

Cultural evolutionary dynamics with prestige bias

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Abstract

Copying role-models can be an efficient method for acquiring knowledge. A common bias when choosing a role-model to copy is success bias: copying whoever appears more successful. This bias depends on the performance of the role-model alone, with no other factors. We propose an additional bias that may be prevalent in cultural transmission: influence bias, in which role-model choice is affected by the number of individuals that have already copied each potential role-model. We combine success and influence bias together to a “prestige bias” and analyze its effects on cultural-evolutionary dynamics using mathematical analysis and stochastic simulations. We find analytic approximations to our stochastic model, facilitating further mathematical analysis and reducing the computational complexity of simulations. We validate these approximations using simulations, and demonstrate their robustness to model assumptions. We also find approximations to the fixation probability and the fixation time of an invading favored (by bias) cultural trait, in both constant and changing environments, which resemble Kimura’s approximations for population-genetic models. These approximations show that success bias effectively plays the part of natural selection, whereas influence bias effectively reduces the population size. Influence bias also accelerates the evolutionary dynamics, as can be expected in a *rich-getting-richer* process. Our model may provide a good description of cultural transmission, especially in human societies where social media is popular. Further work is needed to test if this model could predict various phenomena in cultural evolution when extended with the effects of selection and innovation.

Introduction

28 **Cultural transmission.** In cultural transmission, individuals transmit cultural traits (i.e., behavior, beliefs, norms) to one another, typically via learning and demonstrating (Cavalli-Sforza and Feldman, 30 1981). Examples for cultural traits in humans are behavioral patterns, such as personalities and habits, transmitted via both verbally and by observations (O'Brien et al., 2010). Although cultural 32 transmission is most common in humans, it is also observed in other animals such as chimpanzees (Horner et al., 2010; Kendal et al., 2015), dolphins and whales (Whitehead, 2017). In elephants, 34 McComb et al. (2001) showed that once a matriarch is removed from the group, the group's survival instincts are inferior and that "the possession of enhanced discriminatory abilities by the oldest 36 individual [matriarch] in a group can influence the social knowledge of the group as a whole." By playing audio recordings of African elephants, they showed that groups with a matriarch recognize 38 and react better to hostile or friendly calls than groups without a matriarch. Battesti et al. (2012) showed that choice of oviposition site in fruit flies is culturally transmitted: inexperienced flies that 40 spent some time with experienced flies chose the same type of oviposition site even without directly observing this behavior. How the information is transmitted is still an open question, but it has been 42 suggested that flies may use olfactory cues like other animals, such as rodents and bees.

Direction of transmission. Similar to genetic transmission, culturally transmitted traits can be trans- 44 mitted from parents to offspring, and their effects of can be physiological rather than behavioral. For example, parents can "teach" their children to be strong or tall, within some biological limits, by 46 instructing them to maintain a specific diet and engage in physical activity. Contrary to genetic transmission, cultural transmission can be non-vertical, that is, traits may be transmitted via social learning 48 from non-parental individuals, and even unrelated individuals such as teachers, leaders, media, or any stranger that interacts with the learning individual. Thus, cultural transmission may combine 50 vertical transmission, where parents transmit to their offspring; oblique transmission, where adults transmit traits to unrelated offspring; and horizontal transmission, where peers from the same age 52 cohort transmit to one another. Vertical transmission is also possible in the opposite direction: parents may copy traits from their offspring (Cavalli-Sforza and Feldman, 1981; Creanza et al., 2017).

54 **Transmission biases.** In social learning, transmission biases cause a trait to have a disproportionate probability to be transmitted compared to its frequency in the population. Although more common in 56 cultural transmission, transmission biases do occur in genetic transmission. For example, *wtf* genes in yeast bias their transmission to the gamete by secreting a long life-expectancy poison together with a 58 short life-expectancy antidote, so that a gamete without the gene will perish because the poison will outlive the antidote (Eickbush et al., 2019). Importantly, even when a trait is disfavored by natural 60 selection, it may still spread in a population due to transmission biases that are strong enough to overcome selection (Boyd and Richerson, 1988, Ch. 8 pg. 279). Cohen et al. (2021) show that 62 cooperative behavior can evolve in an individual due to horizontal transmission bias even when there is no benefit to it, or when it benefits its competitors.

64 **Success bias.** Rendell et al. (2010) have conducted a tournament between learning strategies. Each
strategy defines when individuals observe and copy from others, and when they engage in individual
66 learning, in which an individual learns a cultural trait on his own. The best strategies had a high
frequency of social learning relative to individual learning, even when the transmission error was
68 almost 50%. From these results we understand that all the winning strategies were mostly based on
success biased social learning, meaning it contributed more to the general success of the population
70 than individual learning. However, all winning strategies included individual learning to some degree,
implying that success-biased learning alone isn't the best way to advance, even when success is
72 measured accurately.

Evaluating success. Boyd and Richerson (1988, Ch. 5) suggest that the evaluation of success can
74 be divided into three groups: *direct bias*, *indirect bias* and *frequency-dependent bias*. A direct bias
occurs when a variation of a trait is more attractive than others, and is evaluated by *directly* testing the
76 variation of the trait. For example, an individual observing a Ping-Pong match can attempt both of the
observed paddle grips to determine which grip is better. An indirect bias occurs when an individual
78 uses the value of one trait to determine the attractiveness of another, so it *indirectly* evaluates the
attractiveness of the role-model. For example, an observer may copy the paddle grip of the Ping-Pong
80 player who scored more points in the match, thus indirectly evaluating the grip by the points scored. A
frequency-dependent bias occurs when an individual has a probability to copy a variant of the trait that
82 higher or lower than trait's frequency among demonstrators. For example, when an individual is 80%
likely to copy the common paddle grip even when only 60% of the population is using it, it is said to be
84 frequency-biased, or in this case, conformist. Frequency bias could be negative, i.e., non-conformist
bias. Conformity and non-conformity are well-known biases in cultural transmission (Molleman et al.,
86 2013), and its effect on cultural evolution have been studied with both models (Denton et al., 2022,
2020) and experiments (Aljadeff et al., 2020).

88 **Prestige.** Prestige means having a good reputation or high esteem, therefore does not directly signify
success (although it may imply it), making it an indirect bias. Both Boyd and Richerson (1988, Ch.
90 8) and Fogarty et al. (2017) suggest that prestige biases are probably more common in humans than
success biases. Boyd and Richerson (1988, Ch. 8) add that maladaptive traits may spread widely
92 in a population if indirect biases are strong enough. They suggest that such biases could lead to a
runaway process caused by a cultural equivalent of sexual selection (Andersson, 1994). On the other
94 hand, Henrich and Broesch (2011) suggest that prestige biases, over generations, can lead to cultural
adaptations, and that although prestige can lead to maladaptive traits spreading in the population, it
96 can also accelerate the spread of adaptive traits. Prestige is often mentioned in the cultural-evolution
literature, but seldom modeled.

98 **Influence bias.** Today, social media provides an easy way to estimate the social and cultural influence
individuals have over others, and therefore may have an effect on decision making. Online social
100 networks such as *Facebook* or *Instagram* are known to affect the influence of individuals (Anagnos-
topoulos et al., 2008; Peng et al., 2018; Diga and Kelleher, 2009), and specific marketing practices

102 were invented to capitalize on this effect (Lee et al., 2012). Here, we model such influence as an
indirect bias in cultural transmission, in which the choice of a role-model depends on the choices
104 made by other individuals that have already chosen a role-model. In addition to using influence bias as
an easy way to approximate role-models worth, it can also be a used to approximate it better than the
106 copier’s own estimation. This bias can save the copier costs: time, effort etc, and it can also improve
its choice of role-model.

108 This bias depends on the state of a role-model rather than on its trait, in contrast to frequency biases
such as conformity (Denton et al., 2022), which depend on the frequency of a trait in the population
110 or in a sample of role-models. We define a model of cultural transmission with prestige bias that
combines both success and influence biases, provide analytic approximations for this model, and
112 analyze its dynamics.

Models

114 We begin with a continuous trait model with indirect bias suggested by Boyd and Richerson (1988),
develop an extension with influence bias, and then develop a model with a dichotomous trait. We
116 implemented our stochastic models and approximations, performed statistical analyses, and produced
figures using Python (Van Rossum et al., 2007) with NumPy (Van Der Walt et al., 2011) and Matplotlib
118 (Hunter, 2007). Source code is available at <https://github.com/yoavram-lab/PrestigeBias>.

Continuous trait

120 We follow the model of Boyd and Richerson (1988), assuming only oblique transmission of the trait
and omitting the indirect trait in order to reduce model complexity. We consider a population of N
122 individuals, described by a single trait with a continuous value. Each generation, N naive individuals,
or copiers, choose an individual from the previous generation, or role-models, from which they will
124 copy their trait. Similar to a Wright-Fisher model, we assume non-overlapping generations such that
the entire population is replaced in each generation. The population at time t can be described by
126 $\mathbf{A}(t) = (A_1(t), \dots, A_N(t))$ where $A_i(t)$ is trait value of individual i at time t . We assume the initial
population is drawn from a standard normal distribution, $\mathbf{A}(0) \sim N(0, 1)$. Cultural transmission is
128 modeled by a function F such that

$$A_i(t + 1) = F_i(\mathbf{A}(t)) . \quad (1)$$

130 **Success bias.** Boyd and Richerson (1988, Ch. 8, p. 247-249) describe a blended transmission algo-
rithm by defining F as a weighted average of the traits of all role-models,

$$F_i(\mathbf{A}) = \sum_{j=1}^N G_{i,j} \cdot A_{i,j} , \quad (2)$$

where $G_{i,j}$ is the success bias of role-model j in the eyes of copier i ,

$$G_{i,j} = \frac{\beta(A_{i,j})}{\sum_{k=1}^N \beta(A_{i,k})}, \quad (3)$$

$A_{i,j}$ is the absolute trait value copier i estimates for role-model j with some error $e_i \sim N(0, \eta^2)$,

$$A_{i,j} = A_j + e_i, \quad (4)$$

and $\beta(\cdot)$ is the bias function that quantifies the success bias of a role-model,

$$\beta(A_{i,j}) = b \cdot \exp\left(-\frac{(A_{i,j} - \hat{A})^2}{2J}\right), \quad (5)$$

with \hat{A} as the arbitrary optimal trait value, and J and b as parameters that control the bias strength.

Therefore, $G_{i,j}$ is a relative success score that copier i assigns to role-model j , equivalent to relative fitness in evolutionary-genetic transmission models.

Boyd and Richerson (1988) note that the deterministic blended transmission algorithm they use has alternatives. We thus develop a similar stochastic model with transmission from a single random role-model. Instead of eq. (2), we define the transmission function F as a random variable with its distribution given by

$$\Pr(F_i(\mathbf{A}) = A_j) = G_{i,j}, \quad (6)$$

such that $G_{i,j}$ gives the probability of copier i to choose to copy the trait of role-model j .

