

# Multiple Models

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## 1 Motivation

## 2 Perturbing Training Examples

## 3 Summary

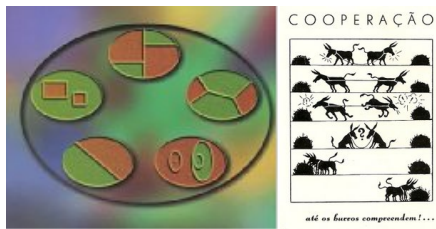
# Outline

- 1 Motivation
- 2 Perturbing Training Examples
- 3 Summary

# Multiple Models

How to take advantage of these differences?

Would be possible to obtain an ensemble of classifiers with a performance better than each individual classifier?



Observation: There is no overall better algorithm.

- Experimental results from Statlog and Metal project;
- Theoretical Results: *No free lunch* theorems.

# Multiple Models

A simulation study:

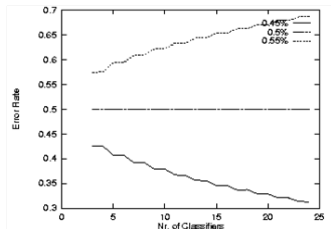
- Consider a decision problem with two equi-probable classes:  
 $P(Class_1) = P(Class_2)$
- The number of classifiers in the ensemble varies between [3, ..., 25].
- All classifiers have the same probability of error. Assume  
 $P_{error}(Classifier_i) = \{0.45; 0.5; 0.55\}$

Multiple Model: aggregate the predictions of individual classifiers

- For each example
  - Each classifier predicts a class label.
  - Count the votes for each class
  - Predict the most voted class: *uniform voting*.

# Multiple Models: Simulation

Study how the error varies when varying the number of classifiers in the ensemble.  
Probability of error of each classifier:



- $P = 0.5$  (random choice)  
The error of the ensemble is constant: 0.5
- $P > 0.5$   
The error of the ensemble increases linearly with the number of classifiers.
- $P < 0.5$   
The error of the ensemble **decreases** linearly with the number of classifiers.

# Another Necessary Condition

## Necessary Condition

The error of the ensemble decreases, with respect to each individual classifier, iff each individual classifier has a performance better than a random choice.

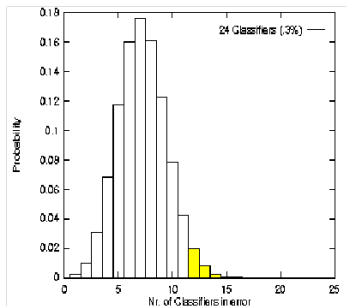
# Multiple Models: Simulation

Assume an ensemble of 23 classifiers:

- probability of error of each classifier: 30%;
- aggregation by uniform vote.

Given a test example:

- the ensemble will be in error iff 12 or more classifiers are in error.
- The probability of error in the ensemble is given by the area under the curve of a binomial distribution;
- In this case this area is 0.026.
- Much less than each individual classifier





# Necessary Conditions

*To achieve higher accuracy the models should be diverse and each model must be quite accurate Ali & Pazzani 96*

## Necessary Conditions

Classifiers in the ensemble, should have:

- performance better than random guess;
- non-correlated errors;
- errors in different regions of the instance space.

# Multiple Models

- Combining Outputs
  - Voting Methods
  - Fusion of Classifiers
  - Model Applicability
- Perturbing the set of training examples
  - Homogeneous Classifiers
    - Bagging
    - Boosting
  - Heterogeneous Classifiers
    - Cascading
    - Stacking
- Perturbing the set of attributes
- Perturbing test examples

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## Using different distributions of examples

- Bagging, L. Breiman 92
- Boosting, R. Schapire and Y. Freund, 94





# Bagging

Given a dataset  $D$  with  $n$  examples, bagging generates  $m$  new training sets  $D_i$ , each of size  $n'$ , by sampling from  $D$  uniformly and with replacement.

- By sampling with replacement, some observations may be repeated in each  $D_i$ .
- When drawing with replacement  $n'$  values out of a set of  $n$  (different and equally likely), the expected number of unique draws is  $1 - (1 - \frac{1}{n})^{n'}$
- For large  $n$ , this probability is  $1 - 1/e$ , where  $e$  is the base of natural logarithms
- On average, each replica will contain 36.8% of duplicates

# Why Bagging Works ?

Choosing the majority vote over several classifiers reduces the randomness associated with individual models.

