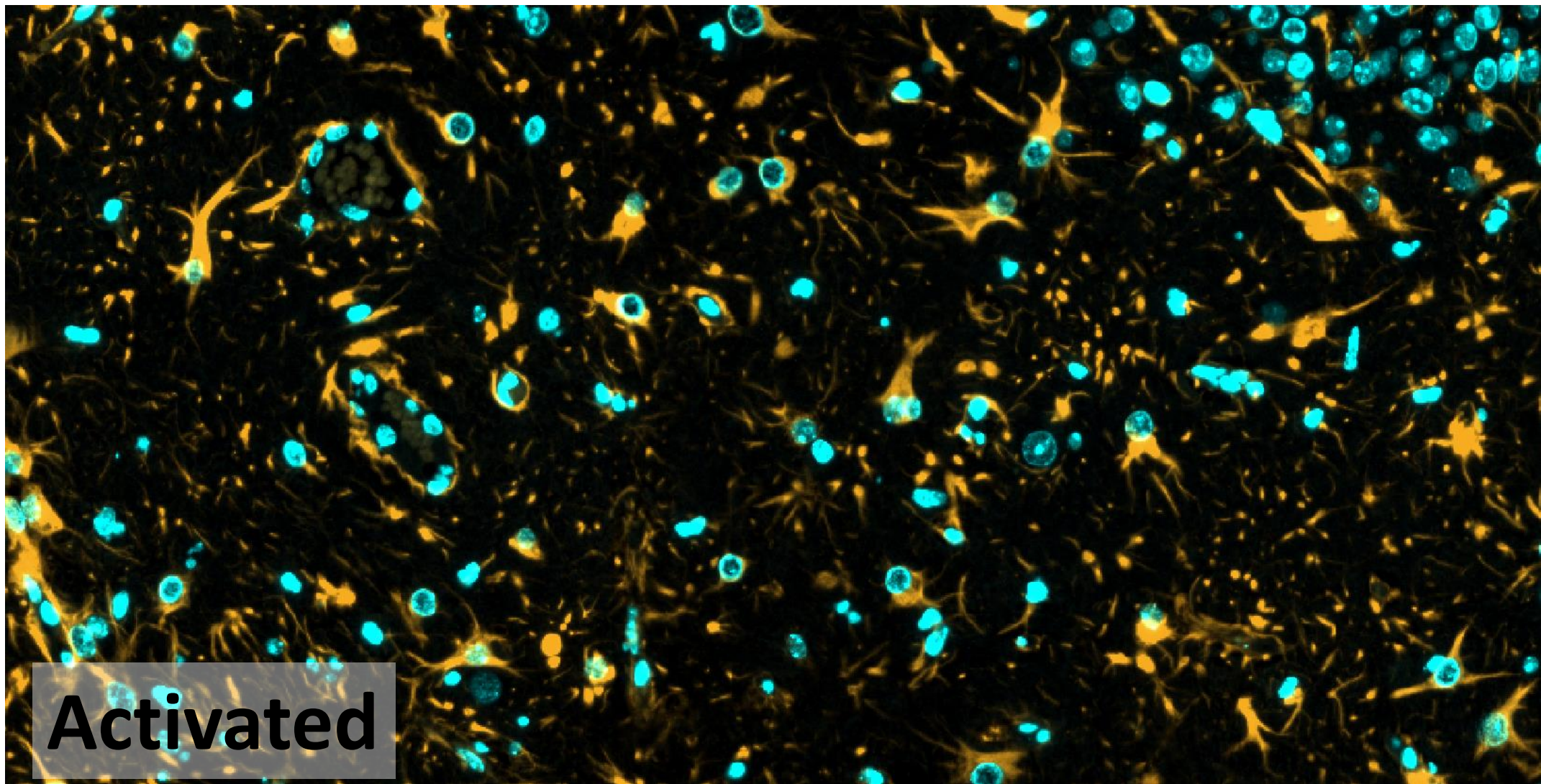
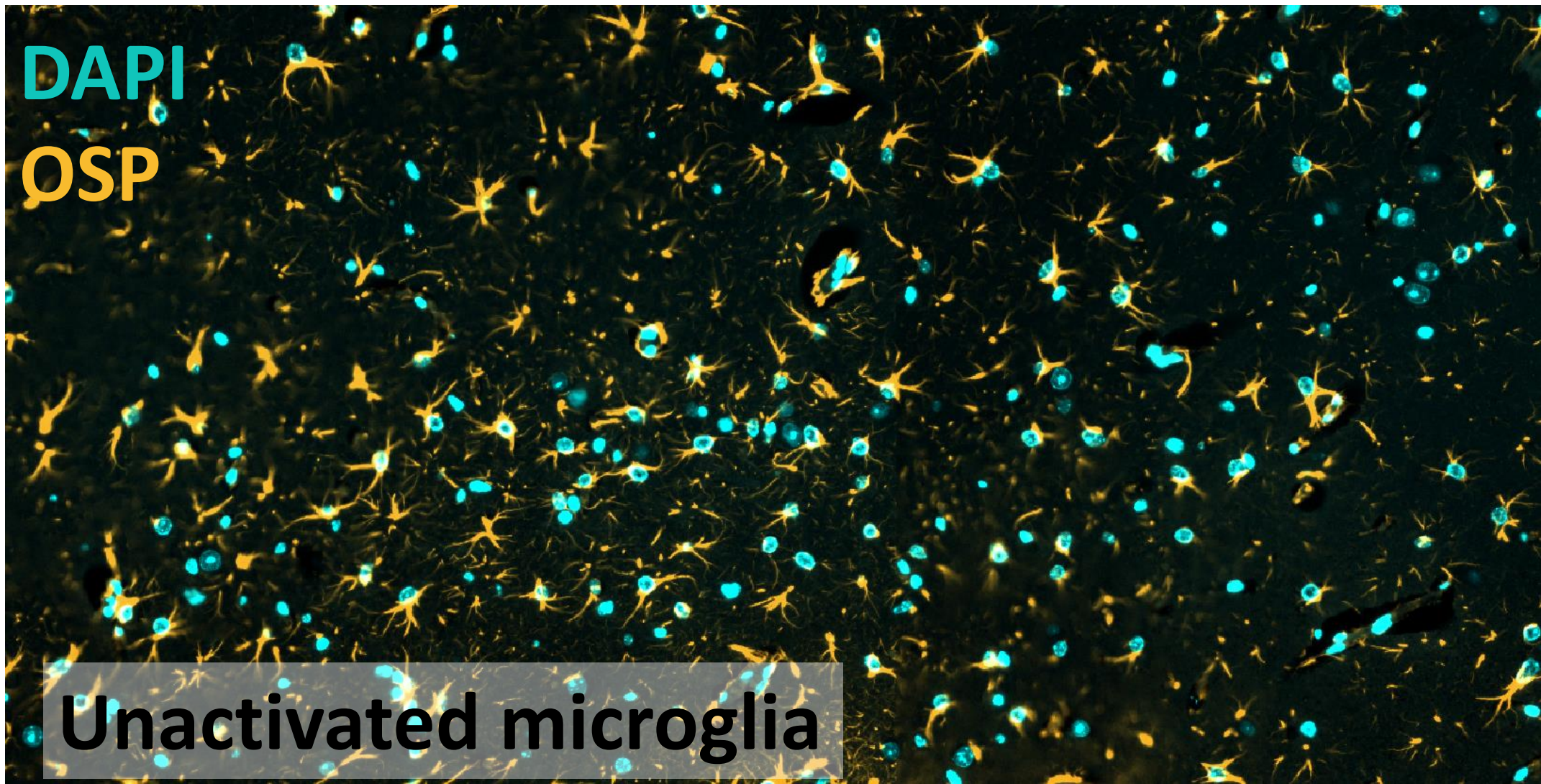


Dimensionality reduction- PCA & UMAP

Johannes Müller

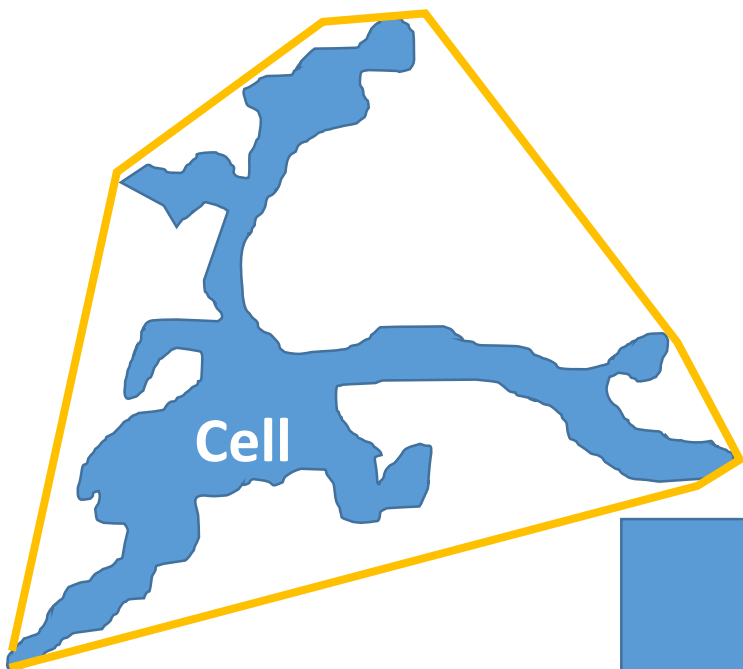
Ideal situation: Biological property is related to a known, measurable feature in image data

Example: Unactivated vs. activated microglia in mouse brain



Existing scores: “Ramification index” (Wittekind et al., 2022)

$$Rammification\ index = \frac{A_C}{A_P}$$

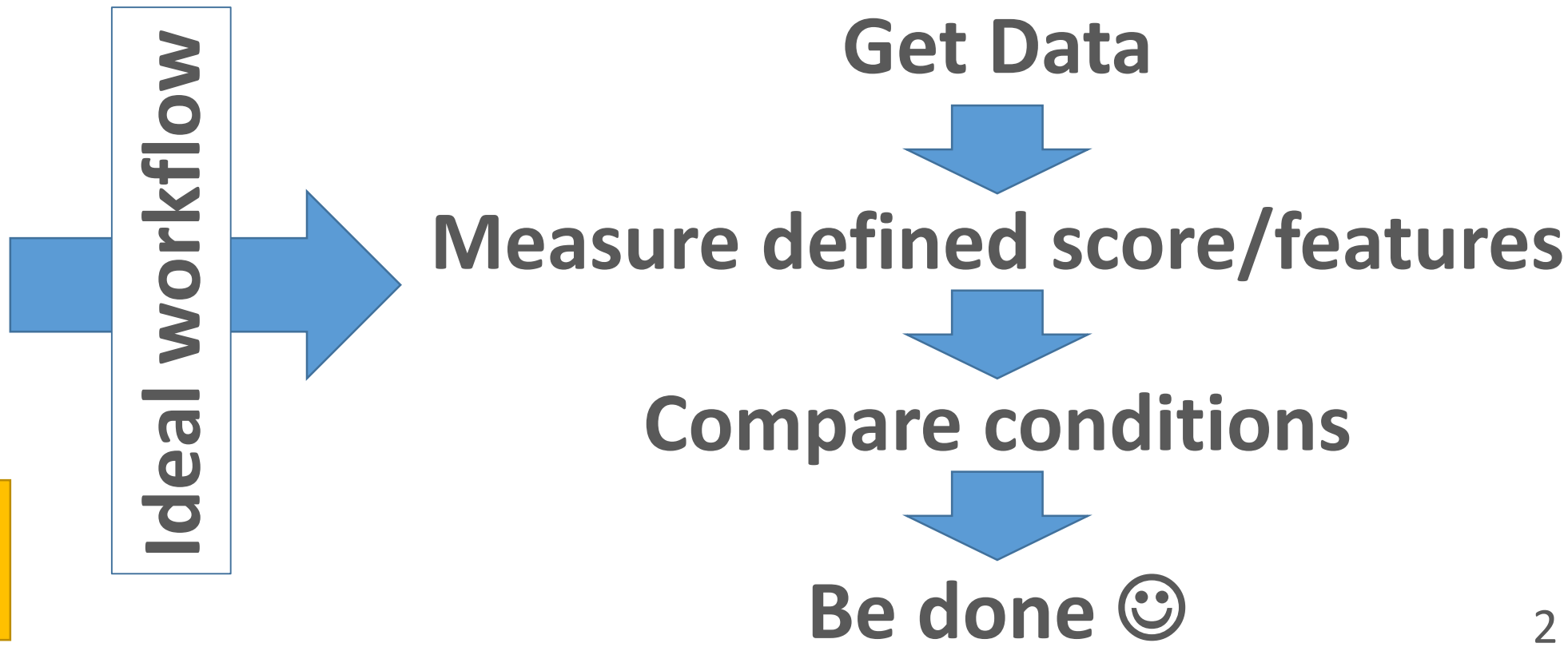


That’s actually just…?

