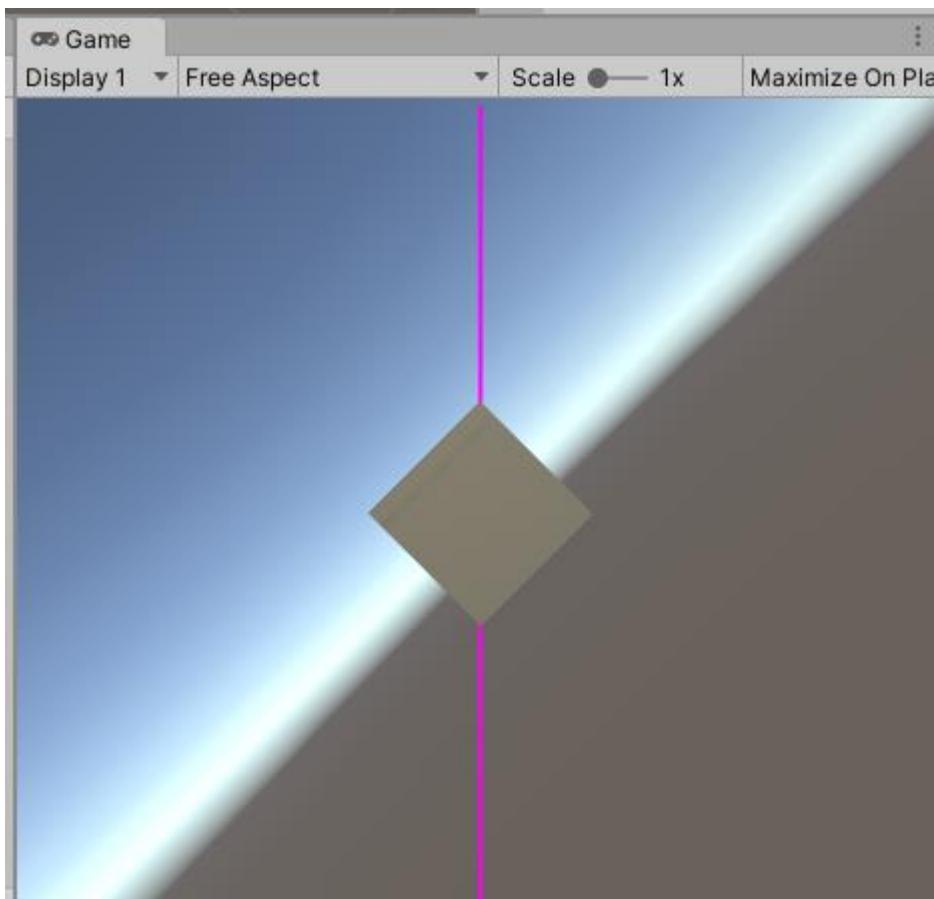
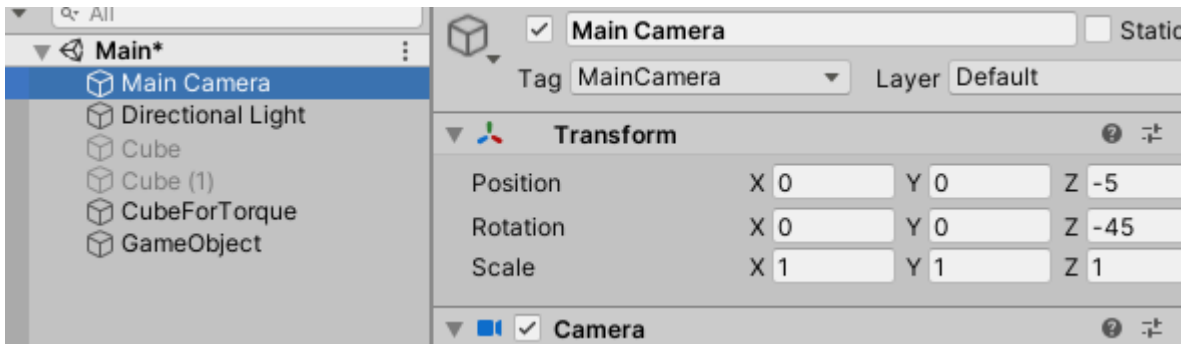
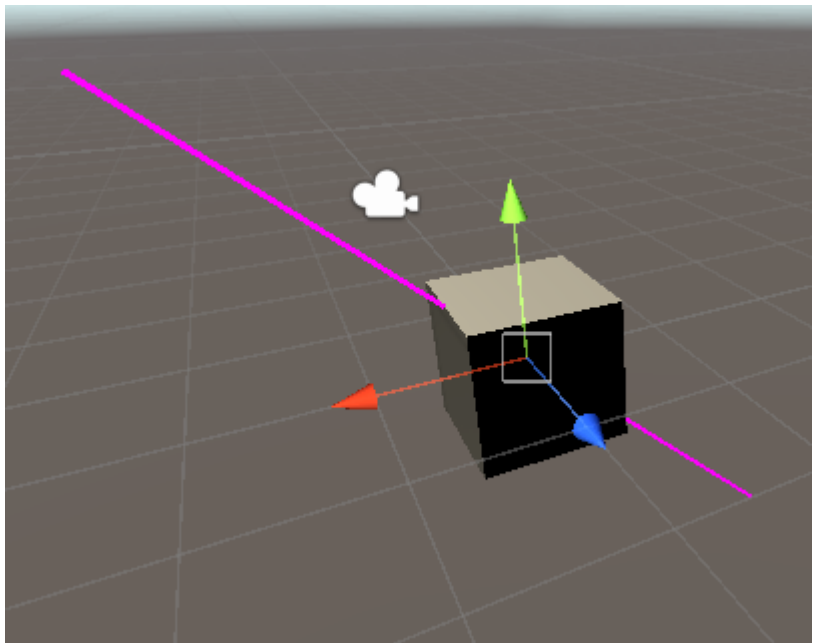
