

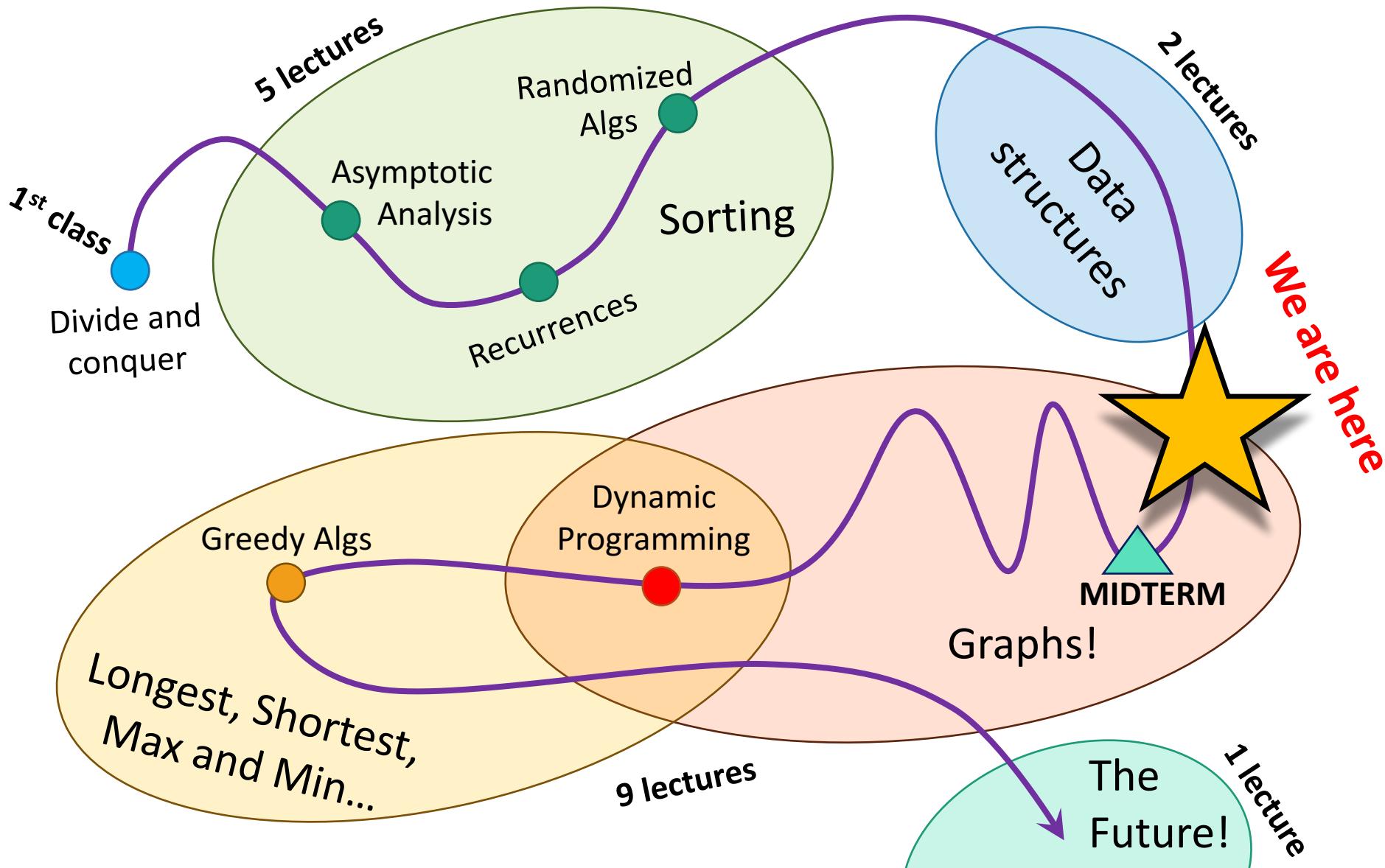
Lecture 9

Graphs, BFS and DFS

Announcements!

- HW4 due Friday
- **MIDTERM** in class, Monday 10/30.
 - That's 1 week from today. **Please show up.**
 - During class, 1:30-2:50
 - If your last name is A-M: 370-370 (here)
 - If your last name is N-V: 160-124
 - If your last name is W-Z: 160-323
 - You may bring one double-sided letter-size page of notes, that ***you have prepared yourself.***
- Any material through Hashing (Lecture 8) is fair game.
- Practice exams on the website
- Review Session tomorrow in Section

Roadmap

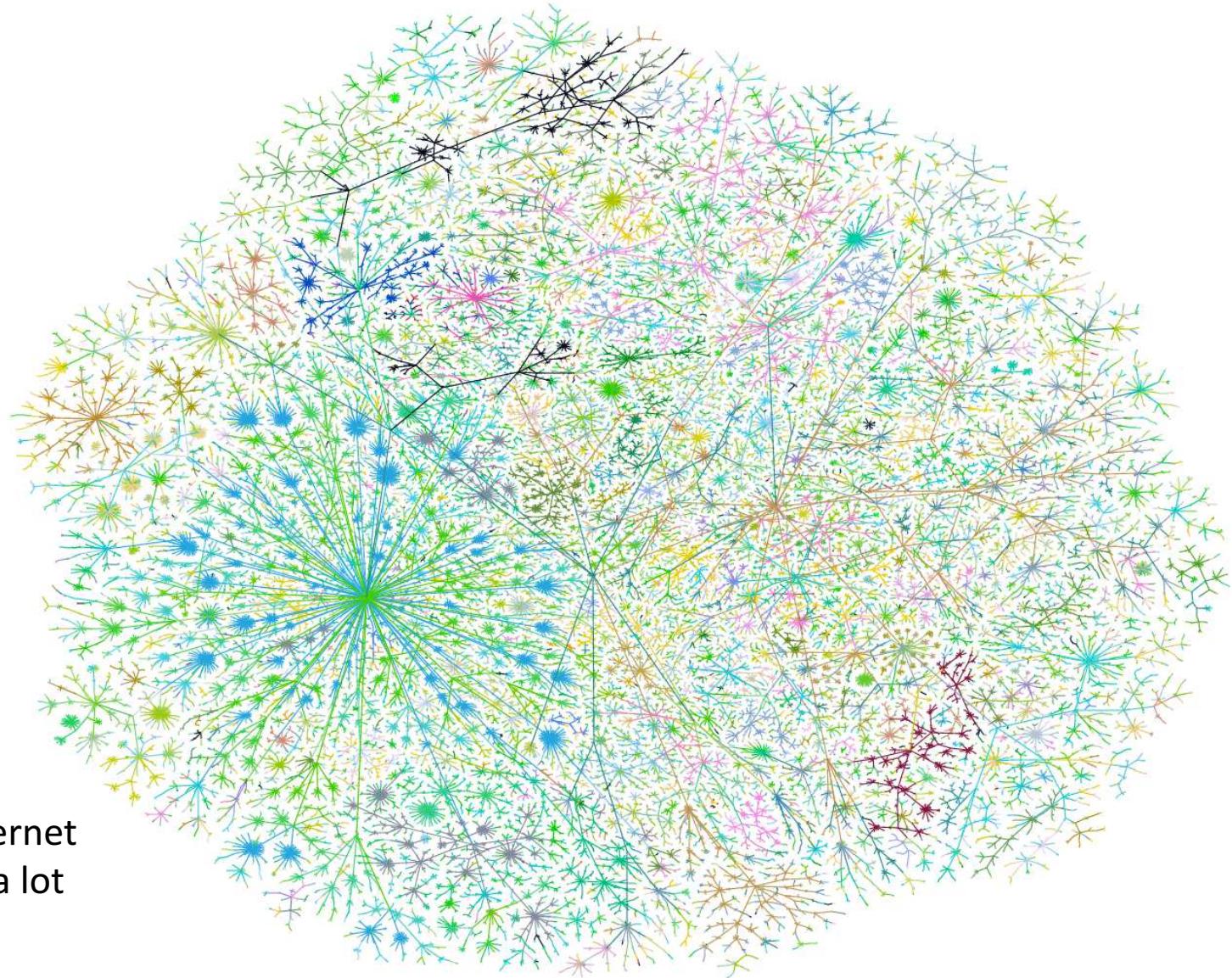


Outline

- Part 0: Graphs and terminology
- Part 1: Depth-first search
 - Application: topological sorting
 - Application: in-order traversal of BSTs
- Part 2: Breadth-first search
 - Application: shortest paths
 - Application (if time): is a graph bipartite?

Part 0: Graphs

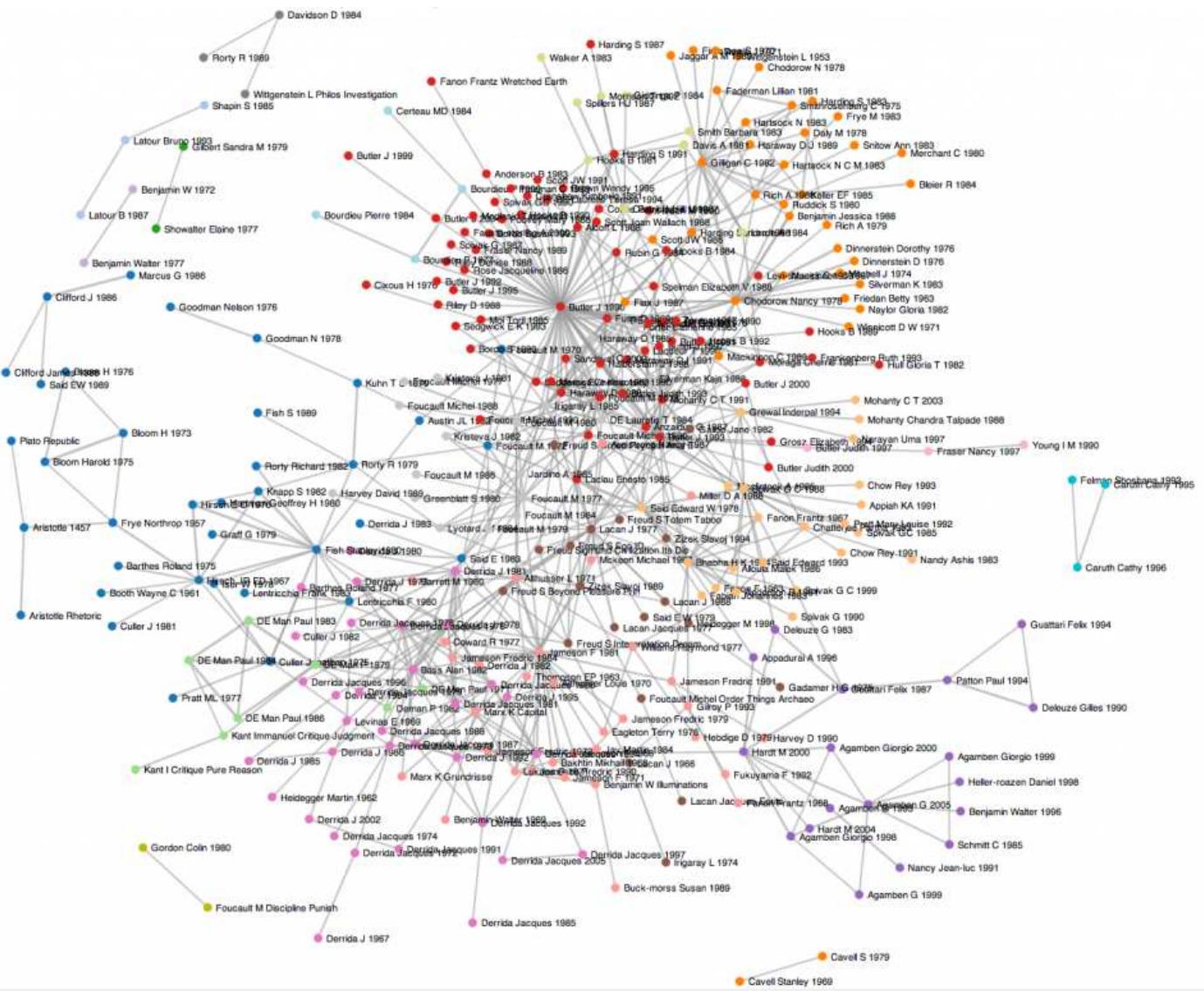
Graphs



Graph of the internet
(circa 1999...it's a lot
bigger now...)

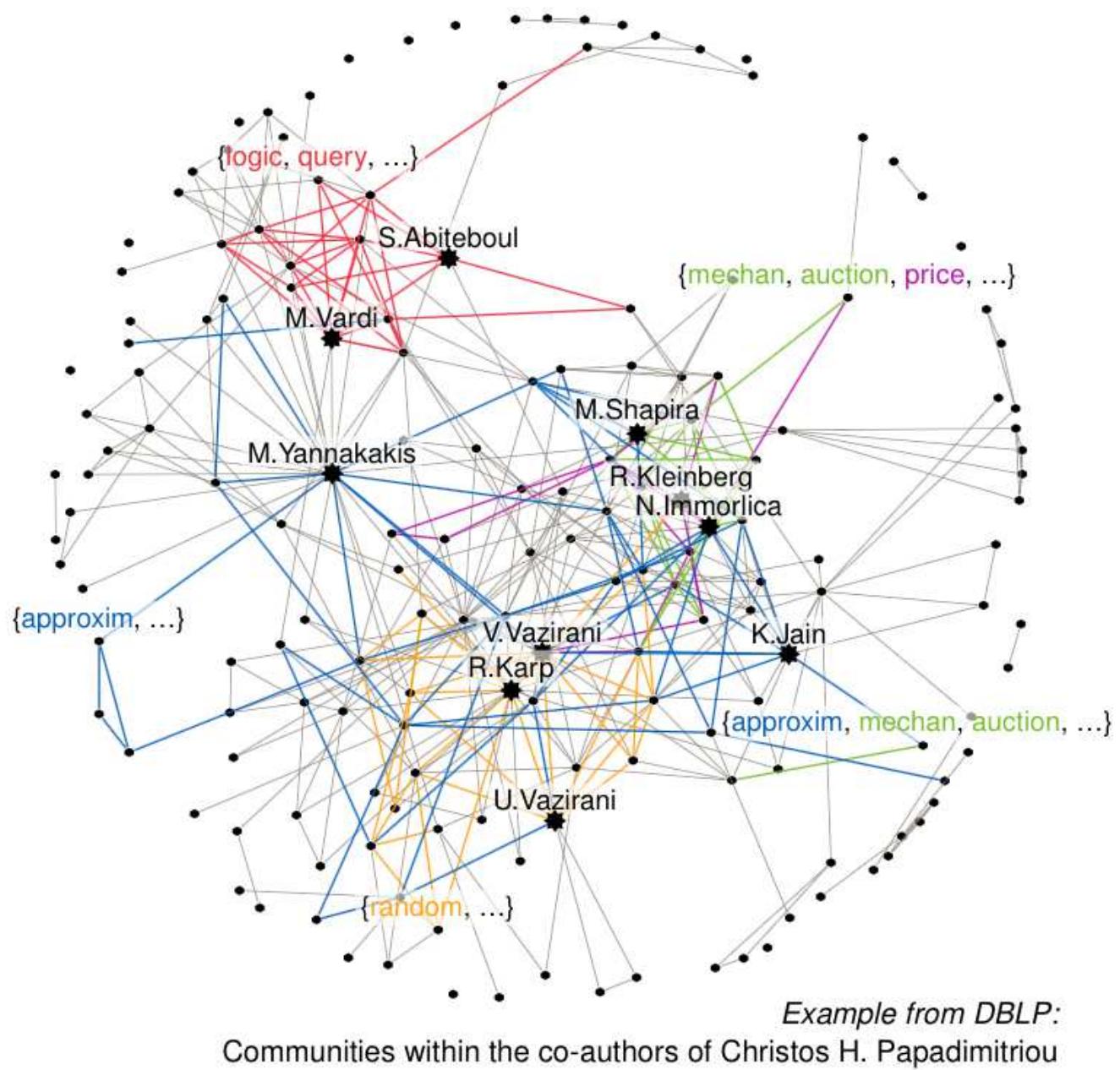
Graphs

Citation graph of literary theory academic papers



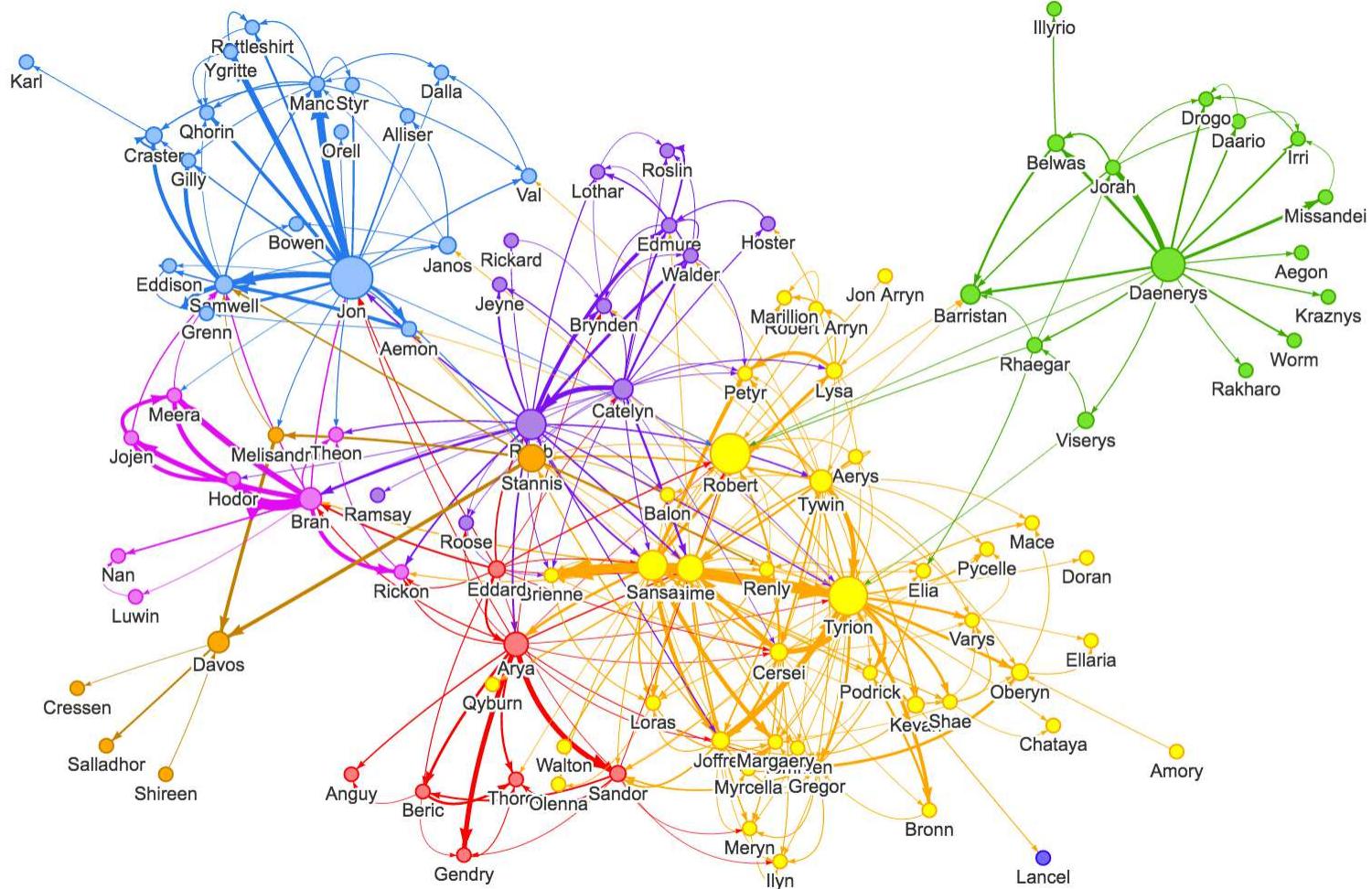
Graphs

Theoretical Computer
Science academic
communities



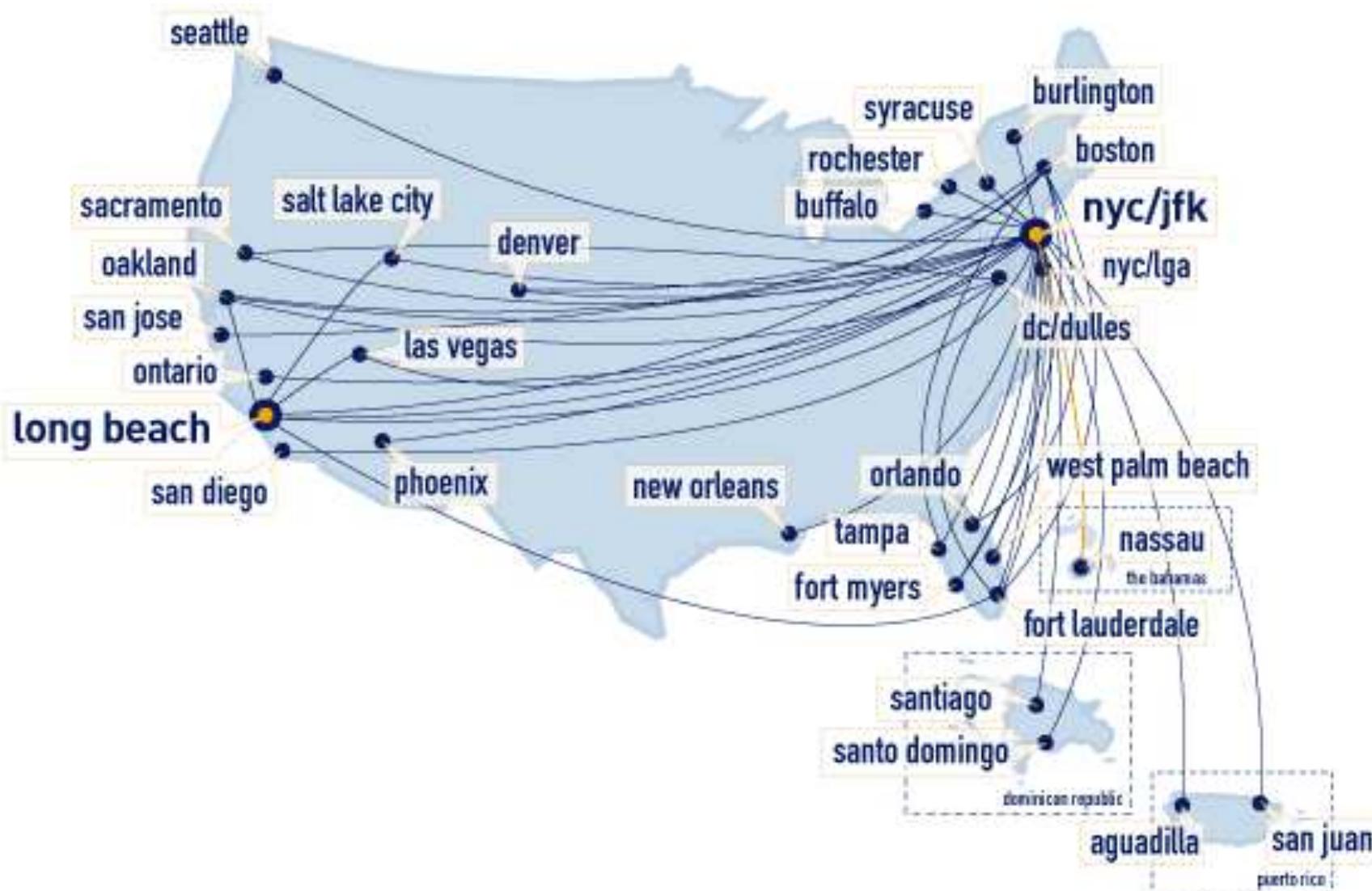
Graphs

Game of Thrones Character Interaction Network



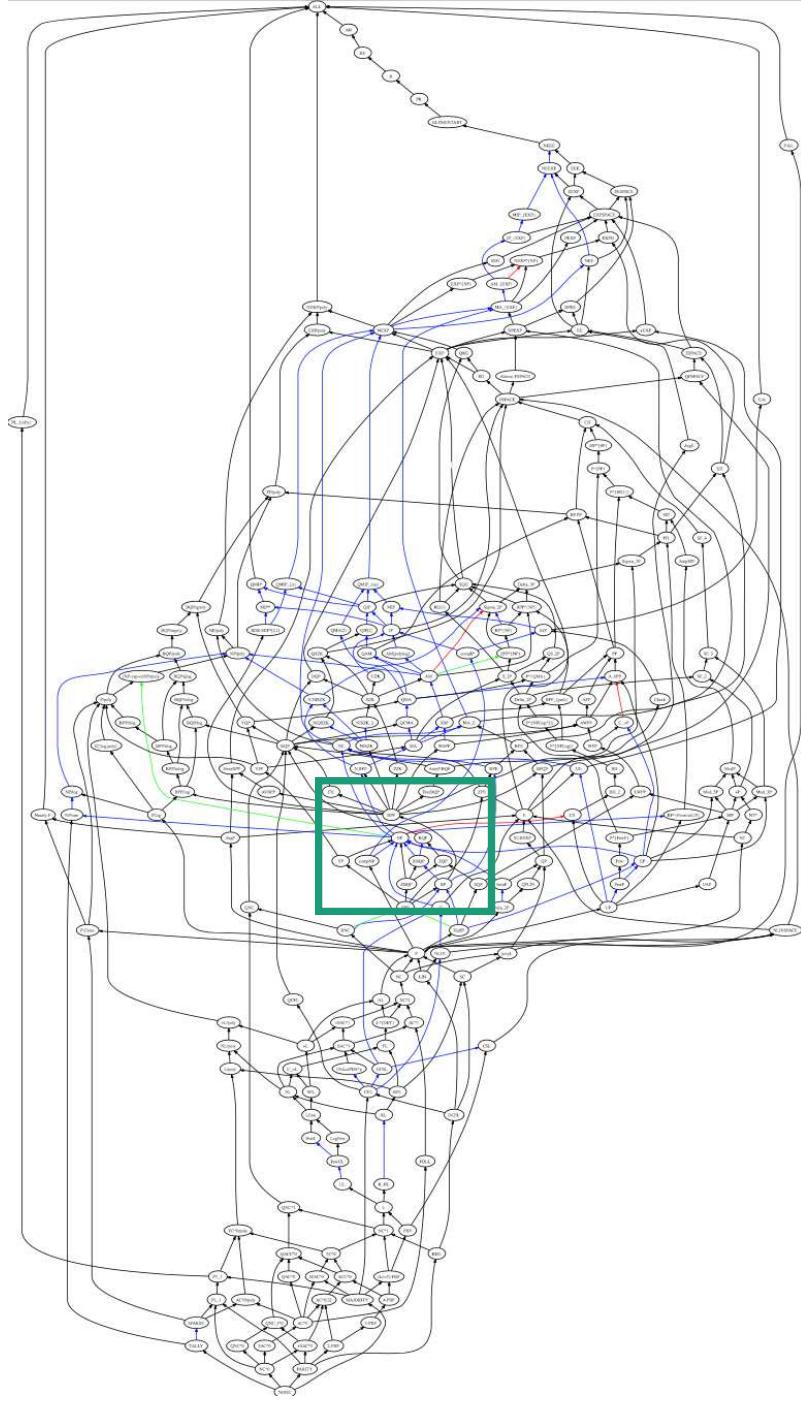
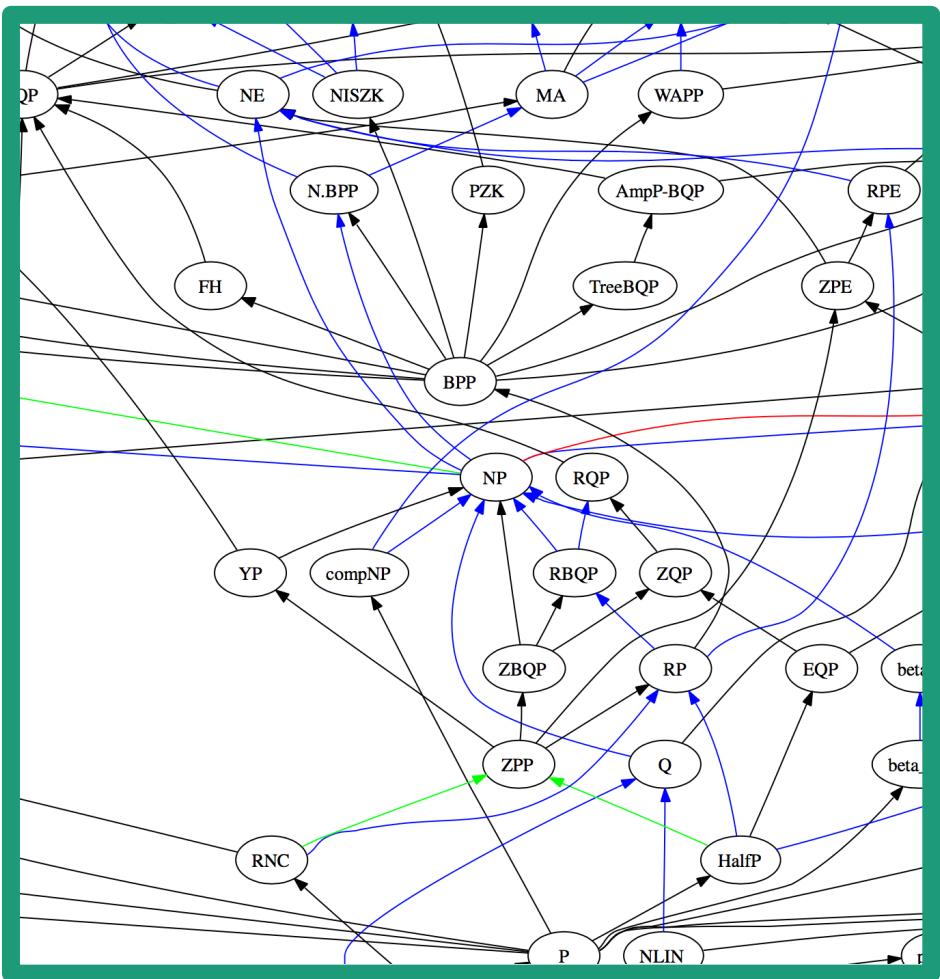
Graphs

jetblue flights



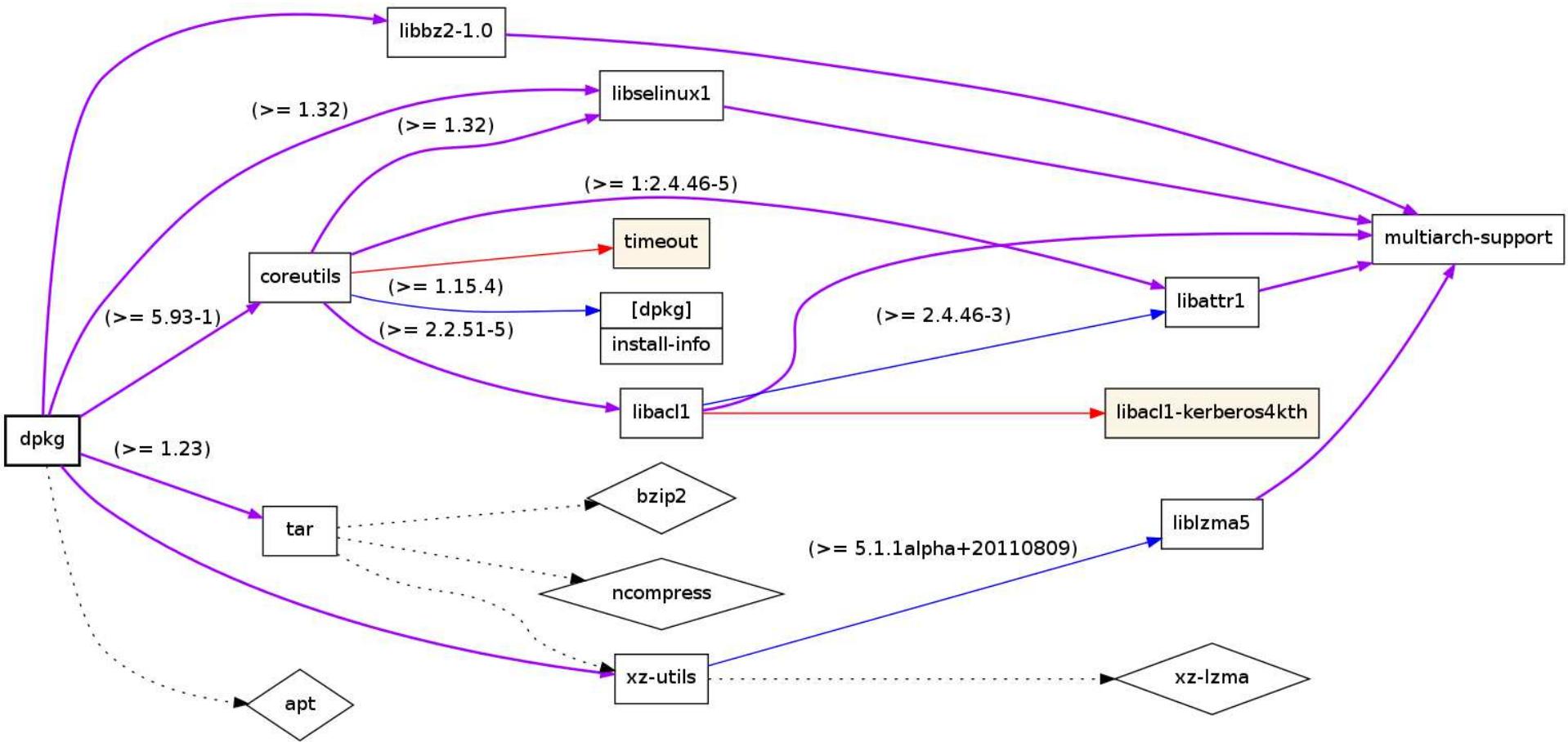
Graphs

Complexity Zoo
containment graph



Graphs

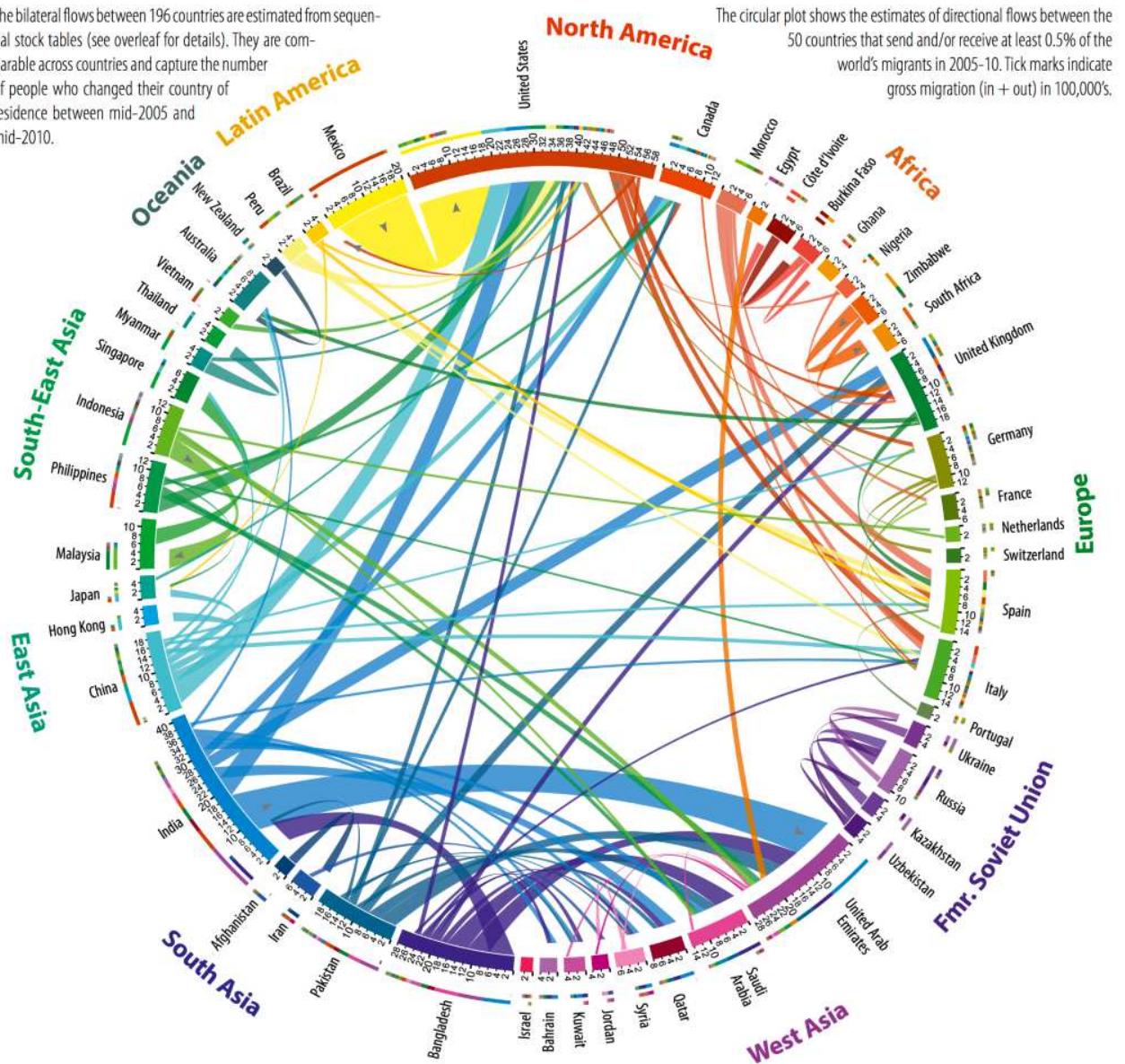
debian dependency (sub)graph



Graphs

Immigration flows

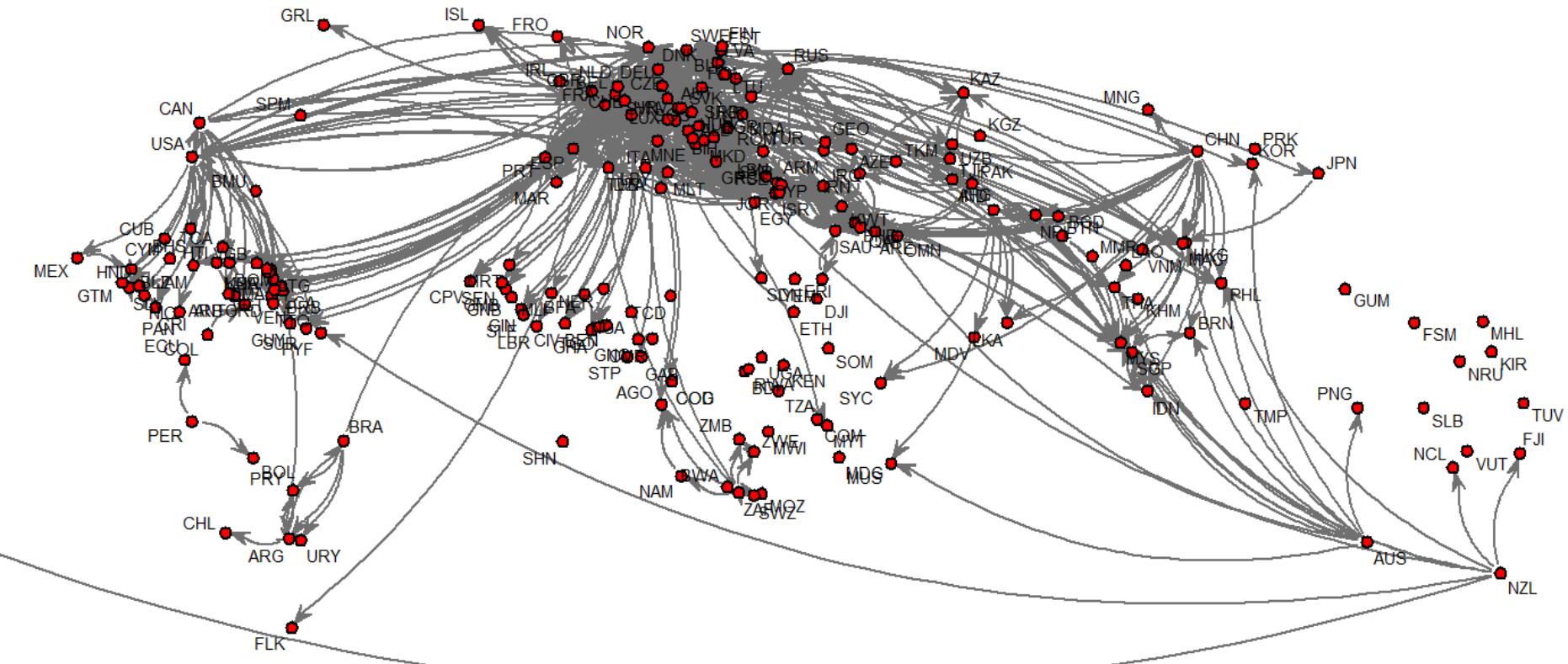
The bilateral flows between 196 countries are estimated from sequential stock tables (see overleaf for details). They are comparable across countries and capture the number of people who changed their country of residence between mid-2005 and mid-2010.



