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Examination	University	Institute	Year	CPI / %
Graduation	IIT Bombay	IIT Bombay	2024	8.04
Intermediate	CBSE	P.S.B.B.S.S School KK Nagar	2020	98.20%
Matriculation	CBSE	P.S.B.B.S.S School KK Nagar	2018	98.80%

Pursuing Honours in Computer Science and a Minor in ML and Data Science from CMInDS SCHOLASTIC ACHIEVEMENTS

• Secured All India Rank 308 in Joint Entrance Examination Advanced among 1.5 Lakh candidates	['20]
• Present in the top 0.5% in Joint Entrance Examination Mains among 0.85 million candidates	['20]

- Two time Recipient of the Kishore Vaigyanik Protsahan Yojana KVPY Fellowship (Both SA & SX Stream) ['20]
- Scored 412/450 Marks in BITSAT (Birla Institute of Technology and Science Admission Test)
- Scored among the top 1% and was qualified for the Indian National Chemistry Olympiad(INChO) ['20]
- Awarded National Talent Search Examination NTSE Scholarship by the Government of India

# KEY TECHNICAL PROJECTS

#### **International Aerial Robotics Competition**

[Oct'21- Present]

'20]

['18]

UMIC, IIT Bombay | Association for Unmanned Vehicle Systems International Foundation (AUVSI)

- Developing a system of Autonomous Quadcopters for the Longest Running Aerial Robotics Competition
- Working as a Sr. Machine Learning Engineer in Project AeRoVe, an interdisciplinary team of 25+ students
- ullet Employed a pipeline for a custom-dataset of more than  ${f 3K+}$  images collected by the drone to speed-up annotation
- $\bullet \ \ \text{Achieved accuracy} (\textbf{mAP}) \ \text{of} \ \textbf{95.6\%} \ \text{on} \ \ \textbf{YOLOv4-tiny} \ \text{models for custom object detection} \\$
- Surveyed literature on object detection and tracking, including R-CNN, Fast R-CNNs, YOLOv3, YOLOv4, SORT and DeepSORT to enhance localisation accuracy and ensure smooth autonomous flight of the drone
- Ideated direction vector estimation on 3D Point Cloud data using RANSAC Segmentation & Clustering with PCL
- Reduced inference time by 300% by optimizing detection models by building serialized TRTengines in C++ using the Nvidia TensorRT library while deploying custom-YOLOv4 models on Nvidia Jetson Xavier NX

#### Deep Reinforcement Learning for Stock Trading

[Apr'21 - Jul'21]

Seasons of Code-'21 | Web and Coding Club (WnCC)

- Trained an intelligent agent to actually trade in the markets, by using various reinforcement learning methods
- Investigated the concepts involved in **Tabular Methods** like Markov Decision Processes, Monte Carlo Methods, Dynamic Programming, Temporal-Difference learning for solving **Reinforcement Learning problems**
- Scrutinized research papers and implemented **PPO** (Proximal Policy Gradient), an Actor-Critic RL algorithm
- Explored classic control problems such as Cartpole & Acrobat-v1 environments in the OpenAI-Gym library
- Examined and backtested quant trading strategies like mean-reversion, pair-trading on Quantconnect platform
- Learnt and tried Technical and Fundamental analysis techniques and methodologies from Zerodha Varsity

#### Arcface: Deep Face Recognition Model

[Aug'21 - Present]

GNR638 Course Project | Guide: Prof.Biplab Banarjee

- Surveyed literature on face recognition including DeepFace, FaceNet, SphereFace ,CosFace and the State-of-the-Art Arcface paper to learn discriminative feature vectors and implement few-shot face recognition
- Implemented Arcface Layer from scratch and used transfer learning with ResNet50 architecture as backbone feature extractor in TensorFlow to get highly discriminative features and acheived a verification acc. of 93.2%
- Trained the Arcface model on the LFW (Labeled Faces in the Wild) dataset of 350+ people with 1.4K+ images
- Designed experiment and analysed results to compare Adam & SGD and determine the best **optimizer** for training
- Estimated the distance threshold and evaluated various distance metrics for optimal model performance
- Deployed the model using python based **Flask** micro web framework with a frontend UI designed with HTML and CSS to upload images and view results. Ajax and **JavaScript** was used for frontend-backend communication

#### DRDO'S UAV-Guided UGV Navigation Challenge

[Mar'22 - Apr'22]

Project AeRoVe | Inter-IIT Tech Meet 10.0

- Won 3<sup>rd</sup> place in DRDO's navigation challenge among 12 IITs at the InterIIT Tech Meet representing IITB
- Developed a combination of an Unmanned Ground Vehicle (UGV) and a guiding Unmanned Aerial Vehicle (UAV) autonomously capable of mapping and navigating snow covered mountainous terrain solely using **drone feedback**
- Experimented with various **keypoint detection** algorithms on images to find the pose and heading of the UGV
- Combined CV techniques such as Canny Edge Detection, Sobel Filters, Blurring, Adaptive Thresholding and Countour Detection with ML algorithms to get 99%+ precision in the location and direction of UGV
- Implemented a DNN for Terrain Semantic Segmentation to derive waypoints for control and navigation

#### ASME STUDENT DESIGN CHALLENGE 2021

[Jan '21 - Apr'21]

