

MAT347 Lecture Notes

ARKY!! :3C

'25 Fall & '26 Winter Semester

Contents

1	Day 1: Rubik's Cube (Sept. 3, 2025)	2
2	Day 2: More Non-commutative Gaussian Elimination (Sep. 5, 2025)	4
3	Day 3: NCGE, Pt. 3 (Sep. 10, 2025)	5
4	Day 4: NCGE, Pt. 4 (Sep. 12, 2025)	7
5	Day 5: Group Homomorphisms, Normal Subgroup (Sep. 17, 2025)	9
6	Day 6: Normal Subgroup as Kernel of Homomorphism (Sep. 19, 2025)	11
7	Day 7: First and Second Isomorphism Theorems (Sep. 24, 2025)	13
8	Day 8: Third Isomorphism Theorem (Sep. 26, 2025)	15
9	Day 9: Lattice Theorem and Simple Groups (Oct. 1, 2025)	16
10	Day 10: Jordan-Hölder Decomposition (Oct. 3, 2025)	18
11	Day 11: ... (Oct. 8, 2025)	19
12	Day 12: Group Actions, First Sylow Theorem (Oct. 10, 2025)	20

§1 Day 1: Rubik's Cube (Sept. 3, 2025)

The first semester of this class will be taught by Dror Bar-Natan instead of Joe Repka. Since this was a last minute change, the Quercus, tutorials, textbook, homework policy, etc. are all unknown for now (until the rest of the week probably).

This will be today's **handout**. Let $G = \langle g_1, \dots, g_\alpha \rangle$, i.e., the group generated by g_1, \dots, g_α , be a subgroup of S_n , with $n = O(100)$. To understand G , let us start by computing $|G|$. *insert long digression about Rubik's cubes that can be read elsewhere.*

Definition 1.1. A *group* is a set G along with a binary multiplication $m : G \times G \rightarrow G$ usually written as $(g_1, g_2) \mapsto g_1 \cdot g_2 = m(g_1, g_2)$ such that

- (i) m is associative, i.e., for all $g_1, g_2, g_3 \in G$, we have that $(g_1 g_2) g_3 = g_1 (g_2 g_3)$,
- (ii) m has an identity, i.e., there exists some $e \in G$ such that $g \cdot e = e \cdot g = g$ for all $g \in G$,
- (iii) m has an inverse, i.e., for all $g \in G$, there exists some $h \in G$ such that $g \cdot h = e = h \cdot g$,

We present a few examples of groups for intuition.

- (a) $(\mathbb{Z}, m = +)$, $(\mathbb{Q}, +)$, $(\mathbb{R}, +)$, $(\mathbb{C}, +)$, $(F, +)$ are naturally all groups. We also have that $(2\mathbb{Z}, +)$ is a group, even though it is not a field, because it does not admit inverses.
- (b) $(\mathbb{Q} \setminus \{0\}, \times)$ has identity given by 1 and naturally admits inverses because all reciprocals are contained within $\mathbb{Q} \setminus \{0\}$ itself. We commonly write the rationals without zero as \mathbb{Q}^\times .
- (c) If $n \in \mathbb{Z}_{\geq 0}$, then let $S_n := \{\sigma : \underline{n} \rightarrow \underline{n} \mid \sigma \text{ is bijective}\}$, where we define $\underline{n} = \{1, \dots, n\}$.¹ Let the group operation on S_n be given by composition. Here, Dror goes into a big digression on how composition should be written, and he suggests the following,²

$$\sigma \cdot \mu = \mu \circ \sigma = \sigma // \mu.$$

Indeed, S_n is a group, where its identity element e is given by the identity function on \underline{n} . We have that $|S_n| = n!$.

As a substantive example, consider $S_2 = \{[1, 2], [2, 1]\}$, where $[1, 2]$ represents the identity function and $[2, 1]$ represents the function mapping 1 to 2 and 2 to 1. Then we obtain the following possible compositions,

$$\begin{aligned} [1, 2][1, 2] &= [1, 2], \\ [1, 2][2, 1] &= [2, 1], \\ [2, 1][1, 2] &= [2, 1], \\ [2, 1][2, 1] &= [1, 2]. \end{aligned}$$

As for S_3 , we have that S_3 contains 6 functions, comprised of all the possible permutations possible on $\{1, 2, 3\}$. One such composition is given as follows,

$$[1, 3, 2][2, 1, 3] = [2, 3, 1], \quad [2, 1, 3][1, 3, 2] = [3, 1, 2],$$

¹angry yapping incoming i am so used to seeing $[n]$ when i saw that on the board i was like, watefak!!!

²also, plus one angry footnote for using $//$ as a composition symbol

which confirms that S_3 is indeed not abelian (i.e., non-commutative).

In the opposite direction, S_1 consists of an identity function only; clearly, $|S_1| = 1! = 1$. S_0 is the set of all permutations on \emptyset , which is clearly the empty set, meaning the “empty function” on the empty set is the only function in S_0 ; similarly, $|S_0| = 0! = 1$.

(d) There are 24 rotational symmetries of a cube.

(e) The orthogonal transformations $o(3) = \{A \in M_{3 \times 3}(\mathbb{R}) \mid A \cdot A^\top = I\}$ form a group.

Theorem 1.2. The identity element of a group is unique. If G is a group and e, e' are both identity elements, then for all $g \in G$, we have that $eg = ge = g$ and $e'g = ge' = g$, and $e = e'$.

Proof. Observe that $e' = e' \cdot e = e$. □

Theorem 1.3. The inverse of an element in a group is unique. Let G be a group and $g \in G$; if h, h' satisfy $gh = hg = e = gh' = h'g$, then $h = h'$.

Proof. Observe that $h' = h' \cdot e = h'(gh) = (h'g)h = eh = h$. □

From here on, the inverse of g will be denoted g^{-1} , i.e., g^{-1} is the unique inverse of g .

Theorem 1.4. If $ac = bc$ in a group then $a = b$.

Proof. Given that $ac = bc$, we have $acc^{-1} = bcc^{-1}$, implying $a = b$. □

Theorem 1.5. $(ab)^{-1} = b^{-1}a^{-1}$.

Proof. Observe that $(ab)(b^{-1}a^{-1}) = abb^{-1}a^{-1} = aea^{-1} = aa^{-1} = e$. □

Definition 1.6. A subset $H \subset G$ of a group G is called a subgroup if H is closed under multiplication, $e \in H$, and admits inverses (i.e., H is a group itself with the multiplication operation from G). We write $H < G$.

As an example, $(2\mathbb{Z}, +) < (\mathbb{Z}, +) < (\mathbb{Q}, +), (\mathbb{R}, +), (\mathbb{C}, +)$. The Rubik's cube group is also a subgroup of S_{54} .

§2 Day 2: More Non-commutative Gaussian Elimination (Sep. 5, 2025)

The syllabus is not yet public, but you should check this [link](#) next Wednesday for more information. Our TAs are Jacob and Matt. The course code for this class is “MAT347”, and it carries the iconic ‘7’, meaning this class will be “hard as shit”.

