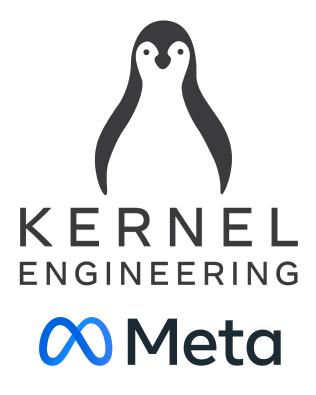
## HOWTO: design kernel extensions with BPF struct\_ops



#### Motivation

- The kernel is not a place to implement a policy
- Examples of policies
  - TCP congestion control
  - OOM detection and selection
  - packet scheduling in networking
  - task selection and placement
  - security policies
  - various heuristics
- Solution: implement a policy as a kernel module or as a BPF program

#### Motivation

- The kernel have no room for uapi mistakes
- We make mistakes all the time

# Old way of extending kernel with BPF

- Add new program type to uapi/bpf.h for every use case
  - Grew to 32 types over the years
- Sprinkle hooks in the kernel
- Add specific helpers
- uapi mistakes are forever
  - 6 out of 32 have zero users :(
- root cause
  - each program type means unique and specific bpf program context as only input argument

#### Lesson learned

- No new prog types
  - Though people still send patches to add them
- No new helpers
  - This decision caused fights between developers

# non-uapi alternative

- struct\_ops
- kfuncs

# Kernel "struct \*\_ops"

- collection of callbacks
- typically named "struct foo\_ops"
- Example: file\_ops, inode\_ops, vm\_ops, net\_device\_ops, tcp\_congestion\_ops, ...
- It's an interface definition
- modules provide implementation for the interface
- In object oriented terminology "struct \*\_ops" describes an abstract class where callbacks are pure virtual functions

It's an example of good interface design.

```
struct tcp_congestion_ops {
        /* return slow start threshold (required) */
        u32 (*ssthresh)(struct sock *sk);
        /* do new cwnd calculation (required) */
        void (*cong avoid)(struct sock *sk, u32 ack, u32 acked);
        /* call before changing ca_state (optional) */
        void (*set state)(struct sock *sk, u8 new state);
        /* call when cwnd event occurs (optional) */
        void (*cwnd_event)(struct sock *sk, enum tcp_ca_event ev);
        char
                                name[TCP CA NAME MAX];
                                *owner;
        struct module
       void (*init)(struct sock *sk);
        void (*release)(struct sock *sk);
};
```

- callbacks invoked by TCP networking stack
- lots of congestion control algorithms implemented as built-in and as kernel modules

```
net/ipv4/tcp_bbr.c: return tcp_register_congestion_control(&tcp_bbr_cong_ops);
net/ipv4/tcp_bic.c: return tcp_register_congestion_control(&bictcp);
net/ipv4/tcp_cubic.c: return tcp_register_congestion_control(&cubictcp);
net/ipv4/tcp_dctcp.c: return tcp_register_congestion_control(&dctcp);
...
```

```
net/ipv4/tcp cubic.c:
static struct tcp_congestion_ops cubictcp = {
        .init
                       = cubictcp init,
        .ssthresh
                       = cubictcp_recalc_ssthresh,
        .cong_avoid
                       = cubictcp_cong_avoid,
                       = cubictcp_state,
        .set_state
        .undo_cwnd
                       = tcp_reno_undo_cwnd,
        .cwnd_event
                       = cubictcp_cwnd_event,
        .pkts_acked
                       = cubictcp_acked,
                       = THIS_MODULE,
        .owner
                       = "cubic",
        .name
```

```
static void cubictcp_cwnd_event(struct sock *sk, enum tcp_ca_event event)
        if (event == CA_EVENT_TX_START) {
                struct bictcp *ca = inet_csk_ca(sk);
                u32 now = tcp_jiffies32;
                s32 delta;
                delta = now - tcp sk(sk)->lsndtime;
                /* We were application limited (idle) for a while.
                 * Shift epoch_start to keep cwnd growth to cubic curve.
                 */
                if (ca->epoch_start && delta > 0) {
                        ca->epoch_start += delta;
                        if (after(ca->epoch_start, now))
                                ca->epoch_start = now;
                return;
```

# TCP congestion control in BPF

- tcp\_congestion\_ops was an inspiration for BPF struct\_ops
- Designed by Martin KaFai Lau <martin.lau@kernel.org> 4+ years ago
- Goals:
  - callbacks don't need to change on the kernel side to call into BPF programs
  - BPF programs are indistinguishable from kernel modules implementing \*\_ops
  - do not impose any uapi restrictions on the kernel