Graphs

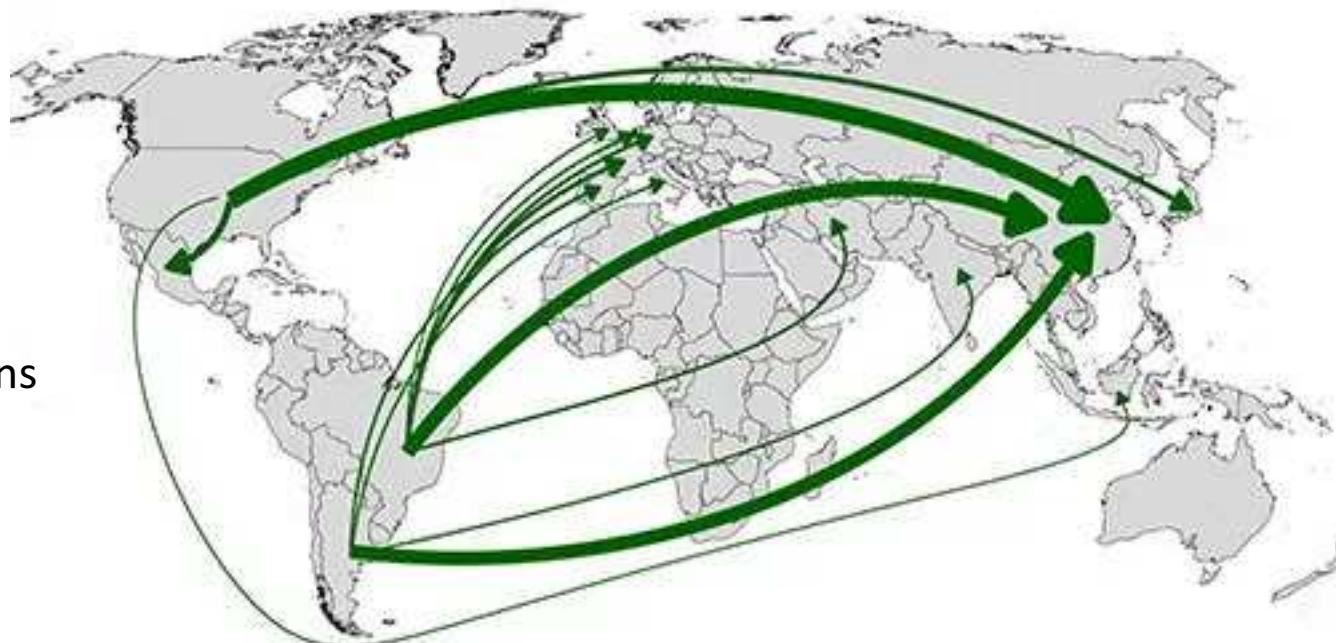
Potato trade

World trade in fresh potatoes, flows over 0.1 m US\$ average 2005-2009

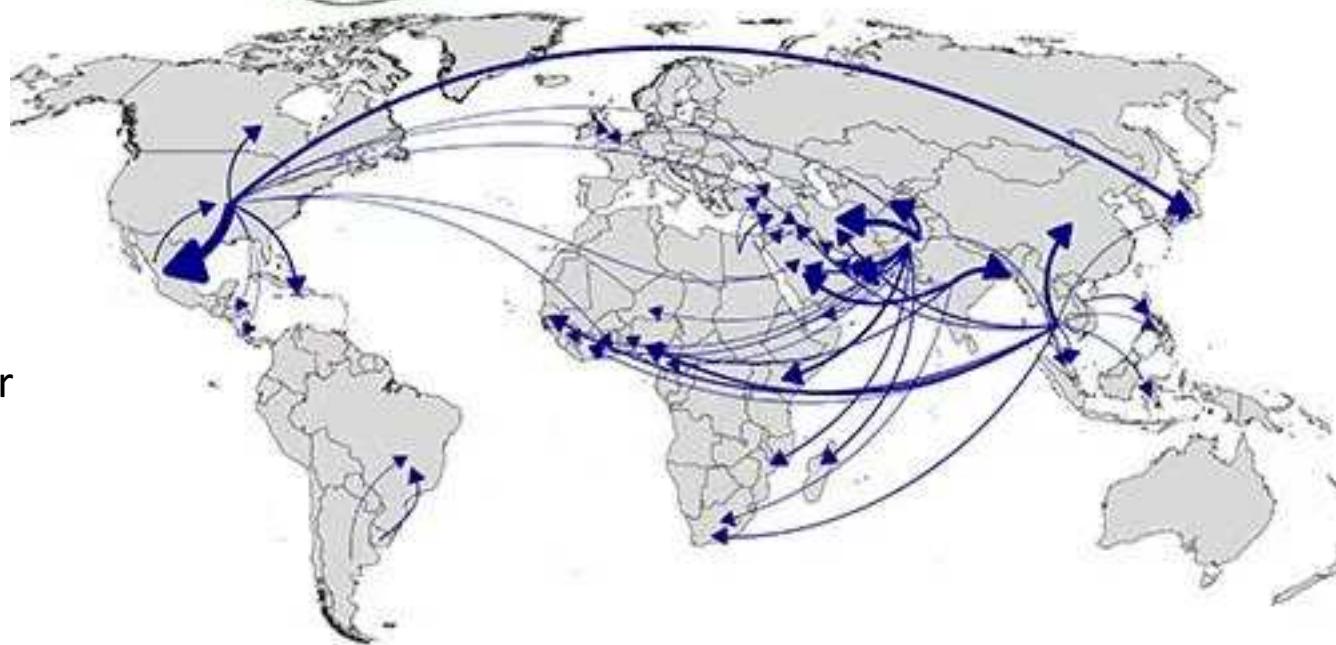


Graphs

Soybeans

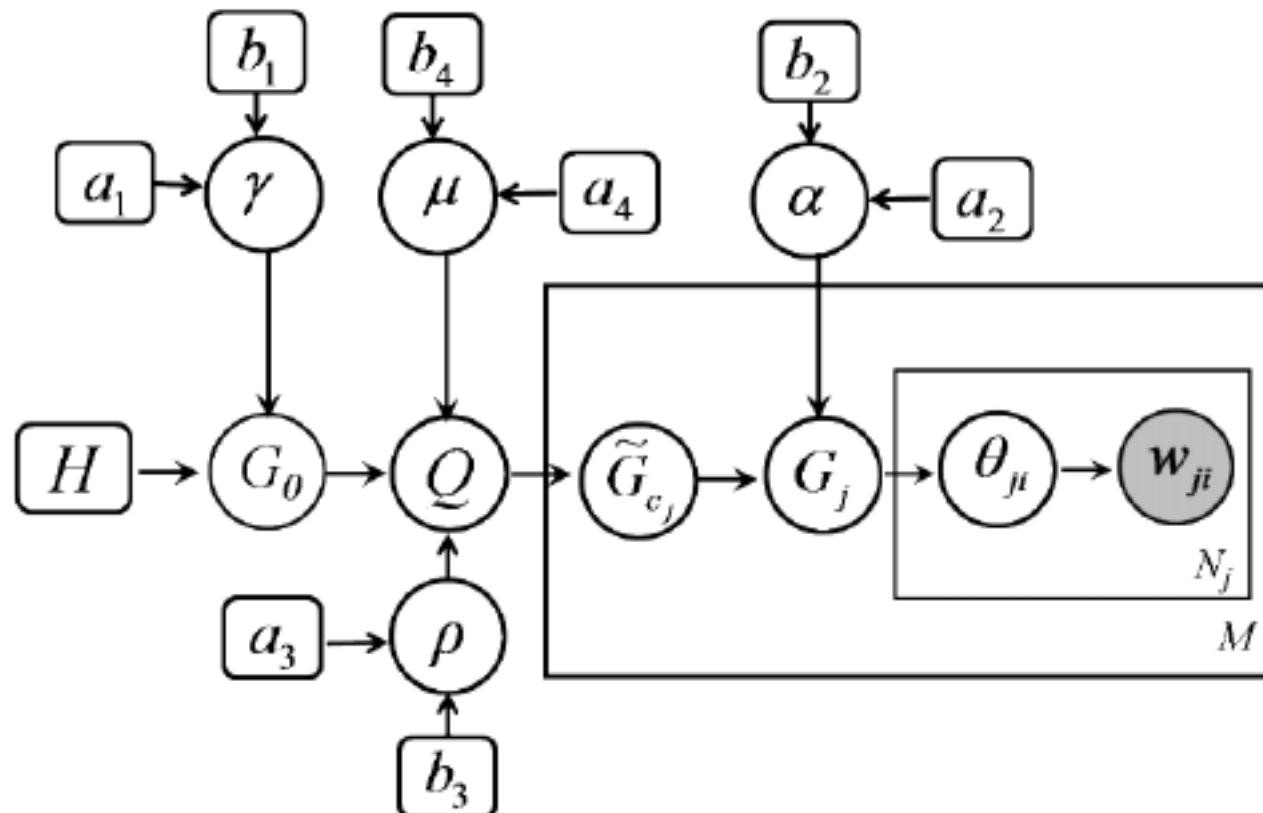


Water



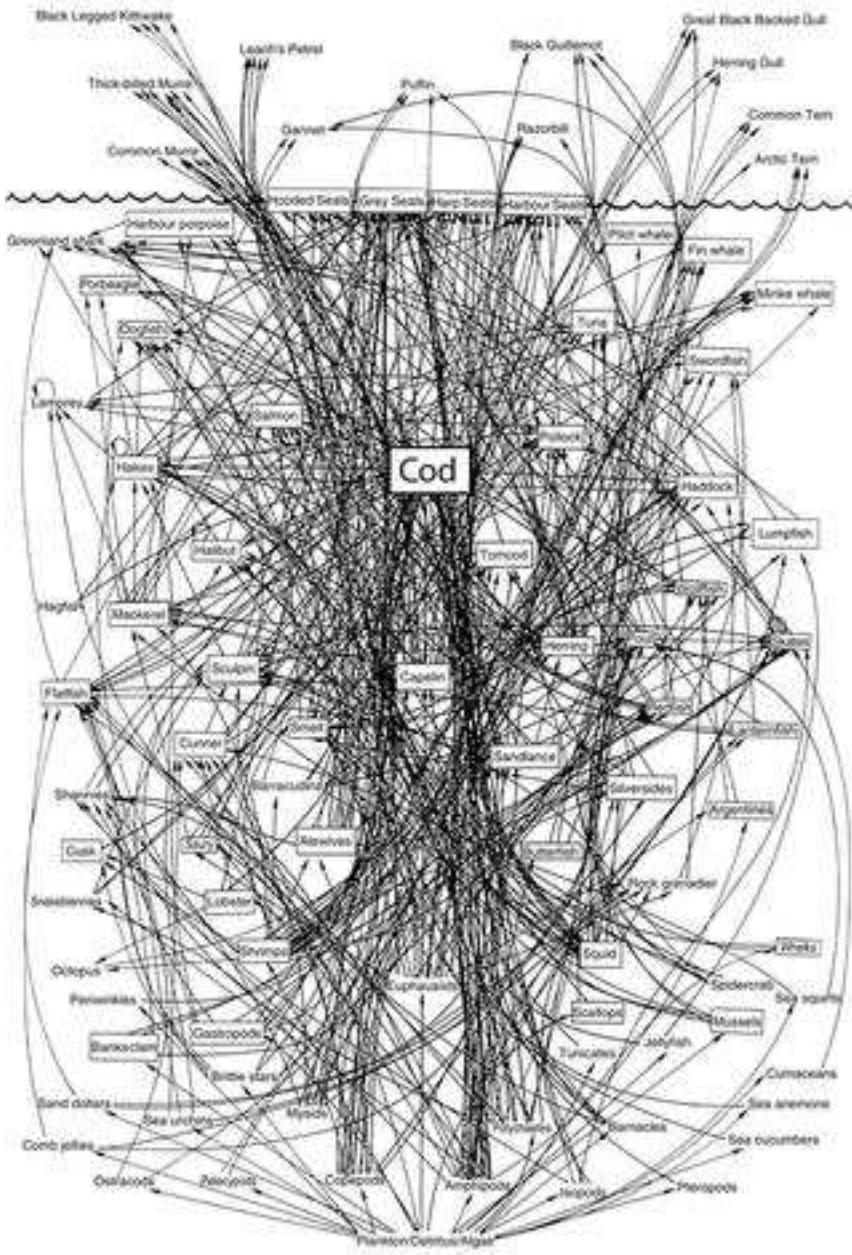
Graphs

Graphical models



Graphs

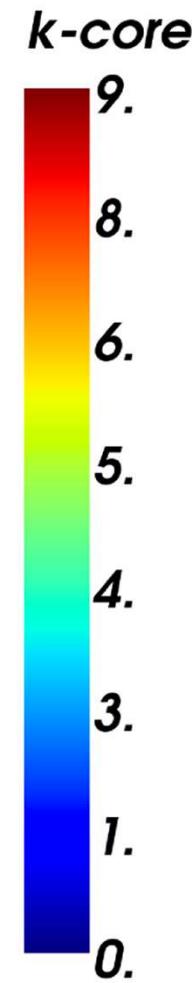
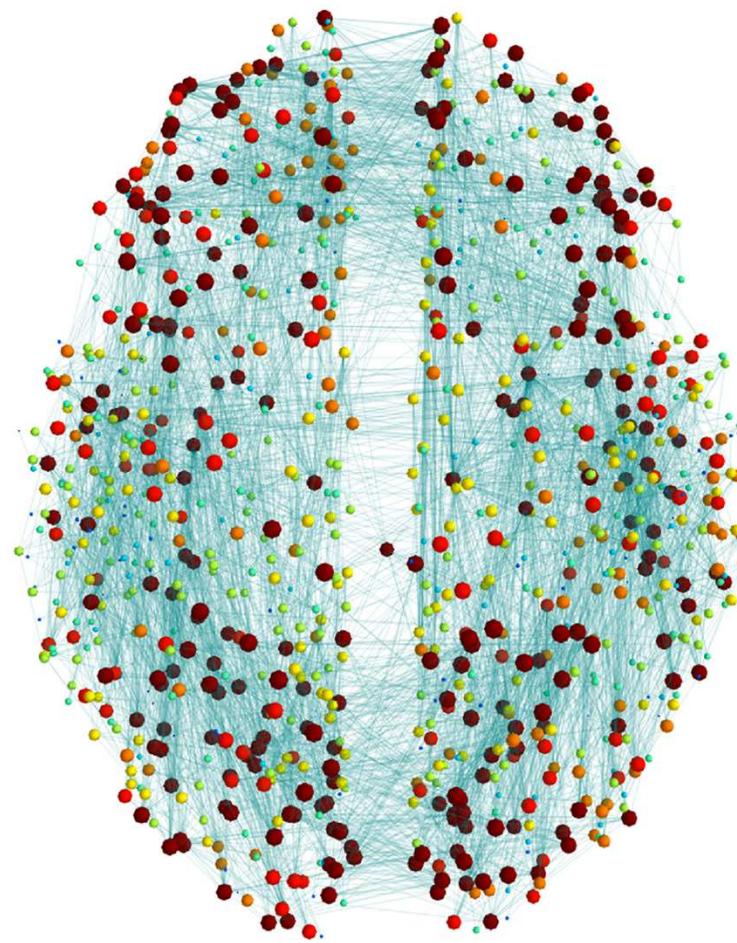
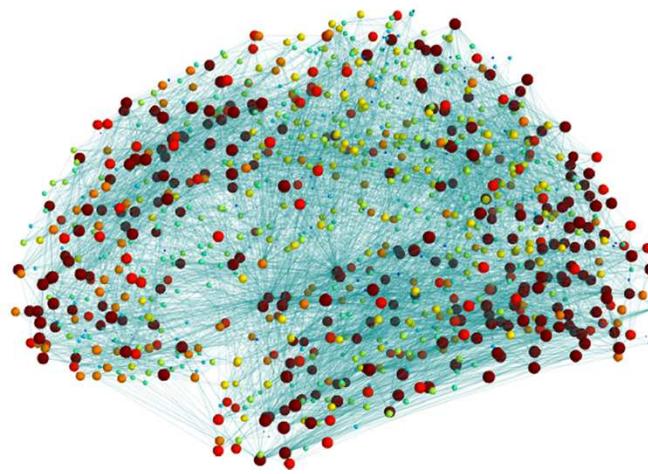
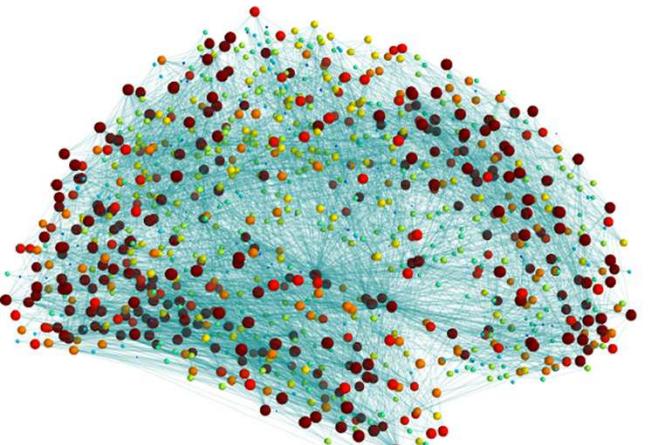
What eats what in
the Atlantic ocean?



A simplified food web for the Northwest Atlantic. © IMMA

Graphs

Neural connections
in the brain



Graphs

- There are a lot of graphs.
- We want to answer questions about them.
 - Efficient routing?
 - Community detection/clustering?
 - From pre-lecture exercise:
 - Computing Bacon numbers
 - Signing up for classes without violating pre-req constraints
 - How to distribute fish in tanks so that none of them will fight.
- This is what we'll do for the next several lectures.

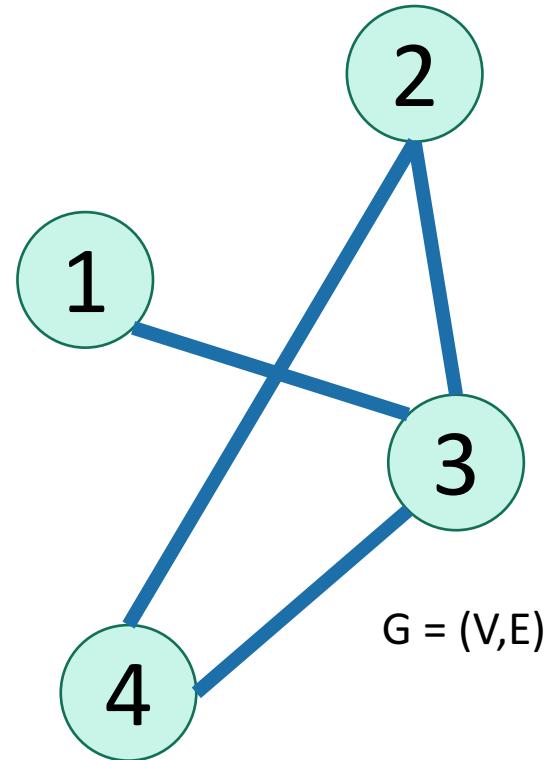
Undirected Graphs

- Has **vertices** and **edges**

- V is the set of vertices
- E is the set of edges
- Formally, a graph is $G = (V, E)$

- Example

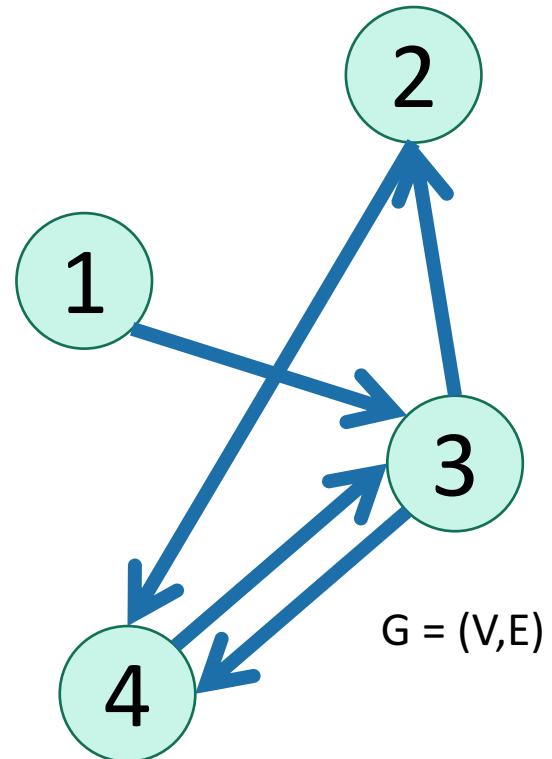
- $V = \{1, 2, 3, 4\}$
- $E = \{ \{1, 3\}, \{2, 4\}, \{3, 4\}, \{2, 3\} \}$



- The **degree** of vertex 4 is 2.
 - There are 2 edges coming out
- Vertex 4's **neighbors** are 2 and 3

Directed Graphs

- Has **vertices** and **edges**
 - V is the set of vertices
 - E is the set of **DIRECTED** edges
 - Formally, a graph is $G = (V, E)$
- Example
 - $V = \{1, 2, 3, 4\}$
 - $E = \{ (1, 3), (2, 4), (3, 4), (4, 3), (3, 2) \}$

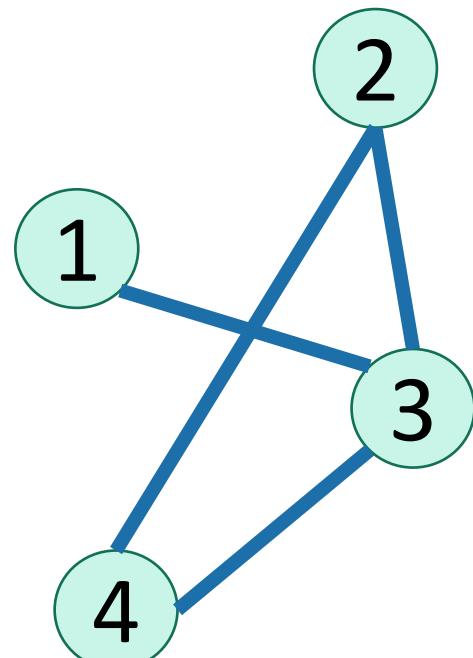


- The **in-degree** of vertex 4 is 2.
- The **out-degree** of vertex 4 is 1.
- Vertex 4's **incoming neighbors** are 2, 3.
- Vertex 4's **outgoing neighbor** is 3.

How do we represent graphs?

- Option 1: adjacency matrix

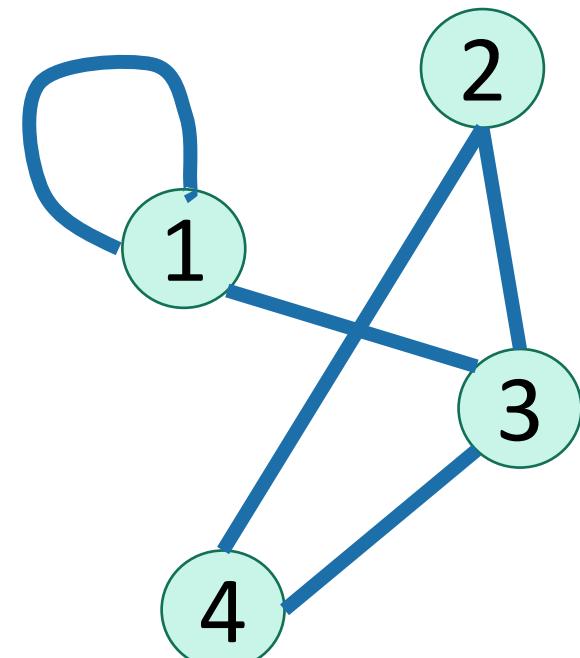
$$\begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix} \end{matrix}$$



How do we represent graphs?

- Option 1: adjacency matrix

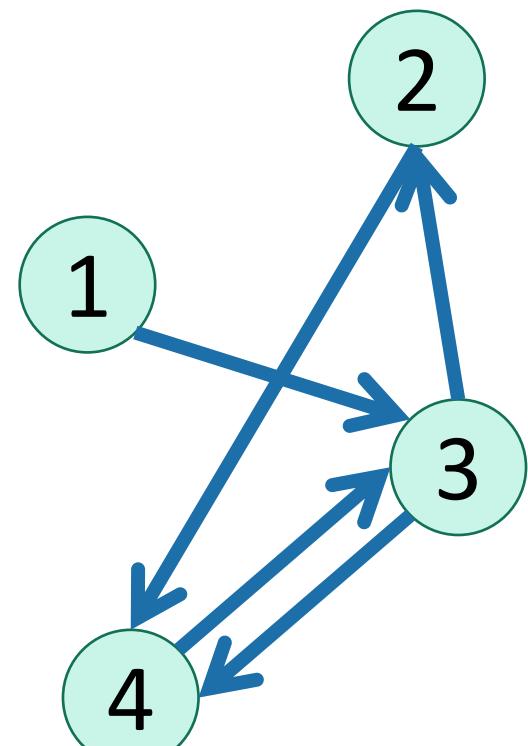
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How do we represent graphs?

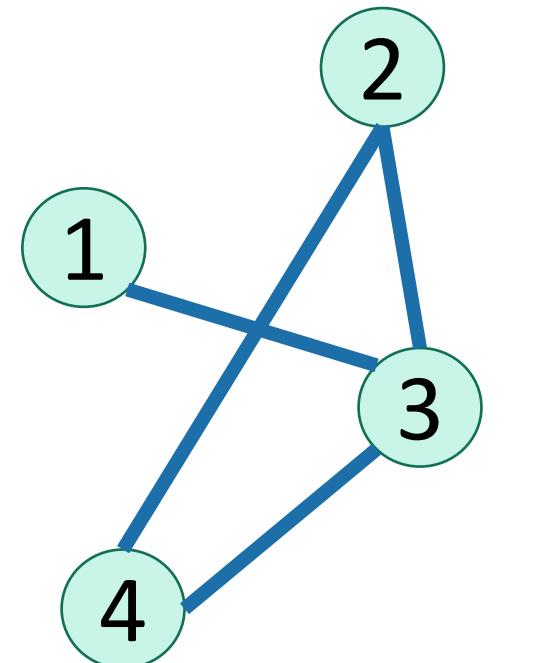
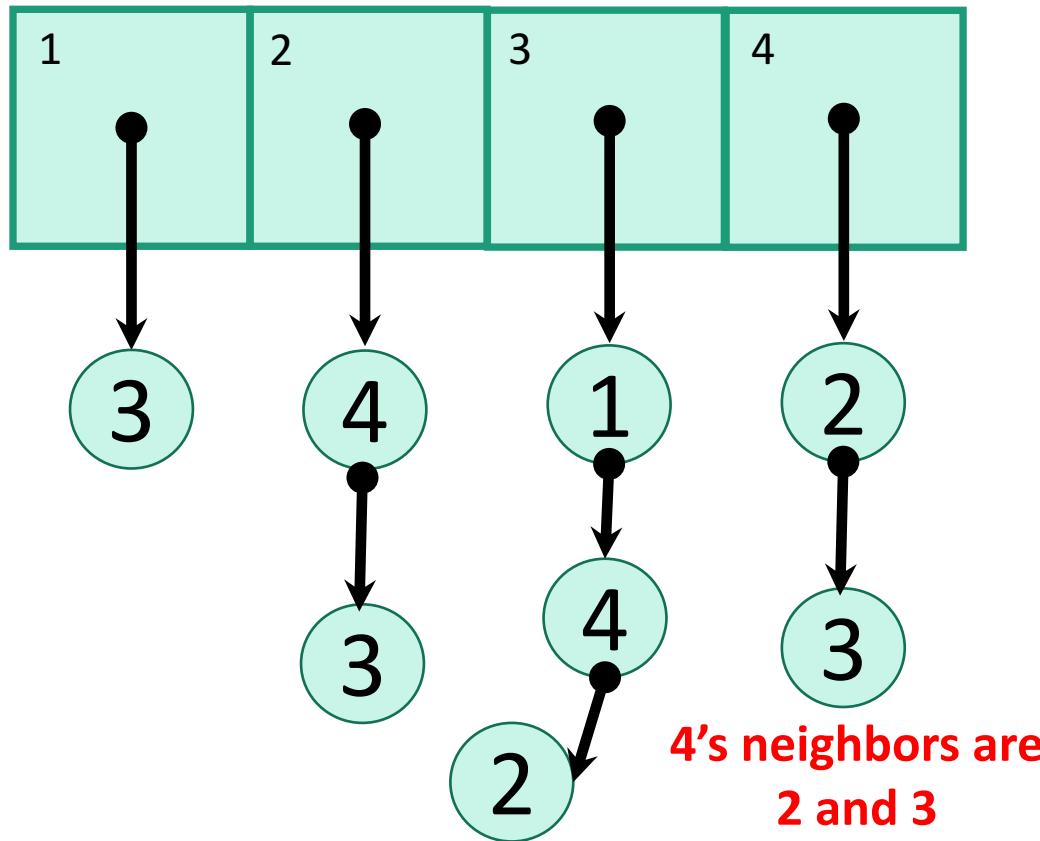
- Option 1: adjacency matrix

Destination					
		1	2	3	4
Source	1	0	0	1	0
	2	0	0	0	1
	3	0	1	0	1
	4	0	0	1	0

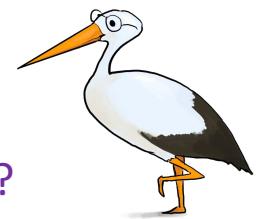


How do we represent graphs?

- Option 2: linked lists.



How would you
modify this for
directed graphs?



In either case

- Vertices can store other information
 - Attributes (name, IP address, ...)
 - helper info for algorithms that we will perform on the graph
- Want to be able to do the following operations:
 - **Edge Membership:** Is edge e in E?
 - **Neighbor Query:** What are the neighbors of vertex v?

Trade-offs

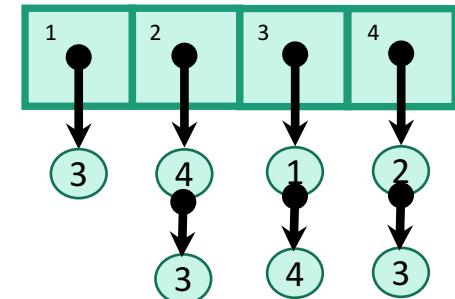
Say there are n vertices
and m edges.

$$\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

Edge membership
Is $e = \{v,w\}$ in E ?

$O(1)$

Generally better
for sparse graphs



Neighbor query
Give me v 's neighbors.

$O(n)$

$O(\deg(v))$

Space requirements

$O(n^2)$

$O(n + m)$

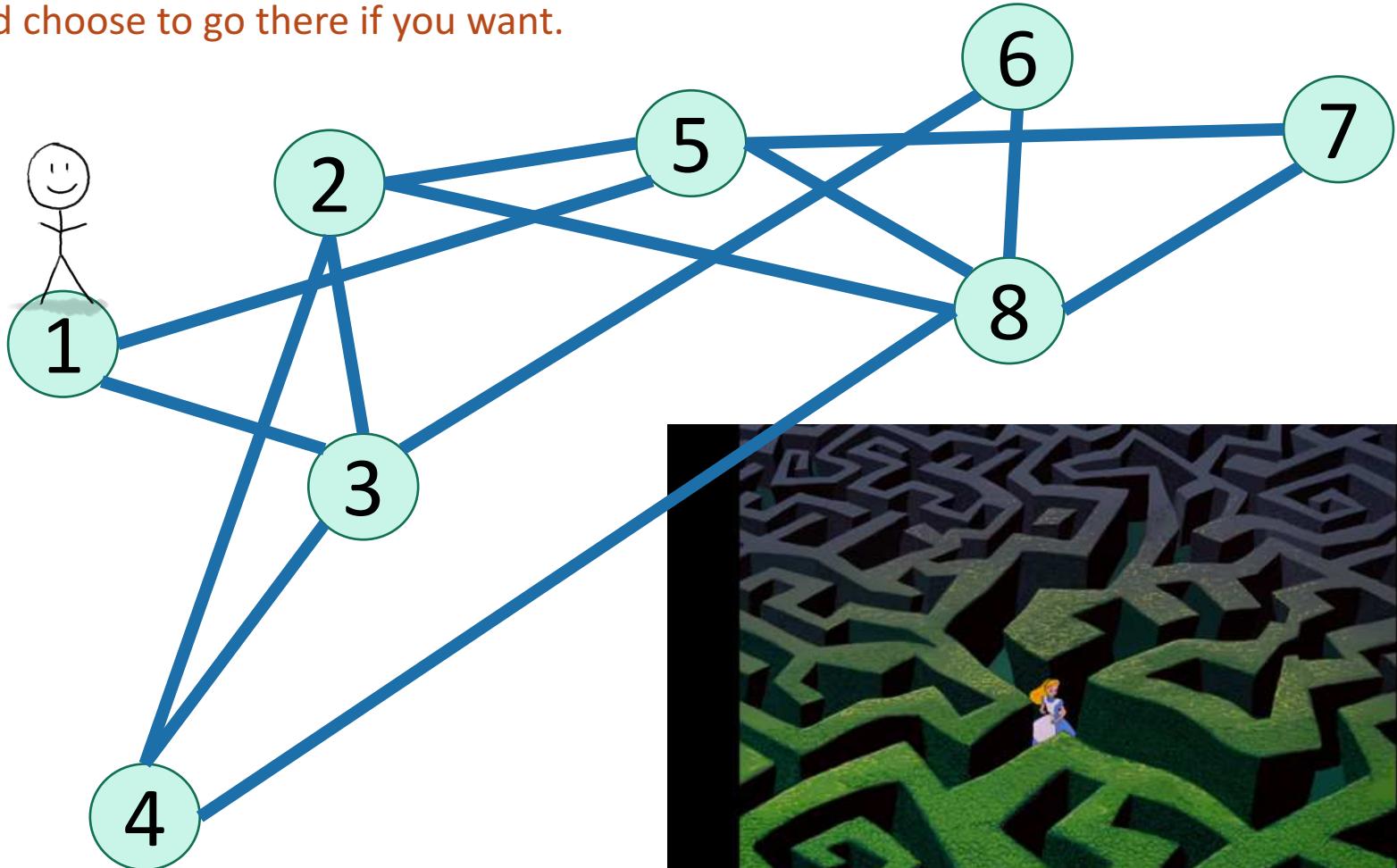
See Lecture 9 IPython notebook for the actual
data structure that we will be using!

We'll assume this
representation for
the rest of the class

Part 1: Depth-first search

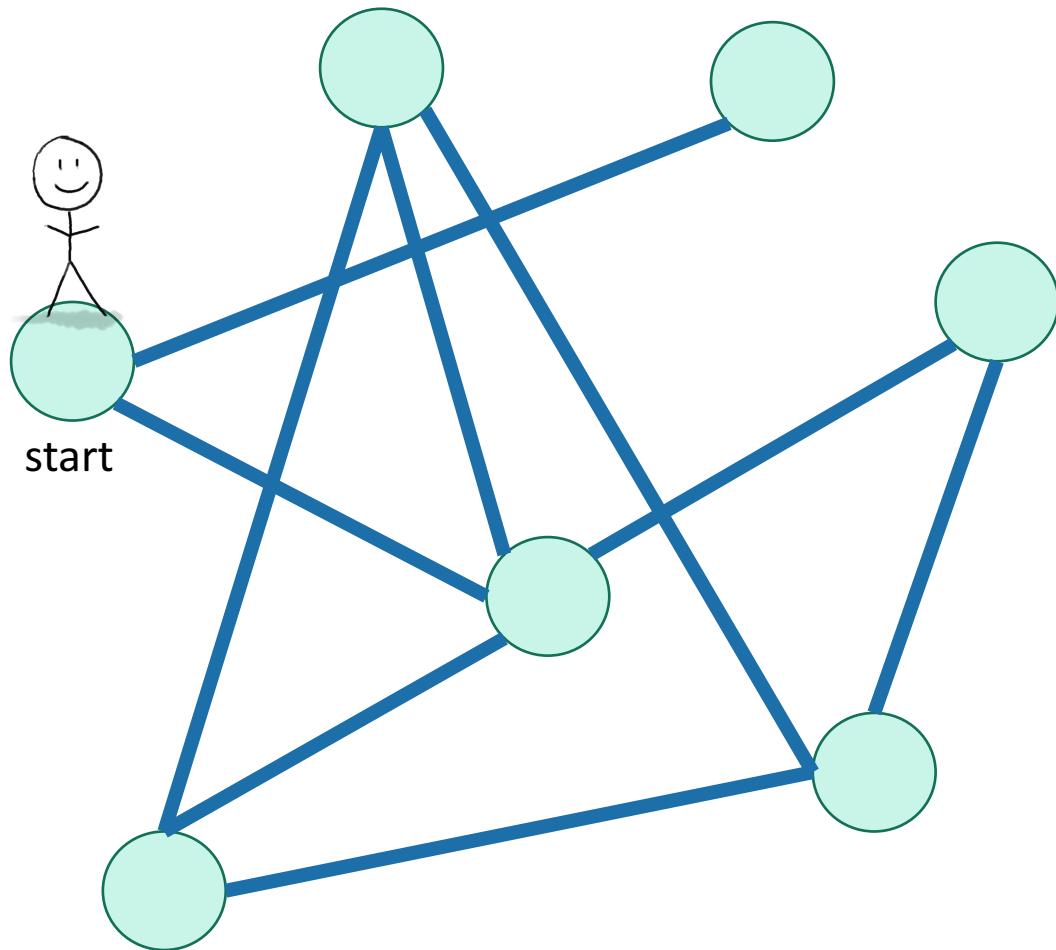
How do we explore a graph?

At each node, you can get a list of neighbors,
and choose to go there if you want.



Depth First Search

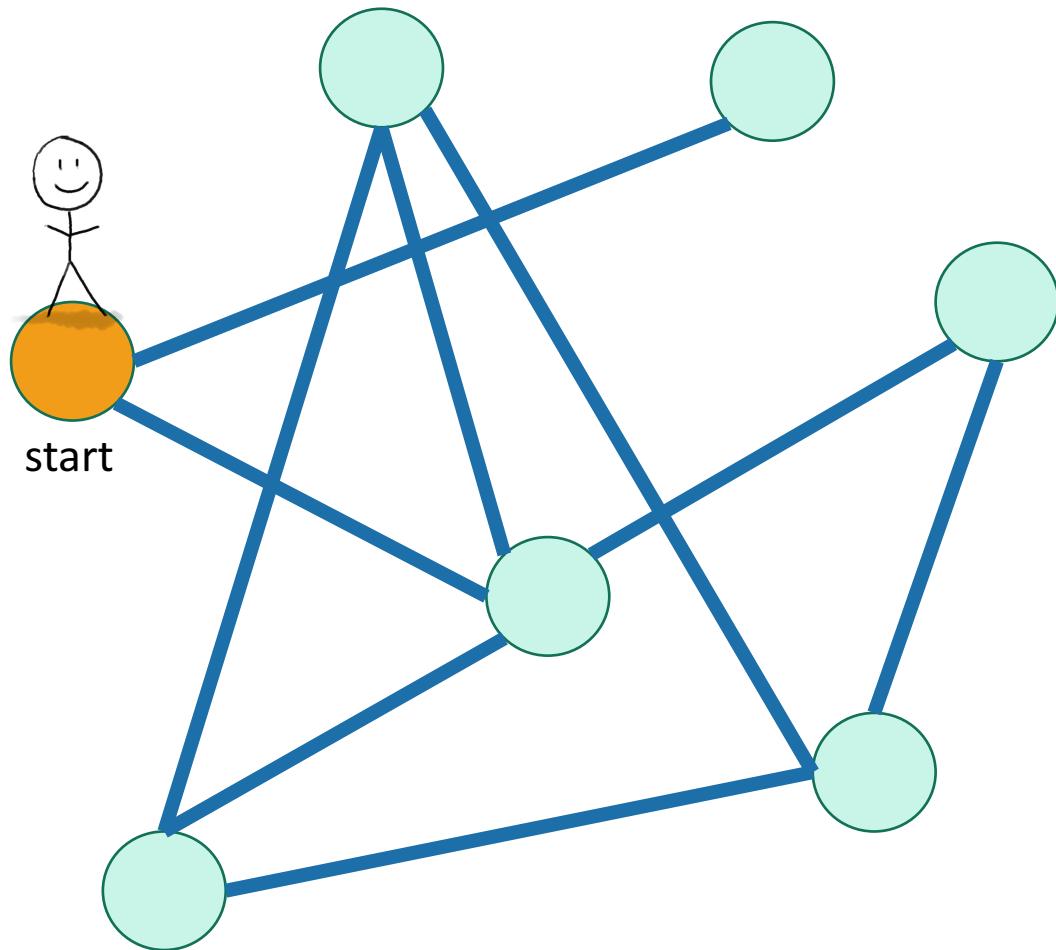
Exploring a labyrinth with chalk and a piece of string



- Not been there yet
- Been there, haven't explored all the paths out.
- Been there, have explored all the paths out.