Influence bias. Here we introduce a new element to the model. We assume that in each generation, copiers choose their role-models one by one. We denote $K_{i,j}$ as the number of copiers that chose role-model j after copier i chose a role-model. Thus, i out of N copiers already chose a role-model, $\sum_{j=1}^N K_{i,j} = i$, and there are $N - i$ copiers that have yet to choose a role-model. The stochastic process of role-model choice,

$$\{\mathbf{K}_i = (K_{i,1}, \dots, K_{i,N})\}_{i=1}^N, \quad (7)$$

is described by the recurrence equation

$$K_{i,j} = K_{i-1,j} + S_{i,j}, \quad i, j = 1, 2, \dots, N, \quad (8)$$

where $S_{i,j} = 1$ if the i -th copier chose role-model j and 0 otherwise, and the initial state is $K_{0,j} = 0$.

Following eq. (6), the probability that the i -th copier chose role-model j is given by the prestige of role-model j in the eyes of copier i ,

$$\Pr(S_{i,j} = 1 \mid S_{1,j}, S_{2,j}, \dots, S_{i-1,j}) = G_{i,j}. \quad (9)$$

The prestige $G_{i,j}$ of role-model j in the eyes of copier i is determined by the estimated biased trait value $\beta(A_{i,j})$ and the number of copiers that chose role-model j before copier i , $K_{i-1,j}$, replacing eq. (3) of Boyd and Richerson (1988) with

$$G_{i,j} = \frac{\alpha_{ij} \cdot \beta(A_{i,j}) + (1 - \alpha_{ij}) \cdot K_{i-1,j}}{W_i} . \quad (10)$$

Here, the bias weight α_{ij} is a characteristic of the interaction of role-model j with copier i , that determines the relative significance of success and influence within the role-model's overall prestige, in the eyes of the copier. The trait of role-model j estimated by copier i , $A_{i,j}$, remains as in eq. (4), and W_i is a normalizing factor that sums the numerator over all role-models ($1 \leq j \leq N$) to ensure $\sum_{j=1}^N G_{i,j} = 1$.

Dichotomous trait

To allow for mathematical analysis of the model, we introduce a simplified version where the trait only has two phenotypes: the optimal phenotype \hat{A} and the sub-optimal phenotype A . All role-models with the same phenotype will contribute to the probability of that phenotype to be transmitted, and thus influence is determined by the number of copiers that have already chosen a role-model with either phenotype. In addition, we assume homogeneous α for simplicity and for easier mathematical analysis. Therefore, the probability of the i -th copier to copy phenotype A is

$$G_{i,A} = \frac{(N - X)\alpha'\beta(A) + K_{i,A}}{i - 1 + (N - X)\alpha'\beta(A) + X\alpha'\beta(\hat{A})} = \frac{(N - X)\alpha'\beta(A) + K_{i,A}}{i - 1 + (N - X)\alpha'\beta(A) + \alpha'X} \quad (11)$$

where X is the number of role-models with trait \hat{A} and $K_{i,A}$ is the number of copiers that already chose A when copier i chooses a role-model and α' is the odd ratio of the bias weight $\alpha' = \frac{\alpha}{1-\alpha}$.

We prove this equation later, based on the proof of the Dirichlet-Multinomial approximation.

Initially, we assume the population has a single individual with phenotype \hat{A} and $N - 1$ individuals with phenotype A . The rest of the details follow the continuous trait model.

Results

Our model is defined by two nested stochastic processes. Change over multiple generations is described by the phenotype distribution at each generation, $\{\mathbf{A}(t)\}_t$. The transition from one generation to the next is described by the number of copiers each role-model has after i copiers have chosen a role-model, $\{\mathbf{K}_i\}_{i=1}^N$. We emphasize that the models are nested: $\mathbf{A}(t + 1)$ can be computed from $\mathbf{A}(t)$ by evaluating \mathbf{K}_N . However, the former requires iterating over eqs. (8) and (9).

Thus, we sought to find an equivalent stochastic process that has the same joint distribution as \mathbf{K}_N . We found two such approximations, summarized here and explained in detail below. In both we assume

either α_j is a trait of role-model j only (contrary to α_{ij} that included the relation with copier i), or a completely homogeneous α .

Generalized binomial approximation. The number of copiers of a specific role-model at each step, $K_{i,j}$, follows the *generalized binomial distribution* (Drezner and Farnum, 1993) and therefore, (i) the expected number of copiers of role-model j equals its prestige in the eyes of the first copier, multiplied by the total number of copiers, that is, $E[K_{N,j}] = N \cdot G_{1,j}$ if trait estimation error is uniform for all copiers ($e = e_i$ for $i = 1, \dots, N$); and (ii) the expected number of copiers of each role-model equals its relative biased trait value, similar to the role of relative fitness in population-genetic models, that is, $E[K_{N,j}] = \beta(A_j + e)/\bar{\beta}$ if the bias weight is uniform for all role-models ($\alpha = \alpha_j$ for $j = 1, \dots, N$), where $\bar{\beta} = 1/N \sum_{j=1}^N \beta(A_j + e)$ is the population mean estimated trait value.

Dirichlet-Multinomial approximation. The role-model choice process, $\{\mathbf{K}_i\}_{i=1}^N$, is equivalent to a *Pólya urn* model if trait estimation error is uniform for all copiers ($e = e_i$ for all $i = 1, \dots, N$), meaning there's no meaning for the order of copiers. Therefore, the number of copiers of all role-models, $\mathbf{K}_i = (K_{i,1}, \dots, K_{i,N})$, follows a Dirichlet-Multinomial distribution, $\mathbf{K}_i \sim DM(N, \mathbf{G}_1)$, where $\mathbf{G}_1 = (G_{1,1}, \dots, G_{1,N})$ is the prestige vector of all role-models in the "eyes" of the first copier. Note that here $G_{i,j}$ is only a function of the trait values A_j and the bias weights α_j , as the estimation error is uniform, meaning all copiers are identical.

Generalized binomial approximation

The generalized binomial distribution (GBD) emerges from a series of dependent Bernoulli trials (in contrast to the standard binomial distribution in which trials are independent) and is parameterized by $GBD(n, p, \theta)$ where n is the number of trials, p is the probability of success of the first trial, and θ is the correlation between trials ($\theta = 0$ gives the standard binomial distribution).

Result 1 (Generalized binomial approximation). *The number of copiers of role-model j after i copiers have chosen a role-model follows the GBD, $K_{i,j} \sim GBD(i, \alpha_j \cdot \beta(A_j + e))$ if $e_i = e$ for all role-models $i = 1, \dots, N$.*

Proof. We denote $Q_j(k, i) = P(K_{i,j} = k \mid K_{i-1,j})$ as the probability that exactly k out of i copiers choose role-model j given $K_{i-1,j}$ our of $i - 1$ copiers chose role-model j . Using conditional probability and eq. (8),

$$Q_j(k, i) = P_j(S_{i,j} = 1 \mid k - 1, i - 1) \cdot Q_j(k - 1, i - 1) + P_j(S_{i,j} = 0 \mid k, i - 1) \cdot Q_j(k, i - 1), \quad (12)$$

where $S_{i,j} = 1$ when the i -th copier chooses role-model j . Equation (12) is equivalent to eq. (2.1) by Drezner and Farnum (1993), which completes the proof.

This result gives the following two corollaries on the expected number of followers of a given role-model by the end of the role-model choice process. The proof of corollary 2 is in Appendix A.

Corollary 1. $E[K_{N,j}] = N \cdot G_{1,j}$.

Proof. Drezner and Farnum (1993, eq. (2.3)) show that $E[k] = N \cdot Q_j(1, 1)$ (modified from their notation). $Q_j(1, 1)$ is the initial probability to choose role-model j , before any role-model choices are made. $Q_j(1, 1) = G_{1,j}$ by definition, which completes the proof.

Corollary 2. $E[K_{Nj}] = \alpha_j \cdot \beta(A_j + e) / \overline{\alpha \cdot \beta(A + e)}$, where the averaging in the denominator is over the role-models index, j .

The special case where the bias weight is uniform for all role-models ($\alpha = \alpha_j$ for $j = 1, \dots, N$) is interesting, because we can evaluate the expected number of copiers using a linear equation

$$E[K_{Nj}] = N \cdot \frac{\alpha \cdot \beta(A_j + e)}{\sum_{m=1}^N \alpha \cdot \beta(A_m + e)} = \beta(A_j + e) / \overline{\beta(A + e)}, \quad (13)$$

where the only variable is $A_j + e$, because $\overline{\beta(A + e)}$ is the mean of the distribution we draw the trait values from, modified by some constant parameters of β . We can then denote $L = 1 / \overline{\beta(A + e)}$ and write

$$E[K_{Nj}] = L \cdot \beta(A_j + e). \quad (14)$$

Numerical validation. To validate our results we ran 1,000 simulations of the full model, and compared the results with corollary 2. We compare the distribution of number of copiers by plotting the histograms of both our simulations results and the expected values based on corollary 2. We used the average of the 1,000 simulations to eliminate drift errors, as can be seen in fig. 1.

Although basic, fig. 1 shows good fit of the GB approximation. This validation is initial, and the more extensive validations we do on the Dirichlet-Multinomial approximation, because it is what we will use in our analysts.