## TCP congestion control in BPF

```
tools/testing/selftests/bpf/progs/bpf cubic.c:
SEC(".struct ops")
struct tcp congestion ops cubic = {
       .init = (void *)bpf cubic init,
       .ssthresh = (void *)bpf_cubic_recalc_ssthresh,
       .cong_avoid
                      = (void *)bpf cubic cong avoid,
       .set_state
                      = (void *)bpf cubic state,
       .undo_cwnd
                      = (void *)bpf_cubic_undo_cwnd,
                      = (void *)bpf_cubic_cwnd_event,
       .cwnd_event
       .pkts acked
                      = (void *)bpf cubic acked,
                      = "bpf cubic",
       .name
```

## TCP congestion control in BPF

```
SEC("struct ops")
void BPF_PROG(bpf_cubic_cwnd_event, struct sock *sk, enum tcp_ca_event event)
        if (event == CA_EVENT_TX_START) {
                struct bpf_bictcp *ca = inet_csk_ca(sk);
                __u32 now = tcp_jiffies32;
                s32 delta;
                delta = now - tcp_sk(sk)->lsndtime;
                /* We were application limited (idle) for a while.
                 * Shift epoch_start to keep cwnd growth to cubic curve.
                 */
                if (ca->epoch_start && delta > 0) {
                        ca->epoch start += delta;
                        if (after(ca->epoch_start, now))
                                ca->epoch start = now;
                return;
```

## TCP congestion control in BPF vs kernel

```
SEC("struct_ops")
void BPF_PROG(bpf_cubic_cwnd_event, struct sock *sk, enum tcp_ca_event
event)
                                                                            static void cubictcp_cwnd_event(struct sock *sk, enum tcp_ca_event event)
                                                                                    if (event == CA_EVENT_TX_START) {
        if (event == CA_EVENT_TX_START) {
                                                                                            struct bictcp *ca = inet_csk_ca(sk);
                struct bpf_bictcp *ca = inet_csk_ca(sk);
                                                                                            u32 now = tcp_jiffies32;
                __u32 now = tcp_jiffies32;
                                                                                            s32 delta;
                __s32 delta;
                                                                                            delta = now - tcp_sk(sk)->lsndtime;
                delta = now - tcp_sk(sk)->lsndtime;
                                                                                            /* We were application limited (idle) for a while.
                /* We were application limited (idle) for a while.
                                                                                             * Shift epoch_start to keep cwnd growth to cubic curve.
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                                                                                            if (ca->epoch_start && delta > 0) {
                if (ca->epoch_start && delta > 0) {
                                                                                                    ca->epoch_start += delta;
                        ca->epoch_start += delta;
                                                                                                    if (after(ca->epoch_start, now))
                        if (after(ca->epoch_start, now))
                                                                                                            ca->epoch_start = now;
                                 ca->epoch_start = now;
                                                                                            return;
                return;
```

# TCP congestion control in BPF vs kernel

```
SEC("struct_ops")
void BPF_PROG(bpf_cubic_cwnd_event, struct sock *sk, enum tcp_ca_event
event)
                                                                            static void cubictcp_cwnd_event(struct sock *sk, enum tcp_ca_event event)
                                                                                    if (event == CA_EVENT_TX_START) {
        if (event == CA_EVENT_TX_START) {
                                                                                            struct bictcp *ca = inet_csk_ca(sk);
                struct bpf_bictcp *ca = inet_csk_ca(sk);
                                                                                            u32 now = tcp_jiffies32;
                __u32 now = tcp_jiffies32;
                                                                                            s32 delta;
                __s32 delta;
                                                                                            delta = now - tcp sk(sk)->lsndtime;
                delta = now - tcp sk(sk)->lsndtime;
                                                                                            /* We were application limited (idle) for a while.
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                                                                                             * Shift epoch_start to keep cwnd growth to cubic curve.
                 * Shift epoch_start to keep cwnd growth to cubic curve.
                                                                                            if (ca->epoch_start && delta > 0) {
                if (ca->epoch_start && delta > 0) {
                                                                                                    ca->epoch_start += delta;
                        ca->epoch_start += delta;
                                                                                                    if (after(ca->epoch_start, now))
                        if (after(ca->epoch_start, now))
                                                                                                            ca->epoch_start = now;
                                 ca->epoch_start = now;
                                                                                            return;
                return;
```

Same speed!

compiles to BPF ISA and JITed to native

compiles to native

# Why implement TCP congestion control in BPF instead of kernel module?

- Safety
  - If it loads it won't crash the kernel
- Portability
  - Doesn't depend on the kernel version
  - Compile once and load BPF programs on many servers running different kernel versions
- Debuggability and observability
  - BPF programs are compiled with source code embedded in
  - GPL license is enforced
  - bpftool can profile and examine loaded programs

