INCOMPLETENESS FOR STABLY COMPUTABLE FORMAL SYSTEMS

YASHA SAVELYEV

ABSTRACT. We prove, for stably computably enumerable formal systems, (stably c.e. for short) direct generalizations of the first and second incompleteness theorems of Gödel. A typical stably c.e. set is the set of Diophantine equations with no integer solutions, and in particular such sets are generally not c.e. For any formal system F in the language of arithmetic s.t. $F \vdash PA$, either F is not stably c.e. or F is not 1-consistent, or there exists a suitably constructable and G(F) s.t. $F \nvdash G(F)$ and s.t.

$$(F \text{ is 1-consistent}) \implies G(F)$$

is a theorem of PA. In particular, in the last case, G(F) is true in the standard model, and if F is in addition 2-consistent then G(F) is F-independent. This is the first extension of Gödel's disjunction non c.e., i.e. non Σ_1 formal systems. To give one physically motivated example, let \mathcal{H} be the suitable infinite time limit (stabilization in the sense of the paper) of the mathematical output of humanity, specializing to first order sentences in the language of arithmetic (for simplicity), and understood as a formal system. As we shall show \mathcal{H} may not be c.e. even if all the physical processes relevant to \mathcal{H} are Turing computable. Thus, the original Gödel disjunction is not meaningful when applied to \mathcal{H} . On the other hand, under the same Turing computability assumption, \mathcal{H} would be stably c.e. (at least within our mathematical interpretation) and so we may apply our disjunction to \mathcal{H} .

1. Introduction

For an introduction/motivation based around physical ideas the reader may see Appendix A. We begin by quickly introducing the notion of stable computability, in a specific context.

Let \mathcal{A} denote the abstract set of first order sentences of arithmetic. And suppose we are given a map

$$M: \mathbb{N} \to \mathcal{A} \times \{\pm\},$$

for $\{\pm\}$ denoting a set with two elements +, -.

Definition 1.1.

• $\alpha \in \mathcal{A}$ is M-stable if there is an m with $M(m) = (\alpha, +)$ s.t. there is no n > m with $M(n) = (\alpha, -)$. Let $M^s \subset \mathcal{A}$ be the set of M-stable α , called the stabilization of M.

We may informally understand M as a "machine" producing arithmetic "truths", while allowing for corrections, with \mathbb{N} playing the role of time. In this case the interpretation of the above could be the following. $M(n) = (\alpha, +)$ only if at the moment n M decides that α is true. While

$$M(m) = (\alpha, -)$$

only if $M(n) = (\alpha, +)$ for some n < m, and at the moment m, M no longer asserts that α is true, either because at this moment M is unable to decide α , or because it has decided it to be false.

In this paper we are mainly interested in the properties of the sets M^s . The following definition is preliminary, as we did not yet define Turing machines with abstract sets of inputs and outputs, see Section 2.1, and Definition 3.2 for a complete definition.

Definition 1.2. A subset $S \subset \mathcal{A}$, is called **stably computably enumerable** or stably c.e. if there is a Turing machine $T : \mathbb{N} \to \mathcal{A} \times \{\pm\}$ so that $S = T^s$. In this case, we will say that T stably computes S.

It is important to note right away that S may well be not c.e. but still be stably c.e., see Example 3.3.

Let RA denote Robinson arithmetic that is Peano arithmetic PA without induction. Let \mathcal{F}_0 denote the set of RA-decidable formulas ϕ in arithmetic with one free variable. We recall the following:

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Definition 1.3. Given $F \subset A$, understood as formal system in the language of arithmetic, we say that it is 1-consistent if it is consistent, if $F \vdash RA$, and if for any formula $\phi \in \mathcal{F}_0$ the following holds:

$$F \vdash \exists m : \phi(m) \implies \neg \forall m : F \vdash \neg \phi(m).$$

We say that it is 2-consistent if the same holds for Π_1 formulas ϕ with one free variable, more specifically formulas $\phi = \forall n : g(m, n)$, with g RA-decidable.

The first theorem below is a direct generalization of the modern form of Gödel's first incompleteness theorem, as we mainly just weaken the assumption of F being c.e. to being stably c.e.

Theorem 1.4. Suppose that $F \subset \mathcal{A}$ is stably c.e., and $F \vdash PA$. Then there is a constructible, from a specification of a Turing machine T stably computing F, sentence $\alpha(F) \in \mathcal{A}$ so that $F \nvdash \alpha(F)$ if F is 1-consistent and $F \nvdash \neg \alpha(F)$ if F is 2-consistent.

The second theorem below directly generalizes the more striking second incompleteness theorem of Gödel. Some ramifications of this are discussed in Appendix A.

Theorem 1.5. Let F, T and $\alpha(F)$ be as in the theorem just above. Then

$$(1.6) (F is 1-consistent) \implies \alpha(F)$$

is a theorem of PA. More formally stated, the sentence (1.6) is logically equivalent in ZF to an arithmetic sentence provable by PA. In particular, $\alpha(F)$ is true in the standard model of arithmetic whenever F is 1-consistent. Consequently, since by assumption $F \vdash PA$,

$$F \nvdash (F \text{ is 1-consistent}),$$

that is F cannot prove its own 1-consistency.

The above theorems will be entirely formalized in set theory ZF, (in other words meta-logic will not appear).

- 1.1. Relationship with known results. The main distinction with the theorems of Gödel is that the set F is merely Σ_2 definable when F is stably c.e. As far as the first incompleteness Theorem 1.4, there is much previous history on attempts of generalizations of a similar kind dating almost back to Gödel. To give one recent example, in the work of Salehi and Seraji [17], which we also recommend for additional references, the general Corollary 2.11 partially implies Theorem 1.4, when F is deductively closed (which is not our assumption, but this might not be material). One further possible difference is that our sentence is constructible. Surprisingly, the authors of [17] point out that in general when n is at least 3 for a Σ_{n+1} definable, n-consistent theory F there is no constructible, Π_{n+1} definable, F independent sentence, although such a sentence does exist. On the other hand, I am not aware of any previous results on generalizations of the second incompleteness theorem to non c.e. formal systems. As pointed out in [17] there are examples of complete, consistent Δ_2 definable extensions of PA. So that any extensions of the second Gödel incompleteness theorem to Δ_2 definable sets must require stronger consistency assumptions. The second Theorem 1.5 says that 1-consistency is sufficient, when F is stably c.e. We will discuss some further background and ramifications for Theorem 1.5 in Appendix A.
- 1.2. **Generalizations.** There are natural candidates for how to generalize theorems above. We may replace $M: \mathbb{N} \to \mathcal{A} \times \{\pm\}$ by $M: \mathbb{N}^n \to \mathcal{A} \times \{\pm\}$, using this we can define a notion of n-stable computability, specializing to stable computability for n=1. This is theoretically very interesting, but is difficult and a practical motivation for such a notion is less clear, so we will not presently attempt to develop things in such generality.

Finally, we note that, our argument also readily reproves the original first and second incompleteness theorems of Gödel from first principles and within set theory ¹, with our Gödel sentence constructed directly via the theory of Turing machines. In particular, the somewhat mysterious to non-logicians diagonal Lemma, ordinarily used in modern renditions of the proof, is not used.

¹Assuming existence of a certain encoding category S, which is in part classical.

2. Some preliminaries

For more details on Turing machines we recommend the book of Soare [18]. Our approach here is however possibly novel in that we do not work with concrete Gödel encodings, instead abstractly axiomatizing their expected properties. This results in a certain encoding category, which will allow us to work with the language of set theory more transparently.

What follows is the definition of our variant of a Turing machine, which is a computationally equivalent, minor variation of Turing's original machine. We go over these basics primarily to set notation. The main preliminaries start in Section 2.1.

Definition 2.1. A Turing machine M consists of:

- Three infinite (1-dimensional) tapes T_i, T_o, T_c , (input, output and computation) divided into discreet cells, next to each other. Each cell contains a symbol from some finite alphabet Γ with at least two elements. A special symbol $b \in \Gamma$ for blank, (the only symbol which may appear infinitely many often).
- Three heads H_i , H_o , H_c (pointing devices), H_i can read each cell in T_i to which it points, H_o , H_c can read/write each cell in T_o , T_c to which they point. The heads can then move left or right on the tape.
- A finite set of internal states Q, among these is "start" state q_0 . And a non-empty subset $F \subset Q$ of final states.
- Input string Σ : the collection of symbols on the tape T_i , so that to the left and right of Σ there are only symbols b. We assume that in state q_0 H_i points to the beginning of the input string, and that the T_c , T_o have only b symbols.
- A finite set of instructions: I, that given the state q the machine is in currently, and given the symbols the heads are pointing to, tells M to do the following. The actions taken, 1-3 below, will be (jointly) called an executed instruction set or just step:
 - (1) Replace symbols with another symbol in the cells to which the heads H_c , H_o point (or leave them).
 - (2) Move each head H_i, H_c, H_o left, right, or leave it in place, (independently).
 - (3) Change state q to another state or keep it.
- Output string Σ_{out} , the collection of symbols on the tape T_o , so that to the left and right of Σ_{out} there are only symbols b, when the machine state is final. When the internal state is one of the final states we ask that the instructions are to do nothing, so that these are frozen states.

