The finite difference equations governing the motion of the baroclinic (internal) modes, governing equations are expressed as

$$\delta_c^t \eta + \delta_f^x (\overline{D}_b^x U) + \delta_f^y (\overline{D}_b^y V) + \delta_f^\sigma (W) = 0$$

$$\delta^{t}(\overline{\overline{D}_{b}^{x}}\overline{U}^{t}) + \delta^{x}_{b}[(\overline{\overline{D}_{b}^{x}}\overline{U}_{f}^{x}] + \delta^{y}_{f}[(\overline{\overline{D}_{b}^{y}}\overline{U}_{b}^{x}] + \delta^{y}_{f}[(\overline{\overline{D}_{b}^{y}}\overline{U}_{b}^{x}) - \overline{f}\overline{V}_{f}^{y}D_{b}^{x} - \overline{(f}\overline{V}_{f}^{y}D_{b}^{x}) + g\overline{D}_{b}^{x}\delta_{b}^{x}\eta = \delta^{\sigma}_{b}\left[\overline{K_{Mb}}(\overline{D_{b}^{x}}\overline{U}_{b}^{y}) - \overline{f}\overline{V}_{b}^{y}D_{b}^{x} - \overline{(f}\overline{V}_{f}^{y}D_{b}^{x}) - \overline{f}\overline{V}_{f}^{y}D_{b}^{x} - \overline{(f}\overline{V}_{f}^{y}D_{b}^{x}) - \overline{f}\overline{V}_{b}^{y}D_{b}^{x} - \overline{(f}\overline{V}_{f}^{y}D_{b}^{x}) - \overline{f}\overline{V}_{f}^{y}D_{b}^{x} - \overline{(f}\overline{V}_{f}^{y}D_{b}^{x}) - \overline{f}\overline{V}_{b}^{y}D_{b}^{x} - \overline{(f}\overline{V}_{f}^{y}D_{b}^{x}) - \overline{f}\overline{V}_{f}^{y}D_{b}^{x} - \overline{f}\overline{V}_{f}^{y}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{x}D_{b}^{$$

$$\delta^{t}(\overline{D_{b}^{y}V}^{t}) + \delta_{f}^{x}[(\overline{D_{b}^{x}U})_{b}^{y}\overline{V}_{b}^{x}] + \delta_{b}^{y}[(\overline{D_{b}^{y}V})_{f}^{y}\overline{V}_{b}^{y}] + \delta_{f}^{y}((\overline{D_{b}^{y}V})_{f}^{y}\overline{V}_{b}^{y}) + \overline{f}\overline{U_{f}^{x}D_{b}^{y}} + \overline{f}\overline{U_{f}^{x}D_{b}^{$$

$$\delta^{t}(\overline{TD})^{t} + \delta_{f}^{x}(\overline{T}_{b}^{x}U\overline{D}_{b}^{x}) + \delta_{f}^{y}(\overline{T}_{b}^{y}V\overline{D}_{b}^{y}) + \delta_{f}^{\sigma}(\overline{T}_{b}^{\sigma}W) = \delta_{b}^{\sigma}(\frac{K_{H}}{D^{n+1}}\delta_{f}^{\sigma}T^{n+1}) + \delta_{f}^{x}\left[\overline{A_{H}}_{b}^{x}\overline{H}_{b}^{x}\delta_{b}^{x}(T^{n-1} - T_{CLIM})\right] + \delta_{f}^{y}\left[\overline{A_{H}}_{b}^{y}\overline{H}_{b}^{y}\delta_{b}^{y}(T^{n-1} - T_{CLIM})\right] + \delta_{f}^{\sigma}R$$

$$(4)$$

$$\delta^{t}(\overline{SD})^{t} + \delta^{x}_{f}(\overline{S}^{x}_{b}U\overline{D}^{x}_{b}) + \delta^{y}_{f}(\overline{S}^{y}_{b}V\overline{D}^{y}_{b}) + \delta^{\sigma}_{f}(\overline{S}^{\sigma}_{b}W) = \delta^{\sigma}_{b}(\frac{K_{H}}{D^{n+1}}\delta^{\sigma}_{f}S^{n+1}) + \delta^{x}_{f}\left[(\overline{A_{H}}^{x}_{b}\overline{H}^{x}_{b}\delta^{x}_{b}(S^{n-1} - S_{CLIM})\right] + \delta^{y}_{f}\left[\overline{A_{H}}^{y}\overline{H}^{y}_{b}\delta^{y}_{b}(S^{n-1} - S_{CLIM})\right]$$