## Existing and upcoming struct\_ops users

- tcp\_congestion\_ops
- hid\_bpf\_ops
  - HID drivers
- sched\_ext\_ops
  - task scheduler
- Qdisc\_ops
  - Network queuing discipline (when fq, fq\_codel, pfifo, htb is not enough)
- fuse-bpf
- OOM-bpf

#### Interaction between kernel and BPF code

- Kernel C code is compiled into native CPU ISA with native calling convention
- BPF C code is compiled into BPF ISA with BPF calling convention
  - JIT translate BPF ISA into native ISA
  - calling from/to kernel/BPF requires conversion of arguments/return value
- BPF calling convention prescribes that arguments are passed in R1-R5 and return value in R0
  - LLVM and GCC compile C to BPF ISA this way

# Comparison of calling conventions

	BPF	x86	Arm64	Risc-V
Arg 1 Arg 3 Arg 4 Arg 5 Arg 6	r1 r2 r3 r4 r5	rdi rsi rdx rcx r8 r9	x0 x1 x2 x3 x4 x5	a0 a1 a2 a3 a4 a5
Return	r0	rax	x0	a0

#### No extra cost to/from BPF on x86

	BPF	x86	Arm64	Risc-V
Arg 1 Arg 2 Arg 3 Arg 4 Arg 5 Arg 6	r1 r2 r3 r4 r5	rdi rsi rdx rcx r8 r9	x0 x1 x2 x3 x4 x5	a0 a1 a2 a3 a4 a5
Return	r0	rax	x0	a0

One to one mapping of BPF registers to x86 registers

#### One extra mov to return from BPF to Arm64

	BPF	x86	Arm64	Risc-V
Arg 1 Arg 3 Arg 4 Arg 5 Arg 6	r1 r2 r3 r5	rdi rsi rdx rcx r8 r9	x0 x1 x2 x3 x4 x5	a0 a1 a2 a3 a4 a5
Return	r0	rax	x0	a0

- The first function argument and return value are in the same register
- JIT has to map BPF R1 and R0 to two different registers and add an extra copy after the CALL instruction
  - R1 is mapped to x0
  - R0 is mapped to x7

# Ways of calling into the kernel

- helpers
- kfuncs

# BPF helpers: compiler translate calling conventions

```
// kernel/bpf/helpers.c:
BPF_CALL_2(bpf_map_lookup_elem, struct bpf_map *, map, void *, key)
  return (unsigned long) map->ops->map_lookup_elem(map, key);
// macro magic expands into:
static inline u64 ____bpf_map_lookup_elem(struct bpf_map * map, void * key)
  return (unsigned long) map->ops->map_lookup_elem(map, key);
u64 bpf_map_lookup_elem(u64 map, u64 key, u64 r3, u64 r4, u64 r5) // BPF program calls this function
  return ____bpf_map_lookup_elem((struct bpf_map *)map, (void *)key);
// and compiled to:
(gdb) disassemble bpf_map_lookup_elem
Dump of assembler code for function bpf_map_lookup_elem:
  All arguments and return value are in
  0xfffffffff11f40c9 <+9>: mov
                               (%rdi),%rax
                                                             correct registers. No extra copies.
  *0x60(%rax)
```

End of assembler dump.

## BPF helpers ... no more

- Helper's disadvantage:
  - helpers have hard coded IDs in uapi/bpf.h
  - kernel modules cannot add them
  - subsystems cannot easily introduce them
- Solution:
  - stop adding helpers and introduce kfunc mechanism
  - kfunc is an unstable interface between BPF programs and the kernel
  - kernel modules can define their own kfuncs

```
git grep "FN(" include/uapi/linux/bpf.h 211 helpers git grep '^__bpf_kfunc\>' 175 kfuncs
```

#### BPF kfuncs internals

- kfuncs rely on BPF Type Format (BTF)
- function prototype is converted to btf func model

```
struct btf_func_model {
    u8 ret_size;
    u8 ret_flags;
    u8 nr_args;
    u8 arg_size[MAX_BPF_FUNC_ARGS];
    u8 arg_flags[MAX_BPF_FUNC_ARGS];
};
```

- JITs use btf\_func\_model to translate BPF calling convention to native
  - nop on x86-64 because
    - all BPF registers are mapped 1-1 to x86 registers and
    - type promotion rules are the same (unlike risc-v)
  - not easy on x86-32

# Calling kfuncs on x86-32

i386 kernel is compiled with "-mregparm=3":

The first three args of a function will be considered for putting into the 32bit register EAX, EDX, and ECX.