Solidity

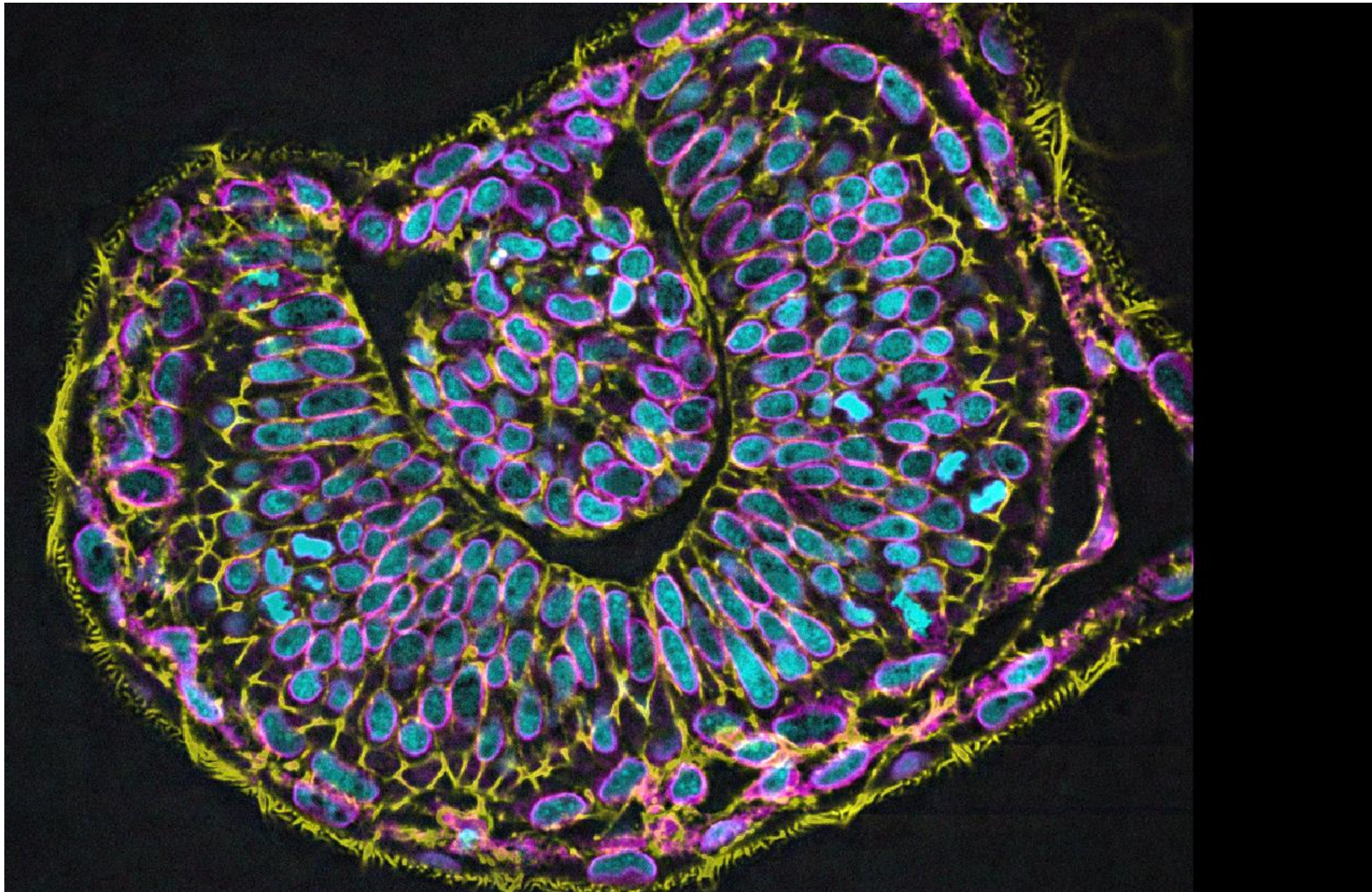
Perimeter

Circularity



More typical situation:

- We expect or know of a biological effect (e.g., through external cues, cell growth stages, etc.)
- We do not know how this effect can be measured or how it manifests itself

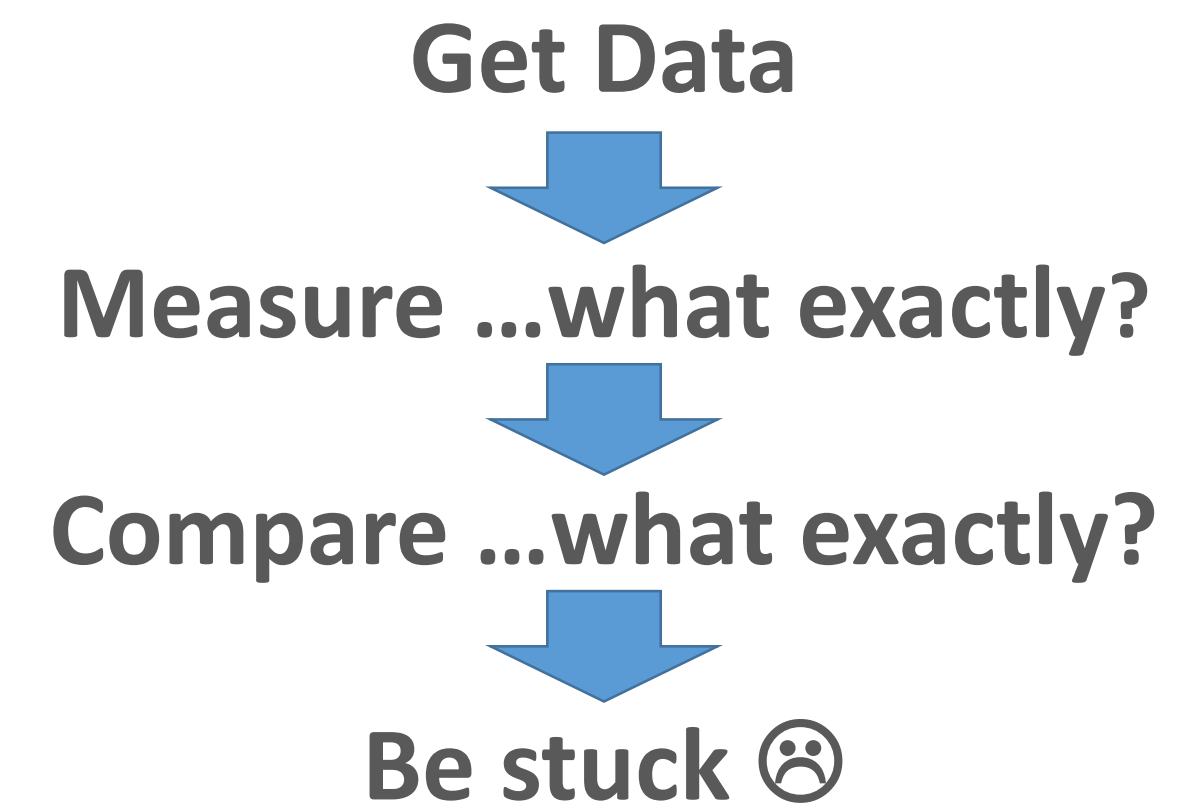


Source: Mauricio Rocha Martins, Norden lab, MPI CBG

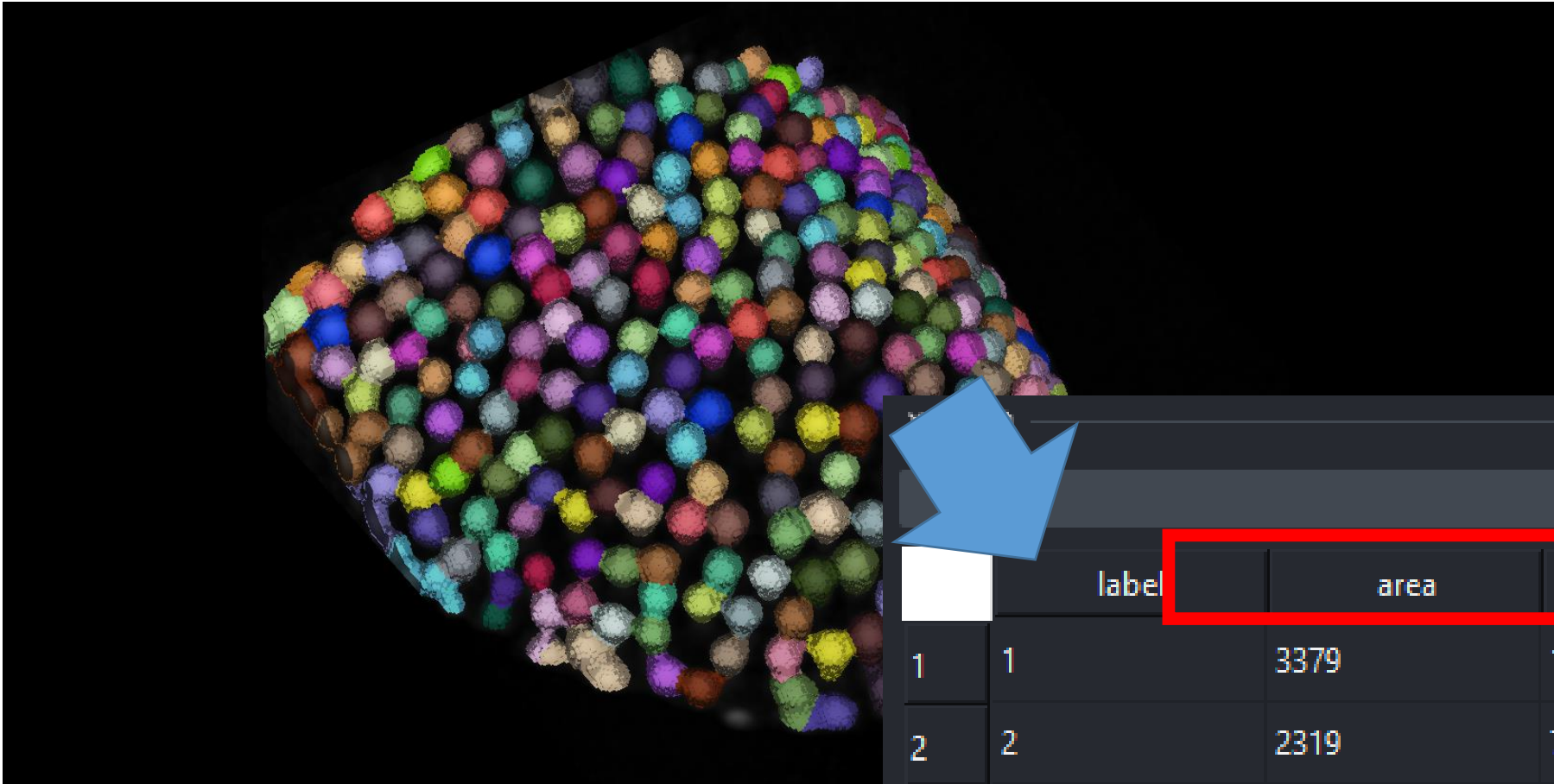
Example:

Developing zebrafish eye

Hypothesis: Cells develop differently depending on where they are



We can measure tons of features but still have no idea about what’s happening!



