

view_frames Result

Recorded at time: 2229.342

map

Broadcaster: /amcl
Average rate: 46.617 Hz
Most recent transform: 2229.806 (-0.464 sec old)
Buffer length: 4.848 sec

odom

Broadcaster: /gazebo
Average rate: 20.252 Hz
Most recent transform: 2229.318 (0.024 sec old)
Buffer length: 4.444 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2229.342 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2229.342 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (2229.342 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.227 Hz
Most recent transform: 2229.274 (0.068 sec old)
Buffer length: 4.400 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.227 Hz
Most recent transform: 2229.274 (0.068 sec old)
Buffer length: 4.400 sec

right_wheel