Definition 2.2. A complete configuration of a Turing machine M or total state is the collection of all current symbols on the tapes, position of the heads, and current internal state. Given a total state \mathfrak{s} , $\delta^M(\mathfrak{s})$ will denote the successor state of \mathfrak{s} , obtained by executing the instructions set of M on \mathfrak{s} , or in other words $\delta^M(\mathfrak{s})$ is one step forward from \mathfrak{s} .

So a Turing machine determines a special kind of function:

$$\delta^M: \mathcal{C}(M) \to \mathcal{C}(M),$$

where $\mathcal{C}(M)$ is the set of possible total states of M.

Definition 2.3. A Turing computation, or computation sequence for M is a possibly not eventually constant sequence

$$*M(\Sigma) := \{\mathfrak{s}_i\}_{i=0}^{i=\infty}$$

of total states of M, determined by the input Σ and M, with \mathfrak{s}_0 suitable initial configuration, in particular having internal state is q_0 , and where $\mathfrak{s}_{i+1} = \delta^M(\mathfrak{s}_i)$. If the sequence $\{\mathfrak{s}_i\}_{i=0}^{i=\infty}$ is eventually constant: $\mathfrak{s}_i = \mathfrak{s}_{\infty}$ for $\forall i > n$, for some n, and if the internal state of \mathfrak{s}_{∞} is a final state, then we say that the computation halts. For a given Turing computation $*M(\Sigma)$, we will write

$$*M(\Sigma) \to x$$
,

if $*M(\Sigma)$ halts and x is the corresponding output string.

We write $M(\Sigma)$ for the output string of M, given the input string Σ , if the associated Turing computation $*M(\Sigma)$ halts. Denote by Strings the set of all finite strings of symbols in Γ . Then a Turing machine M determines a partial function that is defined on all $\Sigma \in Strings$ s.t. $*M(\Sigma)$ halts, by $\Sigma \mapsto M(\Sigma)$.

In practice, it will be convenient to allow our Turing machine T to reject some elements of Strings as valid input. We may formalize this by asking that there is a special final machine state $q_{reject} \in F$ so that $T(\Sigma)$ halts with internal state q_{reject} . In this case we say that T rejects Σ . The set $\mathcal{I} \subset Strings$ of strings not rejected by T is also called the set of T-permissible input strings. We do not ask that for $\Sigma \in \mathcal{I} *T(\Sigma)$ halts. If $*T(\Sigma)$ does halt then we will say that Σ is T-acceptable.

Definition 2.4. We denote by \mathcal{T} the set of all Turing machines with a distinguished final machine state q_{reject} .

Instead of tracking q_{reject} explicitly, we may write

$$T:\mathcal{I}\to\mathcal{O}$$
,

where $\mathcal{I} \subset Strings$ is understood as the subset of all T-permissible strings, or just $input \ set$ and \mathcal{O} is the set output strings or $output \ set$.

Definition 2.5. Given a partial function

$$f: \mathcal{I} \to \mathcal{O},$$

we say that a Turing machine $T \in \mathcal{T}$

$$T:\mathcal{I}\to\mathcal{O}$$

computes f if T = f as partial functions on \mathcal{I} . In other words the set of permissible strings of T is \mathcal{I} , and as a partial function on \mathcal{I} , T = f. We say that f is **computable** if such a T exists.

2.1. Abstractly encoded sets and abstract Turing machines. The material of this section will be used in the main arguments. Instead of specifying Gödel encodings we just axiomatize their expected properties. Working with encoded sets/maps as opposed to concrete subsets of Strings/functions will have some advantages as we can involve set theory more transparently, and construct computable maps axiomatically. This kind of approach is likely very obvious to experts, but I am not aware of this being explicitly introduced in computability theory literature. As I myself am not an expert I wanted to make it explicit for my own sake.

An **encoding** of a set A is at the moment just an injective set map $e: A \to Strings$. But we will need to axiomatize this further. The **encoding category** S will be a certain small "arrow category" whose objects are maps $e_A: A \to Strings$, for e_A an embedding called **encoding map of** A, determined by a set A. More explicitly, the set of objects of S consists of some set of pairs (A, e_A) where A is a set, and $e_A: A \to Strings$ an embedding, determined by A. We may denote $e_A(A)$ by A_e . We now describe the morphisms. Suppose that we are given a commutative diagram:

$$A \xrightarrow{T} B$$

$$\downarrow^{e_A} \qquad \downarrow^{e_B}$$

$$A_e \subset Strings \xrightarrow{T_e} B_e \subset Strings.$$

where T is a partial map, and $T_e \in \mathcal{T}$ is a Turing machine in the standard sense above, with the set of permissible inputs A_e . Then the set of morphisms from (A, e_A) to (B, e_B) consists of equivalence classes of such commutative diagrams (T, T_e) , where the equivalence relation is $(T, T_e) \sim (T', T'_e)$ if T = T'. If in addition a morphism has a representative (of the equivalence class) (T, T_e) , with T_e primitive recursive then we call it a *a primitive recursive morphism*.

Notation 1. We may just write $A \in \mathcal{S}$ for an object, with e_A implicit.

We call such an $A \in \mathcal{S}$ an **abstractly encoded set** so that \mathcal{S} is a category of abstractly encoded sets. The morphisms set from between objects A, B in \mathcal{S} as usual will be denoted by $hom_{\mathcal{S}}(A, B)$. The composition maps

$$hom_{\mathcal{S}}(A,B) \times hom_{\mathcal{S}}(B,C) \to hom_{\mathcal{S}}(A,C)$$

are defined once we fix a prescription for the composition of Turing machines. That is

$$[(T, T_e)] \circ [(T', T'_e)] = [(T \circ T', T_e \circ T'_e)],$$

for $[\cdot]$ denoting the equivalence class and $[(T, T_e)] \in hom_{\mathcal{S}}(B, C)$ and $[(T', T'_e)] \in hom_{\mathcal{S}}(A, B)$. In addition, we ask that \mathcal{S} satisfies the following axioms.

- (1) For $A \in \mathcal{S}$ A_e is computable (recursive). Here, as is standard, a set $S \subset Strings$ is called *computable* if both S and its complement are computably enumerable, with S called *computably enumerable* if there is a computable partial function $Strings \to Strings$ with range S.
- (2) For $A, B \in \mathcal{S}$,

$$(A_e \cap B_e) = \emptyset.$$

In particular each $A \in \mathcal{S}$ is determined by A_e .

(3) If $A, B \in \mathcal{S}$ then $A \times B \in \mathcal{S}$ and the projection maps $pr^A : A \times B \to A$, $pr^B : A \times B \to B$ complete to morphisms of \mathcal{S} , so that in particular we have a commutative diagram:

$$\begin{array}{c} A \times B \xrightarrow{pr^A} A \\ \downarrow^{e_{A \times B}} & \downarrow^{e_A} \\ (A \times B)_e \xrightarrow{pr_e^A} A_e, \end{array}$$

similarly for pr^B .

- (4) If $f: A \to B$ completes to a morphism of \mathcal{S} , and $g: A \to C$ completes to a morphism of \mathcal{S} then $A \to B \times C$, $a \mapsto (f(a), g(a))$ completes to a morphism of \mathcal{S} . This combined with Axiom 3 implies that if $f: A \to B$, $g: C \to D$ extend to morphisms of \mathcal{S} then the map $A \times B \to C \times D$, $(a,b) \mapsto (f(a),g(b))$ extends to a morphism of \mathcal{S} .
- (5) The set $\mathcal{U} = Strings$ and \mathcal{T} are encoded i.e. $\mathcal{U}, \mathcal{T} \in \mathcal{S}$. We use the alternative name \mathcal{U} for Strings, as in this case the encoding map has the same domain and range, which is possibly confusing. The partial map

$$U: \mathcal{T} \times \mathcal{U} \to \mathcal{U}$$
,

 $U(T,\Sigma):=T(\Sigma)$ whenever $*T(\Sigma)$ halts and undefined otherwise, extends to a morphism of \mathcal{S} . We can understand a representative, (U,U_e) , of the morphism, as the "universal Turing machine".

- (6) The encoding map $e_{\mathcal{U}}: \mathcal{U} \to Strings$ is classically computable. (This makes sense since $\mathcal{U} = Strings$). It follows from this that for $A \in \mathcal{S}$ the encoding map $e_A: A \to \mathcal{U}$ itself extends to a morphism of \mathcal{S} .
- (7) The next axiom gives a prescription for construction of Turing machines. Let $A, B, C \in \mathcal{S}$, and suppose that $f: A \times B \to C$ extends to a morphism of \mathcal{S} . Let $f^a: B \to C$ be the map $f^a(b) = f(a, b)$. Then there is a map

$$s:A\to\mathcal{T}$$

so that for each a $(f^a, s(a))$ represents a morphism $B \to C$, and so that s extends to a morphism of S.

(8) The final axiom is for utility. If $A \in \mathcal{S}$ then $L(A) \in \mathcal{S}$, where

$$L(A) = \bigcup_{n \in \mathbb{N}} Maps(\{0, \dots, n\}, A),$$

and $Maps(\{0,\ldots,n\},A)$ denotes the set of total maps. We also have:

(a) N is encoded.

