## A REMARK ON DEFORMATION OF GROMOV NON-SQUEEZING

#### YASHA SAVELYEV

ABSTRACT. We prove that in dimension 4 the Gromov non-squeezing phenomenon is persistent with respect to  $C^0$  symplectic perturbations of the symplectic form on the range. This in turn motivates an intriguing question on further deforming non-squeezing to general nearby forms. Our methods consist of a certain trap idea for holomorphic curves, analogous to traps in dynamical systems, and Hofer-Wysocki-Zehnder polyfold regularization in Gromov-Witten theory, especially as recently worked out in this present context by the team of Franziska Beckschulte, Ipsita Datta, Irene Seifert, Anna-Maria Vocke, and Katrin Wehrheim.

### 1. Introduction

One of the most important to this day results in symplectic geometry is the so called Gromov non-squeezing theorem appearing in the seminal paper of Gromov [2]. Let  $\omega_{st} = \sum_{i=1}^{n} dp_i \wedge dq_i$  denote the standard symplectic form on  $\mathbb{R}^{2n}$ . Gromov's theorem then says that there does not exist a symplectic embedding

$$(B_R, \omega_{st}) \hookrightarrow (S^2 \times \mathbb{R}^{2n-2}, \omega_{\pi r^2} \oplus \omega_{st})$$

for R > r, with  $B_R$  the standard closed radius R ball in  $\mathbb{R}^{2n}$  centered at 0, and  $\omega_{\pi r^2}$  a symplectic form on  $S^2$  with area  $\pi r^2$ .

We show that in dimension 4 Gromov's non-squeezing is  $C^0$  persistent in the following sense.

**Theorem 1.1.** Let R > r > 0 be given, let  $\omega_{\pi r^2} \oplus \omega_{st}$  be the symplectic form on  $M = S^2 \times \mathbb{R}^2$  as above. Then there is an  $\epsilon > 0$  s.t. for any symplectic form  $\omega'$  on M,  $C^0$   $\epsilon$ -close to  $\omega$ , there is no symplectic embedding  $\phi: B_R \hookrightarrow (M, \omega')$ , meaning that  $\phi^* \omega' = \omega_{st}$ .

The dimension 4 restriction should not be essential, the only issue is that in higher dimensions a suitable holomorphic trap (Definition 2.2) is more complicated to construct.

It is natural to ask if the above theorem continues to hold for general nearby forms. Or formally this translates to:

Question 1. Let R > r > 0 be given, and let  $\omega = \omega_{\pi r^2} \oplus \omega_{st}$  be the symplectic form on  $M = S^2 \times \mathbb{R}^{2n-2}$ , as above. For every  $\epsilon > 0$  is there a (necessarily non-closed) 2-form  $\omega'$  on M,  $C^0$   $\epsilon$ -close to  $\omega$ , such that there is a symplectic embedding  $\phi : B_R \hookrightarrow M$ , i.e. s.t.  $\phi^*\omega' = \omega_{st}$ ?

We cannot readily reduce this question to just applying Theorem 1.1 (in dimension 4). This is because, while a symplectic form on a subdomain of the form  $\phi(B_R) \subset M$  extends to a symplectic form, by a classical theorem of Gromov [3], the extension may not be  $C^0$  close. Indeed, this appears to be rather unlikely to happen.

The above question seems to be a very difficult, in the sense that very new ideas may be required. My opinion is that the answer is 'yes', in part because it is difficult to imagine any obstruction, for example we no longer have Gromov-Witten theory for general  $\omega'$ . On the other, my attempts to construct an example failed, so that 'no' is certainly very possible.

A work of Müller [5] explores a different kind of question, by instead relaxing the condition of the map being symplectic. There is no direct connection to our problem. As pull-backs by diffeomorphisms of nearby forms may not be nearby. Hence, there is no way to go from nearby embeddings that we work with to  $\epsilon$ -symplectic embeddings of Müller.

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#### 2. A Trap for holomorphic curves

**Definition 2.1.** We say that a pair  $(\omega, J)$  of a 2-form  $\omega$  on M and an almost complex structure J on M are compatible if  $\omega(\cdot, J\cdot)$  defines a J-invariant inner product on M. For other basic notions of J-holomorphic curves we refer the reader to [4].

**Definition 2.2.** Let  $(M, \omega)$  be a symplectic manifold,  $A \in H_2(M)$  fixed, and J an  $\omega$ -compatible almost complex structure. Let  $K \subset M$  be a closed subset. Suppose that for each t, and for every  $x \in \partial K$  (the topological boundary) there is a J-holomorphic (real codimension 2) compact hyperplane  $H_x$  through x satisfying:

- $H_x \subset K$ .
- A · H<sub>x</sub> ≤ 0, where the right-hand side is the intersection number of a smooth representative of A with H<sub>x</sub>.

We call such a K a J-holomorphic trap (for class A curves).

**Lemma 2.3.** Let  $M, \omega, J$  be as above. And let K be a J-holomorphic trap for class A curves. Then any closed J-holomorphic class A curve u, intersecting K has image contained in K.

Proof. Suppose that u intersects  $\partial K$ , otherwise we already have image  $u \subset interior(K)$ , since image u is connected (and by elementary topology). Then u intersects  $H_x$  as in the statement, for some x. As  $A \cdot H_x \leq 0$ , by positivity of intersections [4, Section 2.6], image  $u \subset H_x \subset \partial K$ .

# 3. Proof of Theorem 1.1

Suppose by contradiction that for every  $\epsilon > 0$  there is an  $\omega_1$  s.t.  $d_{C^0}(\omega, \omega_1) < \epsilon$  and such that there exists a symplectic embedding

$$\phi: B_R \hookrightarrow (M, \omega_1).$$

Our specific  $C^0$  distance  $d_{C^0}$ , on the spaces of forms, will be with respect to the metric g induced by  $(\omega, J)$  for J the standard product complex structure.

