

# **Lecture 25**

## **Shape**

## **Deformation**

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# Last Time: Graphics Performance

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- Early Z
- Deferred Shading
- Using Environment Maps for Complex Lighting
- Texture Use and Re-Use (Atlases)
- Avoiding State Changes (big objects)
  - Matrix Palettes

# Animation by Transformation

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Translate or rotate...

## 1. Change each vertex

- compute N vertices
- transmit N vertices between CPU and GPU

## 2. Change a transformation

- change 1 number (maybe 12 for a matrix)
- send 1 matrix to GPU

Downside: limited things we can do (with simple transformations)

# More Generally...

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Make one shape

Deform it to other shapes

- easier to animate
- easier to model/control

# Animation by Deformation

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## Advantages:

1. performance (don't need to compute every vertex)
  - no need to send mesh to graphics hardware each frame
  - per-vertex computation with limited data
2. authoring (artists don't have to sculpt every vertex)
  - design base shape and make coarse adjustments
3. storage (don't need to remember every vertex in every pose)
4. re-use (apply deformations to different base shapes)

# Matrix Palette

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1. Pass multiple matrices (an array of them)
2. Each vertex specifies which matrix it is part of
  - attribute

# Specifying which matrix

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1. Give the number of the matrix
2. Give a vector of weights
  - allows for blending

This is really a setup for skinning...

# Skinning

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1. Each point in one transformation
2. A point in multiple transformations
  - the point has a different "initial" position
  - the transformations are relative

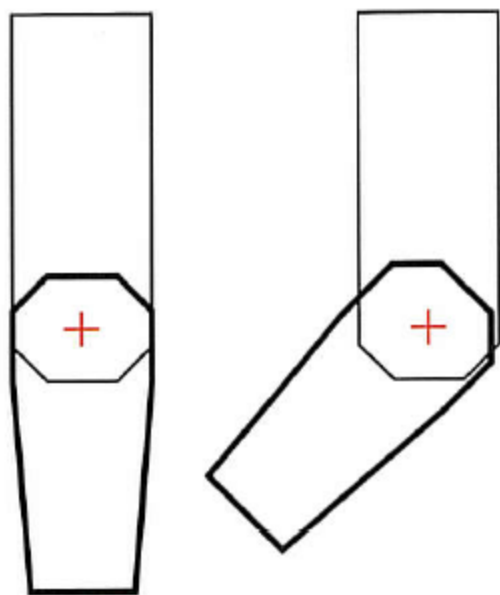


# Skinning

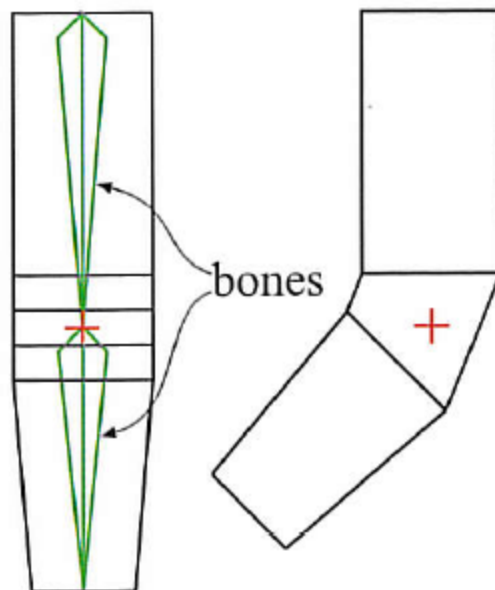
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## Linear Blend Skinning

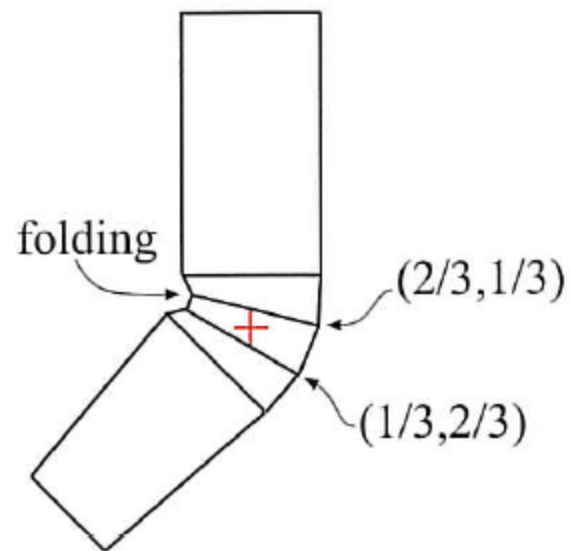
- Each vertex in multiple coordinate systems (weighting)



rigid-body



vertex blending



# Blend Matrices?

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$$p_s = \alpha M_1 p_0 + \beta M_2 p_0$$

is the same as

$$p_s = (\alpha M_1 + \beta M_2) p_0$$

If  $M_1$  and  $M_2$  are rotations, scaling/adding doesn't give a rotation!