(b) Let $A \in \mathcal{S}$ and let

length :
$$L(A) \to \mathbb{N}$$
,

be the length function, s.t. for $l \in L(A)$, $l : \{0, ... n\} \to A$, length(l) = n. Then length extends to a morphism of S.

(c)

$$P: L(A) \times \mathbb{N} \to A$$

extends to a morphism of S, where P(l,i) := l(i), or undefined for i > length(l).

- (d) For $A, B \in \mathcal{S}$ and $f: A \to L(B)$ a partial map, suppose that:
 - The partial map $A \times \mathbb{N} \to B$, $(a, n) \mapsto P(f(a), n)$ extends to a morphism of S.
 - The partial map $A \to \mathbb{N}$, $a \mapsto \text{length}(f(a))$ extends to a morphism of S.

Then f extends to a morphism of S.

Lemma 2.6. If $f: A \to B$ extends to a morphism of S then the map $L(f): L(A) \to L(B)$,

$$l \mapsto \begin{cases} i \mapsto f(l(i)), & \text{if } f(l(i)) \text{ is defined for all } 0 \leq i \leq \operatorname{length}(l) \\ undefined, & \text{otherwise}, \end{cases}$$

extends to a morphism of S. Also, the map $LU: \mathcal{T} \times L(\mathcal{U}) \to L(\mathcal{U})$,

$$l \mapsto \begin{cases} i \mapsto U(T,(l(i))), & \textit{if } U(T,(l(i))) \textit{ is defined for all } 0 \leq i \leq \operatorname{length}(l) \\ \textit{undefined}, & \textit{otherwise} \end{cases}$$

extends to a morphism of S.

Proof. This is just a straightforward application of the axioms and Axiom 8 in particular. We leave the details as an exercise.

The above axioms suffice for our purposes, but there are a number of possible extensions (dealing with other set theoretic constructions like the set theoretic sum). The specific such category \mathcal{S} that we need will be clear from context later on. We only need to encode finitely many types of specific sets. For example \mathcal{S} should contain $\mathbb{N}, \mathcal{T}, \mathcal{A}, \{\pm\}$, with $\{\pm\}$ a set with two elements +, -. The encoding of \mathbb{N} should be suitably natural so that for example the map

$$\mathbb{N} \to \mathbb{N}$$
, $n \mapsto n+1$

completes to a primitive recursive morphism in \mathcal{S} . Strictly speaking this is part of the axioms. The main naturality properties for the encoding of \mathcal{T} are already stated as Axioms 5, 7. The naturality axioms for \mathcal{A} will be implicitly specified further on as needed.

The fact that such encoding categories S exist is a folklore theorem starting with foundational work of Gödel, Turing and others. Indeed, S can be readily constructed from standard Gödel type encodings. For example Axiom 7, in classical terms, just reformulates the following elementary fact, which follows by the "s-m-n theorem" Soare [18, Theorem 1.5.5]. Given a classical 2-input Turing machine

$$T: Strings \times Strings \rightarrow Strings,$$

there is a Turing machine $s_T: Strings \to Strings$ s.t. for each $\Sigma s_T(\Sigma)$ is the Turing-Gödel encoding string (a.k.a. program) of a Turing machine computing the map $\rho \mapsto T(\Sigma, \rho)$.

In modern terms, the construction of S is essentially a part of a definition of a computer programming language (with algebraic data types, e.g. Haskell.)

Definition 2.7. For $A, B \in \mathcal{S}$, an abstract Turing machine from A to B will be a synonym for a class representative of an element of $hom_{\mathcal{S}}(A,B)$. In other words it is a pair (T,T_e) as above, with $T:A \to B$. We will say that the corresponding Turing machine T_e encodes the map T or is the encoding of T. We say that (T,T_e) is total when T is total. We may simply write $T:A \to B$ for an abstract Turing machine, when T_e is implicit. We write $\overline{hom_{\mathcal{S}}}(A,B)$ for the set of abstract Turing machines from A to B.

Often we will say Turing machine in place of abstract Turing machine, since usually there can be no confusion as to the meaning.

We define $\mathcal{T}_{\mathcal{S}}$ to be the set of abstract Turing machines relative to \mathcal{S} as above. More formally:

$$\mathcal{T}_{\mathcal{S}} = \bigcup_{(A,B)\in\mathcal{S}^2} \overline{hom}_{\mathcal{S}}(A,B).$$

 $\mathcal{T}_{\mathcal{S}}$ will not be encoded.

We write Maps(A, B) for the set of partial maps from A to B, and if we say map this just means partial map, unless we say total map. Let

$$\mathcal{M}_{\mathcal{S}} := \bigcup_{(A,B) \in \mathcal{S}^2} Maps(A,B).$$

Given a Turing machine $T: A \to B$, we have an associated map $fog(T): A \to B$ defined by forgetting the additional structure T_e . However, we may also just write T for this map by abuse of notation. So we have a forgetful map

$$fog: \mathcal{T}_{\mathcal{S}} \to \mathcal{M}_{\mathcal{S}},$$

which forgets the extra structure of an encoding Turing machine.

Definition 2.8. We say that $T \in \mathcal{T}_{\mathcal{S}}$ computes $M \in \mathcal{M}_{\mathcal{S}}$ if fog(T) = M. We say that M is computable if some T computes M, or equivalently if M extends to a morphism of \mathcal{S} .

3. Stable computability and arithmetic

In this section, general sets, often denoted as B, are intended to be encoded. And all maps are partial maps, unless specified otherwise.

Definition 3.1. Given a Turing machine or just a map:

$$M: \mathbb{N} \to B \times \{\pm\},\$$

We say that $b \in B$ is M-stable if there is an m with M(m) = (b, +) and there is no n > m with M(n) = (b, -).

Definition 3.2. Given a Turing machine or just a map

$$M: \mathbb{N} \to B \times \{\pm\},\$$

 $we \ define$

$$M^s \subset B$$

to be the set of all the M-stable b. We call this the **stabilization of** M. We say that $S \subset B$ is **stably** c.e. if $S = M^s$ for M as above.

In general M^s may not be computable even if M is computable. Explicit examples of this sort can be readily constructed as shown in the following.

Example 3.3. Let Pol denote the set of all Diophantine polynomials, (also abstractly encoded). We can construct a total computable map

$$A: \mathbb{N} \to Pol \times \{\pm\}$$

whose stabilization consists of all Diophantine (integer coefficients) polynomials with no integer roots. Similarly, we can construct a computable map D whose stabilization consists of pairs (T, n) for $T : \mathbb{N} \to \mathbb{N}$ a Turing machine and $n \in \mathbb{N}$ such that *T(n) does not halt.

In the case of Diophantine polynomials, here is an (inefficient) example. Let

$$Z: \mathbb{N} \to Pol. N: \mathbb{N} \to \mathbb{Z}$$

be total bijective computable maps. The encoding of Pol should be suitably natural so that in particular the map

$$E: \mathbb{Z} \times Pol \to \mathbb{Z}, \quad (n, p) \mapsto p(n)$$

is computable. In what follows, for each $n \in \mathbb{N}$, $A_n \in L(Pol \times \{\pm\})$. \cup will be here and elsewhere in the paper the natural list union operation. More specifically, if $l_1 : \{0, \ldots, n\} \to B, l_2 : \{0, \ldots, m\} \to B$ are two lists then $l_1 \cup l_2$ is defined by:

(3.4)
$$l_1 \cup l_2(i) = \begin{cases} l_1(i), & \text{if } i \in \{0, \dots, n\} \\ l_2(i), & \text{if } i \in \{n+1, \dots, n+m+1\} \end{cases}.$$

If $B \in \mathcal{S}$, it is easy to see by the axioms of \mathcal{S} that $\cup : L(B) \times L(B) \to L(B)$, $(l, l') \mapsto l \cup l'$ is computable. For $n \in \mathbb{N}$ define A_n recursively by: $A_0 := \emptyset$,

$$A_{n+1} := A_n \cup \bigcup_{m=0}^n (Z(m), d^n(Z(m))),$$

where $d^n(p) = +$ if none of $\{N(0), \dots, N(n)\}$ are roots of p, $d^n(p) = -$ otherwise.

Note that

$$\forall n \in \mathbb{N} : A_{n+1}|_{\operatorname{domain} A_n} = A_n, \text{ and } \operatorname{length}(A_{n+1}) > \operatorname{length}(A_n),$$

so we may define $A(n) := A_{n+1}(n)$. With this definition $A(\mathbb{N}) = \bigcup_{n \in \mathbb{N}} \operatorname{image}(A_n)$.

Since E is computable, utilizing the axioms it can be explicitly verified that A is computable, i.e. an encoding Turing machine can be explicitly constructed, from the recursive program above. Moreover, by construction the stabilization A^s consists of Diophantine polynomials that have no integer roots.

3.1. **Decision maps.** By a *decision map*, we mean a map of the form:

$$D: B \times \mathbb{N} \to \{\pm\}.$$

This kind of maps will play a role in our arithmetic incompleteness theorems, and we now develop some of their theory.

