

Lecture 11:

Even More Curves

Last Time

- Basis Functions
- Quadratic Interpolation
- Cubics and Hermite Forms
- Cardinal Splines (Catmull-Rom)
- Bézier Curves
- Bézier Properties
- Geometric Constructions

Today

Review with **The Train**

- Why cardinals?
- Why Béziars?
- Why Arc-Length?

Going beyond **The Train**

- $C[2]$ curves
- Other Cardinals
- Subdivision Curves

The Train!

- "Optional" This Year
- Only for Advanced Points
- Good for showing curve ideas!
- 3D Demo (2014)
- 2D Demo (2019)

What's Good About Cardinals?

1. $C(1)$
2. Local
3. Interpolating

Sketching Cardinals (approximate $s = .5$)

A technical detail of $G(1)$

Is $s = 0$ still $C(1)$? (maybe demo)

How to draw a cardinal?

1. try a bunch of u values
2. convert to a Bézier (draw with the API)

How far does the cardinal go?

It goes outside of its points.

Convert to Bézier!

Arc Length?

- equal steps in u
- equal steps in distance

[demo]

How to implement Arc Length?

Hard to do analytically

Approximate *numerically* (make a table, solve, ...)

Fancier Cardinals: TCB curves

- tension
- continuity
- bias

Used by animators to get more control

What's Good About Béziers?

1. Interpolate end-points, stay in Convex Hull
2. Tangents at ends based on points
3. Good algorithms (geometric and algebraic)
4. Variation-Diminishing (limited wiggles), Affine Invariance
5. General (any degree)
6. And other properties...

What's not good about Béziers

1. Not **projective** invariant
2. Polynomial can't represent conics
 - no exact circles!
3. Hard to get better than $C(1)/G(1)$
4. Sometimes we want **interpolation**

Projective Invariance

Béziars are **affine invariant**

Projection (e.g., general homogeneous coords) requires division

Limited Shapes

Polynomials (like Béziers) can't represent some shapes

Exact circles (and other conic sections)

Rational Polynomial Curves

Represent a curve as the **ratio** of two polynomials

$$f(u) = \frac{\sum a_i u^i}{\sum b_i u^i}$$

Allows for projective invariance

Allows for more shapes (circles, conic sections, ...)

Very complicated - and usually not used in Computer Graphics

Used in mechanical design where exact shapes are required

Better than C(1)/G(1)

requires aligning multiple points

Note:

If we want a very smooth curve, we can make a high degree Bézier

What about Interpolation?

1. Cardinal Splines $C(1)$
2. High-Order Polynomials (smooth)
3. Natural Splines $C(2)$

[demo]

Natural Splines (Cubics)

- Models a "draftsmans spline" (stiff piece of metal)
- $C(2)$
- second derivative is zero at the ends
- requires solving a linear system to compute coefficients from points
- not local

B-Splines

This should be a big topic - but we will scratch the surface

A general way to think about piecewise polynomials.

A lot of history here at Wisconsin

Algebraic and Geometric Constructions

Incredibly General

Thinking in terms of chains of points...

We have points $\mathbf{p}_0, \mathbf{p}_1, \dots, \mathbf{p}_n$

Each point is the beginning of a segment (except at end)

- (d=1) line segments $[\mathbf{p}_0, \mathbf{p}_1], [\mathbf{p}_1, \mathbf{p}_2], \dots [\mathbf{p}_{n-1}, \mathbf{p}_n]$

Even with higher order...

We have points $\mathbf{p}_0, \mathbf{p}_1, \dots, \mathbf{p}_n$

Each point is the beginning of a segment (except at end)