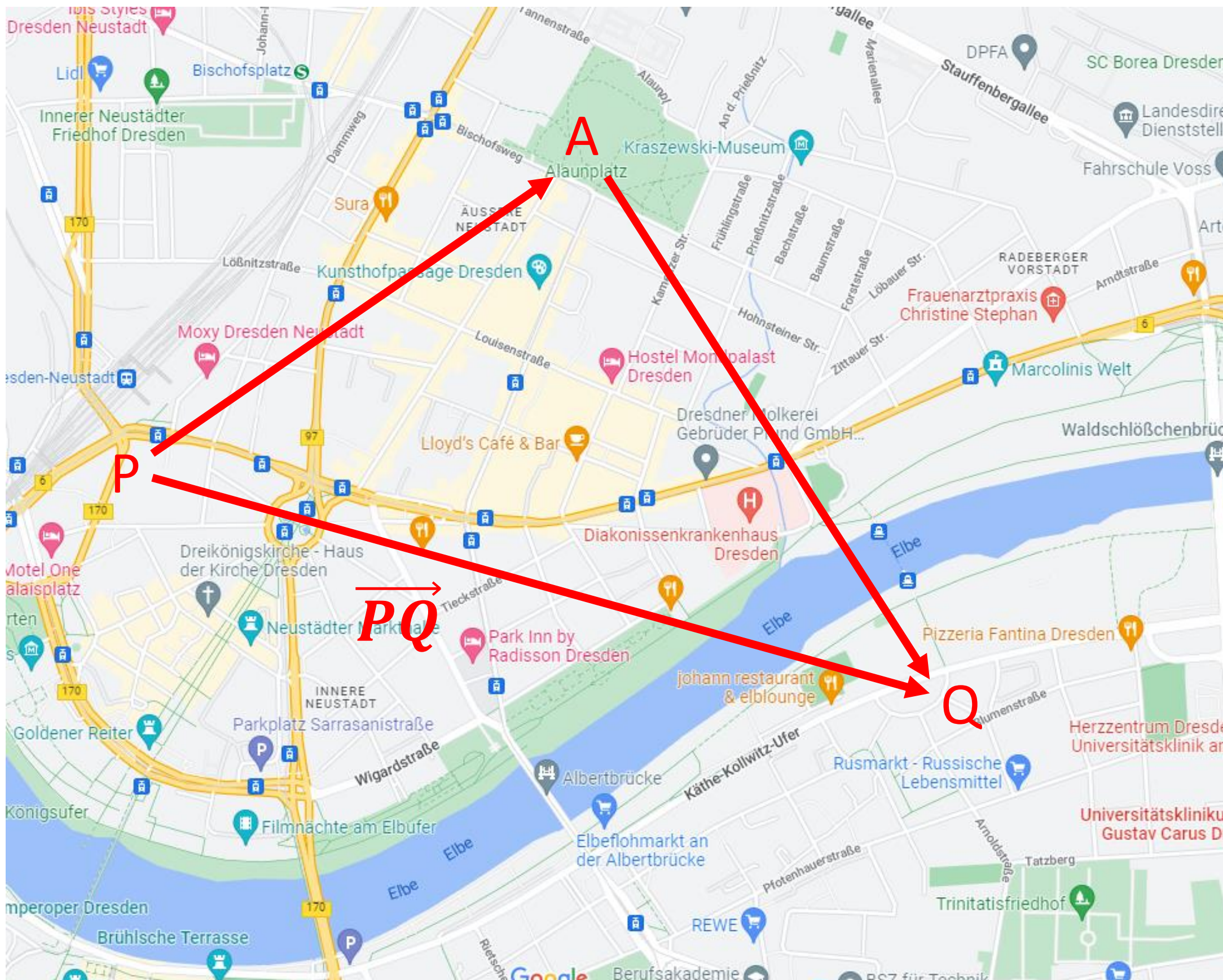
Which of these features reflects interesting biology?

Properties of Result of voronoi otsu labeling (desperant)

Copy to clipboard						Save as csv...						
	label	area	bbox_area	convex_area	equivalent_diamete	max_intensity	mean_intensity	min_intensity	solidity	extent	eret_diameter_ma	local_centroid-0
1	1	3379	13949	5120	18.61786412639...	613.0	345.6717963894...	259.0	0.6599609375	0....	37.3496987939662	15.77952056821...
2	2	2319	7448	3491	16.42230229224...	421.0	297.8434670116...	240.0	0....	0....	38.65229618017...	4....
3	3	2304	14415	4281	16.38681751812...	456.0	300.8298611111...	245.0	0....	0....	34.19064199455...	17.73828125
4	4	3278	13804	5139	18.43048549951...	467.0	316.1446003660...	249.0	0....	0....	34.84250278036...	15.52287980475...
5	5	1501	3315	1681	14.20563625190...	458.0	302.147235176549	236.0	0....	0....	17.97220075561...	6....
6	6	2341	6061	2714	16.47407088948...	594.0	355.4446817599...	261.0	0....	0....	30.67572330035...	16.54250320375...
7	7	1725	3584	1940	14.87979081163...	568.0	343.7866666666...	257.0	0....	0....	17.72004514666...	7.80463768115942
8	8	1502	3840	1753	14.20879025650...	431.0	290.0659121171...	235.0	0....	0....	18.57417562100...	8....
9	9	1602	4080	1894	14.51737058294...	475.0	297.8008739076...	241.0	0....	0....	18.70828693386...	8....
10	10	1395	3600	1624	13.86304166283...	424.0	304.8494623655...	247.0	0....	0.3875	17.60681686165...	7....
11	11	609	1100	697	10.51654029260...	323.0	274.2528735632...	241.0	0....	0....	13.45362404707...	3....
12	12	1686	3757	1894	14.76679738567...	460.0	303.8303677342...	240.0	0....	0....	17.97220075561...	9....
13	13	2157	5184	2531	16.03062694504...	576.0	339.990264255911	270.0	0....	0....	19.54482028569...	8....
14	14	863	2340	1032	11.81237949737...	327.0	272.4449594438...	237.0	0....	0....	16.0312195418814	6....

Most common and intuitive space: **Euclidian space**

Practical example: (local) 2D space



Characteristics of Euclidian space:

- Distance between **P** and **Q** $d(P,Q)$ is **symmetric**: $d(P,Q) = d(Q,P)$
- Distance between **P** and **Q** can be measured as the length (“norm”) of the vector \overrightarrow{PQ}
- Distances satisfy the triangle inequality:

$$d(P, Q) \leq d(P, A) + d(A, Q)$$

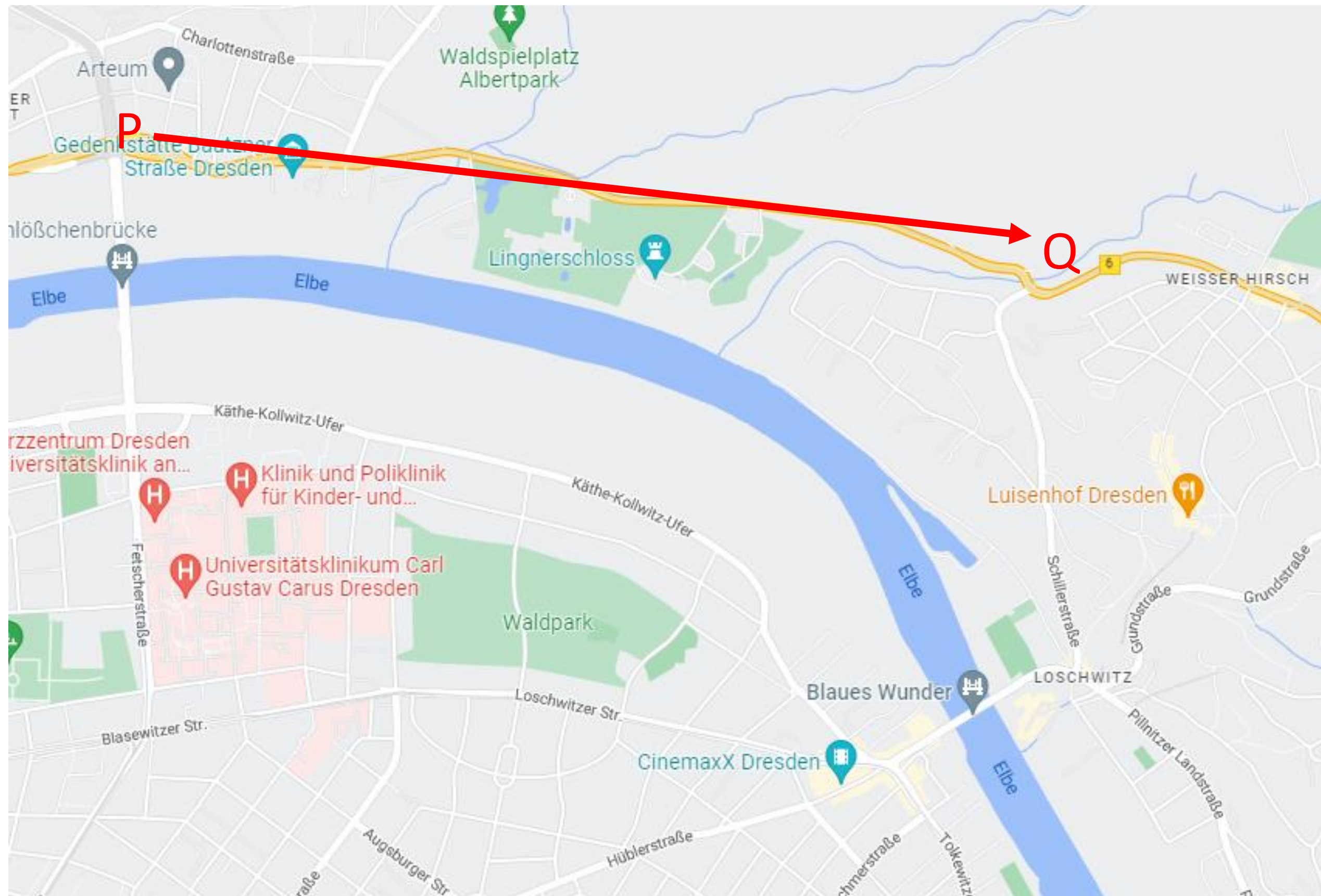
In other words: There is no shorter paths between two points other than a straight line

Maps.google.de

License: <https://about.google/brand-resource-center/products-and-services/geo-guidelines/#google-maps>

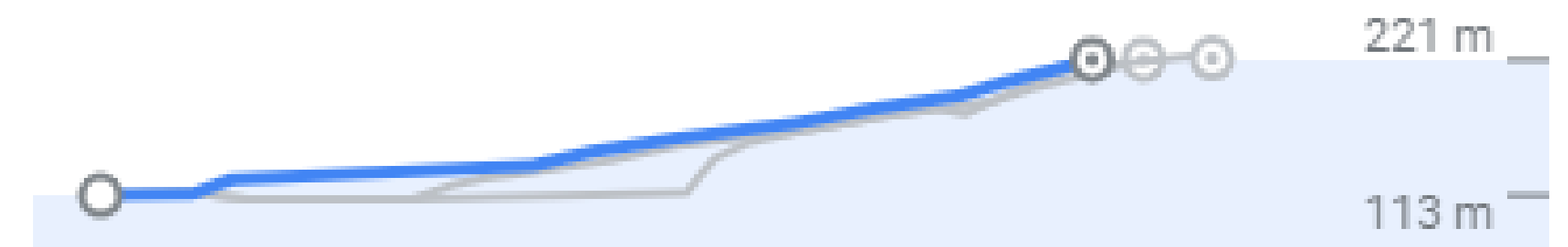
How could **non-Euclidian** spaces look like? → It's surprisingly intuitive!

