### INCOMPLETENESS FOR STABLY COMPUTABLE FORMAL SYSTEMS

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ABSTRACT. We prove, for stably computably enumerable formal systems, direct analogues of the first and second incompleteness theorems of Gödel. A typical stably computably enumerable set is the set of Diophantine equations with no integer solutions, and in particular such sets are generally not computably enumerable. And so this gives the first extension of the second incompleteness theorem to non classically computable formal systems. Let's motivate this with a somewhat physical application. Let  $\mathcal H$  be the suitable infinite time limit (stabilization in the sense of the paper) of the mathematical output of humanity, specializing to first order sentences in the language of arithmetic (for simplicity), and understood as a formal system. Suppose that all the relevant physical processes in the formation of  $\mathcal H$  are Turing computable. Then as defined  $\mathcal H$  may not be computably enumerable, but it is stably computably enumerable. Thus, the classical Gödel disjunction applied to  $\mathcal H$  is meaningless, but applying our incompleteness theorems to  $\mathcal H$  we then get a sharper version of Gödel's disjunction: assume  $\mathcal H \vdash PA$  then either  $\mathcal H$  is not stably computably enumerable or  $\mathcal H$  is not 1-consistent (in particular is not sound) or  $\mathcal H$  cannot prove a certain true statement of arithmetic (and cannot disprove it if in addition  $\mathcal H$  is 2-consistent).

#### 1. Introduction

For an introduction/motivation based around physical ideas the reader may see Appendix A. We begin by quickly introducing the notion of stable computability, in a specific context.

Let  $\mathcal{A}$  denote the abstract set of first order sentences of arithmetic. And suppose we are given a partial map

$$M: \mathbb{N} \to \mathcal{A} \times \{\pm\},\$$

for  $\{\pm\}$  denoting a set with two elements +, -.

# Definition 1.1.

•  $\alpha \in \mathcal{A}$  is M-stable if there is an m with  $M(m) = (\alpha, +)$  s.t. there is no n > m with  $M(n) = (\alpha, -)$ . Let  $M^s \subset \mathcal{A}$  be the set of M-stable  $\alpha$ , called the stabilization of M.

If we informally understand M as a "machine" producing arithmetic "truths", while allowing for corrections, then the above could be given the following interpretation.  $M(n) = (\alpha, +)$  only if at the moment n M decides that  $\alpha$  is true. Meanwhile,

$$M(m) = (\alpha, -)$$

only if at the moment m, M no longer asserts that  $\alpha$  is true, either because at this moment M is unable to decide  $\alpha$ , or because it has decided it to be false.

In this paper, what we are mainly interested in, are the sets  $M^s$  and their properties. The following definition is preliminary, as we did not yet define Turing machines with abstract sets of inputs and outputs, see Section 2.1, and Definition 3.2 for a complete definition.

**Definition 1.2.** A subset  $S \subset \mathcal{A}$ , is called stably computably enumerable or stably c.e. if there is a Turing machine  $T : \mathbb{N} \to \mathcal{A} \times \{\pm\}$  so that  $S = T^s$ . In this case, we will say that T stably computes S.

It is important to note right away that S may well be not c.e. but still be stably c.e., see Example 3.3.

Let RA denote Robinson arithmetic that is Peano arithmetic PA without induction. Let  $\mathcal{F}_0$  denote the set of RA-decidable formulas  $\phi$  in arithmetic with one free variable. We recall the following:

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**Definition 1.3.** Given  $F \subset A$ , understood as formal system in the language of arithmetic, we say that it is 1-consistent if it is consistent, if  $F \vdash RA$ , and if for any formula  $\phi \in \mathcal{F}_0$  the following holds:

$$F \vdash \exists m : \phi(m) \implies \neg \forall m : F \vdash \neg \phi(m).$$

We say that it is 2-consistent if the same holds for  $\Pi_1$  formulas  $\phi$  with one free variable, more specifically formulas  $\phi = \forall n : g(m, n)$ , with g RA-decidable.

The first theorem below is a direct generalization of the modern form of Gödel's first incompleteness theorem, as we mainly just weaken the assumption of F being c.e. to being stably c.e.

**Theorem 1.4.** Suppose that  $F \subset A$  is stably c.e., and  $F \vdash PA$ . Then there is a constructible, from a specification of a Turing machine T stably computing F, sentence  $\alpha(F) \in A$  so that  $F \nvdash \alpha(F)$  if F is 1-consistent and  $F \nvdash \neg \alpha(F)$  if F is 2-consistent.

The second theorem below directly generalizes the more striking second incompleteness theorem of Gödel. Some ramifications of this are discussed in Appendix A.

**Theorem 1.5.** Let F, T and  $\alpha(F)$  be as in the theorem just above. Then

$$(1.6) (F is 1-consistent) \implies \alpha(F)$$

is a theorem of PA. More formally stated, the sentence (1.6) is logically equivalent in ZF to an arithmetic sentence provable by PA. In particular,  $\alpha(F)$  is true in the standard model of arithmetic whenever F is 1-consistent. Consequently, since by assumption  $F \vdash PA$ ,

$$F \nvdash (F \text{ is 1-consistent}),$$

that is F cannot prove its own 1-consistency.

The above theorems will be entirely formalized in set theory ZF, (in other words meta-logic will not appear).

- 1.1. Relationship with known results. The main distinction with the theorems of Gödel is that the set F is merely  $\Sigma_2$  definable when F is stably c.e. As far as the first incompleteness Theorem 1.4, there is much previous history on attempts of generalizations of a similar kind dating almost back to Gödel. To give one recent example, in the work of Salehi and Seraji [17], which we also recommend for additional references, the general Corollary 2.11 partially implies Theorem 1.4, when F is deductively closed (which is not our assumption, but this might not be material). One further possible difference is that our sentence is constructible. Surprisingly, the authors of [17] point out that in general when n is at least 3 for a  $\Sigma_{n+1}$  definable, n-consistent theory F there is no constructible,  $\Pi_{n+1}$  definable, F independent sentence, although such a sentence does exist. On the other hand, I am not aware of any previous results on generalizations of the second incompleteness theorem to non computably enumerable formal systems. As pointed out in [17] there are examples of complete, consistent  $\Delta_2$  definable extensions of PA. So that any extensions of the second Gödel incompleteness theorem to  $\Delta_2$  definable sets must require stronger consistency assumptions. The second Theorem 1.5 says that 1-consistency is sufficient, when F is stably c.e. We will discuss some further background and ramifications for Theorem 1.5 in Appendix A.
- 1.2. **Generalizations.** There are natural candidates for how to generalize theorems above. We may replace  $M: \mathbb{N} \to \mathcal{A} \times \{\pm\}$  by  $M: \mathbb{N}^n \to \mathcal{A} \times \{\pm\}$ , using this we can define a notion of n-stable computability, specializing to stable computability for n=1. This is theoretically very interesting, but is difficult and a practical motivation for such a notion is less clear, so we will not presently attempt to develop things in such generality.

Finally, we note that, our argument also readily reproves the original first and second incompleteness theorems of Gödel from first principles and within set theory <sup>1</sup>, with our Gödel sentence constructed directly via the theory of Turing machines. In particular, the somewhat mysterious to non-logicians diagonal Lemma, ordinarily used in modern renditions of the proof, is not used.

 $<sup>^{1}</sup>$ Assuming existence of a certain encoding category  $\mathcal{S}$ , which is already essentially constructed by Gödel.

#### 2. Some preliminaries

For more details on Turing machines we recommend the book of Soare [18]. Our approach here is however possibly novel in that we do not work with concrete Gödel encodings, instead abstractly axiomatizing their expected properties. This results in a certain encoding category, which will allow us to work with the language of set theory more transparently.

What follows is the definition of our variant of a Turing machine, which is a computationally equivalent, minor variation of Turing's original machine. We go over these basics primarily to set notation. The main preliminaries start in Section 2.1.

## **Definition 2.1.** A Turing machine M consists of:

- Three infinite (1-dimensional) tapes  $T_i, T_o, T_c$ , (input, output and computation) divided into discreet cells, next to each other. Each cell contains a symbol from some finite alphabet  $\Gamma$  with at least two elements. A special symbol  $b \in \Gamma$  for blank, (the only symbol which may appear infinitely many often).
- Three heads  $H_i$ ,  $H_o$ ,  $H_c$  (pointing devices),  $H_i$  can read each cell in  $T_i$  to which it points,  $H_o$ ,  $H_c$  can read/write each cell in  $T_o$ ,  $T_c$  to which they point. The heads can then move left or right on the tape.
- A finite set of internal states Q, among these is "start" state  $q_0$ . And a non-empty subset  $F \subset Q$  of final states.
- Input string  $\Sigma$ : the collection of symbols on the tape  $T_i$ , so that to the left and right of  $\Sigma$  there are only symbols b. We assume that in state  $q_0$   $H_i$  points to the beginning of the input string, and that the  $T_c$ ,  $T_o$  have only b symbols.
- A finite set of instructions: I, that given the state q the machine is in currently, and given the symbols the heads are pointing to, tells M to do the following. The actions taken, 1-3 below, will be (jointly) called an executed instruction set or just step:
  - (1) Replace symbols with another symbol in the cells to which the heads  $H_c$ ,  $H_o$  point (or leave them).
  - (2) Move each head  $H_i, H_c, H_o$  left, right, or leave it in place, (independently).
  - (3) Change state q to another state or keep it.
- Output string  $\Sigma_{out}$ , the collection of symbols on the tape  $T_o$ , so that to the left and right of  $\Sigma_{out}$  there are only symbols b, when the machine state is final. When the internal state is one of the final states we ask that the instructions are to do nothing, so that these are frozen states.