Dirichlet-Multinomial distribution approximation

Pólya urn model. This stochastic process consists of N draws from an urn with an initial amount of colored balls of M colors. When a ball is drawn, it is then placed back in the urn together with an additional new ball of the same color. Let $\mathbf{U}_i = \{u_{i,1}, u_{i,2}, \dots, u_{i,M}\}$ where $u_{i,j}$ is the number of balls of the j -th color in the urn after i draws. Let $S_{i,j} = 1$ when drawing a j -colored ball on the i -th draw, and 0 otherwise. The probability that $S_{i,j} = 1$ given \mathbf{U}_{i-1} is

$$P(S_{i,j} = 1 \mid \mathbf{U}_{i-1}) = \frac{u_{i-1,j}}{\sum_{m=1}^M u_{i-1,m}} = \frac{o_j + w_{i-1,j}}{\sum_{m=1}^M o_m + w_{i-1,m}} = \frac{o_j + w_{i-1,j}}{i - 1 + \sum_{m=1}^M o_m}, \quad (15)$$

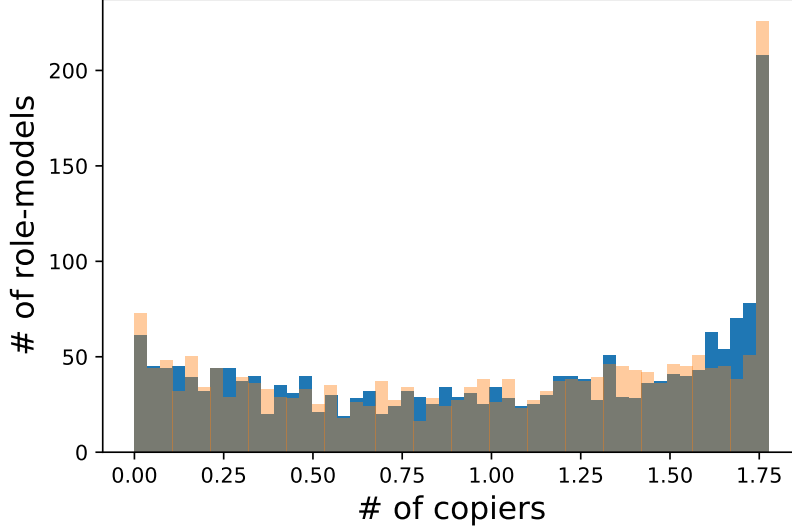


Figure 1: Numerical validation of the GB approximation. The approximation (orange) fits simulation results (blue) well when using 1,000 simulations for both models. Here, population size, $N = 2,000$; bias weight, $\alpha = 0.1$; idea phenotype value, $\hat{A} = 1$; role-model traits $\mathbf{A} \sim N(0, 1)$; success bias value, $\beta(A) = 0.956$.

where o_j is the initial number of balls of the color j in the urn, and $w_{i,j}$ is the cumulative number of new balls that were added to the urn after i draws of the color j .

Result 2 (Pólya urn model). *The role-model choice process, $\{\mathbf{K}_i\}_{i=1}^N$, is equivalent to a Pólya urn model if both trait estimation error and bias weight are uniform in the population, $e = e_j$ and $\alpha = \alpha_j$ for all $j = 1, \dots, N$.*

Proof. Denote $\alpha' = \frac{\alpha}{1-\alpha}$ as the bias weight ratio, and $A'_j = A_j + e$. From eq. (10) and because $\sum_{j=1}^N K_{i,j} = i$, we have

$$G_{i,j} = \frac{\alpha' \beta(A'_j) + K_{i-1,j}}{\sum_{m=1}^N \alpha' \beta(A'_m) + K_{i-1,m}} = \frac{\alpha' \beta(A'_j) + K_{i-1,j}}{i - 1 + \sum_{m=1}^N \alpha' \beta(A'_m)}. \quad (16)$$

Substituting $M = N$, $o_j = \alpha' \beta(A'_j)$, and $w_{i,j} = K_{i,j}$ in eq. (15) gives eq. (16), thus completing the proof.

Frigyik et al. (2010, section 2) prove that the proportion of different colored balls in a Pólya urn model converges to the Dirichlet distribution as the number of draws approaches infinity, based on the *Martingale Convergence Theorem* (Durrett, 1999). We therefore have an approximation for the relative prestige each role-model has when evaluated by copiers. Thus, choosing the role-models for all copiers is equivalent to drawing from a Multinomial distribution where the parameters are the modified weights from a Dirichlet distribution and we have the following corollary.

Corollary 3. *The number of copiers of each role-model follows a Dirichlet-Multinomial distribution, $\mathbf{K}_i \sim DM(N, \mathbf{G}_1)$, under the conditions of Result 2.*

Numerical validation. To validate our analytical result (corollary 3) and test its sensitivity to the assumptions ($e_i = e$ and $\alpha_i = \alpha$ for $i = 1, \dots, N$) we compare it to results of stochastic simulations of the full model. First, we computed an observed distribution of the number of copiers from the average empirical distribution of multiple simulations. We then compared this observed distribution with the expected theoretical DM distribution as can be seen in fig. 2 (a). The difference in distributions was not perceived when plotting both distributions on the same figure, so we used the difference instead. The maximum difference is 0.5 role-models, which indicate a very good fit. In addition, we tested the likelihood of the observed data to be drawn from the DM distribution, against a shuffle of the parameters vector of the DM distribution itself, as seen in fig. 2 (b). We see that the negative log likelihood of the observed data is much higher than any other shuffled version of the parameters vector, supporting our approximation more.

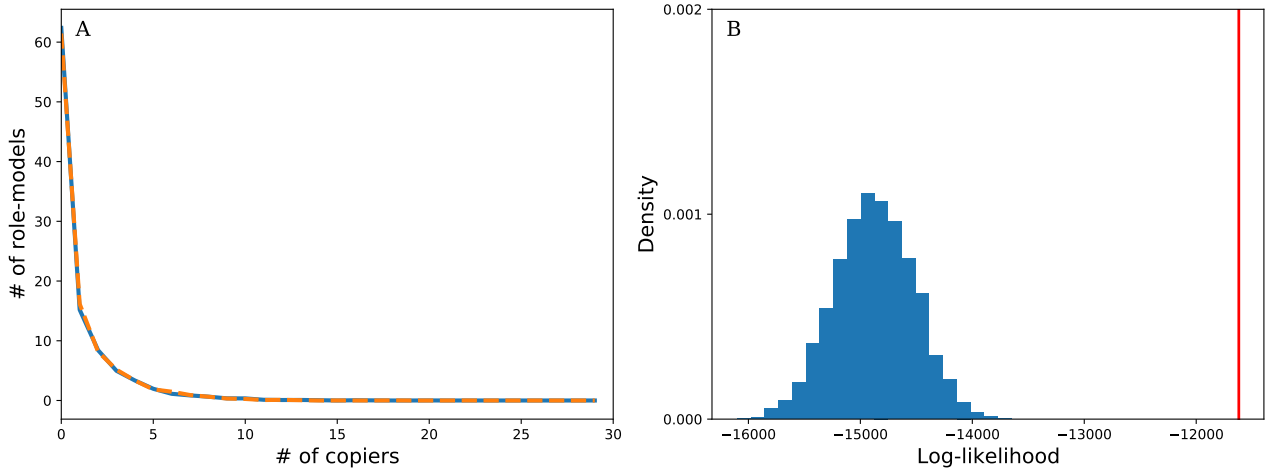


Figure 2: Numerical validation of the DM approximation. We performed computational "experiments" of the role-model choice process and compared them to the DM distribution. **(A)** The difference between the DM distribution (orange) and the empirical distribution of the experiments (blue) is very small. **(B)** The log-likelihood of the DM distribution for results of the experiments (red vertical line) is much higher compared to the log-likelihood of permutations of experiments (blue histogram). Here, population size, $N = 100$; number of experiments, $m = 100$; phenotype values, $\hat{A} = 1$, $A \sim N(0, 1)$; success-bias weight, $\alpha = 0.5$.

Next, we examined the fixation probability and fixation time of a favored phenotype \hat{A} when invading a population of phenotype A and compared results from the full model and the DM approximation. We find that the number of simulations needed to sufficiently approximate our model with the DM approximation is roughly 1,000 (Figure 3). Next, we examined the robustness of the DM approximation to relaxing the approximation assumptions. First, we relaxed our assumption of no estimation error e . Estimation error in the original model was drawn from a normal distribution, and added to the trait value before evaluation of the bias ($A_{ij} = A_j + e_i$). When estimation error is applied, we sample J_i for each copier i from a normal distribution with varying scale (variance). Even when the standard deviation is 0.1, the fixation probability and time is similar (fig. 4). We also relaxed our assumption of a uniform bias weight α (i.e., $\alpha_i = \alpha$). We allowed α to vary in the population, drawing α_j for each

294 role-model j from a normal distribution such that $\alpha_j \sim N(0.5, x)$ where $x \in [10^{-7}, 10^{-1}]$. We found
 again that results of the DM approximation are similar to those from stochastic simulations of the full
 296 model (fig. 5).

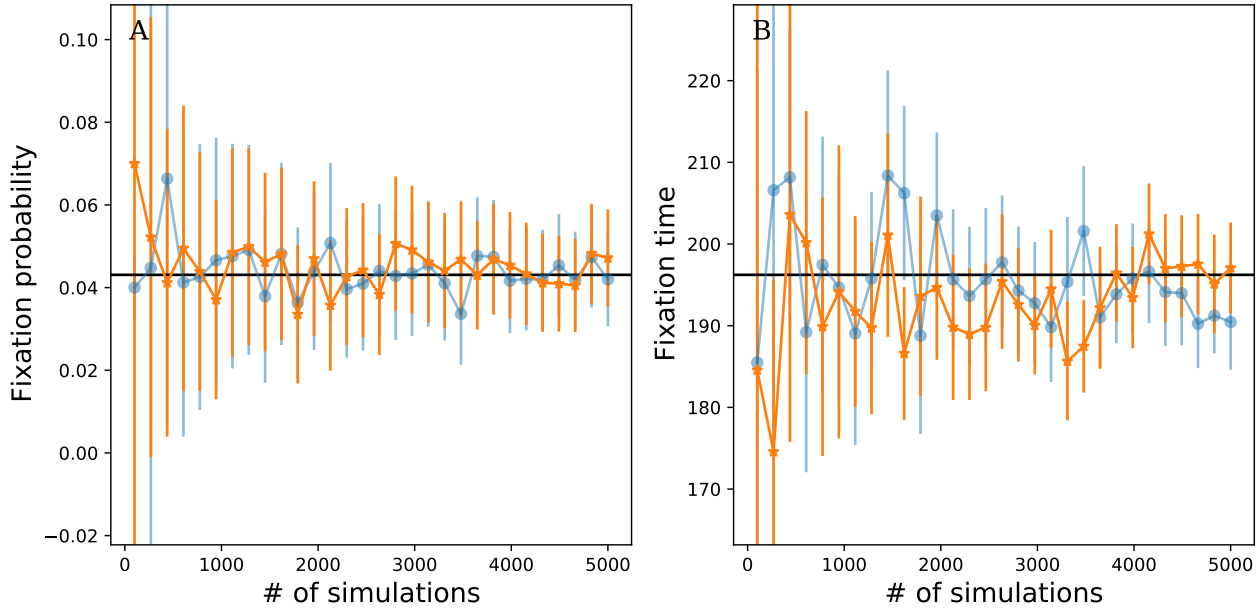


Figure 3: DM Approximation precision as function of number of simulations. Our DM approximation (orange) agrees with stochastic simulation results (blue) when using 1,000 or more simulations. Both fluctuate around the analytic fixation probability approximation (black; eq. (19)). Markers are averages across simulations, error bars are 95% confidence intervals. Here, population size, $N = 1000$; success-bias weight, $\alpha = 0.5$; phenotype values, $\hat{A} = 1$, $A = 0.7$; success-bias value, $\beta(A) = 0.956$.