- Non symmetric distances → $d(P, Q) \neq d(Q, P)$



Use travel time between P and Q as metric for distance

↑ 108 m · ↓ 0 m



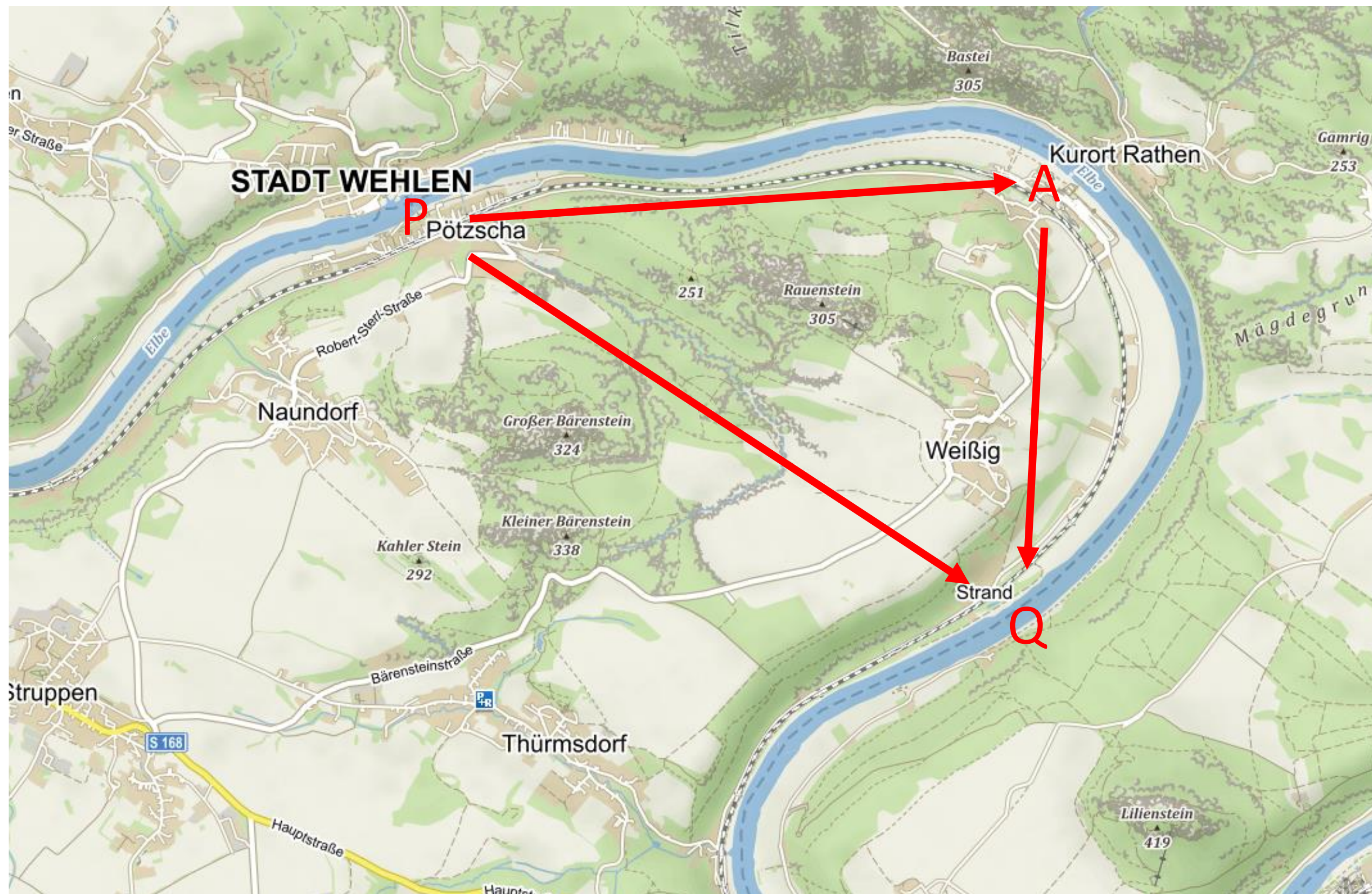
Travelling by bike/foot → it's *much* faster to get from Q to P than vice versa

→ $d(P, Q) > d(Q, P)$

Replacing distance between **P** and **Q** with time between **P** and **Q** makes Dresden non-Euclidian!

How could **non-Euclidian** spaces look like? → It's surprisingly intuitive!

- Breaking the triangle inequality → $d(P, Q) > d(P, A) + d(A, Q)$



Use travel time between P and Q as metric for distance

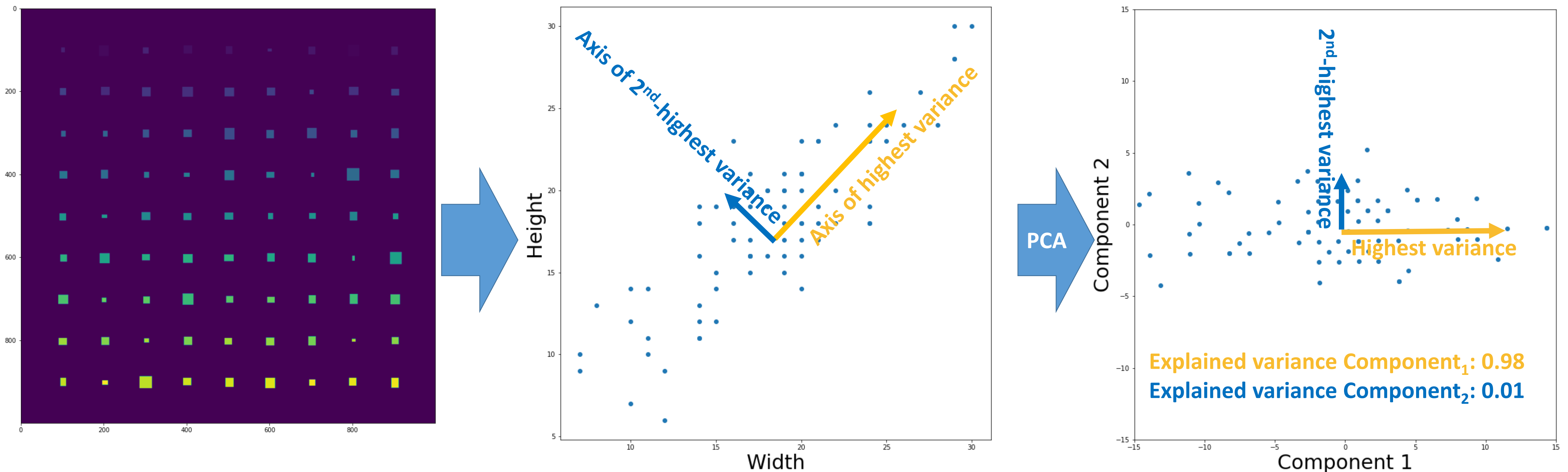
→ Travelling from Stadt Wehlen to Strand by bike is probably faster if you make a detour through Rathen

Mapy.cz

License: https://licence.mapy.cz/?doc=mapy_pu

Principal component analysis:

Decomposes data into linear combinations of features that explain the highest variance



Example: Squares of different size

→ PCA transforms width/height measurements into a coordinate system that explains existing variance better

$$\text{Component}_1 = a_1 * \text{width} + b_1 * \text{height}$$

$$\text{Component}_2 = a_2 * \text{width} + b_2 * \text{height}$$

- **Example:** Squares of different size

→ PCA transforms width/height measurements into a coordinate system that explains existing variance better

$$\begin{aligned} \text{Component}_1 &= a_1 * \text{width} + a_2 * \text{height} \\ \text{Component}_2 &= b_1 * \text{width} + b_2 * \text{height} \end{aligned}$$

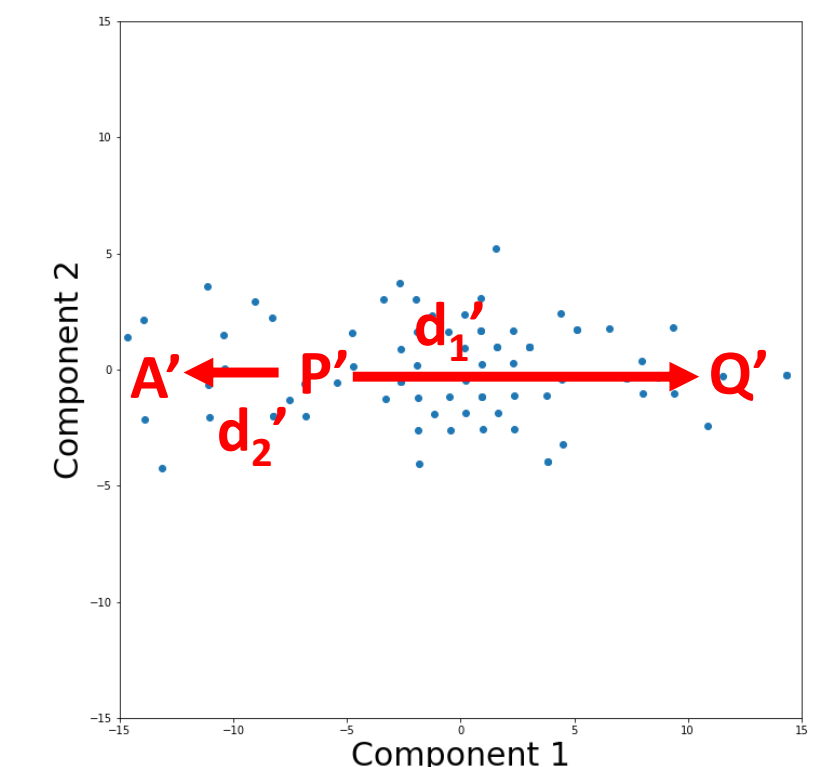
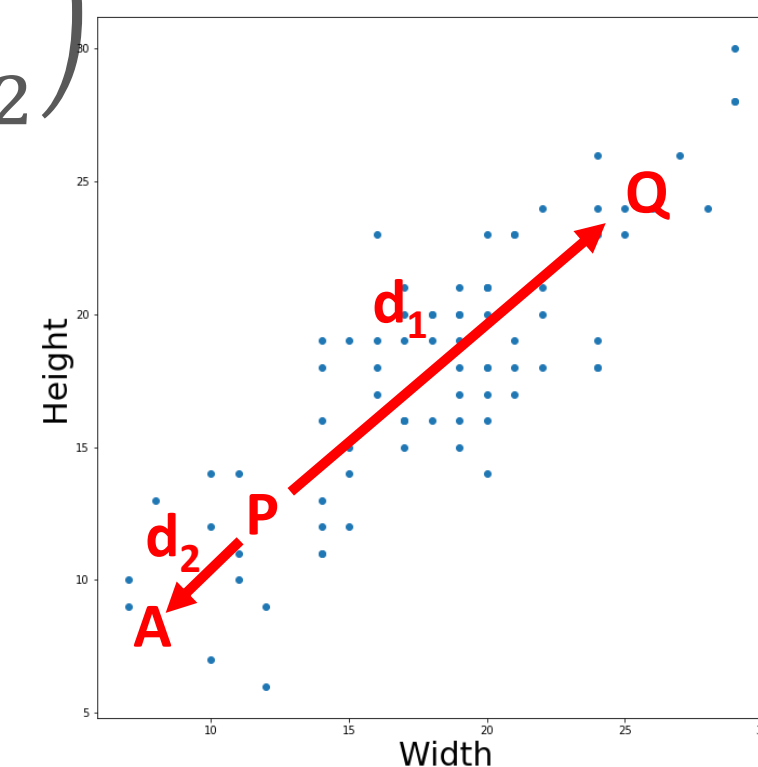
→ This is the result of a multiplication operation:

$$\underbrace{\begin{pmatrix} a_1 & a_2 \\ b_1 & b_2 \end{pmatrix}}_T * \begin{pmatrix} \text{width} \\ \text{height} \end{pmatrix} = \begin{pmatrix} \text{Component}_1 \\ \text{Component}_2 \end{pmatrix}$$

This is a linear operation!
Metrics remain meaningful

→ This works for any number of features!

$$T * \begin{pmatrix} \text{feature}_1 \\ \dots \\ \text{feature}_N \end{pmatrix} = \begin{pmatrix} \text{Component}_1 \\ \dots \\ \text{Component}_2 \end{pmatrix}$$



$$d_1 > d_2 \Rightarrow d_1' > d_2'$$

Import package

```
from sklearn.decomposition import PCA
```

Apply PCA

```
pca = PCA(n_components=2)  
pca.fit(data)
```

PCA

```
PCA(n_components=2)
```

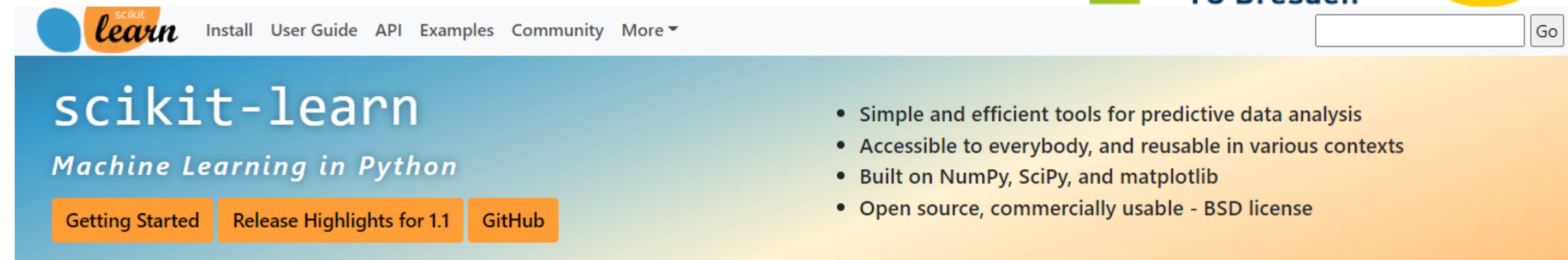
Transform data into transformed space

```
transformed_data = pca.transform(data)
```