The permutation product is the usual composition $\sigma \cdot \tau = \sigma \circ \tau$.³ Today’s goal is to understand $G = \langle g_1, \dots, g_\alpha \rangle \in S_n$, where we wish to answer the questions: (i) what size is $|G|$? (ii) what does it mean to say $\sigma \in G$? (iii) if $\sigma \in G$, how do we write it in terms of the g_i ’s? (iv) what does a random $\sigma \in G$ look like?

Let us construct a lower-triangular table of size $n \times n$, where each box (i, j) describes an operation on how to move the i th sticker to the j th sticker. In particular, we have that if $i = j$, the operation is simply the identity. We start with an empty such table, and we will proceed to fill it in with permutations. For any $\sigma \in S_n$, we have that σ can be represented as a permutation of the form $[1, 2, \dots, i-1, j, *, \dots, *]$, i.e., σ fixes the first $i-1$ entries, and the i th entry contains j . We label such a permutation as $\sigma_{i,j} \in S_n$, and we call i the *pivot*.

We proceed to “feed g_1, \dots, g_α ” in order; to feed a non-identity σ , let the pivotal position be i and let j be given by $\sigma(i)$. If the box (i, j) is empty, let us place σ there; otherwise, if it already contains some $\sigma_{i,j}$, let us place $\sigma' := \sigma_{i,j}^{-1}\sigma$ in there instead. Notice that this makes it so that σ' is indeed the identity for the first i entries, instead of the first $i-1$ entries, meaning we have fixed an additional sticker. After this step, for each pair of occupied boxes (i, j) and (k, l) , let us feed $\sigma_{i,j}\sigma_{k,l}$ and perform the steps above again, until the table no longer changes for any such pair of $(i, j), (k, l)$.

Claim 2.1. This process stops in $O(n^6)$ time; call the resulting table T .

We obtain n^6 from observing that there is approximately n operations per permutation, and hence n per inverse permutation; since computing $\sigma' = \sigma_{i,j}^{-1}\sigma$ potentially requires n inverses, we note that each feeding operation takes at worst n^2 operations. For the $(i, j), (k, l)$ pairs, the table is of $O(n^2)$ size, meaning there are a total of $O(n^4)$ possible foods. Combining these figures we have $O(n^6)$, which is much less than $O(n!)$.

Claim 2.2. Every $\sigma_{i,j} \in T$ is indeed in G .

³so we’re going to be changing the notation conventions every lecture from now on.

§3 Day 3: NCGE, Pt. 3 (Sep. 10, 2025)

Before we return to the discussion on the Rubik's cube, we have another property of inverses to discuss;

Theorem 3.1. Let $a \in G$. Then $(a^{-1})^{-1} = a$.

Proof. $(a^{-1})^{-1} = (a^{-1})^{-1} \cdot (a^{-1} \cdot a) = a$. \square

The point of the twist is that we want to fill every box of our table that can be filled by the group; assuming that the twist hits everything, we would be able to work nicely with the group by just unfurling each permutation progressively. As an example, given (z_1, z_2, \dots) , we wish to find the index k such that $z_k = 1$. We may then apply $\sigma_{1,k}^{-1}$ to (z_1, z_2, \dots) to obtain $(1, \dots)$, on which we may then recursively proceed. Inventing this gives us (z_1, z_2, \dots) in terms of the generators.

Lemma 3.2. Every box (i, j) of the table T is in G .

Proof. We fed generators or elements of the table into the table, but each feed only performs group operations, which means inductively, we are done here. \square

Lemma 3.3. Any $\sigma \in S_n$ fed into the table is a monotone product of elements of T . We have that $\sigma = \sigma_{1,j_1} \cdot \sigma_{2,j_2} \cdots \sigma_{n,j_n}$, where our σ_{i,j_i} s are drawn from the table, and the box in the index (i, j_i) is nonempty.

Proof. There are three possibilities;

- (i) If $\sigma = e$, then it's just $\sigma_{1,1}\sigma_{2,2}\sigma_{3,3}\dots$
- (ii) If σ is in the table, suppose its $\sigma_{i,j}$; then $\sigma = \sigma_{1,1} \dots \sigma_{i,j} \dots \sigma_{n,n}$.
- (iii) If σ is neither of these, then suppose σ has pivot i , $\sigma(i) = j$, and $\sigma_{i,j}$ is full; then we just feed $\sigma' = \sigma_{i,j}^{-1}\sigma$. In other words, $\sigma = \sigma_{i,j}\sigma'$, and since you can only repeat this finitely many times, this is eventually $\sigma = \sigma_{1,1} \dots \sigma_{i,j} \dots \sigma_{n,j_n}$. \square

The before holds for $\sigma \in S_n$ fed into the table, but we don't necessarily have that the table T generates the group just yet⁴. If we feed in a generator g_i , we have that g_i is in $\langle T \rangle$, meaning that by feeding our generators, we indeed have that $\langle T \rangle = G$. Therefore, feeding products of elements is to get everything in G as a monotone product.

Lemma 3.4. Two monotone products are equal if and only if they are the same.

Proof. If they are the same, they are equal, so it suffices to check that if two monotone products are equal, they are the same. Suppose that $\sigma_{1,j_1} \dots \sigma_{n,j_n} = \sigma_{1,j'_1} \dots \sigma_{n,j'_n}$. Then

$$\sigma_{i,j_1} \dots \sigma_{n,j_n} = (\sigma_{i,j_1}^{-1} \sigma_{1,j'_1}) \sigma_{2,j'_2} \dots \sigma_{n,j'_n},$$

meaning that

$$\sigma = \sigma_{n,j_n}^{-1} (\sigma_{n-1,j_{n-1}}^{-1} (\dots (\sigma_{1,j_1}^{-1} \sigma_{1,j'_1}) \dots) \sigma_{n-1,j'_{n-1}}) \sigma_{n,j'_n} = e,$$

but then we have $\sigma(1) = 1$, so, since all but the middle are the identity on 1, we have that $\sigma(1) = \sigma_{1,j_1}^{-1} \sigma_{i,j_i}(1)$, meaning $j_1 = j'_1$, and so

$$\sigma = \sigma_{n,j_n}^{-1} (\dots (\sigma_{2,j_2}^{-1} \sigma_{2,j'_2}) \dots) \sigma_{n,j'_n} = e,$$

and so by an inductive process, we are done. \square

⁴if we feed $\sigma \in G$, then we are essentially going to apply #2 until we reach the identity permutation; if we feed in $\sigma \notin G$, then we will arrive at an empty square in the table T

Lemma 3.5. $M = \{\sigma_{1,j_1} \dots \sigma_{n,j_n} \mid j_i \in [n]; \sigma_{i,j_i} \in T\}$ is a group.