Depth First Search

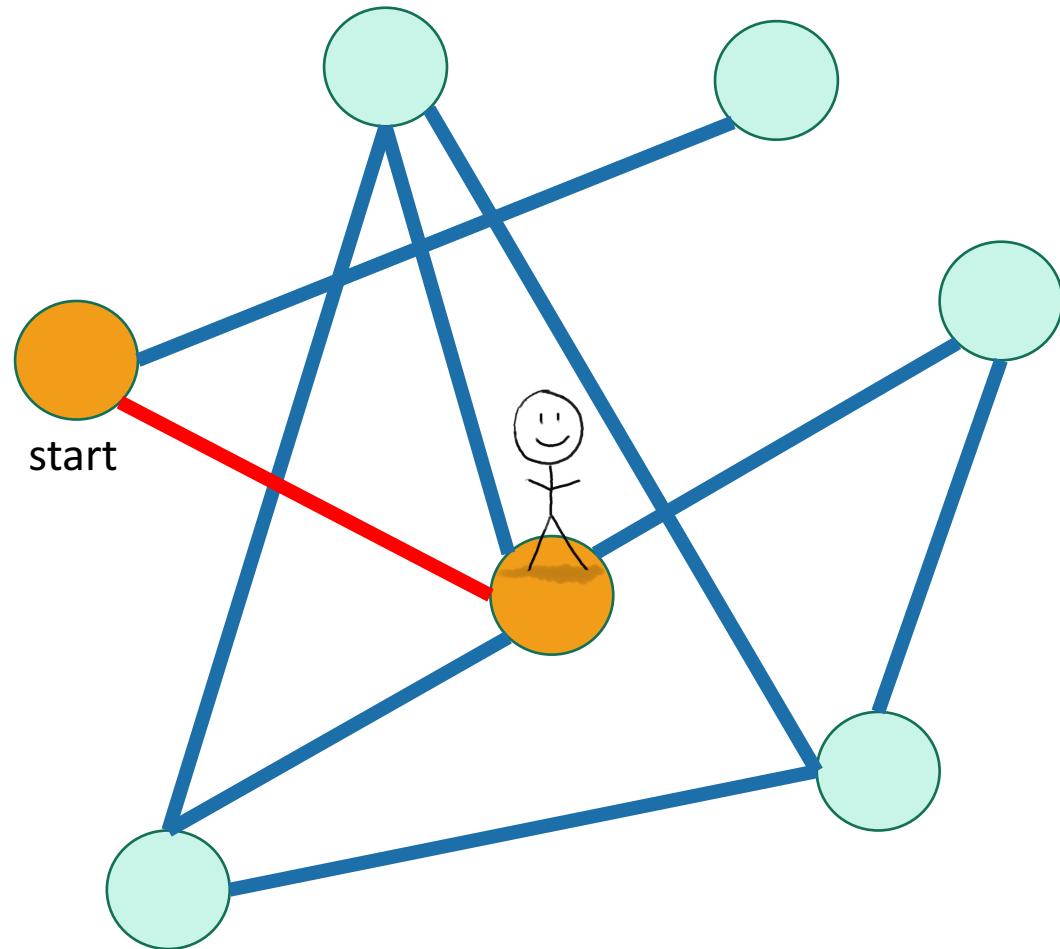
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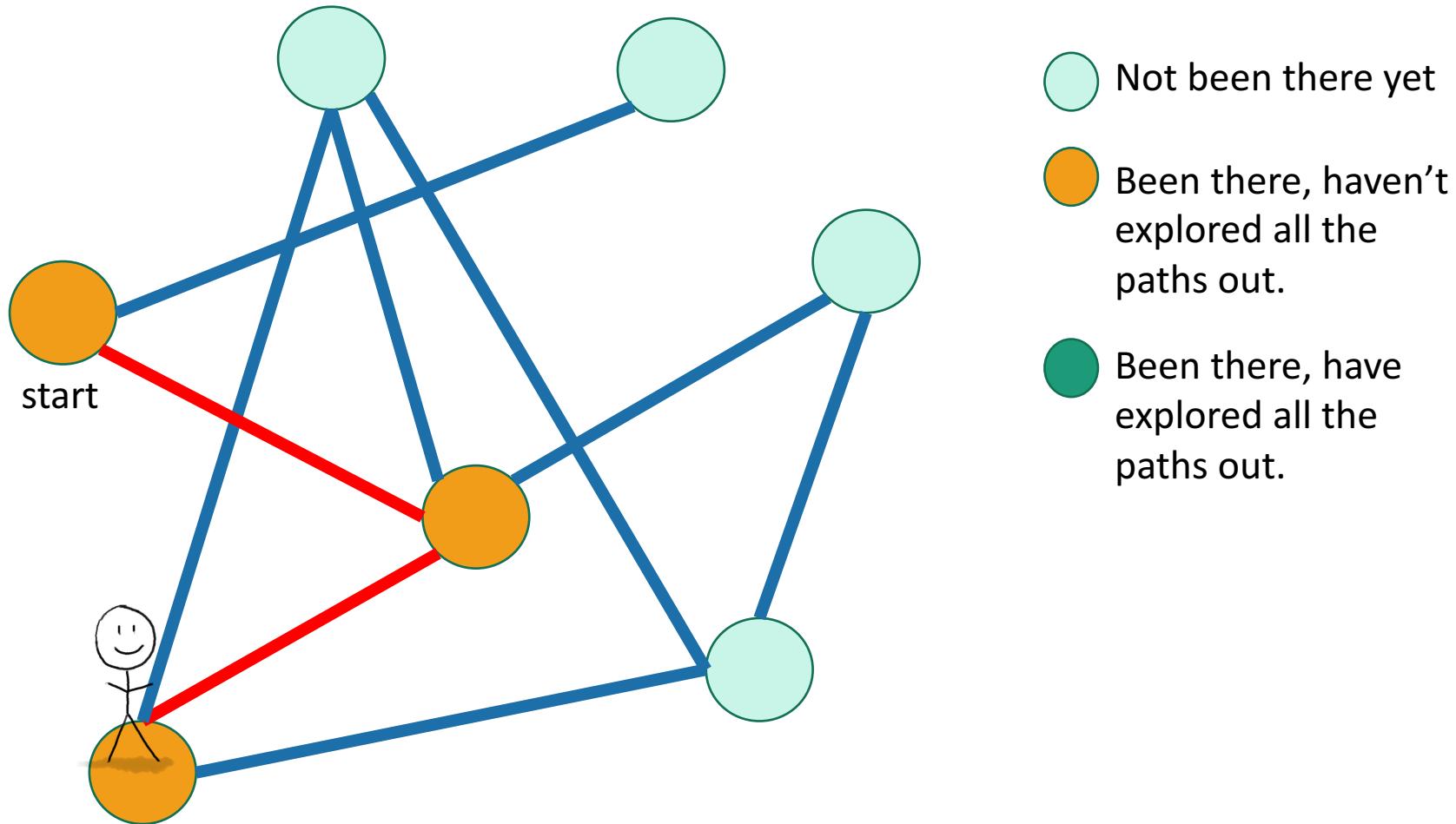
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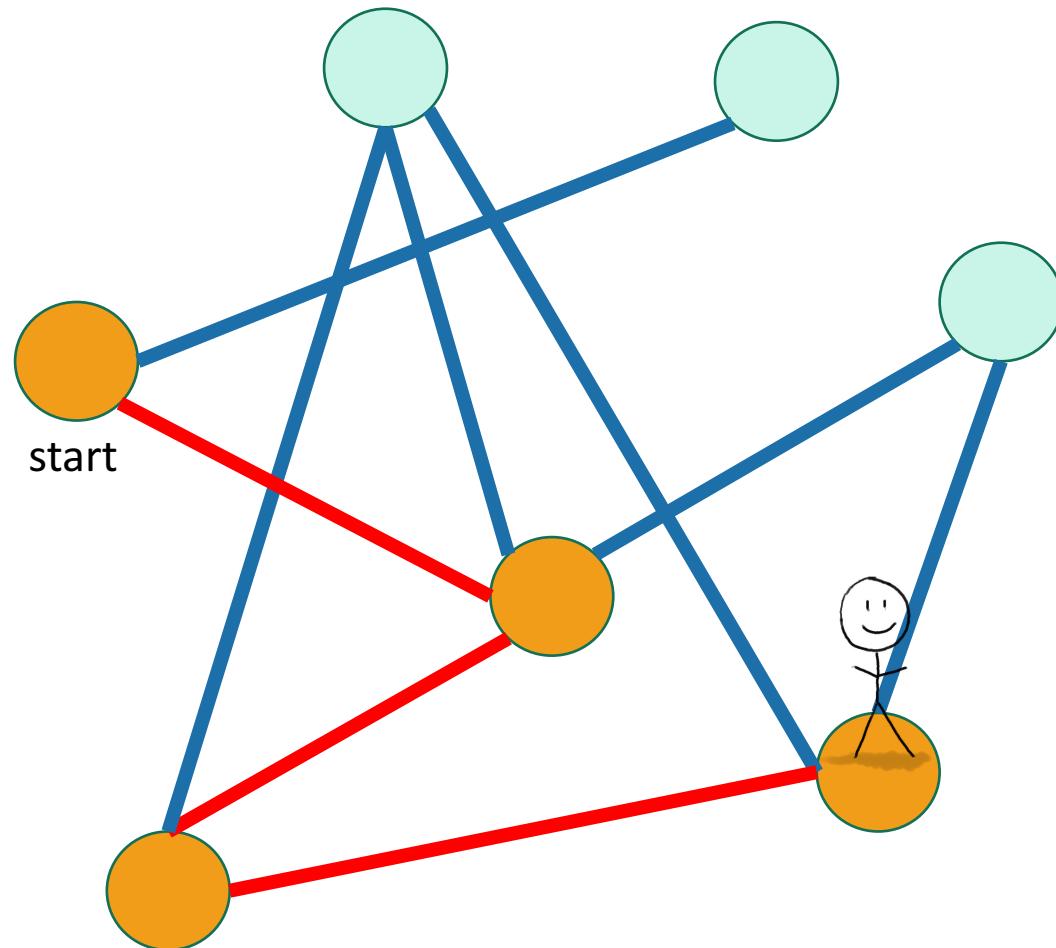
Depth First Search

Exploring a labyrinth with chalk and a piece of string



Depth First Search

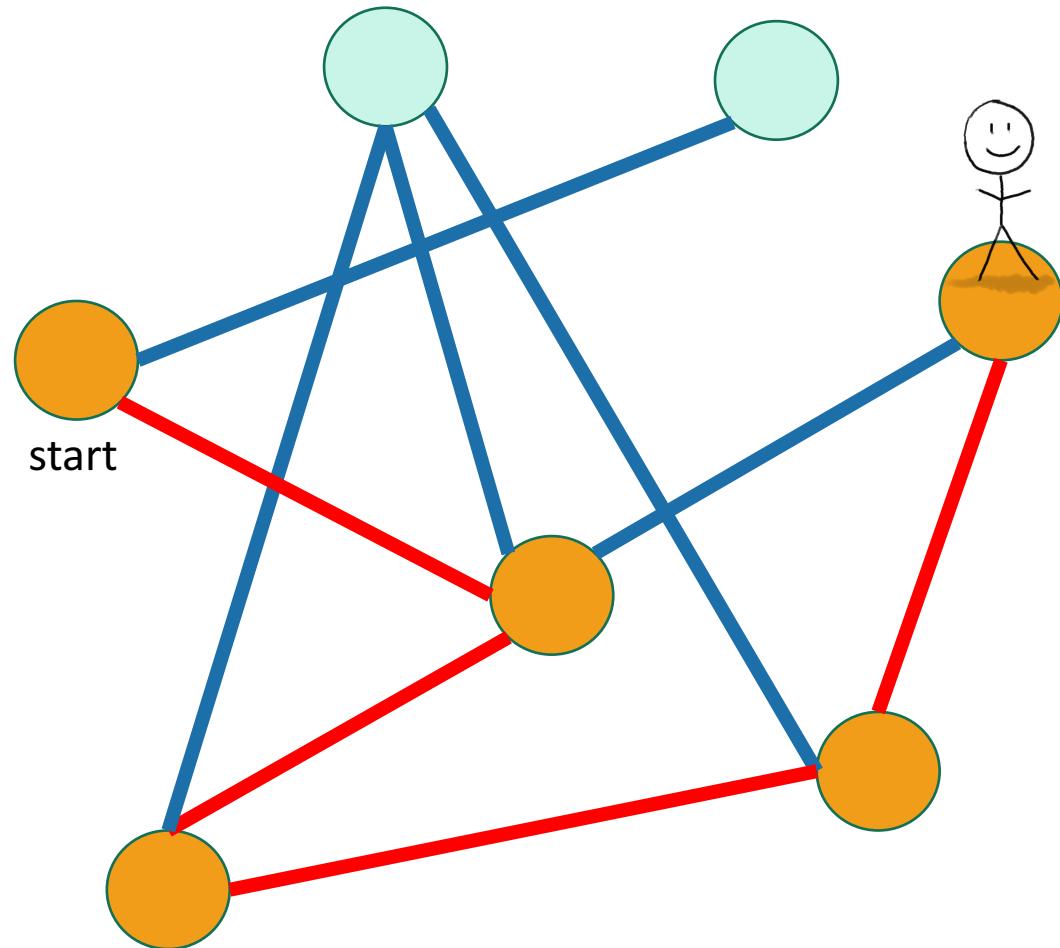
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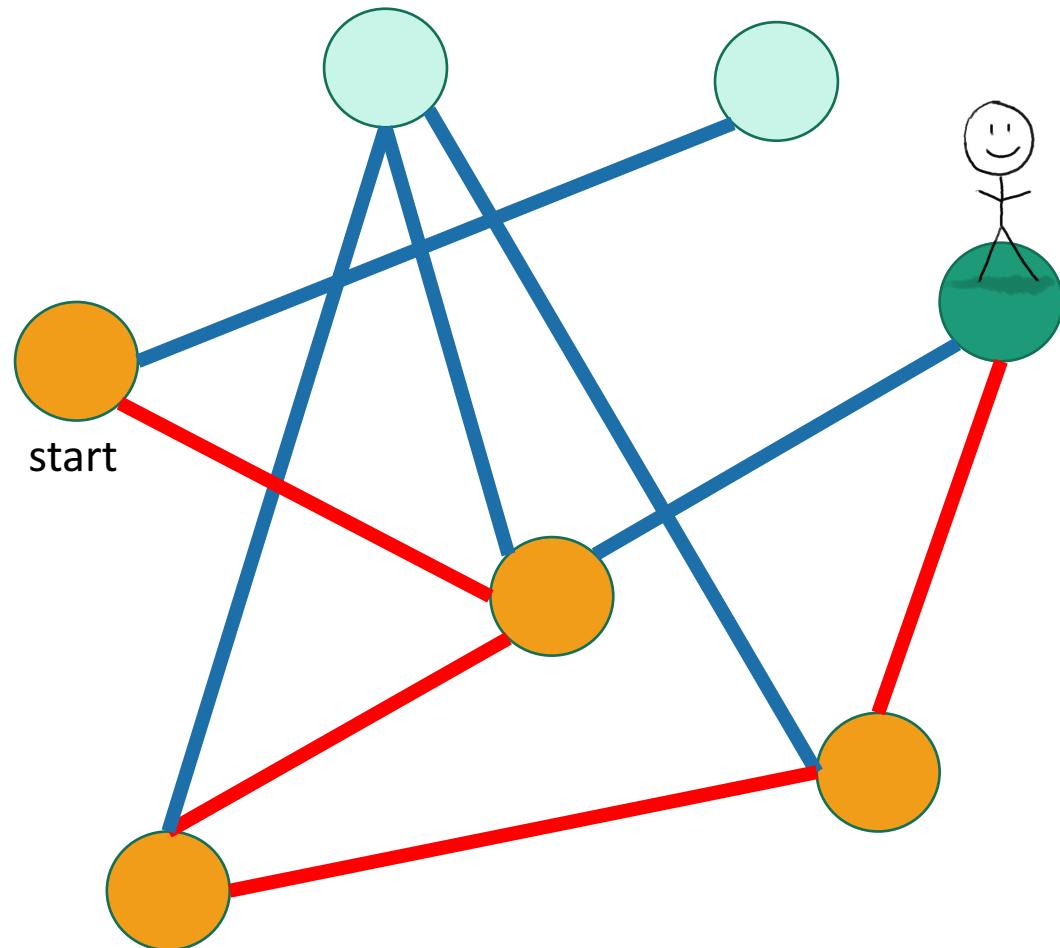
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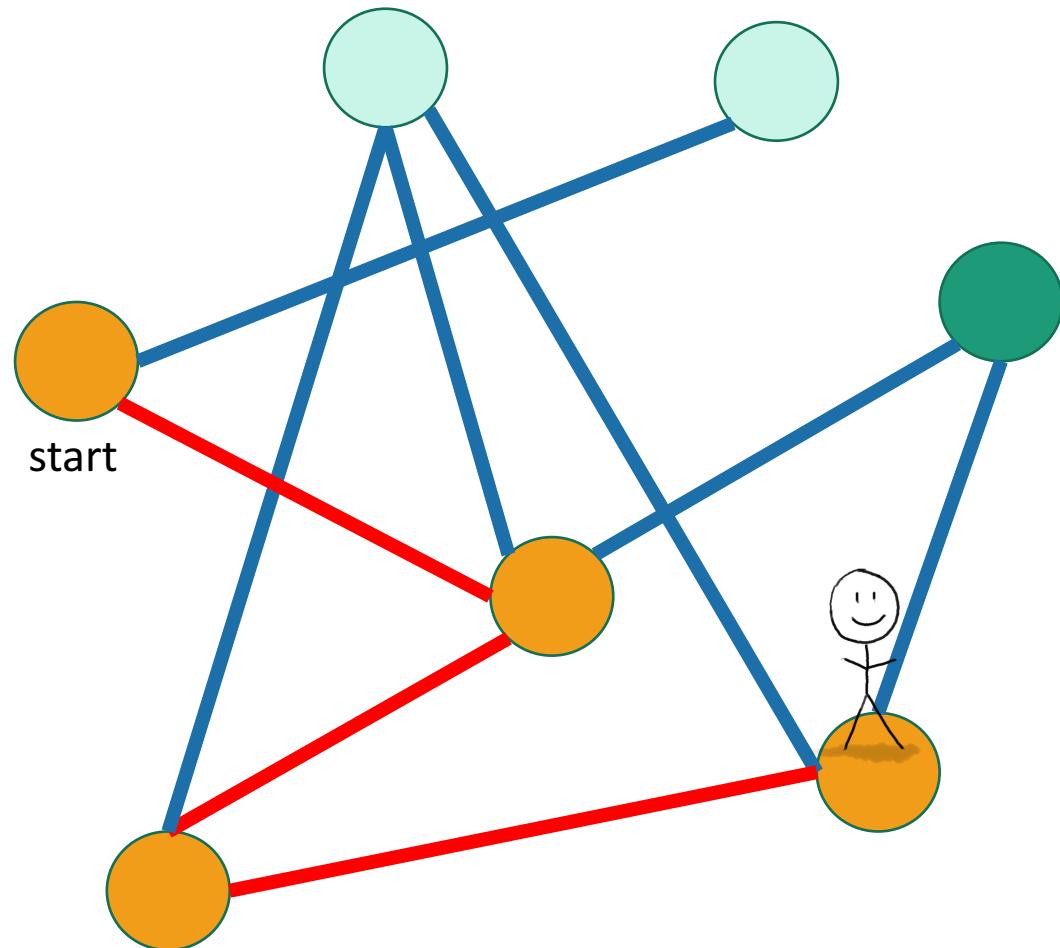
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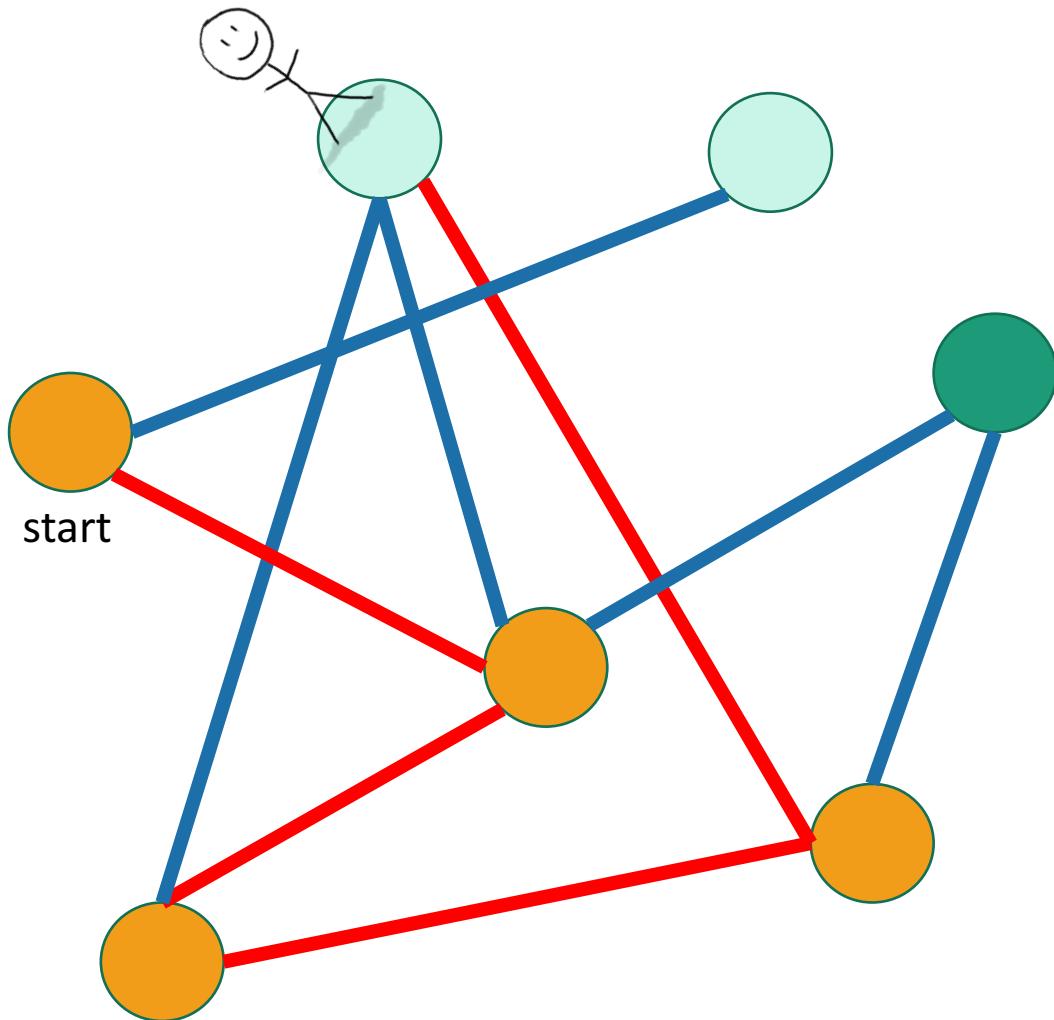
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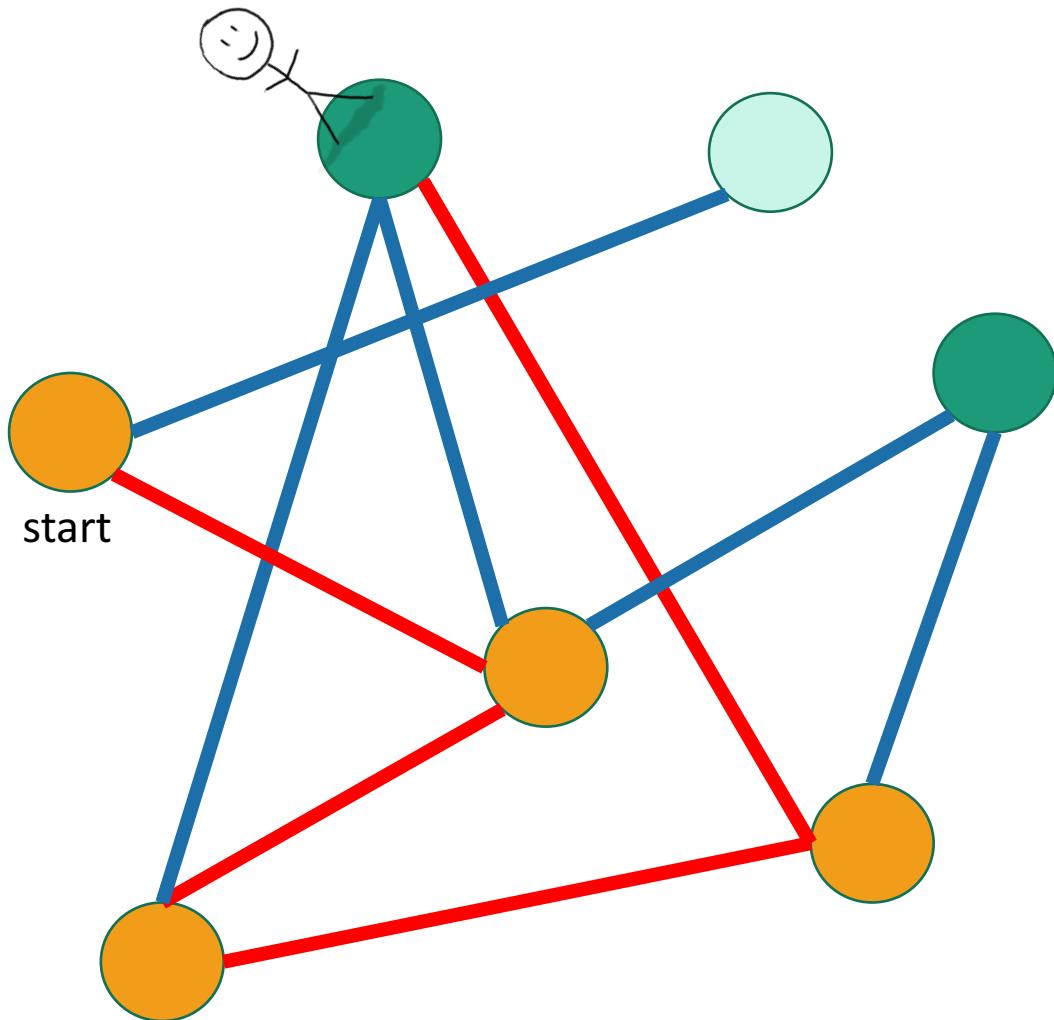
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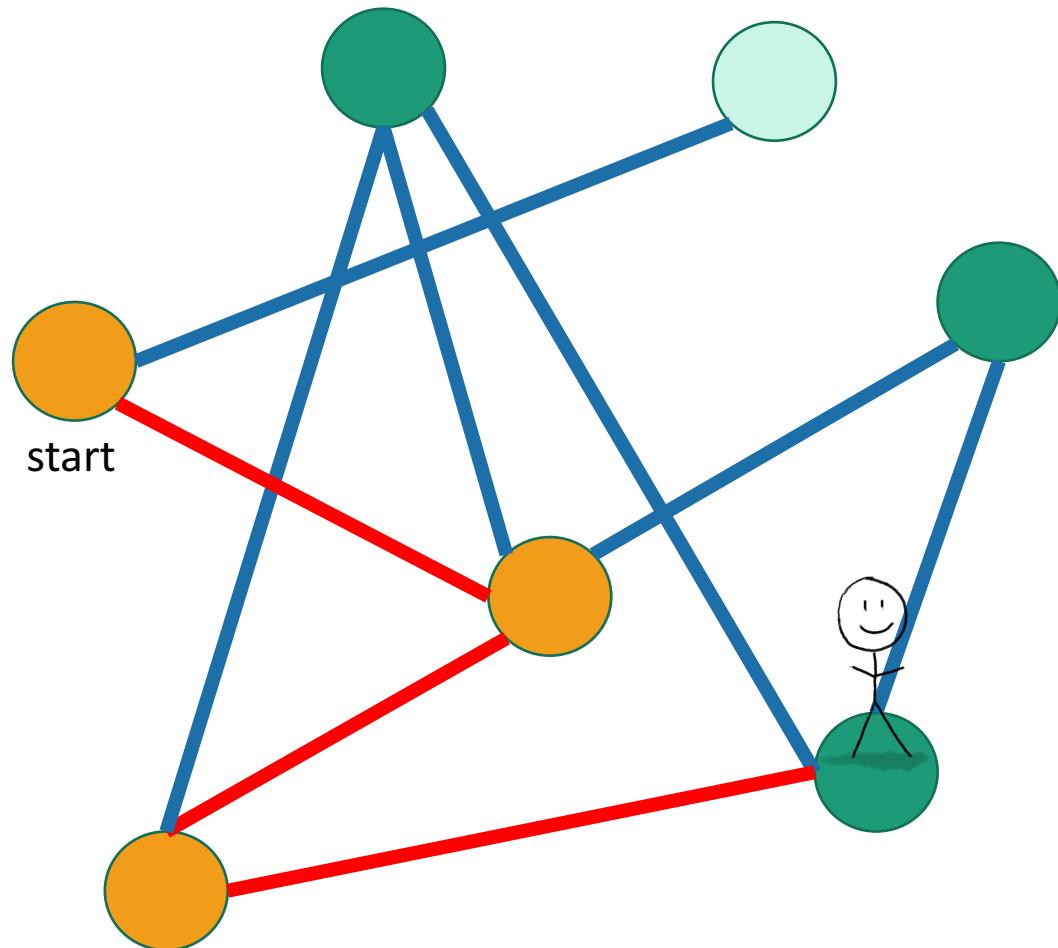
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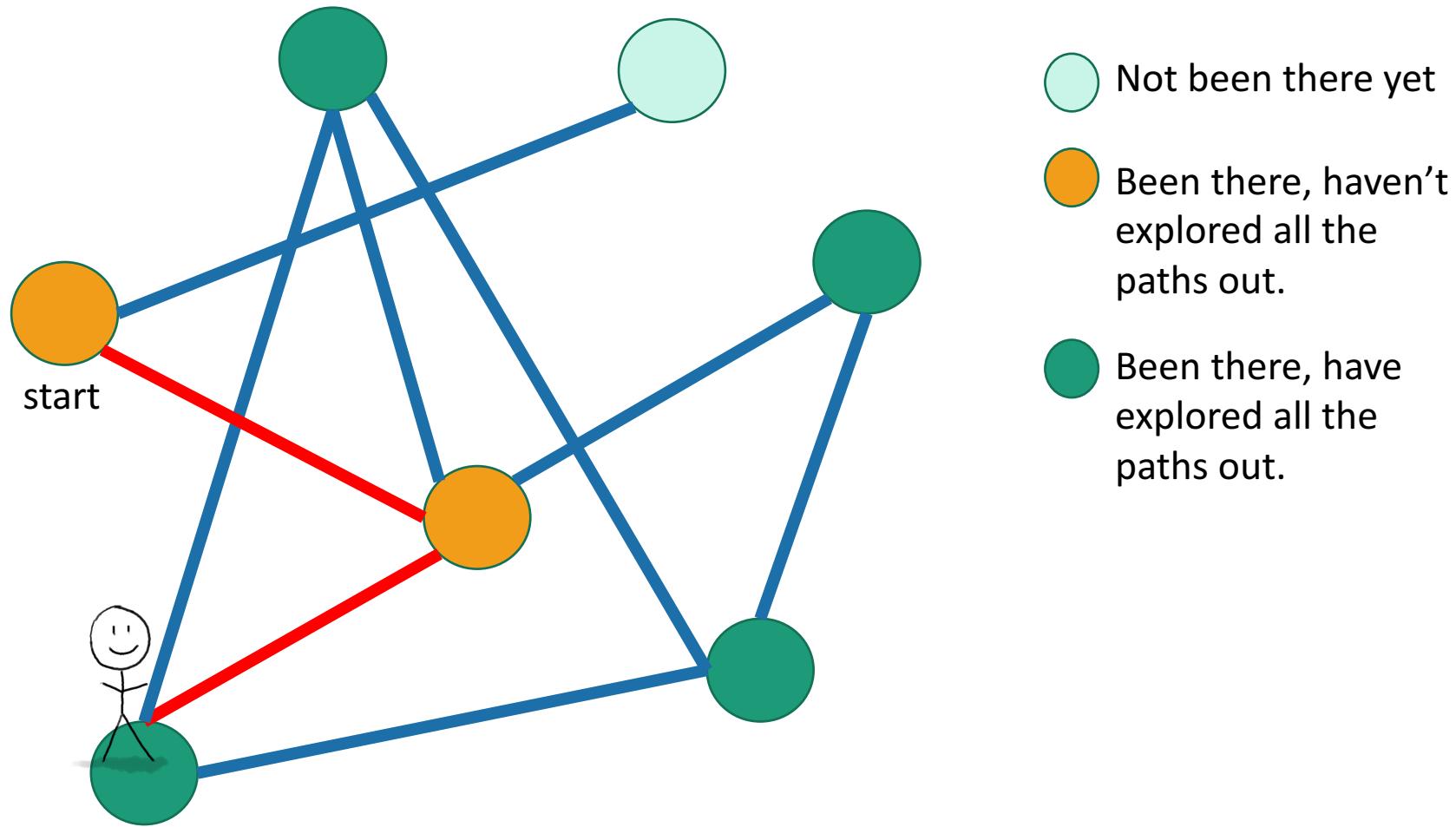
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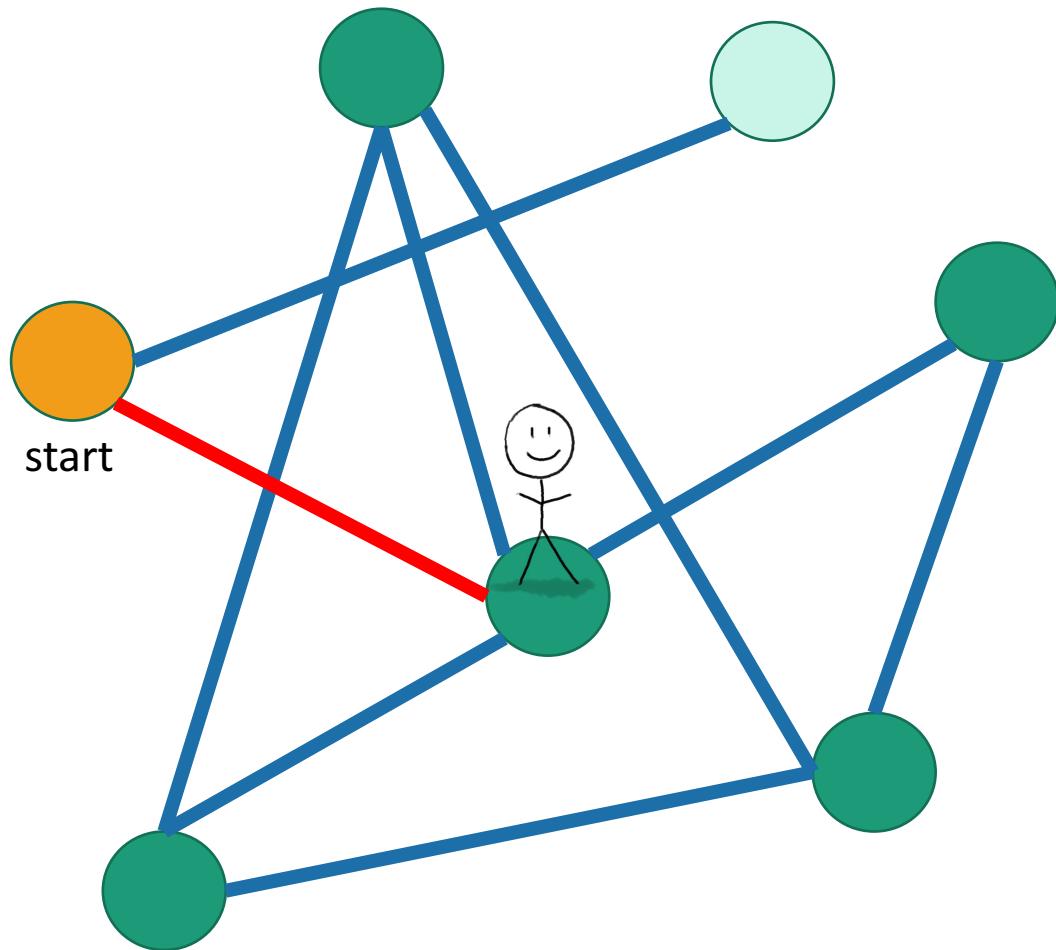
Depth First Search

Exploring a labyrinth with chalk and a piece of string



Depth First Search

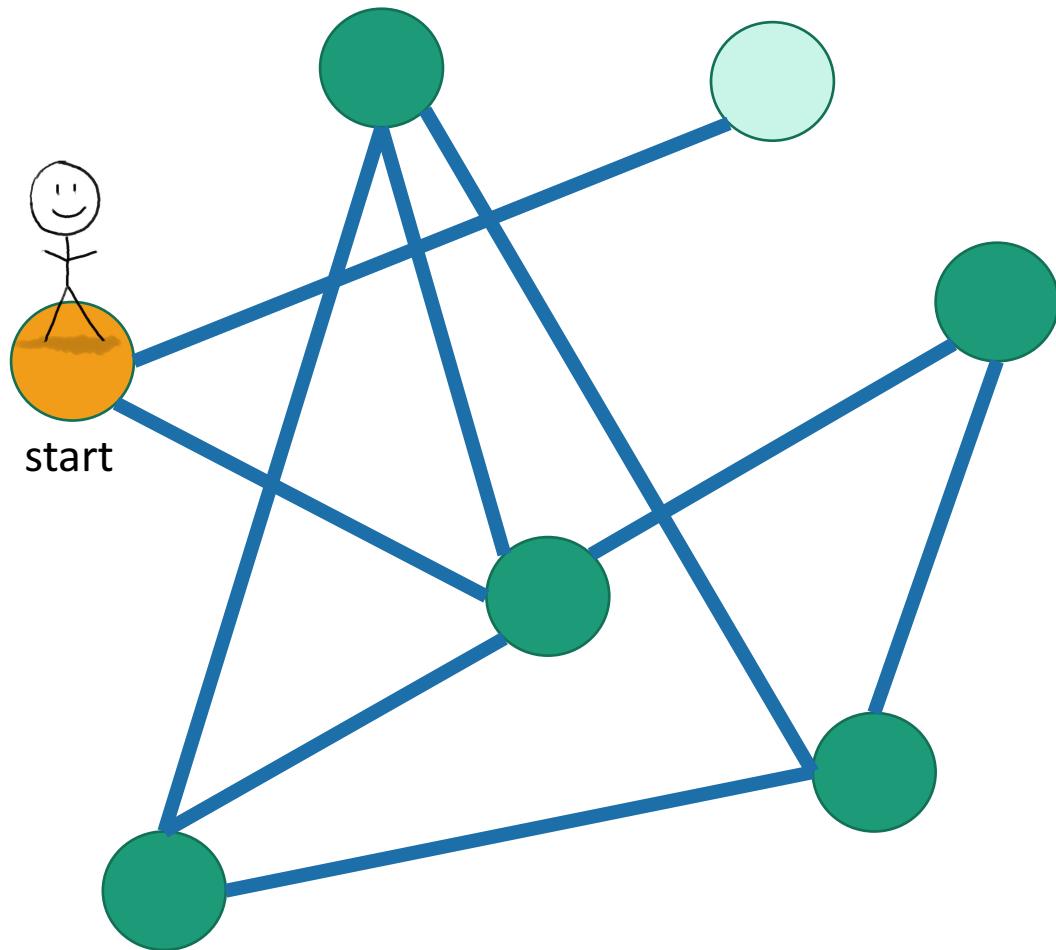
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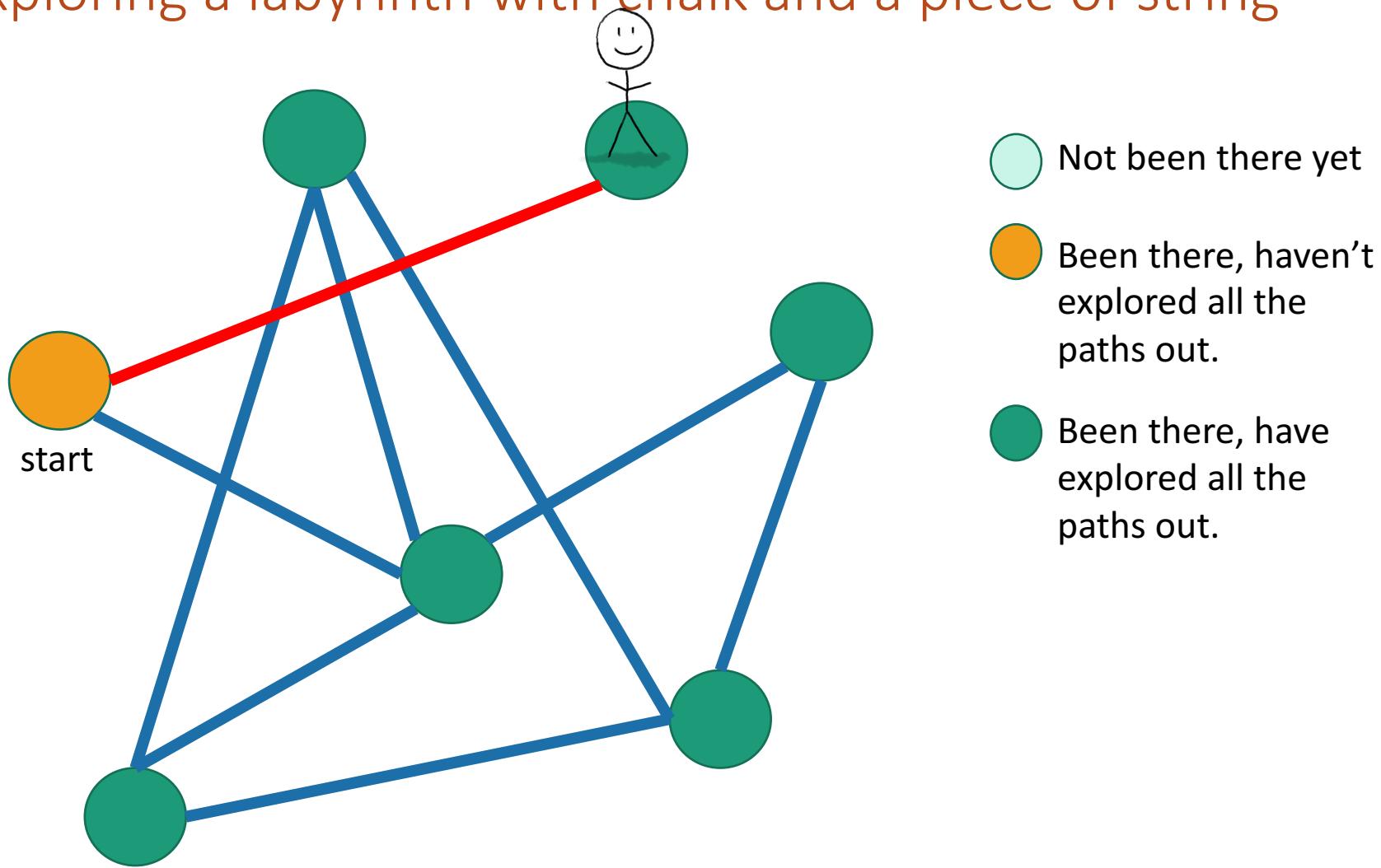
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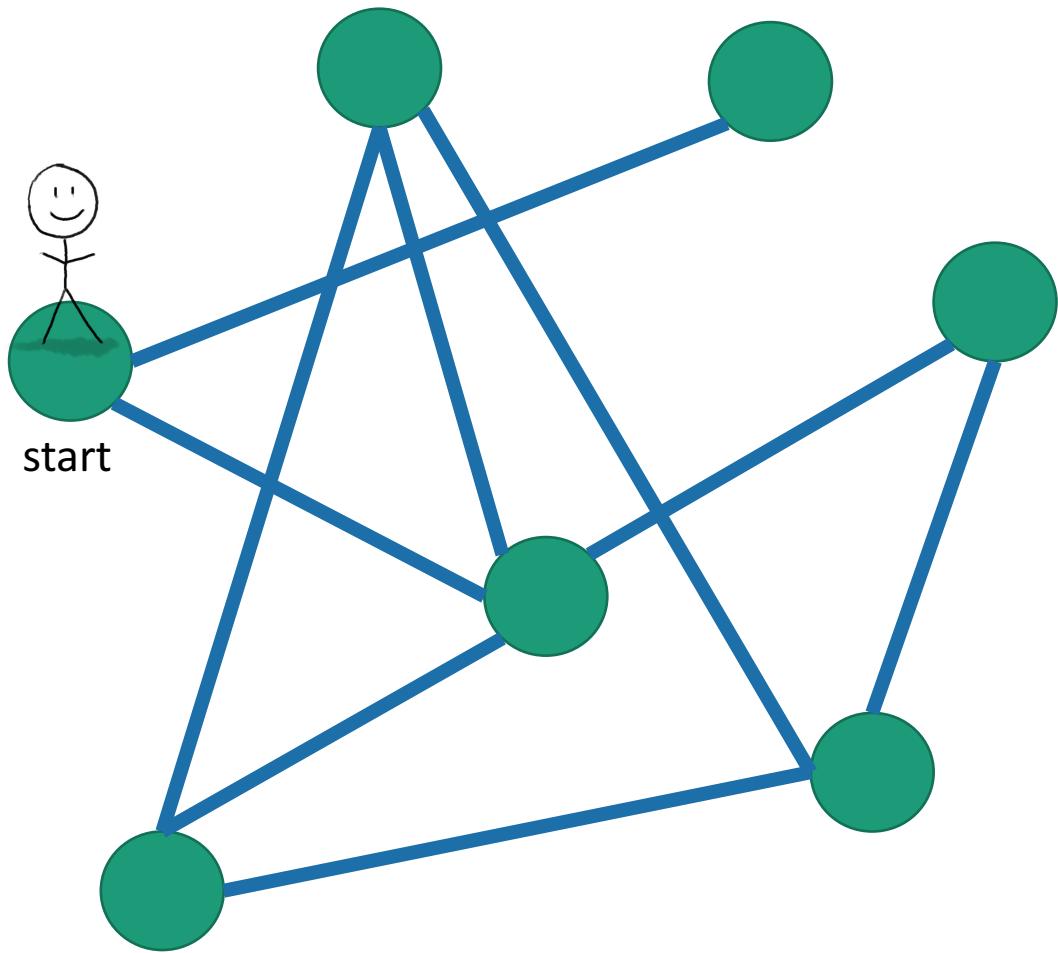
Depth First Search

Exploring a labyrinth with chalk and a piece of string



Depth First Search

Exploring a labyrinth with chalk and a piece of string



Labyrinth:
EXPLORED!

- Not been there yet
- Been there, haven't explored all the paths out.
- Been there, have explored all the paths out.