Inspect explained variance

```
pca.explained_variance_ratio_
```

```
array([0.98773142, 0.01226858])
```



scikit-learn
Machine Learning in Python

- Simple and efficient tools for predictive data analysis
- Accessible to everybody, and reusable in various contexts
- Built on NumPy, SciPy, and matplotlib
- Open source, commercially usable - BSD license

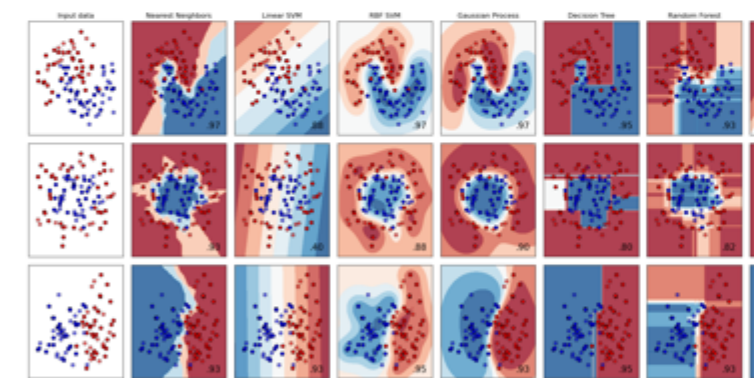
Getting Started Release Highlights for 1.1 GitHub

Classification

Identifying which category an object belongs to.

Applications: Spam detection, image recognition.

Algorithms: SVM, nearest neighbors, random forest, and more...



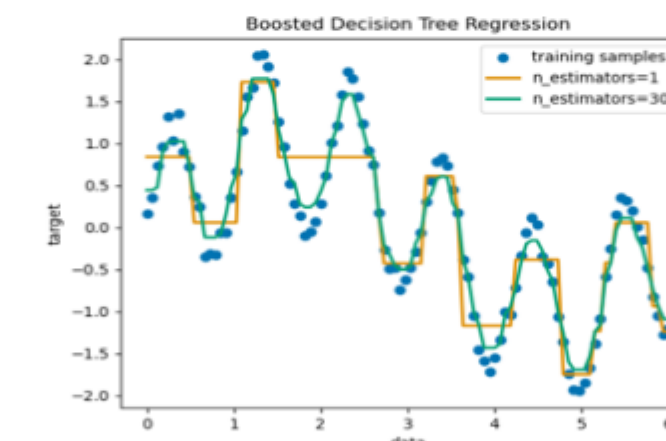
Examples

Regression

Predicting a continuous-valued attribute associated with an object.

Applications: Drug response, Stock prices.

Algorithms: SVR, nearest neighbors, random forest, and more...



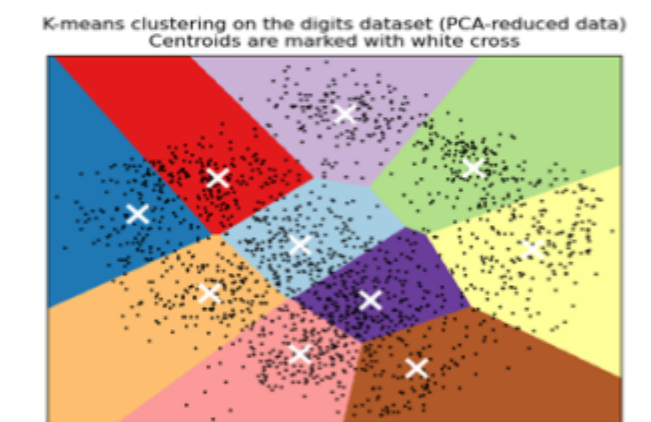
Examples

Clustering

Automatic grouping of similar objects into sets.

Applications: Customer segmentation, Grouping experiment outcomes

Algorithms: k-Means, spectral clustering, mean-shift, and more...



Examples

Dimensionality reduction

Reducing the number of random variables to consider.

Applications: Visualization, Increased efficiency

Model selection

Comparing, validating and choosing parameters and models.

Applications: Improved accuracy via parameter tun-

Preprocessing

Feature extraction and normalization.

Applications: Transforming input data such as text for use with machine learning algorithms.

More complex concept: **Manifolds**

From Wikipedia: “In mathematics, a manifold is a topological space that locally resembles Euclidean space near each point.”

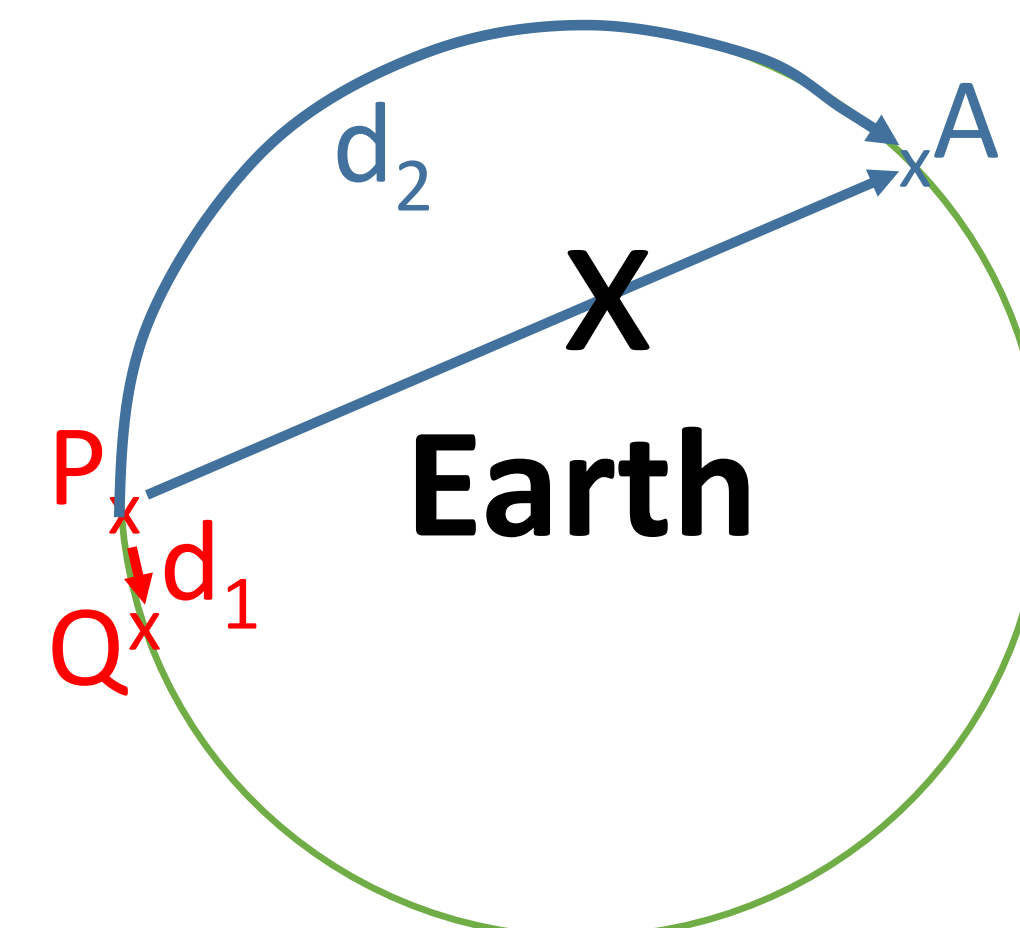


...Is this map Euclidian?

Yes

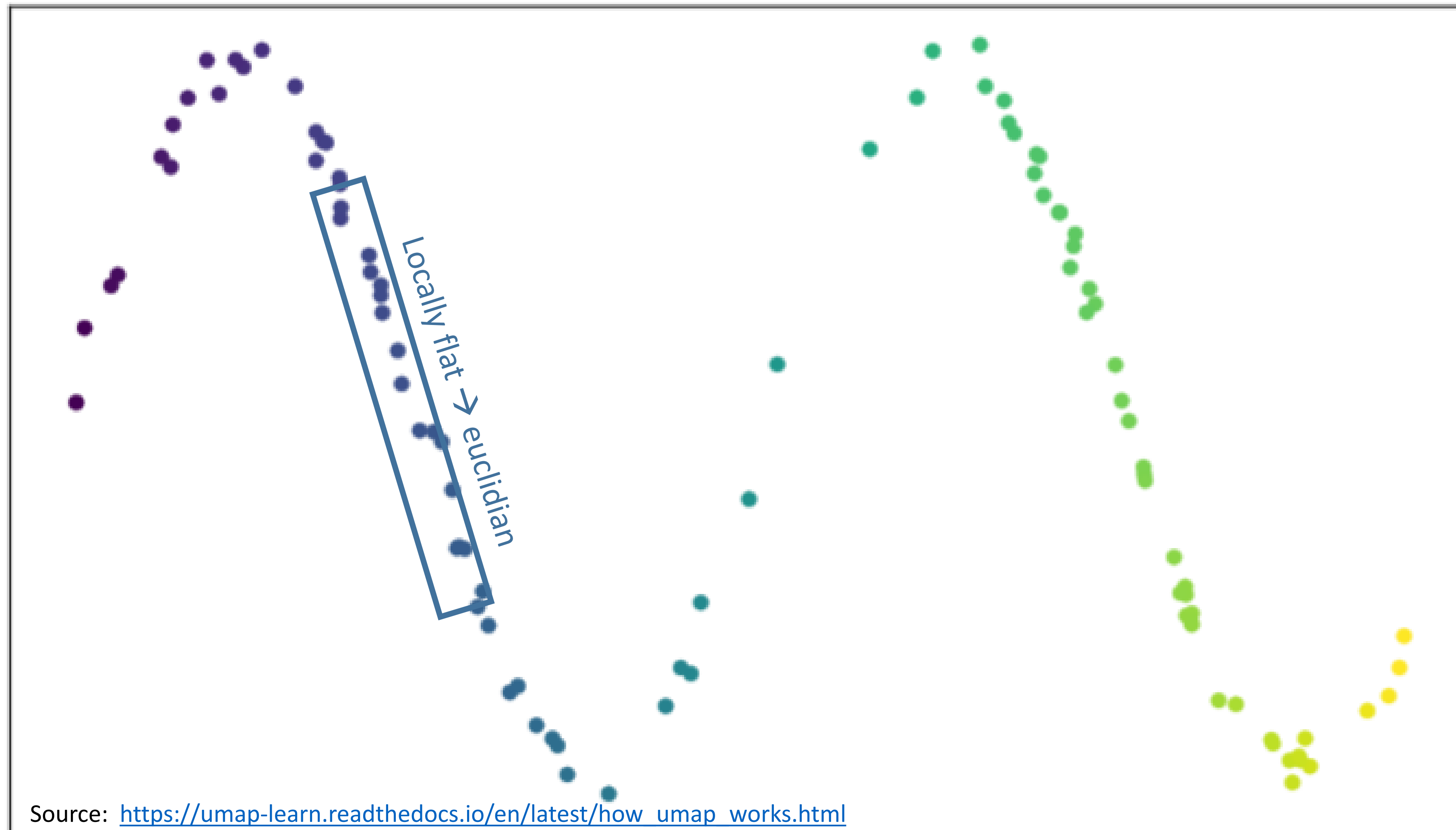
No

- It isn't! The two vectors \overrightarrow{PQ} and \overrightarrow{AB} have the same length, but the real distances (the *norm*) of both are completely different!
- Cropping a small piece from the map gives us a local Euclidian space, where the previous assumptions hold.