Two 32bit registers are used to pass a 64bit arg.

```
void foo(u32 a, u32 b, u32 c, u32 d):
    u32 a: EAX
    u32 b: EDX
    u32 c: ECX
    u32 d: stack

void foo(u64 a, u32 b, u32 c):
    u64 a: EAX (lo32) EDX (hi32)
    u32 b: ECX
    u32 c: stack
```

## Any kernel function can be a kfunc

```
#define __bpf_kfunc __used __retain noinline
__bpf_kfunc void bpf_rcu_read_lock(void)
{
          rcu_read_lock();
}

BTF_KFUNCS_START(common_btf_ids)
BTF_ID_FLAGS(func, bpf_rcu_read_lock)
BTF_KFUNCS_END(common_btf_ids)
```

- Unlike helpers there is no extra code from BPF\_CALL\_N() macros that convert calling convention
- JITs generate translation code
- A lot more efficient on 32-bit architectures

# Ways of calling into BPF program

- prog->bpf\_func(ctx, ...);
  - all networking hooks are done this way
- tracing style
  - kprobe, fentry, tracepoint
- struct\_ops

## Old way of calling into BPF program

```
struct xdp_buff xdp;
struct bpf_prog *prog;
u32 ret;
// store all arguments that needs to be passed to BPF prog in the "context" structure
xdp_init_buff(&xdp, ...);
xdp prepare buff(&xdp, hard start, data, ...);
prog = // fetch the prog pointer from somewhere
// call it with a single "context" argument
ret = prog->bpf func(&xdp, prog->insnsi /* for interpreter */);
switch (ret) {
case XDP_PASS:
 • •
```

# Disadvantages of old way of calling into BPF

- "context" structure is uapi
  - think twice of every field and ways to extend
- plenty of boiler plate code to pack arguments into "context" struct

```
static inline void tcp_ca_event(struct sock *sk,
                                const enum tcp ca event event)
        const struct inet_connection_sock *icsk = inet_csk(sk);
        if (icsk->icsk ca ops->cwnd event)
                icsk->icsk ca ops->cwnd event(sk, event);
net/ipv4/tcp_input.c: tcp_ca_event(sk, CA_EVENT_ECN_IS_CE);
net/ipv4/tcp_input.c: tcp_ca_event(sk, CA_EVENT_ECN_NO_CE);
net/ipv4/tcp_input.c: tcp_ca_event(sk, CA_EVENT_LOSS);
net/ipv4/tcp input.c: tcp ca event(sk, CA EVENT COMPLETE CWR);
net/ipv4/tcp_output.c: tcp_ca_event(sk, CA_EVENT_CWND_RESTART);
net/ipv4/tcp_output.c: tcp_ca_event(sk, CA_EVENT_TX_START);
```

- Just a normal C code
- BPF struct\_ops mechanism generates trampoline to call

```
void (*cwnd_event)(struct sock *sk, enum tcp_ca_event ev);
```

- sk in %rdi is stored to stack
- ev in %rsi is stored to stack
- calls JITed bpf prog directly

```
SEC("struct_ops")
void BPF_PROG(bpf_cubic_cwnd_event, struct sock *sk, enum tcp_ca_event event)
// access 'sk' from BPF program is a read from stack
// while the verifier enforces types
```

- BPF struct\_ops mechanism populates
struct tcp\_congestion\_ops {
 .cwnd\_event = // pointer to trampoline
} cubic;

- Kernel calls native ops callback
  - pass arguments in registers + indirect call
- Kernel calls BPF struct ops callback
  - pass arguments on stack + indirect call + direct call

- No kernel side changes
- No uapi contract

## How to design kernel extension

- Forget about BPF
- Think of clean abstract interface
  - A set of callbacks is an interface from kernel to kernel module (or BPF struct\_ops programs)
  - export\_symbol is an interface from kernel module back into the kernel
  - kfuncs is an equivalent for BPF programs
    - It's more tightly controlled due to type enforcement
- Register new ops
  - register\_bpf\_struct\_ops(&bpf\_tcp\_congestion\_ops, tcp\_congestion\_ops);

#### BPF mission

or why we're still passionate about this code

- To innovate
  - helpers, struct\_ops, kfuncs development satisfies our thirst for innovation
- To enable others to innovate
  - It's a joy to see how struct\_ops enabled hid-bpf and sched-ext
- To challenge what's possible
  - When everyone says "It's impossible" we reply "The whole thing maybe impossible, but this part is doable".