Depth First Search

Exploring a labyrinth with pseudocode

- Each vertex keeps track of whether it is:

- Unvisited 
- In progress 
- All done 



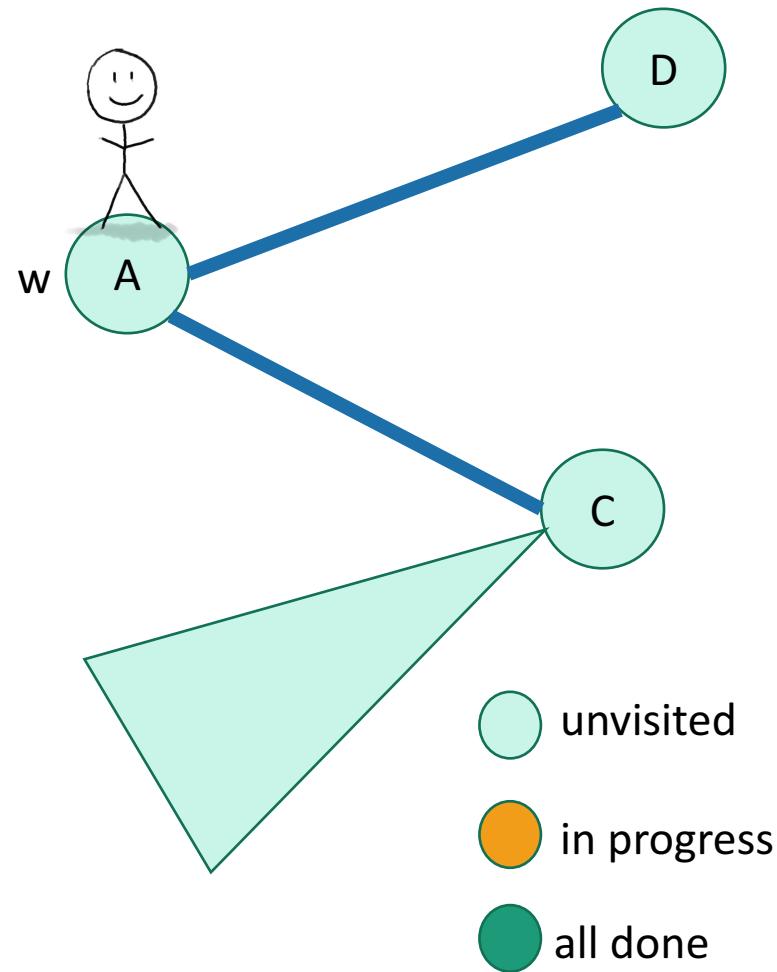
- Each vertex will also keep track of:

- The time we **first enter it**.
- The time we finish with it and mark it **all done**.

You might have seen other ways to implement DFS than what we are about to go through. This way has more bookkeeping, but more intuition – also, the bookkeeping will be useful later!

Depth First Search

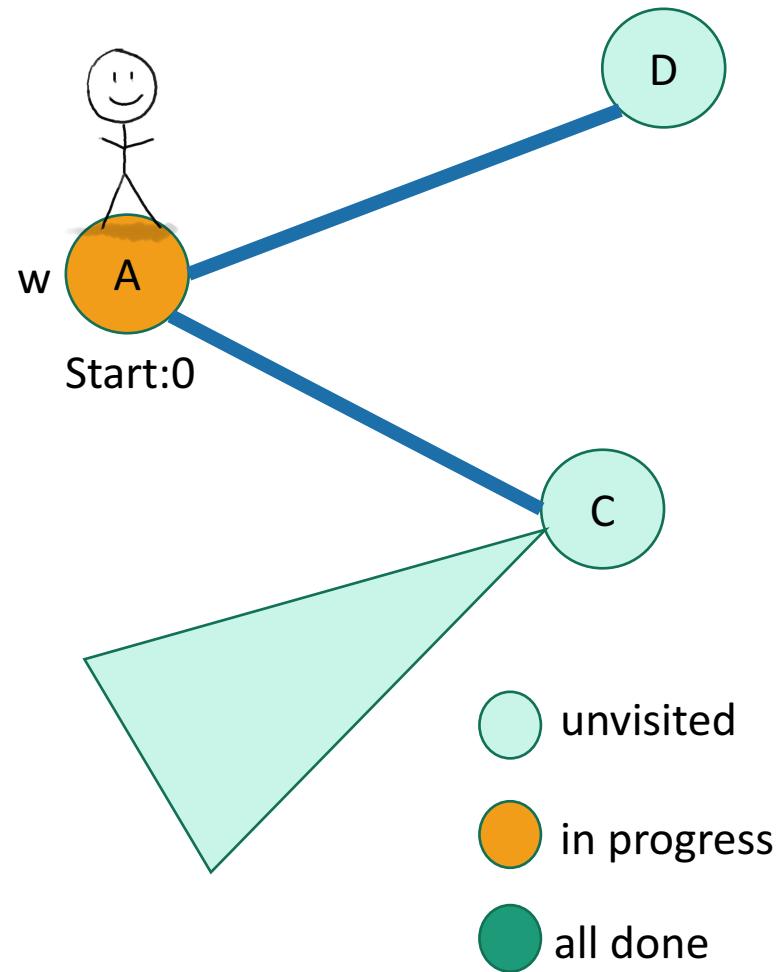
currentTime = 0



- **DFS(w, currentTime):**
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime
= **DFS(v, currentTime)**
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

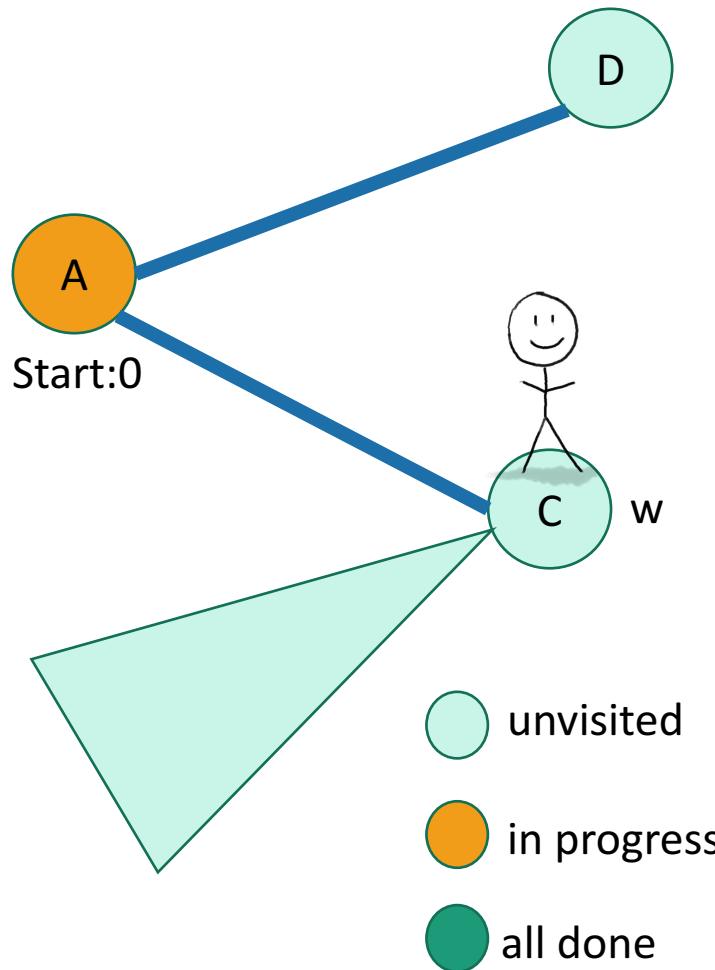
currentTime = 1



- **DFS(w, currentTime):**
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS(v, currentTime)**
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

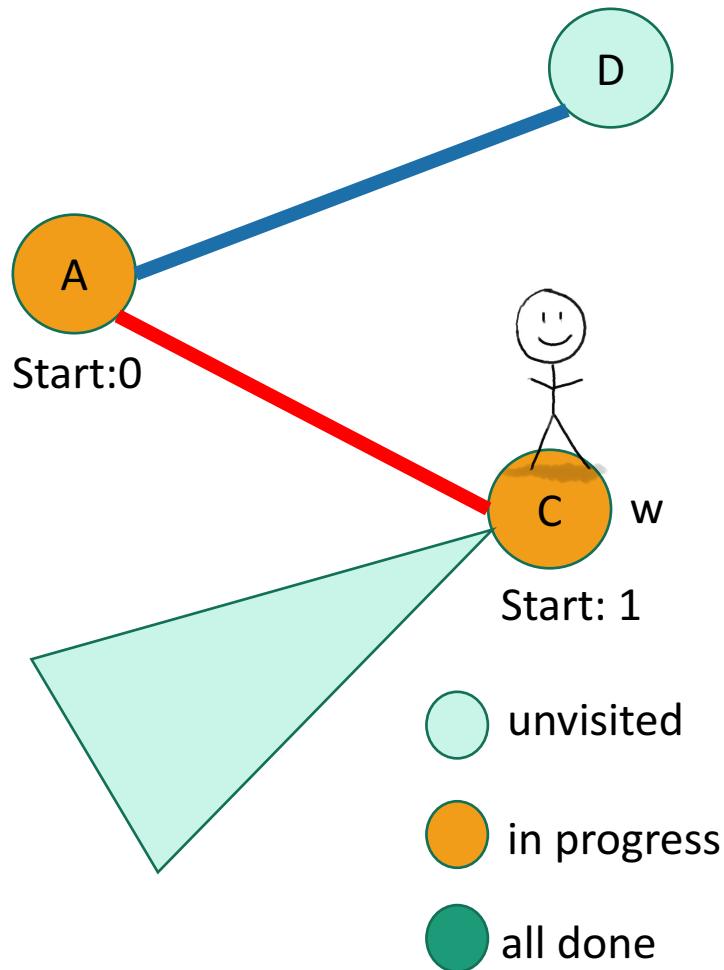
currentTime = 1



- **DFS(w, currentTime):**
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for v in w.neighbors:**
 - **if v is unvisited:**
 - currentTime = **DFS(v, currentTime)**
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

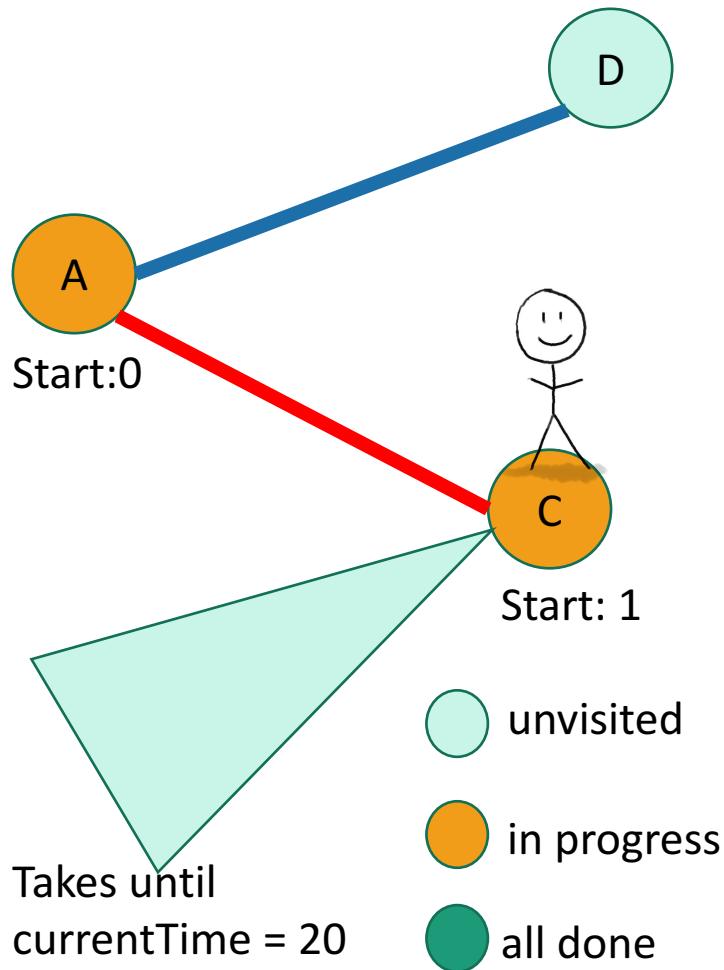
currentTime = 2



- **DFS(w, currentTime):**
 - `w.startTime = currentTime`
 - `currentTime ++`
 - Mark w as **in progress**.
 - **for v in w.neighbors:**
 - **if v is unvisited:**
 - `currentTime`
= **DFS(v, currentTime)**
 - `currentTime ++`
 - `w.finishTime = currentTime`
 - Mark w as **all done**
 - **return currentTime**

Depth First Search

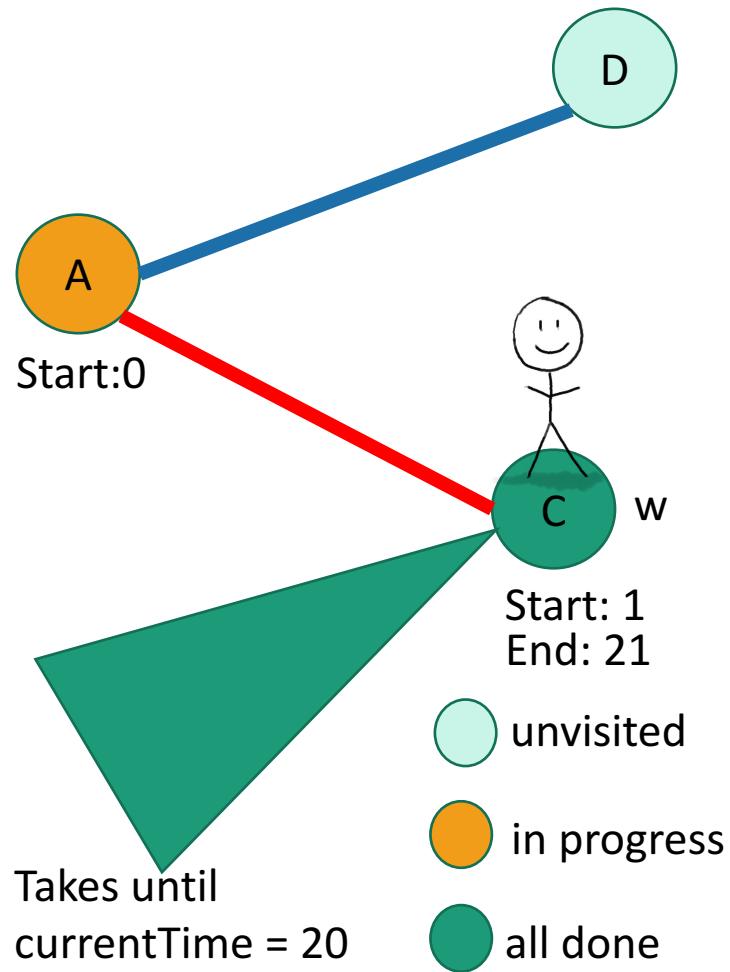
currentTime = 20



- **DFS(w, currentTime):**
 - `w.startTime = currentTime`
 - `currentTime ++`
 - Mark w as **in progress**.
 - **for v in w.neighbors:**
 - **if v is unvisited:**
 - `currentTime`
= **DFS(v, currentTime)**
 - `currentTime ++`
 - `w.finishTime = currentTime`
 - Mark w as **all done**
 - **return currentTime**

Depth First Search

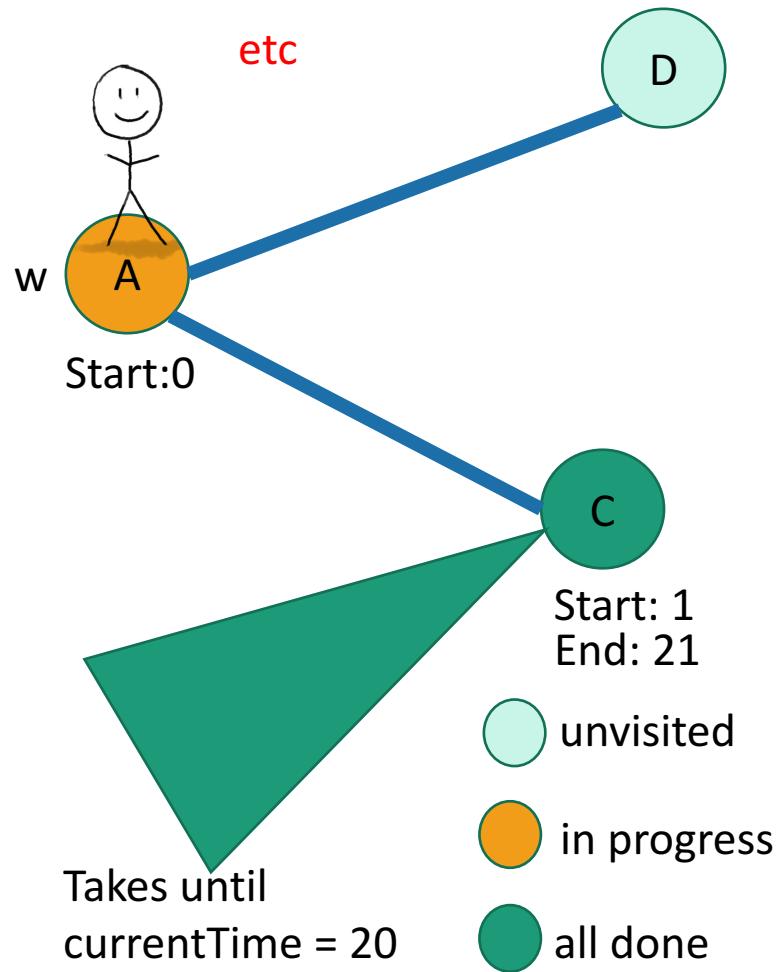
currentTime = 21



- **DFS(w, currentTime):**
 - $w.startTime = currentTime$
 - $currentTime ++$
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - $currentTime = \text{DFS}(v, currentTime)$
 - $currentTime ++$
 - $w.finishTime = currentTime$
 - Mark w as **all done**
 - **return** currentTime

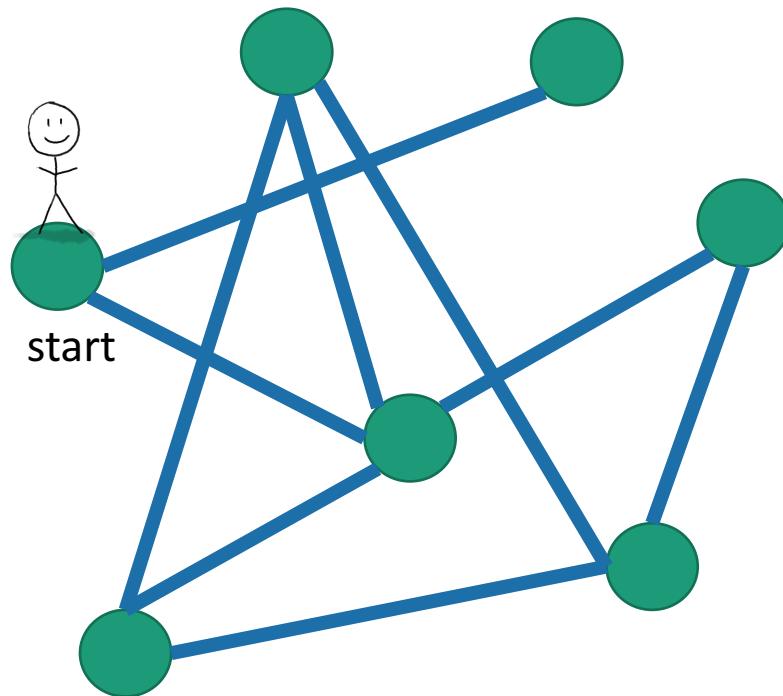
Depth First Search

currentTime = 21



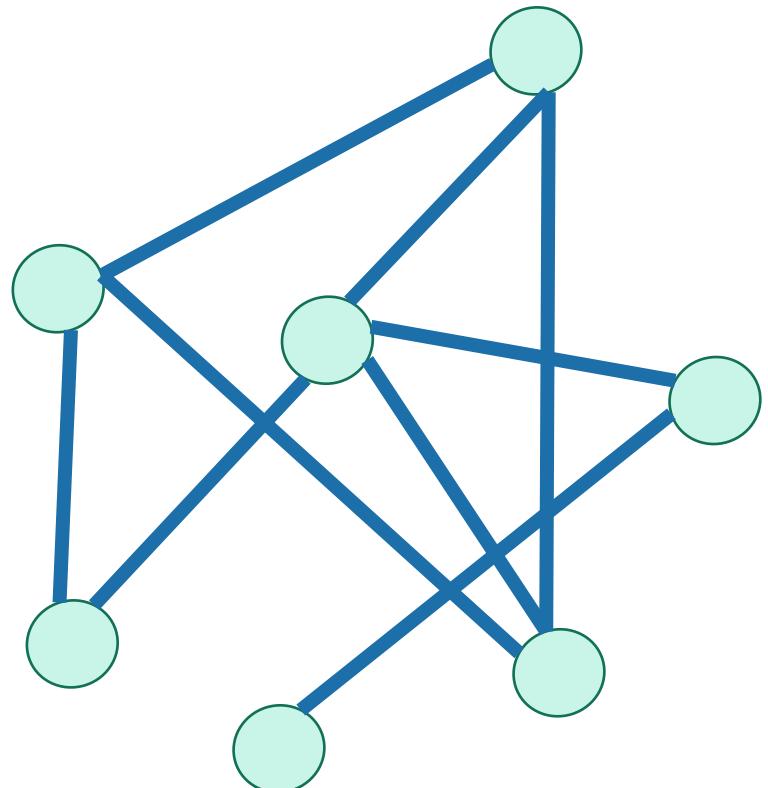
- **DFS(w, currentTime):**
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for v in w.neighbors:**
 - **if v is unvisited:**
 - currentTime = **DFS(v, currentTime)**
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

DFS finds all the nodes reachable from the starting point



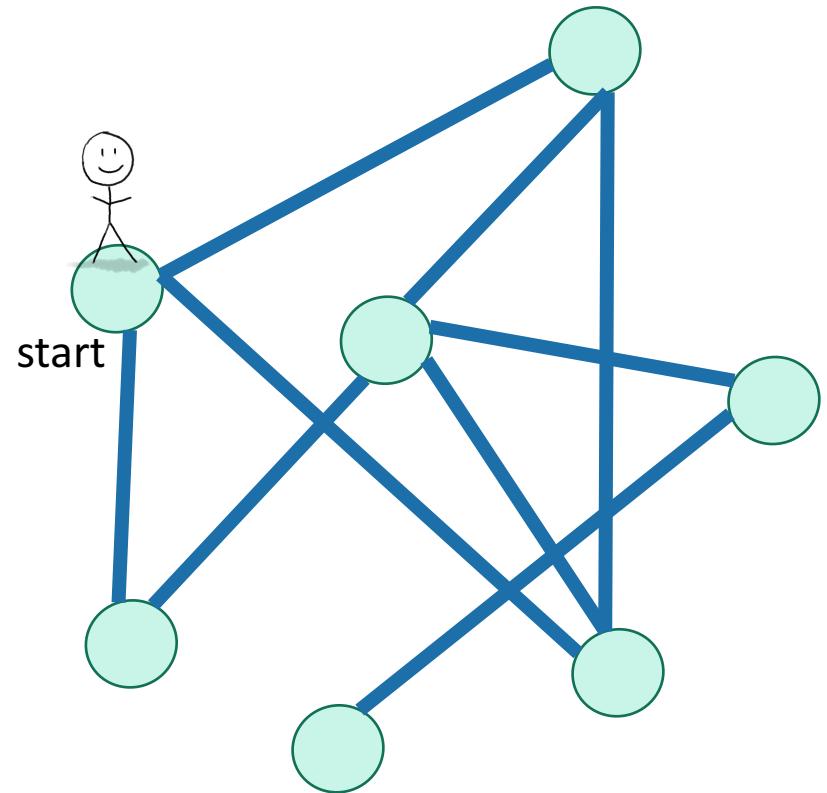
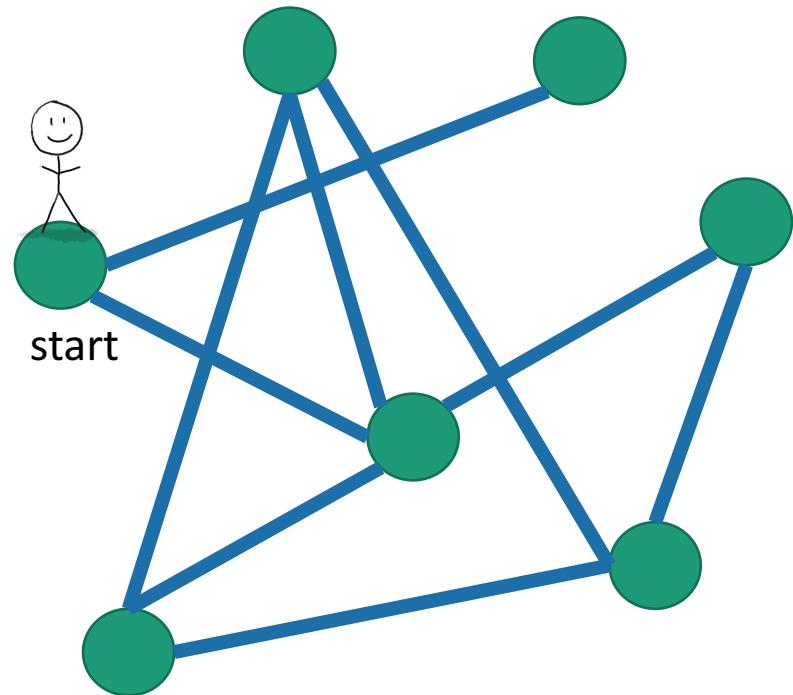
In an undirected graph, this is called a **connected component**.

One application: finding connected components.



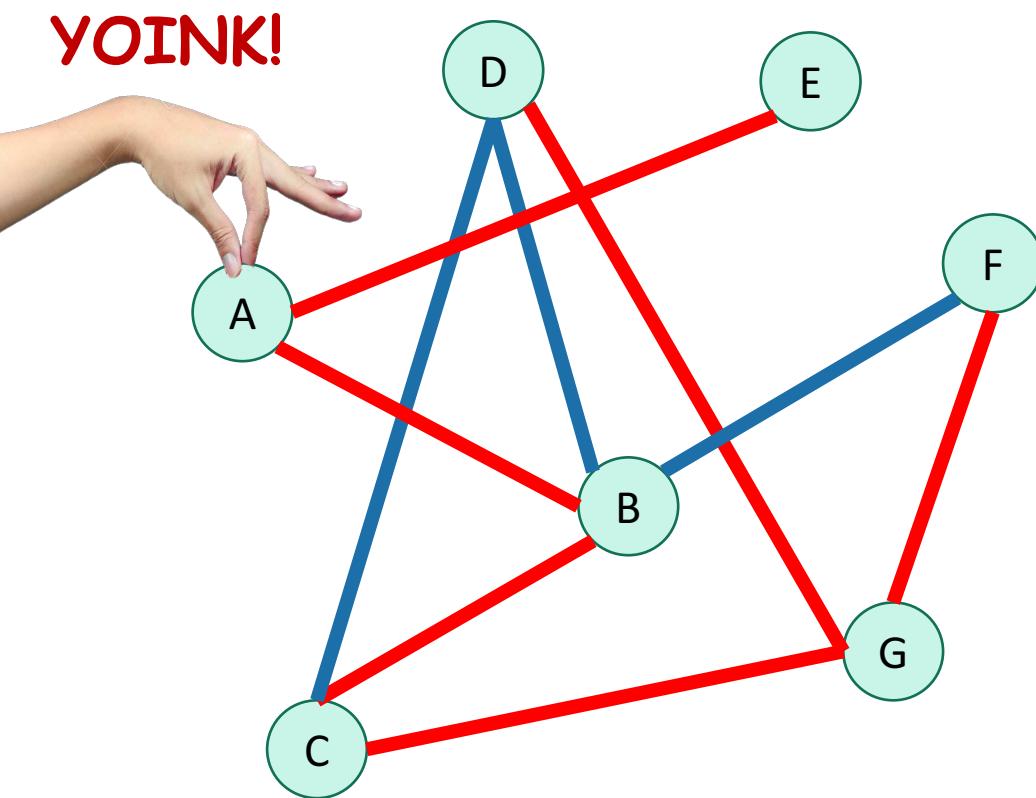
To explore the whole graph

- Do it repeatedly!

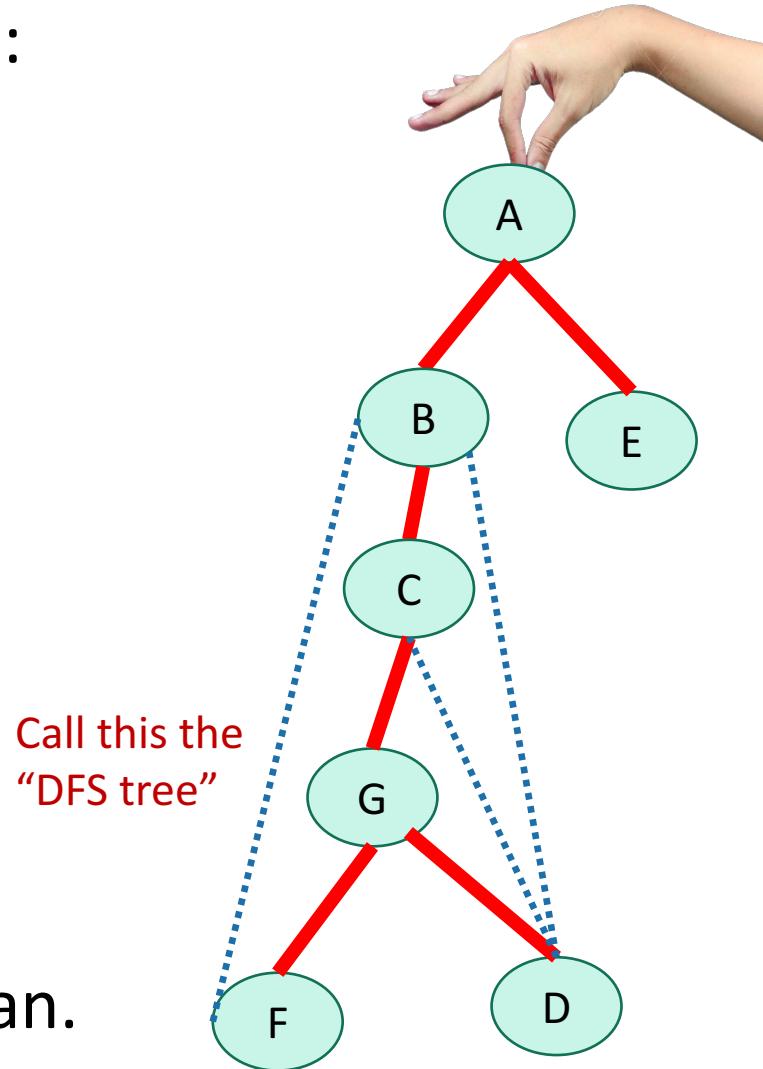


Why is it called depth-first?

- We are implicitly building a tree:



- And first we go as deep as we can.



Running time

To explore just the connected component we started in

- We look at each edge only once.
- And basically don't do anything else.
- So...

$O(m)$



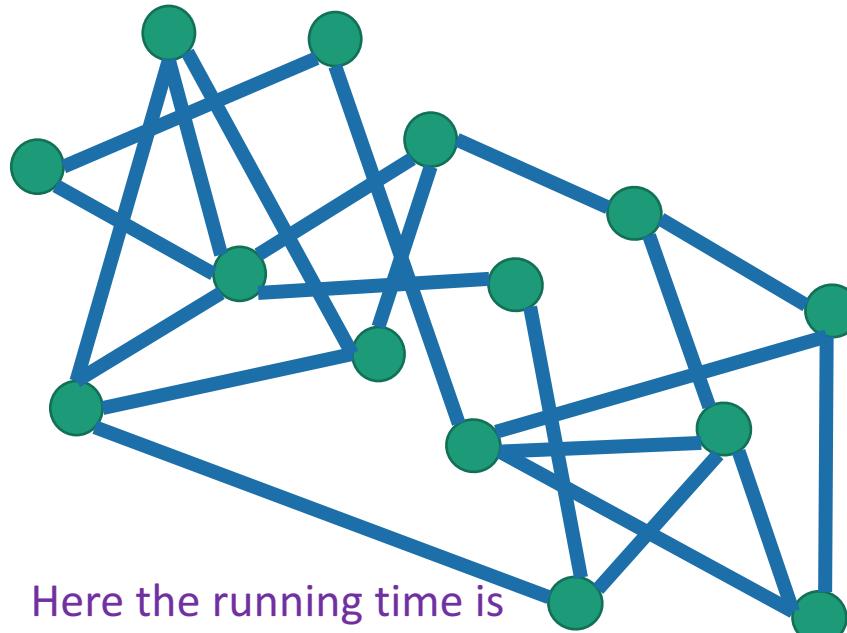
- (Assuming we are using the linked-list representation)
- (Details on board)

Running time

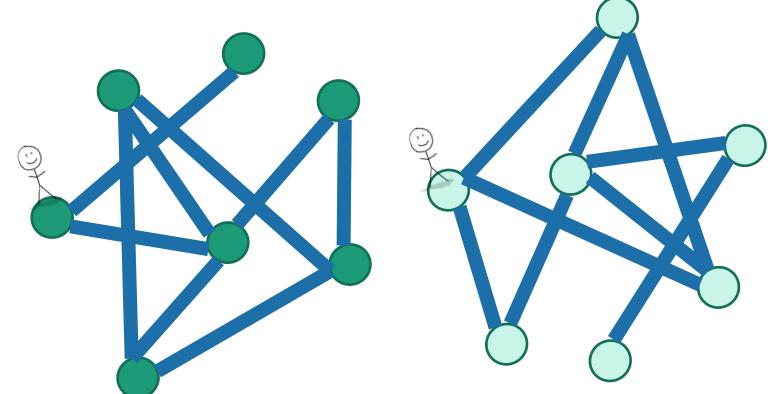
To explore the whole thing

- Explore the connected components one-by-one.
- This takes time *[on board]*

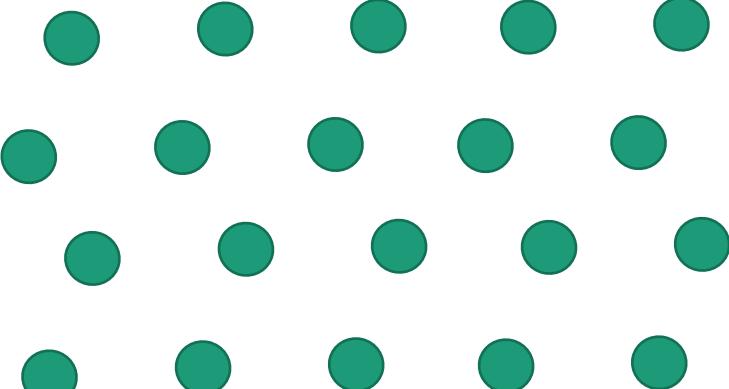
$$O(n + m)$$



Here the running time is
 $O(m)$ like before



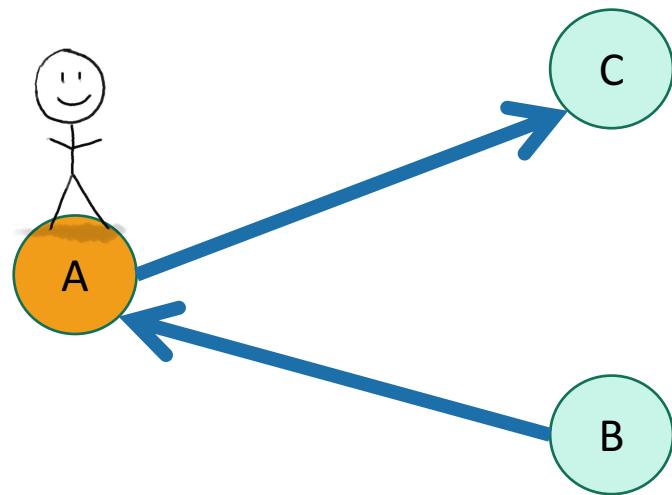
or



Here $m=0$ but it still takes time $O(n)$ to explore the graph.

You check:

DFS works fine on directed graphs too!



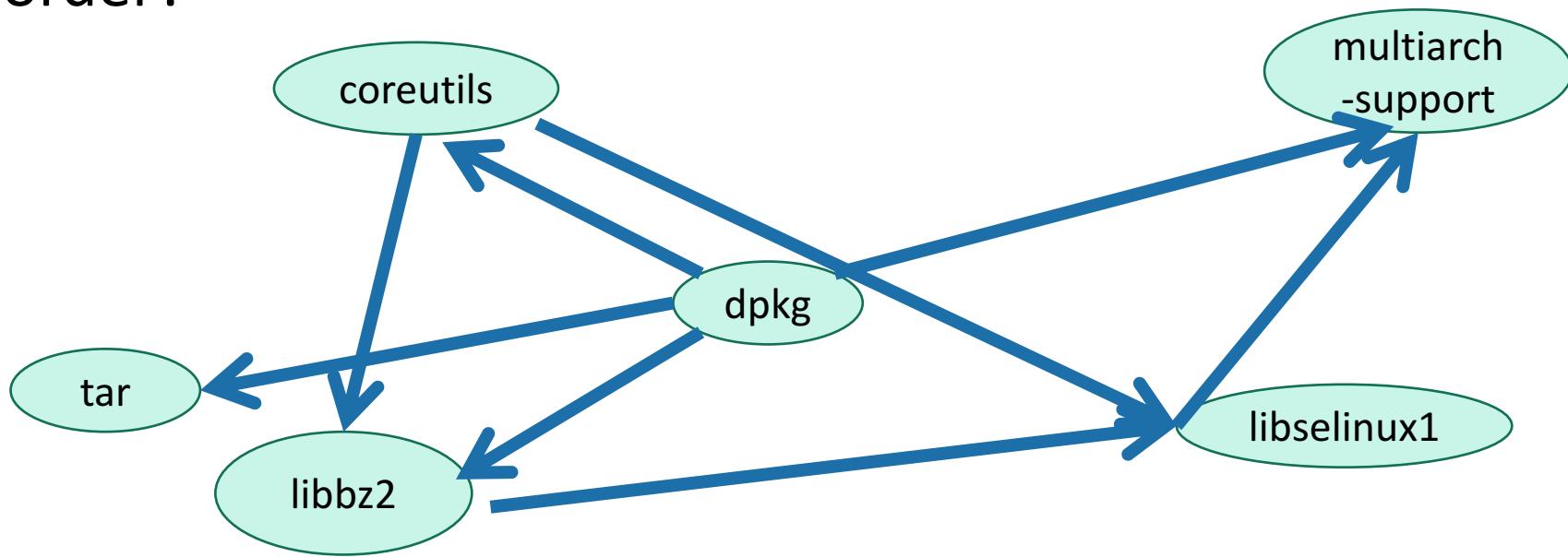
Only walk to C, not to B.



Siggi the studious stork

Pre-lecture exercise

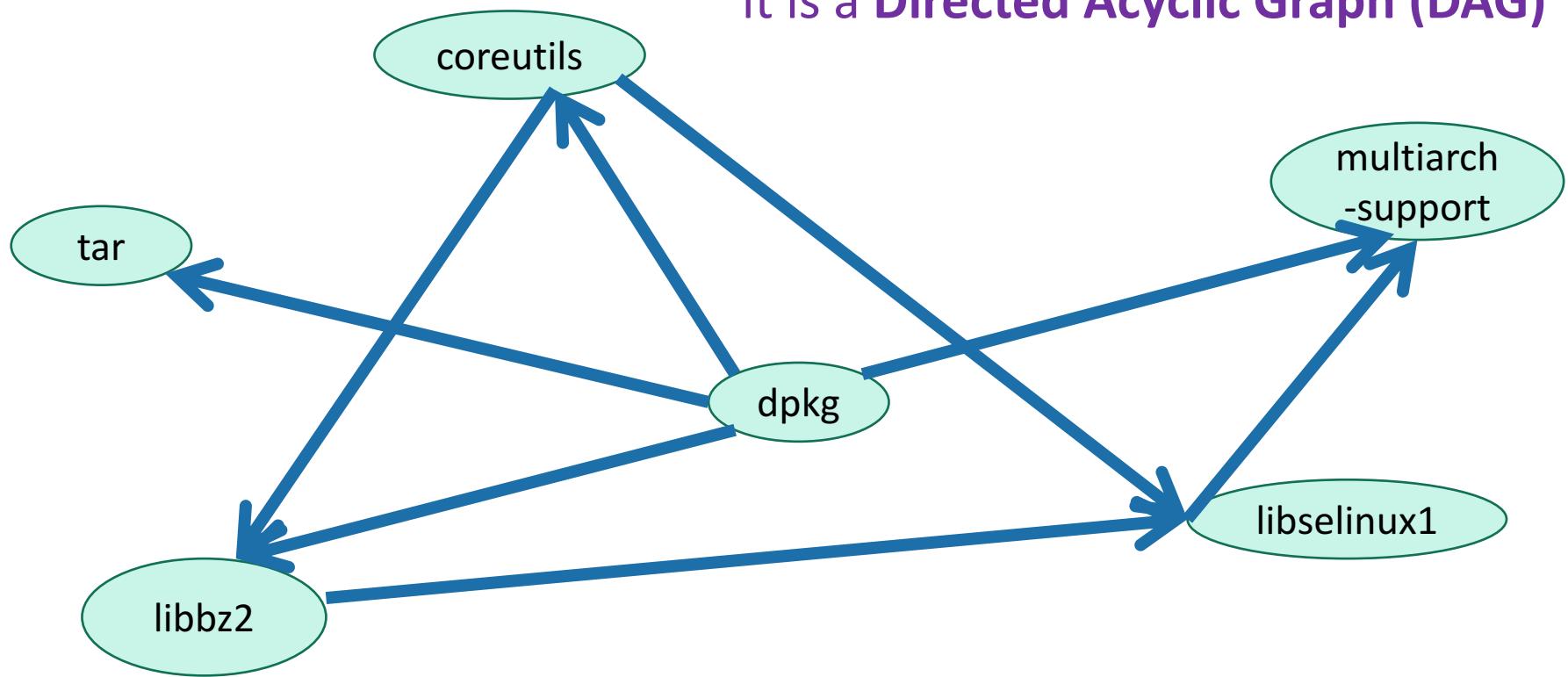
- How can you sign up for classes so that you never violate the pre-req requirements?
- More practically, given a package dependency graph, how do you install packages in the correct order?