d_1 : Euclidian
 d_2 : Non-Euclidian

Initial situation: Our data suggests an underlying structure (“topology”) but we don’t have a model for it



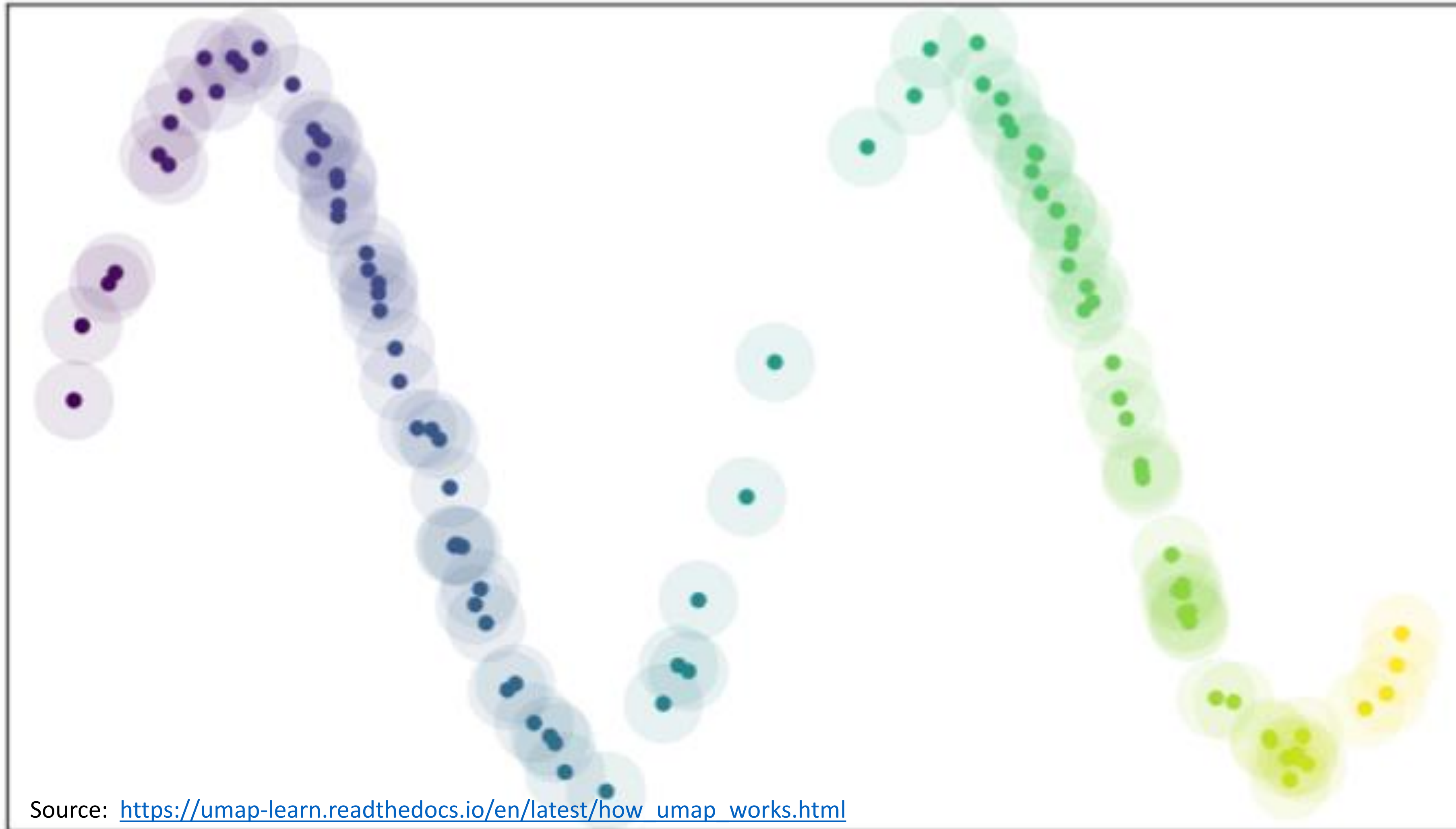
Idea:

Reconstruct underlying topology to identify a space that best explains differences in our data

Approach:

Identify neighboring points in data by setting a neighborhood radius

Initial situation: Our data suggests an underlying structure (“topology”) but we don’t have a model for it



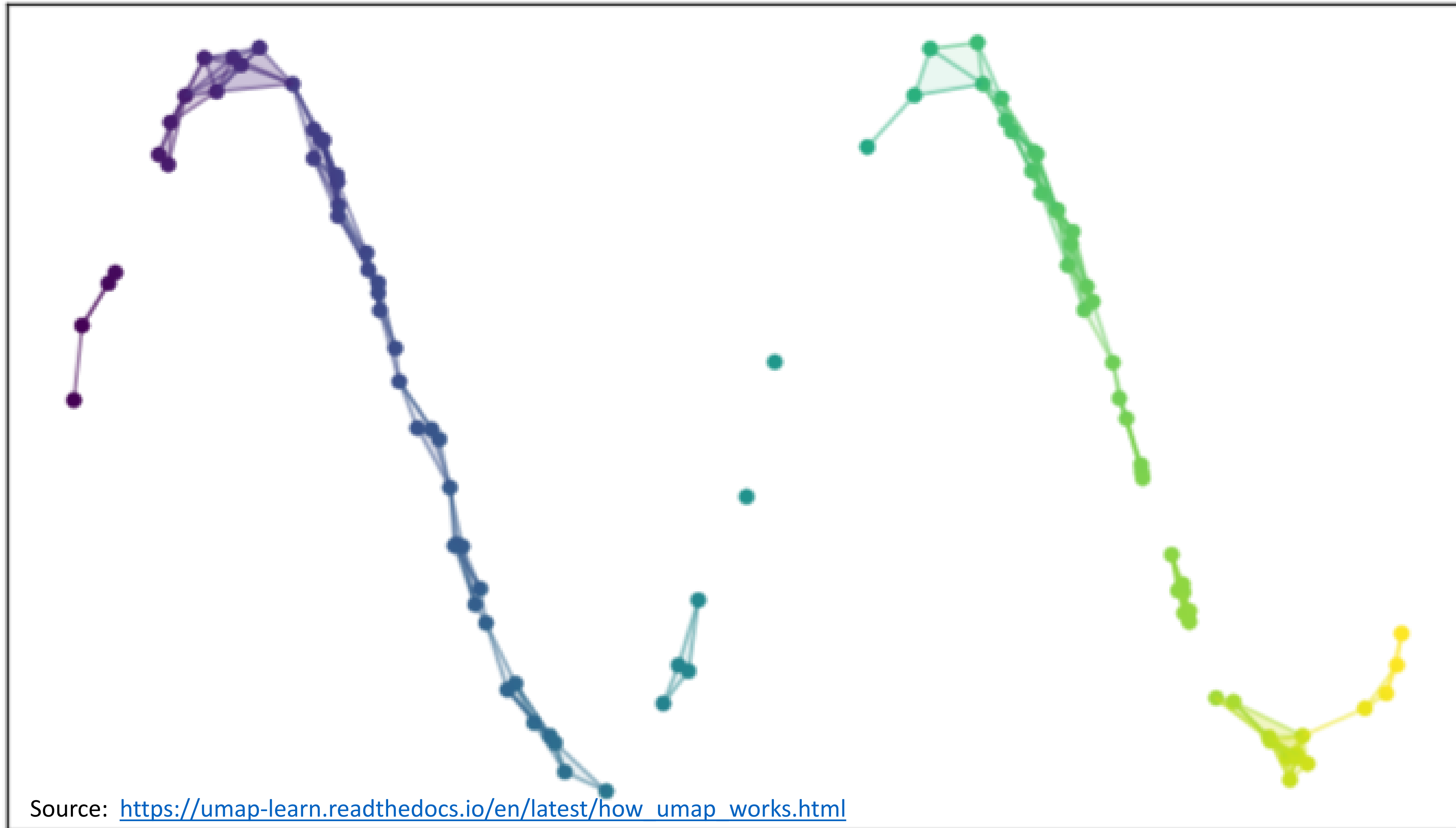
Idea:

Reconstruct underlying topology to identify a space that best explains differences in our data

Approach:

Identify neighboring points in data by setting a neighborhood radius

Initial situation: Our data suggests an underlying structure (“topology”) but we don’t have a model for it



Result:

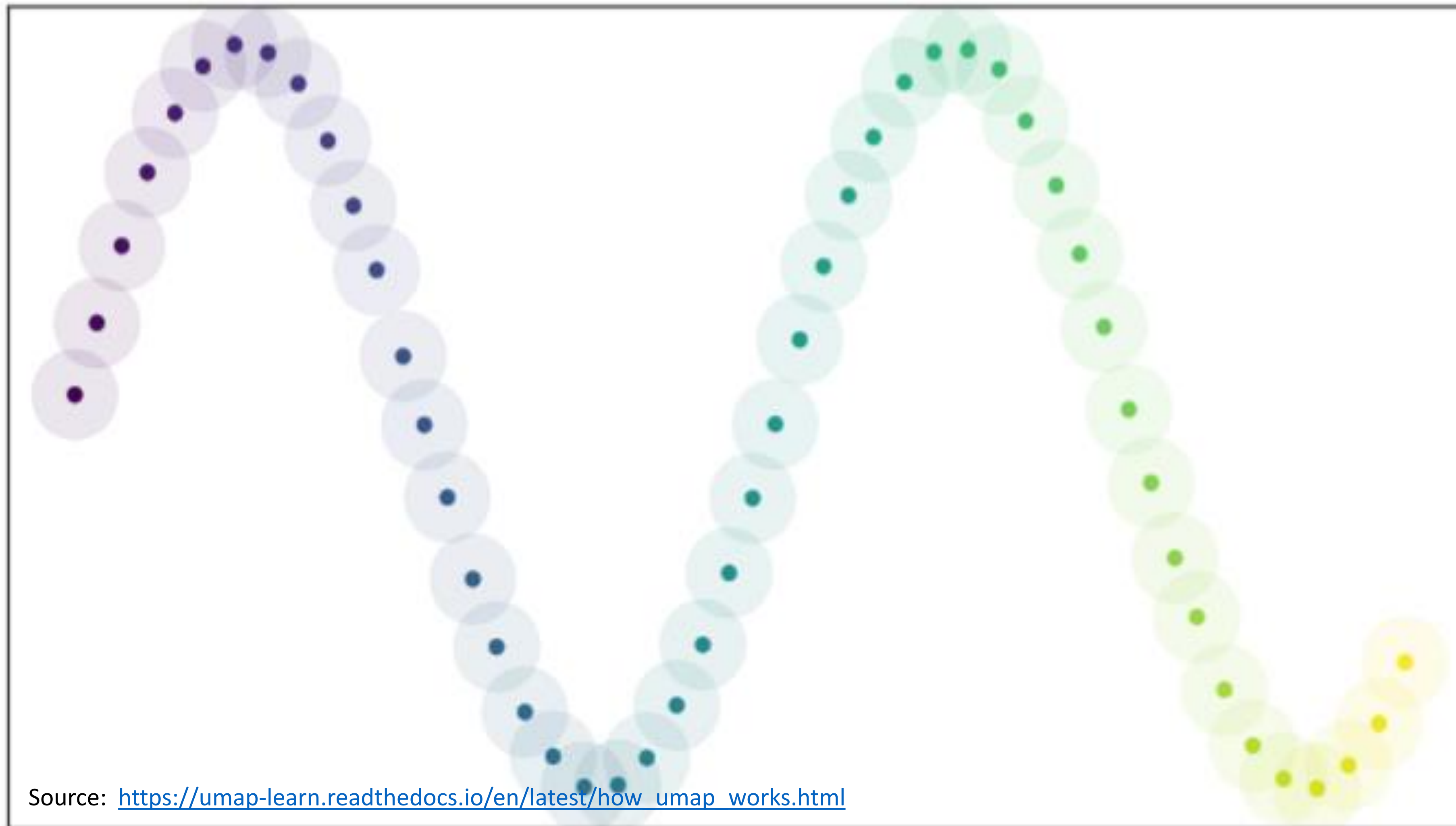
Neighborhood graph of close points

Problem:

The scarcity of the points leads to a disconnected neighborhood

→ Searching neighbors by radius may not be viable

Initial situation: Our data suggests an underlying structure (“topology”) but we don’t have a model for it



