

Macroeconomic Theory II (Spring 2022)

Assignment 3 Solution

Consider the stochastic neoclassical growth model we studied in class. Assume that $u(c) = \frac{c^{1-\sigma}-1}{1-\sigma}$, $f(z, k, n) = zk^\alpha n^{1-\alpha}$ and $\log(z') = \rho \log(z) + \epsilon$ where ϵ is normally distributed with mean zero and variance σ_ϵ^2 . Set $\sigma = 2, \rho = 0.95, \sigma_\epsilon = 0.01$.

1. Assume a period in the model corresponds to a quarter in the data. Calibrate δ, β and α to match investment-output ratio of 25%, share of labor cost in the production as 2/3, capital-to-quarterly output ratio of 12, and consumption-output ratio of 75%.

Parameter	Moment to match	Value
α	$\frac{\omega N}{Y} = 1 - \alpha$	0.33
δ	$1 = (1 - \delta) + \frac{I}{K} = (1 - \delta) + \frac{I}{Y} \frac{Y}{K}$	0.02
β	$1/\beta = \alpha \frac{Y}{K} + (1 - \delta)$	0.993

2. Compute the deterministic steady-state values for capital, consumption, output and investment.

Solve Euler equation:

$$u_c = \beta \mathbb{E}_c'(z' \alpha k'^{\alpha-1} + 1 - \delta)$$

Solve steady state values:

$$K^* = \left[\frac{1 - \beta(1 - \delta)}{\alpha\beta} \right]^{\frac{1}{\alpha-1}}$$

$$Y^* = (K^*)^\alpha$$

$$C^* = Y^* - \delta K^*, \quad I^* = \delta K^*$$

3. Linearize the model around the steady-state (if you feel more comfortable you can use the log-linearization method). Show your equations.

Log-linearize the following three equations.

$$y = f(x) \approx f(x^*) + f'(x^*)(x - x^*) \quad C^{-\sigma} = \beta \mathbb{E}_{z'|z} C'^{-\sigma} (z' \alpha (K')^{\alpha-1} + 1 - \delta) \quad (1)$$

$$\Rightarrow \frac{y - f(x^*)}{y^*} \approx \frac{f'(x^*)x^*}{y^*} \frac{x - x^*}{x^*} \quad C + K' = zK^\alpha + (1 - \delta)K \quad (2)$$

$$\Rightarrow \frac{y - y^*}{y^*} = \hat{y} \approx \frac{f'(x^*)x^*}{y^*} \hat{x} = \frac{d \ln y}{d \ln x} \bigg|_{x^*} \hat{x} \quad \log(z') = \rho \log(z) + \epsilon' \quad (3)$$

$$\frac{d \ln y}{d \ln x} \bigg|_{x^*} = \frac{d y^*}{d x^*} \bigg/ \left(\frac{y^*}{x^*} \right)$$

We get:

$$\begin{aligned} -\sigma\hat{c} &= -\sigma\mathbb{E}\hat{c}' + \rho\hat{z} + (\alpha - 1)\hat{k}' \\ C^*\hat{c} + K^*\hat{k}' &= z^*(K^*)^\alpha(\hat{z} + \alpha\hat{k}) + (1 - \delta)K^*\hat{k} \\ \hat{z}' &= \rho\hat{z} + \epsilon' \end{aligned}$$

Fit the system of equations into the matrix representation

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & \alpha - 1 & -\sigma \\ 0 & K^* & 0 \end{bmatrix} \begin{bmatrix} \hat{z}' \\ \hat{k}' \\ \mathbb{E}\hat{c}' \end{bmatrix} = \begin{bmatrix} \rho & 0 & 0 \\ -\rho & 0 & -\sigma \\ z^*(K^*)^\alpha & \alpha z^*(K^*)^\alpha + (1 - \delta)K^* & -C^* \end{bmatrix} \begin{bmatrix} \hat{z} \\ \hat{k} \\ \hat{c} \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \epsilon'_z$$

4. Solve the policy function for capital and consumption using linearized (or log-linearized) model. The solution of linearized model will give you the rules for consumption and capital as deviations from steady-states. To find the policy functions in levels, convert these rules using the definitions for the deviations from steady-state.

Let $\hat{k}' = a_1\hat{k} + a_2\hat{z}$, then

$$\begin{aligned} -\sigma\hat{c} &= -\sigma\mathbb{E}\hat{c}' + \rho\hat{z} + (\alpha - 1)(a_1\hat{k} + a_2\hat{z}) \\ C^*\hat{c} + K^*(a_1\hat{k} + a_2\hat{z}) &= z^*(K^*)^\alpha(\hat{z} + \alpha\hat{k}) + (1 - \delta)K^*\hat{k} \\ \hat{z}' &= \rho\hat{z} + \epsilon' \end{aligned}$$