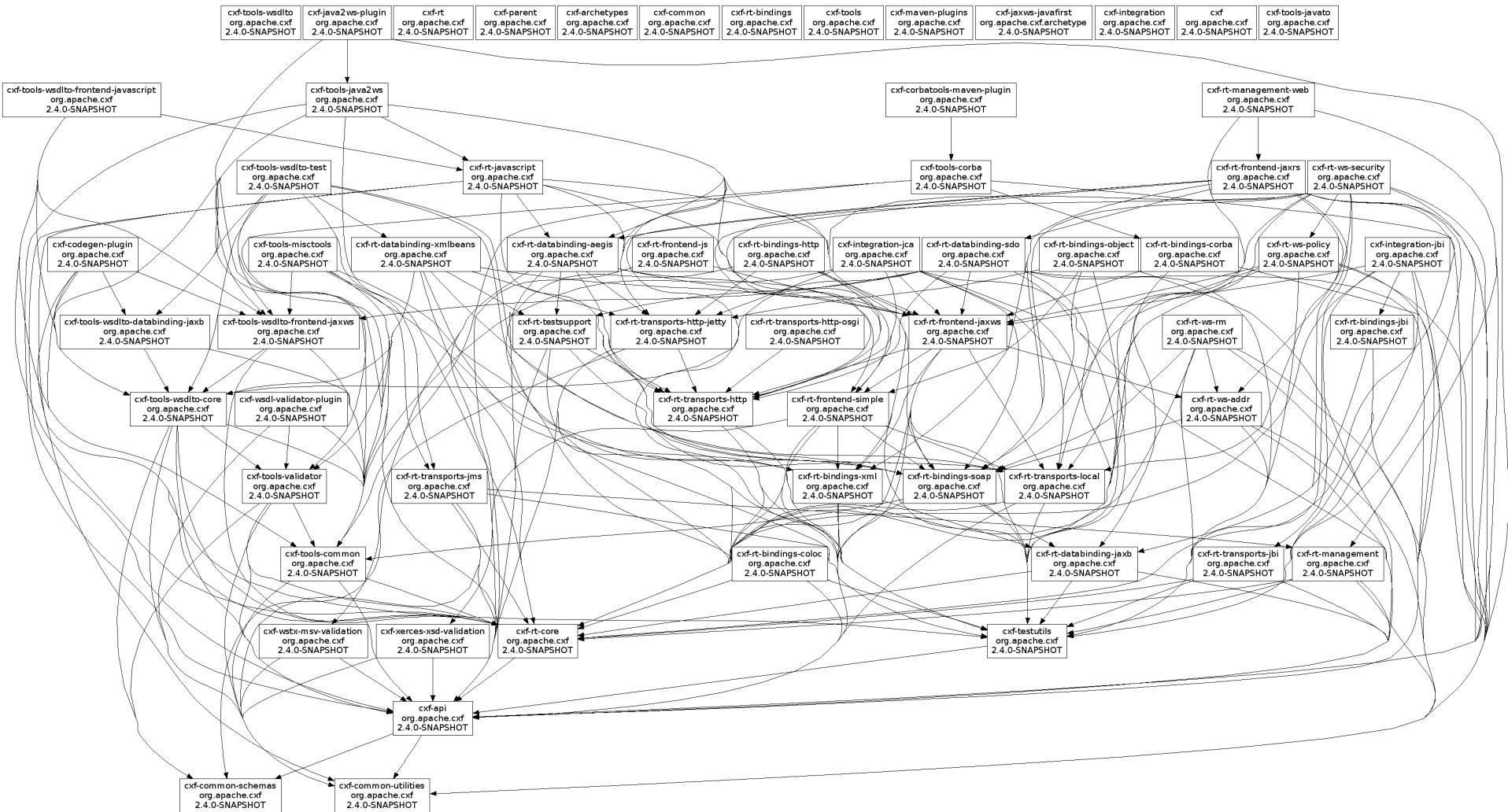
Application: topological sorting

- Question: in what order should I install packages?

Suppose the dependency graph has no cycles:
it is a **Directed Acyclic Graph (DAG)**

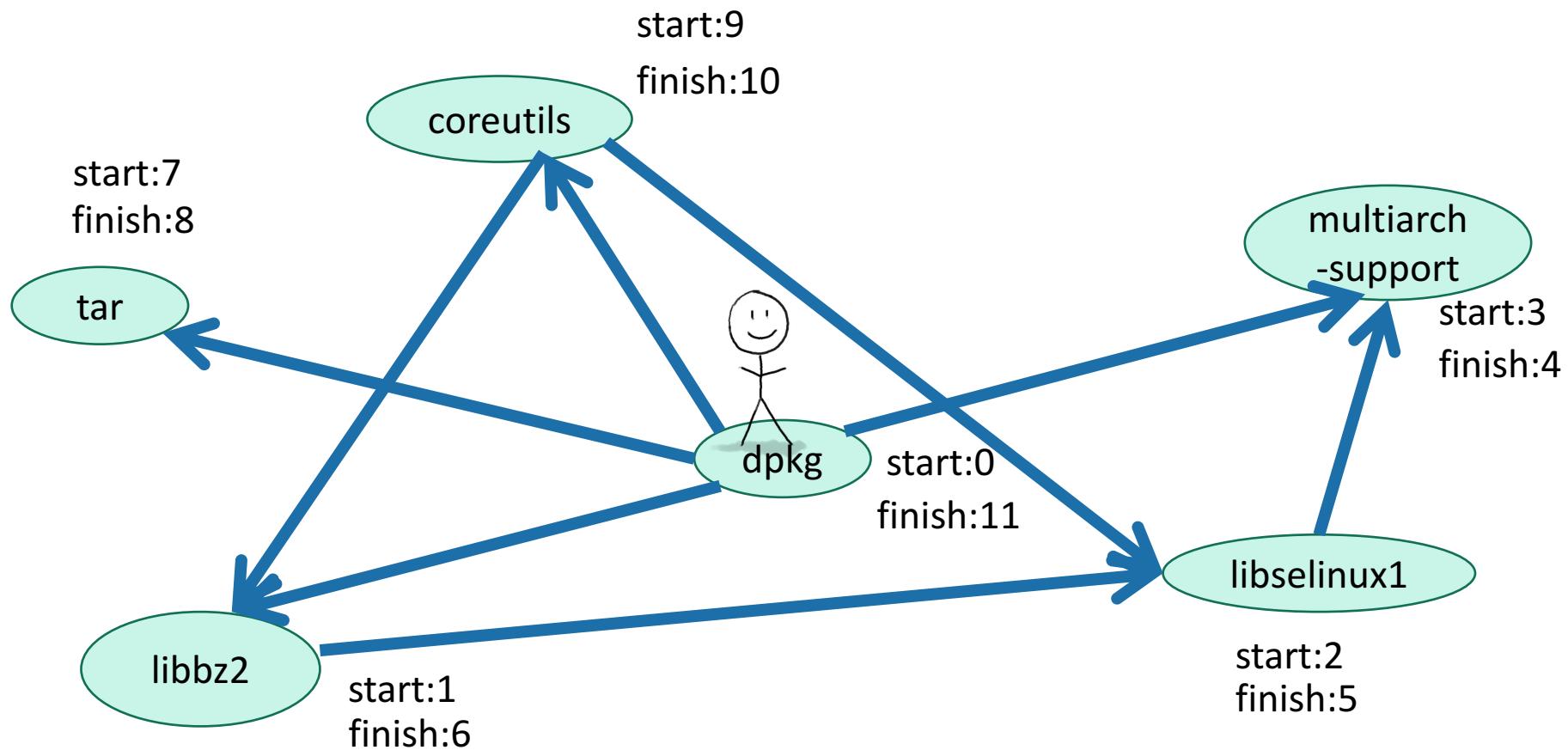


Can't always eyeball it.



Let's do DFS

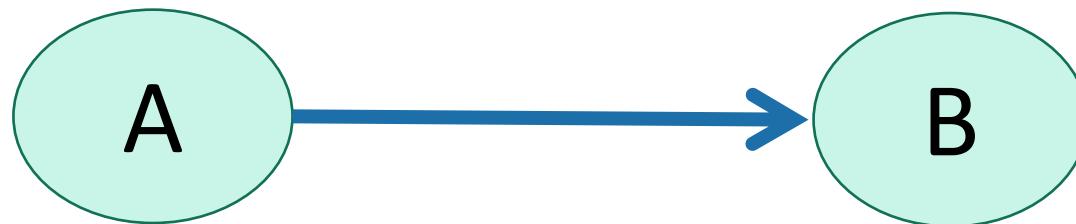
Discussion and observations on board.



Finish times seem useful

Suppose the underlying graph has no cycles

Claim: In general, we'll always have:



finish: [larger]

finish: [smaller]

To understand why, let's go back to that DFS tree.

A more general statement

(this holds even if there are cycles)

This is called the “parentheses theorem” in CLRS

(check this statement carefully!)



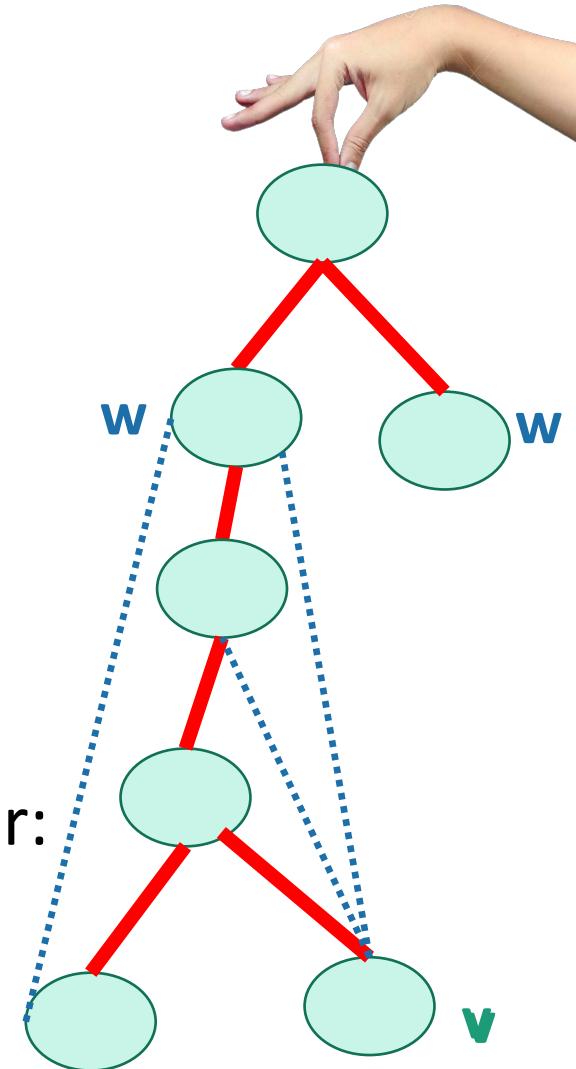
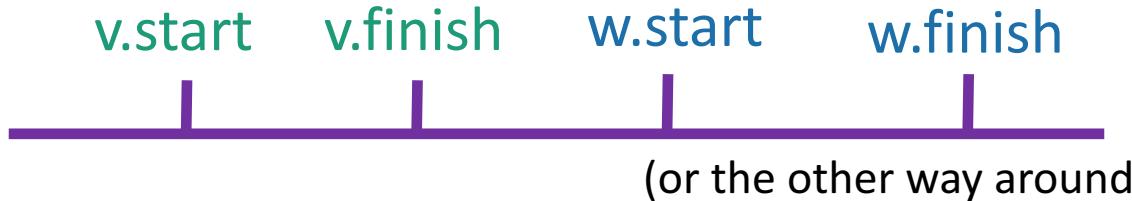
- If v is a descendant of w in this tree:



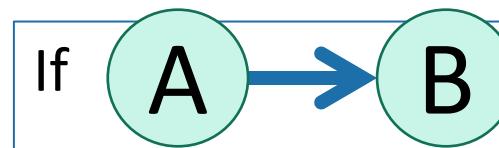
- If w is a descendant of v in this tree:



- If neither are descendants of each other:



So to prove this ->



Then $B.\text{finishTime} < A.\text{finishTime}$

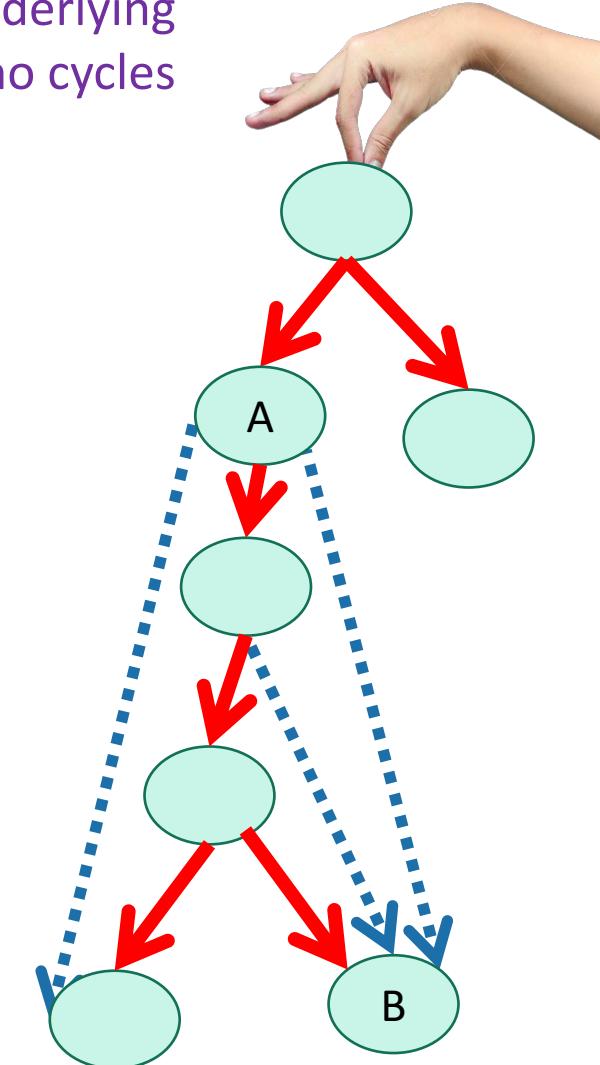
Suppose the underlying graph has no cycles

- **Case 1:** B is a descendant of A in the DFS tree.

- Then



- aka, $B.\text{finishTime} < A.\text{finishTime}$.

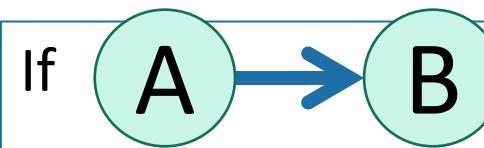


So to prove this ->

NOTE: In class this case was missing!!!

I messed up 😞

But it's here now.



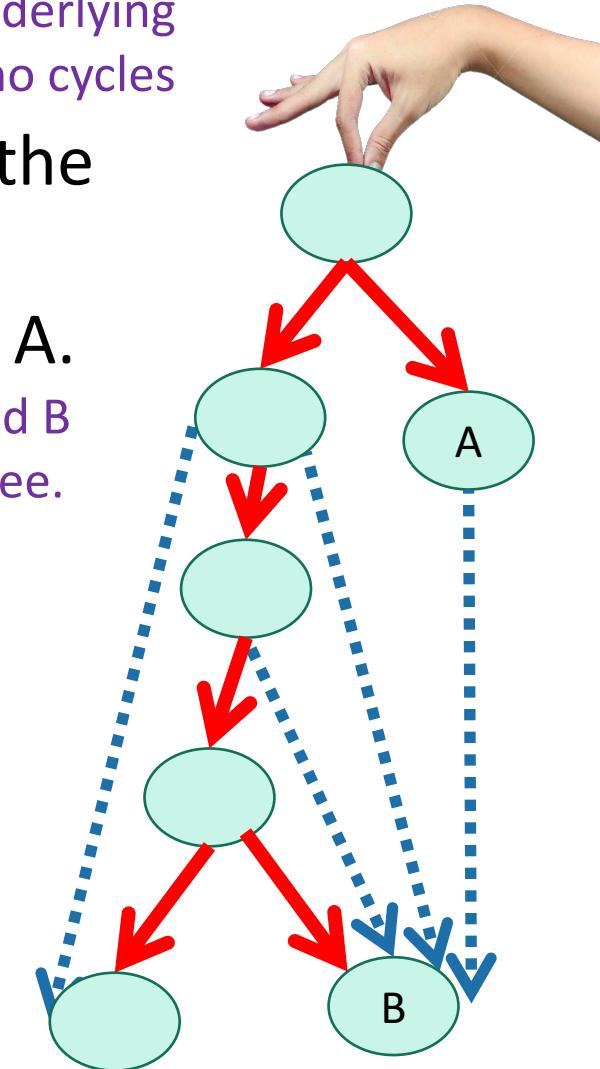
Then $B.\text{finishTime} < A.\text{finishTime}$

Suppose the underlying graph has no cycles

- **Case 2:** B is a **NOT** descendant of A in the DFS tree.
- Then we must have explored B before A.
 - Otherwise we would have gotten to B from A, and B would have been a descendant of A in the DFS tree.
- Then



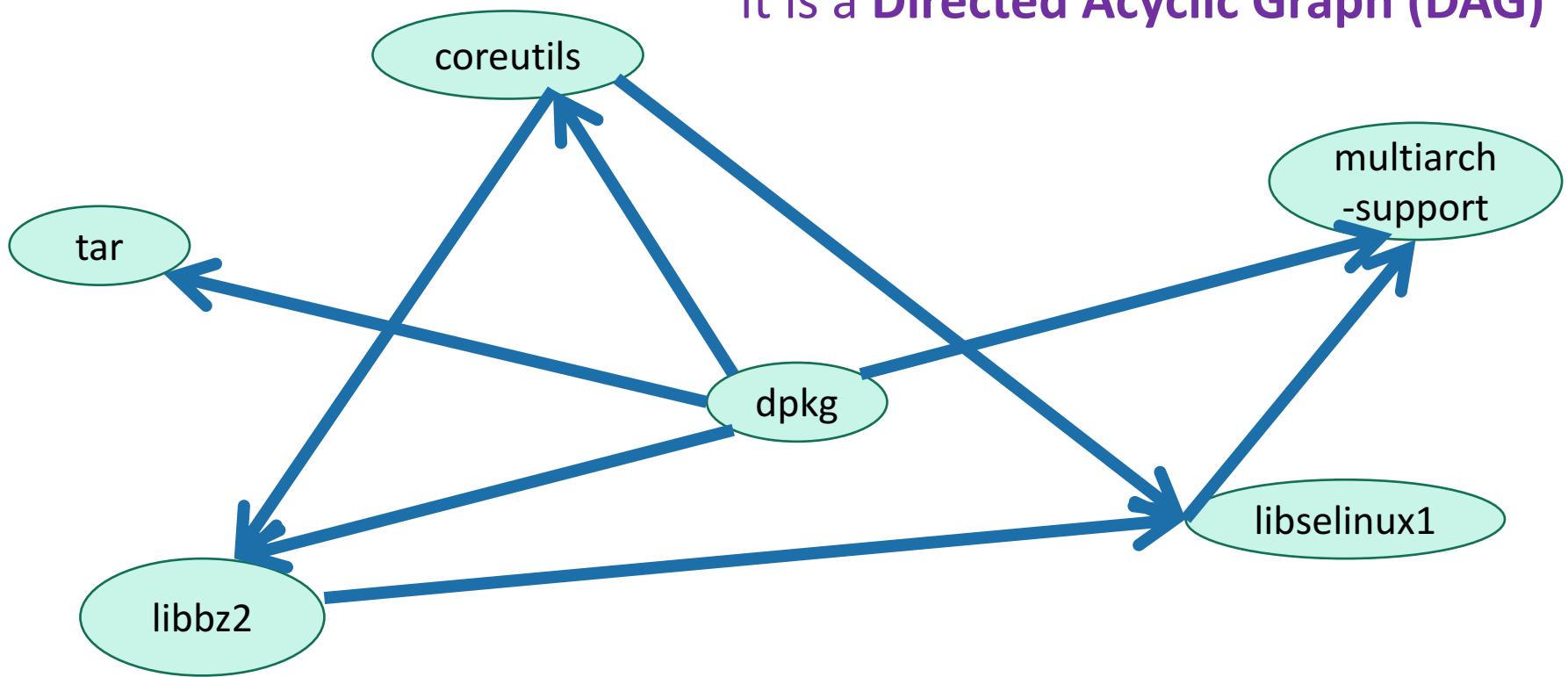
- aka, $B.\text{finishTime} < A.\text{finishTime}$.



Back to this problem

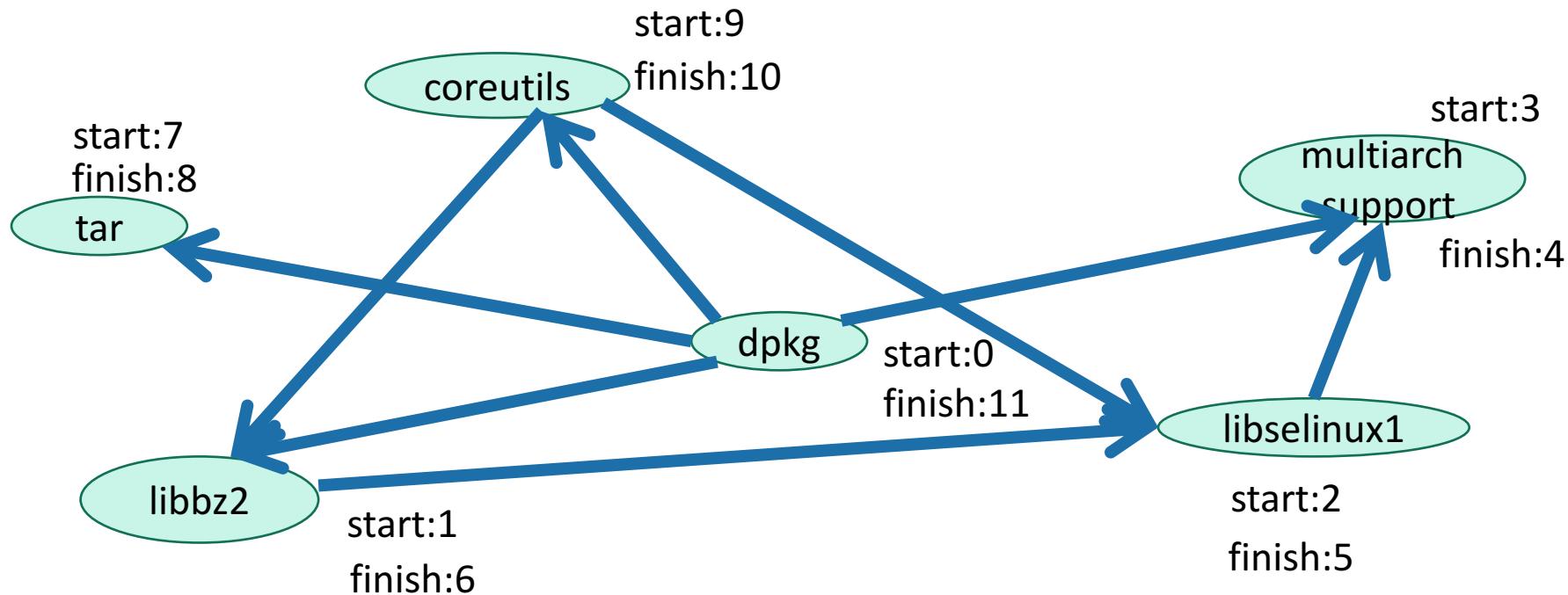
- Question: in what order should I install packages?

Suppose the dependency graph has no cycles:
it is a **Directed Acyclic Graph (DAG)**



In reverse order of finishing time

- Do DFS
 - Maintain a list of packages, in the order you want to install them.
 - When you mark a vertex as **all done**, put it at the **beginning** of the list.
- dpkg
 - coreutils
 - tar
 - libbz2
 - libselinux1
 - multiarch_support



For implementation, see IPython notebook

```
In [69]: print(G)
```

```
CS161Graph with:  
    Vertices:  
        dkpg,coreutils,multiarch_support,libselinux1,libbz2,tar,  
    Edges:  
        (dkpg,multiarch_support) (dkpg,coreutils) (dkpg,tar) (dkpg,libbz2)  
        (coreutils,libbz2) (coreutils,libsSelinux1) (libsSelinux1,multiarch_support)  
        (libbz2,libsSelinux1)
```

```
In [71]: V = topoSort(G)  
for v in V:  
    print(v)
```

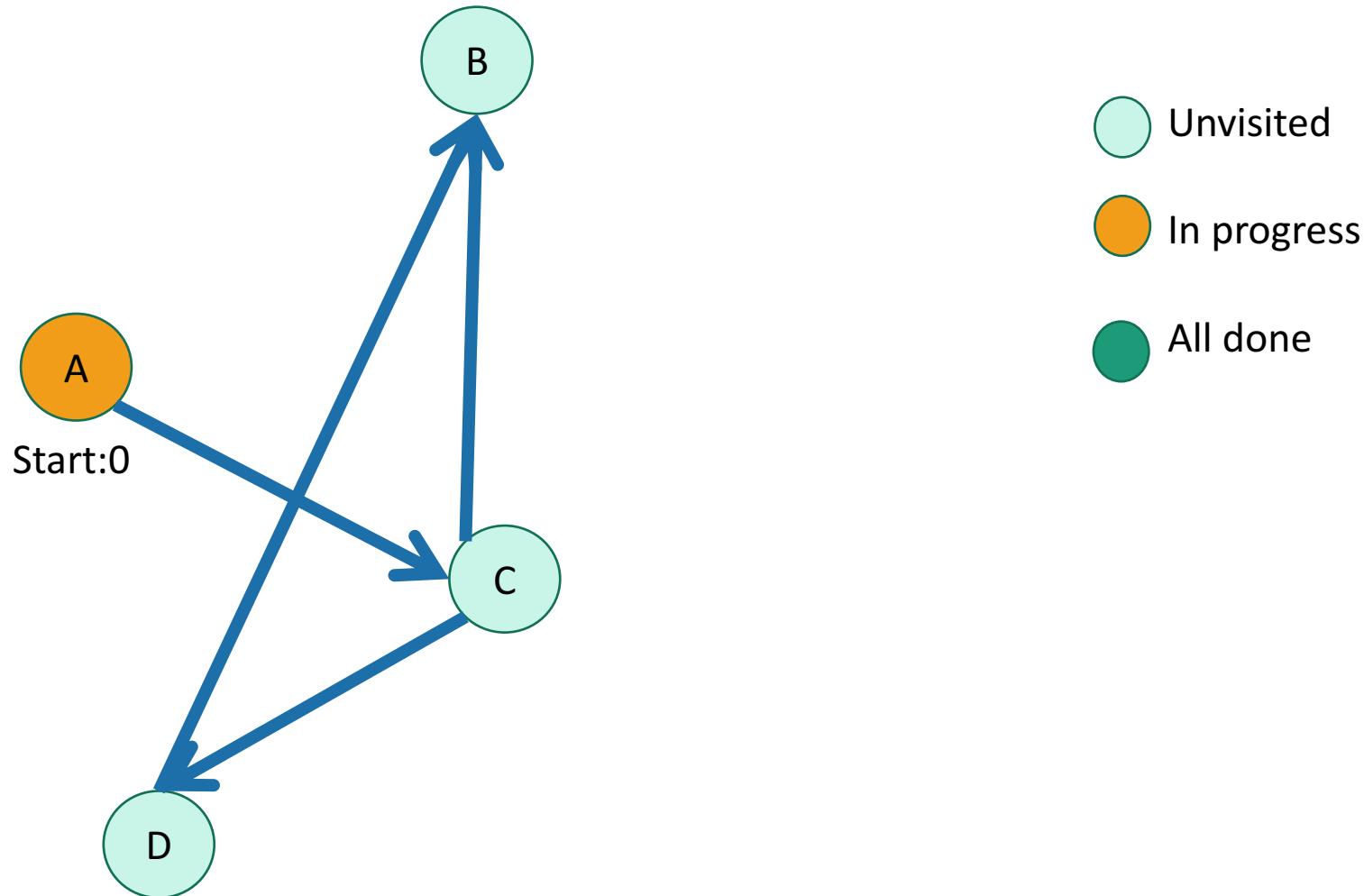
```
dkpg  
tar  
coreutils  
libbz2  
libsSelinux1  
multiarch_support
```

What did we just learn?

- DFS can help you solve the **TOPOLOGICAL SORTING PROBLEM**
 - That's the fancy name for the problem of finding an ordering that respects all the dependencies
- Thinking about the DFS tree is helpful.

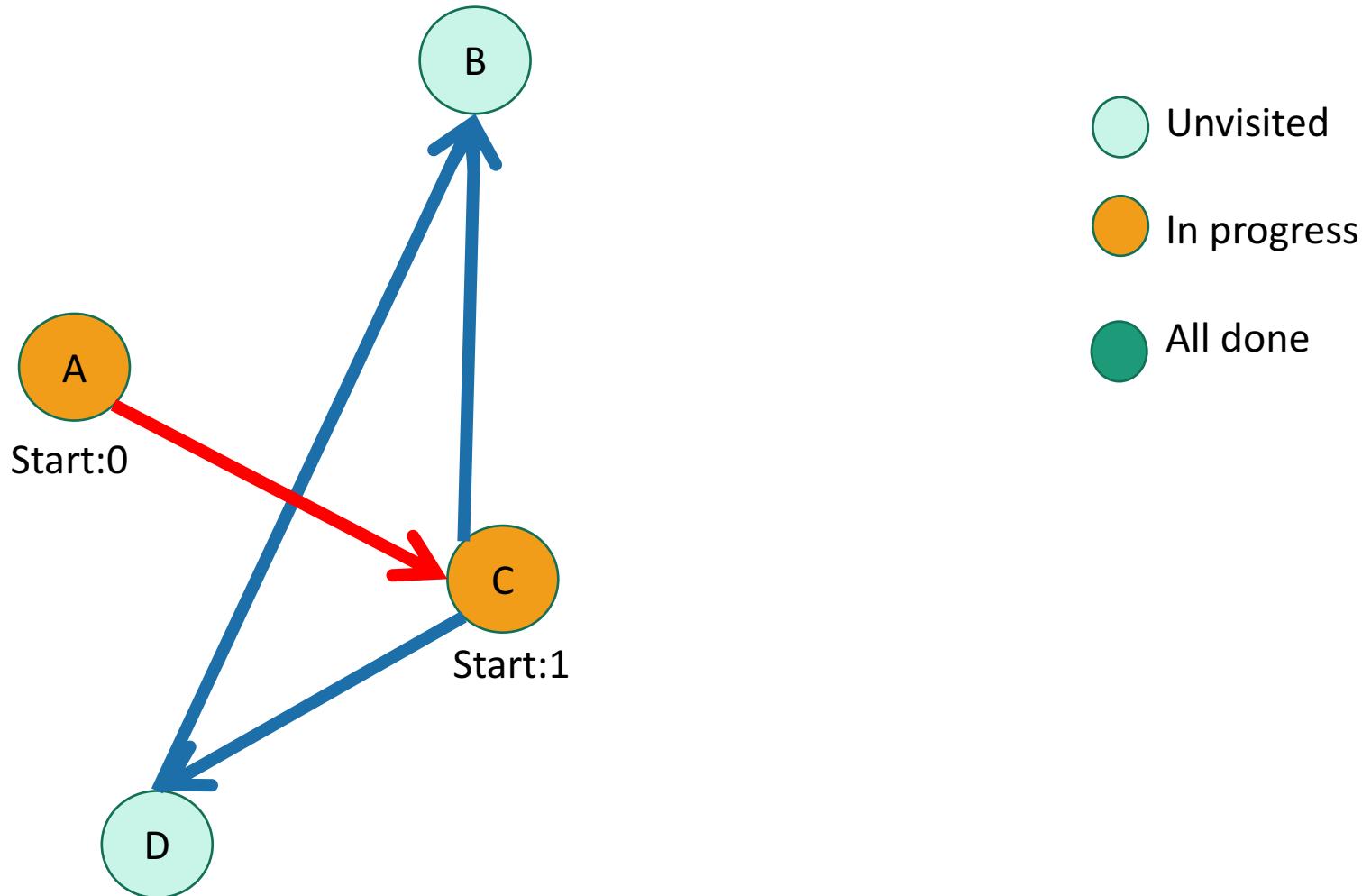
Example:

This example skipped in class – here for reference.



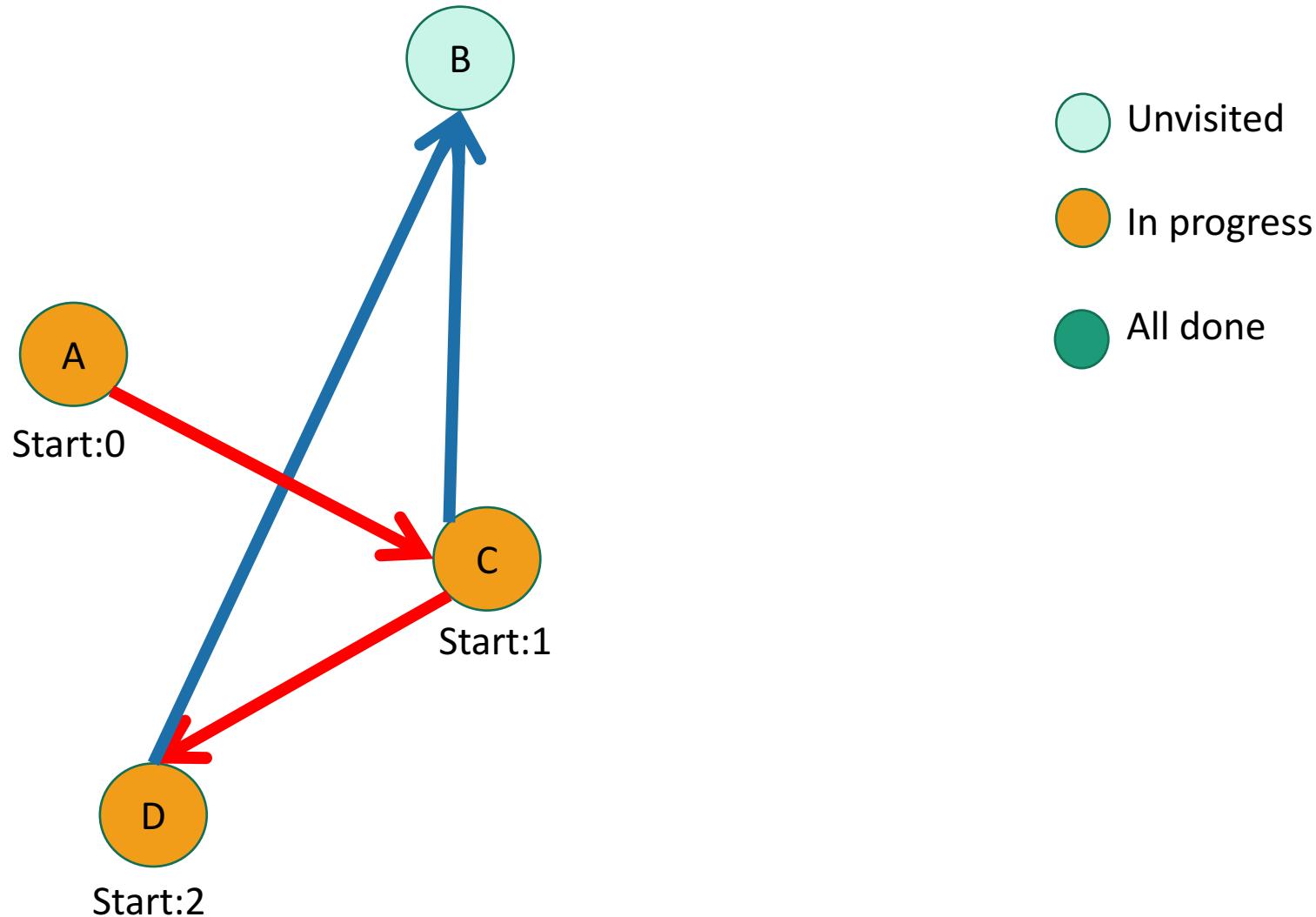
Example

This example skipped in class – here for reference.



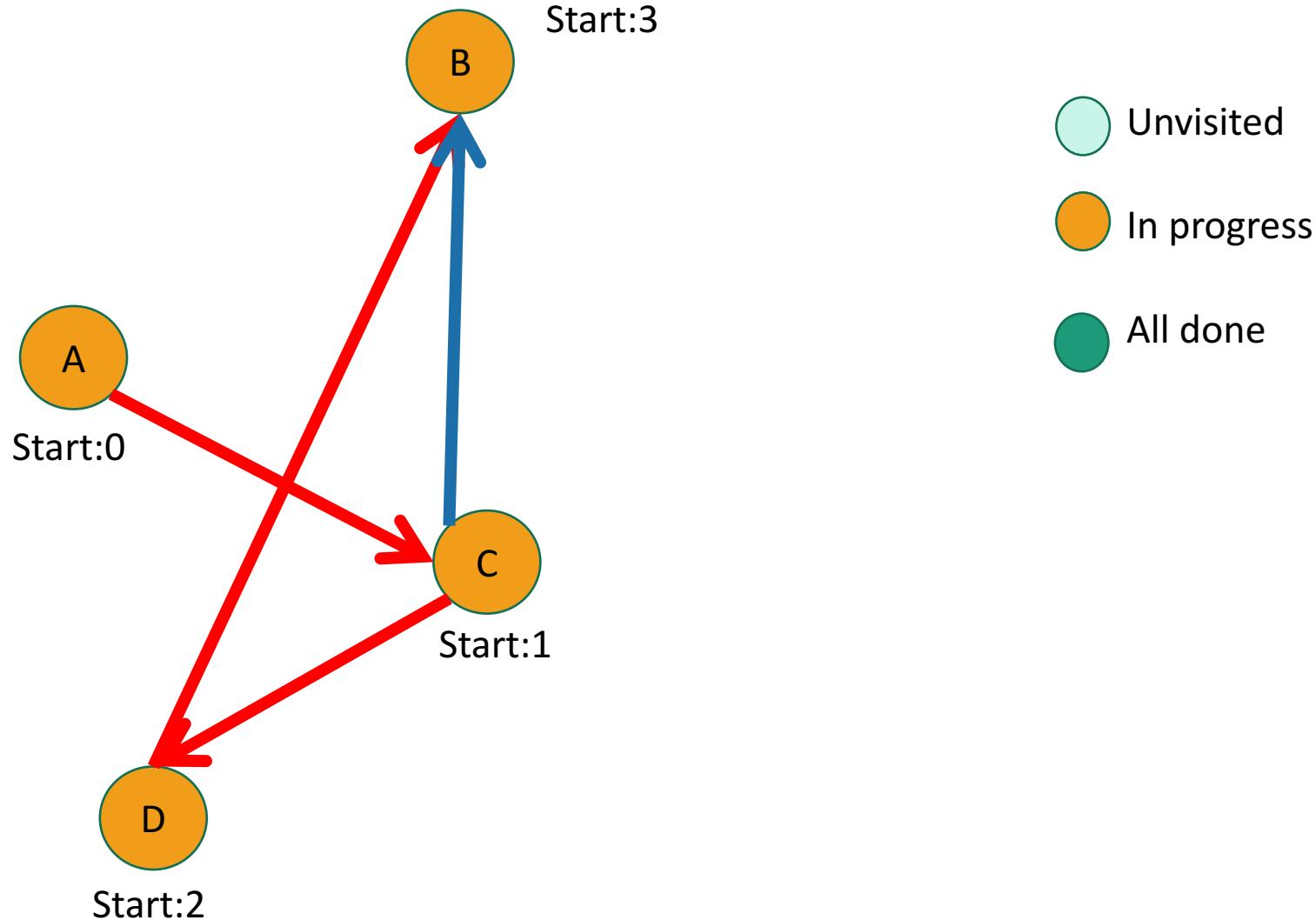
Example

This example skipped in class – here for reference.



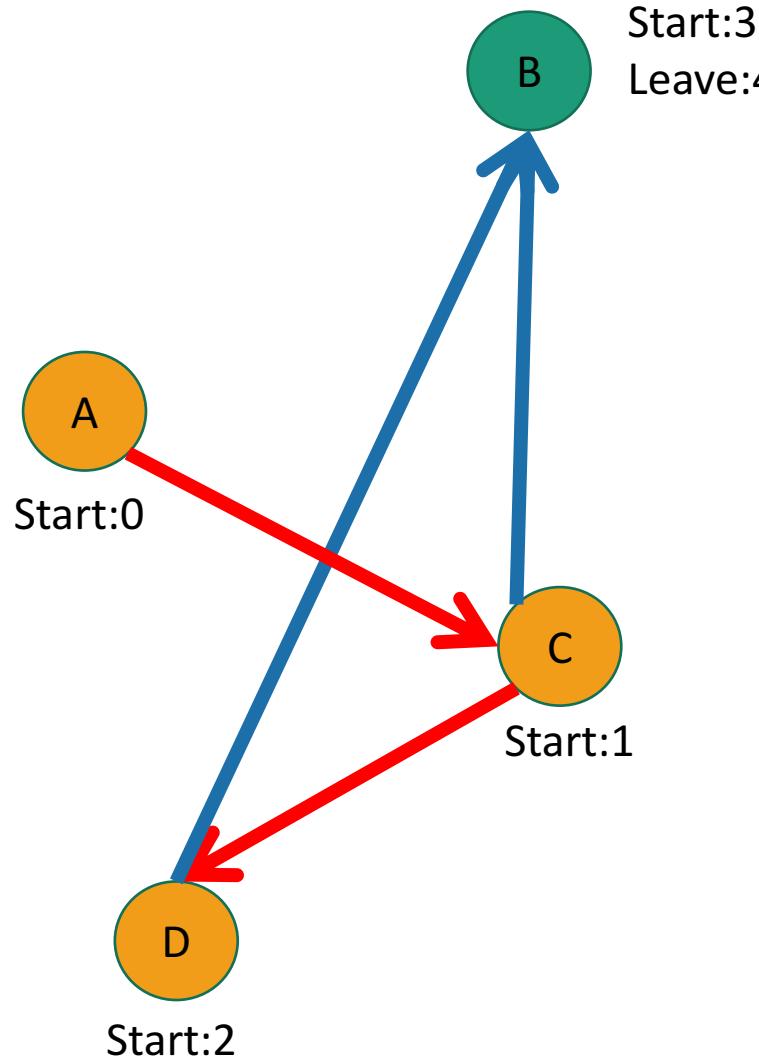
Example

This example skipped in class – here for reference.



Example

This example skipped in class – here for reference.

