



Image thresholding

Johannes Müller

With material from
Robert Haase, BiaPoL, PoL TU Dresden
Marcelo Zoccoler, BiaPol, PoL, TU Dresden
Benoit Lombardot, Scientific Computing Facility, MPI CBG





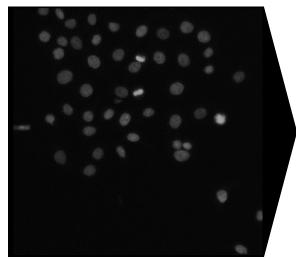
https://scikit-image.org/docs/stable/api/skimage.dresdeml

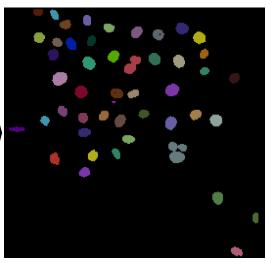
Aim:

Separate background from foreground

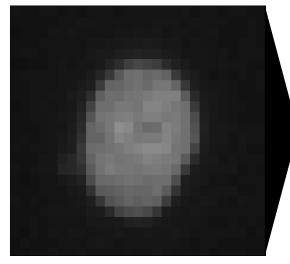
Vocabulary:

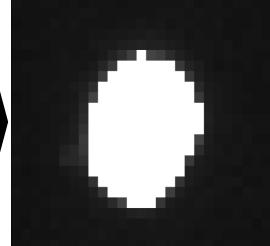
- Segmentation:
 - → Assigning a meaningful *label* to each pixel
 - → Segmentation is a *classification* problem
- Semantic segmentation:
 Differentiate pixels into multiple *classes* (e.g., membrane, nucleus, cytosol, etc.)
- Instance segmentation:
 Differentiate multiple occurrences of the same class into separate instances of this class (e.g., separate *label* for each cell in image)





Instance segmentation





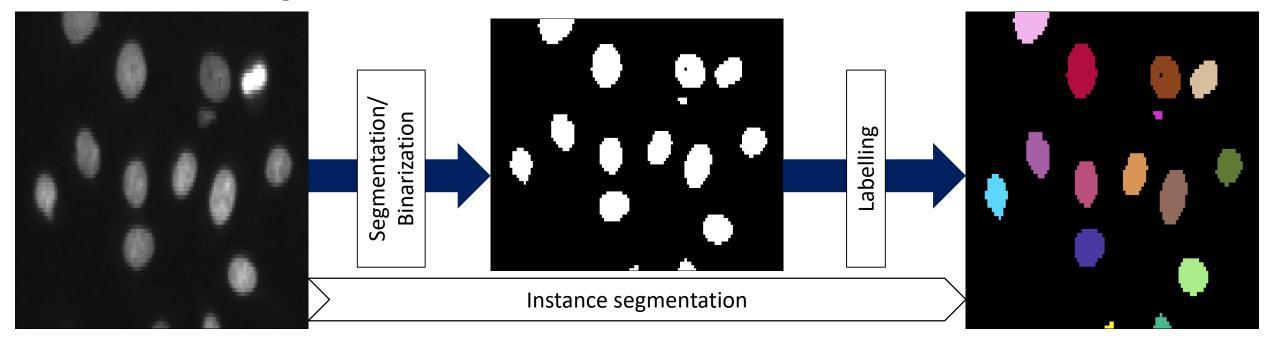
Semantic segmentation

Segmentation and labelling



Analyzing properties (features) of individual objects in images requires instance segmentation

- Methods
 - Thresholding + connected components labeling
 - Spot detection + seeded watershed
 - Edge detection based
 - Machine learning



Thresholding in Python



- Applying a threshold to an image requires to compare every pixel to the threshold value
- We can compare values in Python with:

In this case, "image" is a numpy array \rightarrow some operations are automatically applied to every pixel!