Lemma 3.6. $M_k = \{\sigma_{k,j_k} \dots \sigma_{n,j_n} \mid j_i \in [n]; \sigma_{i,j_i} \in T\}$ is a group.

Proof. M_n is a group, because M_n is just the identity. The proof is to be continued. \square

Personal note; claims 3 and 4 from Dror's handout is used to establish a bijection between valid Rubik's cubes moves (i.e., elements of G), and elements in M (monotone products of red boxes in T).

If we have $M_1 = G$, then we can solve the questions set out at the beginning of our course, namely,

- (i) Compute $|G|$; we have that $|G| = |M_1|$.
- (ii) Given $\sigma \in S_n$, decide if $\sigma \in G$; suppose we feed σ into T . If it would change the table, then σ is not in G .
- (iii) Write a $\sigma \in G$ in terms of the generators g_i ; by keeping track of the elements we feed in, we can find each of the boxes of T in terms of the generators, so we can write each element as a monotone product in terms of the generators.
- (iv) Product random elements $\sigma \in G$; for each $i \in [n]$, pick some j_i randomly such that $\sigma_{i,j_i} \in T$. Then we may take the product of all such σ_{i,j_i} to produce a random element of G .

In a random tangent, we now proceed to define cycle notation. Suppose

$$G = \langle (1\ 2\ 3), (1\ 2)(3\ 4) \rangle;$$

we now proceed to fill in a 4×4 lower-triangular T , which Dror spent a lot of time trying to do. It also taught me that I am never going to even bother solving a Rubik's cube with this algorithm; this goes without saying but there is no chance in hell I'm typing all that shit down.

§4 Day 4: NCGE, Pt. 4 (Sep. 12, 2025)

We do a review of the non-commutative Gaussian elimination process.

(i) We have that $T \subset G$. Recall the definition that

$$M_k = \{\sigma_{k,j_k} \dots \sigma_{n,j_n} \mid \sigma_{i,j_i} \in T\}.$$

(ii) Anything fed into the table is in M_1 .

(iii) If two monotone products are equal as elements of S_n , then they are the same.

Theorem 4.1. For all k , $M_k \cdot M_k \subset M_k$; we note that in general, $A \cdot B = \{ab \mid a \in A, b \in B\}$.

Corollary 4.2. $M_1 \cdot M_1 \subset M_1$, meaning that $M_1 = G$.

Proof. To see this, $M_1 \subset G$ per its construction, as all the generators of G , g_1, \dots, g_α , have been fed into M_1 . Observe that by our previous claims, we have that products of elements in M_1 are in M_1 . To check that M_1 is in fact a group (which requires M_1 to be closed under inverses and the group operation), we may first note that it is closed under multiplication, and observe the following;

$$e = g^0, g = g^1, g^2, g^3, \dots$$

is an infinite sequence, where each of the elements in said sequence are in G . However, G is a finite group, meaning that there must be some sort of periodicity in the sequence. Without loss of generality, for all $n < m$ such that $g^n = g^m$, let us write $m = n + k$, where $k > 0$. Since $g^n = g^n g^k$, we must have that $e = g^k$, meaning that g^{k-1} is indeed the inverse of g . Thus, we establish that if G is finite and M_1 is a subset closed under multiplication, then M_1 is a subgroup of G . Thus, we conclude that $G = M_1$ by double inclusion. \square

Definition 4.3. We define the *order* of $g \in G$ to be $\text{ord}_G(g) = |g|$, i.e., the smallest possible k such that $g^k = e$.

We now prove the theorem with backwards induction (from the maximum value of k to the minimum value, i.e., $k = n$ to $k = 1$).

Proof. We start with the base case; $M_n \cdot M_n \subset M_n$ is trivially true, because M_n contains only the identity, so $\{\text{id}\}\{\text{id}\} \subset \{\text{id}\}$ is obviously true.

Since Dror doesn't want to work with some random k , we're going to assume $M_5 \cdot M_5 \subset M_5$, and show that $M_4 \cdot M_4 \subset M_4$ as a consequence.⁵ Again, Dror doesn't like indices, so he's going to start by showing that $\sigma_{8,j} \cdot M_4 \subset M_4$. Observe that the set of all $\sigma_{8,j} M_4 \subset \bigcup_{j_4 \geq 4} \sigma_{8,j} (\sigma_{4,j_4} \cdot M_5)$; by associativity, we have that

$$\bigcup_{j_4 \geq 4} \sigma_{8,j} (\sigma_{4,j_4} \cdot M_5) = \bigcup_{j_4 \geq 4} (\sigma_{8,j} \sigma_{4,j_4}) M_5.$$

We have that $\sigma_{8,j} \sigma_{4,j_4}$ is a monotone product in M_4 , meaning that the above is a subset of $M_4 \cdot M_5$, which is equal to $\bigcup_j \sigma_{4,j} (M_5 \cdot M_5)$, which, by our inductive hypothesis, we have that

$$\bigcup_j \sigma_{4,j} (M_5 \cdot M_5) \subset \bigcup_j \sigma_{4,j} M_5 \subset M_4,$$

⁵damn!!!! i hate indices!!!! rah!!!! grrr snarl growllll.... (bongos) BOMBS OVER BAGHDADDDddddd

since all $\sigma_{4,j}M_5$ is a monotone product in M_4 . Moreover, observe that using our process above, we obtain

$$\sigma_{4,j_4} \dots \sigma_{n,j_n} M_4 \subset \sigma_{4,j_4} \dots \sigma_{n-1,j_{n-1}} M_4,$$

and so on, since we may note that σ_{i,j_i} for $i \geq 4$ still fixes the pivot at 4. In the end, we have that any $\sigma \in M_4$ must satisfy $\sigma M_4 \subset M_4$, and so we are done with the inductive step. \square

Recall that in math so far, we've seen linear functions $L : V \rightarrow W$ and continuous functions $F : X \rightarrow Y$. We now discuss maps between groups.

Definition 4.4. Let G, H be groups. $\varphi : G \rightarrow H$ is called a *group homomorphism* (morphism) if its a set map and $\varphi(xy) = \varphi(x)\varphi(y)$, $\varphi(e_G) = e_H$, and $\varphi(x^{-1}) = \varphi(x)^{-1}$.

§5 Day 5: Group Homomorphisms, Normal Subgroup (Sep. 17, 2025)

Recall the definition of a group homomorphism,

Definition 5.1. $\varphi : G \rightarrow H$ is said to be a group homomorphism (where G, H are groups) if it is a structure-perserving group transformation, i.e.,

- (i) $\varphi(xy) = \varphi(x)\varphi(y)$,
- (ii) $\varphi(e_G) = e_H$,
- (iii) $\varphi(x^{-1}) = \varphi(x)^{-1}$

for all $x, y \in G$.