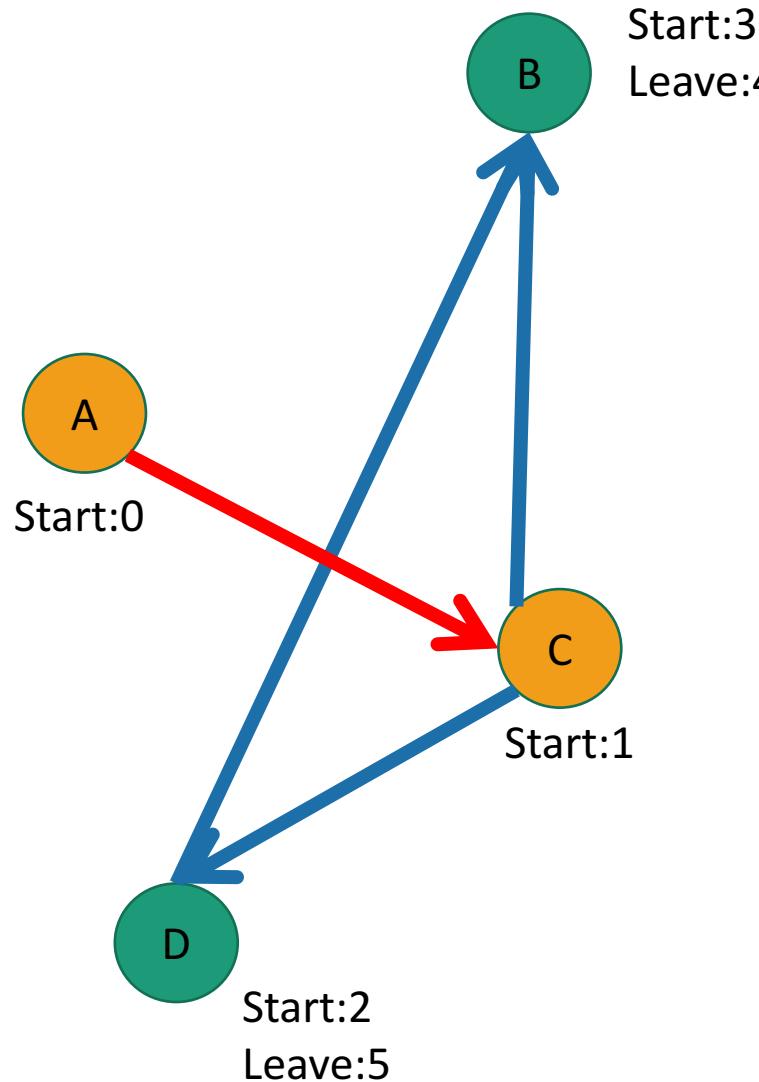


- Unvisited (Light Green)
- In progress (Orange)
- All done (Teal)



Example

This example skipped in class – here for reference.

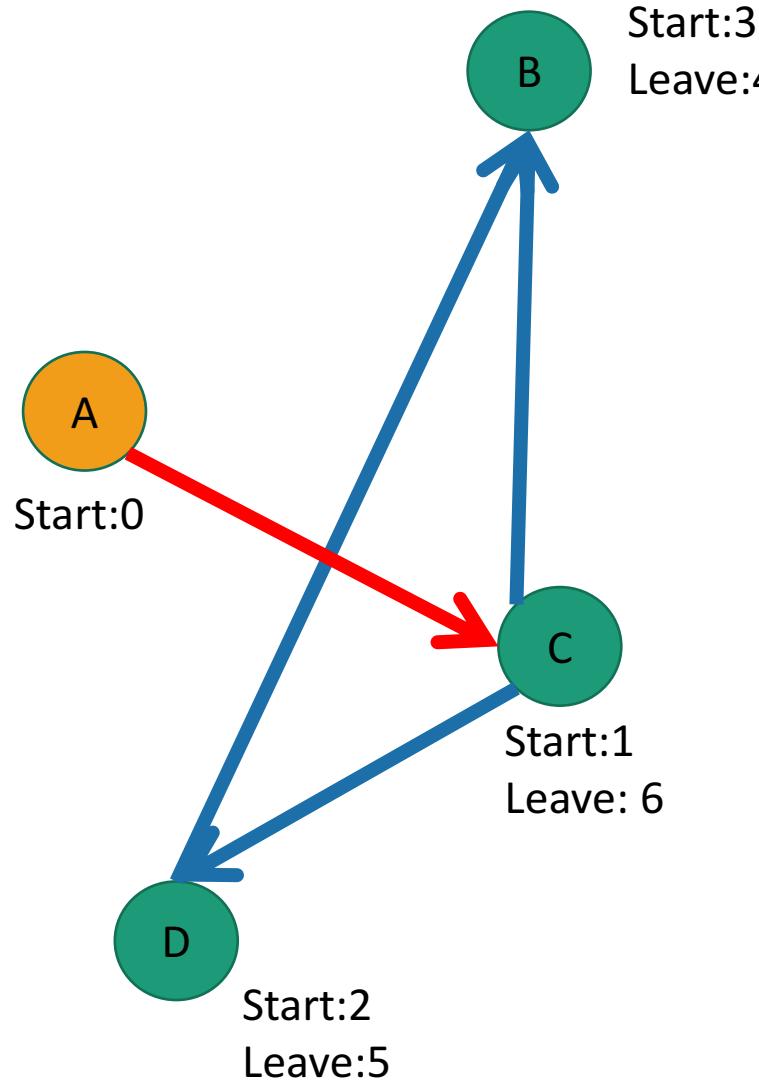


- Unvisited (light green circle)
- In progress (orange circle)
- All done (teal circle)



Example

This example skipped in class – here for reference.



Unvisited

In progress

All done

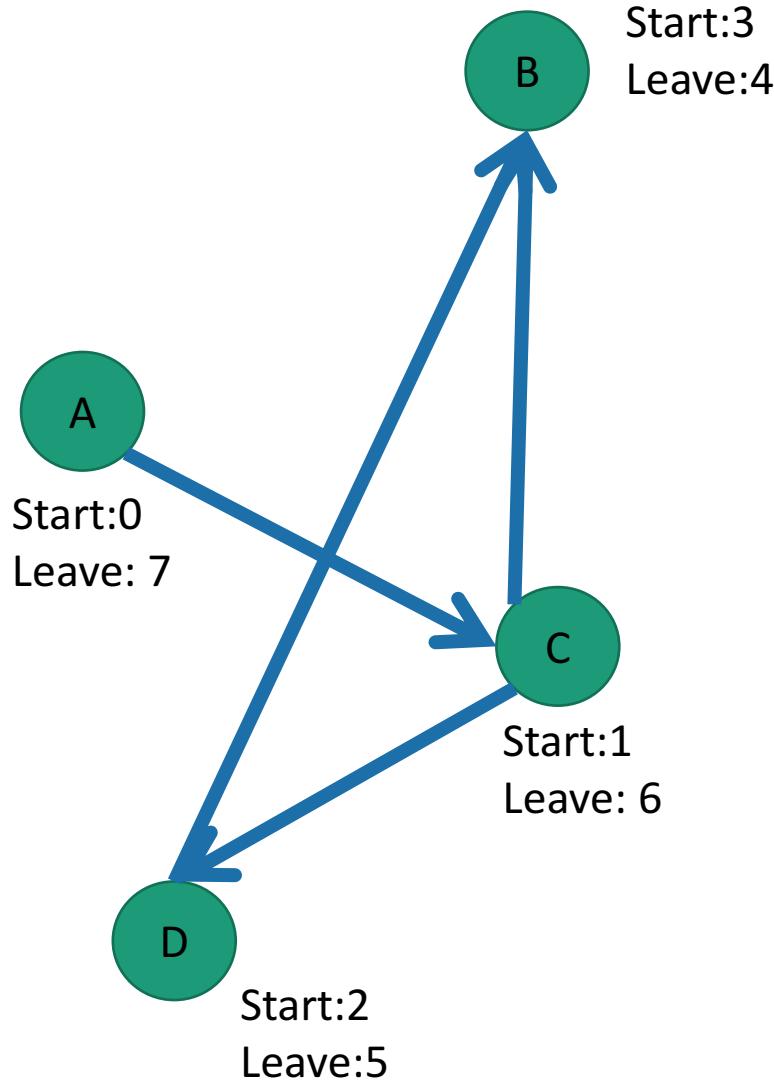
C

D

B

Example

This example skipped in class – here for reference.



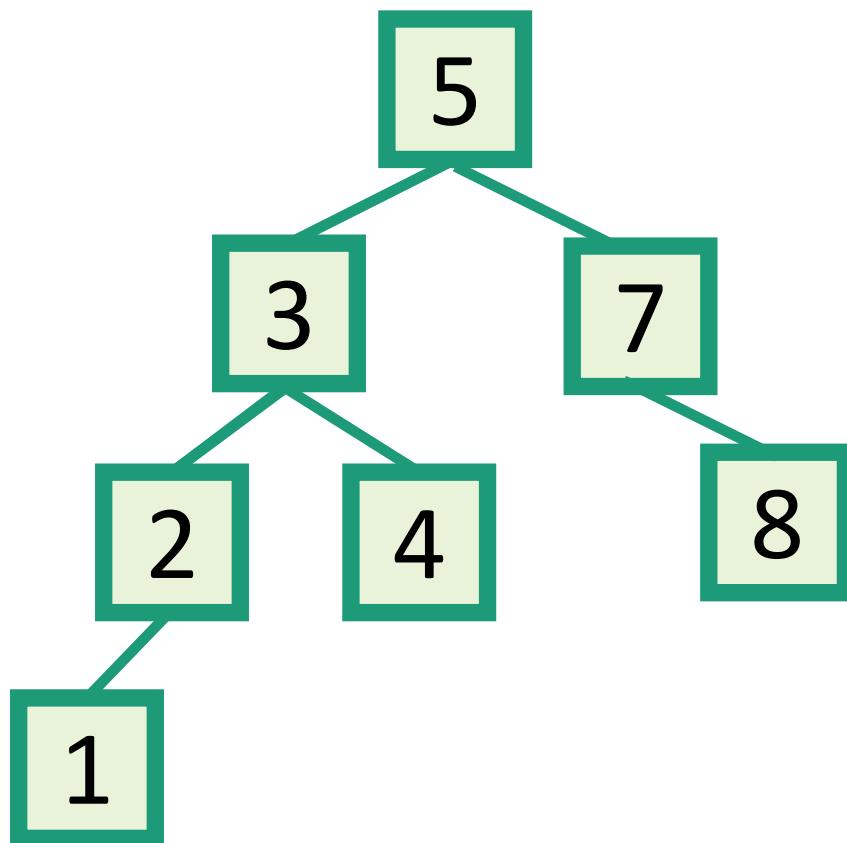
- Unvisited
- In progress
- All done

Do them in this order:



Another use of DFS

- In-order enumeration of binary search trees



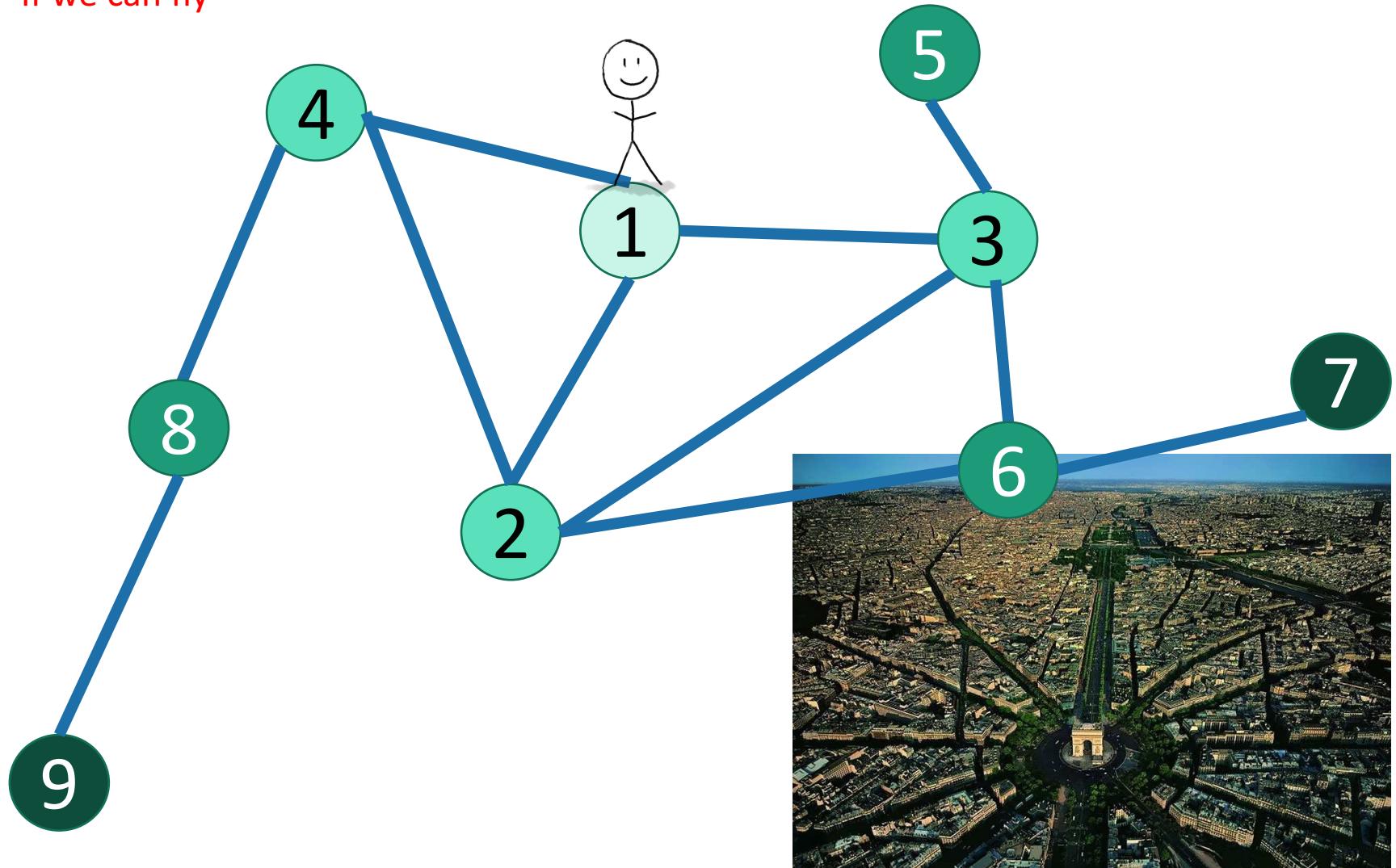
Given a binary search tree, output all the nodes **in order**.

Instead of outputting a node when you are done with it, output it when you are done with the left child and before you begin the right child.

Part 2: breadth-first search

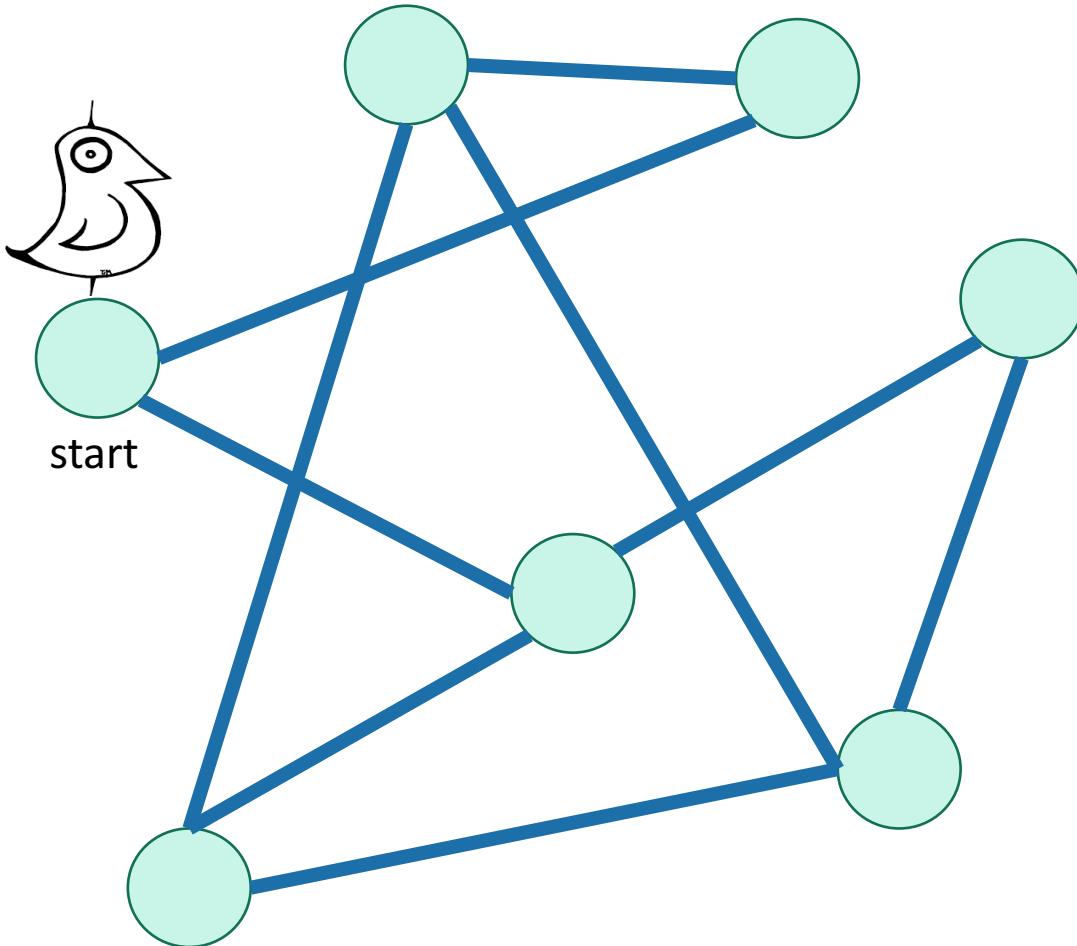
How do we explore a graph?

If we can fly



Breadth-First Search

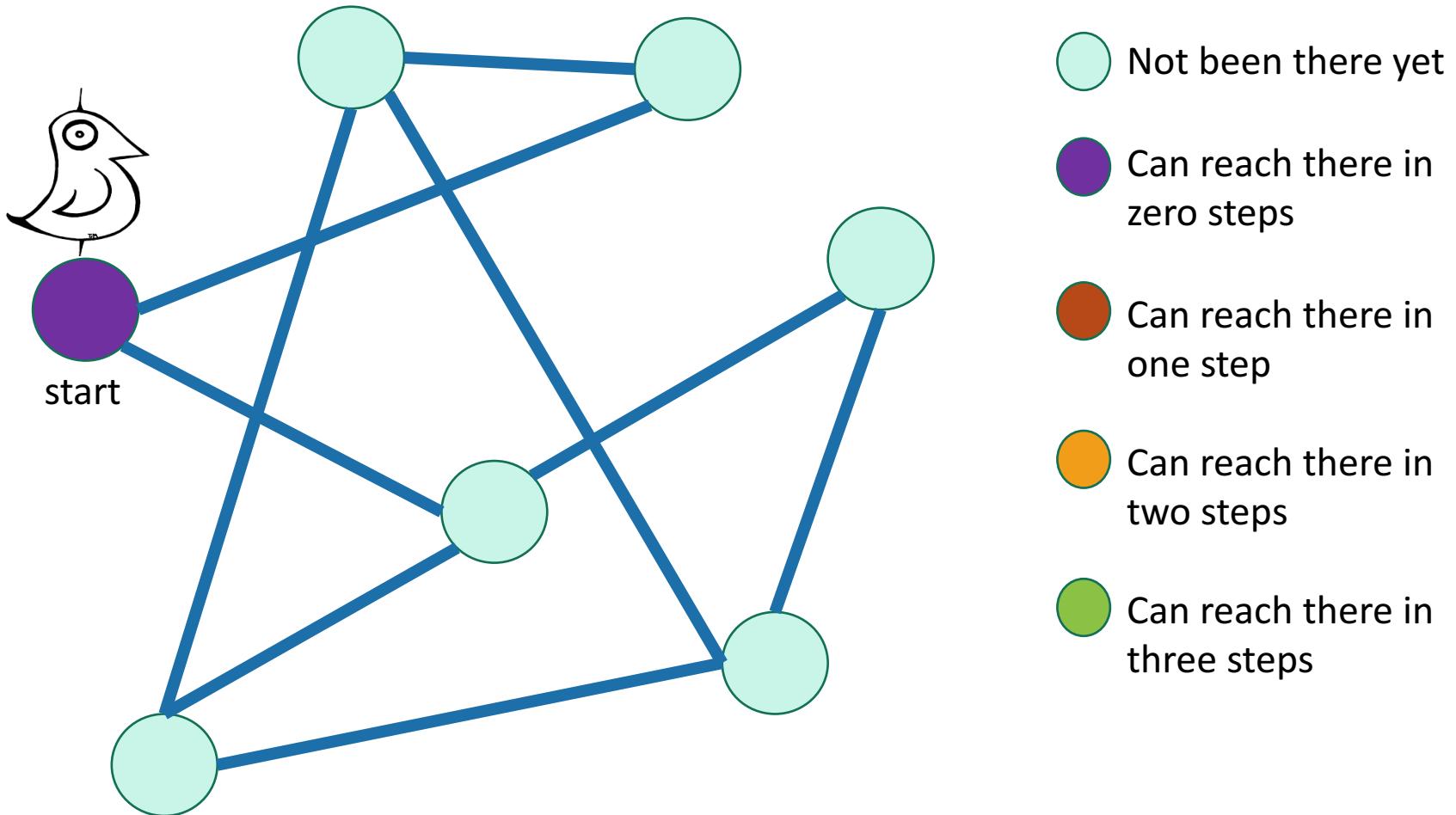
Exploring the world with a bird's-eye view



- Not been there yet
- Can reach there in zero steps
- Can reach there in one step
- Can reach there in two steps
- Can reach there in three steps

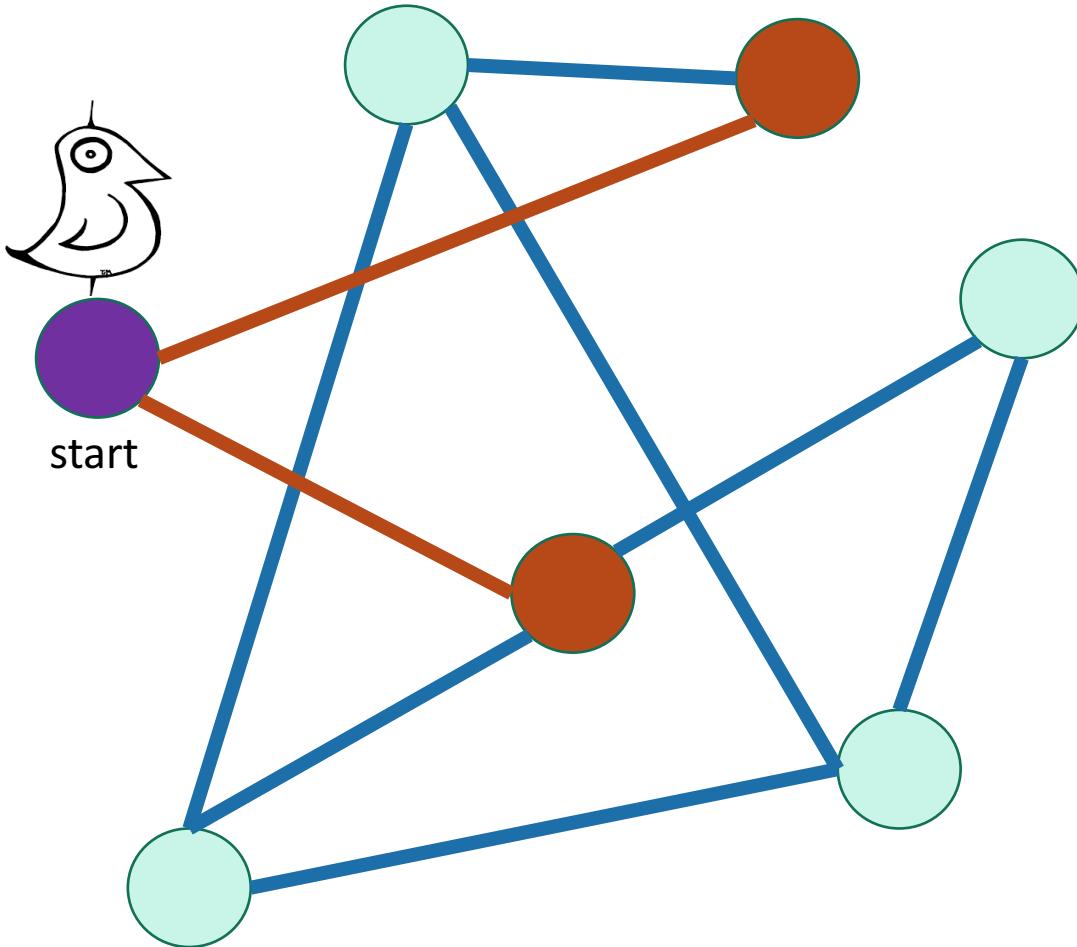
Breadth-First Search

Exploring the world with a bird's-eye view



Breadth-First Search

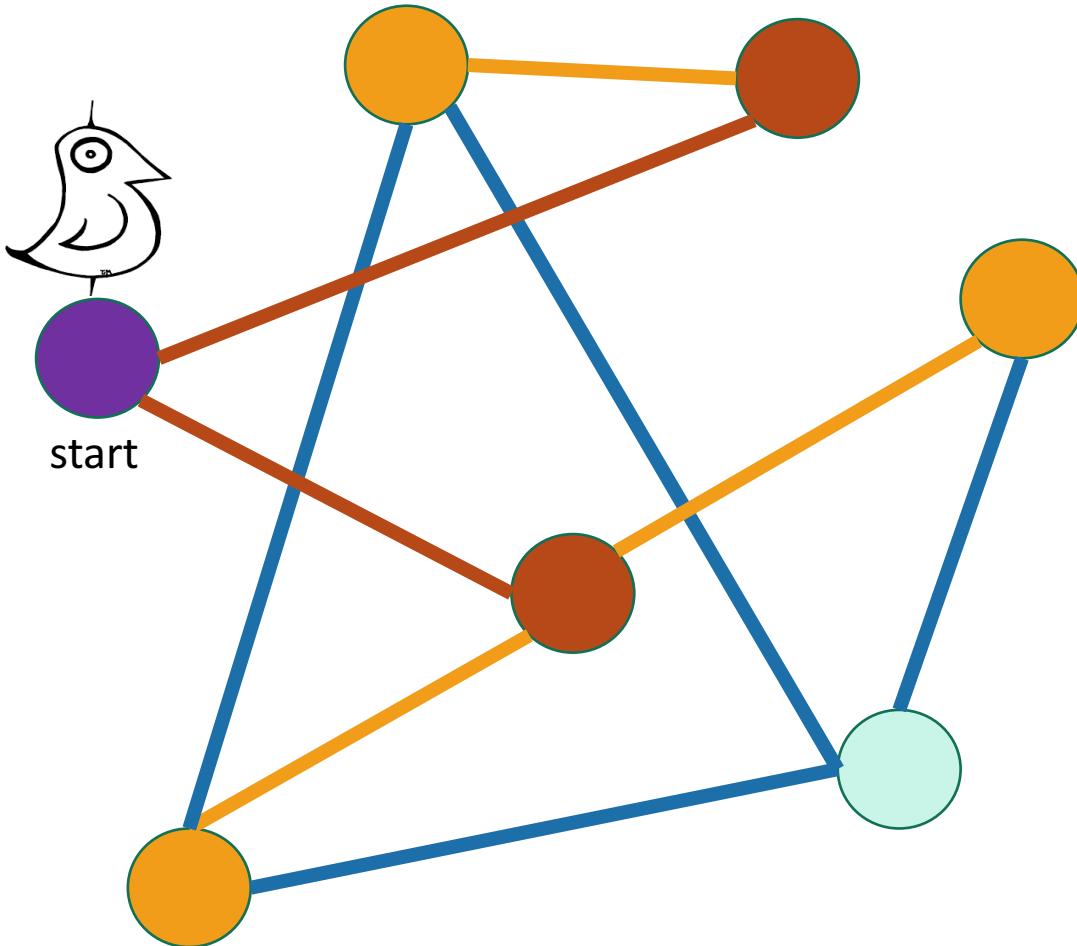
Exploring the world with a bird's-eye view



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Breadth-First Search

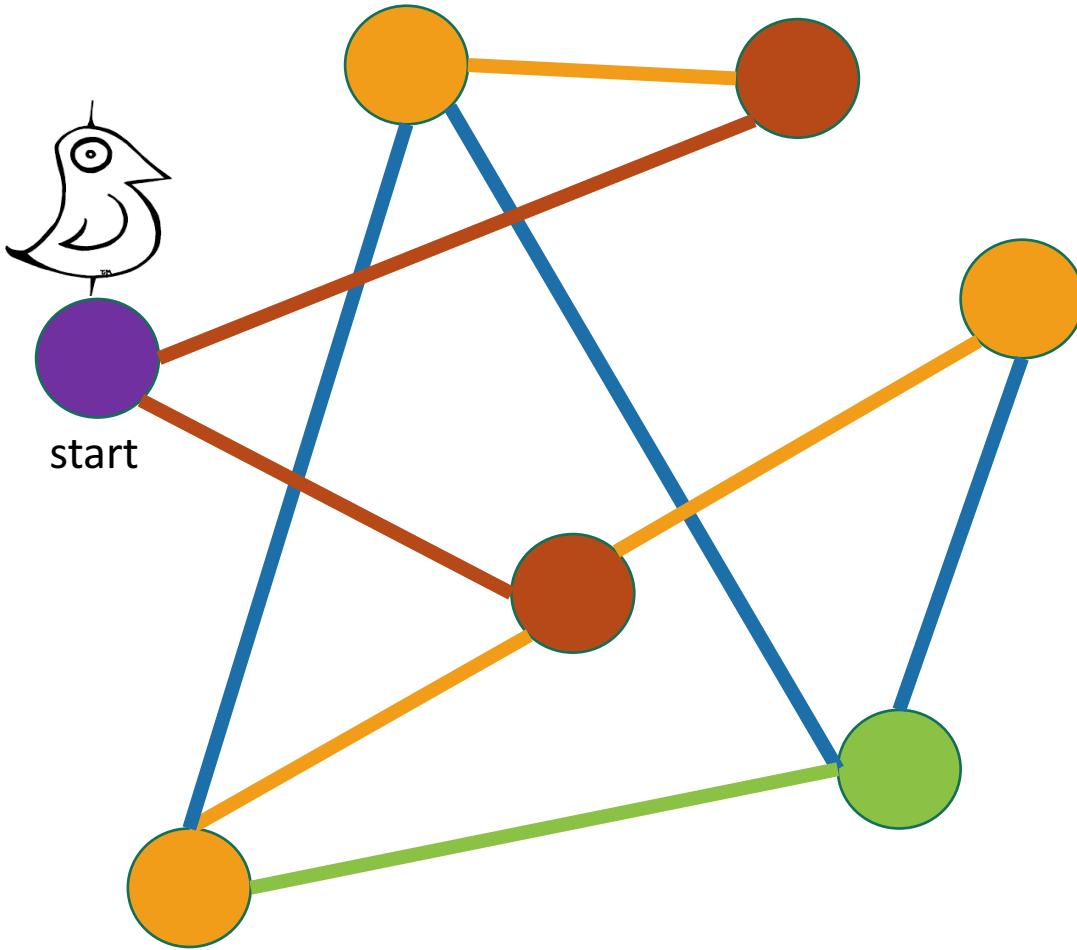
Exploring the world with a bird's-eye view



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Breadth-First Search

Exploring the world with a bird's-eye view



Not been there yet

Can reach there in zero steps

Can reach there in one step

Can reach there in two steps

Can reach there in three steps

World:
EXPLORED!

Same disclaimer as for DFS: you may have seen other ways to implement this,
this will be convenient for us.

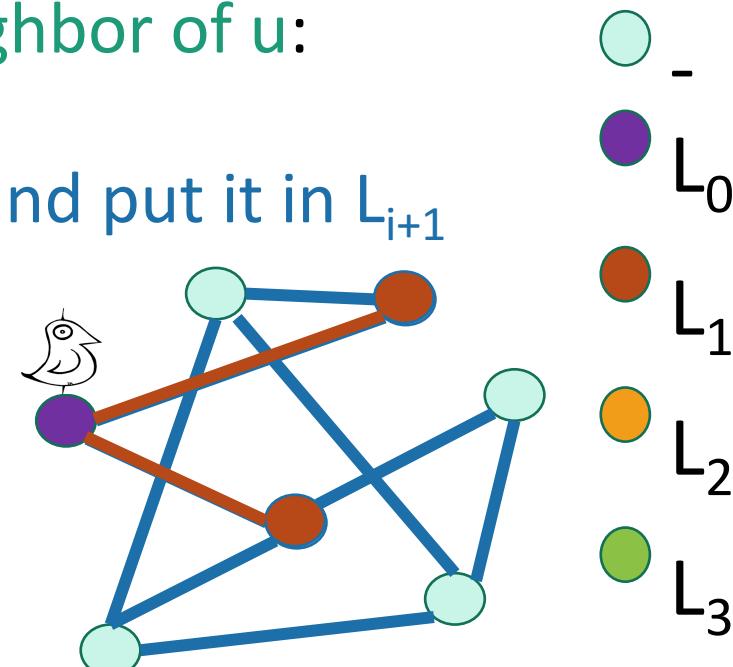
Breadth-First Search

Exploring the world with pseudocode

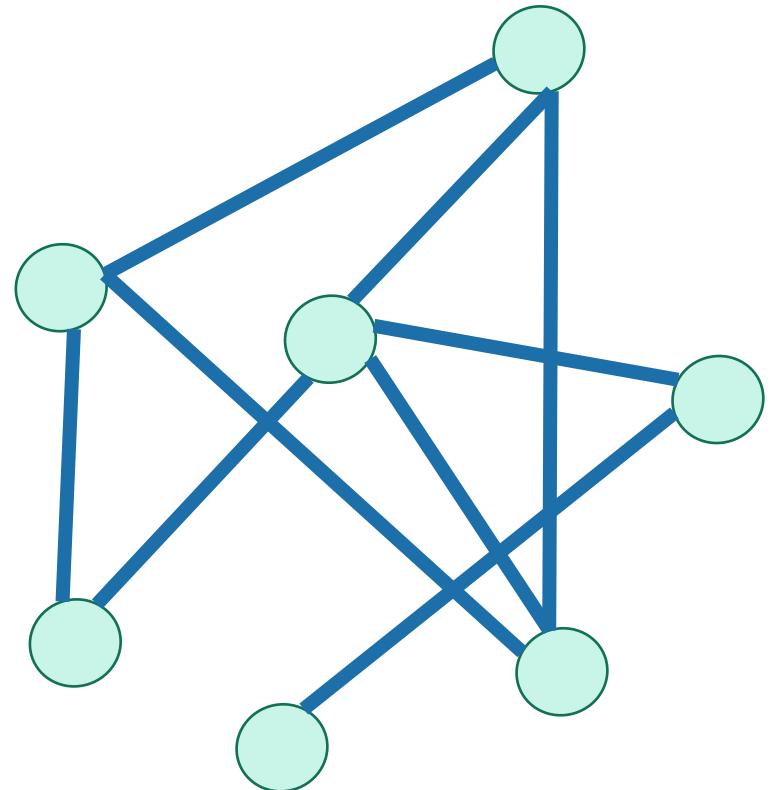
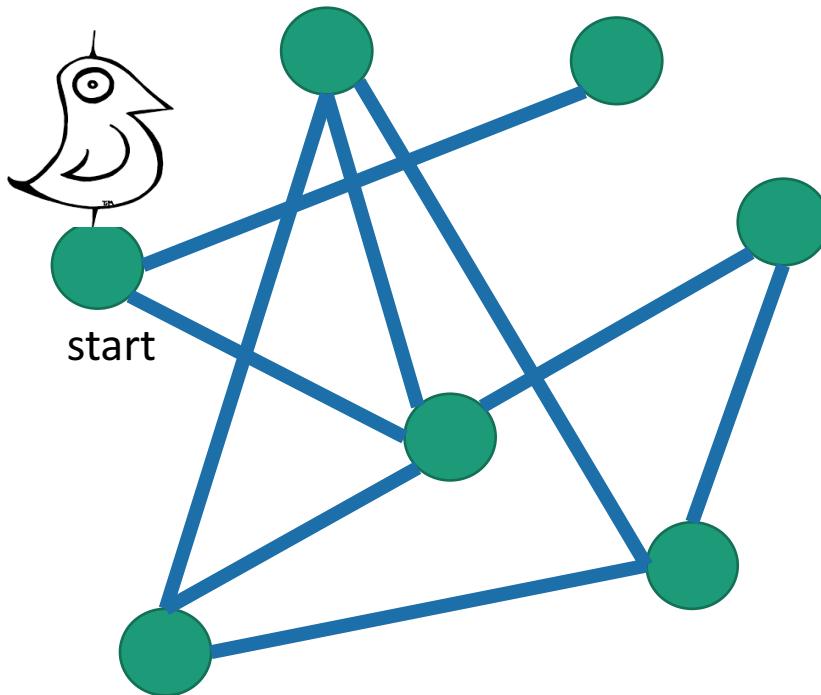
- Set $L_i = []$ for $i=1,\dots,n$
- $L_0 = \{w\}$, where w is the start node
- **For** $i = 0, \dots, n-1$:
 - **For** u in L_i :
 - **For** each v which is a neighbor of u :
 - **If** v isn't yet visited:
 - mark v as visited, and put it in L_{i+1}

L_i is the set of nodes
we can reach in i
steps from w

Go through all the nodes
in L_i and add their
unvisited neighbors to L_{i+1}



BFS also finds all the nodes
reachable from the starting point



It is also a good way to find all
the **connected components**.

Running time

To explore the whole thing

- Explore the connected components one-by-one.
- Same argument as DFS: running time is

$$O(n + m)$$

Verify these!

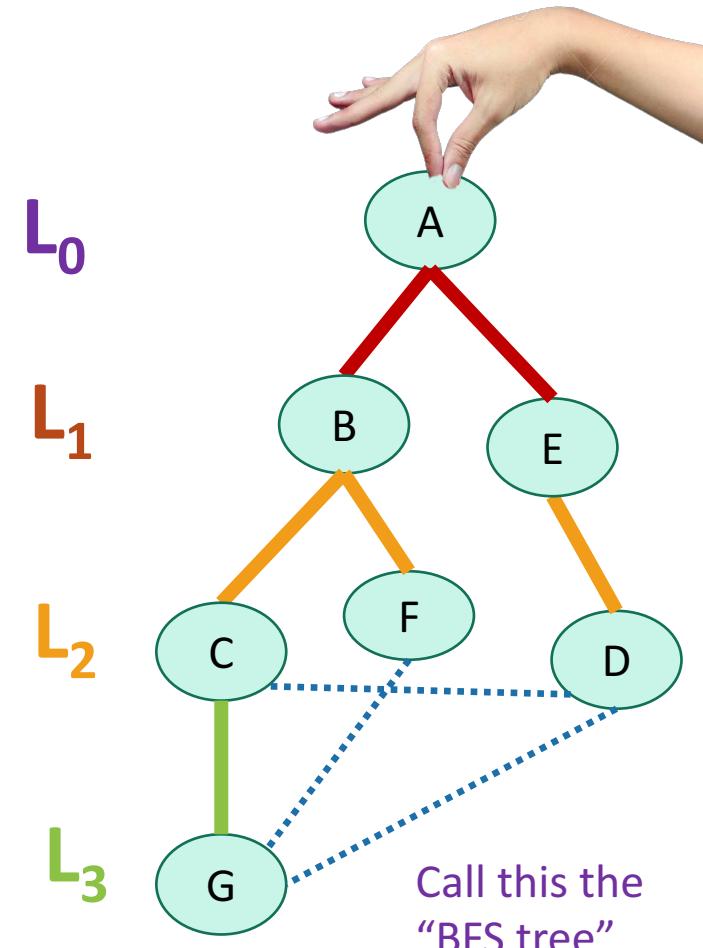
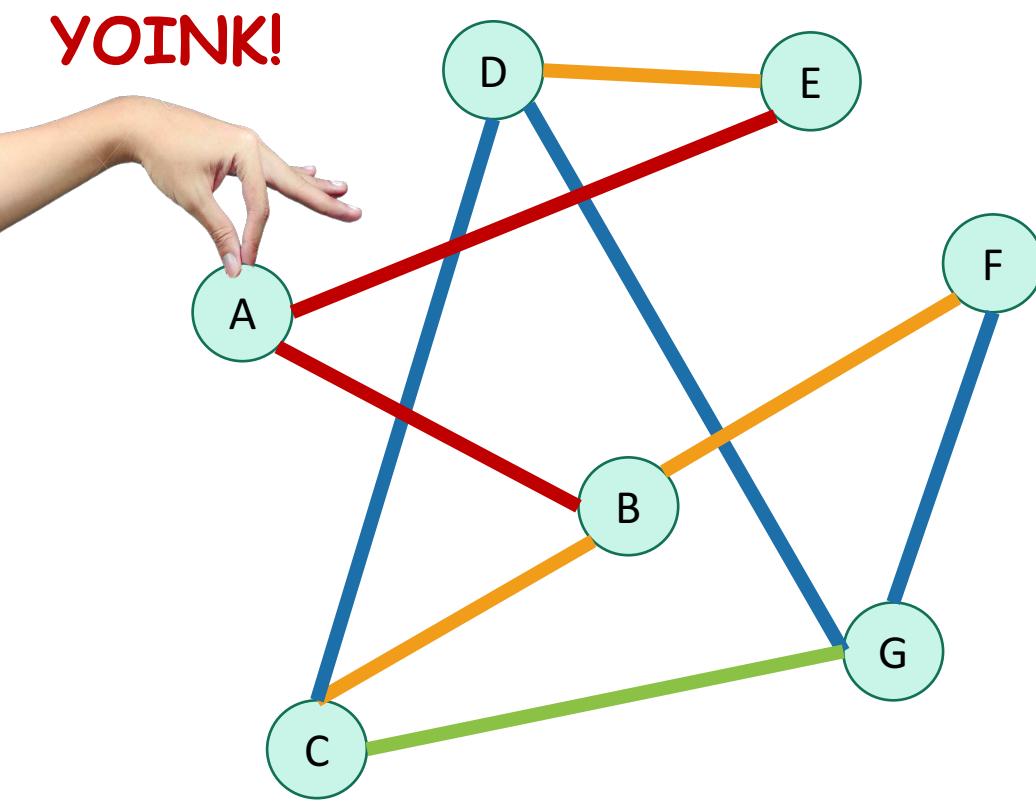


- Like DFS, BFS also works fine on directed graphs.

Siggi the Studious Stork

Why is it called breadth-first?