$$(5)$$

$$\overline{\delta^t(q^2D)}^t + \delta^x_f(\overline{U}^\sigma_b\overline{q^2}^x_b\overline{D}^x_b) + \delta^y_f(\overline{V}^\sigma_b\overline{q^2}^y_b\overline{D}^y_b) + \delta^\sigma_c(Wq^2) = \delta^\sigma_b\left[\overline{K}^\sigma_{qf}(\frac{\delta^\sigma_fq^2}{D})^{n+1}\right] + \frac{2K_M}{D}\left[(\delta^\sigma_b\overline{U}^x_f)^2 + (\delta^\sigma_b\overline{V}^y_f)^2\right] + \frac{2g}{\rho_0}K_H\delta^\sigma_b\rho - \frac{2Dq^3}{B_1l} + \delta^x_f\left[\overline{\overline{A}^{mb}_b}\overline{H}^x_b\delta^x_b(q^2)^{n-1}\right] + \delta^y_f\left[\overline{\overline{A}^{mb}_b}\overline{H}^y_b\delta^y_b(q^2)^{n-1}\right]$$

$$(6)$$

$$\overline{\delta^t(q^2lD)}^t + \delta^x_f(\overline{U}^\sigma_b\overline{q^2l}^x_b\overline{D}^x_b) + \delta^y_f(\overline{V}^\sigma_b\overline{q^2l}^y_b\overline{D}^y_b) + \delta^\sigma_c(Wq^2l) = \delta^\sigma_b\left[\overline{K}^\sigma_q(\frac{\delta^\sigma_fq^2l}{D})^{n+1}\right] + lE_1\frac{K_M}{D}\left[(\delta^\sigma_b\overline{U}^x_f)^2 + (\delta^\sigma_b\overline{V}^y_f)^2\right] + \frac{lE_1g}{\rho_0}K_H\delta^\sigma_b\rho - \frac{Dq^3}{B_1}\left\{1 + E_2\left[\frac{l}{\kappa D}\left(\frac{-1}{\sigma} + \frac{1}{1+\sigma}\right)\right]^2\right\} + \delta^x_f\left[\overline{\overline{A_M}^x}^\sigma_b\overline{H}^x_b\delta^x_b(q^2l)^{n-1}\right] + \delta^y_f\left[\overline{\overline{A_M}^y}^\sigma_b\overline{H}^y_b\delta^y_b(q^2l)^{n-1}\right]$$

$$\frac{\partial p}{\partial \sigma} = -\rho g D \tag{8}$$

(9)

(16)

(17)

(18)

$$\rho = \rho(T, S, p)$$

The finite difference equations governing the motion of the external modes, governing equations are expressed as

$$\delta^t \overline{\eta}^t + \delta_f^x (\overline{D}_b^x \overline{U}) + \delta_f^y (\overline{D}_b^y \overline{V}) = 0$$

$$\delta^{t}\overline{(\overline{D_{b}^{x}}\overline{U})}^{t} + \delta_{b}^{x}(\overline{D_{b}^{x}}\overline{U}_{f}^{x}\overline{U}_{f}^{x}) + \delta_{f}^{y}(\overline{D_{b}^{y}}\overline{V}_{b}^{x}\overline{U}_{b}^{y}) - \overline{\widetilde{f}\overline{V_{f}^{y}}}D_{b}^{x} - \overline{f}\overline{\overline{V_{f}^{y}}}D_{b}^{x} + g\overline{D_{b}^{x}}\delta_{b}^{x}\eta = \delta_{b}^{x}(2\overline{A_{M}}D\delta_{f}^{x}\overline{U}^{n-1}) + \delta_{f}^{y}\left[\overline{\overline{A_{M}^{y}}}b\overline{D_{b}^{x}}b(\delta_{b}^{x}\overline{V} + \delta_{b}^{y}\overline{U})^{n-1}\right] + \phi_{x}$$