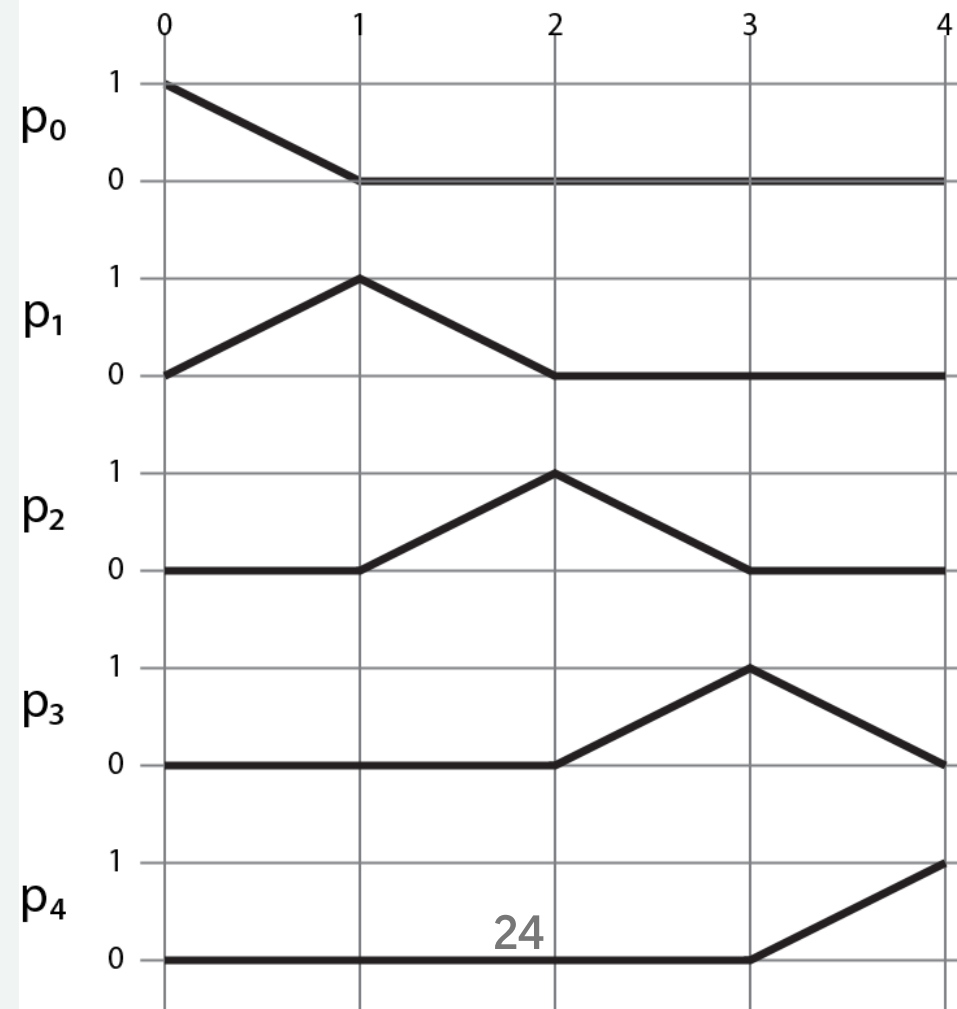
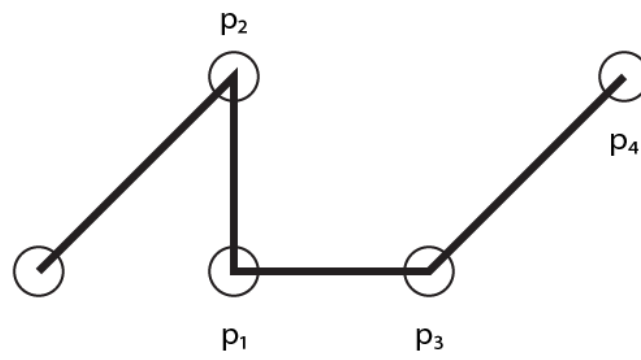
- (d=1) line segments $[\mathbf{p}_0, \mathbf{p}_1], [\mathbf{p}_1, \mathbf{p}_2], \dots [\mathbf{p}_{n-1}, \mathbf{p}_n]$
- (d=2) quadratics $[\mathbf{p}_0, \mathbf{p}_1, \mathbf{p}_2], [\mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3], \dots [\mathbf{p}_{n-2}, \mathbf{p}_{n-1}, \mathbf{p}_n]$