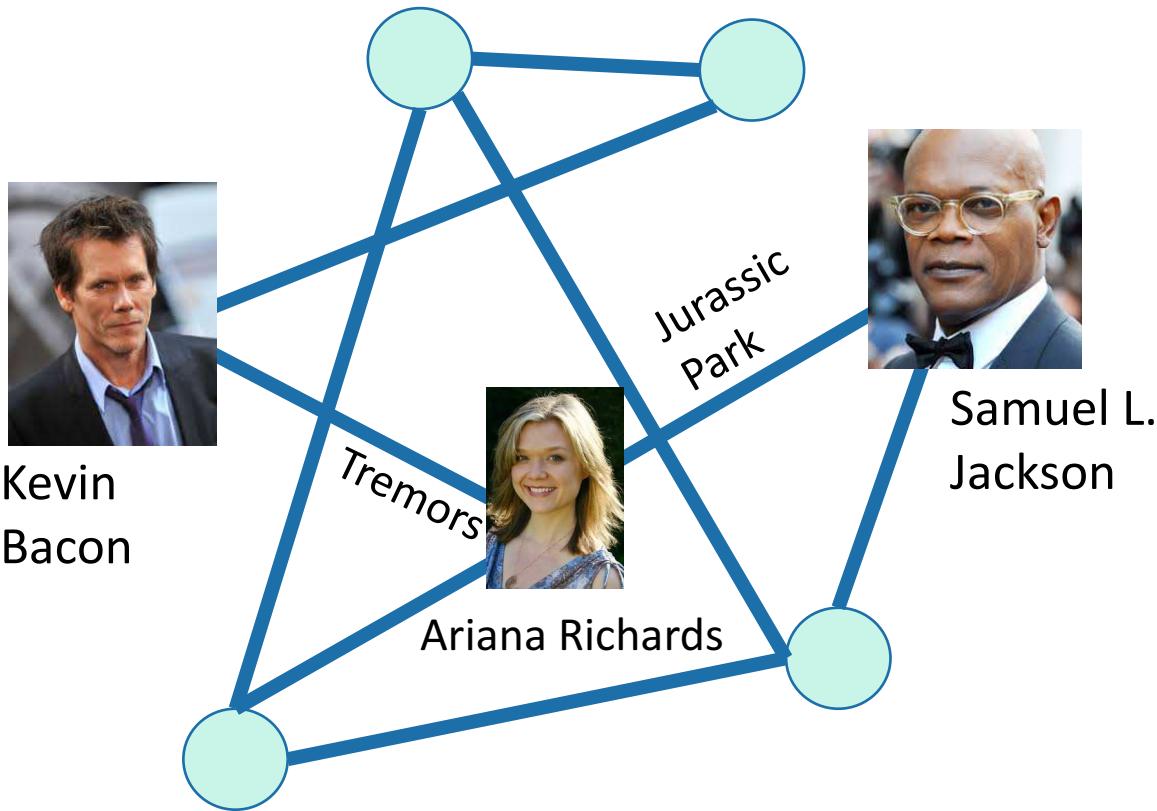
- We are implicitly building a tree:



- And first we go as broadly as we can.

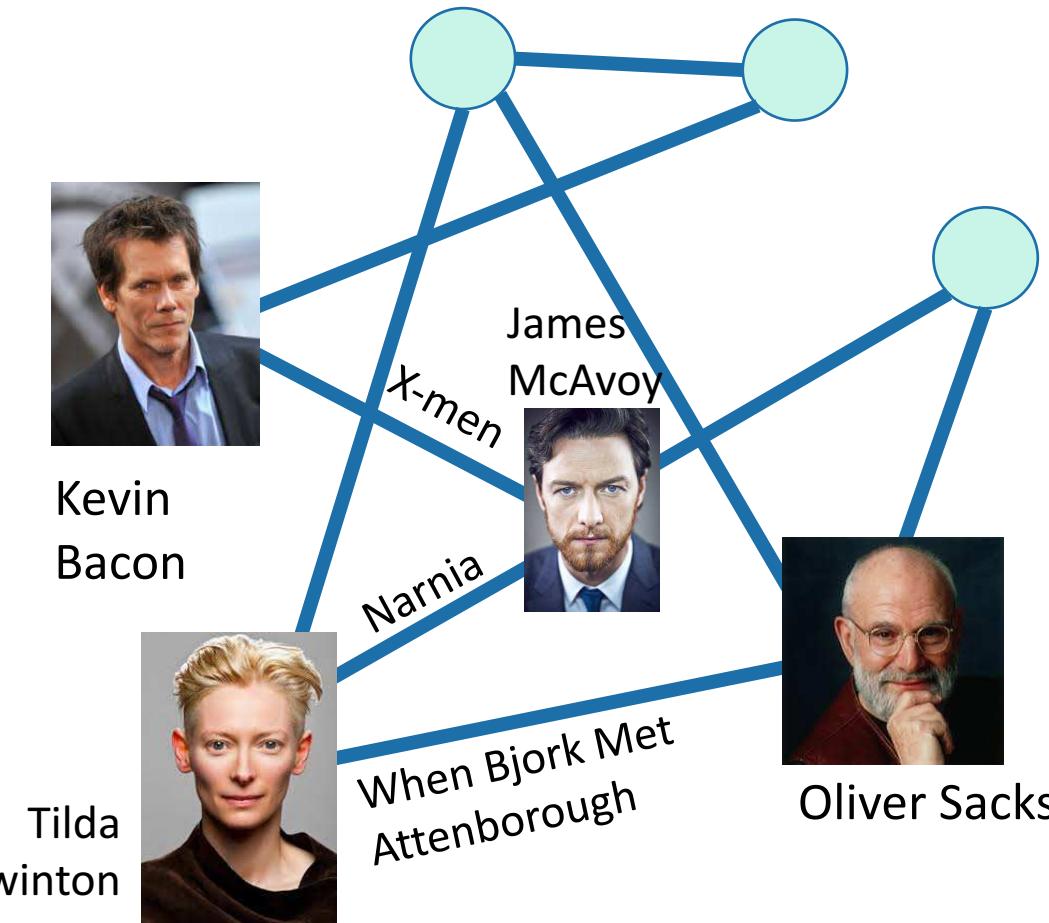
Pre-lecture exercise

- What is Samuel L. Jackson's Bacon number?



(Answer: 2)

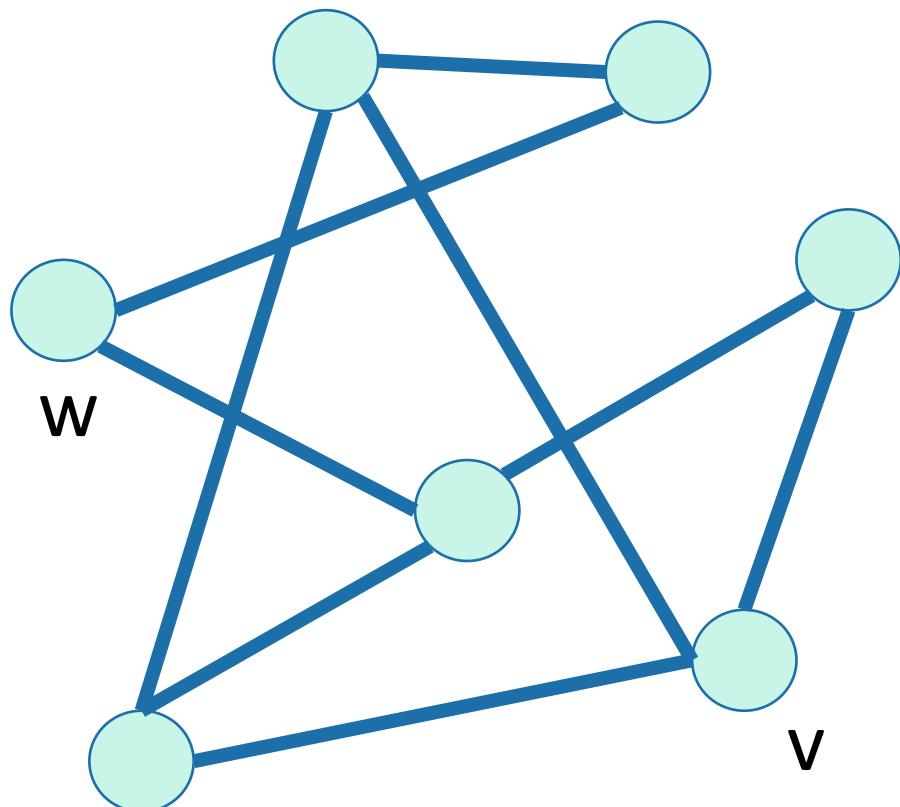
I wrote the pre-lecture exercise before I realized that I really wanted an example with distance 3



It is really hard to find people with Bacon number 3!

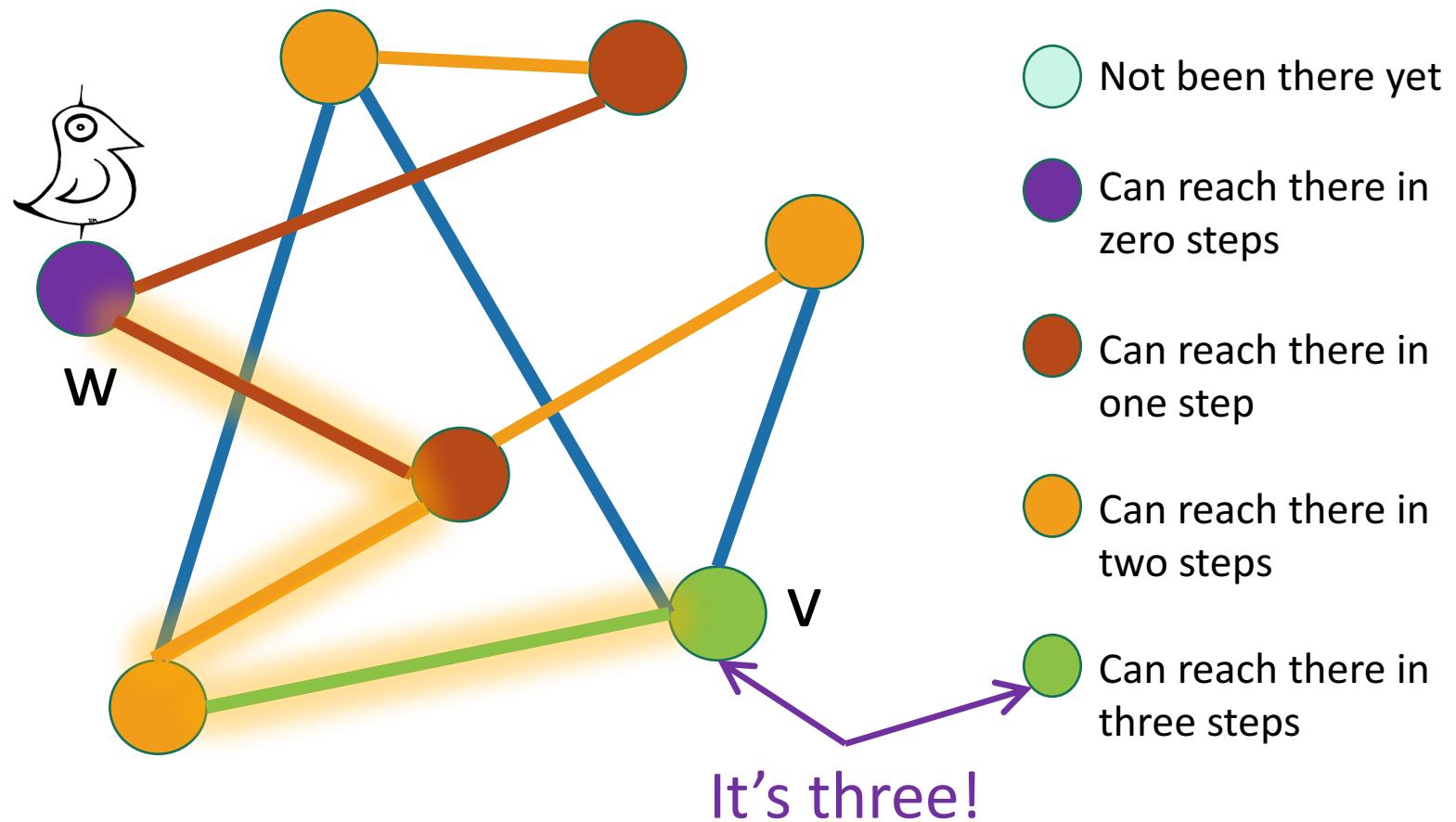
Application: shortest path

- How long is the shortest path between w and v?



Application: shortest path

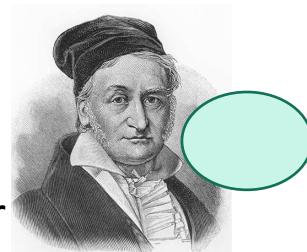
- How long is the shortest path between w and v?



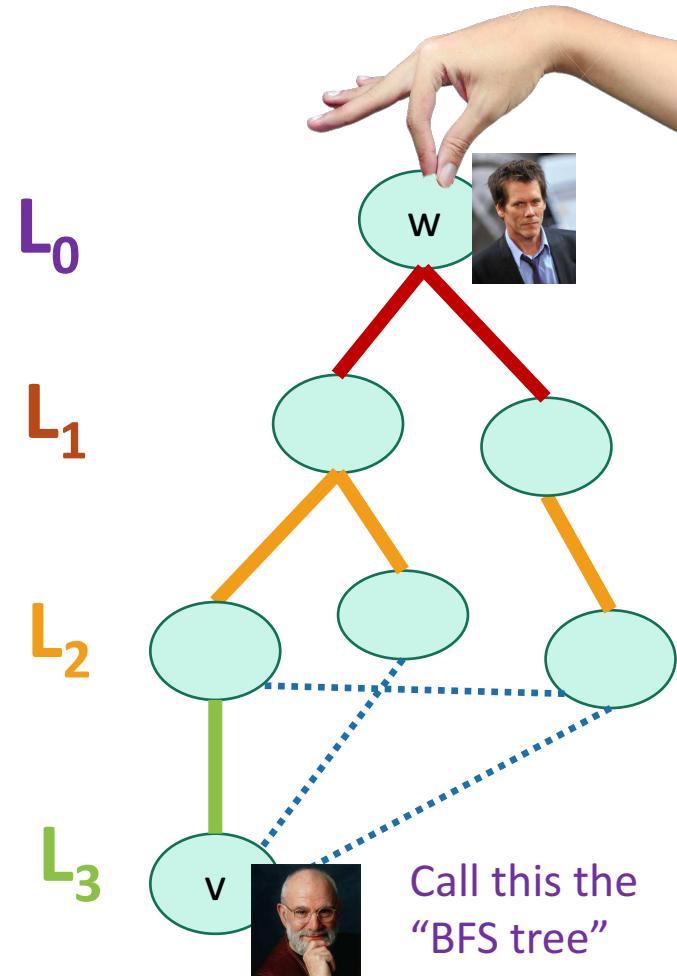
To find the **distance** between w and all other vertices v

- Do a BFS starting at w
- For all v in L_i
 - The shortest path between w and v has length i
 - A shortest path between w and v is given by the path in the BFS tree.
- If we never found v, the distance is infinite.

Gauss has no Bacon number

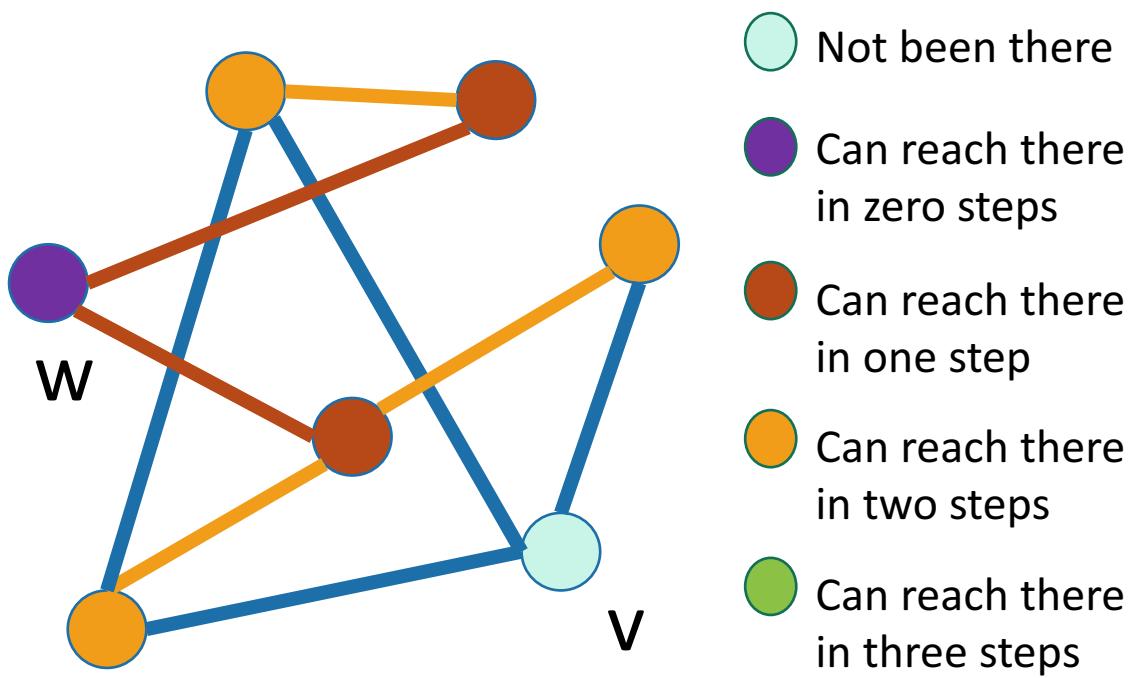


The **distance** between two vertices is the length of the shortest path between them.



Call this the
“BFS tree”

Proof idea (on board)



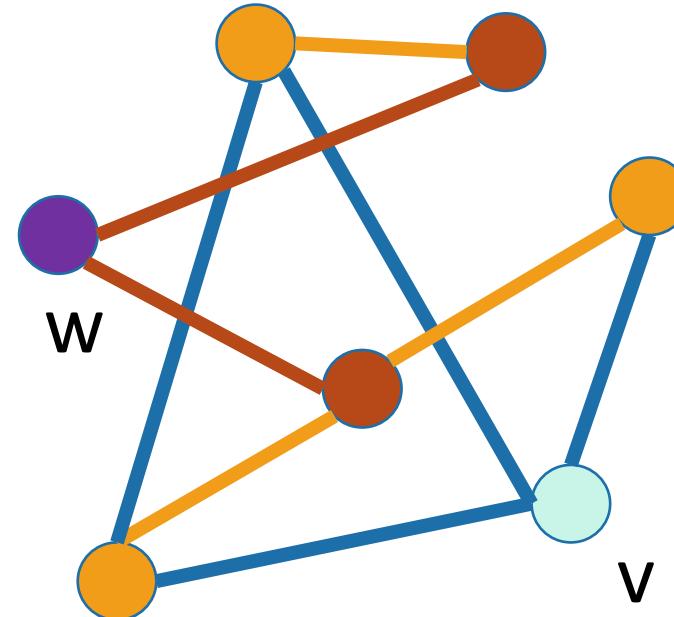
Proof idea

**THIS SLIDE
SKIPPED IN CLASS**



Just the idea...see
CLRS for details!

- Suppose by **induction** it's true for vertices in L_0, L_1, L_2
 - For all $i < 3$, the vertices in L_i have distance i from v .
- **Want to show:** it's true for vertices of distance 3 also.
 - aka, the shortest path between w and v has length 3.
- **Well, it has distance at most 3**
 - Since we just found a path of length 3
- **And it has distance at least 3**
 - Since if it had distance $i < 3$, it would have been in L_i .



- Not been there
- Can reach there in zero steps
- Can reach there in one step
- Can reach there in two steps
- Can reach there in three steps

What did we just learn?

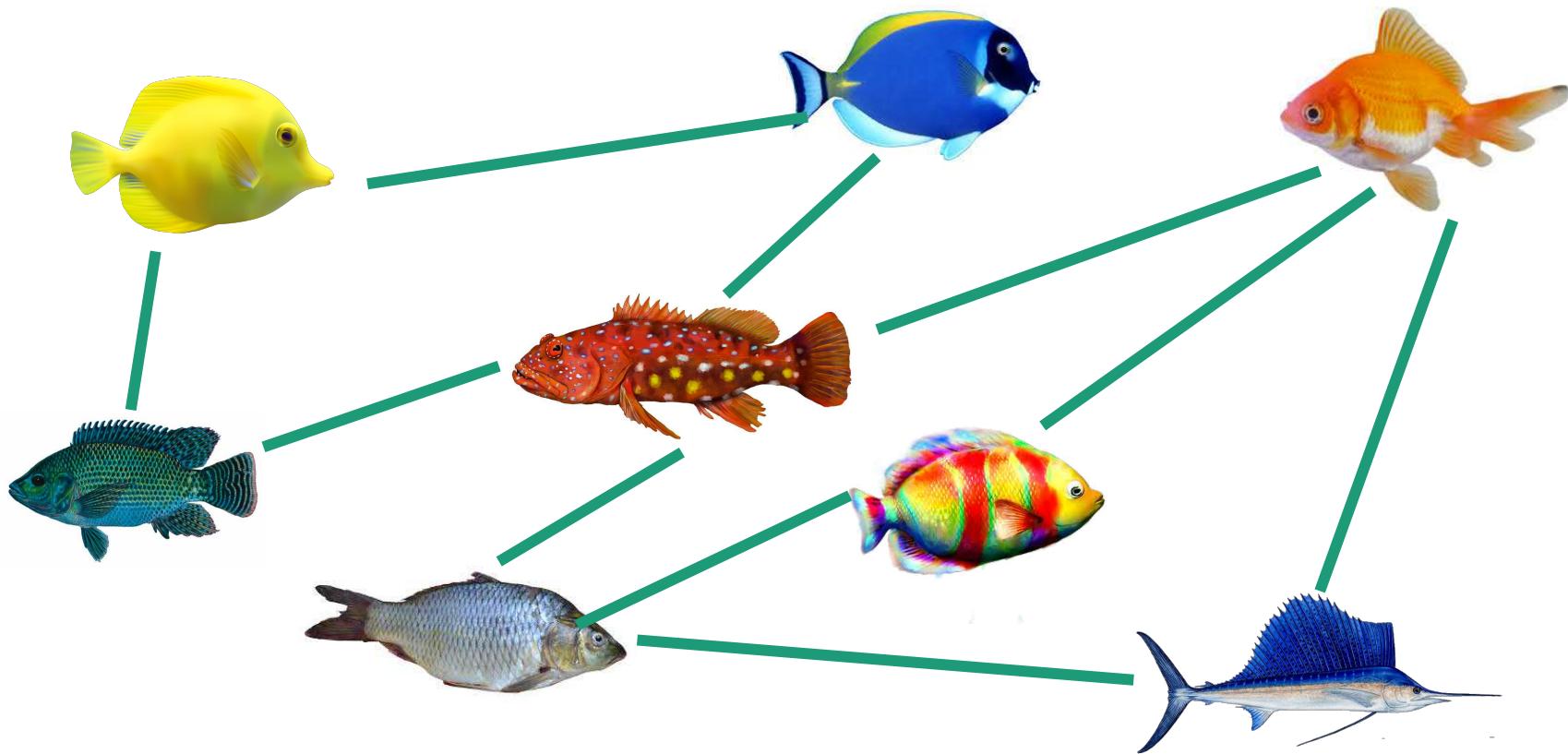
- The BFS tree is useful for computing distances between pairs of vertices.
- We can find the shortest path between u and v in time $O(m)$.

The BSF tree is also helpful for:

- Testing if a graph is bipartite or not.

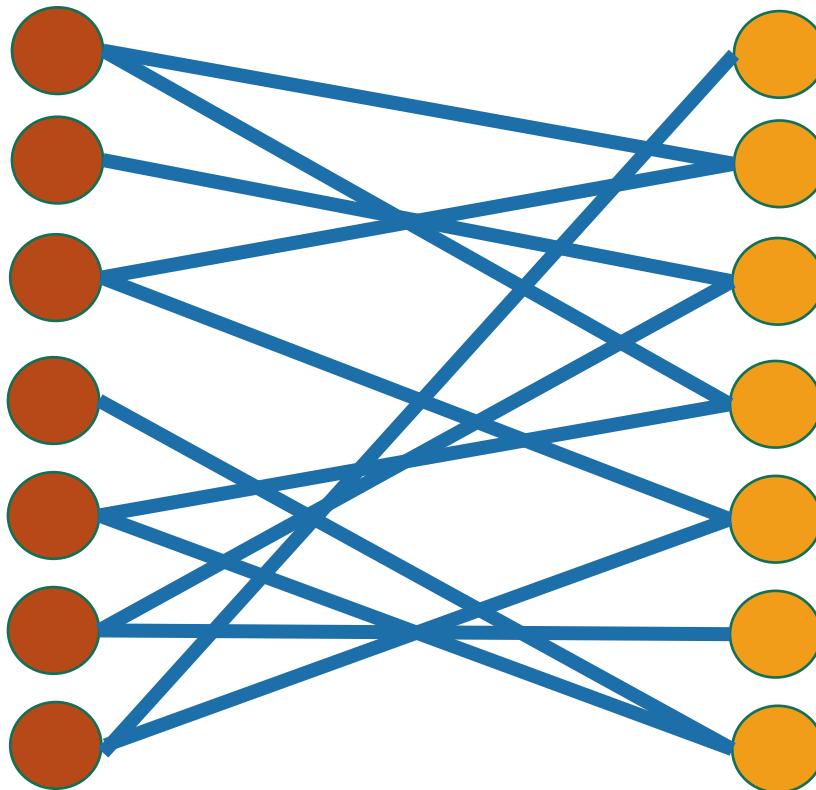
Pre-lecture exercise: fish

- Some pairs of species will fight if put in the same tank.
- You only have two tanks.
- Connected fish will fight.



Application: testing if a graph is bipartite

- Bipartite means it looks like this:



Can color the vertices red and orange so that there are no edges between any same-colored vertices

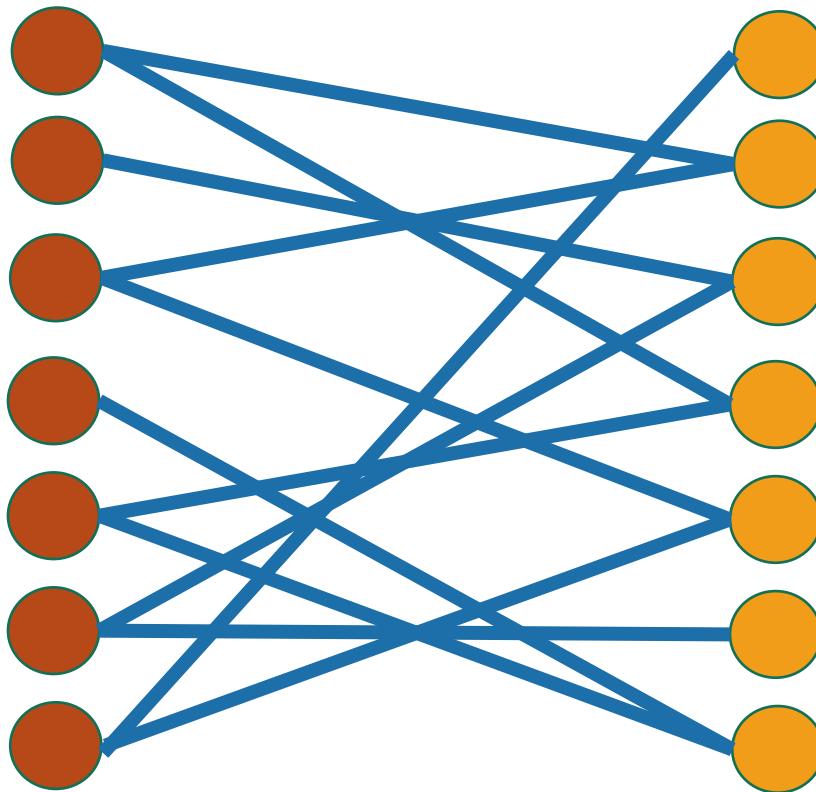
Example:

- are in tank A
- are in tank B
- if the fish fight

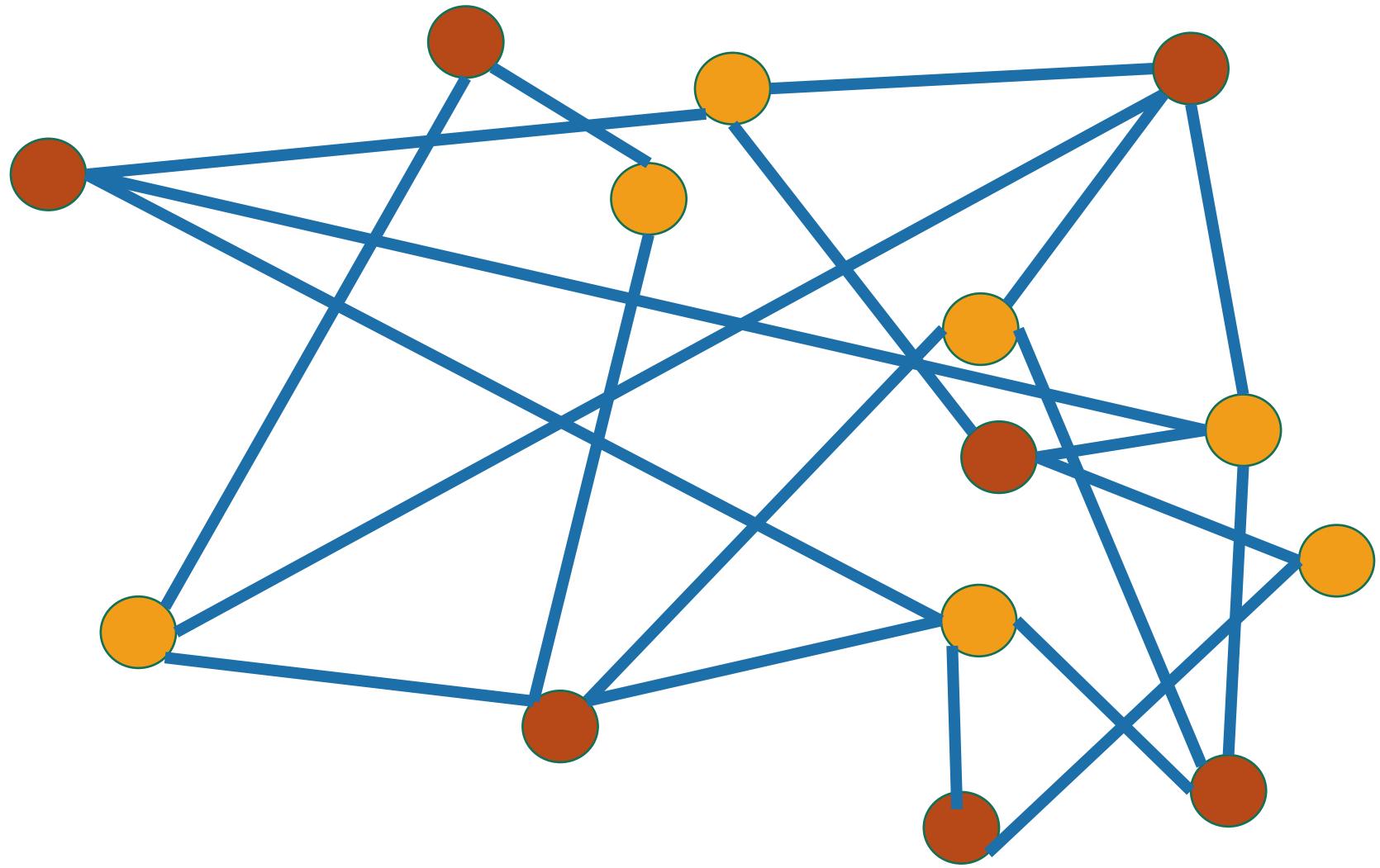
Example:

- are students
- are classes
- if the student is enrolled in the class

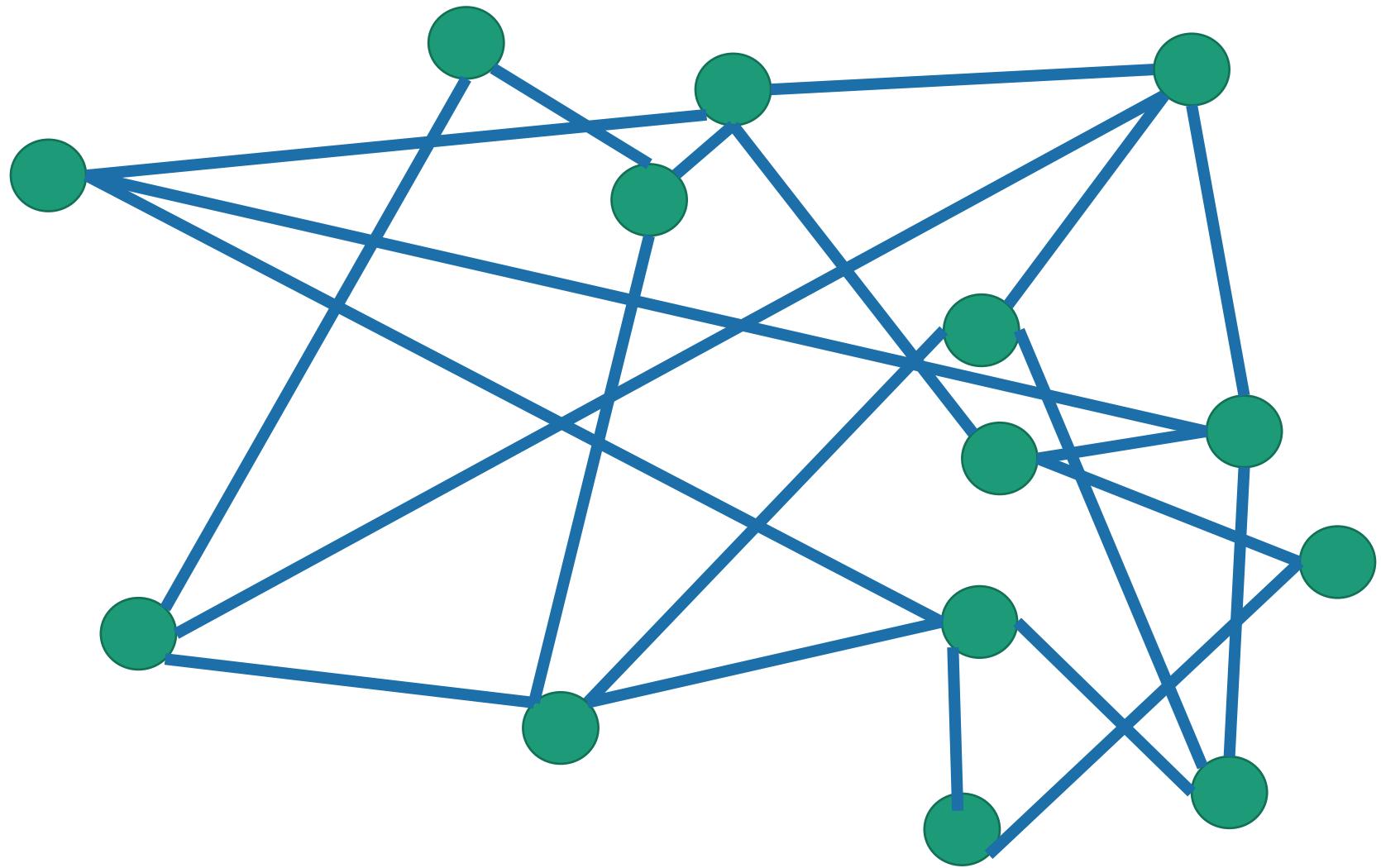
Is this graph bipartite?



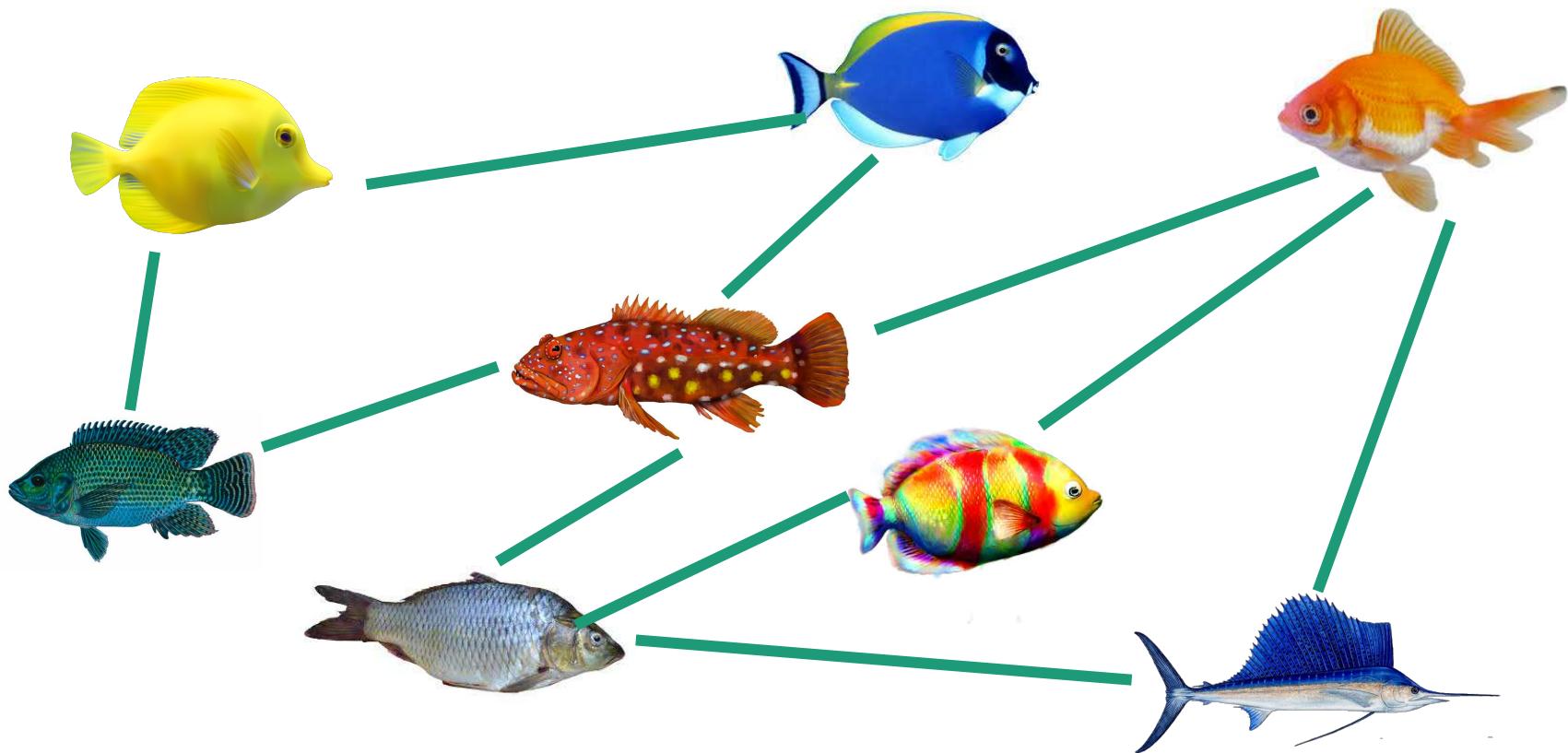
How about this one?



How about this one?

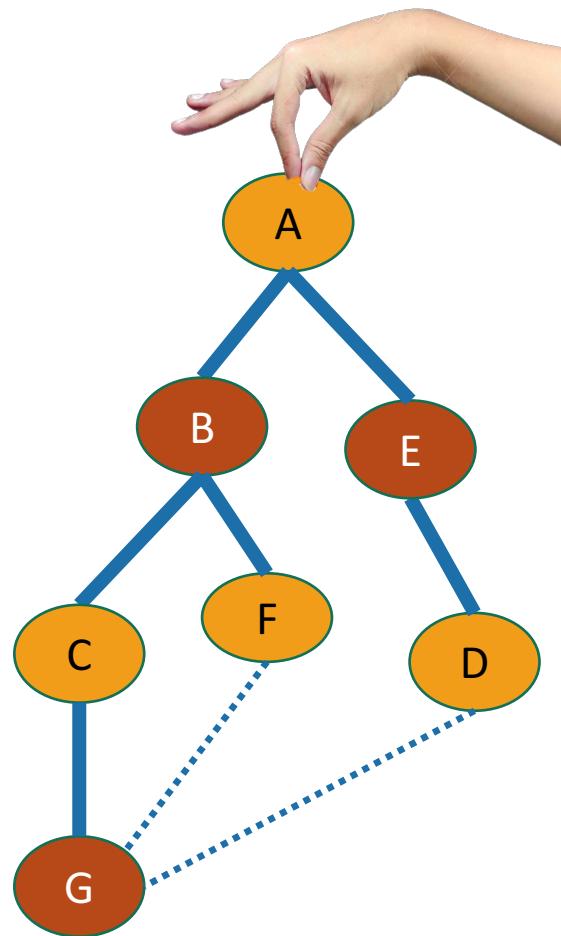


This one?



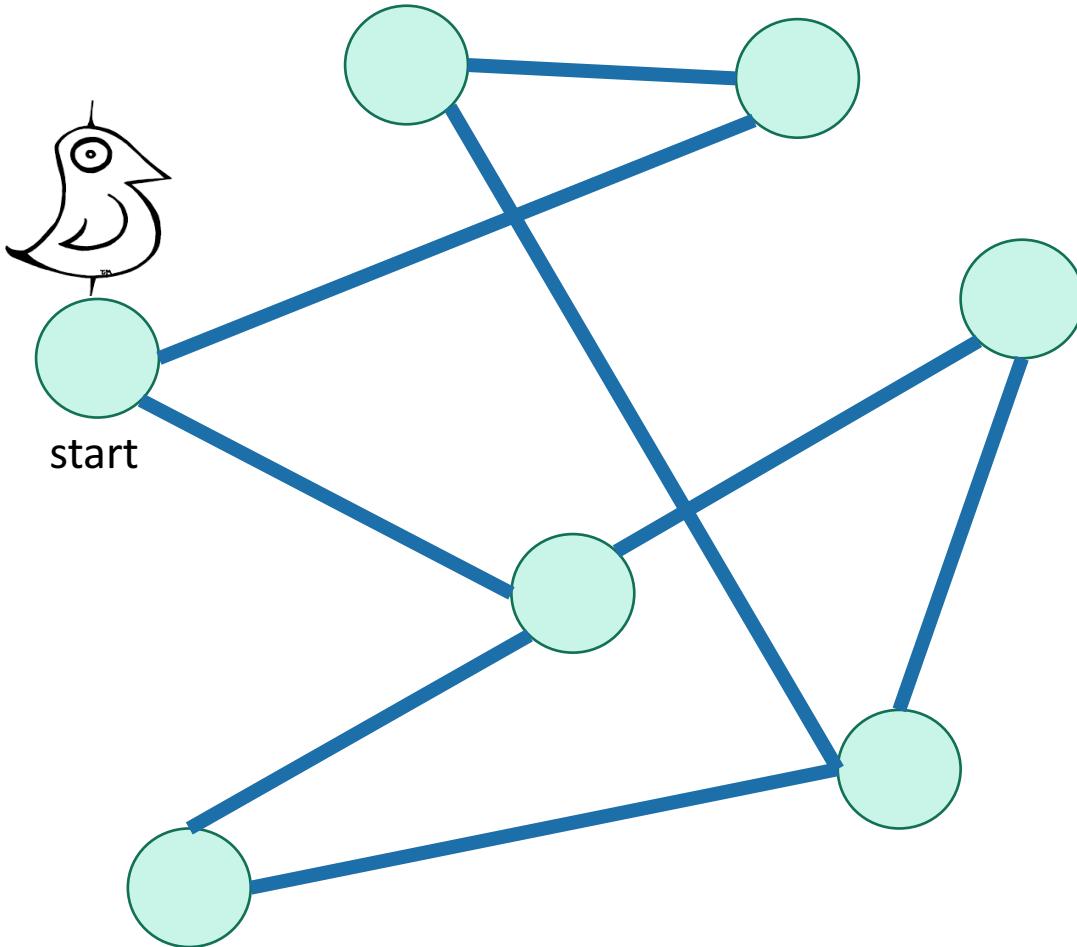
Solution using BFS

- Color the levels of the BFS tree in alternating colors.
- If you never color two connected nodes the same color, then it is bipartite.
- Otherwise, it's not.