**Definition 2.2.** A complete configuration of a Turing machine M or total state is the collection of all current symbols on the tapes, position of the heads, and current internal state. Given a total state  $\mathfrak{s}$ ,  $\delta^M(\mathfrak{s})$  will denote the successor state of  $\mathfrak{s}$ , obtained by executing the instructions set of M on  $\mathfrak{s}$ , or in other words  $\delta^M(\mathfrak{s})$  is one step forward from  $\mathfrak{s}$ .

So a Turing machine determines a special kind of function:

$$\delta^M: \mathcal{C}(M) \to \mathcal{C}(M),$$

where  $\mathcal{C}(M)$  is the set of possible total states of M.

Definition 2.3. A Turing computation, or computation sequence for M is a possibly not eventually constant sequence

$$*M(\Sigma) := \{\mathfrak{s}_i\}_{i=0}^{i=\infty}$$

of total states of M, determined by the input  $\Sigma$  and M, with  $\mathfrak{s}_0$  suitable initial configuration, in particular having internal state is  $q_0$ , and where  $\mathfrak{s}_{i+1} = \delta^M(\mathfrak{s}_i)$ . If the sequence  $\{\mathfrak{s}_i\}_{i=0}^{i=\infty}$  is eventually constant:  $\mathfrak{s}_i = \mathfrak{s}_{\infty}$  for  $\forall i > n$ , for some n, and if the internal state of  $\mathfrak{s}_{\infty}$  is a final state, then we say that the computation halts. For a given Turing computation  $*M(\Sigma)$ , we will write

$$*M(\Sigma) \to x$$
,

if  $*M(\Sigma)$  halts and x is the corresponding output string.

We write  $M(\Sigma)$  for the output string of M, given the input string  $\Sigma$ , if the associated Turing computation  $*M(\Sigma)$  halts. Denote by Strings the set of all finite strings of symbols in  $\Gamma$ . Then a Turing machine M determines a partial function that is defined on all  $\Sigma \in Strings$  s.t.  $*M(\Sigma)$  halts, by  $\Sigma \mapsto M(\Sigma)$ .

In practice, it will be convenient to allow our Turing machine T to reject some elements of Strings as valid input. We may formalize this by asking that there is a special final machine state  $q_{reject} \in F$  so that  $T(\Sigma)$  halts with internal state  $q_{reject}$ . In this case we say that T rejects  $\Sigma$ . The set  $\mathcal{I} \subset Strings$  of strings not rejected by T is also called the set of T-permissible input strings. We do not ask that for  $\Sigma \in \mathcal{I} *T(\Sigma)$  halts. If  $*T(\Sigma)$  does halt then we will say that  $\Sigma$  is T-acceptable.

**Definition 2.4.** We denote by  $\mathcal{T}$  the set of all Turing machines with a distinguished final machine state  $q_{reject}$ .

Instead of tracking  $q_{reject}$  explicitly, we may write

$$T:\mathcal{I}\to\mathcal{O}$$
,

where  $\mathcal{I} \subset Strings$  is understood as the subset of all T-permissible strings, or just  $input \ set$  and  $\mathcal{O}$  is the set output strings or  $output \ set$ .

**Definition 2.5.** Given a partial function

$$f: \mathcal{I} \to \mathcal{O},$$

we say that a Turing machine  $T \in \mathcal{T}$ 

$$T:\mathcal{I}\to\mathcal{O}$$

**computes** f if T = f as partial functions on  $\mathcal{I}$ . In other words the set of permissible strings of T is  $\mathcal{I}$ , and as a partial function on  $\mathcal{I}$ , T = f. We say that f is **computable** if such a T exists.

2.1. Abstractly encoded sets and abstract Turing machines. The material of this section will be used in the main arguments. Instead of specifying Gödel encodings we just axiomatize their expected properties. Working with encoded sets/maps as opposed to concrete subsets of  $\mathbb{N}$ /functions will have some advantages as we can involve set theory more transparently, and construct computable functions axiomatically. This kind of approach is likely very obvious to experts, but I am not aware of this being explicitly introduced in computability theory literature. As I myself am not an expert I wanted to make it explicit for my own sake.

An **encoding** of a set A is at the moment just an injective set map  $e: A \to Strings$ . But we will need to axiomatize this further. The **encoding category** S will be a certain small "arrow category" whose objects are maps  $e_A: A \to Strings$ , for  $e_A$  an embedding called **encoding map of** A, determined by a set A. More explicitly, the set of objects of S consists of some set of pairs  $(A, e_A)$  where A is a set, and  $e_A: A \to Strings$  an embedding, determined by A. We may denote  $e_A(A)$  by  $A_e$ . We now describe the morphisms. Suppose that we are given a commutative diagram:

$$A \xrightarrow{T} B$$

$$\downarrow_{e_A} \qquad \downarrow_{e_B}$$

$$A_e \subset Strings \xrightarrow{T_e} B_e \subset Strings,$$

where T is a partial map, and  $T_e \in \mathcal{T}$  is a Turing machine in the standard sense above, with the set of permissible inputs  $A_e$ . Then the set of morphisms from  $(A, e_A)$  to  $(B, e_B)$  consists of equivalence classes of such commutative diagrams  $(T, T_e)$ , where the equivalence relation is  $(T, T_e) \sim (T', T'_e)$  if T = T'. If in addition a morphism has a representative (of the equivalence class)  $(T, T_e)$ , with  $T_e$  primitive recursive then we call it a *a primitive recursive morphism*.

**Notation 1.** We may just write  $A \in \mathcal{S}$  for an object, with  $e_A$  implicit.

We call such an  $A \in \mathcal{S}$  an **abstractly encoded set** so that  $\mathcal{S}$  is a category of abstractly encoded sets. The morphisms set from between objects A, B in  $\mathcal{S}$  as usual will be denoted by  $hom_{\mathcal{S}}(A, B)$ . The composition maps

$$hom_{\mathcal{S}}(A,B) \times hom_{\mathcal{S}}(B,C) \to hom_{\mathcal{S}}(A,C)$$

are defined once we fix a prescription for the composition of Turing machines. That is

$$[(T, T_e)] \circ [(T', T'_e)] = [(T \circ T', T_e \circ T'_e)],$$

for  $[\cdot]$  denoting the equivalence class and  $[(T, T_e)] \in hom_{\mathcal{S}}(B, C)$  and  $[(T', T'_e)] \in hom_{\mathcal{S}}(A, B)$ . In addition, we ask that  $\mathcal{S}$  satisfies the following axioms.

- (1) For  $A \in \mathcal{S}$   $A_e$  is computable (recursive). Here, as is standard, a set  $S \subset Strings$  is called computable if both S and its complement are computably enumerable, with S called computably enumerable if there is a computable partial function  $Strings \to Strings$  with range S.
- (2) For  $A, B \in \mathcal{S}$ ,

$$(A_e \cap B_e) = \emptyset.$$

In particular each  $A \in \mathcal{S}$  is determined by  $A_e$ .

(3) If  $A, B \in \mathcal{S}$  then  $A \times B \in \mathcal{S}$  and the projection maps  $pr^A : A \times B \to A$ ,  $pr^B : A \times B \to B$  complete to primitive recursive morphisms of  $\mathcal{S}$ , so that in particular we have a commutative diagram:

$$\begin{array}{c} A \times B \xrightarrow{pr^A} A \\ \downarrow^{e_{A \times B}} & \downarrow^{e_A} \\ (A \times B)_e \xrightarrow{pr_e^A} A_e, \end{array}$$

similarly for  $pr^B$ .

- (4) If  $f: A \to B$  completes to a morphism of  $\mathcal{S}$ , and  $g: A \to C$  completes to a morphism of  $\mathcal{S}$  then  $A \to B \times C$ ,  $a \mapsto (f(a), g(a))$  completes to a morphism of  $\mathcal{S}$ . This combined with Axiom 3 implies that if  $f: A \to B$ ,  $g: C \to D$  extend to morphisms of  $\mathcal{S}$  then the map  $A \times B \to C \times D$ ,  $(a,b) \mapsto (f(a),g(b))$  extends to a morphism of  $\mathcal{S}$ .
- (5) The set  $\mathcal{U} = Strings$  and  $\mathcal{T}$  are encoded i.e.  $\mathcal{U}, \mathcal{T} \in \mathcal{S}$ . We use the alternative name  $\mathcal{U}$  for Strings, as in this case the encoding map has the same domain and range, which is possibly confusing. The partial map

$$U: \mathcal{T} \times \mathcal{U} \to \mathcal{U}$$
,

 $U(T, \Sigma) := T(\Sigma)$  whenever  $*T(\Sigma)$  halts and undefined otherwise, extends to a morphism of S. We can understand a representative of the morphism  $(U, U_e)$  as the "universal Turing machine".