In particular, the three properties above are equivalent to $\varphi(xy^{-1}) = \varphi(x)\varphi(y)^{-1}$; they are also equivalent to the implication that (i) implies (ii), (iii). Below are some examples of group homomorphisms,

- (a) Let \mathbb{Z}, \mathbb{R} both be equipped with addition; then the inclusion map $\mathbb{Z} \rightarrow \mathbb{R}$ is a group homomorphism.
- (b) The function $\exp : (\mathbb{R}, +) \rightarrow (\mathbb{R}_{>0}, \times)$ is a group homomorphism ($e^{x+y} = e^x e^y$).
- (c) $\mathbb{R} \ni t \mapsto e^{2\pi i t} \in \{z \in \mathbb{C} \mid |z| = 1\} = S^1 \subset \mathbb{C}$ is a group homomorphism.
- (d) $\varphi : S_4 \rightarrow S_3$ given by mapping the faces of a tetrahedron to the three pairs arising from identifying its opposite edges is also a homomorphism.

As an aside, groups, together with their homomorphisms, form a category. In category theory terms, objects (groups) and maps (group homomorphisms) are seen as points and morphisms.

- (i) The identity map $I : G \rightarrow G$ is a homomorphism.
- (ii) If $\phi : G \rightarrow H$ and $\psi : H \rightarrow K$ are homomorphisms, then $\psi \circ \phi$ is a homomorphism.

A morphism is called an *isomorphism* if it has an inverse that is also a morphism, i.e., $\varphi : G \rightarrow H$ is an isomorphism if and only if it is bijective with $\varphi^{-1} : H \rightarrow G$ being a group homomorphism.

Definition 5.2. $\text{Aut } G = \{\varphi : G \rightarrow G \mid \varphi \text{ is an isomorphism}\}$; i.e., $\text{Aut } G$ is the set of all group isomorphisms.

As an example, $\text{Aut } \mathbb{Z}$ consists of the identity morphism and the “multiplication by -1 ” morphism, both of which we may readily check to satisfy isomorphism properties.

Claim 5.3. $\text{Aut } G$ is a group under composition.

Given any group G , there is a map $C : G \rightarrow \text{Aut } G$ called “conjugation”, where $G \ni h \mapsto C_h \in \text{Aut } G$; we have that $C_h(g) := h^{-1}gh = g^h$, i.e., “conjugation of g by h ”, where $C_h : G \rightarrow G$.

- (i) C_h is a morphism, since $C_h(g_1 \cdot g_2) = C_h(g_1) \cdot C_h(g_2)$, since $(g_1 \cdot g_2)^h = g_1^h \cdot g_2^h$, i.e.,

$$g_1^h g_2^h = h^{-1} g_1 h h^{-1} g_2 h = h^{-1} g_2 g_1 h = (g_1 g_2)^h.$$

- (ii) C_h is an invertible map; in fact, $C_h \circ C_{h^{-1}} = I$. We see this by considering that $(g^{h_1})^{h_2} = g^{h_1 \circ h_2}$. In this way, $g \mapsto (g^{h^{-1}})^h = g^{h^{-1}h} = g^e = g$, and the same holds when we consider $g \mapsto (g^h)^{h^{-1}}$.

Claim 5.4. C is an anti-homomorphism, i.e. $\varphi(ab) = \varphi(b)\varphi(a)$. Specifically, $C_{h_1 \circ h_2}(g) = C_{h_2} \circ C_{h_1}(g)$, which we see from expanding both sides to obtain $g^{h_1 \cdot h_2} = (g^{h_1})^{h_2}$.

Claim 5.5. Let $\varphi : G \rightarrow H$ is a morphism. Then $\ker \varphi = \{g \in G \mid \varphi(g) = e_H\}$ is a subgroup of G . We write $\ker \varphi < G$. Also, $\text{im } \varphi = \{\varphi(g) \mid g \in G\} < H$, meaning that $\text{im } \varphi$ is a subgroup too.

As an example, let $t \mapsto e^{2\pi i t}$ from $\mathbb{R} \rightarrow S^1$; we have that

$$\ker t = \{t \mid e^{2\pi i t} = 1\} = \{t \mid \cos 2\pi t + i \sin 2\pi t = 1\} = \mathbb{Z}.$$

We also have that if $\varphi : S_4 \rightarrow S_3$, then $\ker \varphi = \{I, (12)(34), (14)(23), (13)(24)\}$, and $\text{im } \varphi = S_3$. In general, if $H < G$, then H is always in the image of φ for some φ ; we may immediately see this to be true by considering the inclusion $H \hookrightarrow G$.

Claim 5.6. If $\varphi : G \rightarrow S^1$ and $g \in \ker \varphi$, then for any $h \in G$, $g^h \in \ker \varphi$.

Proof. $\varphi(g^h) = \varphi(h^{-1}gh) = \varphi(h^{-1})\varphi(g)\varphi(h) = \varphi(h^{-1})\varphi(h) = e$, meaning that $g^h \in \ker \varphi$. \square

Yet, if we consider the example where $S_3 < S_4$, is there $\varphi : S_3 \rightarrow S_n$ such that $\ker \varphi = S_3$? We observe that $(23) \in S_3$, and $(23)^{34} = (34)(23)(34) = [1432] \notin S_3$, meaning that S_3 is not a kernel in S_n .

Definition 5.7. $N < G$ is called *normal* in G and denoted $N \triangleleft G$ if $n \in N$, $h \in G$, then $n^h \in N$ if and only if $h^{-1}Nh \subset N$.⁶

Claim 5.8. $\varphi : G \rightarrow H$ has $\ker \varphi \triangleleft G$.

Suppose $N \triangleleft G$. Is there a morphism $\varphi : G \rightarrow H$ such that $N = \ker \varphi$?

⁶we're going to use lhd for normal subgroup and see if it works, like "left hand delta" ig

§6 Day 6: Normal Subgroup as Kernel of Homomorphism (Sep. 19, 2025)

Term test 1 has been moved a week earlier to Nov. 4; homework 1 is due at 11:59pm today, and homework 2 is online now.

We now recap last class' definitions,

Definition 6.1. We say that $N \triangleleft G$ if $N < G$ and for all $h \in G$, we have that $N^h = h^{-1}Nh = N$. We say that N is *normal*.

Claim 6.2. If $\varphi : G \rightarrow H$, then $\ker \varphi \triangleleft G$.

Given $N \triangleleft G$, there exists a unique $\varphi : G \twoheadrightarrow H$ (we denote surjections with double headed arrows, \twoheadrightarrow) with $\ker \varphi = N$. As an aside, surjections are the same as equivalence relations. This is a general set theoretic fact, and we should be aware of it.

Let us discuss in terms of sets, for now. We say that a relation $\sim : X \times X \rightarrow \{T, F\}$ (i.e., true or false) on a set X is called an *equivalence relation*, where $a \sim b$ if $\sim(a, b) = T$, if it satisfies the following axioms,

- (i) (*Reflexivity*) For all $x \in X$, we have that $x \sim x$.
- (ii) (*Symmetry*) For all $x, y \in X$, we have that $x \sim y$ if and only if $y \sim x$.
- (iii) (*Transitivity*) For all $x, y, z \in X$, if $x \sim y$ and $y \sim z$, then $x \sim z$.

