

view_frames Result

Recorded at time: 212.682

odom

Broadcaster: /gazebo
Average rate: 20.206 Hz
Most recent transform: 212.669 (0.013 sec old)
Buffer length: 4.850 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10.211 Hz
Most recent transform: 212.608 (0.074 sec old)
Buffer length: 4.701 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.211 Hz
Most recent transform: 212.608 (0.074 sec old)
Buffer length: 4.701 sec

right_wheel