Write \hat{c} and $\mathbb{E}\hat{c}'$ in terms of \hat{k} and \hat{z} :

$$\begin{aligned} \hat{c} &= \frac{z^*(K^*)^\alpha(\hat{z} + \alpha\hat{k}) + (1 - \delta)K^*\hat{k} - K^*(a_1\hat{k} + a_2\hat{z})}{C^*} \\ \hat{c}' &= \frac{z^*(K^*)^\alpha(\hat{z}' + \alpha\hat{k}') + (1 - \delta)K^*\hat{k}' - K^*(a_1\hat{k}' + a_2\hat{z}')}{C^*} \\ \mathbb{E}\hat{c}' &= \frac{z^*(K^*)^\alpha(\rho\hat{z} + \alpha(a_1\hat{k} + a_2\hat{z})) + (1 - \delta)K^*(a_1\hat{k} + a_2\hat{z}) - K^*(a_1(a_1\hat{k} + a_2\hat{z}) + a_2\rho\hat{z})}{C^*} \end{aligned}$$

Plug it back:

$$\begin{aligned} & -\sigma(z^*(K^*)^\alpha(\hat{z} + \alpha\hat{k}) + (1 - \delta)K^*\hat{k} - K^*(a_1\hat{k} + a_2\hat{z})) \\ &= -\sigma(z^*(K^*)^\alpha(\rho\hat{z} + \alpha(a_1\hat{k} + a_2\hat{z})) + (1 - \delta)K^*(a_1\hat{k} + a_2\hat{z}) - K^*(a_1(a_1\hat{k} + a_2\hat{z}) + a_2\rho\hat{z})) \\ &+ C^*(\rho\hat{z} + (\alpha - 1)(a_1\hat{k} + a_2\hat{z})) \end{aligned}$$

a_1 and a_2 can be solved as:

$$\begin{aligned} -\sigma(z^*(K^*)^\alpha\alpha + (1 - \delta)K^* - K^*a_1) &= -\sigma(z^*(K^*)^\alpha(\alpha a_1 + (1 - \delta)K^*a_1 - K^*a_1^2) + C^*(\alpha - 1)a_1 \\ -\sigma(z^*(K^*)^\alpha - K^*a_2) &= -\sigma(z^*(K^*)^\alpha(\rho + \alpha a_2) + (1 - \delta)K^*a_2 - K^*(a_1a_2 + a_2\rho)) \\ &+ C^*(\rho + (\alpha - 1)a_2) \end{aligned}$$

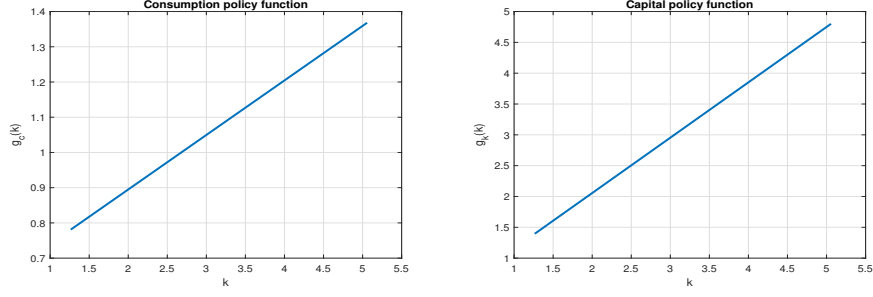


Figure 1: Policy function

5. Solve the model using value function iteration method.

- (a) To do this you need to convert the AR(1) process into Markov process. I uploaded a code which does it for you. The method is called tauchen method. It takes the inputs N , number of grid points for the shock, μ , mean value of the shock, ρ , persistency of the shock, σ , standard deviation of the shock, and m , the maximum distance to the mean in terms of multiples of the standard deviation. You can set $N = 7$ and $m = 3$. The other inputs are the parameters of the model. The output of the code is Z , the discretized values for the shock, $Zprob$, the transition matrix for the shock, where entry (i, j) of the matrix is showing the transition probability from state z_i to state z_j . Be careful that the levels you obtained using the matlab code, Z , are the log values of the shock. To convert them into actual levels, take the exponent of Z .
- (b) When discreizing the capital, center the grid points around k^* , steady-state capital level, and set the lower bound of capital $\underline{k} = (1 - \kappa)k^*$ and upper bound to $\bar{k} = (1 + \kappa)k^*$. You can start by using $N_k = 200$ grid points for k and set $\kappa = 0.6$.

- (c) Solve the model using value function iteration method. Compute the associated policy functions and value functions. Plot them against capital for different values of the shock.

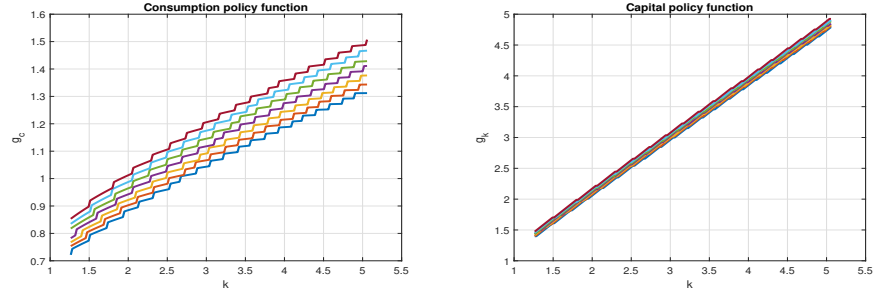


Figure 2: Policy function

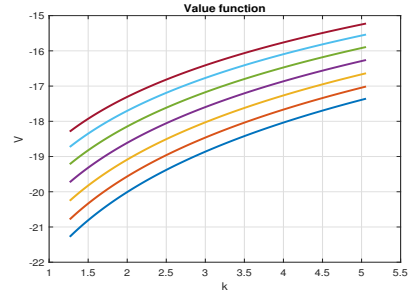


Figure 3: Value function

- (d) Report the robustness of your results with respect to N_k and κ . Try two other values, say $N_k \in \{100, 500\}$ and $\kappa \in \{0.3, 0.8\}$ and plot the policy function for capital for the mean value of the shock.