Definition 3.5. Let $B \in \mathcal{S}$, define

$$A\mathcal{D}_B := \overline{hom}_{\mathcal{S}}(B \times \mathbb{N}, \{\pm\}),$$

and define

$$\mathcal{D}_B := \{ T \in \mathcal{T} | T = T'_e \text{ for } (T', T'_e) \in A\mathcal{D}_B \}.$$

Since T' above is uniquely determined, from now on, for $T \in \mathcal{D}_B$, when we write T' it is meant to be of the form above.

First we will explain construction of elements of \mathcal{D}_B from Turing machines of the following form.

Definition 3.6. Let $B \in \mathcal{S}$, define

$$A\mathcal{T}_B := \overline{hom}_{\mathcal{S}}(\mathbb{N}, B \times \{\pm\}),$$

and define

$$\mathcal{T}_B := \{ T \in \mathcal{T} | T = T'_a \text{ for } (T', T'_a) \in A\mathcal{T}_B \}.$$

From now on, given $T \in \mathcal{T}_{\mathcal{B}}$, if we write T' then it is will be assumed to be of the form above.

Lemma 3.7. Let $B \in \mathcal{S}$. There is a computable total map

$$K_B: \mathcal{T} \to \mathcal{T}$$
,

with the properties:

- (1) For each T, $K_B(T) \in \mathcal{T}_B$.
- (2) If $T \in \mathcal{T}_B$ then $K_B(T)$ and T encode the same map $\mathbb{N} \to B \times \{\pm\}$, in other words $T' = (K_B(T))'$.

Proof. Let $G: \mathcal{T} \times \mathbb{N} \to B \times \{\pm\}$ be the composition of the sequence of maps

$$\mathcal{T} \times \mathbb{N} \xrightarrow{id \times e_{\mathbb{N}}} \mathcal{T} \times \mathcal{U} \xrightarrow{U} \mathcal{U} \xrightarrow{e_{B \times \{\pm\}}^{-1}} B \times \{\pm\},$$

where the last map $e_{B \times \{\pm\}}^{-1}$ is defined by:

$$\Sigma \mapsto \begin{cases} e_{B \times \{\pm\}}^{-1}(\Sigma), & \text{if } \Sigma \in (B \times \{\pm\})_e \\ \text{undefined}, & \text{otherwise.} \end{cases}$$

In particular, this last map is computable as $(B \times \{\pm\})_e$ is by assumption computable/decidable. Hence, G is a composition of computable maps and so is computable. By Axiom 7 there is an induced computable map $K_B: \mathcal{T} \to \mathcal{T}$ so that $K_B(T)$ is the encoding of $G^T: \mathbb{N} \to B \times \{\pm\}$, $G^T(n) = G(T, n)$. By construction, if $T \in \mathcal{T}_B$ then $T' = (K_B(T))'$, so that we are done.

3.1.1. Constructing decision Turing machines.

Definition 3.8. Let $l \in L(B \times \{\pm\})$. Define $b \in B$ to be l-stable if there is an $m \leq \operatorname{length}(l)$ s.t. l(m) = (b, +) and there is no $m < k \leq \operatorname{length}(l)$ s.t. l(k) = (b, -).

Define

$$G: B \times \mathcal{T} \times \mathbb{N} \to \{\pm\}$$

to be the map:

$$G(b,T,n) = \begin{cases} \text{undefined,} & \text{if } (K_{\mathcal{A}}(T))'(i) \text{ is undefined for some } 0 \leq i \leq n \\ +, & b \text{ is } l\text{-stable for } l = \{(K_{\mathcal{A}}(T))'(0), \dots, K_{\mathcal{A}}(T))'(n)\} \\ -, & \text{otherwise.} \end{cases}$$

Let

$$(3.9) g: \mathbb{N} \to L(\mathbb{N})$$

be the map $g(n) = \{0, ..., n\}$, it is clearly computable directly by the Axiom 8. We can express G as the composition of the sequence of maps:

$$B \times \mathcal{T} \times \mathbb{N} \xrightarrow{id \times K_B \times g} B \times \mathcal{T} \times L(\mathbb{N}) \xrightarrow{id \times id \times L(e_{\mathbb{N}})} B \times \mathcal{T} \times L(\mathcal{U}) \xrightarrow{id \times LU} B \times L(\mathcal{U})$$

$$\xrightarrow{id \times L(e_{B \times \{\pm\}})} B \times L(B \times \{\pm\}) \to \{\pm\},$$

where the last map is:

$$(b,l) \mapsto \begin{cases} +, & \text{if } b \text{ is } l\text{-stable} \\ -, & \text{otherwise,} \end{cases}$$

which is computable by explicit verification, utilizing the axioms. And where $L(e_{\mathbb{N}}), L(e_{B\times\{\pm\}}^{-1})$ and LU are as in Lemma 2.6. In particular all the maps in the composition are computable and so G is computable.

Let

$$(3.10) Dec_B: \mathcal{T} \to \mathcal{T},$$

be the computable map corresponding G via Axiom 7, so that $Dec_B(T)$ is the encoding of

$$G^T: B \times \mathbb{N} \to \{\pm\}, G^T(b,n) = G(b,T,n).$$

The following is immediate:

Lemma 3.11. $Dec_B(T)$ has the property:

$$\forall T \in \mathcal{T} : Dec_B(T) \in \mathcal{D}_B.$$

Furthermore, if $T \in \mathcal{T}_B$ and is total then $Dec_B(T)$ is total.

Definition 3.12. For a Turing machine or just a map $D: B \times N \to \{\pm\}$, we say that $b \in B$ is D-decided if there is an m s.t. D(b,m) = + and for all $n \geq m$ $D(b,n) \neq -$. Likewise, for $T \in \mathcal{D}_B$ we say that $b \in B$ is T-decided if it is T'-decided. Also for $T \in \mathcal{T}_A$ we say that b is T-stable if it is T'-stable in the previous sense.

Lemma 3.13. Suppose that $T \in \mathcal{T}_B$ and T' is total then b is T-stable iff b is $Dec_B(T)$ -decided.

Proof. Suppose that b is T-stable. In particular, there is an $m \in \mathbb{N}$ so that b is l-stable for $l = \{T'(0), \dots, T'(n)\}$ all $n \geq m$. Thus, by construction

$$\forall n \geq m : G(B, T, n) = +,$$

and so b is G^T -decided (this is as above), and so $Dec_B(T)$ -decided.

Similarly, suppose that b is $Dec_B(T)$ -decided, then there is an m s.t. G(b,T,m)=+ and there is no n>m s.t. G(b,T,n)=-. It follows, since $T'=(K_B(T))'$, that $\exists m'\leq m: T'(m')=(b,+)$ and there is no n>m' s.t. T'(n)=(b,-). And so b is T-stable.

Example 3.14. By the Example 3.3 above there is a Turing machine

$$P = Dec_{\mathcal{A}}(A) : Pol \times \mathbb{N} \to \{\pm\}$$

that stably soundly decides if a Diophantine polynomial has integer roots, meaning:

p is P-decided $\iff p$ has no integer roots.

Likewise, there is a Turing decision machine that stably soundly decides the halting problem, in this sense.

Definition 3.15. Given a map

$$M: B \times \mathbb{N} \to \{\pm\}$$

and a Turing machine

$$M': B \times \mathbb{N} \to \{\pm\},\$$

we say that M' stably computes M if

$$b$$
 is M -decided $\iff b$ is M' -decided.

If $T \in \mathcal{D}_B$ then we say that T stable computes M iff T' stably computes M. Here, as before, $T' \in A\mathcal{D}_B$ is such that $T'_e = T$.

3.2. Arithmetic decision maps. Let \mathcal{A} be as in the introduction the set of sentences of arithmetic. Let $\mathcal{T}_{\mathcal{A}}$ be as in Definition 3.6 with respect to $B = \mathcal{A}$. That is elements of $\mathcal{T}_{\mathcal{A}}$ are of the form $T = T'_e$ for $(T', T'_e) \in A\mathcal{T}_{\mathcal{A}} = \overline{hom}_{\mathcal{S}}(\mathbb{N}, \mathcal{A} \times \{\pm\})$.

The following is a version for stably c.e. formal systems of the classical fact, going back to at least Gödel, that for a formal system with a c.e. set of axioms we may computably enumerate its theorems. Moreover, the procedure to obtain the corresponding Turing machine is constructive.

Notation 2. Note that each $T \in \mathcal{T}_{\mathcal{A}}$, determines the set

$$(T')^s \subset \mathcal{A},$$

called the stabilization of T', we hereby abbreviate the notation for this set as T^s .

Lemma 3.16. There is a computable total map:

$$C:\mathcal{T}\to\mathcal{T}$$

so that $\forall T \in \mathcal{T} : C(T) \in \mathcal{T}_{\mathcal{A}}$. If in addition $T \in \mathcal{T}_{\mathcal{A}}$ and T' is total then $(C(T))^s$ is the deductive closure of T^s .

Proof. Let L(A) be as in axioms of S, defined with respect to B = A. The following lemma is classical and its proof is omitted. Strictly speaking we of course need that the encoding of A is suitably natural. We may assume the standard Gödel encoding.