Fixation probability and time

298 After finding that the DM distribution is a good approximation of the (within-generation) role-model
 choice process, we turn our attention to the (between-generation) evolutionary dynamics. We focus
 300 on the fixation probability and fixation time of a favored phenotype, using a diffusion-equation
 approximation approach, similar to analyses of population-genetic models (Kimura, 1962; Kimura
 302 and Ohta, 1969; Otto and Whitlock, 2006). We are mainly interested in the effect of the bias weight,
 α , which determines the relative effect of success and influence on prestige bias, given by eq. (10).
 304 For simplicity, we do not include role-model estimation error in this analysis, i.e $e_i = 0$ for every
 copier i . As shown above, transmission in our model is approximately DM distributed (corollary 3
 306 and eq. (16)).

We start by finding the expectation and variance of the change in frequency from one generation to the
 308 next, which are the drift and diffusion terms of the diffusion equation. The proof is in Appendix B.

310 **Result 3** (Drift and diffusion terms in a constant environment). *Let x and x' be the frequency of type \hat{A}
 in a population with N individuals in the current and next generation, and β is the success coefficient*

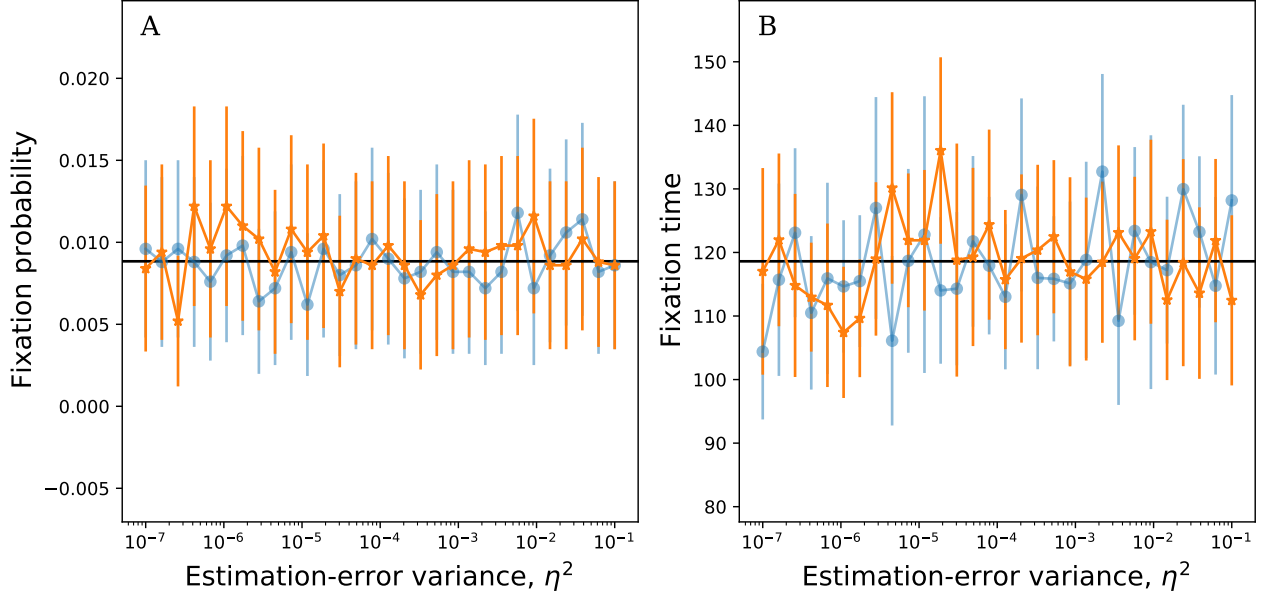


Figure 4: Robustness of DM approximations to success estimation error. Both the DM approximation (orange) and our approximation (black) agree with the stochastic simulations (blue), even with a high estimation error. Markers are averages across simulations, error bars are 95% confidence intervals. 5,000 simulations per data point; population size, $N = 1000$; success-bias weight, $\alpha = 0.1$; phenotype values, $\hat{A} = 1, A = 0.7$; bias strength parameter $J \sim N(1, \eta^2)$ where $\eta \in [10^{-7}, 10^{-1}]$.

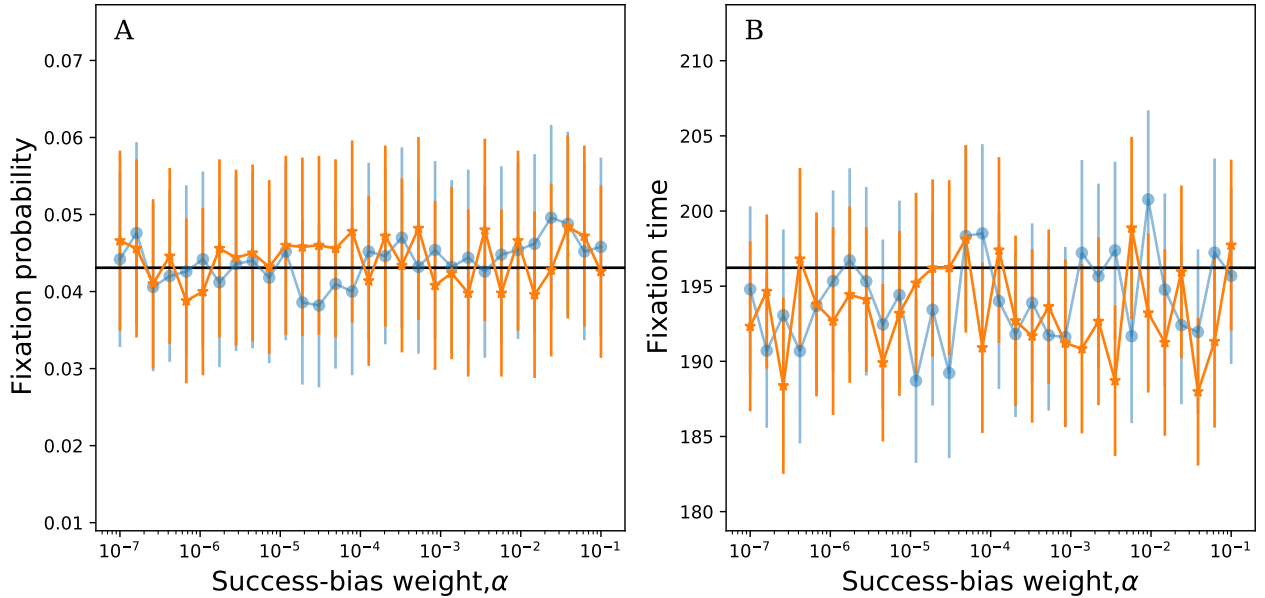


Figure 5: Robustness of DM approximations to variation in the bias weight α . Both the DM approximation (orange) and Kimura's equation (black line) fit the stochastic simulations (blue) well even with a high variation in success bias weight. Markers for average across 5,000 simulations, error bars are 95% confidence intervals. Here, population size, $N = 1000$; success bias weight normally distributed, $\alpha \sim N(0.5, x^2)$; phenotype values $\hat{A} = 1, A = 0.7$; success bias value, $\beta(A) = 0.956$.

312 of phenotype A , $\beta = \beta(A) < \beta(\hat{A}) = 1$. Then,

$$E[x' - x] \approx x(1 - x)(1 - \beta), \quad V(x' - x) \approx x(1 - x) \left(\frac{1}{\alpha N + (1 - \alpha)} \right). \quad (17)$$

314 This analysis gives a surprising result relating the parameters α and β to parameters of the classical
 Wright-Fisher model from population genetics: the selection coefficient s , a measure of the effect of
 316 natural selection on the change in frequency of genotypes, and the effective population size, N_e , a
 measure of the effect of random genetic drift on the change in frequency of genotypes. In a diffusion-
 318 equation approximation of the classical Wright-Fisher model, the expectation and variance of the
 change in frequency are $E[x' - x] = x + x(1 - x)s + o(s)$ and $V[x' - x] = x(1 - x)/N_e$ (Kimura, 1962,
 320 eq. 7). Therefore, we have the following result.

322 **Result 4** (Effective selection coefficient and population size). *The effective selection coefficient s and
 effective population size N_e can be written in terms of the success coefficient β (eq. (5)), the bias
 324 weight α (eq. (10)), and the population size N as*

$$s = 1 - \beta(A), \quad N_e = \alpha N + (1 - \alpha). \quad (18)$$

326 Using our effective selection coefficient, $1 - \beta$, and effective population size, N_e , with the population-
 genetics fixation probability approximation given by Kimura (1962, eq. 8), we get the following result.

328

Result 5 (Fixation probability). *The fixation probability is approximately*

$$\pi = \frac{1 - e^{-2(1-\beta)N_e x}}{1 - e^{-2(1-\beta)N_e}} \quad (19)$$

where x is the initial frequency of the favored phenotype \hat{A} .

332 Similarly, we can use $1 - \beta$ and N_e in the population-genetics fixation time approximation given by
 Kimura and Ohta (1969, eq. 17).

334

Result 6 (Fixation time).

$$T = J_1 + \frac{1 - u(x)}{u(x)} \cdot J_2, \quad (20)$$

336 where, given $S = N_e(1 - \beta)$ and $x = \frac{1}{N_e}$,

$$u(x) = \frac{1 - e^{-2Sx}}{1 - e^{-2S}} \quad (21)$$

338 and,

$$J_1 = \frac{2}{(1 - \beta)(1 - e^{-2S})} \int_x^1 \frac{(e^{2S\xi} - 1)(e^{-2S\xi} - e^{-2S})}{\xi(1 - \xi)} d\xi, \quad (22)$$

340

$$J_2 = \frac{2}{(1-\beta)(1-e^{-2S})} \int_0^P \frac{(e^{2S\xi} - 1)(1 - e^{-2S\xi})}{\xi(1-\xi)} d\xi \quad (23)$$

342

$$T = \frac{1-\pi}{1-\beta} \int_0^x \frac{e^{2(1-\beta)\xi} - 1}{\xi(1-\xi)} d\xi + \frac{\pi}{1-\beta} \int_x^1 \frac{1 - e^{-2(1-\beta)(1-\xi)}}{\xi(1-\xi)} d\xi \quad (24)$$

Note that these integrals cannot be solved in closed form, so we can only estimate them numerically.

Numerical validation. We compare our approximations (eqs. (19) and (24)) with results of simulations of our dichotomous model using various α and β values, as well as simulations of the Wright-Fisher model, using the effective selection coefficient, $s_e = 1 - \beta$, and effective population size, $N_e = \alpha N + (1 - \alpha)$. We find see that the two models have similar dynamics, and both are well approximated our approximations (Figure 6).

Changing environment . After finding a good approximation in constant environment, where the favorable trait is always \hat{A} , we proceeded to find an approximation for a changing environment. Following Ram et al. (2018), we find the following expressions for the expectation and variance of the change in frequency between t generations. The proof is in Appendix C.