Let's see the N_k case at first. $N_k = 500$ uses finer grid than $N_k = 100$.

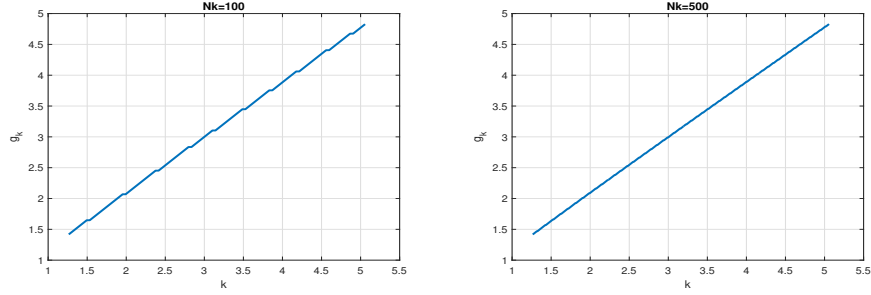


Figure 4: N_k comparison

If we use fine grids, we can obtain more robust policy function. However, it takes more time to compute the policy function. Now let's look at κ case. When κ increases, the gap between lower bound and upper bound becomes bigger. This will become coarse grids because N_k is same in this case. Therefore, we can obtain more robust policy function in $\kappa = 0.3$ case.

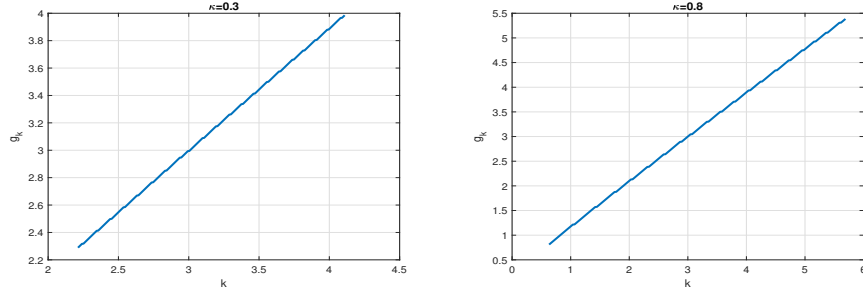


Figure 5: κ comparison

- (e) Compare the policy function for capital obtained using linearized model and value function iteration method. Discuss the goodness of approximation in the linearized model.

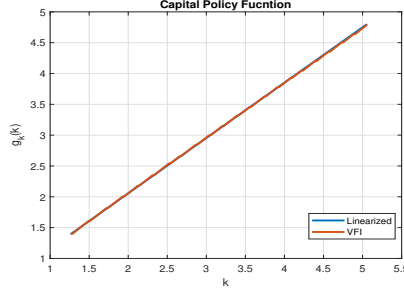


Figure 6: Linearized and VFI

If you compare the both methods, you can know that the results are very similar. Therefore, the fit of the linearized model is pretty good.

- (f) Do the same comparison of policy functions for $\sigma = 5$ and $\sigma = 10$. Discuss the sensitivity of approximation with respect to σ .

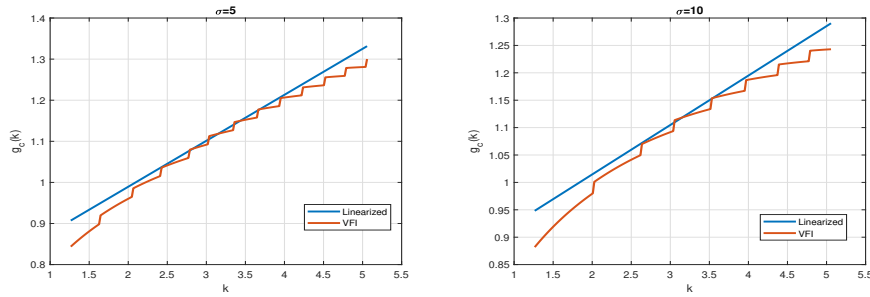


Figure 7: σ comparison

I used the consumption policy function instead of the capital policy function because we can recognize the difference better. As you can see, the approximation grows worse as σ gets bigger. If the utility function is log function, we can obtain the following policy function for consumption.

$$c_t = (1 - \alpha\beta)k_t^\alpha$$

The consumption function does not include σ parameter. Therefore, the gap between linearized model and VFI model are small. However, when σ gets bigger, the policy function becomes more concave, so we can get worse results. But we can know that the fit is good near the steady state.