Lemma 3.17. There is a total computable map:

$$\Phi: L(\mathcal{A}) \times \mathbb{N} \to \mathcal{A}$$

with the following property. For each $l \in L(A)$, $\Phi(\{l\} \times \mathbb{N})$ is the set of all sentences provable by the formal system l, the latter being shorthand for the image of the corresponding map $l: \{0, \ldots, n\} \to A$.

Let K_A be as in Lemma 3.7, with respect to B = A. Define a map

$$\zeta: \mathcal{T} \times \mathbb{N} \times L(\mathcal{A}) \to \{\pm\}$$

by

$$\zeta(T,n,l) = \begin{cases} \text{undefined,} & \text{if } (K_{\mathcal{A}}(T))'(i) \text{ is undefined for some } 0 \leq i \leq n \\ +, & \text{if for each } 0 \leq i \leq n, \ l(i) \text{ is } l\text{-stable for } l = \{(K_{\mathcal{A}}(T))'(0), \dots, K_{\mathcal{A}}(T))'(n)\} \\ -, & \text{otherwise.} \end{cases}$$

We can express ζ as the composition of the sequence of maps

$$\mathcal{T} \times \mathbb{N} \times L(\mathcal{A}) \xrightarrow{K_{\mathcal{A}} \times id \times id} \mathcal{T} \times \mathbb{N} \times L(\mathcal{A}) \xrightarrow{id \times g \times id} \mathcal{T} \times L(\mathbb{N}) \times L(\mathcal{A})$$

$$\xrightarrow{id \times L(e_{\mathbb{N}}) \times id} \mathcal{T} \times L(\mathcal{U}) \times L(\mathcal{A}) \xrightarrow{LU \times id} L(\mathcal{U}) \times L(\mathcal{A}) \xrightarrow{L(e_{\mathcal{A}}^{-1}\{\pm\}) \times id} L(\mathcal{A} \times \{\pm\}) \times L(\mathcal{A}) \to \{\pm\}.$$

Here the last map is

$$(l,l') \mapsto \begin{cases} +, & \text{if } l'(i) \text{ is } l\text{-stable, for each } 0 \leq i \leq \text{length}(l') \\ -, & \text{otherwise} \end{cases}$$

it is computable by explicit verification utilizing the axioms. The map g in the second map is as in (3.9). Thus, all maps in the composition are computable and ζ is computable.

Now define G to be the composition of the sequence of maps:

$$\mathcal{T} \times L(\mathbb{N}) \xrightarrow{K_{\mathcal{A}} \times L(e_{\mathbb{N}})} \mathcal{T} \times L(\mathcal{U}) \xrightarrow{LU} L(\mathcal{U}) \xrightarrow{L(e_{\mathcal{A} \times \{\pm\}})} L(\mathcal{A} \times \{\pm\}) \xrightarrow{L(pr_{\mathcal{A}})} L(\mathcal{A}),$$

where $pr_{\mathcal{A}}: \mathcal{A} \times \{\pm\} \to \mathcal{A}$ is the natural projection. The third and fourth map are as in Lemma 2.6 for $e_{\mathcal{A} \times \{\pm\}}^{-1}$, as in Lemma 3.7. All the maps in the composition are computable directly by the axioms of \mathcal{S} and so G is computable.

We may now construct our map C. In what follows \cup will be the natural list union operation as previously in (3.4). Set

$$L_n(\mathbb{N}) := \{l \in L(\mathbb{N}) | \max l \le n, \max l \text{ the maximum of } l \text{ as a map} \}.$$

For $n \in \mathbb{N}$, define $U_n^T \in L(\mathcal{A} \times \{\pm\})$ recursively by $U_0^T := \emptyset$,

$$U_{n+1}^T := U_n^T \cup \bigcup_{l \in L_{n+1}(\mathbb{N})} (\Phi(G(T, l), n+1), \zeta(T, n+1, G(T, l))).$$

As in Example 3.3 we define $U^T: \mathbb{N} \to \mathcal{A} \times \{\pm\}$ by $U^T(n) := U^T_{n+1}(n)$, note that the right-hand side may be undefined since G is only a partial map. So U^T is a partial map. And this induces a partial map

$$U: \mathcal{T} \times \mathbb{N} \to \mathcal{A} \times \{\pm\},\$$

 $U(T,n) := U^T(n)$. U is computable by explicit verification, utilizing the axioms of S, i.e. an encoding Turing machine can be readily constructed from the recursive program for $\{U_n^T\}$ above. Hence, by the Axiom 7 there is an induced by U computable map:

$$C: \mathcal{T} \to \mathcal{T}$$
,

s.t. for each $T \in \mathcal{T}$ C(T) computes U^T . If $T \in \mathcal{T}_A$ and is total then $(U^T)^s$ is by construction the deductive closure of $(K_A(T))^s = T^s$. So the map C has the needed property, and we are done. \square

Definition 3.18. Let \mathcal{F}_0 , as in the introduction, denote the set of formulas ϕ of arithmetic with one free variable so that $\phi(n)$ is an RA-decidable sentence for each n. Let $M: \mathbb{N} \to \mathcal{A} \times \{\pm\}$ be a map (or a Turing machine). The notation $M \vdash \alpha$ will be short for $M^s \vdash \alpha$. We say that M is speculative if the following holds. Let $\phi \in \mathcal{F}_0$, and set

$$\alpha_{\phi} = \forall m : \phi(m),$$

then

$$\forall m : RA \vdash \phi(m) \implies M \vdash \alpha_{\phi}.$$

Note that of course the left-hand side is not the same as $RA \vdash \alpha_{\phi}$.

We may informally interpret this condition as saying that M initially outputs α as a hypothesis, and removes α from its list (that is α will not be in M^s) only if for some m, $RA \vdash \neg \phi(m)$. Note that we previously constructed an Example 3.3 of a Turing machine, with an analogue of this speculative property. Moreover, we have the following crucial result, which to paraphrase states that there is an operation Spec that converts a stably c.e. formal system to a speculative stably c.e. formal system, at a certain loss of consistency.

Theorem 3.20. There is a computable total map $Spec: \mathcal{T} \to \mathcal{T}$, with the following properties:

- (1) image $Spec \subset \mathcal{T}_{\mathcal{A}}$.
- (2) Let $T \in \mathcal{T}_A$. Set $T_{spec} = Spec(T)$ then T'_{spec} is speculative, moreover if T' is total then so is
- (3) Using Notation 2, if $T \in \mathcal{T}_{\mathcal{A}}$ then $T^s_{spec} \supset T^s$ (4) If $T \in \mathcal{T}_{\mathcal{A}}$ and T^s is 1-consistent then T^s_{spec} is consistent.

Proof. \mathcal{F}_0 , \mathcal{A} are assumed to be encoded so that the map

$$ev: \mathcal{F}_0 \times \mathbb{N} \to \mathcal{A}, \quad (\phi, m) \mapsto \phi(m)$$

is computable.

Lemma 3.21. There is a total computable map $F: \mathbb{N} \to \mathcal{F}_0 \times \{\pm\}$ with the property:

$$F^s = G := \{ \phi \in \mathcal{F}_0 \mid \forall m : RA \vdash \phi(m) \}.$$

Proof. The construction is analogous to the construction in the Example 3.3 above. Fix any total, bijective, Turing machine

$$Z: \mathbb{N} \to \mathcal{F}_0.$$

For a $\phi \in \mathcal{F}_0$ we will say that it is n-decided if

$$\forall m \in \{0, \dots, n\} : RA \vdash \phi(m).$$

In what follows each F_n has the type of ordered finite list of elements of $\mathcal{F}_0 \times \{\pm\}$, and \cup will be the natural list union operation, as previously. Define $\{F_n\}_{n\in\mathbb{N}}$ recursively by $F_0 := \emptyset$,

$$F_{n+1} := F_n \cup \bigcup_{\phi \in \{Z(0), \dots, Z(n)\}} (\phi, d^n(\phi)),$$

where
$$d^n(\phi) = +$$
 if ϕ is n-decided and $d^n(\phi) = -$ otherwise.

We set $F(n) := F_{n+1}(n)$. This is a total map $F : \mathbb{N} \to \mathcal{F}_0 \times \{\pm\}$, having the property $F(\mathbb{N}) = \mathbb{N}$ $\cup_n \operatorname{image}(F_n)$. F is computable by explicit verification, using the axioms of S.

Returning to the proof of the theorem. Let $K = K_A : \mathcal{T} \to \mathcal{T}$ be as in Lemma 3.7. For $\phi \in \mathcal{F}_0$ let α_{ϕ} be as in (3.19). Define: $H: \mathcal{T} \times \mathbb{N} \to \mathcal{A} \times \{\pm\}$ by

$$H(T,n) := \begin{cases} (K_{\mathcal{A}}(T))'(k), & \text{if } n = 2k+1\\ (\alpha_{pr_{\mathcal{F}_0} \circ F(k)}, pr_{\pm} \circ F(k)), & \text{if } n = 2k, \end{cases}$$

where $pr_{\mathcal{F}_0}: \mathcal{F}_0 \times \{\pm\} \to \mathcal{F}$, and $pr_{\pm}: \mathcal{F}_0 \times \{\pm\} \to \{\pm\}$ are the natural projections. H is computable directly by the axioms of S. (Factor H as a composition of computable maps as previously.)