- (6) The encoding map  $e_{\mathcal{U}}: \mathcal{U} \to Strings$  is classically computable. (This makes sense since  $\mathcal{U} = Strings$ ). It follows from this that for  $A \in \mathcal{S}$  the encoding map  $e_A: A \to \mathcal{U}$  itself extends to a morphism of  $\mathcal{S}$ .
- (7) The next axiom gives a prescription for construction of Turing machines. Let  $A, B, C \in \mathcal{S}$ , and suppose that  $f: A \times B \to C$  extends to a morphism of  $\mathcal{S}$ . Let  $f^a: B \to C$  be the map  $f^a(b) = f(a, b)$ . Then there is a map

$$s:A\to\mathcal{T}$$

so that for each a  $(f^a, s(a))$  represents a morphism  $B \to C$ , and so that s extends to a morphism of S.

(8) The final axiom is for utility. If  $A \in \mathcal{S}$  then  $L(A) \in \mathcal{S}$ , where

$$L(A) = \bigcup_{n \in \mathbb{N}} Maps(\{0, \dots, n\}, A),$$

and  $Maps(\{0,\ldots,n\},A)$  denotes the set of total maps. We also have:

(a) N is encoded.

(b) Let  $A \in \mathcal{S}$  and let

length : 
$$L(A) \to \mathbb{N}$$
,

be the length function, s.t. for  $l \in L(A)$ ,  $l : \{0, ... n\} \to A$ , length(l) = n. Then length extends to a morphism of S.

(c)

$$P: L(A) \times \mathbb{N} \to A$$

extends to a morphism of S, where P(l,i) := l(i), where P(l,i) is undefined for i > length(l)

(d) For  $A, B \in \mathcal{S}$  and  $f: A \to L(B)$  a partial map, if the partial map  $A \times \mathbb{N} \to B$ ,  $(a, n) \mapsto P(f(a), n)$  extends to a morphism of  $\mathcal{S}$  then f extends to a morphism of  $\mathcal{S}$ . In particular, the above axioms imply the following. If  $f: A \to B$  extends to a morphism of  $\mathcal{S}$  then the map  $L(f): L(A) \to L(B)$ ,

$$l \mapsto \begin{cases} i \mapsto f(l(i)), & \text{if } f(l(i)) \text{ is defined for all } 0 \leq i \leq \text{length}(l) \\ undefined & \text{otherwise.} \end{cases}$$

extends to a morphism of S. Also, the map  $LU: \mathcal{T} \times L(\mathcal{U}) \to L(\mathcal{U})$ ,

$$LU(T,l)(i) := \begin{cases} U(T,(l(i))), & \text{if } U(T,(l(i))) \text{ is defined for all } 0 \leq i \leq \text{length}(l) \\ undefined, & \text{otherwise} \end{cases}$$

extends to a morphism of S.

The above axioms suffice for our purposes, but there are a number of possible extensions (dealing with other set theoretic constructions). The specific such category  $\mathcal S$  that we need will be clear from context later on. We only need to encode finitely many types of specific sets. For example  $\mathcal S$  should contain  $\mathbb N$ ,  $\mathcal A$ ,  $\{\pm\}$ , with  $\{\pm\}$  a set with two elements +, -. The encoding of  $\mathbb N$  should be suitably natural so that for example the map

$$\mathbb{N} \to \mathbb{N}, \quad n \mapsto n+1$$

completes to a primitive recursive morphism in S. Strictly speaking this is part of the axioms. The main naturality axiom for the encoding of T is already stated as Axiom 5.

The fact that such encoding categories S exist is a folklore theorem starting with foundational work of Gödel, Turing and others. Indeed, S can be readily constructed from standard Gödel encodings. For example Axiom 7, in classical terms, just reformulates the following elementary fact, which follows by the "s-m-n theorem" Soare [18, Theorem 1.5.5]. Given a classical 2-input Turing machine  $T: \mathbb{N} \times \mathbb{N} \to \mathbb{N}$ , there is a Turing machine  $s_T: \mathbb{N} \to \mathbb{N}$  s.t. for each  $n s_T(n)$  is the Gödel number of a Turing machine computing the map  $m \mapsto T(n, m)$ .

In modern terms, the construction of S is just a part of a definition of a computer programming language.

**Definition 2.6.** For  $A, B \in \mathcal{S}$ , an abstract Turing machine from A to B,  $(T, T_e): A \to B$ , will be a synonym for a class representative of an element of  $hom_{\mathcal{S}}(A, B)$ . In other words it is a pair  $(T, T_e)$  as above. We will say that the corresponding Turing machine  $T_e$  encodes the map T or is the encoding of T. We may simply write  $T: A \to B$  for an abstract Turing machine, when  $T_e$  is implicit. We write  $hom_{\mathcal{S}}(A, B)$  for the set of abstract Turing machines from A to B.

Often we will say Turing machine in place of abstract Turing machine, since usually there can be no confusion as to the meaning.

We define  $\mathcal{T}_{\mathcal{S}}$  to be the set of abstract Turing machines relative to  $\mathcal{S}$  as above. More formally:

$$\mathcal{T}_{\mathcal{S}} = \bigcup_{(A,B)\in\mathcal{S}^2} \overline{hom}_{\mathcal{S}}(A,B).$$

For writing purposes we condense the above as follows.

**Definition 2.7.** An **encoded map** will be a synonym for a partial map  $M: A \to B$ , with A, B abstractly encoded sets. When A, B are understood to be encoded we may just say map instead of encoded map, particularly when M is total. Maps(A, B) will denote the set of encoded maps from A to B.

The set

$$\mathcal{M}_{\mathcal{S}} := \bigcup_{(A,B)\in\mathcal{S}^2} Maps(A,B)$$

will denote the set of encoded maps. Given a Turing machine  $T: A \to B$ , we have an associated map  $fog(T): A \to B$  defined by forgetting the additional structure  $T_e$ . However, we may also just write T for this map by abuse of notation. So we have a forgetful map

$$fog: \mathcal{T}_{\mathcal{S}} \to \mathcal{M}_{\mathcal{S}},$$

which forgets the extra structure of an encoding Turing machine.

**Definition 2.8.** We say that  $T \in \mathcal{T}_{\mathcal{S}}$  computes  $M \in \mathcal{M}_{\mathcal{S}}$  if fog(T) = M. We say that M is computable if some T computes M, or equivalently if T extends to a morphism of  $\mathcal{S}$ .

### 3. Stable computability and arithmetic

In this section, general sets, often denoted as B, are intended to be encoded. And all maps are partial maps, unless specified otherwise.

**Definition 3.1.** Given a Turing machine or just a map:

$$M: \mathbb{N} \to B \times \{\pm\},\$$

We say that  $b \in B$  is M-stable if there is an m with M(m) = (b, +) and there is no n > m with M(n) = (b, -).

**Definition 3.2.** Given a Turing machine or just a map

$$M: \mathbb{N} \to B \times \{\pm\},\$$

we define

$$M^s \subset B$$

to be the of all the M-stable b. We call this the stabilization of M. We say that  $S \subset B$  is stably c.e. if  $S = M^s$  for M as above.

In general  $M^s$  may not be computable even if M is computable. Explicit examples of this sort can be readily constructed as shown in the following.

Example 3.3. Let Pol denote the set of all Diophantine polynomials, (also abstractly encoded). We can construct a total computable map

$$A: \mathbb{N} \to Pol \times \{\pm\}$$

whose stabilization consists of all Diophantine (integer coefficients) polynomials with no integer roots. Similarly, we can construct a computable map D whose stabilization consists of pairs (T, n) for  $T : \mathbb{N} \to \mathbb{N}$  a Turing machine and  $n \in \mathbb{N}$  such that \*T(n) does not halt.

In the case of Diophantine polynomials, here is an (inefficient) example. Let

$$Z: \mathbb{N} \to Pol, N: \mathbb{N} \to \mathbb{Z}$$

be total bijective computable maps. The encoding of *Pol* should be suitably natural so that in particular the map

$$E: \mathbb{Z} \times Pol \to \mathbb{Z}, \quad (n, p) \mapsto p(n)$$

is computable. In what follows, for each  $n \in \mathbb{N}$ ,  $A_n$  has the type of ordered finite list of elements of  $Pol \times \{\pm\}$ , with order starting from 0. Specifically, such a list is a function  $f : \{0, \ldots, n\} \to Pol \times \{\pm\}$  for some  $n \in \mathbb{N}$ . Usually, will be here and elsewhere in the paper the natural list union operation. More specifically,

if  $f_1:\{0,\ldots,n\}\to Pol\times\{\pm\}, f_2:\{0,\ldots,m\}\to Pol\times\{\pm\}$  are two such lists then  $f_1\cup f_2$  is defined by:

(3.4) 
$$f_1 \cup f_2(i) = \begin{cases} f_1(i), & \text{if } i \in \{0, \dots, n\} \\ f_2(i), & \text{if } i \in \{n+1, \dots, n+m+1\} \end{cases}.$$

Define  $A_n$  recursively by:  $A_0 := \emptyset$ ,

$$A_{n+1}:=A_n\cup\bigcup_{m=0}^n(Z(m),d^n(Z(m))),$$
 where  $d^n(p)=+$  if none of  $\{N(0),\ldots,N(n)\}$  are roots of  $p,\,d^n(p)=-$  otherwise.

Set  $A := \bigcup_n A_n$ , which is an ordered infinite list i.e. a map  $A : \mathbb{N} \to Pol \times \{\pm\}$ . Since E is computable, utilizing Axiom 4 it can be explicitly verified that A is computable, i.e. an encoding Turing machine can be explicitly constructed, from the recursive program above. Moreover, by construction the stabilization  $A^s$  consists of Diophantine polynomials that have no integer roots.