This leads to weird artifacts...

# Blend Artifacts

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# Blend artifacts

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# Skeletons

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## Bones as coordinate systems

- how to specify movements?
  - inverse kinematics
  - motion capture
- how to draw the character

# Linear Blend Skinning?

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- Popular because it is simple
- Artists work around artifacts
- More complex alternatives exist - trade complexity for quality

# More Generally...

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Make one shape

Deform it to other shapes

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# Non-Linear Deformations

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- Bend/Twist/Other
- Lattice / Free-Form Deformation
- Cages

# Deformations as space transformations

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$$x', y', z' = f(x, y, z)$$

# Grid Deformers

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# Free-Form Deformations (FFD)

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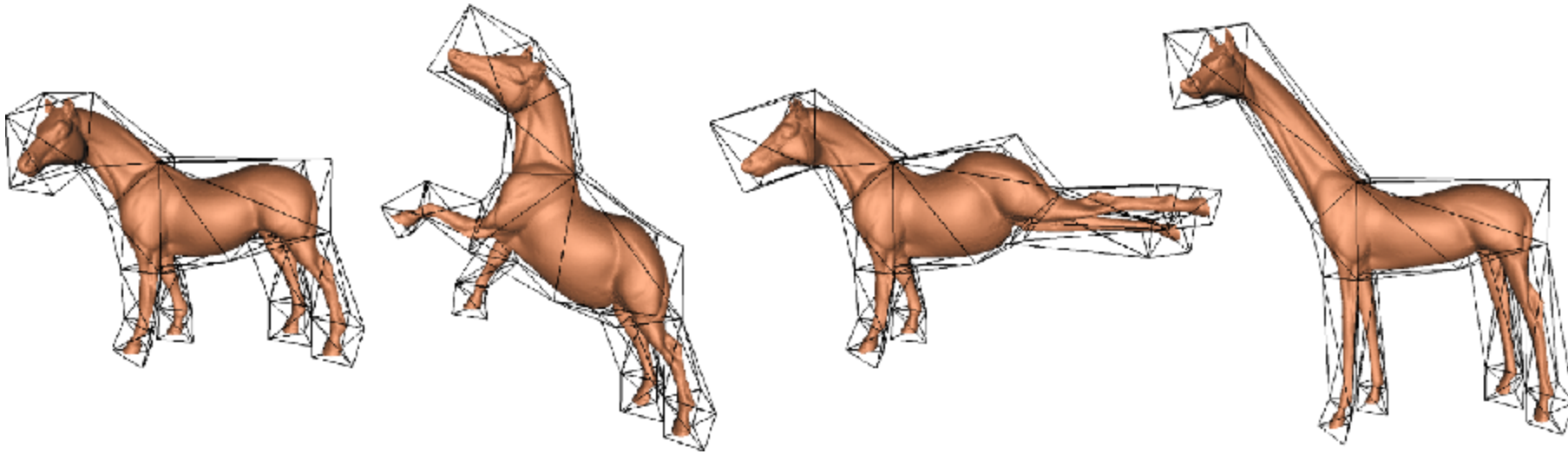
# The trick: coordinates in irregular shapes

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- Triangles (Barycentric)
- Squares (XY)
- Anything else? (generalized barycentric)