UMIC, IIT Bombay | American Society of Mechanical Engineers (ASME)

- International Student Design Challenge focusing on efficient energy capture, storage and use in robotics
- Secured 4<sup>th</sup> position WORLDWIDE in the World Finals stage of the competition amongst 30+ teams
- Worked in the **Mechanical** subsystem to build a bot to carry a **5** kg payload powered by a single AAA battery
- Designed the robot and made a 3D CAD model in Fusion360 and analyzed the mechanical feasibility of the design
- Engineered circuit to charge super-capacitor and battery using a solar panel and wind turbine under 60 seconds

#### OTHER PROJECTS

#### Car Price Prediction Model

[Jun'21]

Self Project

- Trained a Random Forest Regressor with test set RMSE of 1.31 to predict resale value of cars using sk-learn
- Deployed model using Flask & Jsonify libraries and created front-end interface using HTML to get input data

#### Image Handling and Processing

[Sep'21 - Nov'21]

CS215 Course Project | Guide: Prof. Suyash Awate

- Scripted Python code to plot the closest representations of RGB images of fruit using **PCA** and generate new images which are representative of the dataset, by randomly sampling these representations
- Performed Multivariate Gaussian fitting to the MNIST dataset, to identify the modes of variation (PCA)

Hactoberfest 2021 [Oct'21]

Self Project

- Hacktoberfest is a monthlong celebration of open source software by DigitalOcean, Intel and Deepwrite
- Contributed 5 PRs which were inspected and merged to 4 different repositories maintained by WNCC IIT Bombay

#### **ASR Role Playing Seminar**

[Jan'22-Apr'22]

CS753 Course Project | Guide: Prof. Preethi Jyothi

- Presented a seminar talk on a paper on Audio-Visual Video Parsing discussing the task, method and experiments
- Implemented End-to-End Neural Speaker Diarization which partitions audio input according to speaker identity
- Reviewed a paper titled Learning Audio-Visual Dereverberation and analysed the pros & cons of the model
- Prepared a poster for the BERT-ASR paper highlighting the main ideas of the paper visually with minimal text
- ullet Compiled a scientific report on the paper titled Mask-CTC explaining the architecture & training method used
- ullet Used Kaldi ASR and Coqui deep-learning toolkits to train and make f ASR and f STT systems in regional languages

### LEADERSHIP ROLES

# Manager, Project AeRoVe | UMIC IIT Bombay

[May'22 - Present]

UMIC is a student technical team that promotes and adheres to the idea of innovation and techno-preneurship

- Managing a team of 22, responsible for gaining sponsorships and establishing a strong social media presence
- Moderating and channeling information between the Core team members and the Non-Core team members
- Managing a budget of ₹1.5+ million and responsible for procuring required equipment for the technical team
- Conducted a 3-phase recruitment drive for the biz-team and shortlisted 5 candidates out of 70+ total applicants
- Mentoring and training 2 freshman students in the Machine Learning & Computer Vision subsystem of AeRoVe

#### Coordinator, Project AeRoVe | UMIC IIT Bombay

[Jan'21 - May'22]

 $Team\ of\ 25+\ students\ working\ on\ autonomous\ ground\ {\it \& erial\ vehicles\ competing\ internationally}$ 

- Member of the team in charge of planning, organizing and publicizing events under the Innovation Cell
- Spearheaded 2 technical recruitment drives to induct members from a pool of 200+ UG applicants for core team
- Mentored a team of 5 freshmen recruits in the S.T.A.R Program to ideate and solve complex-robotics projects

# TECHNICAL SKILLS

**Programming Languages** Python, C, C++, Java, Bash, URDF, Xacro

ML & Data Science TensorFlow, PyTorch, TensorRT, OpenCV, Numpy, Pandas, Scipy, scikit-learn

Frameworks
Git, L⁴TEX, Arduino, ROS, Gazebo, Kaldi ASR, Coqui STT, Fusion360
Web Development
HTML, CSS, Bootstrap, Javascript, Django, Flask

## KEY COURSES UNDERTAKEN

Computer Science Data Structures and Algorithms, Software Systems Lab, Discrete Structures, Computer Net-

works, Design and Analysis of Algorithms, Operating Systems\*, Compilers\*\*

ML/DL & Statistics ML for Remote Sensing II, Automatic Speech Recognition, Foundations of Intelligent & Learning Agents\*, Artificial Intelligence\*, Data Analysis and Interpretation, Machine Learning

Specialization<sup>\$</sup>, Deep Learning Specialization<sup>\$</sup>, Fundamentals of Reinforcement Learning<sup>\$</sup>

\* To be completed by Dec '22

\*\* To be completed by Apr '23

\* Online Courses

#### EXTRA-CURRICULAR ACTIVITIES

- Mentored two teams of young scientific minds in the TrailBlazHER Innovation Challenge 2021
- Trained for 9 years in Alan-Thilak Shito Ryu Karate and Silambattam and received a Black-belt
- Placed **2<sup>nd</sup>** in galaxy **Science Quiz** twice and won the Mind Storm Quiz at IIT Mardras' **Forays** Mathfest
- Completed a 10 level Robotics course and graduated with distinction in Programming from Kidobotikz
- Attended a 6 week long summer program on Game Theory in Duke Univ's TIP at Shiv Nadar University Noida