## 3.1. **Decision maps.** By a *decision map*, we mean a map of the form:

$$D: B \times \mathbb{N} \to \{\pm\}.$$

This kind of maps will play a role in our arithmetic incompleteness theorems, and we now develop some of their theory.

# **Definition 3.5.** Let $B \in \mathcal{S}$ , define

$$A\mathcal{D}_B := \overline{hom}_{\mathcal{S}}(B \times \mathbb{N}, \{\pm\}),$$

and define

$$\mathcal{D}_B := \{ T \in \mathcal{T} | T = T'_e \text{ for } (T', T'_e) \in A\mathcal{D}_B \}.$$

Since T' above is uniquely determined, from now, for  $T \in \mathcal{D}_B$ , when we write T' it is meant to be of the form above.

First we will explain construction of elements of  $\mathcal{D}_B$  from Turing machines of the following form.

### **Definition 3.6.** Let $B \in \mathcal{S}$ , define

$$A\mathcal{T}_B := \overline{hom}_{\mathcal{S}}(\mathbb{N}, B \times \{\pm\}),$$

and define

$$\mathcal{T}_B := \{ T \in \mathcal{T} | T = T'_e \text{ for } (T', T'_e) \in A\mathcal{T}_B \}.$$

From now on, given  $T \in \mathcal{T}_{\mathcal{B}}$ , if we write T' then it is will be assumed to be of the form above.

### **Lemma 3.7.** Let $B \in \mathcal{S}$ . There is a computable total map

$$K_B: \mathcal{T} \to \mathcal{T}$$
,

with the properties:

- (1) For each T,  $K_B(T) \in \mathcal{T}_B$ .
- (2) If  $T \in \mathcal{T}_B$  then  $K_B(T)$  and T encode the same map  $\mathbb{N} \to B \times \{\pm\}$ , in other words  $T' = (K_B(T))'$ .

*Proof.* Let  $G: \mathcal{T} \times \mathbb{N} \to B \times \{\pm\}$  be the composition of the sequence of maps

$$\mathcal{T} \times \mathbb{N} \xrightarrow{id \times e_{\mathbb{N}}} \mathcal{T} \times \mathcal{U} \xrightarrow{U} \mathcal{U} \xrightarrow{e_{B \times \{\pm\}}^{-1}} B \times \{\pm\},$$

where the last map  $e_{B \times \{\pm\}}^{-1}$  is defined by:

$$\Sigma \mapsto \begin{cases} e_{B \times \{\pm\}}^{-1}(\Sigma) & \text{if } \Sigma \in (B \times \{\pm\})_e \\ \text{undefined} & \text{otherwise.} \end{cases}$$

In particular, this last map is computable as  $(B \times \{\pm\})_e$  is by assumption computable/decidable. Hence, G is a composition of computable maps and so is computable. By Axiom 7 there is an induced computable map  $K_B: \mathcal{T} \to \mathcal{T}$  so that  $K_B(T)$  is the encoding of  $G^T: \mathbb{N} \to B \times \{\pm\}$ ,  $G^T(n) = G(T, n)$ . By construction, if  $T \in \mathcal{T}_B$  then  $T' = (K_B(T))'$ , so that we are done.

### 3.1.1. Constructing decision Turing machines.

**Definition 3.8.** Let  $l \in L(B \times \{\pm\})$ ,  $l : \{0, ..., n\} \to B \times \{\pm\}$ . Define  $b \in B$  to be l-stable if there is an  $m \le n$  s.t. l(m) = (b, +) and there is no  $m < k \le n$  s.t. l(k) = (b, -). Let  $T \in \mathcal{T}_B$ . Define  $b \in B$  to be (T, n)-stable if there is an  $m \le n$  s.t. T(m) = (b, +) and there is no  $m < k \le n$  s.t. T(k) = (b, -). We say that b is T-stable if it is T'-stable in the previous sense, or equivalently b is (T, n)-stable for all n.

Define G to be the composition of the sequence of maps:

$$\mathcal{T} \times B \times \mathbb{N} \xrightarrow{K_B \times e_B \times id} \mathcal{T} \times \mathcal{U} \times \mathbb{N} \to B \times L(\mathcal{U}) \xrightarrow{id \times L(e_{B \times \{\pm\}}^{-1})} B \times L(B \times \{\pm\}) \to \{\pm\},$$

where the maps are as follows. Let #i denote  $e_{\mathbb{N}}(i)$ . Then the second map is the map

$$(T,b,n) \mapsto \begin{cases} (b,\{T(\#0),\dots,T(\#n)\}), \text{ if } T(\#i) \text{ is defined for all } 0 \leq i \leq n, \\ undefined \text{ otherwise.} \end{cases}$$

This map is computable directly by the Axioms 5, 8d and 4.  $e_{B\times\{\pm\}}^{-1}$  in the third map is as in the proof of Lemma 3.7, and  $L(e_{B\times\{\pm\}}^{-1})$  is as in Axiom 8. And the last map is:

$$(b,l) \mapsto \begin{cases} + & \text{if } b \text{ is } l\text{-stable} \\ - & \text{otherwise,} \end{cases}$$

which is computable by explicit verification utilizing Axiom 8. So all the maps in the composition are computable and so G is computable. Let

$$(3.9) Dec_B: \mathcal{T} \to \mathcal{T},$$

be the computable map corresponding G via Axiom 7. In particular this has the property:

$$\forall T \in \mathcal{T} : Dec_B(T) \in \mathcal{D}_B$$
,

and more specifically,  $Dec_B(T)$  is the encoding of  $G^T: B \times \mathbb{N} \to \{\pm\}, G^T(b,n) = G(T,b,n)$ .

**Definition 3.10.** For a Turing machine or just a map  $D: B \times N \to \{\pm\}$ , we say that  $b \in B$  is D-decided if there is an m s.t. D(b,m) = + and for all  $n \ge m$   $D(b,n) \ne -$ . Likewise, for  $T \in \mathcal{D}_B$  we say that  $b \in B$  is T-decided if it is T'-decided.

**Lemma 3.11.** Let  $T \in \mathcal{T}$ , and suppose that  $K_B(T)$  is total then b is  $K_B(T)$ -stable iff b is  $Dec_B(T)$ -decided.

*Proof.* Suppose that b is  $K_B(T)$ -stable. In particular, there is an  $m \in \mathbb{N}$  so that b is  $(K_B(T), n)$ -stable for all  $n \geq m$ . Thus, by construction

$$\forall n \geq m : G(T, b, n) = +$$

and so b is  $G^T$ -decided (this is as above), and so  $Dec_B(T)$ -decided.

Similarly, suppose that b is  $Dec_B(T)$ -decided, then there is an m s.t. G(T,b,m)=+ and there is no n>m s.t. G(T,b,n)=-. It follows that  $\exists m'\leq m: K_B(m')=(b,+)$  and there is no n>m' s.t.  $K_B(n)=(b,-)$ . And so b is  $K_B(T)$ -stable.

Example 3.12. By the Example 3.3 above there is a Turing machine

$$P = Dec_{\mathcal{A}}(A) : Pol \times \mathbb{N} \to \{\pm\}$$

that stably soundly decides if a Diophantine polynomial has integer roots, meaning:

$$p$$
 is  $P$ -decided  $\iff p$  has no integer roots.

Likewise, there is a Turing decision machine that stably soundly decides the halting problem, in this

**Definition 3.13.** Given a map

$$M: B \times \mathbb{N} \to \{\pm\}$$

and a Turing machine

$$M': B \times \mathbb{N} \to \{\pm\},\$$

we say that M' stably computes M if

$$b$$
 is  $M$ -decided  $\iff b$  is  $M'$ -decided.

If  $T \in \mathcal{D}_B$  then we say that T stable computes M iff T' stably computes M. Here, as before,  $T' \in A\mathcal{D}_B$ is such that  $T'_e = T$ .

3.2. Arithmetic decision maps. Let  $\mathcal{A}$  be as in the introduction the set of sentences of arithmetic. Let  $\mathcal{T}_{\mathcal{A}}$  be as in Definition 3.6 with respect to  $B = \mathcal{A}$ . That is elements of  $\mathcal{T}_{\mathcal{A}}$  are of the form  $T = T'_e$ for  $(T', T'_e) \in A\mathcal{T}_A = \overline{hom}_{\mathcal{S}}(\mathbb{N}, A \times \{\pm\}).$ 

The following is a version for stably c.e. formal systems of the classical fact, going back to at least Gödel, that for a formal system with a c.e. set of axioms, we may computably enumerate its theorems. Moreover, the procedure to obtain the corresponding Turing machine is constructive.

**Notation 2.** Note that each  $T \in \mathcal{T}_{\mathcal{A}}$ , determines the set

$$(T')^s \subset \mathcal{A},$$

called the stabilization of T', we hereby abbreviate the notation for this set as  $T^s$ .

**Lemma 3.14.** There is a computable total map:

$$C: \mathcal{T} \to \mathcal{T}$$

so that  $\forall T \in \mathcal{T} : C(T) \in \mathcal{T}_A$ , if in addition  $T \in \mathcal{T}_A$  and is total then  $(C(T))^s$  is the deductive closure of  $T^s$ .

*Proof.* Let L(A) be as in axioms of S, defined with respect to B = A. The following lemma is classical and its proof is omitted.

