a stable clustering quality within a certain parameter range.
- The fastest among existing online hierarchical clustering algorithms.



## Conclusion

- StreaKHC conducts its search in a top-down manner, avoiding searching all nodes in the cluster tree as required by existing methods.
- It is designed based on the point-set kernel that has constant time for each similarity computation, it updates the cluster tree very efficiently with each emerging new data point, and maintains a high-quality cluster tree in real-time.
- It utilises the data-dependent property of Isolation kernel to effectively detect clusters of varied densities in which most existing algorithms have difficulty separating.



StreaKHC can be obtained from: https://github.com/tulip-lab/open-code/tree/master/StreaKHC