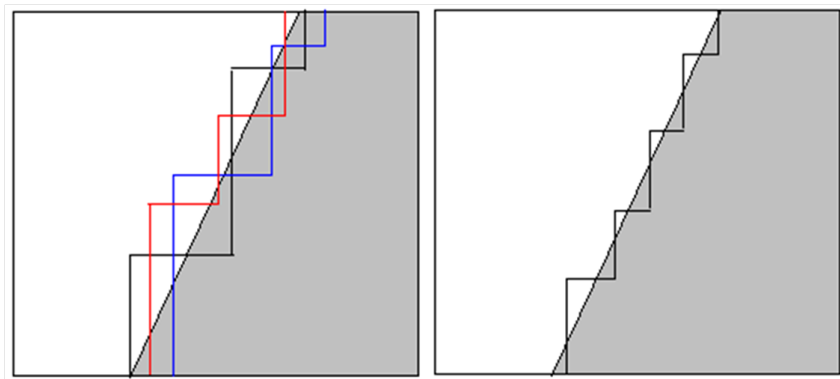
## Example: decision trees

Decision trees use greedy algorithms. The training set can influence too much in:

- The choice of attributes for splitting-tests;
- The choice of *cut\_points*



# Why Bagging Works ?



# Bagging

## Properties:

- Requires unstable algorithms (greedy like)
- Algorithms sensible to small perturbations of the training set;
  - Decision trees, Rule learners, Neural Networks, etc.
- Easy to implement with any algorithm;
- Easy to implement in parallel environments.

## The bias-variance argument:

Error decreases due to reduction in the variance component.

# Random Forests

Breiman, *Random Forests*, MLJ 2001;

## A variant of Bagging;

- Repeat  $k$  times
  - Training set = Draw with replacement  $N$  examples;
  - Built a decision tree
    - Choose (without replacement)  $i$  features
    - Choose best of these  $i$  as the root of this (sub)tree
  - Do NOT prune

where  $N$  is the nr. of examples,  $F$  nr. of features, and  $i$  some number  $\ll F$ .

# Boosting

- Can a set of *weak learners* create a single *strong learner*?
- A weak learner is defined to be a classifier which is only slightly correlated with the true classification.
- A strong learner is a classifier that is arbitrarily well-correlated with the true classification.

Rob Schapire, *Strength of Weak Learnability* Journal of Machine Learning Vol. 5, pages 197-227. 1990

# Boosting

## Theoretical framework

- Given:
  - A confidence level  $\delta$ , so high as desired;
  - An error bound  $\epsilon$ , so small as desired;
- Is it possible to design an algorithm that with probability  $\delta$  generates an hypothesis with error  $\epsilon$  for *any* distribution of examples generated for a given problem?

Boosting is one of such algorithms!

# Boosting

## Characteristics

- Boosting is an iterative algorithm;
- Associates a weight with each example;
- The weight indicates the probability of the example being select in a uniform sampling;

# Boosting

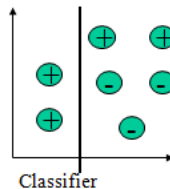
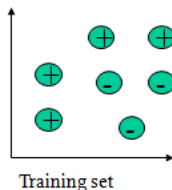
## Base Algorithm

- Input:
  - *weak-learner* algorithm that generates a classifier better than a random guess;
  - Training set.
- Initialize uniform weights of examples, sum equal to one;
- For  $i$  in  $1 \dots N$ 
  - Generate a classifier using the actual distribution of the examples;
  - The weight of the examples misclassified increases;
  - The weight of the examples correctly classified decreases;
- The classifiers generated in all iterations are aggregated using weighted voting.