354

Result 7 (Drift and diffusion terms in a changing environment). *Let x be the initial frequency of the invading phenotype and X_t is the number of individuals with the phenotype at time t . Then,*

$$E[X_t/N - x] \simeq x(1-x)S_t/N_e, \quad \text{and} \quad V(X_t/N - x) \simeq tx(1-x)/N_e, \quad (25)$$

where $S_t = \sum_{i=1}^t N(1 - \beta_i)$.

Using the drift and diffusion terms and following Ram et al. (2018), we can approximate the fixation probability in a changing environment using

360

$$\tilde{\pi} = \frac{1 - e^{-2\frac{S_n}{n}N_ex}}{1 - e^{-2\frac{S_n}{n}N_e}} \quad (26)$$

where $\frac{S_n}{n} = \frac{k-l}{k+l}(1 - \beta)$ and $n = k + l$. That is, we use the average selection coefficient during a cycle of $k + l$ generations as the selection coefficient eq. (19).

Numerical validation. Comparing our approximation, eq. (26) to numerical simulations, we find that the approximation fits simulations results well for variable bias weights, α , which corresponds to the effective population size (Figure 7A).

However, the approximation is more sensitive to the value of the success bias coefficient β (Figure 7B). We suspect that when β is too small, there will not be many cycles in the simulations, because either the population reaches a high frequency of the fitter phenotype after just a few cycles, or the fitter

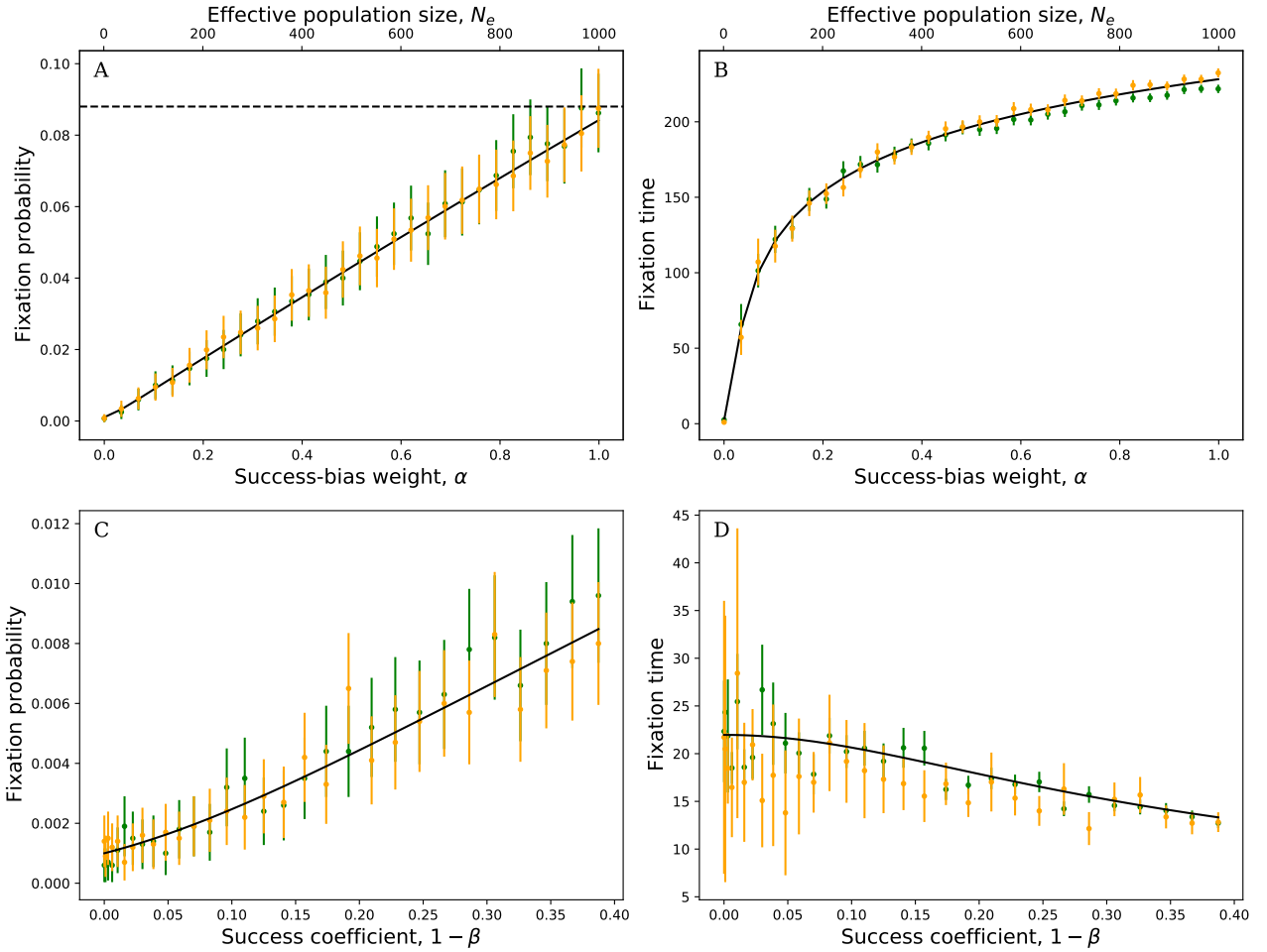


Figure 6: Fixation probability and time in a constant environment. Fixation probability and time (in generations) as a function of the success-bias weight α (bottom x-axis), or effective population size N_e (top x-axis) in the top row, and as a function of the success coefficient, $1 - \beta$, on the bottom row. The approximation (black; eq. (19)) agrees with both DM simulations (green) and Wright-Fisher simulation (orange). Fixation probability (A) is bounded by $2s_e = 2(1 - \beta)$ (blue). Markers are averages of 10,000 simulations, error bars show 95% confidence intervals for panels A and B and 75% for panels C and D. Here, Population size, $N = 1,000$; phenotype values, $\hat{A} = 1$, $A = 0.7$ (A and B), $A = a \cdot \hat{A}$ with $0.01 \leq a \leq 0.99$ (panels C and D); success coefficient, $1 - \beta = s = 0.044$ (A and B); success-bias weight, $\alpha = 0.01$ (panels C and D).

phenotype becomes extinct very quickly. For the β values (0.65 and below), the fixation probability exceeds even the constant environment approximation (which is the upper limit). However, this is to be expected, because the diffusion-equation approximations assume weak selection (i.e., low selection coefficient s).

When k is the number of generations where the invading phenotype is favored, and l when the original trait is, we found that for large k -to- l ratio (while keeping constant total cycle length, $n = k + l = 100$), the changing environment approximation, eq. (26) converges to the constant environment approximation, eq. (19), see Figure 7C and Figure 7D.

Result 8. *The effective population size doesn't affect the goodness of fit of the approximation. The success coefficient however, must be even lower than before for the approximation to fit.*

380 The proof is seen in Figure 7A,B. The approximation follows the trend of the simulation results
for all α values. When increasing the success coefficient to more than 0.15, the simulation results
382 were located above the changing environment approximation, and below the constant environment
approximation. We believe the reason is the structure of the cycle. Our proof and approximation in
384 the changing environment are for a large amount of cycles, and when the success coefficient is too
high, there might be very few cycles. Either the ideal trait is copied by enough copiers so that the
386 influence is sufficient to negate the success bias when the cycle changes (and the trait favored by the
bias becomes the disfavored), or the opposite happens, and the ideal trait gets extinct before there were
388 enough copiers that copied it. We then tried to change the ratio between the number of cycles where
 \hat{A} is favored and disfavored. We showed that the approximation fits well regardless of the ratio, but
390 when the ratio of favored generations to disfavored ones is very high, it is very similar to a constant
environment model.