Let  $\epsilon' > 0$  be s.t. any symplectic form  $\omega_1$  on M,  $C^0$   $\epsilon'$ -close to  $\omega$  satisfies:

- $\omega_t = t\omega + (1-t)\omega_1$  is non-degenerate, for each  $t \in [0,1]$ .
- $\omega_t$  is non-degenerate on all fibers of the natural projection  $\pi: (M = S^2 \times \mathbb{R}^2) \to \mathbb{R}^2$ . In what follows we just call them *fibers*.

For  $\epsilon < \epsilon'$  as above, let  $\omega_1$  and  $\phi : B_R \to (M, \omega_1)$  be as in our hypothesis. Set  $B := \phi(B_R)$  and let  $D \supset B$  be an open domain, with compact closure K, s.t. K is the product  $S^2 \times D^2$  for  $D^2 \subset \mathbb{R}^2$  a closed disk. In particular,  $\partial K$  is smoothly folliated by the fibers. We denote by  $T^{vert}\partial K \subset TM$ , the sub-bundle of vectors tangent to the leaves of the above-mentioned foliation.

We may extend  $\phi_*j$  to an  $\omega_1$ -compatible almost complex structure  $J_1$  on M, preserving  $T^{vert}\partial K$  using:

- image  $\phi$  does not intersect  $\partial K$ .
- The non-degeneracy of  $\omega_1$  on the fibers, which follows by the defining condition of  $\epsilon$ .
- The well known existence/flexibility results for almost complex structures on symplectic vector bundles.

We may then extend  $J_1$  to a family  $\{J_t\}$ ,  $t \in [0,1]$ , of almost complex structures on M, s.t.  $J_t$  is  $\omega_t$ -compatible for each t, with  $J_0 = J$  the standard complex structure on M, and such that  $J_t$  preserves  $T^{vert}\partial K$  for each t. The latter condition can be satisfied by similar reasoning as above, using that  $\omega_t$  is non-degenerate on the fibers for each t. Let  $A = [S^2] \otimes [pt]$  be as in the statement. Then K is a compact  $J_t$ -holomorphic trap for class A curves, and for each t.

Set  $x_0 := \phi(0)$ . Denote by  $\mathcal{M}_t$  the space of equivalence classes of maps  $u : \mathbb{CP}^1 \to M$ , where u is a  $J_t$ -holomorphic, class A curve passing through  $x_0$ . The equivalence relation is by the usual reparametrization group action. Then  $\mathcal{M} = \bigcup_t \mathcal{M}_t$  is compact by energy minimality of A, by Lemma 2.3, and by compactness of K.

As explained in [1, Section 3.5], in a essentially identical situation, we may embed  $\mathcal{M}$  into a natural polyfold setup. That is we express  $\mathcal{M}$  as an sc-Fredholm section of a suitable M-polyfold bundle.

The only difference with their setup is that they compactify M to  $S^2 \times T^{2n-2}$ . We of course cannot compactify, and so we have to use the holomorphic trap idea, to force compactness of  $\mathcal{M}$ . Again as in [1], we take the M-polyfold regularization of  $\mathcal{M}$ . This gives a one dimensional cobordism  $\mathcal{M}^{reg}$  between  $\mathcal{M}_0^{reg}$  and  $\mathcal{M}_1^{reg}$ .

Now  $\mathcal{M}_0^{reg}$  is a point: corresponding to the unique  $(J = J_0)$ -holomorphic class A, curve  $u : \mathbb{CP}^1 \to M$  passing through  $x_0$ . In particular,  $\mathcal{M}_1^{reg}$  is non-empty, that is there is a  $J_1$ -holomorphic class A curve  $u_0 : \mathbb{CP}^1 \to M$  passing through  $x_0$ .

Remark 3.1. It is certainly possible that more classical, geometric perturbation style arguments may be adopted to the present problem. There are however difficulties: it is important for us to work with curves constrained to pass through a specific point, instead of doing homological intersection of an unconstrained evaluation cycle, with a point (as in the classical proof of Gromov non-squeezing). For without the specific constraint our moduli space is not even compact, and hence the homological intersection theory makes no sense. Such a constraint may not neatly fit into classical analytical framework of McDuff-Salamon [4].

Now we have:

$$|\langle \omega_1, A \rangle - \pi \cdot r^2| = |\langle \omega_1, A \rangle - \langle \omega, A \rangle| \le \epsilon \pi \cdot r^2,$$

as  $\langle \omega, A \rangle = \pi r^2$ , and as  $d_{C^0}(\omega, \omega_1) < \epsilon$ , (also using that we can find a representative for A whose g-area is  $\pi r^2$ ). So choosing  $\epsilon$  appropriately we get

$$|\int_{\mathbb{CP}^1} u_0^* \omega_1 - \pi r^2| < \pi R^2 - \pi r^2,$$

And consequently,

$$\int_{\mathbb{CP}^1} u_0^* \omega_1 < \pi R^2.$$

We may then proceed exactly as in the now classical proof of Gromov [2] of the non-squeezing theorem to get a contradiction and finish the proof. A bit more specifically,  $\phi^{-1}(\text{image }\phi\cap\text{image }u_0)$  is a minimal surface in  $B_R$ , with boundary on the boundary of  $B_R$ , and passing through  $0 \in B_R$ . By construction it has area strictly less than  $\pi R^2$ , which is impossible by the classical monotonicity theorem of differential geometry. See also [1] where the monotonicity theorem is suitably generalized, to better fit the present context.

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UNIVERSITY OF COLIMA, CUICBAS