**Lemma 3.15.** There is a total Turing machine:

$$\Phi: L(\mathcal{A}) \times \mathbb{N} \to \mathcal{A}$$

with the following property. For each  $l \in L(A)$ ,  $\Phi(\{l\} \times \mathbb{N})$  is the set of all sentences provable by the formal system l, the latter being shorthand for the image of the corresponding map  $l: \{0, \ldots, n\} \to A$ .

Given  $T \in \mathcal{T}$  let  $(K_A(T))' : \mathbb{N} \to \mathcal{A} \times \{\pm\}$  be as in Lemma 3.7. Define a map

$$\zeta: \mathcal{T} \times \mathbb{N} \times L(\mathcal{A}) \to \{\pm\}$$

by

by 
$$\zeta(T,n,l) = \begin{cases} undefined & \text{if } K_{\mathcal{A}}(T)(i) \text{ is undefined for some } 0 \leq i \leq n \\ +, & \text{if for each } i \in \mathbb{N}, \ P(l,i) \text{ is } (K_{\mathcal{A}}(T),n)\text{-stable (this is as above in Definition 3.8)} \\ -, & \text{otherwise.} \end{cases}$$

We can express  $\zeta$  as the composition of the sequence of maps

$$\mathcal{T} \times \mathbb{N} \times L(\mathcal{A}) \xrightarrow{K_{\mathcal{A}} \times id \times id} \mathcal{T} \times \mathbb{N} \times L(\mathcal{A}) \to \mathcal{T} \times L(\mathbb{N}) \times L(\mathcal{A})$$

$$\xrightarrow{id \times L(e_{\mathbb{N}}) \times id} \mathcal{T} \times L(\mathcal{U}) \times L(\mathcal{A}) \xrightarrow{LU \times id} L(\mathcal{U}) \times L(\mathcal{A}) \xrightarrow{L(e_{\mathcal{A} \times \{\pm\}}) \times id} L(\mathcal{A} \times \{\pm\}) \times L(\mathcal{A}) \to \{\pm\}.$$

Here the unindicated maps are as follows. The last map is

$$(l,l') \mapsto \begin{cases} +, & \text{if for each } 0 \le i \le \text{length}(l') \ l'(i) \text{ is } l\text{-stable} \\ -, & \text{otherwise} \end{cases}$$

it is computable by explicit verification utilizing the axioms. And the second map is  $id \times g \times id$  for  $g: \mathbb{N} \to L(\mathbb{N})$  the map  $n \mapsto \{0, \dots, n\}$  it is computable directly by Axiom 8. Thus, all maps in the composition are computable and  $\zeta$  is computable.

Now define G to be the composition of the sequence of maps:

$$\mathcal{T} \times L(\mathbb{N}) \xrightarrow{K_{\mathcal{A}} \times L(e_{\mathbb{N}})} \mathcal{T} \times L(\mathcal{U}) \xrightarrow{LU} L(\mathcal{U}) \xrightarrow{L(e_{\mathcal{A} \times \{\pm\}}^{-1})} L(\mathcal{A} \times \{\pm\}) \xrightarrow{L(pr_{\mathcal{A}})} L(\mathcal{A}),$$

where  $pr_{\mathcal{A}}: \mathcal{A} \times \{\pm\} \to \mathcal{A}$  is the natural projection, and  $L(pr_{\mathcal{A}})$  is the induced map as in the Axioms of  $\mathcal{S}$ . The second map is as in Axiom 8. The third map is induced as in Axiom 8 by  $e_{\mathcal{A} \times \{\pm\}}$ , with the latter as in Lemma 3.7. The last map is induced as in Axiom 8 by  $pr_{\mathcal{A}}$ . All the maps in the composition are computable directly by the axioms of  $\mathcal{S}$  and so G is computable.

We may now construct our map C. In what follows  $\cup$  will be the natural list union operation as previously in (3.4). Set

$$L_n(\mathbb{N}):=\{l\in L(\mathbb{N})|\max l\leq n, \ \max l \ \text{the maximum of} \ l \ \text{as a map}\}.$$

For  $n \in \mathbb{N}$ , define  $U_n^T \in L(\mathcal{A} \times \{\pm\})$  recursively by  $U_0^T := \emptyset$ ,

$$U_{n+1}^T := U_n^T \cup \bigcup_{l \in L_{n+1}(\mathbb{N})} (\Phi(G(T,l),n+1),\zeta(T,n+1,G(T,l))).$$

Set  $U^T := \bigcup_n U_n^T$ , which is a partial map  $U : \mathbb{N} \to \mathcal{A} \times \{\pm\}$ . And this induces a partial map

$$U: \mathcal{T} \times \mathbb{N} \to \mathcal{A} \times \{\pm\},$$

 $U(T,n) := U^T(n)$ . U is computable by explicit verification, utilizing the axioms of S, i.e. an encoding Turing machine can be readily constructed from the recursive program above. Hence, by the Axiom 7 there is an induced by U computable map:

$$C: \mathcal{T} \to \mathcal{T}$$

s.t. for each  $T \in \mathcal{T}$  C(T) computes  $U^T$ . If  $T \in \mathcal{T}_{\mathcal{A}}$  and is total then  $(U^T)^s$  is by construction the deductive closure of  $(K_{\mathcal{A}}(T))^s = T^s$ . So the map C has the needed property, and we are done.  $\square$ 

**Definition 3.16.** Let  $\mathcal{F}_0$ , as in the introduction, denote the set of formulas  $\phi$  of arithmetic with one free variable so that  $\phi(n)$  is an RA-decidable sentence for each n. Let  $M : \mathbb{N} \to \mathcal{A} \times \{\pm\}$  be a map (or a Turing machine). The notation  $M \vdash \alpha$  will be short for  $M^s \vdash \alpha$ . We say that M is **speculative** if the following holds. Let  $\phi \in \mathcal{F}_0$ , and set

$$(3.17) \alpha_{\phi} = \forall m : \phi(m),$$

then

$$\forall m : RA \vdash \phi(m) \implies M \vdash \alpha_{\phi}.$$

Note that of course the left-hand side is not the same as  $RA \vdash \alpha_{\phi}$ .

We may informally interpret this condition as saying that M initially outputs  $\alpha$  as a hypothesis, and removes  $\alpha$  from its list (that is  $\alpha$  will not be in  $M^s$ ) only if for some m,  $RA \vdash \neg \phi(m)$ . Note that we previously constructed an Example 3.3 of a Turing machine, with an analogue of this speculative property. Moreover, we have the following crucial result, which to paraphrase states that there is an operation Spec that converts a stably c.e. formal system to a speculative stably c.e. formal system, at a certain loss of consistency.

**Theorem 3.18.** There is a computable total map  $Spec: \mathcal{T} \to \mathcal{T}$ , with the following properties:

- (1) image  $Spec \subset \mathcal{T}_{\mathcal{A}}$ .
- (2) Let  $T \in \mathcal{T}_{\mathcal{A}}$ . Set  $T_{spec} = Spec(T)$  then  $T'_{spec}$  is speculative.
- (3) Using Notation 2, if  $T \in \mathcal{T}_{\mathcal{A}}$  then  $T^s_{spec} \supset T^s$

(4) If  $T \in \mathcal{T}_{\mathcal{A}}$  and  $T^s$  is 1-consistent then  $T^s_{spec}$  is consistent.

*Proof.*  $\mathcal{F}_0$ ,  $\mathcal{A}$  are assumed to be encoded so that the map

$$ev: \mathcal{F}_0 \times \mathbb{N} \to \mathcal{A}, \quad (\phi, m) \mapsto \phi(m)$$

is computable.

**Lemma 3.19.** There is a total Turing machine  $F: \mathbb{N} \to \mathcal{F}_0 \times \{\pm\}$  with the property:

$$F^s = G := \{ \phi \in \mathcal{F}_0 \mid \forall m : RA \vdash \phi(m) \}.$$

*Proof.* The construction is analogous to the construction in the Example 3.3 above. Fix any total, bijective, Turing machine

$$Z: \mathbb{N} \to \mathcal{F}_0$$
.

For a  $\phi \in \mathcal{F}_0$  we will say that it is n-decided if

$$\forall m \in \{0, \dots, n\} : RA \vdash \phi(m).$$

In what follows each  $F_n$  has the type of ordered finite list of elements of  $\mathcal{F}_0 \times \{\pm\}$ , and  $\cup$  will be the natural list union operation, as previously. Define  $F_n$  recursively by  $F_0 := \emptyset$ ,

$$F_{n+1} := F_n \cup \bigcup_{\phi \in \{Z(0), \dots, Z(n)\}} (\phi, d^n(\phi)),$$

where  $d^n(\phi) = +$  if  $\phi$  is n-decided and  $d^n(\phi) = -$  otherwise.

Set  $F := \bigcup_n F_n$ , which is an ordered infinite list i.e. a map

$$F: \mathbb{N} \to \mathcal{F}_0 \times \{\pm\}.$$

F is computably by explicit verification, using the axioms of S.

