```python
"""personne_detect.py | Robin Forestier | 28.03.2022

[WARN] The camera is placed on top of the door.

Detecting moving personne on video.
"""

# import OpenCV
import cv2
import numpy as np

class PersonneDetect:
    """This class is used to detect people in a video stream."""
    def __init__(self):
        self.img = []
        self.copy = []
        self.detected = []
        self.backSub = cv2.createBackgroundSubtractorKNN(history=100,
        dist2Threshold=500.0, detectShadows=False)

    def img_to_gray(self):
        """If the image is in color, convert it to grayscale """

        if len(self.img.shape) == 3:
            self.img = cv2.cvtColor(self.img, cv2.COLOR_BGR2GRAY)
        else:
            pass

    def contour_detect(self, threshold):
        """Detect the biggest contours in the image and store them in a list

        :param threshold: The threshold image that was used
        :type threshold: numpy.ndarray
        """

        self.detected = []

        # Finding contours in the image.
        cnts, hierarchy = cv2.findContours(threshold, cv2.RETR_EXTERNAL,
        cv2.CHAIN_APPROX_SIMPLE)

        # for eache contour
        for cnt in cnts:
            # if the perimeter is bigger than 100
            if 200 < cv2.arcLength(cnt, True) < 2000:
                # creting a bounding rect around it.
                # Creating a bounding rectangle around the contour.
                x, y, w, h = cv2.boundingRect(cnt)
                # store it
                self.detected.append([x, y, w, h])
                # draw a green rectangle.
                cv2.rectangle(self.copy, (x, y), (x + w, y + h), (0, 255, 0), 3)

    def personne_detect(self, img):
        """Detecting personne on image with background subtraction (KNN)

        :param img: The input image
        :type img: numpy.ndarray
        :return: the copy of the image with the green rectangle around the detected
        personne.
        :rtype: numpy.ndarray
        """

        self.img = img
        self.copy = img.copy()

        # Converting the image to grayscale if it is in color.
        self.img_to_gray()
        # Applying the background substractor to the image.
        fgmask = self.backSub.apply(self.img)
        # Blurring the image to remove the noise.
        blurImage = cv2.GaussianBlur(fgmask, (5, 5), 0)
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70          # Thresholding the image to make it binary.
71          _, th = cv2.threshold(blurImage, 1, 255, cv2.THRESH_BINARY)
72
73          # Realising 4 morphology transformation to clear the image of impure pixel.
74          # To dilate the shape and close it.
75          kernel = np.ones((9, 9), np.uint8)
76          #kernel = cv2.getStructuringElement(cv2.MORPH_ELLIPSE, (9, 9))
77          cv2.imshow("th", th)
78          # th = cv2.erode(th, kernel, iterations=1)
79          # th = cv2.morphologyEx(th, cv2.MORPH_OPEN, kernel)
80          th = cv2.morphologyEx(th, cv2.MORPH_CLOSE, kernel)
81          th = cv2.dilate(th, kernel, iterations=2)
82          th = cv2.morphologyEx(th, cv2.MORPH_CLOSE, kernel)
83          cv2.imshow("t", th)
84
85          # call contour_detect for detect them.
86          self.contour_detect(th)
87
88          # return th copy of the img (with the green rectangle)
89          return self.copy
90
91
92  if __name__ == '__main__':
93      # Opening the video file.
94      cap = cv2.VideoCapture("vue_top.mp4")
95      # Creating an object of the class PersonneDetect.
96      p = PersonneDetect()
97
98      while True:
99          # Reading the next frame from the video file.
100         _, img = cap.read()
101         # Resizing the image to a smaller size to make the algorithm faster.
102         # img = cv2.resize(img, (640, 480), interpolation=cv2.INTER_AREA)
103
104         # Calling the function `personne_detect` of the class `PersonneDetect` and
            passing the image `img` as argument.
105         img = p.personne_detect(img)
106
107         # Showing the image in a window named "img".
108         cv2.imshow("img", img)
109
110         # Stop the program when the user press the key `q`.
111         if cv2.waitKey(50) == ord("q"):
112             break
113
114     # Closing the video file and destroying all the windows.
115     cv2.destroyAllWindows()
116     cap.release()
117
```