As an example of an equivalence relation, let $f : X \rightarrow Y$ be a function, and define $a \sim b$ for $a, b \in X$ if $f(a) = f(b)$.

Definition 6.3. Let (X, \sim) be a set equipped with an equivalence relation \sim ; given some $x \in X$, we say $[x]_\sim = \{y \in X \mid x \sim y\}$. The subscript \sim denoting which equivalence class it belongs to is dropped if it is evident from context.

Claim 6.4. Equivalence classes are either equal or disjoint, i.e., let $[x], [y]$ be equivalence classes; we have that $[x] \cap [y]$ is either \emptyset or $[x] = [y]$. The former occurs if $x \not\sim y$, and the latter occurs if $x \sim y$.

Definition 6.5. We say that $X/\sim = \{[x] \mid x \in X\}$ is the set of equivalence classes on X .

Definition 6.6. $\phi : X \rightarrow X/\sim$ is the quotient map $\phi : X \ni x \mapsto [x]$. We have that ϕ is surjective. Specifically, $\phi : X \twoheadrightarrow Y \implies a \sim b$ if $\phi(a) = \phi(b)$, and \sim induces the $\phi : X \rightarrow X/\sim$ map.

We now look to construct the surjection $\varphi : G \twoheadrightarrow H$ with $\ker \varphi = N \triangleleft G$. Given $N \triangleleft G$, we define $g_1 \sim g_2$ if and only if $g_1^{-1}g_2 \in N$. This comes from the train of thought where we want $\varphi(g_1) = \varphi(g_2) \implies \varphi(g_1)^{-1}\varphi(g_2) = \varphi(g_1^{-1}g_2) = e$, i.e., we're constructing φ such that N is the kernel of φ . Clearly, we can see that \sim is an equivalence relation when defined as earlier; reflexivity and symmetry are immediate, and for transitivity, we see that if $a, b, c \in G$ are such that $a^{-1}b, b^{-1}c \in N$, then $a^{-1}c = (a^{-1}b)(b^{-1}c) \in N$, since N is a subgroup and is closed.

In this manner, let us write $G/\sim = \{[g] \mid g \in G\}$. We write this group as $G/N = \{gN \mid g \in G\}$, and $[g] = g \cdot N = \{g \cdot n \mid n \in N\}$. Indeed, we have that $\phi : G \rightarrow G/N$ by $\phi(g) = g \cdot N$. It remains to check that ϕ is a group homomorphism and $\ker \phi = N$. Let us define a group structure on G/N by including the operation $[g_1] \cdot [g_2] = [g_1g_2]$. To check

that \cdot is well-defined, observe that for any $g_1 \sim g'_1$ and $g_2 \sim g'_2$, we have that $g_1 g_2 \sim g'_1 g'_2$, since by definition, there exists $n_1, n_2 \in N$ where $g'_1 = g_1 \cdot n_1$, and $g'_2 = g_2 \cdot n_2$, so

$$g'_1 g'_2 = g_1 n_1 g_2 n_2 = g_1 g_2 g_2^{-1} n_1 g_2 n_2 = g_1 g_2 n_1^{g_2} n_2 \in g_1 g_2 N,$$

where we use the fact that N is normal to see that $n_1^{g_2} \in N$. We note that this is the only place that we've used the fact that N is normal.

Theorem 6.7. Let G/N be a group, and let $\phi : G \rightarrow G/N$ be a morphism (recall that we let $g \mapsto gN$). Then $\ker \phi = N$.⁷

Proof. Since we already established that ϕ is a well-defined morphism, we have that $\ker \phi = \{g \in G \mid \phi(g) = gN = N\} = N$, since $gN = N$ if and only if $g \in N$ (which is true in general for any subgroup, not just normal N). \square

⁷we call this the natural homomorphism irc? and its surj

§7 Day 7: First and Second Isomorphism Theorems (Sep. 24, 2025)

Recall from last lecture that we define $G/N := \{gN \mid g \in G\}$, where if $N \triangleleft G$, then $(g_1N)(g_2N) = g_1g_2N$, making it a group.

Example 7.1. Let $N = n\mathbb{Z} = \mathbb{Z} = G$ (where $n \in \mathbb{Z}$, and we regard $n\mathbb{Z}$ as the group of all integers divisible by n). We write the “lazy notation” \mathbb{Z}/n for $\mathbb{Z}/n\mathbb{Z}$,⁸ which is a group as $n\mathbb{Z}$ is normal as \mathbb{Z} is abelian. We have that $\mathbb{Z}/n\mathbb{Z} = \{[0], [1], \dots, [n-1]\}$, i.e., the equivalence classes of integers modulo n , where $[a] + [b] = [a + b]$.

As an aside, $H < G$ implies that $|G| = |H| \cdot |G/H|$, which should be regarded as the statement that “every coset has size $|H|$ ”, and that there are $|G/H|$ cosets (given by the equivalence classes). In turn, we obtain

Theorem 7.2 (Lagrange’s Theorem). If $H < G$, then $|H|$ divides into $|G|$.

As a quick check, take $|S_4| = 24$, and $|S_3| = 6$. Clearly, $6 \mid 24$.

We now proceed to introduce the isomorphism theorems. Recall the rank-nullity theorem; let $L : V \rightarrow W$ be a linear map between vector spaces. Then

$$\dim L = \dim \ker L + \dim \operatorname{im} L.$$

Specifically, we have that $V/\ker L \cong \operatorname{im} L$. We may generalize this notion to groups as well.

Theorem 7.3 (First Isomorphism Theorem). Given a morphism $\phi : G \rightarrow H$, then $G/\ker \phi \cong \operatorname{im} \phi$.

Proof. The proof of this theorem is you “read the definition and do the only reasonable thing”. Let $R : [g]_{\ker \phi} \mapsto \phi(g)$; we wish to show that R is well-defined and multiplicative. Let $L : \phi(g) \mapsto [g]$; clearly, we have that $L \circ R$ and $R \circ L$ are both the identity, so it remains to check that both maps are well-defined (we skip the proof of multiplicativity).

If g, g' are such that $[g] = [g']$, then $g^{-1}g' \in \ker \phi$, meaning that $\phi(g^{-1})\phi(g') = e$, i.e., $\phi(g) = \phi(g')$. In the other direction, let $h \in \operatorname{im} \phi$ be such that $\phi(g) = h = \phi(g')$; we check that $[g] = [g']$. We have that $\phi(g^{-1}g') = \phi(g)^{-1}\phi(g') = h^{-1}h = e$, and so g, g' belong to the same equivalence class.

A personal note; this proof is better seen by considering

$$\begin{array}{ccc} G & \xrightarrow{\phi} & H \\ \pi \downarrow & \nearrow R & \\ G/\ker \phi & & \end{array}$$

and that we are checking R is a well-defined map. Note that even though π wasn’t defined in the proof, just see it as part of the factorization sending to cosets. \square

We now give a preview of the second isomorphism theorem; let $H, K < G$ be such that $H \cap K$ is a subgroup of both H and K . Then $H/(H \cap K) \cong HK/K$.