# Boosting: Example

*Weak learner* – generate an hyper-plane perpendicular to one of the axis

1<sup>a</sup> Iteration

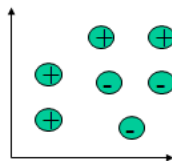




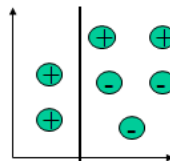
# Boosting: Example

*Weak learner* – generate an hyper-plane perpendicular to one of the axis

1<sup>a</sup> Iteration

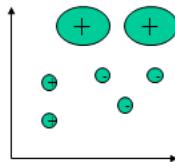


Training set



Classifier

2<sup>a</sup> Iteration

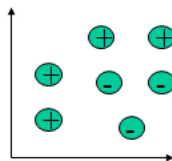


Training set

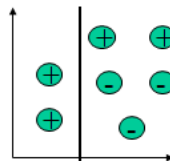
# Boosting: Example

*Weak learner* – generate an hyper-plane perpendicular to one of the axis

1<sup>a</sup> Iteration

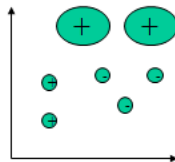


Training set

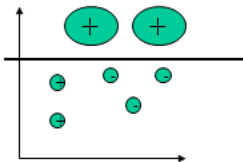


Classifier

2<sup>a</sup> Iteration



Training set

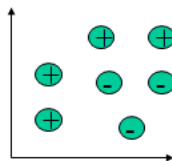


Classifier

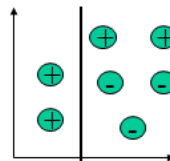
# Boosting: Example

*Weak learner* – generate an hyper-plane perpendicular to one of the axis

1<sup>a</sup> Iteration

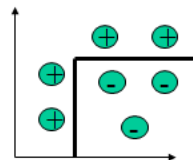


Training set

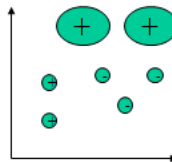


Classifier

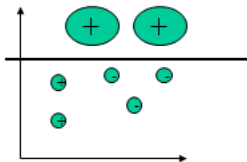
**Ensemble of the  
2 classifiers**



2<sup>a</sup> Iteration



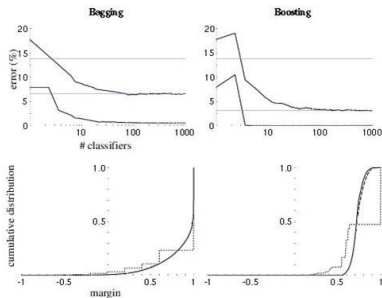
Training set



Classifier

# Comparison between Bagging & Boosting

- Bagging
  - Error reduction due to reduction in Variance;
  - Effective with unstable classifiers;
  - Not reported increase of error;
- Boosting
  - Error reduction due to reduction in bias and variance;
  - risky in problems with noise (increase of the error);

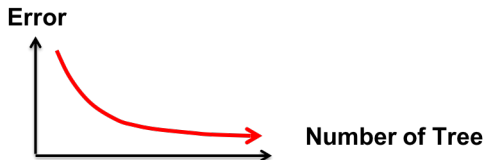


# XGBoost - Extreme Gradient Boosting Tree

- Additive tree model: add new trees that complement the already-built ones



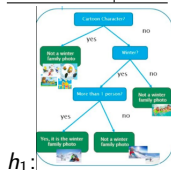
## Greedy Algorithm



# XGBoost: Learning

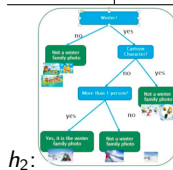
## First tree:

$e_1$	$\mathbf{x}_1$	$y_1$
$e_2$	$\mathbf{x}_2$	$y_2$
...		
$e_n$	$\mathbf{x}_n$	$y_n$



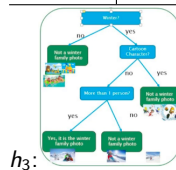
## Second tree:

$e_1$	$\mathbf{x}_1$	$y_1 - h_1(e_1)$
$e_2$	$\mathbf{x}_2$	$y_2 - h_1(e_2)$
...		
$e_n$	$\mathbf{x}_n$	$y_n - h_1(e_n)$



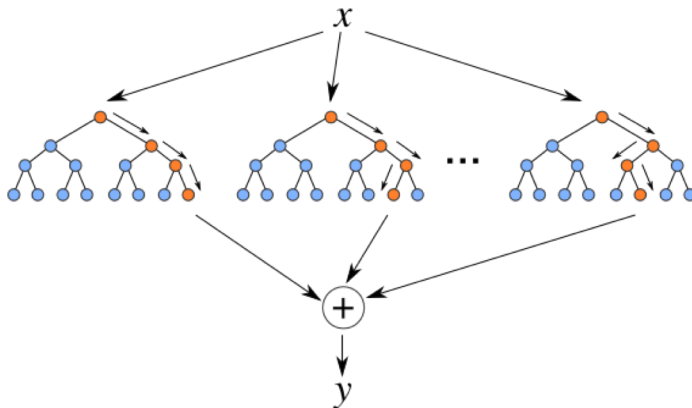
## Second tree:

$e_1$	$\mathbf{x}_1$	$y_1 - h_1(e_1) - h_2(e_1)$
$e_2$	$\mathbf{x}_2$	$y_2 - h_1(e_2) - h_2(e_2)$
...		
$e_n$	$\mathbf{x}_n$	$y_n - h_1(e_n) - h_2(e_n)$



# XGBoost - Extreme Gradient Boosting Tree

- Response is the optimal linear combination of all decision trees



# Stacking Generalization

Wolpert, *Stacking Generalization*, Neural Networks, Nr. 5, 1992

## Layered Learning

The output of an ensemble of trained classifiers is used as input to the next-layer of classifiers.