$$(11)$$

$$\delta^t \overline{(\overline{D_b^y}\overline{V})}^t + \delta_f^x (\overline{\overline{D_b^x}\overline{U}_b^y}\overline{V}_b^x) + \delta_b^y (\overline{\overline{D_b^y}\overline{V}_f^y}\overline{V}_f^y) + \overline{\overline{f}\overline{U_f^x}D_b^y} + \overline{f}\overline{\overline{U}_f^x}D_b^y + \overline{f}\overline{\overline{U}_f^x}D_b^y + g\overline{D}_b^y \delta_b^y \eta = \delta_b^y (2\overline{A_M}D\delta_f^y \overline{V}^{n-1}) + \delta_f^x \left[\overline{\overline{A_M}_b}\overline{D_b^x}\overline{V}_b^y (\delta_b^x \overline{V} + \delta_b^y \overline{U})^{n-1}\right] + \phi_y$$

$$(12)$$

where

$$\tilde{f} = \frac{1}{\Delta x \Delta y} [\overline{V}_f^y \delta_c^x (\Delta y) - \overline{U}_f^x \delta_c^y (\Delta x)]$$

$$A_M = \frac{1}{2}C\Delta x \Delta y \sqrt{(\delta_f^x U)^2 + \frac{1}{2}[\delta_c^y (\overline{U}_f^x)_c + \delta_c^x (\overline{V}_f^y)]^2 + (\delta_f^y V)^2}$$

$$\tag{14}$$

$$A_H = A_M * TPRNI \tag{15}$$

$$K_M = qlS_M$$

$$K_H = qlS_H$$

$$K_q = qlS_q$$

$$\frac{\widetilde{f}}{\widetilde{f}} = \frac{1}{\Delta \Delta} \left[\overline{\overline{V}}_f^y \delta_c^x(\Delta y) - \overline{\overline{U}}_f^x \delta_c^y(\Delta x) \right]$$

$$\tilde{\overline{f}} = \frac{1}{\Delta x \Delta y} \left[\overline{\overline{V}}_f^y \delta_c^x(\Delta y) - \overline{\overline{U}}_f^x \delta_c^y(\Delta x) \right]$$

$$\phi_x = -WU(0) + WU(-1) - \frac{g(\overline{D}_b^x)^2}{\rho_0} \Sigma_{z=1}^k \left\{ \left[\Sigma_{zz=1}^k \delta_b^x \overline{\rho_{zz}^{\prime}}^{\sigma} \Delta_b^{\sigma} \sigma_{zz} \right]_z \Delta \sigma_z \right\} + \frac{g\overline{D}^x \delta_b^x D}{\rho_0} \Sigma_{z=1}^k \left\{ \left[\Sigma_{zz=1}^k \overline{\sigma_{zz}^{\sigma}}^{\sigma} \delta_b^{\sigma} (\overline{\rho_{zz}^{\prime}})_b^x \right]_z \Delta \sigma_z \right\} + G_x$$

$$(20)$$

$$\phi_{y} = -WV(0) + WV(-1) - \frac{g(\overline{D}_{b}^{y})^{2}}{\rho_{0}} \Sigma_{z=1}^{k} \left\{ \left[\Sigma_{zz=1}^{k} \delta_{b}^{y} \overline{\rho_{zzb}^{\prime}} \Delta_{b}^{\sigma} \sigma_{zz} \right]_{z} \Delta \sigma_{z} \right\} + \frac{g\overline{D}^{y} \delta_{b}^{y} D}{\rho_{0}} \Sigma_{z=1}^{k} \left\{ \left[\Sigma_{zz=1}^{k} \overline{\sigma_{zzb}^{\sigma}} \delta_{b}^{\sigma} (\overline{\rho_{zz}^{\prime}})_{b}^{y} \right]_{z} \Delta \sigma_{z} \right\} + G_{y}$$

$$(21)$$