Each segment is $[\mathbf{p}_i, \mathbf{p}_{i+1}, \dots, \mathbf{p}_{i+d}]$

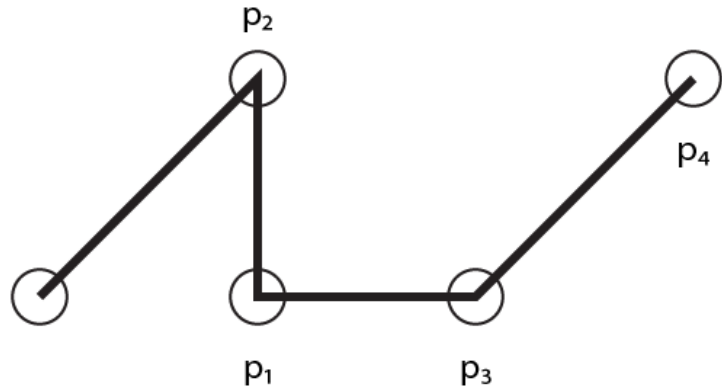
Thinking in terms of Basis Functions

Consider connecting line segments

$$\mathbf{f}(u) = (1 - u) \mathbf{p}_i + u \mathbf{p}_{i+1}$$

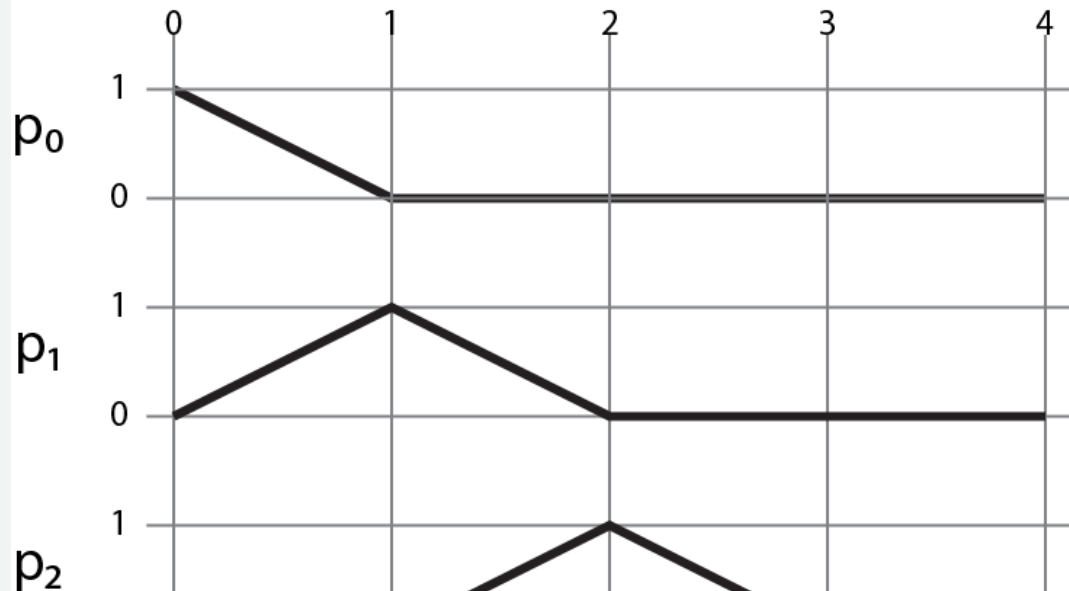


What about these Basis Functions?