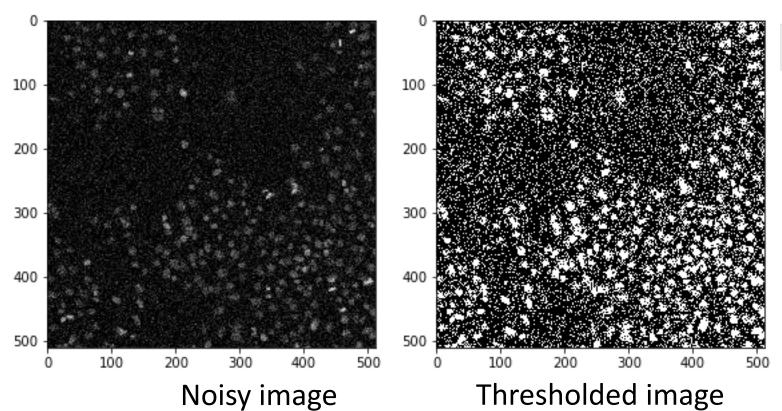
We can then simply store the output of this element-wise comparison in a new variable:

```
binary = image > threshold
```

Reminder: pre-processing!



- Before we can create masks, we need to pre-process images:
 - Noise removal
 - Background subtraction



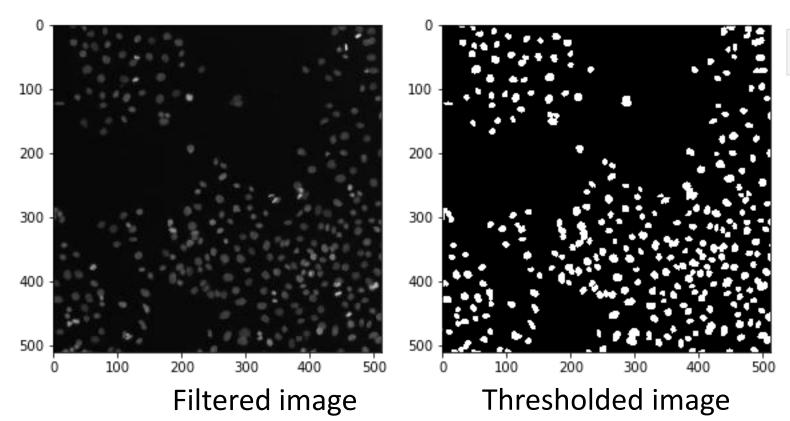
filtered = filters.median(image)

Image filtering *filters* relevant information for subsequent operations from the image!

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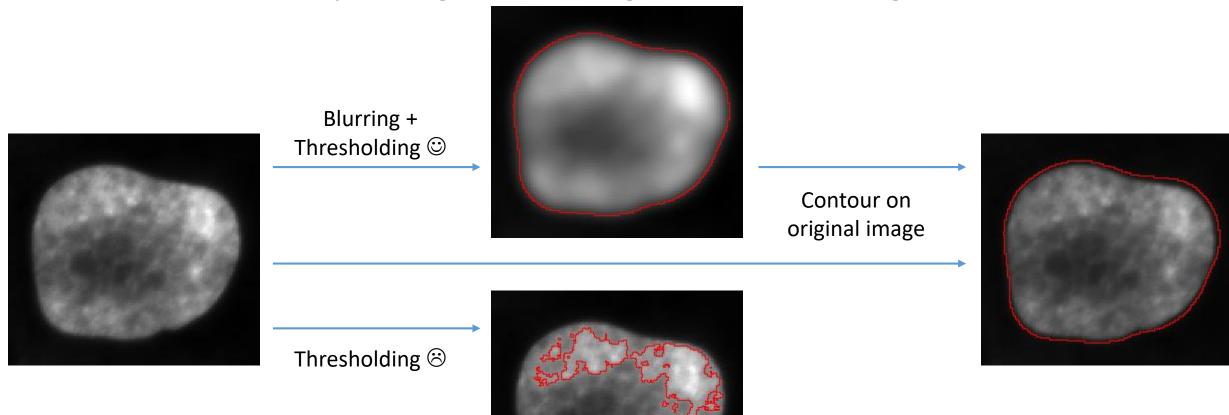
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Image filtering *filters* relevant information for subsequent operations from the image!

Low-pass filtering to improve thresholding results



- In case thresholding algorithms outline the wrong structure, <u>blurring in advance</u> may help.
- However: Do not continue processing the blurred image, continue with the original!