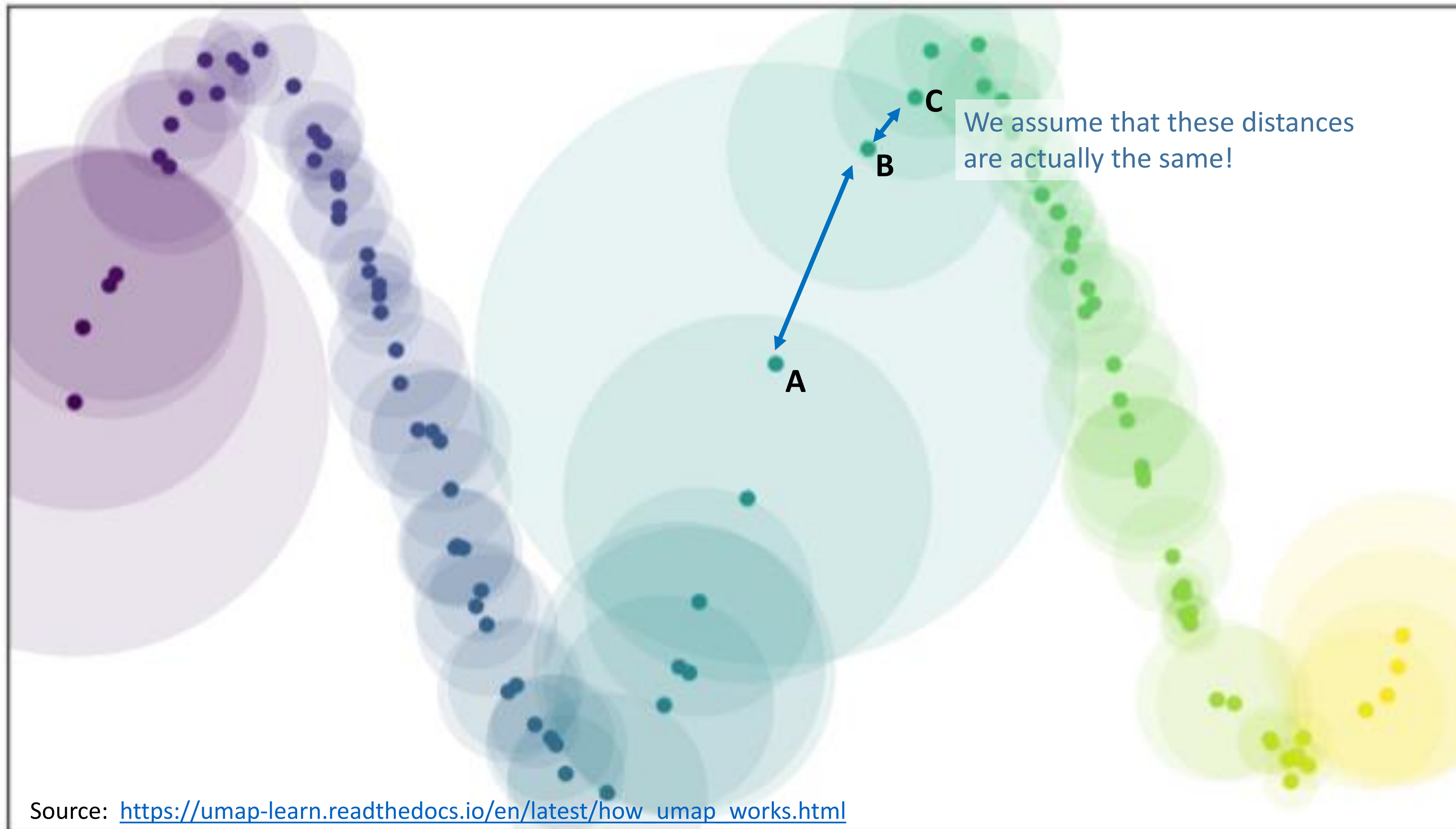
Ideally:

Data spread uniformly on the curve

→ Allows capturing the global structure through neighborhood

→ We typically don’t have this luxury

Initial situation: Our data suggests an underlying structure (“topology”) but we don’t have a model for it



Catch:

We *assume* that the data is actually uniform!

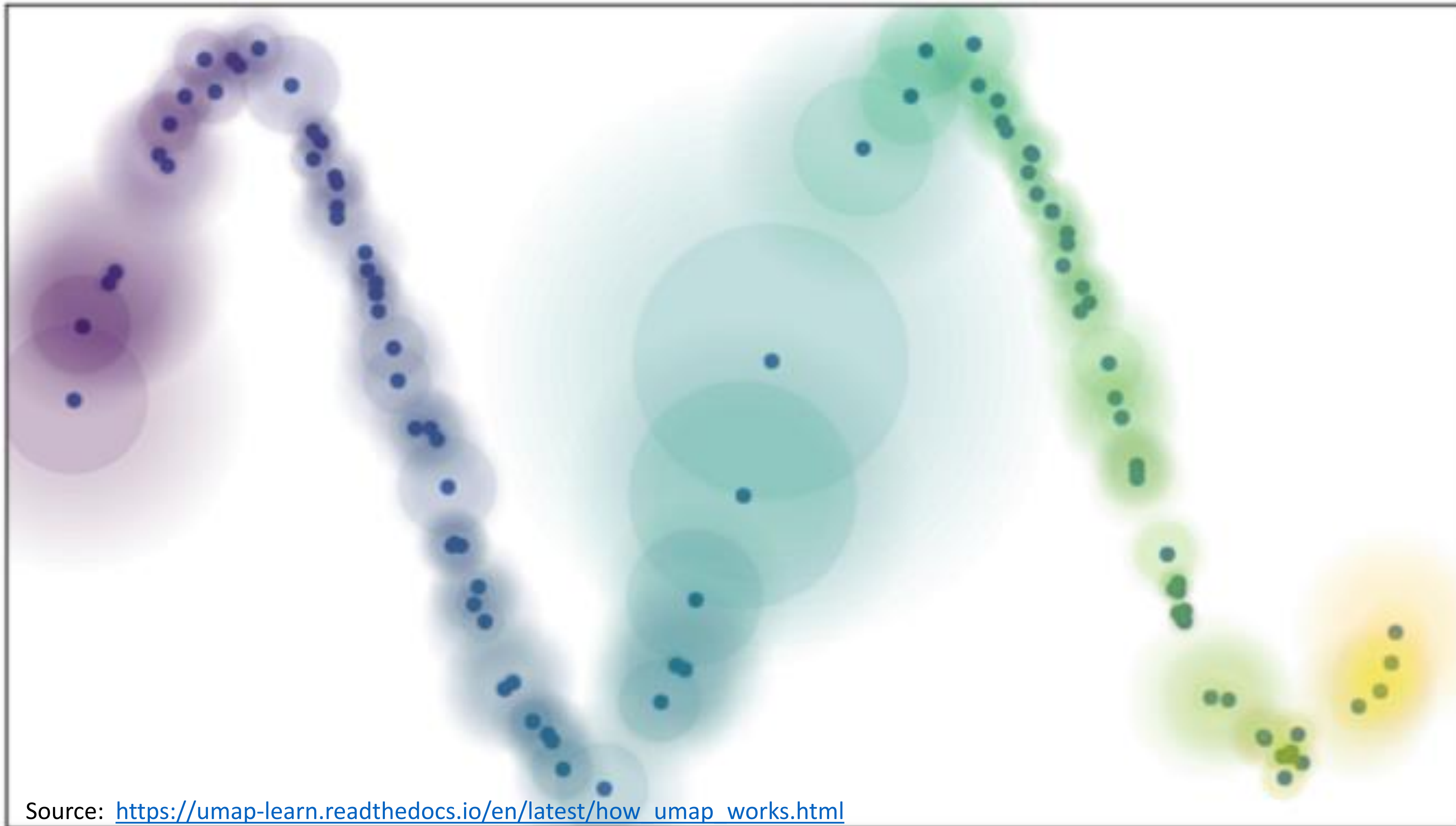
Each point now has its own distance metric assigned to it

→ $d(A, B)$ from A’s point of view: 1

→ $d(B, C)$ from B’s point of view: 1

This works well globally, but doesn’t capture local structure appropriately

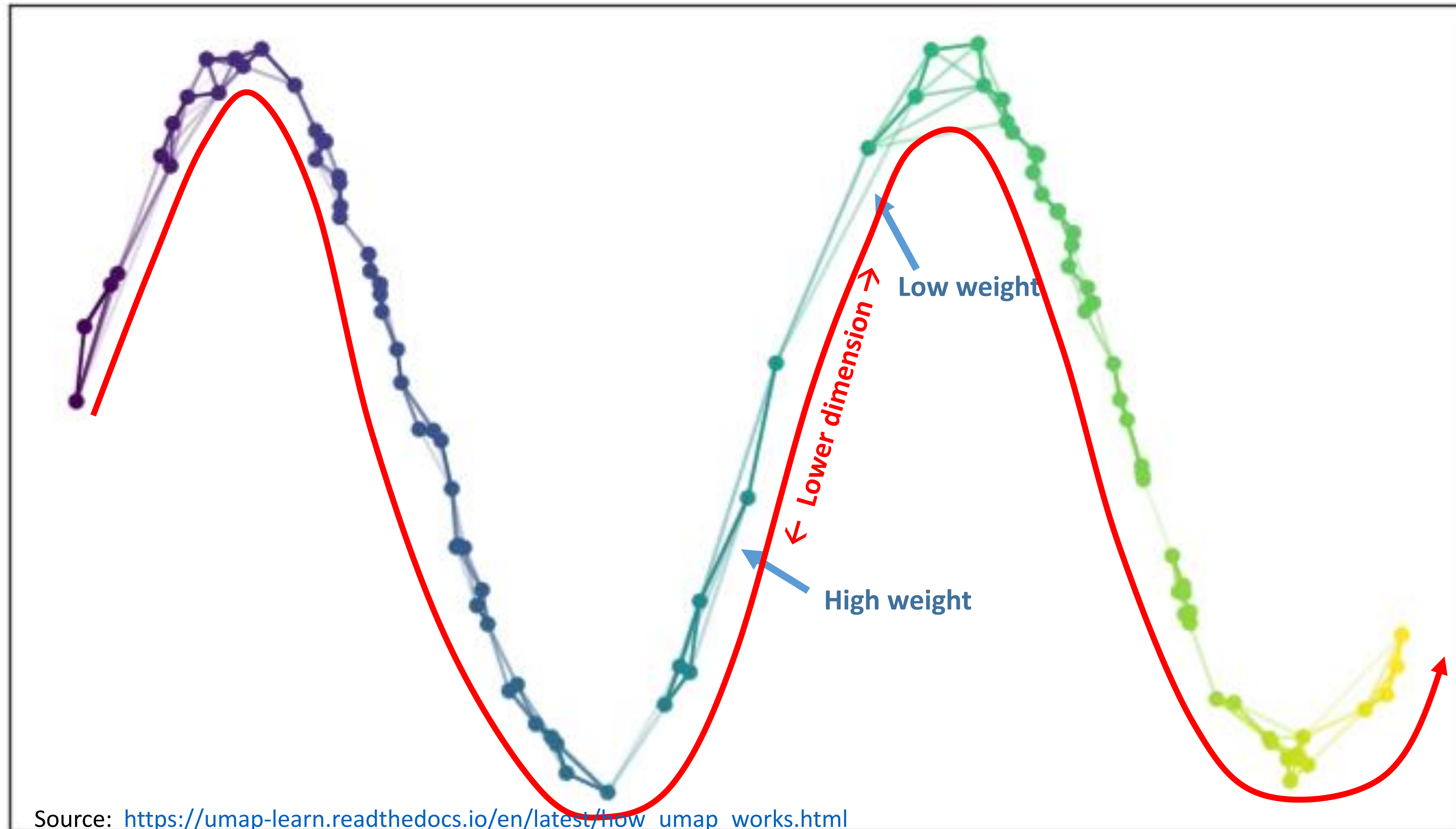
Initial situation: Our data suggests an underlying structure (“topology”) but we don’t have a model for it



Compromise:

- Demand that each point is connected to its closest neighbor
- Weigh connection to further neighbors with distance beyond nearest neighbor