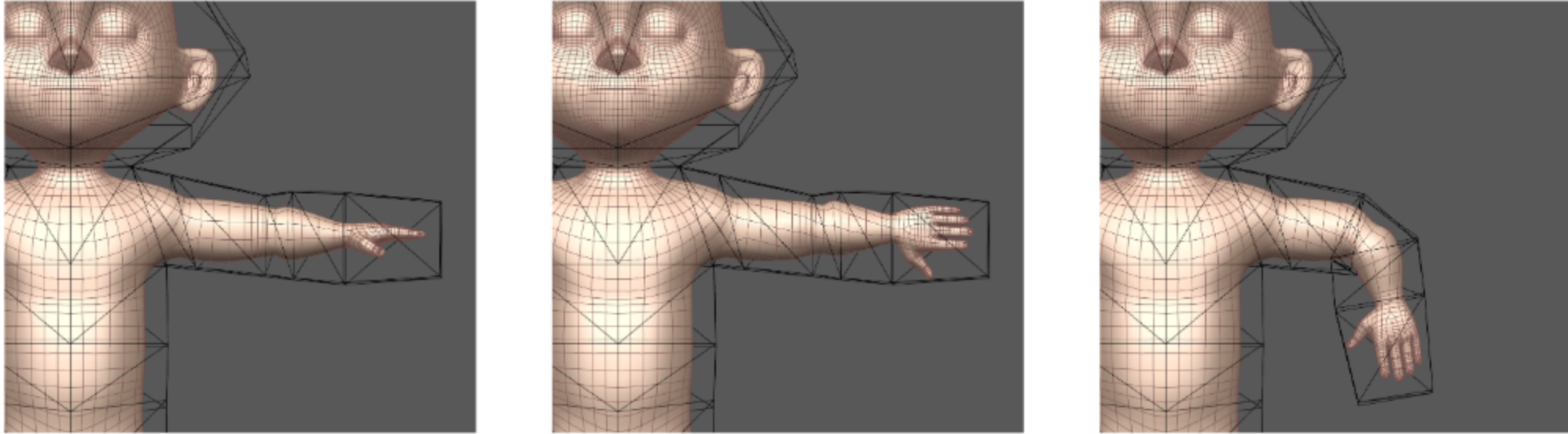
# Cages (Coordinate-based Deformations)

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# Harmonic Coordinates (Pixar 2000s)

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<https://graphics.pixar.com/library/HarmonicCoordinatesB/paper.pdf>

# Multiple Mesh concepts

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# Shape Interpolation (Morphing)

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Create multiple copies of the mesh

- each copy is a **morph target**

Vertices interpolate between targets

- blend their positions in each target
- $p = w_1p_1 + w_2p_2 + w_3p_3$  for each vertex

Send all meshes to the hardware

Each frame only changes the weights

# Downsides

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1. Need to make all the meshes
2. Meshes need to correspond
3. In-between values may not be meaningful
4. Control by blending (not always easy)

# In THREE

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Built in to THREE!

(see that weird blobby thing in the graphics town demo)

# OK, But What Can I Do for my Project?

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In Graphics Town you can:

1. Be careful about texture usage (use an Atlas!)
2. Use fewer, bigger objects
3. Use Environment Maps
4. Try Skinning and Morphing (built into THREE)
5. Try implementing complex deformations (good shaders practice)

Avoid doing "stupid" things (things you can't see, redundancy, ...)

# More generally...

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How do we make smooth shapes?

# Curves vs. Surfaces vs. Solids

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# Curves in 3D

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Everything we learned in 2D

just another dimension

dimensions are independent in polynomial curves

# Curves in 3D

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- Tangent Vector
- Normal Plane

How do we orient an object in the normal plane?

We need a **frame** - a coordinate system that moves along curve

It needs to be consistent



# Roller Coasters (Trains in 3D)

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The ghost of 559 past...

## 1. Frenet Frame

- Tangent
- Normal Vector (direction of 2nd derivative)
- Bi-Normal (cross product of 1st two)
- **what if one vanishes?** (straight segment)

## 2. Interpolate Up Vector

# Solid Modeling

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A (non-infinite) surface (area) is bounded by a curve

A curve may (or may not) bound a surface (area)

A (non-infinite) solid is bounded by a surface

A surface may (or may not) bound a solid

If you want a solid, be careful (that's a different class)

# Surface Modeling

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Flat surfaces (or piecewise flat)

- polygons
- triangles
- meshes

Standard shapes

- cone
- cylinder
- sphere (ball is volume)
- and many more...

# Surface of Revolution

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1. Define a 2D Shape
2. Revolve it around an axis

# Generalized Cylinders (1) Tubes

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1. Define a spine (function of  $t$ )
2. Give a radius

# Generalized Cylinders (2) Cones

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1. Define a spine (function of  $t$ )
2. Define a radius (function of  $t$ )

# Generalized Cylinders (3) Sweeps

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1. Define a spine
2. Define a cross-section shape

# Fancy Sweeps

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2D Shape interpolation along spine