Let $Spec: \mathcal{T} \to \mathcal{T}$ be the computable map corresponding to H via Axiom 7. In particular, for each $T \in \mathcal{T}$, Spec(T) encodes the map

$$T_{spec}' := H^T : \mathbb{N} \to \mathcal{A} \times \{\pm\}, \quad H^T(n) = H(T, n),$$

which by construction is speculative. Now, Spec(T) satisfies the Properties 1, 2, 3 immediately by construction. It only remains to check Property 4.

Lemma 3.22. Let $T \in \mathcal{T}_{\mathcal{A}}$, then T^s_{spec} is consistent unless for some $\phi \in G$

$$T^s \vdash \neg \forall m : \phi(m).$$

Proof. Suppose that T_{spec}^{s} is inconsistent so that:

$$T^s \cup \{\alpha_{\phi_1}, \dots, \alpha_{\phi_n}\} \vdash \alpha \land \neg \alpha$$

for some $\alpha \in \mathcal{A}$, and some $\phi_1, \ldots, \phi_n \in G$. Hence,

$$T^s \vdash \neg(\alpha_{\phi_1} \land \ldots \land \alpha_{\phi_n}).$$

But

$$\alpha_{\phi_1} \wedge \ldots \wedge \alpha_{\phi_n} \iff \forall m : \phi(m),$$

where ϕ is the formula with one free variable: $\phi(m) := \phi_1(m) \wedge \ldots \wedge \phi_n(m)$. Clearly $\phi \in G$, since $\phi_i \in G$, $i = 1, \ldots, n$. Hence, the conclusion follows.

Suppose that T^s_{spec} inconsistent, then by the lemma above for some $\phi \in G$:

$$T^s \vdash \exists m : \neg \phi(m).$$

Since T^s is 1-consistent:

$$\exists m : T^s \vdash \neg \phi(m).$$

But ϕ is in G, and $T^s \vdash RA$ (recall Definition 1.3) so that $\forall m : T^s \vdash \phi(m)$ and so

$$\exists m : T^s \vdash (\neg \phi(m) \land \phi(m)).$$

So T^s is inconsistent, a contradiction, so T^s_{spec} is consistent.

4. Semantic incompleteness for stably computable formal systems

We start with the simpler semantic case, essentially for the purpose of exposition. However, many elements here will be reused for the main theorems in the next section.

Let $\mathcal{D}_{\mathcal{T}} \subset \mathcal{T}$ be as in Definition 3.5 with respect to $B = \mathcal{T}$.

Definition 4.1. For $T \in \mathcal{D}_{\mathcal{T}}$, T is T-decided, is a special case of Definition 3.12. Or more specifically, it means that the element $T \in \mathcal{T}$ is T'-decided. We also say that T is not T-decided, when $\neg(T \text{ is } T\text{-decided}) \text{ holds.}$

Definition 4.2. We call a map $D: \mathcal{T} \times \mathbb{N} \to \{\pm\}$ **Turing decision map**. We say that such a D is stably sound on $T \in \mathcal{T}$ if

$$(T \text{ is } D\text{-decided}) \implies (T \in \mathcal{D}_{\mathcal{T}}) \wedge (T \text{ is not } T\text{-decided}).$$

We say that D is stably sound if it is stably sound on all T. We say that D stably decides T if:

$$(T \in \mathcal{D}_{\mathcal{T}}) \wedge (T \text{ is not } T\text{-decided}) \implies T \text{ is } D\text{-decided}.$$

We say that D stably soundly decides T if D is stably sound on T and D stably decides T. We say that D is stably sound and complete if D stably soundly decides T for all $T \in \mathcal{T}$.

The informal interpretation of the above is that each such D is understood as an operation with the properties:

- For each T, n D(T, n) = + if and only if D "decides" at the moment n that the sentence $(T \in \mathcal{D}_T) \wedge (T \text{ is not } T\text{-decided})$ is true.
- For each T, n D(T, n) = if and only if D cannot "decide" at the moment n the sentence $(T \in \mathcal{D}_T) \wedge (T \text{ is not } T\text{-decided})$, or D "decides" that it is false.

In what follows for $T \in \mathcal{T}$, and D as above, $\Theta_{D,T}$ is shorthand for the sentence:

$$(T \in \mathcal{D}_{\mathcal{T}}) \wedge (T \text{ stably computes } D).$$

Lemma 4.3. If D is stably sound on $T \in \mathcal{T}$ then

$$\neg \Theta_{D,T} \vee \neg (T \text{ is } D\text{-decided}).$$

Proof. If T is D-decided then since D is stably sound on $T, T \in \mathcal{D}_{\mathcal{T}}$ and T is not T-decided, so if in addition $\Theta_{D,T}$ then T is not D-decided a contradiction.

The following is the "stable" analogue of Turing's halting theorem.

Theorem 4.4. There is no (stably) computable Turing decision map D that is stably sound and complete.

Proof. Suppose otherwise, and let D be stably sound and complete. Then by the above lemma we obtain:

$$(4.5) \qquad \forall T \in \mathcal{D}_{\mathcal{T}} : \Theta_{D,T} \vdash \neg (T \text{ is } D\text{-decided}).$$

But it is immediate:

$$(4.6) \qquad \forall T \in \mathcal{D}_{\mathcal{T}} : \Theta_{D,T} \vdash (\neg (T \text{ is } D\text{-decided})) \vdash \neg (T \text{ is } T\text{-decided})).$$

So combining (4.5), (4.6) above we obtain

$$\forall T \in \mathcal{D}_T : \Theta_{D,T} \vdash \neg (T \text{ is } T\text{-decided}).$$

But D is complete so $(T \in \mathcal{D}_T) \land \neg (T \text{ is } T\text{-decided}) \implies T \text{ is } D\text{-decided and so:}$

$$\forall T \in \mathcal{D}_{\mathcal{T}} : \Theta_{D,T} \vdash (T \text{ is } D\text{-decided}).$$

Combining with (4.5) we get

$$\forall T \in \mathcal{D}_{\mathcal{T}} : \neg \Theta_{D,T}$$

which is what we wanted to prove.

Theorem 4.7. Suppose $F \subset A$ is stably c.e. and sound as a formal system, then there is a constructible (given a Turing machine stably computing F) true in the standard model of arithmetic sentence $\alpha(F)$, which F does not prove.

The fact that such an $\alpha(F)$ exists, can be immediately deduced from Tarski undecidability of truth, as the set F must be definable in first order arithmetic by the condition that F is stably c.e. However, our sentence is constructible by very elementary means, starting with the definition of a Turing machine, and the basic form of this sentence will be used in the next section. The above is of course only a meta-theorem. This is in sharp contrast to the syntactic incompleteness theorems in the following section which are actual theorems of ZF.

Proof of Theorem 4.7. Suppose that F is stably c.e. and is sound. Let $(M, M_e) : \mathbb{N} \to \mathcal{A} \times \{\pm\}$ be a total Turing machine s.t. $F = M^s(N)$. Let $C(M_e)$ be as in Lemma 3.16. If we understand arithmetic as being embedded in set theory ZF in the standard way, then for each $T \in \mathcal{T}$ the sentence

$$(T \in \mathcal{D}_{\mathcal{T}}) \wedge (T \text{ is not } T\text{-decided})$$

is logically equivalent in ZF to a first order sentence in arithmetic, that we call s(T). The corresponding translation map $s: \mathcal{T} \to \mathcal{A}, T \mapsto s(T)$ is taken to be computable. Indeed, this kind of translation already appears in the original work of Turing [1].

Define a Turing decision map D by

$$D(T,n) := (Dec_{\mathcal{A}}(C(M_e)))'(s(T),n)$$

for $Dec_{\mathcal{A}}$ as in (3.10) defined with respect to $B = \mathcal{A}$, and where C is as in Section 3. Then by construction, and by Axiom 4 in particular, D is computable by some Turing machine (D, D_e) , we make this more explicit in the following Section 5.

Now D is stably sound by Lemma 3.13 and the assumption that F is sound. So by Lemma 4.3:

$$\neg (D_e \text{ is } D\text{-decided}).$$

In particular, $s(D_e)$ is not $Dec_{\mathcal{A}}(C(M_e))$ -decided, and so $s(D_e)$ is not $C(M_e)$ -stable (Lemma 3.13), i.e. $M \not\vdash s(D_e)$.

On the other hand,

$$\neg(D_e \text{ is } D\text{-decided}) \models \neg(D_e \text{ is } D_e\text{-decided}),$$

by definition. And so since $D_e \in \mathcal{D}_{\mathcal{T}}$ by construction, $s(D_e)$ is satisfied. Set $\alpha(M) := s(D_e)$ and we are done.