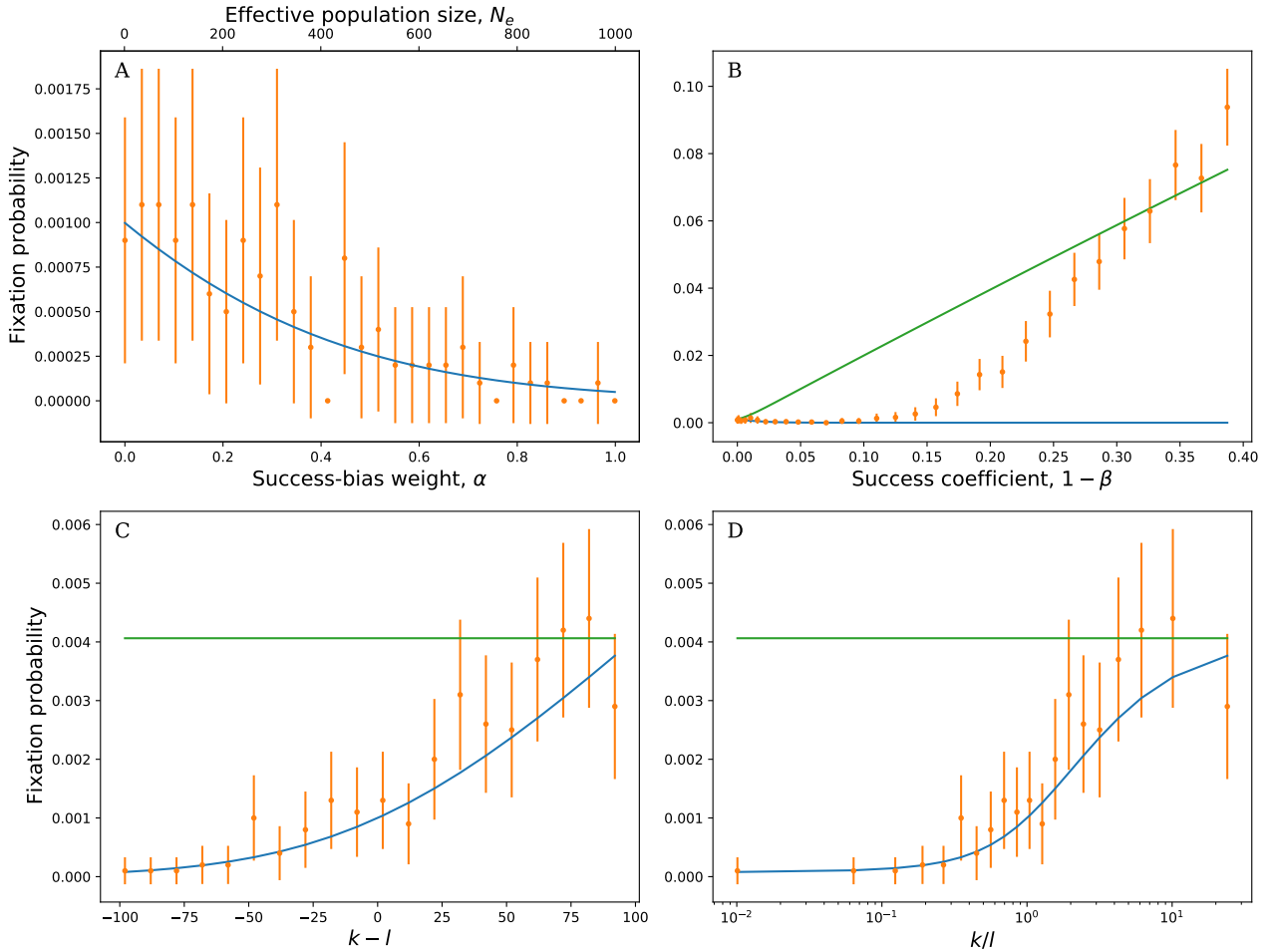


Figure 7: Fixation probability in a changing environment. (A) Fixation probability decreases with the the success-bias weight (bottom x-axis) and effective population size (top x-axis). The approximation (blue; eq. (26)) agrees with simulation results (orange). (B) Fixation probability increases with the success coefficient, β . When success bias is large ($1 - \beta > 0.1$), simulation results (orange) are underestimated by the changing environment approximation (blue; eq. (26)). With even larger success bias ($1 - \beta > 0.35$), even the constant environment approximation (green; eq. (19)) slightly underestimates simulation results, likely because the diffusion equation approximation assumes weak "selection". (C,D) The approximation (blue) is robust to changes in environmental cycle length, as it agrees with simulations (orange) for different sizes of the changing environment cycle, where k and l are the number of generations each trait value is under success bias. When $k > l$, the approximation and the simulations are both very close to the constant environment approximation (green), because the more generations the rare phenotype is favored, the more similar it is to the constant environment model, where it is always favored by the success bias. Markers show average of 10,000 simulations, error bars show 75% (A, C, and D) and 95% (B) confidence intervals. Here, population size, $N = 1,000$; phenotype values, $\hat{A} = 1$, $A = 0.9$ (A and B), $A = 0.8$ (C and D); In (A), the success coefficient is: $1 - \beta = s = 0.005$; In (B, C, and D) the success-bias weight is $\alpha = 0.1$.

392 Adaptive success-bias weight

We ran simulations of the role-model choice process during a single generation in which every
 394 copier evaluates its own optimal success-bias weight, α^* , which minimizes the expected squared error

between the estimated and the ideal trait values,

$$\alpha^* = \underset{j}{\operatorname{argmin}} \sum_{j=1}^N \frac{\alpha A_j + (1 - \alpha) K_j}{\sum_{l=1}^N \alpha A_l + (1 - \alpha) K_l} \cdot (\hat{A} - A_j)^2, \quad (27)$$

where A_j is the trait of role-model j and K_j the number of copiers that already chose role-model j .

We find that when copiers adapt their success-bias weight, it decreases with the number of copiers that have already chosen a role-model (Figure 8). Moreover, their estimation error is much lower compared to a constant success-bias weight, which gives roughly the same high estimation error to all copiers (compare Figure 8B and C): in this example, the adaptive weight estimation error converges to 0.046, whereas a constant weight gives values > 0.74 .

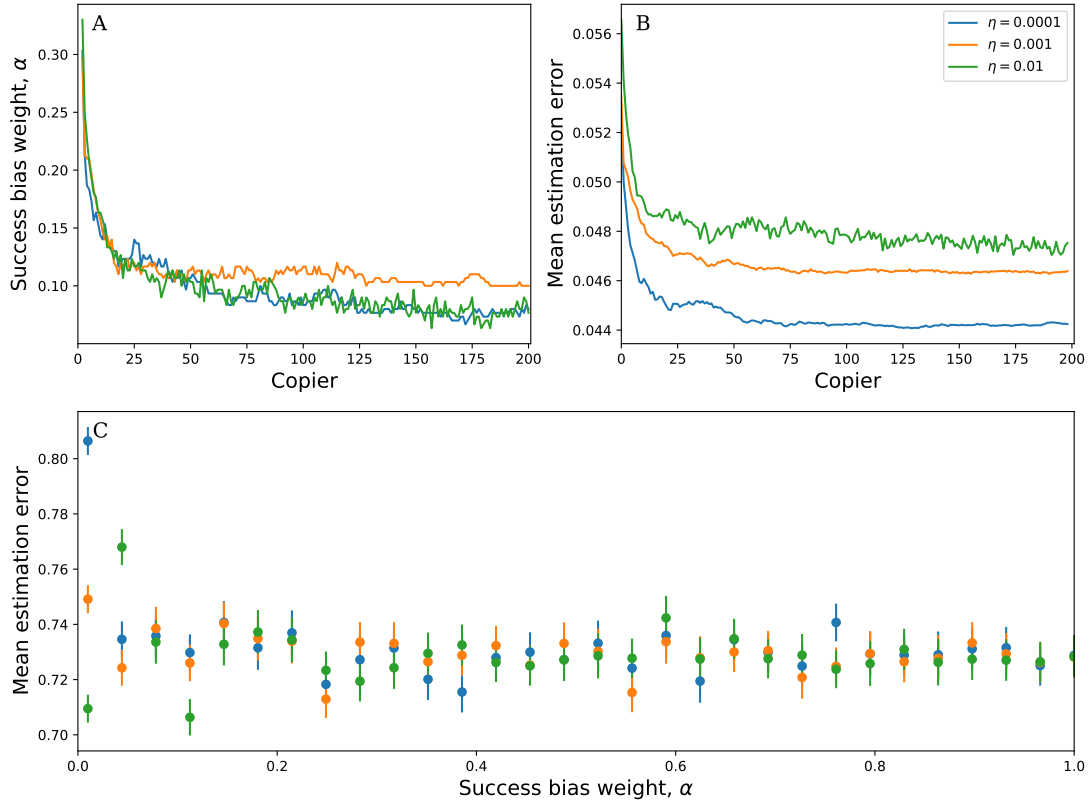


Figure 8: Advantage of an adaptive success-bias weight. Both success-bias weight α (A) and estimation error (B) decrease during the role-model choosing process, demonstrating that influence becomes more favored as more copiers have made their choice. However, when α is homogeneous (C), the mean estimation error doesn't decrease, regardless of α or η . The mean estimation error in the homogeneous α model is larger by a factor of 10 than the adaptive α model. Here, population size $N = 200$; estimation error is normally distributed $e \sim N(0, \eta^2)$ with standard deviation $\eta = 0.0001$ (blue), 0.001 (orange), 0.01 (green), plots are average of 300 simulations.

404 Discussion

During cultural transmission, cultural traits such as attitudes, values, beliefs, and behavioral patterns
406 are transmitted between individuals, for example via copying and social learning. Some cultural traits
or cultural role-models may be copied more often due to transmission biases. A common bias is
408 success bias, in which copiers are more likely to copy a successful role-model. Many models assume
that success can be accurately estimated. However, it has been suggested that because it is hard to
410 estimate success, a more common bias is *prestige bias*—a bias towards role-models perceived to be
successful in other traits (Henrich and Broesch, 2011).

412 Inspired by a model by Boyd and Richerson (1988), we developed a cultural-evolution model with
prestige bias that includes both success and influence biases, where the latter is a bias towards role-
414 models with many copiers. This is accomplished by a role-model choice process: each copier, in its
turn, chooses a role-model, and that choice is affected both by the estimated success of each potential
416 role-model and the number of copiers that already chose each role-mode (eq. 10).

This resulted in a model with two "nested" stochastic processes: the role-model choice process
418 within each generation, and the cultural-evolutionary process between generations. To simplify the
mathematical and computational analysis, we developed analytic approximations for the role-model
420 choice process using the *generalized binomial distribution* (GBD, Result 1) and the *Dirichlet-*
Multinomial distribution (DM, Corollary 3). The latter is especially useful, as it approximates the
422 entire role-model choice process and only requires us to assume that the relative effect of success and
influence is a characteristic of the role-model, rather than the copier.

424 Analyzing the model with the DM distribution, we found approximations for the fixation probability
and fixation time of a cultural trait under biased transmission in a constant environment. Our ap-
426 proximations are similar to Kimura's evolutionary-genetic approximations, such that (i) the difference
between the resident and invading cultural trait values, $1 - \beta(A)$, is equivalent to the selection coeffi-
428 cient in favor of a beneficial allele, s , and (ii) increasing the relative weight of influence versus success
bias, α , decreases the effective population size, N_e (Figure 6).

430 We also analyzed a cyclic changing environment in which the identity of the success-biased trait
switches after a fixed amount of generations (Figure 7). We find that, similarly to the constant
432 environment approximation, a change in the success-bias weight α has no negative effects on the
goodness-of-fit of the approximation to simulation results. We also showed that this approximation is
434 more sensitive to changes in the success coefficient β than the constant environment approximation,
and a lower value is required to have a good fit. The ratio between the number of generation in which
436 the rare phenotype is under positive transmission bias and the number of generations in which it is
under negative bias does not affect the goodness-of-fit of the approximation.

438 We also examined a scenario in which copiers can adapt their success-weight bias, α , to minimize
their copying error, i.e., copy trait values closer to the optimal value. We found that as the role-model
440 choice process proceeds (that is, more copiers make their choices), both the success-bias weight

(adapted by copiers) and the estimation error decrease. The latter is significantly lower compared to a
442 population using a constant, fixed success-bias weight, regardless of the value of the constant weight
(Figure 8). This suggests that the later a copier makes its choice, the more it should rely on choices
444 of previous copiers, and the less it should rely on its own estimation. The rationale, then, is that the
more information a copier has, e.g. by using others as information sources, the more informative and
446 effective his choice can be.

Prestige in the literature. According to King and Cowlishaw (2009), there are two main approaches
448 to group decision making in nature: leadership and consensus. Leaders would usually be high-ranking
members of the group: elders, individuals with many kin relations, or individuals possessing other
450 dominant traits. King and Cowlishaw (2009) describe benefits for the closest associates of a dominant
baboon, such as protection from predators. In some species, like the females of *Eulemur fulvus rufus*
452 (Red lemur), leaders may arise due to nutritional needs, and not due to possessing superior traits
(Erhart and Overdorff, 1999). In humans, leadership also has its costs and benefits. Leaders can
454 make decisions that would most benefit them and their closest followers, while still maintaining group
cohesion. However, wrong decision making that harms the group could result in negative effects
456 for the leader. In modern society, many humans strive for prestigious positions, as they may reap
rewards greater than the risk and costs to achieve them, or due to individual personality and pressure
458 or education from the family.

