#### ME 598/494 Exam 1 - September 13, 2018

## Problem 1 (20 Points)

Check if the following statements are true or not. Please explain.

- (a) If  $x_*$  is a stationary point of a continuous and differentiable function f, then  $x_*$  is a local minimum of f.
- (b) The intersection of two convex sets is also convex. If true, please explain; if not, please provide a counter example.
- (c) If a stationary point  $x_*$  has positive semi definite Hessian, then it is a local solution.
- (d) The problem  $\min_{x_1,x_2}(x_1-2)^2+(x_2-3)^2$  for  $\max\{x_1,x_2\}\leq 1$  (i.e., the larger value of  $x_1$  and  $x_2$  should be no larger than 1) has a unique solution. (Hint: How does the feasible space look like?)

#### **Solutions**

- (a) False. Could be saddle or local maximum.
- (b) True. Consider two convex sets  $S_1$  and  $S_2$  and two elements  $x_1$  and  $x_2$  that both belong to both sets. Since  $x_1$  and  $x_2$  belongs to  $S_1$ , we have  $\lambda x_1 + (1 \lambda)x_2 \in S_1$  for any  $\lambda \in [0, 1]$ . Similarly,  $\lambda x_1 + (1 \lambda)x_2 \in S_2$ . Therefore,  $\lambda x_1 + (1 \lambda)x_2 \in S_1 \cap S_2$ , i.e.,  $S_1 \cap S_2$  is convex.
- (c) False. The Hessian needs to be positive definite for the sufficient condition.
- (d) True.  $(x_1-2)^2+(x_2-3)^2$  is a convex function and  $\max\{x_1,x_2\}\leq 1$  is a convex set.

### Problem 2 (25 Points)

- (a) Concisely **explain** the gradient descent algorithm for solving unconstrained optimization problems without line search. (5 Points)
- (b) Concisely **explain** the Newton's method for solving unconstrained optimization problems without line search. (5 Points)
- (c) Explain why line search is needed for gradient descent and Newton's method. Propose a line search algorithm (can be an existing one). (5 Points)
- (d) Discuss briefly the advantages and disadvantages of using Newton's method in solving optimization problems. (10 Points)

#### **Solutions**

See notes.

# Problem 3 (15 Points)

Consider solving an optimization problem through an iterative algorithm. Let  $x_k$  and  $s_k$  be the current solution and search direction, respectively;  $f(x_k)$  the current objective value; and  $\alpha$  the step size.

- (a) Derive the second-order Taylor's expansion of  $f(x_k + \alpha s_k)$  at  $\alpha = 0$ . (5 points)
- (b) Use Newton's method  $s_k = -H_k^{-1}g_k$  with gradient  $g_k$  and Hessian  $H_k$ . Show that when the expansion in (a) is exact, the optimal step size is  $\alpha = 1$ . (10 points)

#### **Solutions**

Second-order Taylor's expansion of  $f(x_k + \alpha s_k)$  at  $\alpha = 0$  is

$$f(x_k + \alpha s_k) = f_k + \alpha g_k^T s_k + \frac{1}{2} \alpha^2 s_k^T H_k s_k.$$

$$\tag{1}$$

Consider  $s_k = -H_k^{-1}g_k$ , then we have

$$f(x_k + \alpha s_k) = f_k - \alpha g_k^T H_k^{-1} g_k + \frac{1}{2} \alpha^2 g_k^T H_k^{-1} g_k.$$
 (2)

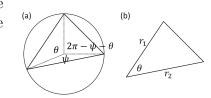
Take derivative to have

$$\frac{df(x_k + \alpha s_k)}{d\alpha} = -g_k^T H_k^{-1} g_k + g_k^T H_k^{-1} g_k \alpha. \tag{3}$$

Set the derivative to zero to have  $\alpha^* = 1$ .

## Problem 4 (20 Points)

Draw a triangle **inside** a circle. Maximize the area of the triangle. (Hint: see figure (a) for one representation of the triangle. The area of the triangle in figure (b) is  $r_1r_2\sin(\theta)$ .)



#### **Solutions**

The area of the triangle is proportional to  $\sin(\theta) + \sin(\psi) + \sin(2\pi - \theta - \psi)$ . The derivatives with respect to  $\theta$  and  $\psi$  are  $\cos(\theta) - \cos(2\pi - \theta - \psi)$  and  $\cos(\psi) - \cos(2\pi - \theta - \psi)$ . Set these to zeros to have  $\theta = \psi = 2\pi/3$ . The Hessian matrix is  $[-\sin(\theta) - \sin(2\pi - \theta - \psi), -\sin(2\pi - \theta - \psi), -\sin(2\pi - \theta - \psi)]$ . Take in  $\theta = \psi = 2\pi/3$  to have  $-\frac{\sqrt{3}}{2}[2, 1; 1, 2]$ . The Hessian is negative definite. Therefore the unique stationary point is a global maximum.

# Problem 5 (20 Points)

Consider a one-dimensional continuously differentiable function f(x) = 0. One way to find its solution is to solve

$$\min_{\mathbf{x}} \quad \frac{1}{2}f(x)^2. \tag{4}$$

- (a) In what cases is this problem strictly convex? (5 Points)
- (b) Consider solving the problem using Newton's method starting at  $x_0$ . Describe the algorithm. (5 Points)
- (c) Please explain in what cases you will not be able to use Newton's method, and how you will resolve this issue. (10 Points, optional for MAE494)

### **Solutions**

The gradient of the objective is f(x)f'(x), the Hessian is  $f'(x)^2 + f(x)f''(x)$ . If the Hessian is positive for all x, then the problem is strictly convex.

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\begin{array}{l} \text{input : } x_0, \, f(x) \\ \text{output: } x^* \\ \text{1 } k = 0, \, \epsilon = 10^{-3}; \\ \text{2 while } |f(x)f'(x)| \geq \epsilon \text{ do} \\ \text{3 } & | s_k = -\frac{f(x)f'(x)}{f'(x)^2 + f(x)f''(x)}; \\ \text{4 } & | \alpha_k = \text{lineSearch}(x_k, f(\cdot), s_k); \\ \text{5 } & | x_{k+1} = x_k + \alpha_k s_k; \\ \text{6 } & | k = k+1; \\ \text{7 end} \end{array}
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Standard inexact line search applies. If Hessian is not positive definite, we will need to regularize the Hessian, e.g., through trust region.