#### **Statistic**

For robust statistics, see the page.

#### **Textbook**

# Matrix cookbook

- The matrix cookbook
- *a* for scalar, *a* for vector, *A* for matrix.
- X for random variable,  $\underline{X}$  for random vector,  $\mathbf{X}$  for random matrix.
- $\mathbb{E}[\underline{a}^T\underline{X}] = \underline{a} \cdot \mathbb{E}\underline{X}$ ;  $\mathbb{E}[A\underline{X}] = A\mathbb{E}\underline{X}$ ;  $\mathbb{E}A\mathbf{X}B = A\mathbb{E}[\mathbf{X}]B$ .
- $\bullet \ \mu := \mathbb{E}\underline{X}, \underline{v} := \mathbb{E}\underline{Y}.$

## Covariance

- $1. \operatorname{Cov}[X,Y] = \operatorname{I\!E}[(X \operatorname{I\!E} X)(Y \operatorname{I\!E} Y)] = \operatorname{I\!E}[(X \operatorname{I\!E} X)(Y \operatorname{I\!E} Y)].$
- $[2.\ V[rac{X}{\sigma_X}]=1,
  ho_{XY}=Cov[ ilde{X}, ilde{Y}]=rac{Cov[X,Y]}{\sigma_X\sigma_Y}$
- 3. The **covariance matrix**  $V[\underline{X}] = \mathbb{E}[(\underline{X} \mu)(\underline{X} \mu)^T] = \mathbb{E}\underline{X}\underline{X}^T \mu\mu^T$ .
- 4. The **variance of r.v.** in the form of  $\underline{a} \cdot \underline{X}$ :  $V[\underline{a} \cdot \underline{X}] = \underline{a}^T V[\underline{X}]\underline{a}$ ;  $V[A\underline{X}] = AV[\underline{X}]A^T$ . When  $||\underline{a}|| = 1$ , it's taking the variance in the direction of  $\underline{a}$ , over the joint p.d.f. (consider variance as the width of the function picture along certain axis).

# Multivariate normal

- 1. Standard normal:  $Z \sim N(0, I)$ .
- 2. (Stretch)  $\underline{X} = D\underline{Z}$  where  $D = diag(\sigma_1, \sigma_2, ...)$ , then  $\underline{X} \sim N(\underline{0}, D^2)$ .
- 3. (Rotate)  $\underline{Y} = Q\underline{X}$  where  $Q^TQ = I$  (orthogonal), then  $\underline{Y} \sim N(\underline{0}, V)$ . Given D to find V and Q, consider that by (Covariance-4),

$$V = V[Y] = V[QX] = QV[X]Q^T = QD^2Q^T$$

Eigenvalue decomposition solves this problem. Say  $eigen(V)=\lambda_{1}, \dots\$ , then  $\lambda_{i}=\simeq_{i}^{2}\$ .

# **Hypothesis Testing**

# Kullback-Leibler divergence

a measure of how one probability distribution P is different from a second, reference probability distribution Q.

## **STAT 400**

Def. (**Bernoulli distribution**,  $X \sim Be(p)$ ) Bernoulli trial is that  $A \in \mathcal{F}$ , and we call the trial a success if A occurs. Bernoulli distribution is based on single Bernoulli trial.

Def. (**Binomial distribution**,  $Y \sim Bin(n,p)$ ) Perform n independent Bernoulli trials with  $p = \mathbb{P}(A)$ , and let Bernoulli r.v.s.  $X_1, X_2 \dots X_n$  be the indicator function of success of the experiments. Let  $Y := \sum X_i$ , then the p.m.f.  $f_Y(k) = \binom{n}{k} p^k (1-p)^{n-k}, k = 1, 2, \dots, n$ . **Binomial process** is that  $Y_n$  to be the number of successes in the first n Be(p) trials.

Def. (**Geometric distribution**,  $W \sim Geom(p)$  ) Keep performing Bernoulli trials until the first success, and let W := the waiting time, then  $f_W(k) = (1-p)^{k-1}p, k=1,2,\ldots,F(x) = 1-(1-p)^x$ .

Def. (Negative Binomial distribution,  $W_r \sim NB(r,p)$  ) Let  $W_r :=$  the waiting time for r successes, then  $f_{W_r}(k) = \binom{k-1}{k-r} p^{r-1} (1-p)^{k-r} p, k=1,2,\dots$ 

Def. (**Poisson distribution**,  $X \sim poisson(\lambda)$ )  $f_X(k) := \frac{\lambda^k}{k!} e^{-\lambda}, k = 1, 2, \dots$  The Poisson distribution is an approximation of a binomial distribution of a rare event in the case that **n** is **large**, **p** is **small**, and  $\lambda = np$  is moderate.

Def. (**Hypergeometric distribution**)  $f_X(k) = \frac{\binom{K}{k}\binom{N-K}{n-k}}{\binom{N}{n}}$ . IE $X = nN_1/N$ ,  $VarX = n\frac{N_1}{N}\frac{N-K}{N}\frac{N-n}{N-1}$ . The sample

Def. (**Multinomial**) Multi-outcome version of hypergeometric.  $f_X(x)=\frac{n!}{\prod x_i!}\prod p_i^{x_i}$ , where  $\mathbb{E}X_i=np_i, VarX_i=np_i(1-p_i)$ .