Henrich and Gil-White (2001) suggested that there are two types of leadership: prestige-based and
460 dominance-based leadership. In the latter, social status is acquired through aggression, intimidation
and violence. It is also more common than prestige in non-human animals. Their definition of prestige
462 seems to overlap with ours. They suggest prestige is composed of estimation in the eyes of other people
(similar to our success bias) and commanding position in people's minds, i.e., the number of followers
464 other people think one has, which they define as *influence*, similar to our influence bias. Henrich and
Gil-White (2001) show that prestige can evolve via natural selection as an efficient process to extract
466 reproductive benefit from the flow of socially transmitted information. They back up their claims by
creating testable predictions and using evidence from the literature and experiments of social sciences.
468 Simply put, prestige can naturally evolve when social learning already exists to save costs of individual
learning.

470 Furthermore, according to Boyd and Henrich (2002), the process of cultural evolution doesn't require
accurate replication of cultural traits, addressed as "representation" in their paper. They base their
472 assumption on three claims: mental representations are non-discrete, cultural transmission is highly
inaccurate, and mental representations are not replicated, but rather are 'reconstructed' through an
474 inferential process that is strongly affected by cognitive 'attractors.' They describe three different
models to support their points. We see a high similarity between their model and ours. Like them, we
476 treat the cultural trait as non-discrete (in the main model, before simplifying it to facilitate analysis).
We also assume error in estimation, such that copiers do not precisely replicate their role-models, but
478 rather reconstruct them to create a potentially different trait, which is their representation of the role-

model's trait. In addition, the inferential process that they describe as strongly affected by cognitive
480 attractors may include our definition of influence bias.

Empirical evidence of prestige bias Chudek et al. (2012) report the first direct tests in children that
482 suggest the existence of prestige bias, defined as the tendency to learn from individuals to whom
others have preferentially attended, learned, or deferred. Their definition of prestige is similar to our
484 influence bias. They showed that the odds of 3-4 years-old children learning from an adult role-model
to whom bystanders had previously preferentially attended for 10 seconds were more than twice those
486 of their learning from a role-models whom bystanders ignored. They also note that prestige effects are
domain sensitive: they found that prestigious role-models were attended more when demonstrating
488 artifact use, whereas role-models presenting food preferences had less attendants, suggesting that the
domain itself (artifact use vs. food preference) can affect the attendance, and hence the prestige of the
490 role-model. This lead Chudek et al. (2012) to suggest that when the trait is costly to learn individually,
prestige will have a stronger bias. It would be interesting to include costs in our model to try and
492 observe these effects and dynamics in a large population.

According to Henrich and Broesch (2011), evolutionary theorists propose that natural selection has
494 favored the emergence of psychological biases for learning from those individuals most likely to
possess adaptive information. Thus, they studied Fijian villages to examine if and how such biases
496 emerge in a small-scale society. They found that Fijian villagers are more likely to learn from role-
models perceived as more successful/knowledgeable, both within and across domains. Their research
498 thus suggests that copying from those perceived as successful, rather than actually are successful, is a
common phenomena. They show that the social networks representing copier–role-model relationships
500 are centralized, suggesting that it is consistent with the prediction that people substantially share
notions about who is a good cultural model, but that individuals' role-model selections are influenced
502 by multiple factors.

We can also find prestige bias in more modern domains such as western medicine. Norredam and
504 Album (2007) examined literature from 1950 to 2005 on the effects of prestige on medicinal practices.
They found that active, specialized, biomedical, and high-technological types of medicine on organs
506 in the upper part of the bodies of young and middle-aged people were accorded high levels of prestige,
whereas medicine and practices with opposite characteristics had low levels of prestige. For example,
508 they found that surgery counts as the most prestigious specialty, while psychiatry is the less prestigious.
In addition, doctors tend to rank practices that require more time to master as more prestigious, while
510 other procedures that are considered easier to master are less prestigious. This means that there may be
very important practices that are neglected due to prestige bias. They concluded that such differences
512 in prestige may bear consequences for actual priority setting in healthcare systems.

Prestige bias can help to cheaply estimate and acquire knowledge, which may facilitate survival and
514 reproduction. However, it is not always the case, and there could be negative repercussions to this
bias, such as invasion of maladaptive traits. Takahashi and Ihara (2019) mention that social learning
516 not only takes the form of random copying of other individuals, but also involves learners' choice of

what to learn and from whom to learn. They suggest a best-of- k model where an individual samples k
518 role-models and chooses the one he deems most "successful". They mentioned that a previous
mathematical analysis has shown that it may sometimes result in maladaptive cultural evolution when
520 the payoffs associated with cultural variants vary stochastically. In such a case, learners may be
selectively disfavored and in the long run replaced by unbiased learners, who simply copy someone
522 chosen at random. They developed new mathematical models that are simpler and mathematically
tractable. They found that best-of- k learning, unlike unbiased learning, can facilitate the invasion of
524 an on average inferior variant that sometimes gives a very high payoff. Our model, which includes
influence bias, is consistent with this claim. When a maladaptive trait is "piggybacking" a role-model
526 with high influence, this trait could spread in the population. In addition, they show that best-of- k
learning can be stable against invasion by unbiased learning if social learning is sometimes combined
528 with individual learning. Our model only includes social learning, and not individual learning, but it
could be interesting to combine it with individual learning and see how it affects the dynamics.

530 Prestige bias can also accelerate reversal of harmful traditions such as child marriage and domestic
violence. Efferson et al. (2020) suggest a *spillover* mechanism, in which an intervention affects a
532 large enough group in a target population, so that others not included in the intervention also change
their behavior. They found that there are individuals who act as *agents*, who are often looked upon,
534 and therefore they are ideal targets for interventions. This is similar to influential role-models in our
model, where a prestigious individual will be copied more often, and will therefore spread his trait
536 faster and wider in the population. They also suggest a way to use this phenomena to change existing
traditions in a population. It is very clear however, that just as it can be used to end harmful traditions,
538 the same agents could start harmful traditions.

Dunbar (2009) hypothesized that larger, more complex brains can store and manage more information
540 and in turn, this information can support the costs of a larger brain. Following up on this, Muthukrishna
and Henrich (2016) offered that prestige can directly affect human physical evolution. They present a
542 concept called *cultural brains*—brains that evolved primarily for the acquisition of adaptive knowledge.
They then develop a model that predicts a strong relationship between brain size and group size,
544 because group size also provides access to more adaptive knowledge. They also presented the
cumulative cultural brain hypothesis, which proposes that human brains have evolved with an ability
546 and tendency for selective, high-fidelity social learning. As part of this process, there are a variety of
strategies and biases that have evolved to hone in on the most adaptive knowledge. These strategies
548 and biases include direct and indirect cues of the popularity of cultural traits (e.g. success and prestige
biases). They suggest that one of the reasons for the extreme increase in brain size in humans is the
550 ability to "cheaply" acquire adaptive knowledge via transmission biases such as prestige.

Further work. One path forward is an analysis of the dynamics of the adaptive success-bias weight
552 model, in which every copier chooses its α . It would be interesting to see the if the mean estimation
error and the adaptive weight, α^* , are converging to specific values, and how they are affected by the
554 model parameters. It may also be possible to relax the assumptions required for our approximations,

such as homogeneous estimation error and success-bias weight. Lastly, it would be interesting to
556 analyze the continuous model and determine how much it differs from the dichotomous model.

Another way to expand our model is to account for the two types of prestige or leadership suggested
558 by Van Vugt and Smith (2019) that are attributed to Confucius and Machiavelli. Confucius viewed
leaders as role-models who exercise influence through possessing superior knowledge, skills, and
560 (outstanding) personal qualities. This fits the success bias in our model. In contrast, Machiavelli
viewed leaders as rulers who exercise influence by imposing costs through (the threat of) punishment
562 and violence. Van Vugt and Smith (2019) suggest that these two opposing views are both partially
supported by the available evidence but each one on its own offers an incomplete view of the complex
564 and dynamic concept of leadership. Several adjustments could be made so that our model reflects
these leadership styles, such as assuming there is a correlation between phenotype to leadership style.
566 The emerging cultural-evolutionary dynamics and their dependence on the costs and benefits are
intriguing.

568 **Conclusions.** Here, we presented support for the existence of prestige biases in cultural transmission,
including the commonly studied success bias. We introduced an influence bias, which has so far
570 received less attention. We believe the combination of these biases may be a strong driving force in
cultural evolution. We show that the relative effect of the two biases changes the effective population
572 size such that the increasing the weight individuals give to influence bias, decreases the effective
population size. We also find a clear advantage to individuals that can choose the relative weight of
574 the two biases.

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Appendices

Appendix A General binomial distribution approximation

Proving $E[K_{Nj}] = \alpha_j \cdot \beta(A_j + e) / \overline{\alpha \cdot \beta(A + e)}$, where the averaging in the denominator is over the role-models index, j .

Proof. The initial prestige of role-model j based on eq. (10) is

$$G_{1,j} = \frac{\alpha_j \cdot \beta(A_j + e)}{\sum_{m=1}^N \alpha_m \cdot \beta(A_m + e)} . \quad (\text{A1})$$

The denominator of eq. (A1) can also be formulated as:

$$\sum_{m=1}^N \alpha_m \beta(A_m + e) = N \cdot \overline{\alpha \cdot \beta(A + e)} , \quad (\text{A2})$$

where $\overline{\alpha \beta(A + e)}$ is the mean value of $\alpha_m \cdot \beta(A_m + e)$ for all m . Using eq. (A2) and **Corollary 1** we get,

$$E[K_{Nj}] = \alpha_j \cdot \beta(A_j + e) \left/ \overline{\alpha \cdot \beta(A + e)} \right. , \quad (\text{A3})$$

Appendix B Drift and diffusion in a constant environment

Proving drift and diffusion terms in a constant environment. Let x and x' be the frequency of type \hat{A} in a population with N individuals in the current and next generation, and β is the success coefficient of phenotype A , $\beta = \beta(A) < \beta(\hat{A}) = 1$. Then,

$$E[x' - x] \approx x(1 - x)(1 - \beta) , \quad V(x' - x) \approx x(1 - x) \left(\frac{1}{\alpha N + (1 - \alpha)} \right) .$$

Proof. Let X be the number of individuals of type \hat{A} such that $x = X/N$. X' is the number of individuals with \hat{A} in the next generation. The expected number of individuals is (due to the DM approximation),

$$E[X'] = N \frac{\alpha_1}{\alpha_1 + \alpha_2} , \quad (\text{B1})$$

where $\alpha_1 = \alpha'X$ and $\alpha_2 = \alpha'(N - X)\beta$, from eq. (11). To use frequencies instead of counts, $E[x'] = E[X'/N] = \frac{1}{N}E[X']$. Putting it together,

$$\begin{aligned} E[x'] &= \frac{1}{N}N \frac{\alpha'xN}{\alpha'xN + \alpha'N(1-x)\beta} = \frac{x}{x + (1-x)\beta} \\ &= \frac{x}{x + (1-x) - (1-x) + (1-x)\beta} = x \frac{1}{1 - (1-x)(1-\beta)} \\ &= x(1 + (1-x)(1-\beta) + o(\beta)) = x + x(1-x)(1-\beta) + o(\beta), \end{aligned} \quad (\text{B2})$$

following Durrett (2008, p. 253, ch 7.2) and because $1/(1-y) = 1 + y + y^2 + \dots$

By definition, x is constant, so $E[x] = x$. We therefore have

$$E[x' - x] = E[x'] - E[x] = x(1-x)(1-\beta) + o(1-\beta), \quad (\text{B3})$$

which gives us the drift term of the diffusion equation.