5. Syntactic incompleteness for stably computable formal systems

Let $s: \mathcal{T} \to \mathcal{A}, T \mapsto s(T)$ be as in the previous section. Define

$$H: \mathcal{T} \times \mathcal{T} \times \mathbb{N} \to \{\pm\},\$$

by $H(M,T,n) := (Dec_{\mathcal{A}}(C(Spec(M))))'(s(T),n)$. We can express H as the composition of the sequence of maps:

$$(5.1) \mathcal{T} \times \mathcal{T} \times \mathbb{N} \xrightarrow{Dec_{\mathcal{A}} \circ C \circ Spec \times s \times id} \mathcal{T} \times \mathcal{A} \times \mathbb{N} \xrightarrow{id \times e_{\mathcal{A} \times \mathbb{N}}} \mathcal{T} \times \mathcal{U} \xrightarrow{U} \mathcal{U} \xrightarrow{e^{-1}_{\{\pm\}}} \{\pm\},$$

where the last map is:

$$\Sigma \mapsto \begin{cases} \text{undefined}, & \text{if } \Sigma \notin \{\pm\}_e \\ e_{\{\pm\}}^{-1}(\Sigma), & \text{otherwise.} \end{cases}$$

So H is a composition of maps that are computable by the axioms of S and so H is computable. Hence, by Axiom 7 there is an associated computable map:

$$(5.2) Tur: \mathcal{T} \to \mathcal{T},$$

s.t. for each $M \in \mathcal{T}$, Tur(M) encodes the map $D^M : \mathcal{T} \times \mathbb{N} \to \{\pm\}$, $D^M(T,n) = H(M,T,n)$. In what follows, $(M, M_e) : \mathbb{N} \to \mathcal{A} \times \{\pm\}$ will be a fixed total Turing machine. We abbreviate D^{M_e} by D and $Tur(M_e)$ by D_e . As usual notation of the form $M \vdash \alpha$ means $M^s \vdash \alpha$.

Proposition 5.3. For $(M, M_e), (D, D_e)$ as above:

$$M^s$$
 is 1-consistent $\Longrightarrow M \nvdash s(D_e)$.

$$M^s$$
 is 2-consistent $\implies M \nvdash \neg s(D_e)$.

Moreover, the sentence:

$$M^s$$
 is 1-consistent $\implies s(D_e)$

is a theorem of PA under standard interpretation of all terms, (this will be further formalized in the course of the proof).

Proof. This proposition is meant to just be a theorem of set theory ZF, however we avoid complete set theoretic formalization, as is common. Arithmetic is interpreted in set theory the standard way, using the standard set $\mathbb N$ of natural numbers. So for example, for $M:\mathbb N\to \mathcal A\times\{\pm\}$ a sentence of the form $M\vdash\alpha$ is a priori interpreted as a sentence of ZF, however if M is a Turing machine this also can be interpreted as a sentence of PA, once Gödel encodings are invoked.

Set $N := (Spec(M_e))'$, in particular this is a speculative total Turing machine $\mathbb{N} \to \mathcal{A} \times \{\pm\}$. Set $s := s(D_e)$. Suppose that $M \vdash s$. Hence, $N \vdash s$ and so s is $C(Spec(M_e))$ -stable, and so by Lemma 3.13 s is $Dec_{\mathcal{A}}(C(Spec(M_e)))$ -decided, and so D_e is D-decided by definition. More explicitly, we deduce the sentence η_{M_e} :

$$\exists m \forall n \geq m : (Tur(M_e))'(Tur(M_e), m) = +.$$

i.e.
$$\exists m \forall n \geq m : D(D_e, m) = +.$$

In other words:

$$(5.4) (M \vdash s) \implies \eta_{M_e}$$

is a theorem of ZF.

If we translate η_{M_e} to an arithmetic sentence we just call $\eta = \eta(M_e)$, then η can be chosen to have the form:

$$\exists m \forall n : \gamma(m, n),$$

where $\gamma(m,n)$ is RA-decidable. The sentence $s=s(D_e)$ is assumed to be of the form $\beta(M_e) \land \neg \eta(M_e)$, where $\beta(M_e)$ is the arithmetic sentence equivalent in ZF to $(D_e = Tur(M_e) \in \mathcal{D}_T)$. Clearly, the translation maps $\mathcal{T} \to \mathcal{A}$, $T \mapsto \beta(T)$, $T \mapsto \eta(T)$ can be taken to be computable, and such that applying Lemma 3.11 (interpreted as a Theorem of PA): we get

$$(5.5) PA \vdash \forall T \in \mathcal{T} : \beta(T).$$

And so

$$(5.6) PA \vdash (\eta(M_e) \implies \neg s(D_e)).$$

Moreover, ZF proves:

$$\eta_{M_e} \implies \exists m \forall n : RA \vdash \gamma(m,n), \text{ trivially}$$

$$\implies \exists m : N \vdash \forall n : \gamma(m,n), \text{ since } N \text{ is speculative}$$

$$\implies N \vdash \eta,$$

$$\implies N \vdash \neg s, \text{ by (5.6) and since } N^s \supset PA.$$

And so combining with (5.4), (5.6) ZF proves:

$$(M \vdash s) \implies (N \vdash s) \land (N \vdash \neg s).$$

Since by Theorem 3.20

$$M^s$$
 is 1-consistent $\implies N^s$ is consistent,

it follows:

(5.7)
$$ZF \vdash (M^s \text{ is 1-consistent } \Longrightarrow M \nvdash s \pmod{N \nvdash s}).$$

Now suppose

$$(M^s \text{ is 2-consistent}) \land (M \vdash \neg s).$$

Since we have (5.5), and since $M \vdash PA$ it follows that $M \vdash \eta$. Now,

$$M \vdash \eta \iff M \vdash \exists m \forall n : \gamma(m, n),$$

 $\implies \neg(\forall m : M \vdash \neg \phi(m))$ by 2-consistency,

where

$$\phi(m) = \forall n : \gamma(m, n).$$

So we deduce

$$\exists m : M \vdash \phi(m).$$

Furthermore,

$$\exists m: M \vdash \phi(m) \implies \exists m \forall n: M \vdash \gamma(m,n), \quad M^s \text{ is consistent}$$

$$\implies \exists m \forall n: RA \vdash \gamma(m,n), \quad M^s \text{ is consistent}, \ M^s \supset RA \text{ and } \gamma(m,n) \text{ is } RA\text{-decidable}.$$

In other words, ZF proves:

$$(M^s \text{ is 2-consistent } \land (M \vdash \neg s)) \implies \eta.$$

And ZF proves:

$$\eta \implies N \vdash s,$$

by constructions. So ZF proves:

$$(M^s \text{ is 2-consistent} \land (M \vdash \neg s)) \implies N \vdash s$$

$$\implies N^s \text{ is inconsistent}$$

$$\implies M^s \text{ is not 1-consistent, by Theorem 3.20}$$

$$\implies M^s \text{ is not 2-consistent.}$$

And so ZF proves:

$$M^s$$
 is 2-consistent $\implies M \nvdash \neg s$.

Now for the last part of the proposition. We essentially just further formalize (5.7) and its consequences in PA. In what follows by equivalence of sentences we mean equivalence in ZF. The correspondence of sentences under equivalence is the standard kind of correspondence assigning predicates involving Turing machines predicates in PA. The basic form of such correspondences is already constructed by Turing [1], so that we will not elaborate. In particular, the correspondences are computable, which just means that the corresponding map $\mathcal{T} \to \mathcal{A}$ is computable.

Definition 5.8. We say that $T \in \mathcal{T}$ is stably 1-consistent if $T \in \mathcal{T}_A$, T' is total and T^s is 1-consistent, (Notation 2).

Then the sentence:

T is stably 1-consistent

is equivalent to an arithmetic sentence we denote:

$$1 - con^s(T)$$
.

The sentence $Spec(T) \not\vdash s(Tur(T))$ is equivalent to an arithmetic sentence we call:

$$\omega(T)$$
.

By the proof of the first part of the proposition, that is by (5.7),

$$(5.9) ZF \vdash \forall T \in \mathcal{T} : (1 - con^s(T) \implies \omega(T)).$$

But we also have:

$$(5.10) PA \vdash \forall T \in \mathcal{T} : (1 - con^s(T) \implies \omega(T)),$$

since the first part of the proposition can be formalized in PA, in fact the only interesting theorems we used are Lemma 3.13, and Theorem 3.20 which are obviously theorems of PA. By Lemma 3.13 and the construction of H:

$$PA \vdash \forall T \in \mathcal{T} : \omega(T) \iff \neg \eta(T).$$

So:

$$PA \vdash \forall T \in \mathcal{T} : (\beta(T) \land \omega(T) \iff s(Tur(T))),$$

Combining with (5.5) and with (5.10) we get:

$$PA \vdash \forall T \in \mathcal{T} : (1 - con^s(T) \implies s(Tur(T))).$$

So if we formally interpret the sentence " M^s is 1-consistent" as the arithmetic sentence $1-con^s(M_e)$, then this formalizes and proves the second part of the proposition.

Proof of Theorems 1.4, 1.5. Let F be as in the hypothesis. As F is stably c.e. we may find a Turing machine (M, M_e) such that $F = M^s$. We may in addition assume that M is total, by classical theory. Let (D, D_e) be as in the proposition above, and set $\alpha(F) := s(D_e)$. Then Theorem 1.4 follows by part one of the proposition above. \square

Appendix A. Briefly on physical ramifications - intelligence, Gödel's disjunction and Penrose

In this appendix we give some additional background, and explore some physical ideas nearby to the mathematical results of the paper. This is intended to be very concise.