⁸i am one million trillion percent he will backtrack this notation after backlash

We start with some intuition. In terms of vector spaces, if we let $V, U \subset W$, then $V/(V \cap U) \cong (V + U)/U$, which we may quickly verify by checking dimensions as follows;

$$\dim \frac{V}{V \cap U} = \dim V - \dim V \cap U = \dim(V + U) - \dim U = \dim \frac{V + U}{U},$$

since

$$\dim U + \dim V = \dim(U + V) + \dim(U \cap V).$$

We now discuss the group analogue of this fact. The intersection of two groups is a group, so we see that $H \cap K$ is a group; moreover,

Claim 7.4. Given $H, K < G$, we have that $HK = \{hk \mid h \in H, k \in K\} < G$ if and only if $HK = KH$.

Proof. We check the reverse implication first, i.e., we want to show that HK is a group. For any $(h_1, k_1), (h_2, k_2) \in HK$, we have that $(h_1, k_1) \cdot (h_2, k_2) = h_1(k_1 h_2)k_2$; we may let $k_1 h_1 = h'k'$ since $KH = HK$, so we obtain $h_1 h'k'k_2 = (h_1 h')(k'k_2) \in HK$. Clearly, the identity is in HK since $e_{HK} = e_{H \cap K} \in HK$, and HK admits inverses since $(hk)^{-1} = k^{-1}h^{-1} = h'k' \in HK$ for some h', k' .

For the forwards direction, assume that $HK < G$; to see $KH \subset HK$, observe that $(kh)^{-1} = h^{-1}k^{-1} \in HK$; so $((kh)^{-1})^{-1} = kh \in HK$. To see $HK \subset KH$, observe that for any $hk \in HK$, we have that $(hk)^{-1} = k^{-1}h^{-1} \in KH$, and so by the same process, $((hk)^{-1})^{-1} = hk \in KH$. \square

Definition 7.5. Let $X \subset G$ be a subset of a group. Then

- (i) $N_G(X) = \{g \in G \mid X^g = X\}$ is called the *normalizer* of X in G . In the case $X = G$, we have that $N_G(G) = G$.
- (ii) $C_G(X) = \{g \in G \mid x^g = x \text{ for all } x \in X\}$ is called the *centralizer* of X in G .
- (iii) $z(G) = C_G(G) = \{g \in G \mid gx = xg \text{ for all } x \in G\}$ is called the *center* of G .

In particular, we may check that all three are groups, and we have $z(G) < C_G(X) < N_G(X) < G$.

Example 7.6. Let $G_0 = \{\pm 1, \pm i\} \subset \mathbb{C}$ where $G_0 \cong \mathbb{Z}/4\mathbb{Z}$, induced by mapping $G_0 \ni i \mapsto [1] \in \mathbb{Z}/4\mathbb{Z}$ and $1 \mapsto [0]$. In this manner, we may define $G = \{\pm 1, \pm i, \pm j, \pm k\} \subset \mathbb{H}$ (where we regard \mathbb{H} as the quaternions). Clearly, $|G| = 8$, and i, j, k are defined to satisfy $i^2 = j^2 = k^2 = -1$. By definition of the quaternions, $ij = k, jk = i, ki = j$, with $ji = -k, kj = -i, ik = -j$, so we see $z(G) = \{1, -1\}$ and the centralizer of G_0 in G is given by $C_G(G_0) = G_0$. To compute the normalizer of G_0 in G , observe that

$$j^{-1}G_0j = G_0, \quad (-j)G_0j = G_0, \quad (-j)ij = -i \in G_0,$$

showing that $N_G(G_0) = \{\pm 1, \pm i, \pm j\}$.

Theorem 7.7 (Second Isomorphism Theorem). Let $H, K < G$ and $H < N_G(K)$. Then $HK = KH$, $H \cap K \triangleleft H$, $K \triangleleft KH$ and

$$\frac{H}{H \cap K} \cong \frac{HK}{K}.$$

Proof. $H < N_G(K)$, so for all $h \in H$, we have $hK = Kh$, i.e., $HK = KH$ and HK is a group as seen previously. We continue the proof next lecture. \square

§8 Day 8: Third Isomorphism Theorem (Sep. 26, 2025)

Dror strongly suggests starting problem set 3 early. Recall the second isomorphism theorem from last class; if $H, K < G$ and $H < N_G(K)$, then $HK = KH$, $K \triangleleft HK$, $H \cap K \triangleleft H$, and $HK/K \cong H/(H \cap K)$.

Proof. We prove each property one by one.

- (i) $HK = KH$ because $hK = Kh$, as $K = h^{-1}Kh$ as $h \in N_G(K)$.
- (ii) $K \triangleleft HK$ by construction, i.e., $K^{hk} = (K^h)^k = K^k = K$.
- (iii) $H \cap K \triangleleft H$; we want to show that if $g \in H \cap K$ and $h \in H$, then $g^h \in H \cap K$. This is true from observing $g^h \in H$ as both $g, h \in H$, and $g^h \in K$ as $g \in K$ and $h \in N_G(K)$.
- (iv) To see the isomorphism, let $R : HK/K \rightarrow H/(H \cap K)$, and $L : H/(H \cap K) \rightarrow HK/K$. R maps $hkK \mapsto h(H \cap K)$, and L maps $[hk]_K \mapsto [h]_{H \cap K}$; clearly, L is well-defined from observing $[h]_{H \cap K} = [h]_K$, since if

$$[h_1]_{H \cap K} = [h_2]_{H \cap K},$$

then $h_1^{-1}h_2 \in H \cap K \subset K$ and so $[h_1]_K = [h_2]_K$. We also see that R is well-defined by taking $[h_1k_1]_K = [h_2k_2]_K$, for which we want to show that $[h_1]_{H \cap K} = [h_2]_{H \cap K}$. We may observe that

$$(h_1k_1)^{-1}(h_2k_2) = k_1^{-1}h_1^{-1}h_2k_2 = k' \in K,$$

meaning $h_1^{-1}h_2 \in H \cap K$, since $h_1^{-1}h_2 \in H$ trivially and

$$k_1(k_1^{-1}h_1^{-1}h_2k_2)k_2^{-1} = k_1k'k_2^{-1} \in K. \quad \square$$

Theorem 8.1 (Third Isomorphism Theorem). If $K, H < G$ with $K < H$ (K is a normal subgroup of H per $K \triangleleft G$), then $\frac{G/K}{H/K} = G/H$.