Using the variance of the DM distribution,

$$V(X') = N \frac{\alpha_1}{\alpha_1 + \alpha_2} \left(1 - \frac{\alpha_1}{\alpha_1 + \alpha_2}\right) \left(\frac{N + \alpha_1 + \alpha_2}{1 + \alpha_1 + \alpha_2}\right). \quad (\text{B4})$$

Again, we want to use frequencies so we have $V(X'/N) = \frac{1}{N^2}V(X')$. Putting it together with our model notations,

$$V(x') = \frac{1}{N^2}N \frac{x}{x + (1-x)\beta} \left(1 - \frac{x}{x + (1-x)\beta}\right) \left(\frac{N + \alpha'xN + \alpha'N(1-x)\beta}{1 + \alpha'xN + \alpha'N(1-x)\beta}\right). \quad (\text{B5})$$

Following Durrett (2008, ch 7.2), we assume $\beta \approx 1$, such that

$$\frac{x}{x + (1-x)\beta} \approx x \quad (\text{B6})$$

and for the entire variance expression we get

$$V(x') \approx \frac{1}{N}x(1-x) \left(\frac{N + \alpha'xN + \alpha'N - \alpha'xN}{1 + \alpha'xN + \alpha'N - \alpha'xN}\right) = x(1-x) \left(\frac{1 + \alpha'}{1 + \alpha'N}\right). \quad (\text{B7})$$

Now because x is a constant, $V(x) = 0$, and therefore

$$V(x' - x) = V(x') - V(x) \approx x(1-x) \left(\frac{1 + \alpha'}{1 + \alpha'N}\right). \quad (\text{B8})$$

α' is the odds ratio of the bias weight,

$$\alpha' = \frac{\alpha}{1 - \alpha}. \quad (\text{B9})$$

Combining eq. (B8) and eq. (B9) we get:

$$V(x' - x) \approx x(1 - x) \left(\frac{1 + \frac{\alpha}{1-\alpha}}{1 + \frac{\alpha}{1-\alpha}N} \right) = x(1 - x) \left(\frac{1}{\alpha N + (1 - \alpha)} \right). \quad (\text{B10})$$

This gives the diffusion term of the diffusion equation.

Appendix C Drift and diffusion in a changing environment

Proving drift and diffusion terms in a changing environment. Let x be the initial frequency of the invading phenotype and X_t is the number of individuals with the phenotype at time t . Then,

$$E[X_t/N - x] \simeq x(1 - x)S_t/N_e, \quad \text{and} \quad V(X_t/N - x) \simeq tx(1 - x)/N_e,$$

where $S_t = \sum_{i=1}^t N(1 - \beta_i)$.

Proof. Let $s_t = N(1 - \beta_t)$, and $S_n = \sum_{i=1}^n s_i$, where β_t is $\beta(A)$ at generation t . We prove by induction both terms in eq. (25). From eq. (B3) we know that

$$E \left[\frac{X_{t+1}}{N} - \frac{X_t}{N} \middle| X_t \right] = \frac{X_t}{N} \left(1 - \frac{X_t}{N} \right) (1 - \beta_{t+1}) = \frac{1}{N} \frac{X_t}{N} \left(1 - \frac{X_t}{N} \right) s_{t+1}. \quad (\text{C1})$$

Also note that using the definition of $V(y) = E[y^2] - (E[y])^2$

$$\begin{aligned} E \left[\frac{X_t}{N} \left(1 - \frac{X_t}{N} \right) \right] &= E \left[\frac{X_t}{N} - \left(\frac{X_t}{N} \right)^2 \right] = E \left[\frac{X_t}{N} \right] - E \left[\left(\frac{X_t}{N} \right)^2 \right] \\ &= E \left[\frac{X_t}{N} \right] - V \left(\frac{X_t}{N} \right) - \left(E \left[\frac{X_t}{N} \right] \right)^2. \end{aligned} \quad (\text{C2})$$

We can now use the induction assumption of $V(\frac{X_t}{N})$ to get

$$E \left[\frac{X_t}{N} \left(1 - \frac{X_t}{N} \right) \right] \simeq E \left[\frac{X_t}{N} \right] \left(1 - E \left[\frac{X_t}{N} \right] \right) - \frac{1}{N_e} tx(1 - x). \quad (\text{C3})$$

From eq. (C1) we know that

$$\begin{aligned} E \left[\frac{X_{t+1}}{N} - \frac{X_t}{N} \right] &= \frac{1}{N} s_{t+1} E \left[\frac{X_t}{N} \left(1 - \frac{X_t}{N} \right) \right] \simeq \frac{1}{N} s_{t+1} \left(E \left[\frac{X_t}{N} \right] \left(1 - E \left[\frac{X_t}{N} \right] \right) - \frac{1}{N_e} tx(1 - x) \right) \\ &\simeq \frac{1}{N} s_{t+1} \cdot E \left[\frac{X_t}{N} \right] \left(1 - E \left[\frac{X_t}{N} \right] \right) - \frac{1}{N_e N} s_{t+1} tx(1 - x). \end{aligned} \quad (\text{C4})$$

Now we omit $O(\frac{1}{Ne \cdot N})$ and get

$$E \left[\frac{X_{t+1}}{N} - \frac{X_t}{N} \right] \simeq \frac{1}{N} s_{t+1} \cdot E \left[\frac{X_t}{N} \right] \left(1 - E \left[\frac{X_t}{N} \right] \right) . \quad (C5)$$

We now look at the induction assumption to see that

$$E \left[\frac{X_t}{N} - x \right] = E \left[\frac{X_t}{N} \right] - E[x] = E \left[\frac{X_t}{N} \right] - x , \quad (C6)$$

so using the assumption we get

$$\begin{aligned} E \left[\frac{X_t}{N} \right] &\simeq \frac{1}{N} S_t x (1 - x) + x , \\ 1 - E \left[\frac{X_t}{N} \right] &\simeq 1 - \frac{1}{N} S_t x (1 - x) + x . \end{aligned} \quad (C7)$$

We use both expressions in eq. (C5) and get

$$\begin{aligned} E \left[\frac{X_{t+1}}{N} - \frac{X_t}{N} \right] &\simeq \frac{1}{N} s_{t+1} \left(\frac{1}{N} S_t x (1 - x) + x \right) \left(1 - \frac{1}{N} S_t x (1 - x) + x \right) \\ &\simeq \frac{1}{N} s_{t+1} \cdot x (1 - x) , \end{aligned} \quad (C8)$$

after again omitting $O(\frac{1}{N^2})$ terms. To conclude the proof, we note that

$$E \left[\frac{X_{t+1}}{N} - x \right] = E \left[\frac{X_{t+1}}{N} - \frac{X_t}{N} \right] + E \left[\frac{X_t}{N} - x \right] , \quad (C9)$$

so again using the induction assumption, together with eq. (C8) we get

$$\begin{aligned} E \left[\frac{X_{t+1}}{N} - x \right] &\simeq \frac{1}{N} s_{t+1} \cdot x (1 - x) + \frac{1}{N} S_t \cdot x (1 - x) \\ &\simeq \frac{1}{N} x (1 - x) (S_t + s_{t+1}) \simeq \frac{1}{N} S_{t+1} x (1 - x) , \end{aligned} \quad (C10)$$

which proves the drift term.

For the diffusion term, we use a property of variance,

$$V \left(\frac{X_{t+1}}{N} \right) = E \left[V \left(\frac{X_{t+1}}{N} \middle| X_t \right) \right] + V \left(E \left[\frac{X_{t+1}}{N} \middle| X_t \right] \right) . \quad (C11)$$

Using eq. (C1) we see that

$$\begin{aligned} E \left[\frac{X_{t+1}}{N} \middle| X_t \right] - E \left[\frac{X_t}{N} \middle| X_t \right] &= \frac{1}{N} s_{t+1} \frac{X_t}{N} \left(1 - \frac{X_t}{N} \right) \\ E \left[\frac{X_{t+1}}{N} \middle| X_t \right] &= \frac{X_t}{N} + \frac{1}{N} s_{t+1} \frac{X_t}{N} \left(1 - \frac{X_t}{N} \right) . \end{aligned} \quad (C12)$$

Using eq. (B10) we get

$$V\left(\frac{X_{t+1}}{N}\middle|X_t\right) = \frac{1}{N_e} \frac{X_t}{N} \left(1 - \frac{X_t}{N}\right), \quad (\text{C13})$$

and using the equation $y'(1 - y') \simeq y(1 - y)$ on the first part of eq. (C11) we get

$$E\left[V\left(\frac{X_{t+1}}{N}\middle|X_t\right)\right] = \frac{1}{N_e} E\left[\frac{X_t}{N} \left(1 - \frac{X_t}{N}\right)\right] \simeq \frac{1}{N_e} x(1 - x). \quad (\text{C14})$$

Moving on to simplify the second part of eq. (C11) using eq. (C12),

$$V\left(E\left[\frac{X_{t+1}}{N}\middle|X_t\right]\right) = V\left(\frac{X_t}{N} + \frac{1}{N} s_{t+1} \frac{X_t}{N} \left(1 - \frac{X_t}{N}\right)\right) \quad (\text{C15})$$

Now, because $\frac{X_t}{N}$ is a frequency, i.e $0 \leq X_t/N \leq 1$, we know that $V\left(\frac{X_t}{N} \left(1 - \frac{X_t}{N}\right)\right) \leq \frac{1}{4}$. We therefore find that

$$V\left(\frac{1}{N} s_{t+1} \frac{X_t}{N} \left(1 - \frac{X_t}{N}\right)\right) \leq \frac{1}{4N^2} s_{t+1}^2, \quad (\text{C16})$$

and so it can be ignored. Combining our equations we get

$$V\left(E\left[\frac{X_{t+1}}{N}\middle|X_t\right]\right) = V\left(\frac{X_t}{N}\right) + O\left(\frac{1}{N^2}\right) \simeq V\left(\frac{X_t}{N}\right). \quad (\text{C17})$$

Using the induction assumption and eq. (C14),

$$V\left(\frac{X_{t+1}}{N}\right) \simeq \frac{1}{N_e} x(1 - x) + \frac{1}{N_e} t x(1 - x) \simeq \frac{1}{N_e} x(1 - x)(t + 1) \quad (\text{C18})$$

which proves the diffusion term.