/home/fxm-cm/catkin _ws/src/cob_control /cob_twist_controller /include/cob_twist_controller /constraint_solvers/solvers /weighted_least_norm_solver.h

/home/fxm-cm/catkin _ws/src/cob_control /cob_twist_controller /src/constraint_solvers /solvers/weighted_least _norm_solver.cpp /home/fxm-cm/catkin _ws/src/cob_control /cob_twist_controller /include/cob_twist_controller /constraint_solvers/solvers /wln_joint_limit_avoidance_solver.h

> /home/fxm-cm/catkin _ws/src/cob_control /cob_twist_controller /src/constraint_solvers /solvers/wln_joint_limit _avoidance_solver.cpp