Proof. Let $R : [[g]_K]_{H/K} \mapsto [g]_H$ and $L : [g]_H \mapsto [[g]_K]_{H/K}$. We check that R is well-defined. For R , observe that if g_1, g_2 are such that

$$[[g_1]_K]_{H/K} = [[g_2]_K]_{H/K},$$

then $[g_1]_K^{-1}[g_2]_K = [h]_K$ for some h , i.e., $g_1^{-1}g_2 = hk$ for some $k \in K$. We want to show that $[g_1]_H = [g_2]_H$, namely, $g_1, g_2 \in H$; but this is already true because $g_1^{-1}g_2 = hk \in HK \subset H$. \square

§9 Day 9: Lattice Theorem and Simple Groups (Oct. 1, 2025)

Recall the first three isomorphism theorems;

- (i) If $\phi : G \rightarrow H$ is a morphism, then $\ker \phi \cong \text{im } \phi$
- (ii) If $H, K < G$ with $K^H = K$, then $H/(H \cap K) \cong HK/K$.
- (iii) If $B, C \triangleleft A$ and $C \triangleleft B$, then $(A/C)/(B/C) \cong A/B$.

We now present the fourth isomorphism theorem.

Theorem 9.1 (Lattice Theorem). If $N \triangleleft G$, then $\pi : G \rightarrow G/N$ induces a “faithful” bijection between $\{H \mid N < H < G\}$ and the subgroups of G/N . Specifically, for all A, B such that $N < A < B < G$, we have that $\{1\} < \pi(A) < \pi(B) < G/N$, and if $N < A \triangleleft B < G$, we have that $\{1\} < \pi(A) \triangleleft \pi(B) < G/N$, and vice versa. Moreover, $\pi(A \cap B) = \pi(A) \cap \pi(B)$.

Proof. Left as an exercise. □

Definition 9.2. A group is said to be *simple* if it admits no normal subgroups aside from $\{e\}$ and itself.

Observe that $\mathbb{Z}/n\mathbb{Z}$ is simple if and only if n is prime. We claim that if $A < \mathbb{Z}$, then A is given by $m\mathbb{Z}$ for some unique m .

Proof. Let $A < \mathbb{Z}$, and observe that if $A = \{0\}$, then $m = 0$; otherwise, let $k = \min\{k \in A \mid k > 0\}$. This means that $m\mathbb{Z} \subset A$. Now, suppose $k \in A$, and write $k = m \cdot q + r$ with $0 \leq r < m$. We have that $r = k - mq \in A$, and by minimality of m , we must have $r = 0$, and so $k = mq$, i.e., $k \in m\mathbb{Z}$. □

In this manner, we see that $m\mathbb{Z} > n\mathbb{Z}$ if and only if $\frac{n}{m}$ is an integer. As an example, observe that $2\mathbb{Z} > 4\mathbb{Z}$, and $\frac{4}{2} = 2 \in \mathbb{Z}$. This means that the set of nontrivial subgroups of $\mathbb{Z}/n\mathbb{Z}$ is equivalent to the set of integers $\{m\mathbb{Z} \mid m \mid n\}$, and the smallest set containing nothing other than $n\mathbb{Z}$ and \mathbb{Z} occurs if and only if n itself is prime.

Example 9.3. Is S_n simple?

No, but it is *nearly*. Let us define the sign function $\text{sign} : S_n \rightarrow \{\pm 1\}$, for which we may regard $\{\pm 1\}$ as a group with two elements. Let $S_n \ni \sigma \mapsto \text{sign}(\sigma) := (-1)^\sigma$, which we will call the *parity* of σ , where if it is even, $\text{sign}(\sigma) = 1$, and odd yields -1 .⁹ It remains to check if sign is a well-defined function.

Let us associate to each $\sigma \in S_n$ a matrix $M_\sigma \in M_{n \times n}$, where $M_\sigma = (\delta_{i, \sigma(i)})_{ij}$, i.e., one such matrix might look like

$$M_{[1,3,2]} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}.$$

In this manner, we have that $\text{sign } \sigma = \det M_\sigma$.

Definition 9.4. A *transposition* is a permutation given by (ij) ; i.e., it admits a single 2-cycle while fixing all other elements.

⁹dror has a pretty confusing explanation of parity, but see this [link](#) for better intuition about it. combinatorics type stuff.

Claim 9.5. Every permutation $\sigma \in S_n$ can be written as a product of transpositions (obviously, such a product is not necessarily unique).

An informal proof of this is to simply observe the bubble sort algorithm. We have that $\text{sign}(\sigma)$ is equal to (-1) to the power of however many transpositions are in the transposition decomposition of σ ; the question is, is this well-defined? We may formally define sign as

$$\text{sign}(\sigma) = \prod_{i=1}^n (-1)^{(\sigma_i)-1}, \quad (\sigma_i = \sigma(i))$$

for which we may write down equivalent formulations

$$\text{sign}(\sigma) = \prod_{i < j} \text{sign}(\sigma_j - \sigma_i) = \prod_{i \neq j} \frac{\text{sign}(\sigma_j - \sigma_i)}{\text{sign}(j - i)} = \prod_{\substack{\{i,j\} \subset [n] \\ i \neq j}} \text{sign}\left(\frac{\sigma_j - \sigma_i}{j - i}\right),$$

where each successive expression is “gooder” than the rest.¹⁰

Theorem 9.6. sign is a morphism.

Proof. Directly write as follows for any $\sigma, \tau \in S_n$,

$$\begin{aligned} (-1)^{\sigma\tau} &= \prod_{i \neq j} \text{sign}\left(\frac{\sigma\tau_j - \sigma\tau_i}{\tau_j - \tau_i}\right) \text{sign}\left(\frac{\tau_j - \tau_i}{j - i}\right) \\ &= \prod_{i \neq j} \text{sign}\left(\frac{\sigma\tau_j - \sigma\tau_i}{\tau_j - \tau_i}\right) \prod_{i \neq j} \text{sign}\left(\frac{\tau_j - \tau_i}{j - i}\right) \\ &= (-1)^\sigma \cdot (-1)^\tau, \end{aligned}$$

since τ is a bijection. □

Definition 9.7. We define the *alternating group* $A_n \subset S_n$ as $\ker \text{sign}$, i.e., the set of even permutations in S_n .

By the first isomorphism theorem, we have that

$$|A_n| = \frac{|S_n|}{2} = \frac{n!}{2}, \quad n \geq 2,$$

by the first isomorphism theorem. For example, $|A_3| = 3$, $|A_4| = 12$, $|A_5| = 60$.

Theorem 9.8. The alternating group A_n is simple for $n \neq 4$. See this [handout](#).

¹⁰dror-ism

§10 Day 10: Jordan-Hölder Decomposition (Oct. 3, 2025)

Recall from last class that if $N \triangleleft G$, then $N, G/N$ are simple. \mathbb{Z}/n is simple if and only if n is prime. The sign function $\text{sign} : S_n \rightarrow \{\pm 1\}$ tells you the parity of a permutation, where $\text{sign } \sigma = 1$ if σ is even and -1 if it is odd. Finally, $A_n = \ker \text{sign}$ is the “alternating” group, i.e., the set of even permutations in S_n .