Let  $K = K_{\mathcal{A}} : \mathcal{T} \to \mathcal{T}$  be as in Lemma 3.7. For  $\phi \in \mathcal{F}_0$  let  $\alpha_{\phi}$  be as in (3.17). Define:  $H : \mathcal{T} \times \mathbb{N} \to \mathcal{A} \times \{\pm\}$  by

$$H(T,n) := \begin{cases} (K_{\mathcal{A}}(T))'(k) & \text{if } n = 2k+1\\ (\alpha_{pr_{\mathcal{F}_0} \circ F(k)}, pr_{\pm} \circ F(k)) & \text{if } n = 2k, \end{cases}$$

where  $pr_{\mathcal{F}_0}: \mathcal{F}_0 \times \{\pm\} \to \mathcal{F}$ , and  $pr_{\pm}: \mathcal{F}_0 \times \{\pm\} \to \{\pm\}$  are the natural projections. H is computable directly by the axioms of  $\mathcal{S}$ . (Factor H as a composition of computable maps as previously.)

Let  $Spec: \mathcal{T} \to \mathcal{T}$  be the computable map corresponding to H via Axiom 7. In particular, for each  $T \in \mathcal{T}$ , Spec(T) encodes the map

$$T'_{spec} := H^T : \mathbb{N} \to \mathcal{A} \times \{\pm\}, \quad H^T(n) = H(T, n),$$

which by construction is speculative. Now, Spec(T) satisfies the Properties 1, 2, 3 immediately by construction. It only remains to check Property 4.

**Lemma 3.20.** Let  $T \in \mathcal{T}_A$ , then  $T^s_{spec}$  is consistent unless for some  $\phi \in G$ 

$$T^s \vdash \neg \forall m : \phi(m).$$

*Proof.* Suppose that  $T_{spec}^{s}$  is inconsistent so that:

$$T^s \cup \{\alpha_{\phi_1}, \dots, \alpha_{\phi_n}\} \vdash \alpha \land \neg \alpha$$

for some  $\alpha \in \mathcal{A}$ , and some  $\phi_1, \ldots, \phi_n \in G$ . Hence,

$$T^s \vdash \neg(\alpha_{\phi_1} \land \ldots \land \alpha_{\phi_n}).$$

But

$$\alpha_{\phi_1} \wedge \ldots \wedge \alpha_{\phi_n} \iff \forall m : \phi(m),$$

where  $\phi$  is the formula with one free variable:  $\phi(m) := \phi_1(m) \wedge \ldots \wedge \phi_n(m)$ . Clearly  $\phi \in G$ , since  $\phi_i \in G$ ,  $i = 1, \ldots, n$ . Hence, the conclusion follows.

Suppose that  $T^s_{spec}$  inconsistent, then by the lemma above for some  $\phi \in G$ :

$$T^s \vdash \exists m : \neg \phi(m).$$

Since  $T^s$  is 1-consistent:

$$\exists m : T^s \vdash \neg \phi(m).$$

But  $\phi$  is in G, and  $T^s \vdash RA$  (recall Definition 1.3) so that  $\forall m : T^s \vdash \phi(m)$  and so

$$\exists m : T^s \vdash (\neg \phi(m) \land \phi(m)).$$

So  $T^s$  is inconsistent, a contradiction, so  $T^s_{spec}$  is consistent.

### 4. Semantic incompleteness for stably computable formal systems

We start with the simpler semantic case, essentially for the purpose of exposition. However, many elements here will be reused for the main theorems in the next section.

Let  $\mathcal{D}_{\mathcal{T}} \subset \mathcal{T}$  be as in Definition 3.5 with respect to  $B = \mathcal{T}$ .

**Definition 4.1.** For  $T \in \mathcal{D}_{\mathcal{T}}$ , T is T-decided, is a special case of Definition 3.10. Or more specifically, it means that the element  $T \in \mathcal{T}$  is T'-decided. We also say that T is not T-decided, when  $\neg(T \text{ is } T\text{-decided}) \text{ holds.}$ 

**Definition 4.2.** We call a map  $D: \mathcal{T} \times \mathbb{N} \to \{\pm\}$  **Turing decision map**. We say that such a D is stably sound on  $T \in \mathcal{T}$  if

$$(T \text{ is } D\text{-decided}) \implies (T \in \mathcal{D}_{\mathcal{T}}) \wedge (T \text{ is not } T\text{-decided}).$$

We say that D is stably sound if it is stably sound on all T. We say that D stably decides T if:

$$(T \in \mathcal{D}_T) \wedge (T \text{ is not } T\text{-decided}) \implies T \text{ is } D\text{-decided}.$$

We say that D stably soundly decides T if D is stably sound on T and D stably decides T. We say that D is stably sound and complete if D stably soundly decides T for all  $T \in \mathcal{T}$ .

The informal interpretation of the above is that each such D is understood as an operation with the properties:

- For each T, n D(T, n) = + if and only if D "decides" at the moment n that the sentence  $(T \in \mathcal{D}_T) \wedge (T \text{ is not } T\text{-decided})$  is true.
- For each T, n D(T, n) = if and only if D cannot "decide" at the moment n the sentence  $(T \in \mathcal{D}_T) \wedge (T \text{ is not } T\text{-decided})$ , or D "decides" that it is false.

In what follows for  $T \in \mathcal{T}$ , and D as above,  $\Theta_{D,T}$  is shorthand for the sentence:

$$(T \in \mathcal{D}_{\mathcal{T}}) \wedge (T \text{ stably computes } D).$$

**Lemma 4.3.** If D is stably sound on  $T \in \mathcal{T}$  then

$$\neg \Theta_{D,T} \lor \neg (T \text{ is } D\text{-}decided).$$

*Proof.* If T is D-decided then since D is stably sound on T,  $T \in \mathcal{D}_{\mathcal{T}}$  and T is not T-decided, so if in addition  $\Theta_{D,T}$  then T is not D-decided a contradiction.

The following is the "stable" analogue of Turing's halting theorem.

**Theorem 4.4.** There is no (stably) computable Turing decision map D that is stably sound and complete.

*Proof.* Suppose otherwise, and let D be stably sound and complete. Then by the above lemma we obtain:

$$(4.5) \qquad \forall T \in \mathcal{D}_{\mathcal{T}} : \Theta_{D,T} \vdash \neg (T \text{ is } D\text{-decided}).$$

But it is immediate:

$$(4.6) \qquad \forall T \in \mathcal{D}_{\mathcal{T}} : \Theta_{D,T} \vdash (\neg (T \text{ is } D\text{-decided})) \vdash \neg (T \text{ is } T\text{-decided})).$$

So combining (4.5), (4.6) above we obtain

$$\forall T \in \mathcal{D}_T : \Theta_{D,T} \vdash \neg (T \text{ is } T\text{-decided}).$$

But D is complete so  $(T \in \mathcal{D}_T) \land \neg (T \text{ is } T\text{-decided}) \implies T \text{ is } D\text{-decided and so:}$ 

$$\forall T \in \mathcal{D}_{\mathcal{T}} : \Theta_{D,T} \vdash (T \text{ is } D\text{-decided}).$$

Combining with (4.5) we get

$$\forall T \in \mathcal{D}_{\mathcal{T}} : \neg \Theta_{D,T},$$

which is what we wanted to prove.

**Theorem 4.7.** Suppose  $F \subset A$  is stably c.e. and sound as a formal system, then there is a constructible (given a Turing machine stably computing F) true in the standard model of arithmetic sentence  $\alpha(F)$ , which F does not prove.

The fact that such an  $\alpha(F)$  exists, can be immediately deduced from Tarski undecidability of truth, as the set F must be definable in first order arithmetic by the condition that F is stably c.e. However, our sentence is constructible by very elementary means, starting with the definition of a Turing machine, and the basic form of this sentence will be used in the next section. The above is of course only a meta-theorem. This is in sharp contrast to the syntactic incompleteness theorems in the following section which are actual theorems of ZF.

Proof of Theorem 4.7. Suppose that F is stably c.e. and is sound. Let  $(M, M_e) : \mathbb{N} \to \mathcal{A} \times \{\pm\}$  be a total Turing machine s.t.  $F = M^s(N)$ . Let  $C(M_e)$  be as in Lemma 3.14. If we understand arithmetic as being embedded in set theory ZF in the standard way, then for each  $T \in \mathcal{T}$  the sentence

$$(T \in \mathcal{D}_{\mathcal{T}}) \wedge (T \text{ is not } T\text{-decided})$$

is logically equivalent in ZF to a first order sentence in arithmetic, that we call s(T). The corresponding translation map  $s: \mathcal{T} \to \mathcal{A}, T \mapsto s(T)$  is taken to be computable. Indeed, this kind of translation already appears in the original work of Turing [1].

Define a Turing decision map D by

$$D(T,n) := (Dec_{\mathcal{A}}(C(M_e)))'(s(T),n)$$

for  $Dec_{\mathcal{A}}$  as in (3.9) defined with respect to  $B = \mathcal{A}$ , and where C is as in Section 3. Then by construction, and by Axiom 4 in particular, D is computable by some Turing machine  $(D, D_e)$ , we make this more explicit in the following Section 5.

Now D is stably sound by Lemma 3.11 and the assumption that F is sound. So by Lemma 4.3:

$$\neg (D_e \text{ is } D\text{-decided}).$$

In particular,  $s(D_e)$  is not  $Dec_{\mathcal{A}}(C(M_e))$ -decided, and so  $s(D_e)$  is not  $C(M_e)$ -stable (Lemma 3.11), i.e.  $M \nvdash s(D_e)$ .