Initial situation: Our data suggests an underlying structure (“topology”) but we don’t have a model for it



Result:

- Global neighborhood graph
- Local scarcity is reflected through edge weights

Last step:

Project this structure into a lower dimension so that overall topology is reflected

<https://umap-learn.readthedocs.io/en/latest/index.html>

Import package

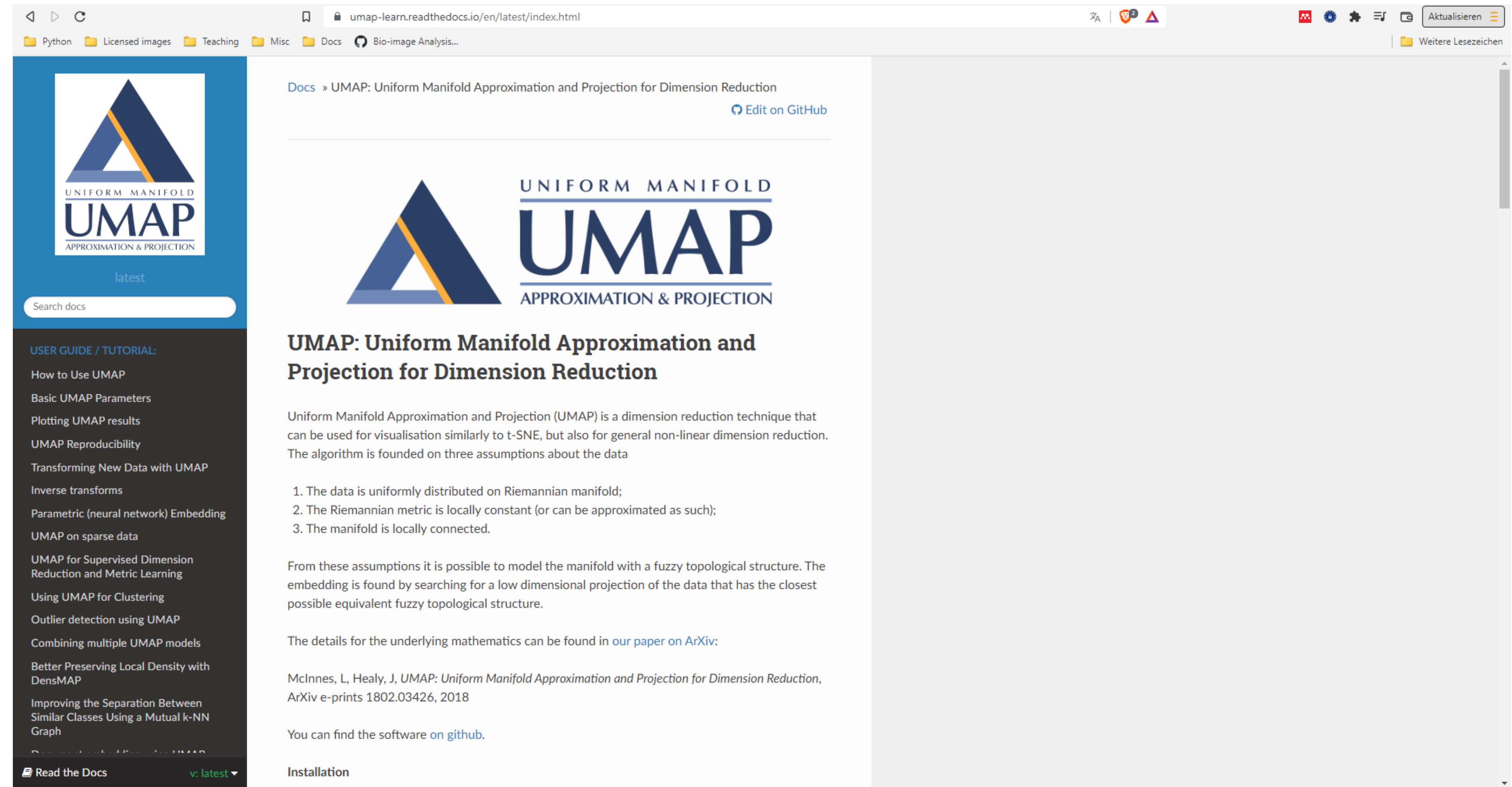
```
import umap
```

Create UMAP object

```
reducer = umap.UMAP()
```

Find projection

```
embedding = reducer.fit_transform(scaled_penguin_data)
embedding.shape
```



Docs » UMAP: Uniform Manifold Approximation and Projection for Dimension Reduction

[Edit on GitHub](#)

UMAP: Uniform Manifold Approximation and Projection for Dimension Reduction

Uniform Manifold Approximation and Projection (UMAP) is a dimension reduction technique that can be used for visualisation similarly to t-SNE, but also for general non-linear dimension reduction. The algorithm is founded on three assumptions about the data

1. The data is uniformly distributed on Riemannian manifold;
2. The Riemannian metric is locally constant (or can be approximated as such);
3. The manifold is locally connected.

From these assumptions it is possible to model the manifold with a fuzzy topological structure. The embedding is found by searching for a low dimensional projection of the data that has the closest possible equivalent fuzzy topological structure.

The details for the underlying mathematics can be found in [our paper on ArXiv](#):

McInnes, L., Healy, J, *UMAP: Uniform Manifold Approximation and Projection for Dimension Reduction*, ArXiv e-prints 1802.03426, 2018

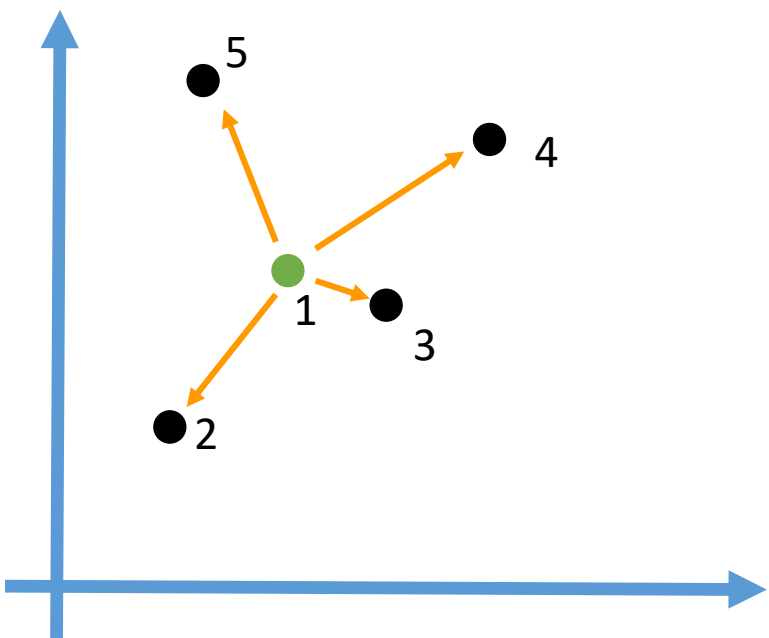
You can find the software [on github](#).

Installation

Takeaways:

- Dimensionality reduction projects data from high-dimensional space into fewer dimensions
- Algorithms try to preserve meaning in the data
- **PCA (principal component analysis):**
 - + Linear method: Metrics are preserved
 - Number of components required as input parameter
- **UMAP (uniform manifold approximation and projection):**
 - + Can capture quite arbitrary topologies
 - The embedded space is Euclidian, *but the transform is not-linear!*
 - Two groups A and B being close (similar) to each other in embedded space \neq A and B also similar in real space

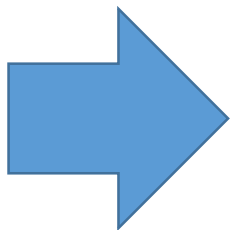
t-SNE: t-distributed Stochastic Neighbor Embedding



→ Construct neighborhood: Points 2-5 are neighbors of #1

→ Introduce similarity between neighbors and scale to [0,1]: $similarity(1,2) = \frac{1}{d(1,2)}$

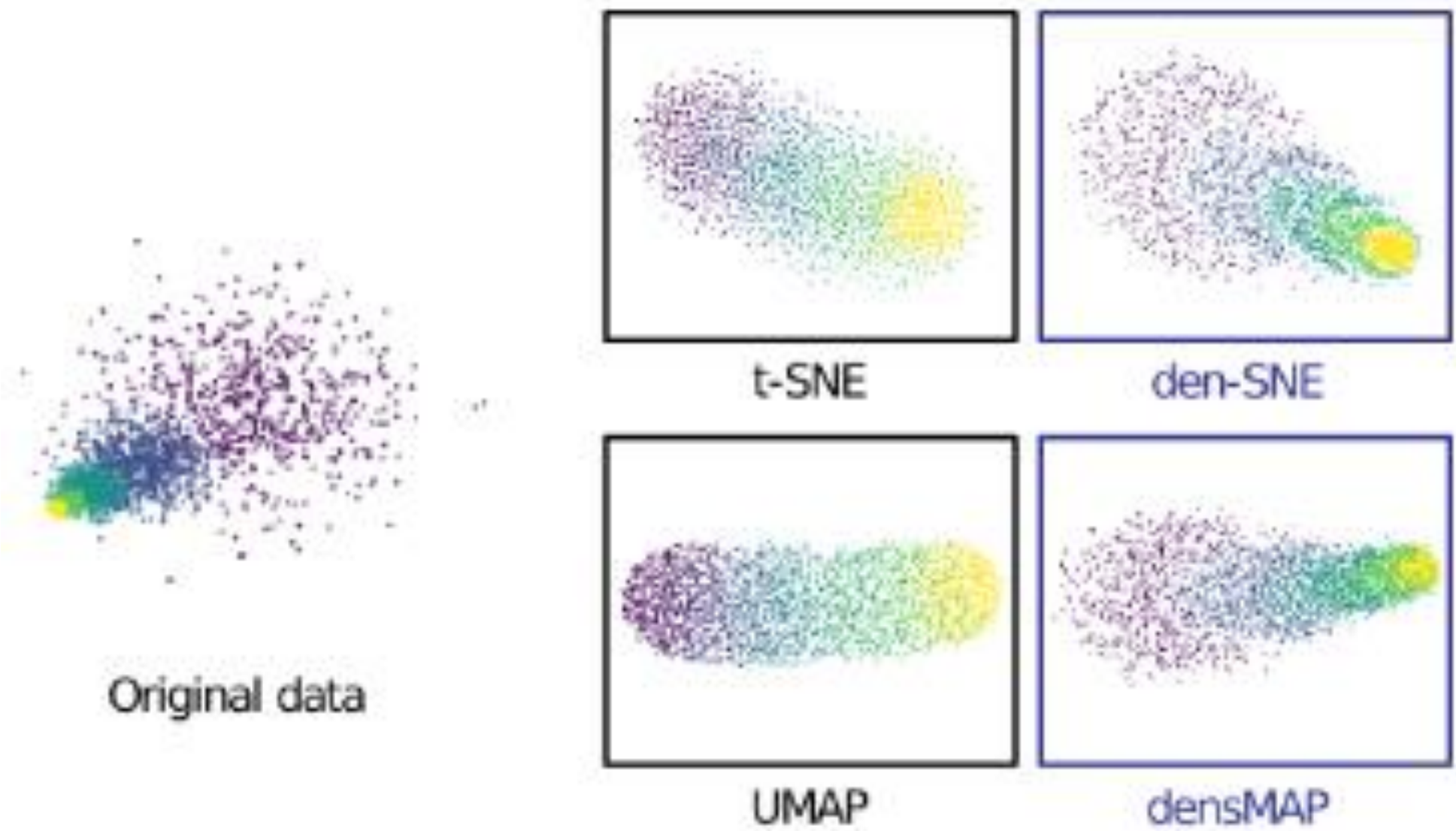
Neighbor	Similarity	Probability
2	0.4	0.19
3	0.8	0.39
4	0.45	0.22
5	0.38	0.19



New coordinates: (0.19, 0.39, 0.22, 0.19)
“stochastic neighborhood embedding”

→ find similar probability distribution in lower space

densMAP: Augmented UMAP so that point density is preserved



Resources:
<https://scikit-learn.org/stable/modules/generated/sklearn.manifold.TSNE.html>
<http://cb.csail.mit.edu/cb/densvis/> (License: <https://github.com/hhcho/densvis/blob/master/LICENSE>)