## Stacked Generalization with 2 layers

- $Layer_0$

**Data** : is original training set;

**Models** : classifiers trained from the  $layer_0$  data;

- $Layer_1$

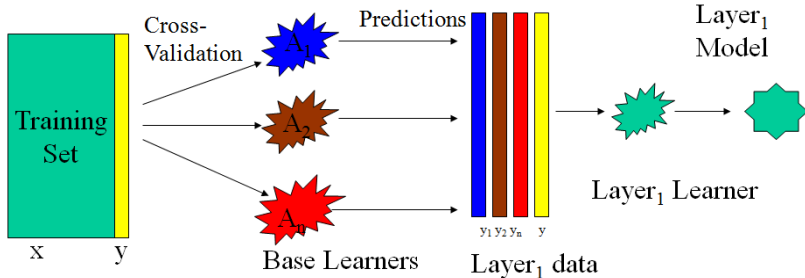
**Data** : the predictions of  $layer_0$  classifiers on  $layer_0$  data using cross-validation;

**Models** : classifier trained from the  $layer_1$  data;



# Stacking Generalization

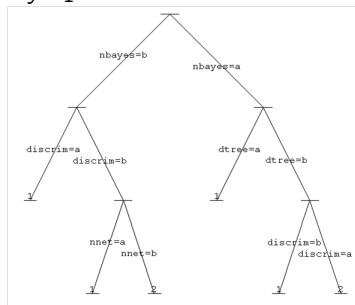
Learning  $Layer_1$  Model



# Stacking Generalization: Example

Base models: naive Bayes, neural net, decision tree, linear discriminant (LDA);

*layer<sub>1</sub>* model: decision tree



*layer<sub>1</sub>* model: LDA

```
> lda(observed~.,df)
Call:
lda.formula(observed ~ ., data = df)

Prior probabilities of groups:
  1  2
0.51 0.49

Group means:
      discrim2  nbayes2      nnet2      dtree2
1 0.4509804 0.5686275 0.5098039 0.3725490
2 0.4285714 0.4693878 0.4489796 0.4693878

Coefficients of linear discriminants:
          LD1
discrim2 -0.3424098
nbayes2  -1.3950698
nnet2    -1.0185849
dtree2    1.0547212
```

# Analysis

## Main Goal

$Layer_1$  classifier search for the best bias between  $layer_0$  classifiers.

*Stacking Generalization: when it works?*, Ting & Witten, IJCAI-97,

- Which Classifier for  $layer_1$ ?
  - Linear discriminant (LDA):  
weighted vote of predictions of each base classifier.
- Which Attributes for  $layer_1$ ?
  - Class probability distribution of base classifiers

## Effectiveness

Stacking is effective in reduction of error's bias component

# Cascade Generalization

Gama, Brazdil; *Cascade Generalization*, Machine Learning, 2000

- Layered Learning: Sequential composition of classifiers,
- A each layer:
  - Learn a classifier
  - Extend the training set with new attributes
  - The new attributes are the predictions of classifier learnt at this layer
  - The new attributes might be:
    - The class label predicted by the classifier;
    - Class distribution given by each base classifier;

# Cascade Generalization

Sequential composition of a naive-Bayes and a Decision Tree:

## Dataset Original

```
3,4,3,4,B
4,1,4,1,B
4,2,2,1,L
5,2,5,3,R
2,5,4,4,R
2,3,4,3,R
5,1,4,5,R
4,3,2,5,L
3,3,2,5,R
1,3,4,5,R
```

## Dataset Extendido

```
3,4,3,4,0.461183,0.077635,0.461183,B
4,1,4,1,0.413818,0.172365,0.413818,B
4,2,2,1,0.838750,0.089446,0.071804,L
5,2,5,3,0.307441,0.089143,0.603416,R
2,5,4,4,0.283686,0.104362,0.611952,R
2,3,4,3,0.213796,0.070892,0.715312,R
5,1,4,5,0.072916,0.075340,0.851744,R
4,3,2,5,0.505602,0.094848,0.399550,L
3,3,2,5,0.391624,0.080813,0.527563,R
1,3,4,5,0.030005,0.043305,0.926691,R
```

## Arvore de Decisao (dataset extendido)

```
File stem <balnew>
Read 625 cases (7 attributes) from balnew.data
Decision Tree:
p3 > 0.471812 : R (288.0)
p3 <= 0.471812 :
|   p1 <= 0.471812 : B (49.0)
|   p1 > 0.471812 : L (288.0)
Tree saved
```

# How to Use?

- Use algorithms with different bias-variance profiles
- At the beginning of the sequence use low-variance algorithms
- At the end of the sequence use low-bias algorithms

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# Summary

Well designed ensembles of classifiers allow improve performance over their individual elements.

## Necessary Conditions

- Variability between elements;
- Low Error correlation;
- Each individual classifier must be better than a random choice.



# Bibliography

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- Wolpert, D. Stacked Generalization, Neural Networks, 1992