On the other hand,

$$\neg (D_e \text{ is } D\text{-decided}) \models \neg (D_e \text{ is } D_e\text{-decided}),$$

by definition. And so since  $D_e \in \mathcal{D}_{\mathcal{T}}$  by construction,  $s(D_e)$  is satisfied. Set  $\alpha(M) := s(D_e)$  and we are done.

5. Syntactic incompleteness for stably computable formal systems

Let  $s: \mathcal{T} \to \mathcal{A}, T \mapsto s(T)$  be as in the previous section. Define

$$H: \mathcal{T} \times \mathcal{T} \times \mathbb{N} \to \{\pm\}$$

to be the composition of the sequence of maps:

$$(5.1) \mathcal{T} \times \mathcal{T} \times \mathbb{N} \xrightarrow{Dec_{\mathcal{A}} \circ C \circ Spec \times s \times id} \mathcal{T} \times \mathcal{A} \times \mathbb{N} \xrightarrow{id \times e_{\mathcal{A} \times \mathbb{N}}} \mathcal{T} \times \mathcal{U} \xrightarrow{U} \mathcal{U} \xrightarrow{e_{\{\pm\}}^{-1}} \{\pm\},$$

where the last map is:

$$\Sigma \mapsto \begin{cases} undefined, & \text{if } \Sigma \notin \{\pm\}_e \\ e_{\{\pm\}}^{-1}(\Sigma), & \text{otherwise.} \end{cases}$$

Of course we may rewrite:  $H(M,T,n) = (Dec_{\mathcal{A}}(C(Spec(M))))'(s(T),n)$ . H is a composition of maps that are computable by the axioms of  $\mathcal{S}$  and so H is computable.

Hence by Axiom 7 there is an associated computable map:

$$(5.2) Tur: \mathcal{T} \to \mathcal{T},$$

s.t. for each  $M \in \mathcal{T}$ , Tur(M) encodes the map  $D^M : \mathcal{T} \times \mathbb{N} \to \{\pm\}$ ,  $D^M(T,n) = H(M,T,n)$ . In what follows,  $(M, M_e) : \mathbb{N} \to \mathcal{A} \times \{\pm\}$  will be a fixed total Turing machine. We abbreviate  $D^{M_e}$  by D and  $Tur(M_e)$  by  $D_e$ . As usual notation of the form  $M \vdash \alpha$  means  $M^s \vdash \alpha$ .

**Proposition 5.3.** For  $(M, M_e), (D, D_e)$  as above:

$$M^s$$
 is 1-consistent  $\implies M \nvdash s(D_e)$ .

$$M^s$$
 is 2-consistent  $\Longrightarrow M \nvdash \neg s(D_e)$ .

Moreover, the sentence:

$$M^s$$
 is 1-consistent  $\implies s(D_e)$ 

is a theorem of PA under standard interpretation of all terms, (this will be further formalized in the course of the proof).

*Proof.* This proposition is meant to just be a theorem of set theory ZF, however we avoid complete set theoretic formalization, as is common in mathematics. Arithmetic is interpreted in set theory the standard way, using the standard set  $\mathbb{N}$  of natural numbers. So for example, for  $M: \mathbb{N} \to \mathcal{A} \times \{\pm\}$  a sentence of the form  $M \vdash \alpha$  is a priori interpreted as a sentence of ZF, however if M is a Turing machine this also can be interpreted as a sentence of PA, once Gödel encodings are invoked.

Set  $N := (Spec(M_e))'$ , in particular this is a speculative total Turing machine  $\mathbb{N} \to \mathcal{A} \times \{\pm\}$ . Set  $s := s(D_e)$ . Suppose that  $M \vdash s$ . Hence,  $N \vdash s$  and so s is  $C(Spec(M_e))$ -stable, and so by Lemma 3.11 s is  $Dec_{\mathcal{A}}(C(Spec(M_e)))$ -decided, and so  $D_e$  is D-decided by definition. More explicitly, we deduce the sentence  $\eta_{M_e}$ :

$$\exists m \forall n \geq m : (Tur(M_e))'(Tur(M_e), m) = +.$$
  
i.e. 
$$\exists m \forall n \geq m : D(D_e, m) = +.$$

In other words:

$$(5.4) (M \vdash s) \implies \eta_{M_e}$$

is a theorem of ZF.

If we translate  $\eta_{M_e}$  to an arithmetic sentence we just call  $\eta = \eta(M_e)$ , then  $\eta$  can be chosen to have the form:

$$\exists m \forall n : \gamma(m,n),$$

where  $\gamma(m,n)$  is RA-decidable. The sentence  $s=s(D_e)$  is assumed to be of the form  $\beta(M_e) \land \neg \eta(M_e)$ , where  $\beta(M_e)$  is the arithmetic sentence equivalent in ZF to  $(D_e = Tur(M_e) \in \mathcal{D}_T)$ . The translation maps  $T \to \mathcal{A}$ ,  $T \mapsto \beta(T)$ ,  $T \mapsto \eta(T)$  can be taken to be computable, and so that

$$(5.5) \qquad \forall T \in \mathcal{T} : PA \vdash \beta(T),$$

where the latter can be satisfied by the construction of H. And so

$$(5.6) PA \vdash (\eta(M_e) \implies \neg s(D_e)).$$

Moreover, ZF proves:

$$\begin{array}{ll} \eta_{M_e} \implies \exists m \forall n: RA \vdash \gamma(m,n), & \text{trivially} \\ \implies \exists m: N \vdash \forall n: \gamma(m,n), & \text{since } N \text{ is speculative} \\ \implies N \vdash \eta, \\ \implies N \vdash \neg s, & \text{by (5.6) and since } N^s \supset PA. \end{array}$$

And so combining with (5.4), (5.6) ZF proves:

$$(M \vdash s) \implies (N \vdash s) \land (N \vdash \neg s).$$

Since by Theorem 3.18

$$M^s$$
 is 1-consistent  $\implies N^s$  is consistent,

it follows:

$$(5.7) ZF \vdash (M^s \text{ is 1-consistent} \implies M \nvdash s \pmod{N \nvdash s}).$$

Now suppose

$$(M^s \text{ is 2-consistent}) \land (M \vdash \neg s).$$

Since we have (5.5), and since  $M \vdash PA$  it follows that  $M \vdash \eta$ .

$$M \vdash \eta \iff M \vdash \exists m \forall n : \gamma(m, n),$$
  
 $\implies \neg(\forall m : M \vdash \neg \phi(m))$  by 2-consistency,

where

$$\phi(m) = \forall n : \gamma(m, n).$$

So we deduce

$$\exists m : M \vdash \phi(m).$$

Furthermore,

$$\exists m : M \vdash \phi(m) \implies \exists m \forall n : M \vdash \gamma(m,n), \quad M^s \text{ is consistent}$$
  
 $\implies \exists m \forall n : RA \vdash \gamma(m,n), \quad M^s \text{ is consistent}, M^s \supset RA \text{ and } \gamma(m,n) \text{ is } RA\text{-decidable}.$ 

In other words, ZF proves:

$$(M^s \text{ is 2-consistent } \land (M \vdash \neg s)) \implies \eta.$$

And ZF proves:

$$\eta \implies N \vdash s$$
,

by constructions. So ZF proves:

$$\begin{array}{ccc} (M^s \text{ is 2-consistent} \wedge (M \vdash \neg s)) & \Longrightarrow & N \vdash s \\ & \Longrightarrow & N^s \text{ is inconsistent} \\ & \Longrightarrow & M^s \text{ is not 1-consistent, by Theorem 3.18} \\ & \Longrightarrow & M^s \text{ is not 2-consistent.} \end{array}$$

And so ZF proves:

$$M^s$$
 is 2-consistent  $\implies M \nvdash \neg s$ .

Now for the last part of the proposition. We essentially just further formalize (5.7) and its consequences in PA. In what follows by equivalence of sentences we mean equivalence in ZF. The correspondence of sentences under equivalence is always meant to be computable, which usually just means that the corresponding map  $\mathcal{T} \to \mathcal{A}$  is computable.

**Definition 5.8.** We say that  $T \in \mathcal{T}$  is stably 1-consistent if  $T \in \mathcal{T}_{\mathcal{A}}$  is total and  $T^s$  is 1-consistent, (Notation 2).

Then the sentence:

T is stably 1-consistent

is equivalent to an arithmetic sentence we denote:

$$1 - con^s(T)$$
.

The sentence  $Spec(T) \nvdash s(Tur(T))$  is equivalent to an arithmetic sentence we call:

$$\omega(T)$$
.

By the proof of the first part of the proposition, that is by (5.7),

$$(5.9) ZF \vdash \forall T \in \mathcal{T} : (1 - con^s(T) \implies \omega(T)).$$

But we also have:

$$(5.10) PA \vdash \forall T \in \mathcal{T} : (1 - con^s(T) \implies \omega(T)).$$

(provided the translations  $T \mapsto 1 - con^s(T)$ ,  $T \mapsto \omega(T)$  are reasonably chosen), since the first part of the proposition can be formalized in PA, in fact the only interesting theorems we used are Lemma 3.11, and Theorem 3.18 which are obviously theorems of PA. By Lemma 3.11 and the construction of H:

$$PA \vdash \forall T \in \mathcal{T} : \omega(T) \iff \neg \eta(T),$$

(again provided the translation  $T \mapsto \omega(T)$  is reasonable). So:

$$PA \vdash \forall T \in \mathcal{T} : (\beta(T) \land \omega(T) \iff s(Tur(T))),$$

Combining with (5.5) and with (5.10) we get:

$$PA \vdash \forall T \in \mathcal{T} : (1 - con^s(T) \implies s(Tur(T))).$$

So if we formally interpret the sentence " $M^s$  is 1-consistent" as the arithmetic sentence  $1-con^s(M_e)$ , then this formalizes and proves the second part of the proposition.

