

Ur5_arm

Get started

There are configs of ur5 and several motion control demos here.

Installation

- Moveit!
- ur5_configs
- ros
- C++

Test

run demo.launch to load the model, and drag the end effector to plan

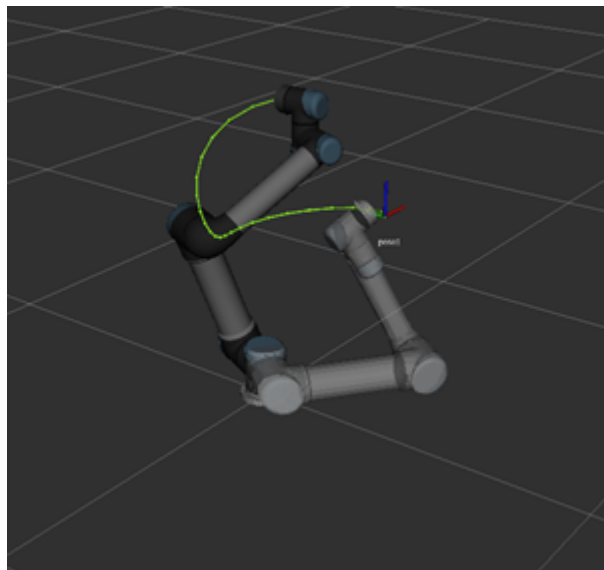
```
roslaunch ur5_kuko demo.launch
```

run ur5_move_group.launch to show all the motion planning demos

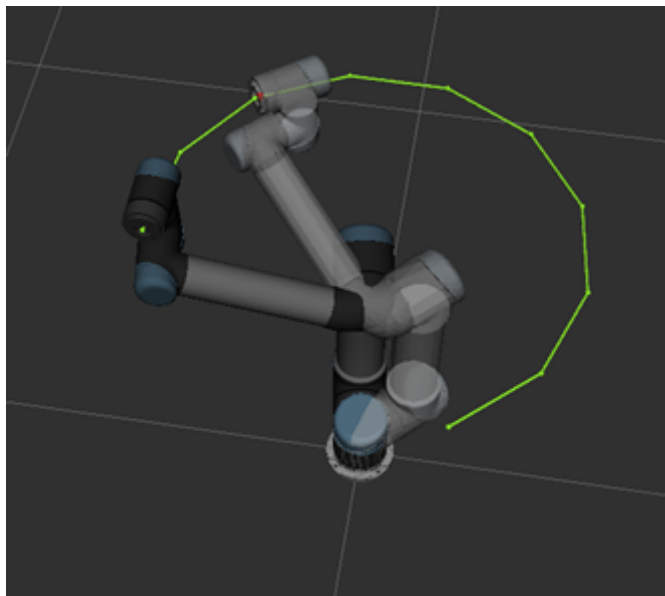
```
roslaunch ur5_move ur5_move_group.launch
```

Show

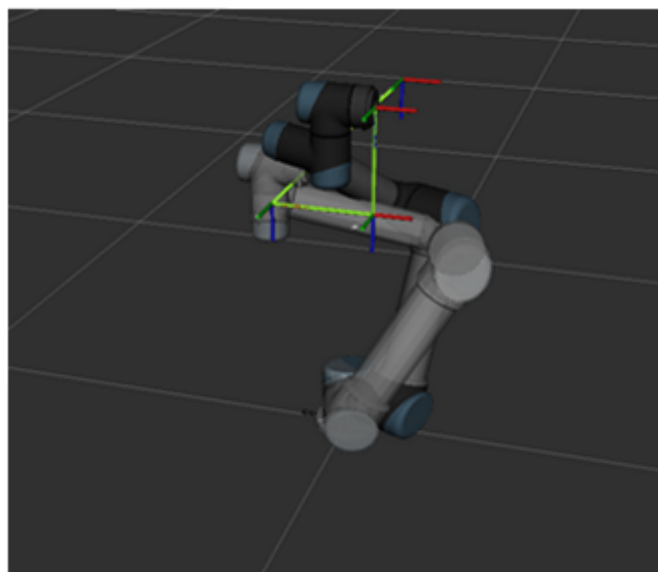
start point to goal point



draw a arc



draw lines



obstacle test