In what follows we understand human intelligence very much like Turing in [2], as a black box which receives inputs and produces outputs. More specifically, this black box M is meant to be some system which contains a human subject. We do not care about what is happening inside M. So we are not directly concerned here with such intangible things as understanding, intuition, consciousness - the inner workings of human intelligence that are supposed to be special. The only thing that concerns us is what output M produces given an input. Given this very limited interpretation, the question that we are interested in is this:

Question 1. Can human intelligence be completely modeled by a Turing machine?

Turing himself has started on a form of Question 1 in his "Computing machines and Intelligence" [2], where he also informally outlined a possible obstruction to a yes answer coming from Gödel's incompleteness theorem. We will remark on this again further on.

A.0.1. Gödel's disjunction. Around the same time as Turing, Gödel argued for a no answer to Question 1, see [11, 310], relating the question to existence of absolutely unsolvable Diophantine problems, see also Feferman [6], and Koellner [13], [14] for a discussion. Let $F \subset \mathcal{A}$ be the mathematical output of a certain idealized mathematician S (where for the moment we leave the latter undefined). Essentially, Gödel argues for a disjunction, the following cannot hold simultaneously:

F is computably enumerable, F is consistent and A,

where A says that F can decide any Diophantine problem. At the same time Gödel doubted that $\neg A$ is possible, again for an idealized S, as this puts absolute limits on what is humanly knowable even in arithmetic. Note that his own incompleteness theorem only puts relative limits on what is humanly knowable, within a fixed formal system.

Claim 1. It is impossible to meaningfully formalize Gödel's disjunction without strengthening the incompleteness theorems.

Already Feferman asks in [6] what is the meaning of 'idealized' above? In the context of the present paper we might propose that it just means stabilized (cf. Section 3 specifically). But there are Turing machines T whose stabilization T^s is not computably enumerable, as shown in Example 3.3. In that case, the above Gödel disjunction becomes meaningless because passing to the idealization may introduce non-computability where there was none before. So in this context one must be extremely detailed with what "idealized" means physically and mathematically. The process of the idealization must be such that non-computability is not introduced in the ideal limit, if we want to apply the classical incompleteness theorems.

Otherwise, if we give up computability of the ideal limit, then we must suitably extend the incompleteness theorems. For example, we may attempt to weakly idealize brain processes as follows. Suppose we know that there is a mathematical model M for the biological human brain, in which the deterioration of the brain is described by some explicit stochastic process, on top of the base cognitive processes. Then mathematically a weak idealization M^{ideal} of M would just correspond to the removal of this stochastic process. Let $F = (M^{ideal})^s$, where $M^{ideal} : \mathbb{N} \to \mathcal{A} \times \{\pm\}$ models the mathematical output of our weakly idealized subject based on the model M^{ideal} . Hence, by construction, F is not stably c.e., only if some cognitive processes of the brain (in the given mathematical model M) were non-computable. We may then meaningfully apply Theorem 1.5 to this F.

A.0.2. Formalizing Gödel's disjunction. As already outlined we must first propose a suitable idealization to which we may apply the incompleteness theorems of this paper. The initial proposal above is to suitably idealize brain processes, but this is only theoretical since we are far from understanding the human brain. Another, more immediate approach is to simply substitute humanity (evolving in

time), in place of a subject. This has its own practical problems that we ignore, but fits well with our expectation that overall human knowledge converges on truth. Thus, we suppose that associated to humanity there is a function:

$$H: \mathbb{N} \to \mathcal{A} \times \{\pm\},\$$

determined for example by majority consensus. Majority consensus is not as restrictive as it sounds. For example if there is a computer verified proof of the Riemann hypothesis α in ZFC, then irrespectively of the complexity of the proof, we can expect majority consensus for α , provided validity of set theory still has consensus. At least if we reasonably interpret H, which is beyond the scope here.

In what follows, $\mathcal{H} = H^s$, for H as outlined above. So that informally \mathcal{H} is the infinite time limit of the mathematical output of humanity in the language of arithmetic. There is clearly some freedom for how the underlying map H is interpreted and constructed, however \mathcal{H} itself is at least morally unambiguous.

Instead of trying to totally specify H, we will instead assume the following axiom:

Axiom A.1. If the physical processes underlying the output of H are computable, this may include computability of certain stochastic variables as probability distribution valued maps - then the set H is stably computably enumerable.

Applying Theorem 1.5 we then get the following.

Theorem A.2. Suppose that $\mathcal{H} \vdash PA$, where \mathcal{H} is understood as a formal system in the language of arithmetic. Then either \mathcal{H} is not stably computably enumerable or \mathcal{H} is not 1-consistent or \mathcal{H} cannot prove a certain true statement of arithmetic (and cannot disprove it if in addition \mathcal{H} is 2-consistent). Assuming the axiom above, this can be restated as follows. Suppose that $\mathcal{H} \vdash PA$ and \mathcal{H} is 1-consistent. Then either there are absolutely non Turing computable processes in nature 2 or there exists a true in the standard model constructive statement of arithmetic $\alpha(\mathcal{H})$ that \mathcal{H} cannot prove (and cannot disprove if \mathcal{H} is in addition 2-consistent). (By constructive we mean provided a specification of a Turing machine stably computing \mathcal{H} .)

By absolutely we mean in any sufficiently accurate physical model. Note that of course existence of absolutely non Turing computable processes in nature is not known. For example, we expect beyond reasonable doubt that solutions of fluid flow or N-body problems are generally non Turing computable (over \mathbb{Z} , if not over \mathbb{R} cf. [3]) ³ as modeled in essentially classical mechanics. But in a more physically accurate and fundamental model both of the processes above may become computable, possibly if the nature of the universe is ultimately discreet. It would be good to compare this theorem with Deutsch [5], where computability of any suitably finite and discreet physical system is conjectured. Although this is not immediately at odds with us, as the hypothesis of that conjecture may certainly not be satisfiable in our case.

A.0.3. Lucas-Penrose thesis. After Gödel, Lucas [10] and later again and more robustly Penrose [16] argued for a no answer based only on consistency and the Gödel incompleteness theorem, that is attempting to remove the necessity to decide A or $\neg A$. For a discussion of Penrose's argument in particular, see for instance Koellner [13], [14]. See also Penrose [16], and Chalmers [4] for earlier discussions.

Using Theorem 1.5, we can modify the Penrose argument as follows. Let P be a human subject, let $P^{ideal}: \mathbb{N} \to \mathcal{A} \times \{\pm\}$ be as above a weak idealization for the mathematical output of P. Set $F_P := (P^{ideal})^s$. Suppose for the moment that F_P is knowably (to P) definable in arithmetic (meaning

²Specifically, we may conclude in the case of this alternative that the brain-universe interaction is not computable. But we cannot immediately conclude that there are non-computable processes specifically "in the human brain", without extensively elaborating on our thought experiment to include some kind of controlled isolation of subjects from the environment.

³We now involve real numbers, but there is a standard theory of computability in this case, in terms of computable real numbers, this is what means over \mathbb{Z} .

that the corresponding formula in arithmetic can be constructed). Suppose also that $F_P \vdash PA$ and suppose that our P asserts the sentence of arithmetic:

F_P is 1-consistent.

(As argued by Penrose, this is a natural kind of assertion, in fact P naturally believes himself to be stably sound meaning that F_P is sound. And we have no reason to believe otherwise.) Thus, $F_P \vdash (F_P \text{ is 1-consistent})$ and so by Theorem 1.5 either F_P is not 1-consistent or F_P is not stably c.e., and in this latter case it follows that there are absolutely non-computable processes in nature.

The above can likely be fully formalized, however the condition that F_P be knowably definable is far from obvious, and perhaps not even true. So that this modified Penrose disjunction does not seem as sharp as the modified Gödel disjunction above, given the state of the art. If some evidence for suitable definability of F_P appears then the situation changes.

Remark A.3. It should also be noted that for Penrose, in particular, "non-computability of intelligence" would be evidence for new physics, and he has specific and very intriguing proposals with Hameroff [9] on how this can take place in the human brain. As we have already indicated, new physics is not a logical necessity for non-computability of brain processes, at least given the state of the art. However, it is very plausible that new physical-mathematical ideas may be necessary to resolve the deep mystery of human consciousness. Here is also a partial list of some partially related work on mathematical models of brain activity, consciousness and or quantum collapse models: [12], [15], [7], [8].

A.0.4. Turing. Finally, let us return to Turing himself. He suggested in [2] that abandoning hope of consistency is the obvious way to circumvent the implications of Gödel incompleteness theorem for computability of intelligence. In view of the Theorem A.2 just above, it appears that this position is untenable. Humans may not be consistent, but it is implausible that the stabilization \mathcal{H} is not sound, since as we say human knowledge appears to converge on truth, and it is rather inconceivable that \mathcal{H} is not 1-consistent. Then we cannot escape incompleteness by the above. So if we insist on computability, then the only plausible way that the incompleteness theorems can be circumvented is to accept that there is an absolute limit on the power of human reason as in the theorem above.

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UNIVERSITY OF COLIMA, DEPARTMENT OF SCIENCES, CUICBAS $Email\ address:$ yasha.savelyev@gmail.com