

FYS-STK3155/4155, lecture  
October 27, 2025

Solving differential eqs  
with Deep learning

$$\frac{dg}{dt} = -\gamma g(t)$$

$$\gamma > 0 \quad t \in [0, \infty)$$

$$g_0 = g(t=0)$$

$$g(t) = g_0 \exp(-\gamma t)$$

$$f(t, g(t), g'(t))$$

$$f(t, g, g') = \frac{dg}{dt} - \gamma g(t) = 0$$

in general

$$f(t, g, g', g^{(2)}, \dots, g^{(m)})$$

$$g \Rightarrow g_T(t) = h_1(t) + h_2(t, \underline{N(t, \epsilon)})$$

↑

trial

Boundary  
+ initial  
conditions

neural  
network  
with  
parameters  $\epsilon$

$$g(t) = g_0 \exp(-\gamma t)$$

$$g_{\bar{T}}(t) = \underbrace{g_0}_{\text{initial}} + tN(t, \theta)$$

initial  
conditions

$$t = 0$$

$$C(\theta) = \frac{1}{n} \sum_{i=0}^{n-1} [g(t, g_{\bar{T}}, \hat{g}_{\bar{T}})]^2$$

$$g_{\bar{T}}(0) = g_0$$

$$\hat{\theta} = \underset{\theta}{\operatorname{arg\,min}} C(\theta)$$

Taylor expansion

$$g(t \pm \Delta t) = g(t) \pm \Delta t \frac{dg}{dt} \Big|_t + \frac{(\Delta t)^2}{2!} \frac{d^2 g}{dt^2} \Big|_t + O(\Delta t^3)$$

Discretize

$$t \rightarrow t_i = t_0 + i \Delta t$$

$$\Delta t = \frac{t_n - t_0}{n} \quad i = 0, 1, 2, \dots, n$$

$$g(t + \Delta t) \Rightarrow g(t_i + \Delta t) = g_{i+1}$$

$$g_{i+1} = g_i + \Delta t g_i' + o(\Delta t^2)$$

$$g_{i+1}' \approx g_i' + \Delta t g_i'' \Rightarrow$$

$$g_i' \approx \frac{g_{i+1} - g_i}{\Delta t}$$

$$g_1 = g_0 - \gamma g_0$$

$$g_2 = g_1 - \gamma g_1$$

⋮

$$g_m = g_{m-1} - \gamma g_{m-1}$$

Euler's  
method

$$-g''(x) = f(x)$$

↑ known function

$$x \in [0, 1]$$

$$g(x=0) = g(x=1) = 0$$

$$f(x) = (3x + x^2) \exp(x)$$

$$g(x) = x(1-x) \exp(x)$$

$$g_T(x) = x(1-x) N(x, \epsilon)$$



$$g''(x) \simeq \frac{g(x+\Delta x) + g(x-\Delta x) - 2g(x)}{(\Delta x)^2}$$

$$g(x) \Rightarrow g(x_i) = S_i$$

$$- \tilde{g}_i = - \left( \frac{S_{i+1} + S_{i-1} - 2S_i}{(\Delta x)^2} \right)$$

$$= f(x_i) = f_i$$

$$g_0 = g_m = 0$$

$$g = \begin{bmatrix} s_1 \\ s_2 \\ \vdots \\ s_{n-1} \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 1 & 0 \\ -1 & 2 & 1 \\ 0 & -1 & 2 \end{bmatrix}$$

$$A \cdot g = \Delta x^2 \cdot f$$

$$g = (A^{-1} \cdot f) \Delta x^2$$

# CNNs overaching view