Per the [handout](#) from last time, we have a proof of why A_n is simple for all but $n = 4$; the proof is just casework bash, so I will not elaborate here.

We now move onto Jordan-Hölder.

Definition 10.1. A Jordan-Hölder decomposition for a group G is a sequence

$$G = G_0 \triangleright G_1 \triangleright \cdots \triangleright G_n = \{0\}$$

such that for all i , $H_i = G_i/G_{i+1}$ is simple.

We give a few motivating examples. Let us consider $\mathbb{Z}/n\mathbb{Z}$, where $n = p_1 \cdots p_k$. Then we have that

$$\mathbb{Z} \triangleright p_1\mathbb{Z} \triangleright p_1p_2\mathbb{Z} \triangleright \cdots \triangleright n\mathbb{Z}.$$

By modding out the entire sequence by $n\mathbb{Z}$, we have

$$\mathbb{Z}/n\mathbb{Z} \triangleright \frac{p_1\mathbb{Z}}{n\mathbb{Z}} \triangleright \frac{p_1p_2\mathbb{Z}}{n\mathbb{Z}} \triangleright \cdots \triangleright \frac{n\mathbb{Z}}{n\mathbb{Z}} = \{e\};$$

let the elements of the sequence be named G_0, G_1, \dots, G_k in order; observe that we have (where we pick a random index because Dror does that),

$$H_2 = \frac{G_2}{G_3} = \frac{p_1p_2\mathbb{Z}/n\mathbb{Z}}{p_1p_2p_3\mathbb{Z}/n\mathbb{Z}} = \frac{p_1p_2\mathbb{Z}}{p_1p_2p_3\mathbb{Z}}$$

by the third isomorphism theorem, and we may factor out p_1, p_2 to obtain $\mathbb{Z}/p_3\mathbb{Z}$, which we know is simple. We may follow the same computation to demonstrate that the above sequence is indeed a Jordan-Hölder decomposition. Note that the decomposition itself is not necessarily unique with respect to the group, however, because as seen above, we may take p_1, \dots, p_k in any order to obtain a sequence with the same property.

For another example, consider $G = S_n$ with $n \geq 5$. We have that

$$G = G_0 \triangleright G_1 = A_1 \triangleright G_2 = \{e\}.$$

We have that $H_0 = S_n/A_n = \text{im}(\text{sign}) = \{\pm 1\} = \mathbb{Z}/2\mathbb{Z}$ which we know is simple, and $H_1 = A_n/\{e\} = A_n$ is simple.

For a third example, consider $G = S_4$ (which has 24 elements). Since A_4 is the only non-simple alternating group, we may write

$$G_0 = S_4 \triangleright A_4 \triangleright \ker \phi = \{e, (12)(34), (13)(24), (14)(23)\} \cong \mathbb{Z}/2\mathbb{Z} \times \mathbb{Z}/2\mathbb{Z} \triangleright \{e\}.$$

where $\phi : A_4 \rightarrow A_3$ and $H_0 = S_4/A_4 = \mathbb{Z}/2\mathbb{Z}$, $H_1 = \text{im } \phi = A_3 = \mathbb{Z}/3\mathbb{Z}$.

§11 Day 11: ... (Oct. 8, 2025)

§12 Day 12: Group Actions, First Sylow Theorem (Oct. 10, 2025)

Recall the definitions from last class; we write the left action $G \curvearrowright X$ denoting a morphism $G \rightarrow S(X)$, where $(g, x) \mapsto gx$ such that $ex = x$ and $(g_1g_2)x = g_1(g_2x)$; similarly, the right action $X \curvearrowleft G$ means an anti-morphism $G \rightarrow S(X)$ where $(x, g) \mapsto xg$, $x = xe$, and $x(g_1g_2) = (xg_1)g_2$. Both left and right actions make a category. We say that a G -set is transitive if, for all x_1, x_2 , there exists g such that $gx_1 = x_2$. Recall the theorem from last class,

Theorem 12.1. Every G -set is a disjoint union of transitive G -sets, and if $G \subset X$ is transitive and $x_0 \in X$, then¹¹

$$X \cong G/[\text{stab}(x_0) := \{g \mid gx_0 = x_0\}] \cong G/H,$$

where the latter isomorphism is given by $(g', (gH)) \mapsto g'gH$.

Proof. Define the equivalence relation \sim on X by $x_1 \sim x_2$ if and only if there exists an element $g \in G$ such that $gx_1 = x_2$. We see that \sim is well-defined, as (i) $ex = x$, (ii) $gx_1 = x_2$ implies $g^{-1}x_2 = x_1$, (iii) if $g_1x_1 = x_2$ and $g_2x_2 = x_3$, then $g_2g_1x_1 = x_3$.

From this, we have that X/\sim is given by the set of orbits of X , i.e., $\{gx_0 \mid x_0 \in X\}$. Each equivalence class is called a G -orbit, and is always of the form Gx_0 for some $x_0 \in X$; clearly, each orbit is transitive, since $x_1 = g_1x_0$ and $x_2 = g_2x_0$ implies $x_1, x_2 \in Gx_0$, with $g_2g_1^{-1}x_1 = x_2$. The disjointness for the first part of the theorem comes from the fact that equivalence classes are always disjoint.

For the second part of the theorem, given $x_1 \in X$, by transitivity, there exists $g \in G$ such that $gx_0 = x_1$. We will construct maps $L : G/H \rightarrow X$ and $R : X \rightarrow G/H$ (where H is the stabilizer) to demonstrate the isomorphism between X and G/H . Let $R(x_1) = gH$; observe this map is well defined because for any other $g' \in G$ satisfying $g'x_0 = x_1$, we have $g'H = gH$, since $gx_0 = x_1$, $g'x_0 = x_1$ imply $gx_0 = g'x_0$, so $x_0 = g^{-1}g'x_0$ implies $g^{-1}g' \in \text{stab}_X(x_0) = H$. Now, let $L : gH \mapsto gx_0$; then L is well-defined as we may check per earlier, so L, R are morphisms of G -sets, meaning we have $L \circ R = I$, $R \circ L = I$. \square

Theorem 12.2 (Orbit-Stabilizer). If $G \curvearrowright X$ and $\{x_i\}$ are representatives from each orbit, then

$$|X| = \sum_i \frac{|G|}{|\text{stab}_X(x_i)|}$$

Proof. The proof is obvious from the above construction. \square

We now introduce the class equation. Let $G \curvearrowright G$ (where conjugation is a right action). Pick one y_i from each nontrivial orbit (each orbit contains at least one element, but some orbits contain nothing else, so nontrivial means non-singleton), i.e., one y_i from each non-trivial “conjugacy class of G ”. Then $|G|$ is given by the the number of 1-element orbits and the sum $\sum_i \frac{|G|}{|\text{stab}_G(y_i)|}$. Specifically, this is written

$$|G| = |Z(G)| + \sum_i [G : C_G(y_i)]$$

¹¹personal note: [link](#)