Threshold algorithms



• Otsu-thresholding (Otsu et Al. 1979): Find threshold so that the summed, weighted variance $Var_{w,sum}$ becomes minimal:

$$Var(I) = \frac{1}{n_I} \sum (I - mean(I))^2$$

$$Var_{w,sum} = \frac{n_A}{n_I} \cdot Var(A) + \frac{n_B}{n_I} \cdot Var(B)$$

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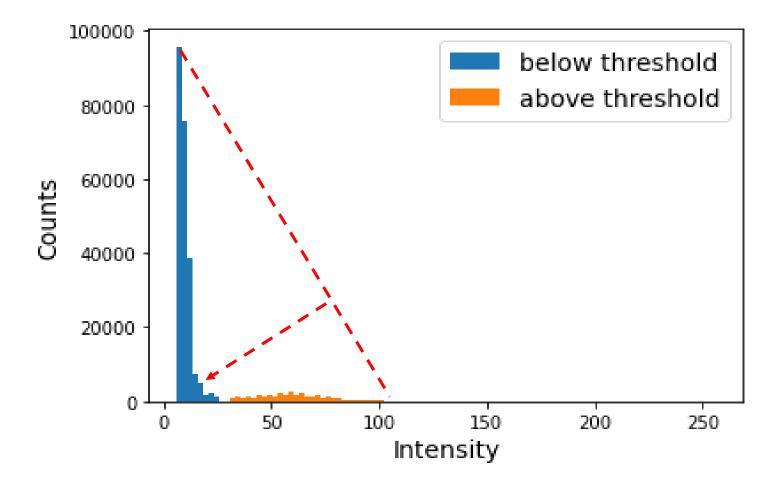
$$Var_{w,sum} = \frac{n_A}{n_I} \cdot Var_{w,sum} = \frac{n_A}{n_I} \cdot Var_{w,s$$

• Statistical thresholding: Pixels above statistical parameter of I belong to foreground. (Possibilities: Mean, Median, Quartiles, etc.)

Threshold algorithms



• **Triangle thresholding**: Draw a line between histogram point with max. counts and max. intensity and find point in histogram with maximal distance to this line (----)



Thresholding with scikit-image



```
threshold = filters.threshold_otsu(image)
```

• Otsu-thresholding (Otsu et Al. 1979): Find threshold so that the summed, weighted variance $Var_{w,sum}$ becomes minimal.

```
threshold = filters.threshold_mean(image)
```

• Statistical thresholding: Pixels above statistical

```
threshold = filters.threshold_triangle(image)
```

• Triangle thresholding: Draw a line between histogram point with max. counts and max. intensity and find point in histogram with maximal distance to this line.

Explore more threshold options in scikit-image with:

from skimage import filters

threshold = filters.threshold_

f	<pre>threshold_isodata</pre>	function	^
f	threshold_li	function	
f	<pre>threshold_local</pre>	function	
f	threshold_mean	function	
f	threshold_minimum	function	
f	<pre>threshold_multiotsu</pre>	function	
f	threshold _niblack	function	
f	threshold _otsu	function	
f	threshold _sauvola	function	
f	<pre>threshold_triangle</pre>	function	~



Cite the thresholding method of your choice properly

We segmented the cell nuclei in the images using the Otsu thresholding method (Otsu et Al. 1979) implemented in scikit-image (van der Walt et Al. 2014).

IEEE TRANSACTIONS ON SYSTEMS, MAN, AND CYBERNETICS, VOL. SMC-9, NO. 1, JANUARY 1979

A Threshold Selection Method from Gray-Level Histograms

NOBUYUKI OTSU

Abstract—A nonparametric and unsupervised method of automatic threshold selection for picture segmentation is presented. An optimal threshold is selected by the discriminant criterion, namely, so as to maximize the separability of the resultant classes in gray



Thresholding: Pitfalls



```
binary = image > a_good_threshold_value_of_my_choice
```

Inter-observer variability

Never use manual thresholding!

- Different observers come to different results when selecting a "good" threshold value
- > You may come to different results when selecting a threshold value repeatedly

```
binary = image > threshold
intensities = some_function_to_measure_intensities(binary, image)
```

Intra-observer variability

Avoid thresholding an image and afterwards measure intensities in the same image

You would measure the threshold you entered

```
binary_1 = image_1 > threshold_1(image_1)
binary_2 = image_2 > threshold_2(image_2)
```

Chose one threshold algorithm:

...and stick to it for the whole study. Using a new method for every image impairs reproducibility!