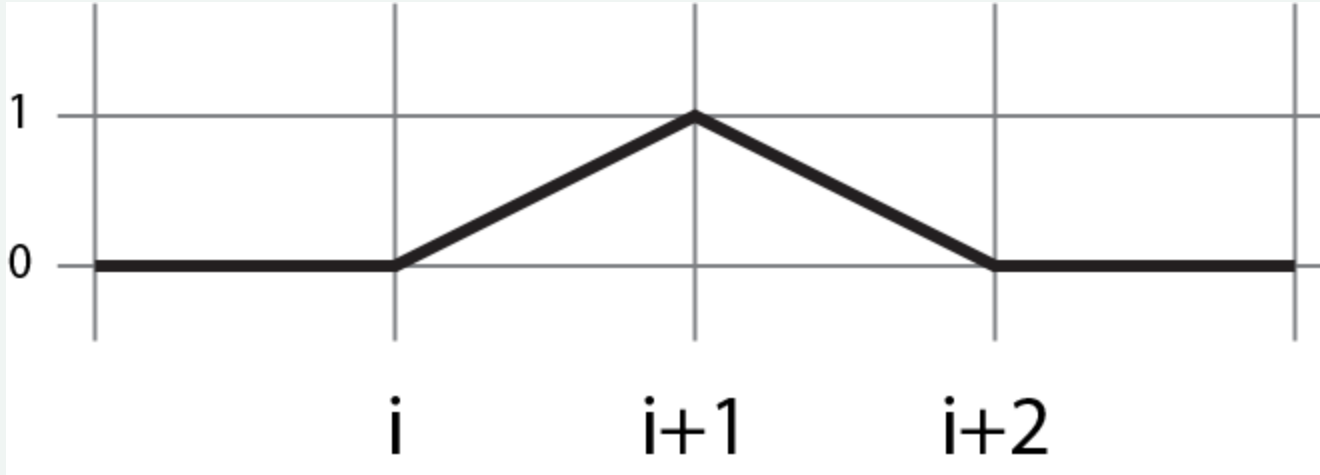


- They are piecewise polynomials
- They have the same continuity
- They repeat (except ends)

- If you have one, you'd have them all



The Linear Basis Functions



$$b_i(t) = \begin{cases} \text{if } t < i \text{ then } 0 \\ \text{elif } t < i + 1 \text{ then } t - i \\ \text{elif } t < i + 2 \text{ then } i + 2 - t \\ \text{else } 0 \end{cases}$$

On a chain of points? (lines)

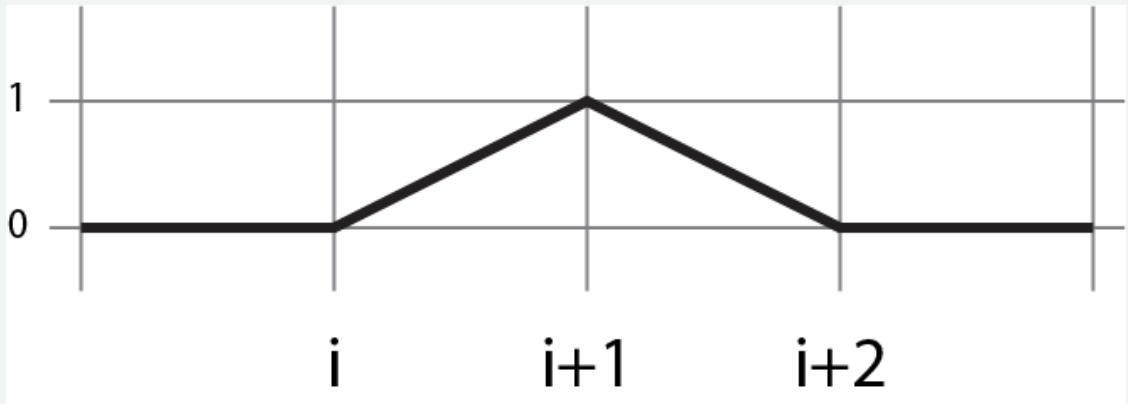
At any parameter value, 2 control points are active

One in each "phase"

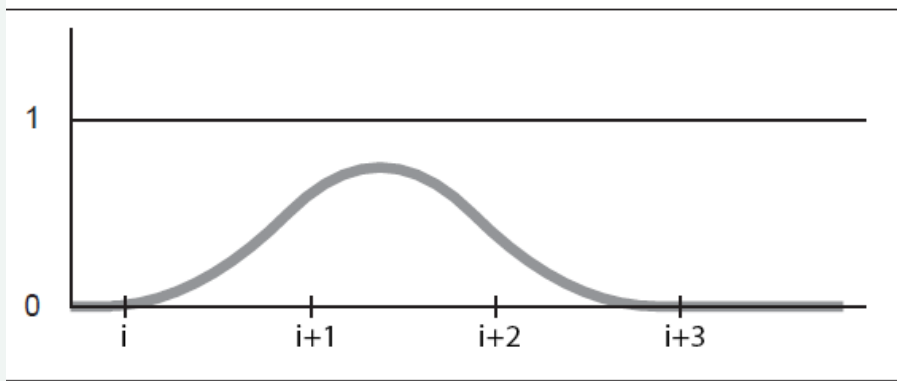
Higher-degree basis functions

Only linear interpolates (like Beziers)