Requires good 3D curves



# Lofting and Other Shape Methods

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Define surfaces by curves

Interpolate between curves

# Free Form Surfaces: Approaches

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Same as curves

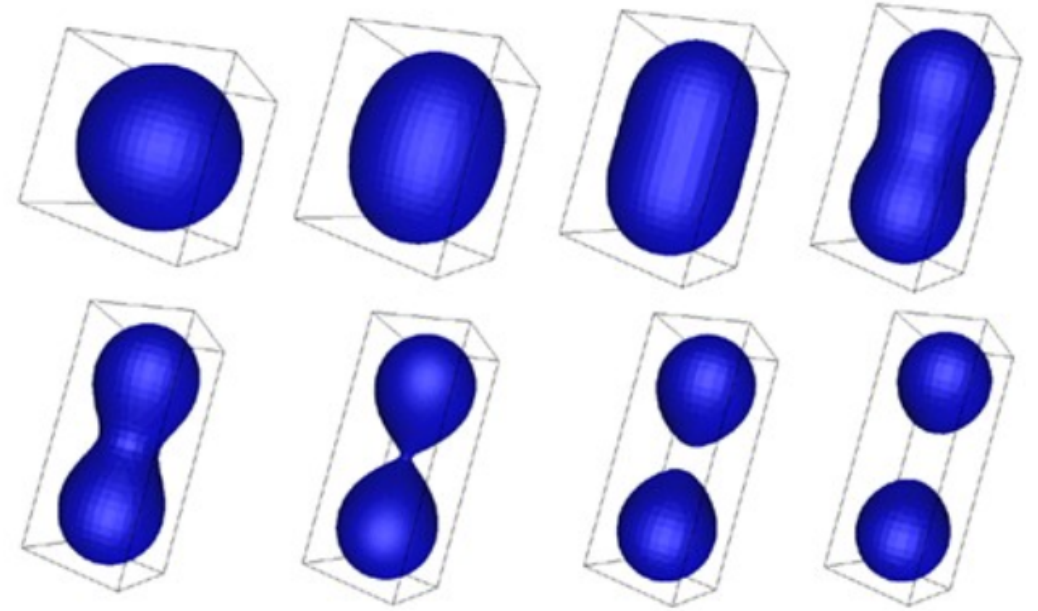
- Parametric:  $(x, y, z) = \mathbf{f}(u, v)$
- Implicit:  $f(x, y, z) = 0$
- Procedural
- Subdivision

# Implicit Surfaces

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$$f(x, y, z) = 0$$

- inside of sphere
- inside of set of spheres
- distance to a set of points
- density (blobs)
  - (falls off to zero quickly)
- model by summing blobs



# How to draw an implicit surface?

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Need to find points on  $f(x, y, z) = 0$

# Free form surfaces

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Is there an analog to polynomial curves?

$$f(u) \rightarrow \mathcal{R}^3$$

# Cubic Polynomials

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curve:  $f(u) = a_0 + a_1u^1 + a_2u^2 + a_3u^3$

surface:  $f(u, v) = ???$

Polynomial in u and v! (tensor product)

$$\begin{aligned} f(u, v) = & a_{00}u^0v^0 + a_{01}u^1v^0 + a_{02}u^2v^0 + a_{03}u^3v^0 + \\ & a_{10}u^0v^1 + a_{11}u^1v^1 + a_{12}u^2v^1 + a_{13}u^3v^1 + \\ & a_{20}u^0v^2 + a_{21}u^1v^2 + a_{22}u^2v^2 + a_{23}u^3v^2 + \\ & a_{30}u^0v^3 + a_{31}u^1v^3 + a_{32}u^2v^3 + a_{33}u^3v^3 \end{aligned}$$

# Tensor Product Surface Patches

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16 coefficients (control points)!

$$\begin{aligned} f(u, v) = & a_{00}u^0v^0 + a_{01}u^1v^0 + a_{02}u^2v^0 + a_{03}u^3v^0 + \\ & a_{10}u^0v^1 + a_{11}u^1v^1 + a_{12}u^2v^1 + a_{13}u^3v^1 + \\ & a_{20}u^0v^2 + a_{21}u^1v^2 + a_{22}u^2v^2 + a_{23}u^3v^2 + \\ & a_{30}u^0v^3 + a_{31}u^1v^3 + a_{32}u^2v^3 + a_{33}u^3v^3 \end{aligned}$$

There are analogs to curve formulations

- Bezier, B-Spline, Interpolating, ...

# Tensor Product Surfaces are Hard!

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How to connect two patches?

- Continuity
- Stitching together

How to cut a patch?

- Make a Hole?
- Make an edge? (attachment)

How about non-square domains?

- inconvenient stretching?
- different topology?



# What do we do instead?

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save it for next time...

# Recap...

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## 1. Animation by deformation

- transformations, skinning, morphing, grids, cages

## 2. Curves in 3D

## 3. Surfaces in 3D

- "primitive" shapes (cylinders, cones, sweeps)
- implicit representations
- parametric surfaces

Subdivision is next