Proof of Theorems 1.4, 1.5. Let F be as in the hypothesis. For a Turing machine  $(M, M_e)$  such that  $F = M^s$  let  $(D, D_e)$  be as in the proposition above, and set  $\alpha(F) := s(D_e)$ . Then Theorem 1.4 follows by part one of the proposition above.  $\square$ 

Appendix A. Briefly on physical ramifications - intelligence, Gödel's disjunction and Penrose

In this appendix we give some additional background, and explore some physical ideas nearby to the mathematical results of the paper. This is intended to be very concise.

In what follows we understand human intelligence very much like Turing in [2], as a black box which receives inputs and produces outputs. More specifically, this black box M is meant to be some system which contains a human subject. We do not care about what is happening inside M. So we are not directly concerned here with such intangible things as understanding, intuition, consciousness - the inner workings of human intelligence that are supposed to be special. The only thing that concerns us is what output M produces given an input. Given this very limited interpretation, the question that we are interested in is this:

Question 1. Can human intelligence be completely modeled by a Turing machine?

Turing himself has started on a form of Question 1 in his "Computing machines and Intelligence" [2], where he also informally outlined a possible obstruction to a yes answer coming from Gödel's incompleteness theorem. We will remark on this again further on.

A.0.1. Gödel's disjunction. Around the same time as Turing, Gödel argued for a no answer to Question 1, see [11, 310], relating the question to existence of absolutely unsolvable Diophantine problems, see also Feferman [6], and Koellner [13], [14] for a discussion. Let  $F \subset \mathcal{A}$  be the mathematical output of a certain idealized mathematician S (where for the moment we leave the latter undefined). Essentially, Gödel argues for a disjunction, the following cannot hold simultaneously:

F is computably enumerable, F is consistent and A,

where A says that F can decide any Diophantine problem. At the same time Gödel doubted that  $\neg A$  is possible, again for an idealized S, as this puts absolute limits on what is humanly knowable even in arithmetic. Note that his own incompleteness theorem only puts relative limits on what is humanly knowable, within a fixed formal system.

Claim 1. It is impossible to meaningfully formalize Gödel's disjunction without strengthening the incompleteness theorems.

Already Feferman asks in [6] what is the meaning of 'idealized' above? In the context of the present paper we might propose that it just means stabilized (cf. Section 3 specifically). But there are Turing machines T whose stabilization  $T^s$  is not computably enumerable, as shown in Example 3.3. In that case, the above Gödel disjunction becomes meaningless because passing to the idealization may introduce non-computability where there was none before. So in this context one must be extremely detailed with what "idealized" means physically and mathematically. The process of the idealization must be such that non-computability is not introduced in the ideal limit, if we want to apply the classical incompleteness theorems. Since we do not yet understand the human brain, this is out of reach even in principle.

Otherwise, if we give up computability of the ideal limit, then we must suitably extend the incompleteness theorems. For example, we may attempt to weakly idealize brain processes as follows. Suppose we know that there is a mathematical model M for the biological human brain, in which the deterioration of the brain is described by some explicit computable stochastic process, on top of the base cognitive processes. Then mathematically a weak idealization  $M^{ideal}$  of M would just correspond to the removal of this stochastic process. Let  $F = (M^{ideal})^s$ , where  $M^{ideal} : \mathbb{N} \to \mathcal{A} \times \{\pm\}$  models the mathematical output of our weakly idealized subject based on the model  $M^{ideal}$ . Hence, by construction, F is not stably computable, only if some cognitive processes of the brain (in the given mathematical model M) were non-computable. We may then meaningfully apply Theorem 1.5 to this F.

A.0.2. Lucas-Penrose thesis. After Gödel, Lucas [10] and later again and more robustly Penrose [16] argued for a no answer based only on soundness and the Gödel incompleteness theorem, that is attempting to remove the necessity to decide A or  $\neg A$ . A number of authors, particularly Koellner [13], [14], argue that there are likely unresolvable meta-logical issues with the Penrose argument, even allowing for soundness. See also Penrose [16], and Chalmers [4] for discussions of some issues. The main issue, as I see it, is the following. The kind of argument that Penrose proposes uses a meta-algorithm P that takes as input specification of a Turing machine or a formal system, and has as output a sentence in a formal system. Moreover, each step of this meta-algorithm is computably constructive. But the goal of the argument is to show that the function representing P be non-computable! So on this rough surface level this appears to be impossible. Note that this is simply a no-go assertion, it does not produce a specific error contained in the Penrose argument, only that such an error must exist. As mentioned Koellner goes deeper to uncover the specific error.

A.O.3. Formalizing Gödel's disjunction. Notwithstanding, we can start by formalizing Gödel's disjunction as follows. As already outlined we must first propose a suitable idealization to which we may apply the incompleteness theorems of this paper. The initial proposal above is to suitably idealize brain processes, but this is only theoretical since we are far from understanding the human brain. Another, more immediate approach is to simply substitute humanity (evolving in time), in place of a subject. This has its own practical problems that we ignore, but fits well with our expectation that

overall human knowledge converges on truth. Thus, we suppose that associated to humanity there is a function:

$$H: \mathbb{N} \to \mathcal{A} \times \{\pm\},$$

determined for example by majority consensus, leaving further details aside. Majority consensus is not as restrictive as it sounds. For example if there is a computer verified proof of the Riemann hypothesis  $\alpha$  in ZFC, then irrespectively of the complexity of the proof, we can expect majority consensus for  $\alpha$ , provided validity of set theory still has consensus. At least if we reasonably interpret H, which is beyond the scope here.

In what follows,  $\mathcal{H} = H^s(\mathbb{N})$ , for H as outlined above. So that informally  $\mathcal{H}$  is the infinite time limit of the mathematical output of humanity in the language of arithmetic. There is clearly some freedom for how the underlying map H is interpreted and constructed, however  $\mathcal{H}$  itself is at least morally unambiguous.

Instead of trying to totally specify H, we will instead assume the following axiom:

**Axiom A.1.** If the physical processes underlying the output of H are computable, this may include computability of certain stochastic variables as probability distribution valued maps - then the set  $\mathcal{H} = H^s(\mathbb{N})$  is stably computably enumerable.

Applying Theorem 1.5 we then get the following.

**Theorem A.2.** Suppose that  $\mathcal{H} \vdash PA$ , where  $\mathcal{H}$  is understood as a formal system in the language of arithmetic. Then either  $\mathcal{H}$  is not stably computably enumerable or  $\mathcal{H}$  is not 1-consistent or  $\mathcal{H}$  cannot decide a certain true statement of arithmetic. Assuming the axiom above, this can be restated as follows. Suppose that  $\mathcal{H} \vdash PA$  and  $\mathcal{H}$  is 1-consistent. Then either there are cognitively meaningful, absolutely non Turing computable processes in the human brain, or there exists a true in the standard model constructive statement of arithmetic  $\alpha(\mathcal{H})$  that  $\mathcal{H}$  can neither prove or disprove. (By constructive we mean provided a specification of a Turing machine stably enumerating  $\mathcal{H}$ .)

By absolutely we mean in any sufficiently accurate physical model. Note that even existence of absolutely non Turing computable processes in nature is not known. For example, we expect beyond reasonable doubt that solutions of fluid flow or N-body problems are generally non Turing computable (over  $\mathbb{Z}$ , if not over  $\mathbb{R}$  cf. [3]) <sup>2</sup> as modeled in essentially classical mechanics. But in a more physically accurate and fundamental model they may both become computable, possibly if the nature of the universe is ultimately discreet. It would be good to compare this theorem with Deutsch [5], where computability of any suitably finite and discreet physical system is conjectured. Although this is not immediately at odds with us, as the hypothesis of that conjecture may certainly not be satisfiable.

Remark A.3. Turing suggested in [2] that abandoning hope of consistency is the obvious way to circumvent the implications of Gödel incompleteness theorem for computability of intelligence. In my opinion this position is untenable. Humans may not be consistent, but it is implausible that the stabilization  $\mathcal{H}$  is not sound, since as we say human knowledge appears to converge on truth, and it is rather inconceivable that  $\mathcal{H}$  is not 1-consistent. Then we cannot escape incompleteness by the above. So if we insist on computability, then the only plausible way that the incompleteness theorems can be circumvented is to accept that there is an absolute limit on the power of human reason as in the theorem above.

Remark A.4. It should also be noted that for Penrose, in particular, non-computability of intelligence would be evidence for new physics, and he has specific and very intriguing proposals with Hameroff [9] on how this can take place in the human brain. As we have already indicated, new physics is not a logical necessity for non-computability of brain processes, at least given the state of the art. However, it is very plausible that new physical-mathematical ideas may be necessary to resolve the deep mystery of human consciousness. Here is also a partial list of some partially related work on mathematical models of brain activity, consciousness and or quantum collapse models: [12], [15], [7], [8].

 $<sup>^2</sup>$ We now involve real numbers, but there is a standard theory of computability in this case, in terms of computable real numbers, this is what means over  $\mathbb{Z}$ .

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