Breadth-First Search

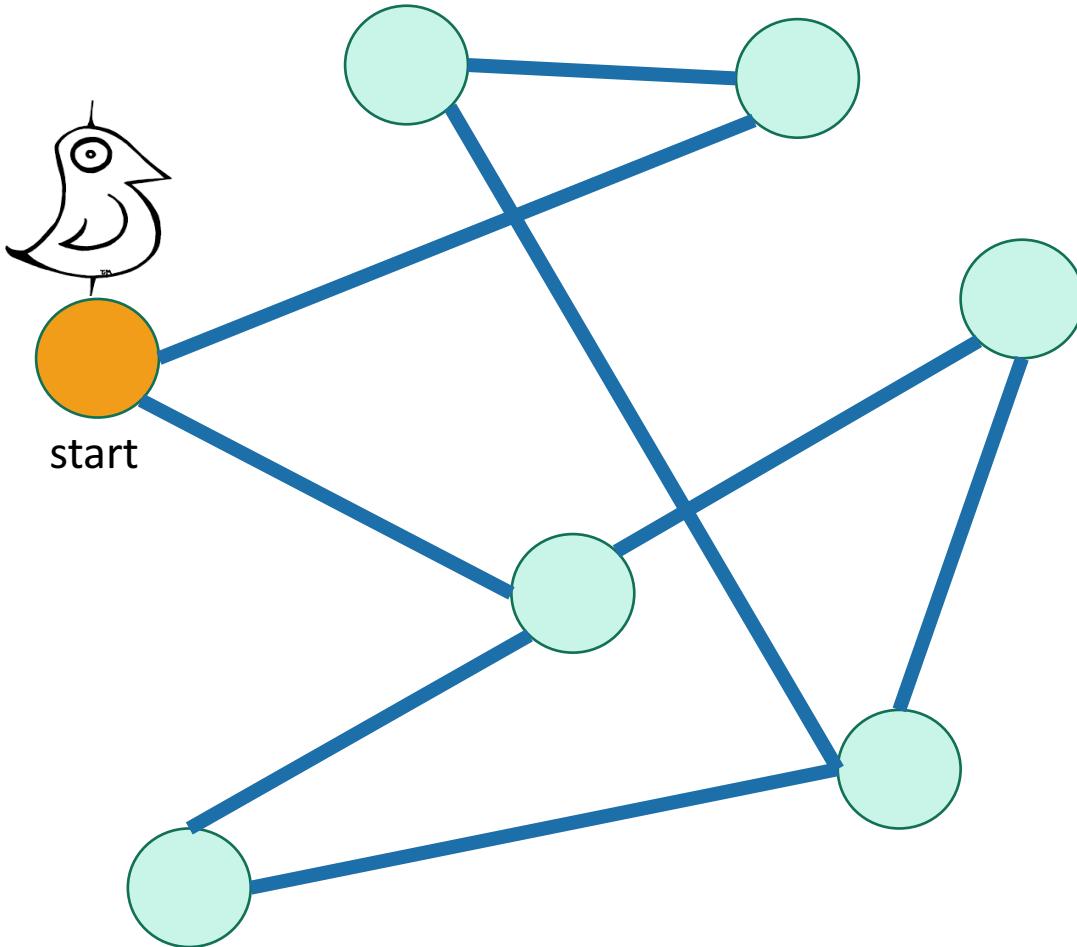
For testing bipartite-ness



- Not been there yet
- Can reach there in zero steps
- Can reach there in one step
- Can reach there in two steps
- Can reach there in three steps

Breadth-First Search

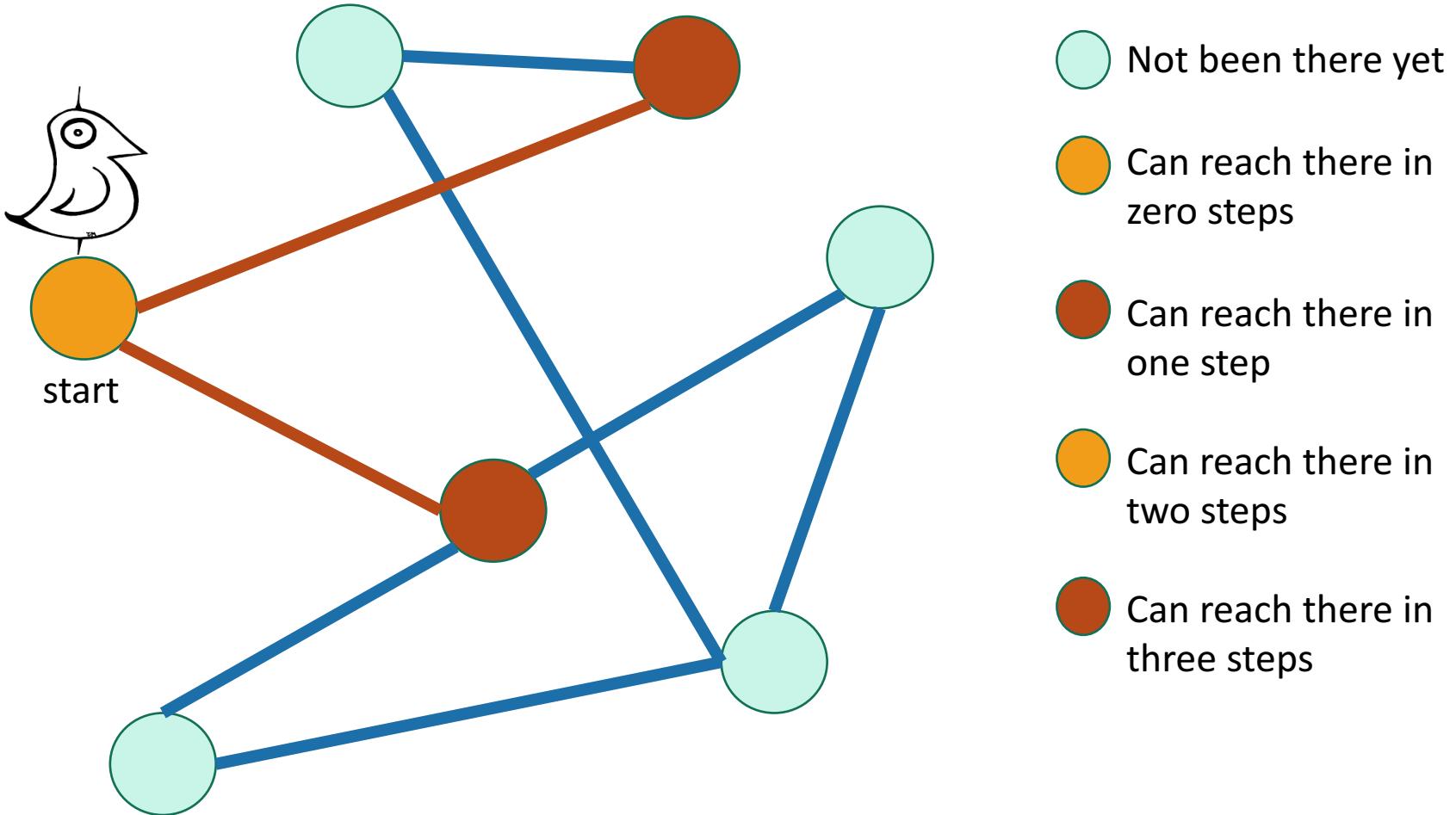
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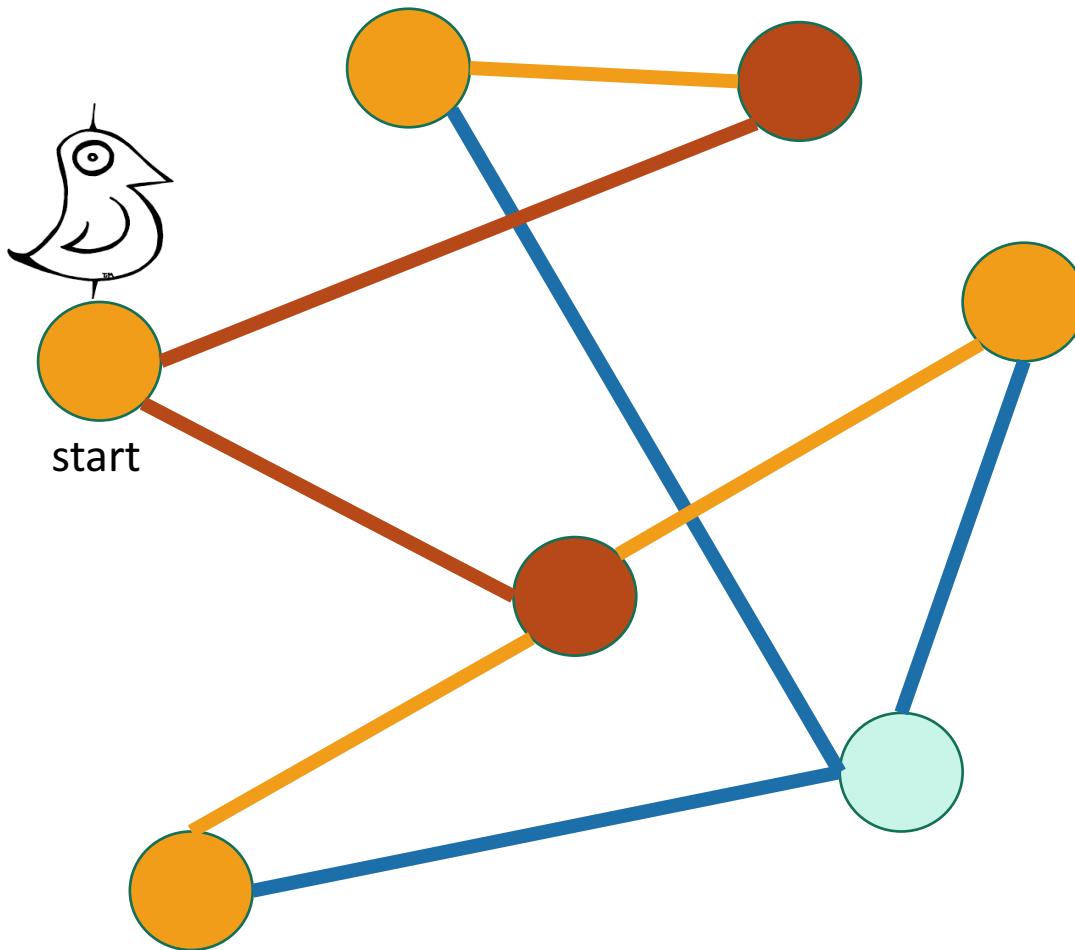
Breadth-First Search

For testing bipartite-ness



Breadth-First Search

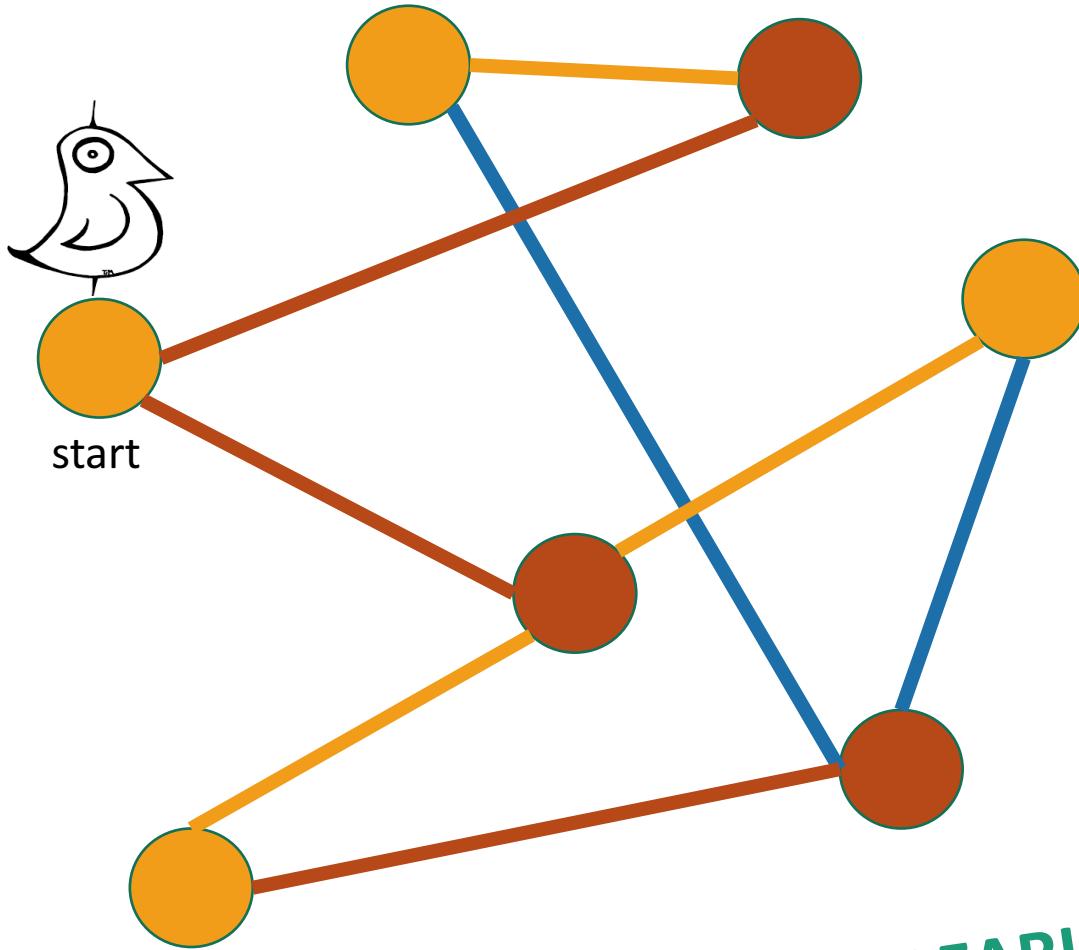
For testing bipartite-ness



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Breadth-First Search

For testing bipartite-ness

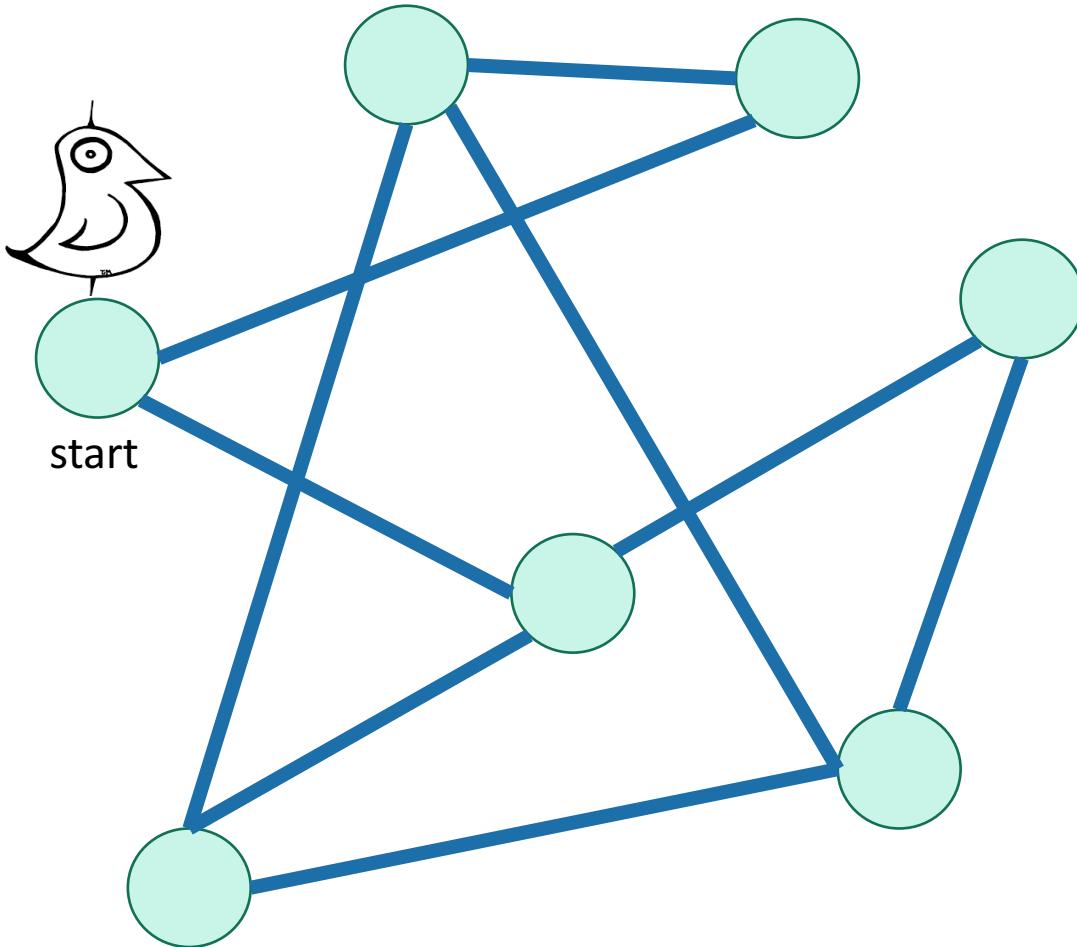


CLEARLY BIPARTITE!

- Not been there yet
- Can reach there in zero steps
- Can reach there in one step
- Can reach there in two steps
- Can reach there in three steps

Breadth-First Search

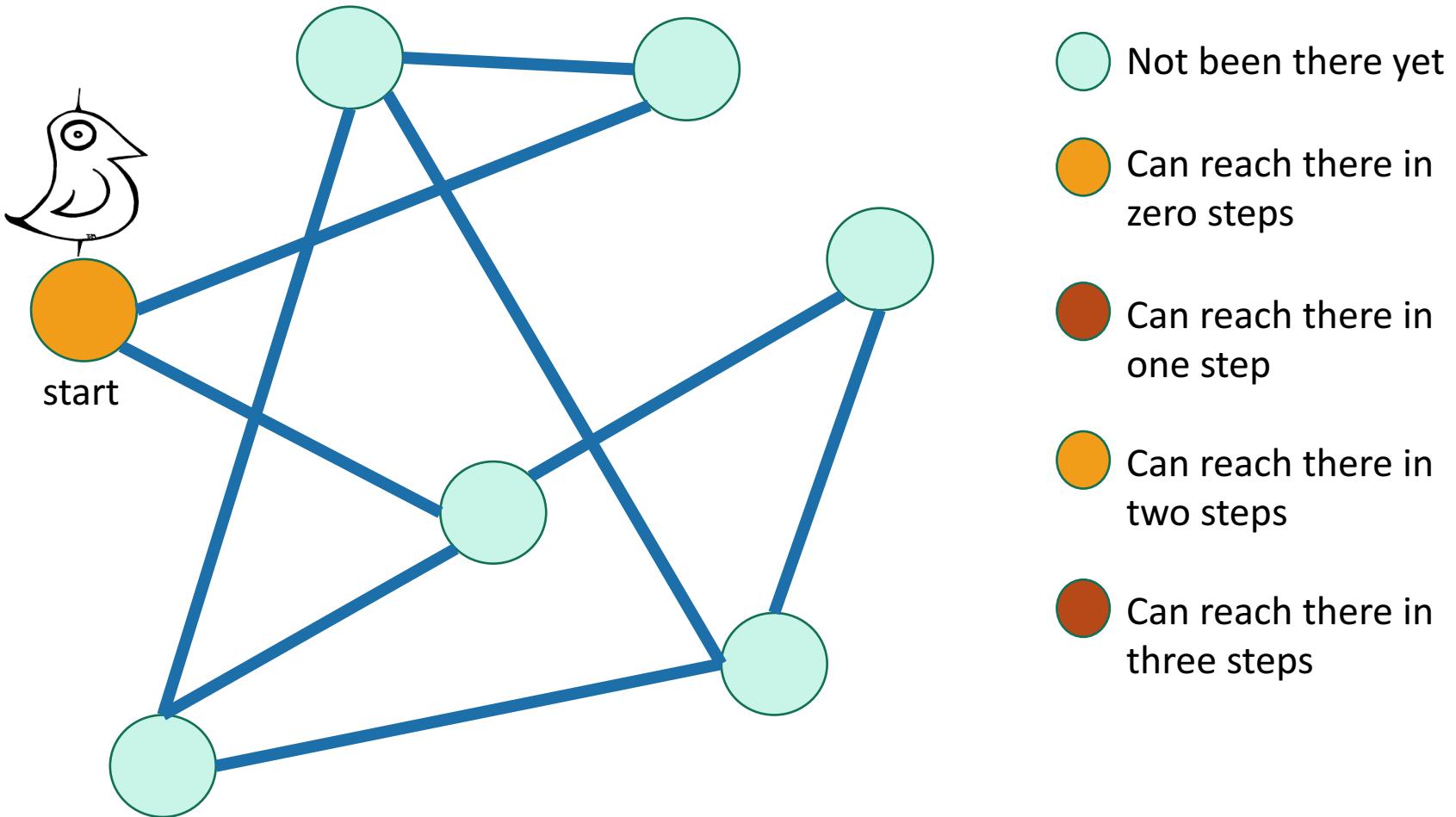
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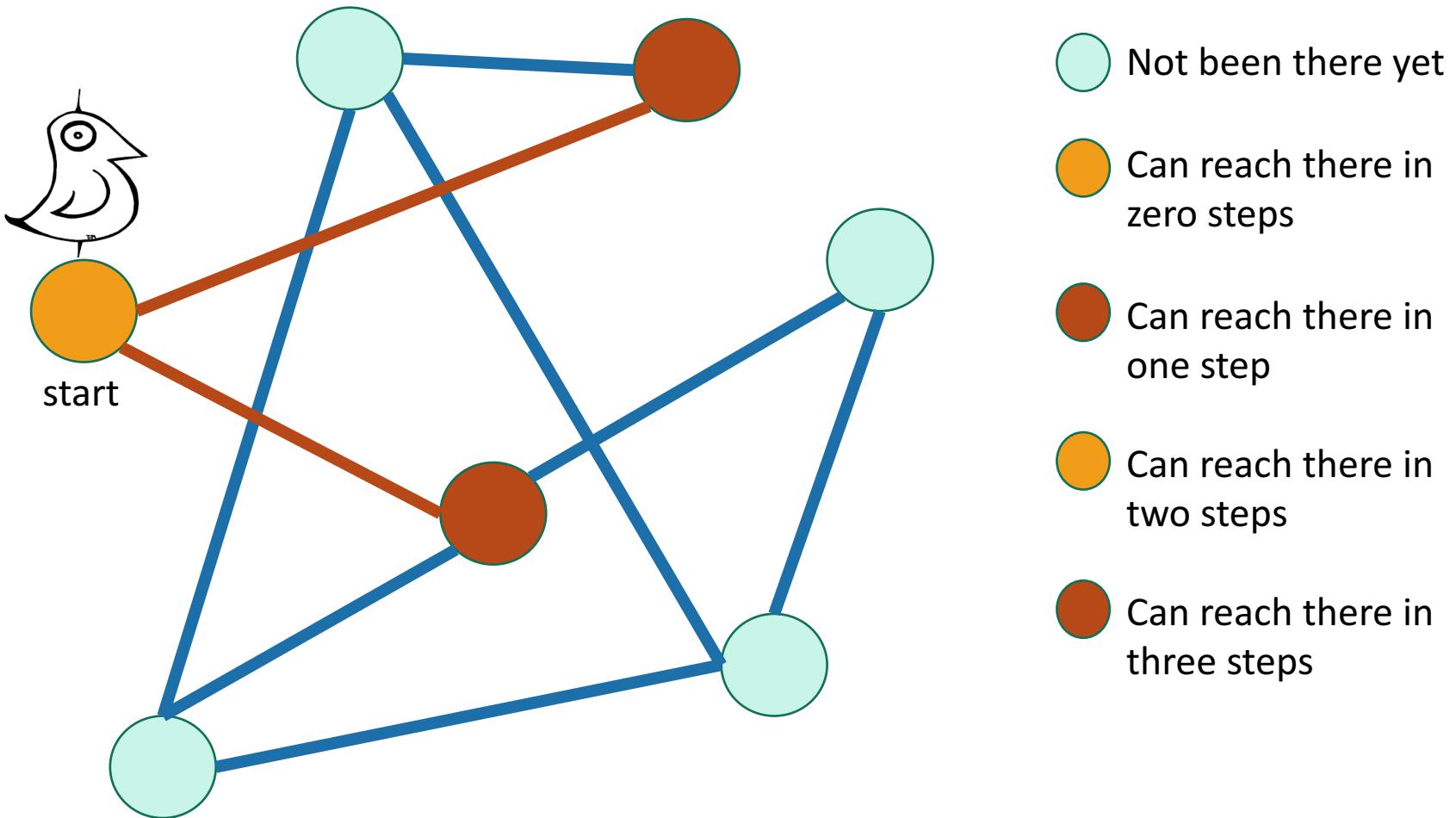
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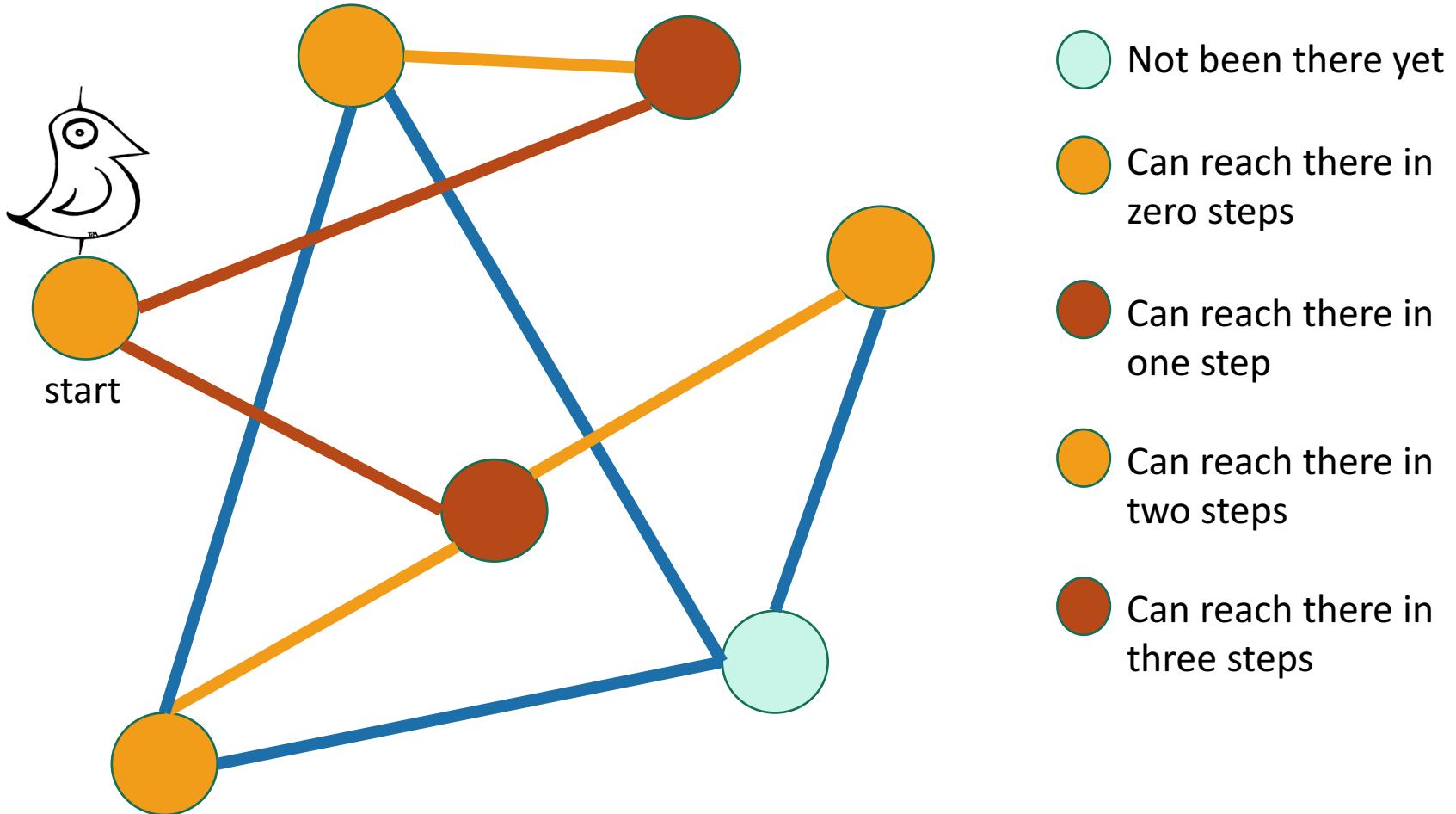
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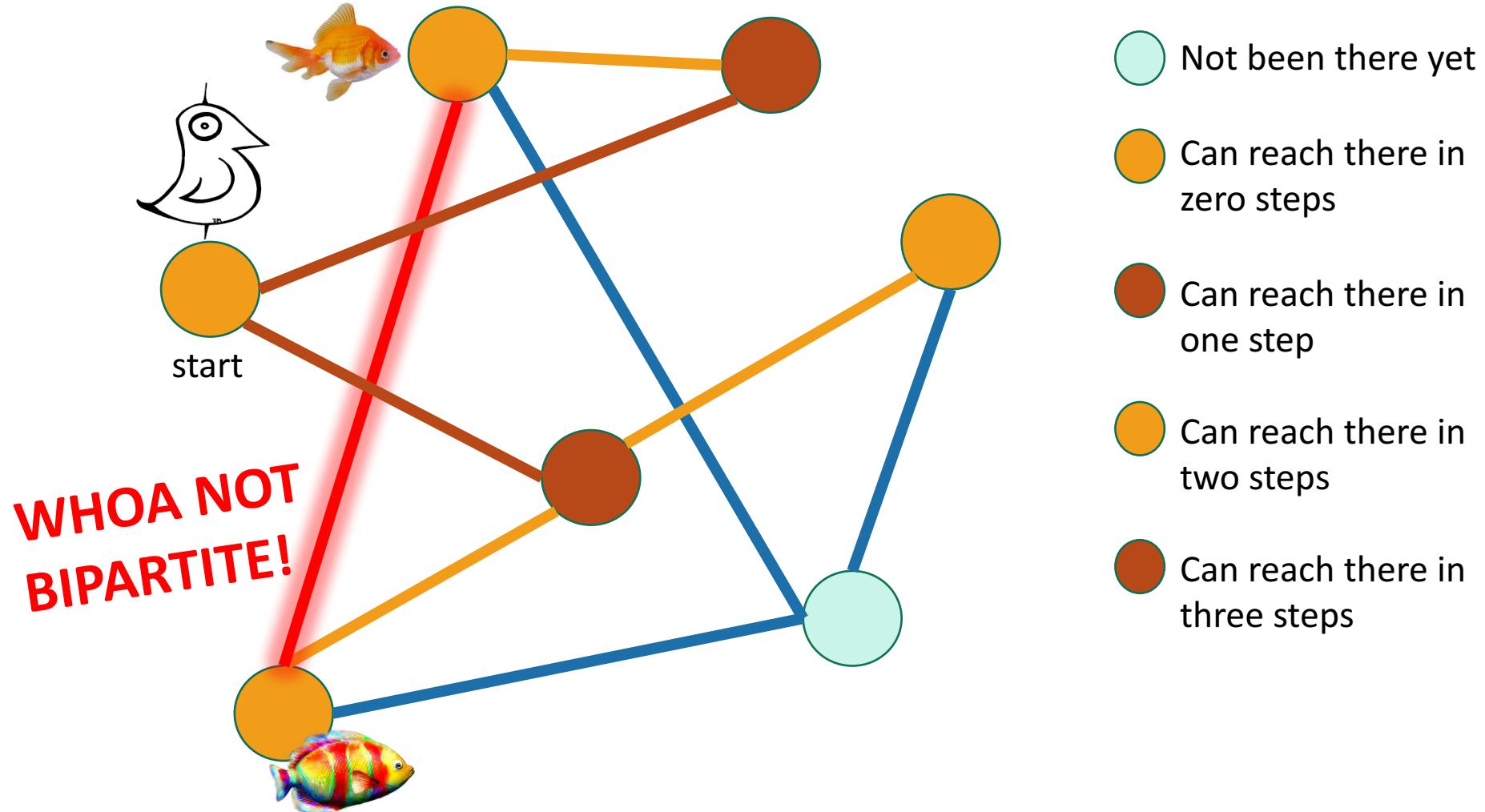
Breadth-First Search

For testing bipartite-ness



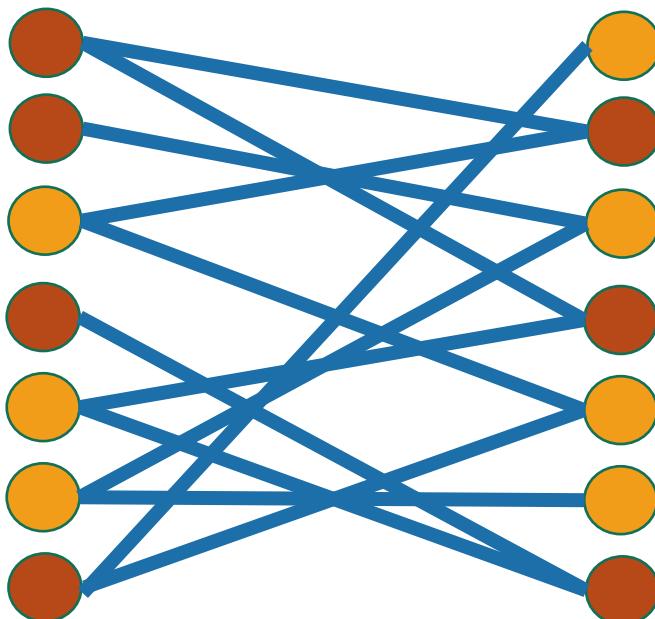
Breadth-First Search

For testing bipartite-ness



Hang on now.

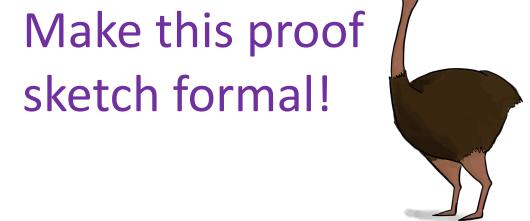
- Just because **this** coloring doesn't work, why does that mean that there is **no** coloring that works?



I can come up
with plenty of bad
colorings on this
legitimately
bipartite graph...



Plucky the
pedantic penguin

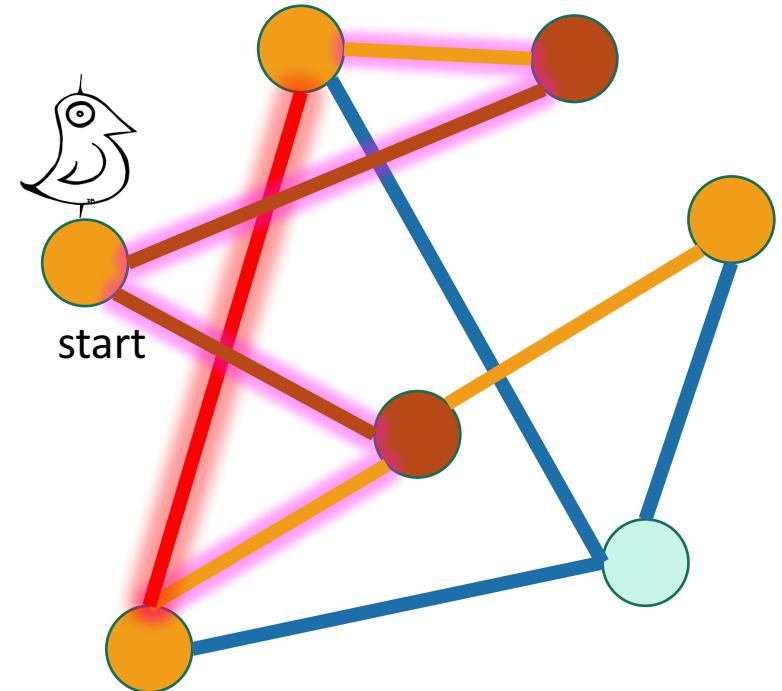
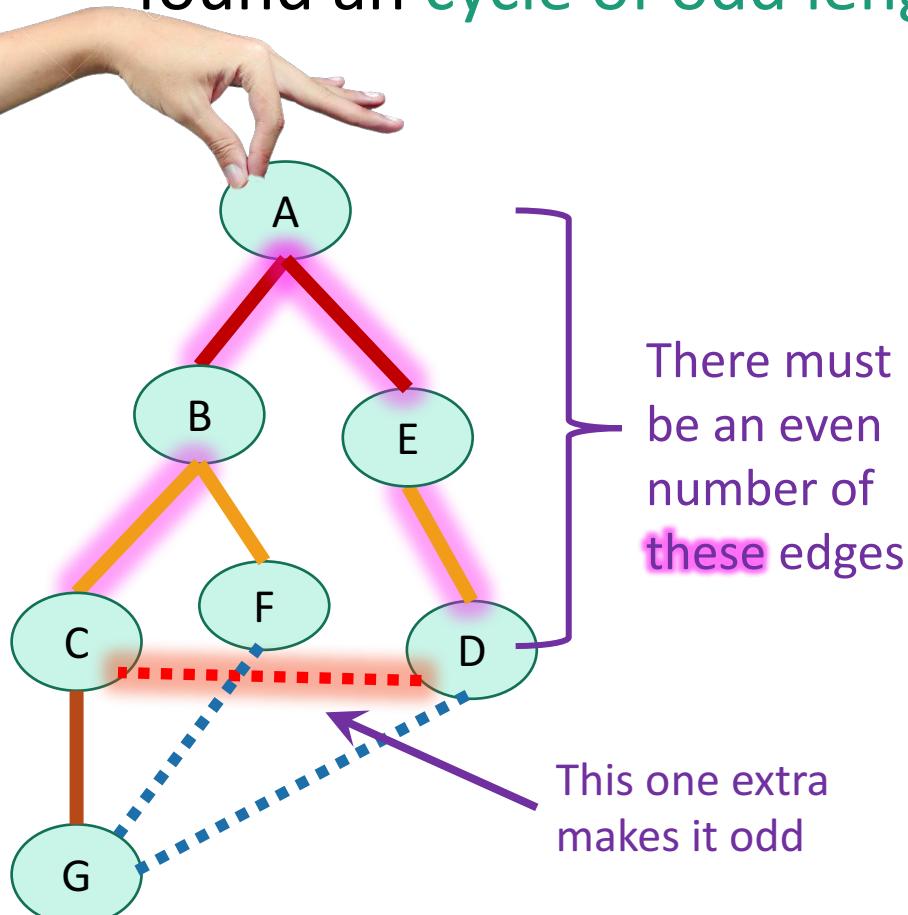


Make this proof sketch formal!

Some proof required

Ollie the over-achieving ostrich

- If BFS colors two neighbors the same color, then it's found an **cycle of odd length** in the graph.



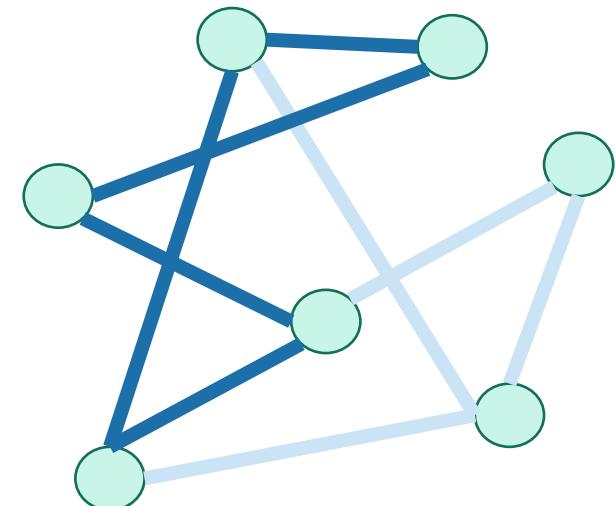
Make this proof
sketch formal!



Some proof required

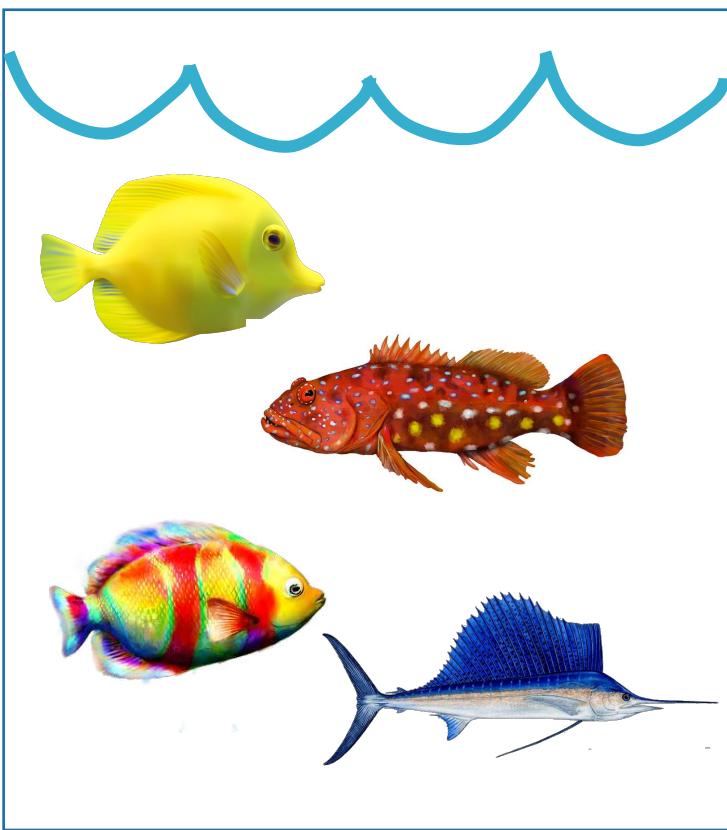
Ollie the over-achieving ostrich

- If BFS colors two neighbors the same color, then it's found an **cycle of odd length** in the graph.
- So the graph has an **odd cycle** as a **subgraph**.
- But you can **never** color an odd cycle with two colors so that no two neighbors have the same color.
 - [Fun exercise!]
- So you can't legitimately color the whole graph either.
- **Thus it's not bipartite.**



What did we just learn?

BFS can be used to detect bipartite-ness in time $O(n + m)$.



Outline

- Part 0: Graphs and terminology
- Part 1: Depth-first search
 - Application: topological sorting
 - Application: in-order traversal of BSTs
- Part 2: Breadth-first search
 - Application: shortest paths
 - Application (if time): is a graph bipartite?



Recap

Recap

- Depth-first search
 - Useful for topological sorting
 - Also in-order traversals of BSTs
- Breadth-first search
 - Useful for finding shortest paths
 - Also for testing bipartiteness
- Both DFS, BFS:
 - Useful for exploring graphs, finding connected components, etc

Still open (next few classes)

- We can now find components in undirected graphs...
 - What if we want to find strongly connected components in directed graphs?
- How can we find shortest paths in weighted graphs?
- What is Samuel L. Jackson's Erdos number?
 - (Or, what if I want everyone's everyone-else number?)

Next Time

- Strongly Connected Components

Before Next Time

- Pre-lecture exercise: Strongly Connected What-Now?