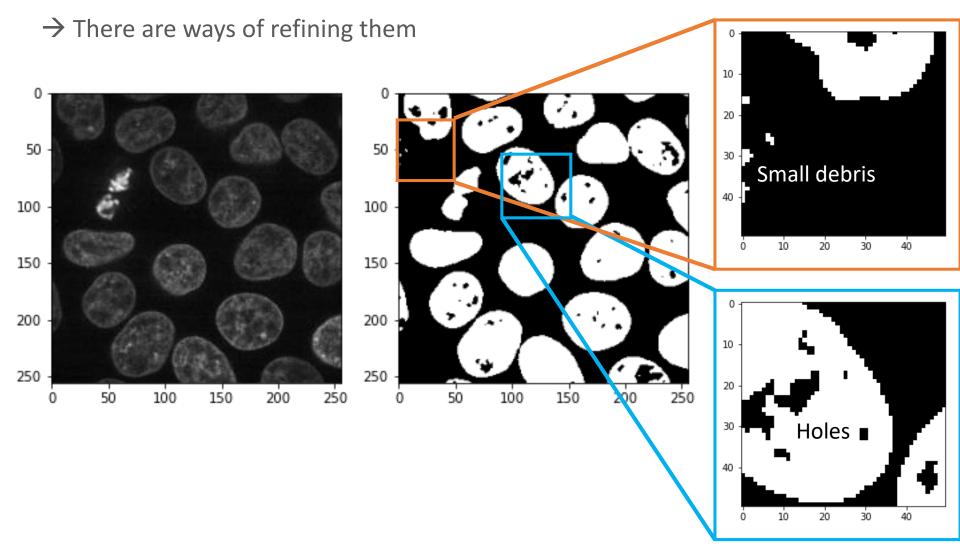
Do not over-engineer

There will be always images where thresholding fails – better report the errors!

Refining masks



Binary mask images may not be perfect immediately after thresholding.



Refining masks: Opening & Closing

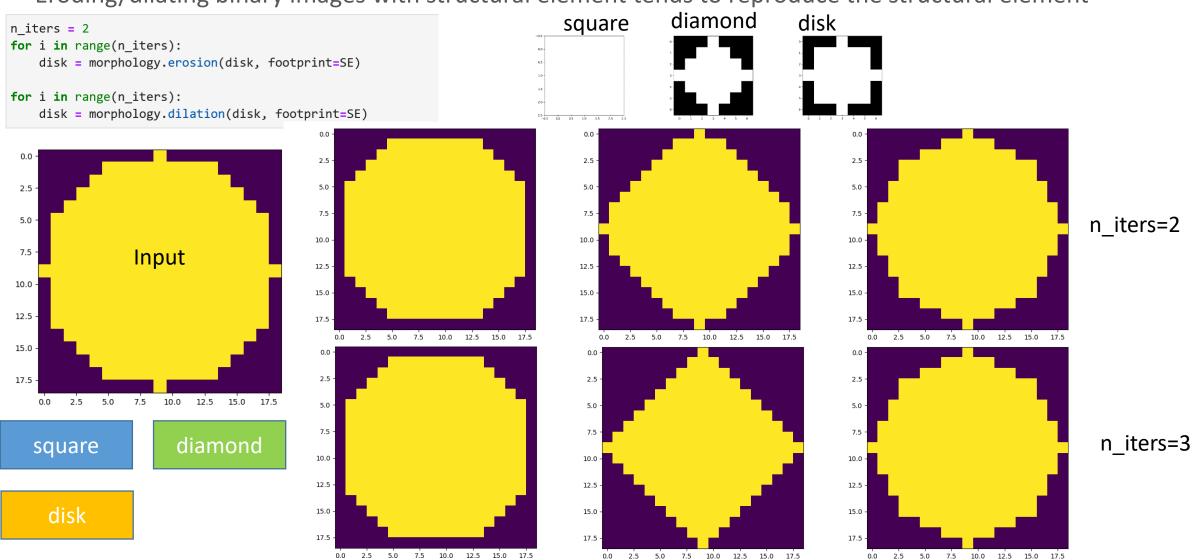




Pitfalls



Eroding/dilating binary images with structural element tends to reproduce the structural element



@jm_mightypirate

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