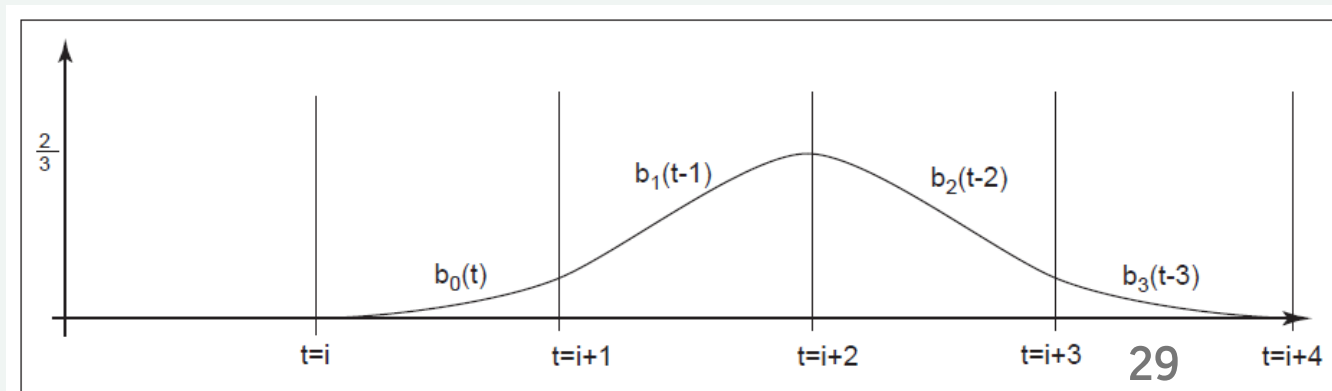
Degree d has $d + 1$ segments, meet with $C(d - 1)$ continuity



Linear



Quadratic



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Cubic

The Simplest B-Splines

- Uniform
- Low order Polynomial ($d=2$ or 3 in graphics)
- Chains of points are chains of polynomials

Cubic B-Splines

- 4 points influence a curve segment
- neighboring segments share 3 points
- each segment is a cubic polynomial

[demo]

Why B-Splines?

- Curves of any degree d
- Locality: each control point influences $d + 1$ segments
- Continuity: curve is $C(d - 1)$
- Stays with the Convex Hull
- Symmetric
- Affine Invariant
- Variation Diminishing
- **not interpolating** (except $d=1$)

Geometric Intuition for B-Splines

or

A More Interesting Subdivision Curve

A Geometric Approach: Chakin Corner Cutting

Subdivide each line segment:

- Mark $1/4$ and $3/4$
- Cut it there

Each iteration gets smoother

- In the limit it will be smooth

Notice:

- does not interpolate its "control points"

What to learn from that?

- Practical? (might need a lot of iterations)
- Subdivision: in the limit, it is a piecewise quadratic
- It converges to a B-Spline
- Approximating curve: it does not interpolate its (initial) points

What to do with these?

Use cubic B-Splines if you want $C(2)$ curves

Even though they do not interpolate, they "behave nicely"

Look up the blending functions if you need them

Train Demo

See how nice B-Splines Are?

The Train Assignment

Are Curves different in 3d?

Curves are not Surfaces!

Dimensions are independent (just 3 numbers per vector)

Equations are the same

Tangent vector - normal plane (perpendicular to vector)

Curve Summary

- Use **parametric** curves
- Use **piecewise** representations, connect with **continuity**
- Use **polynomial** segments, usually **quadratics** or **cubics**
- Use **Hemite** or **Cardinal** interpolation (if you need interpolation)
- Use **Bézier** curves for good control (and API compatibility)
- Use **B-Splines** to get very smooth curves

Get ready for 3D!