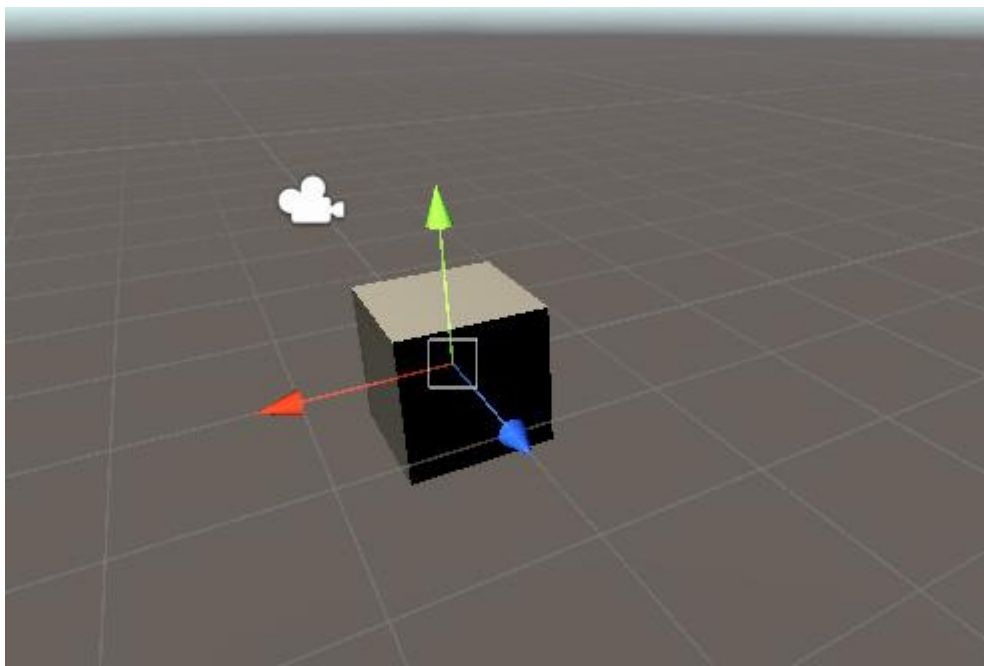
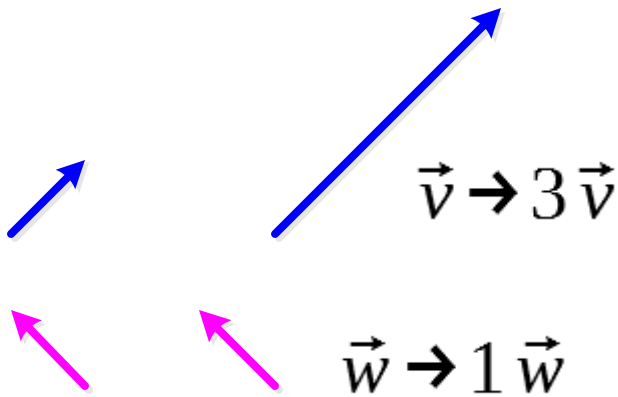
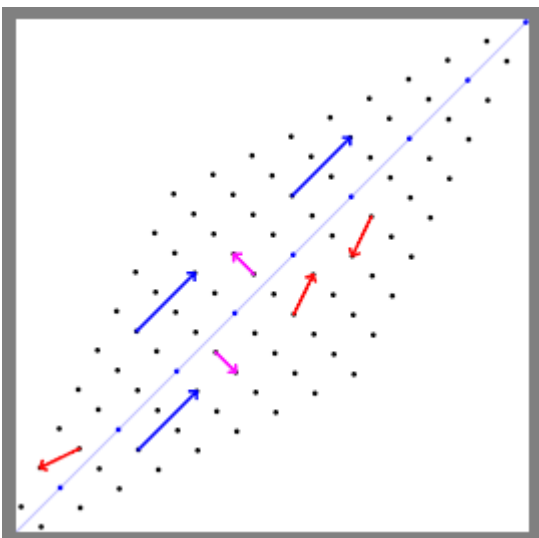
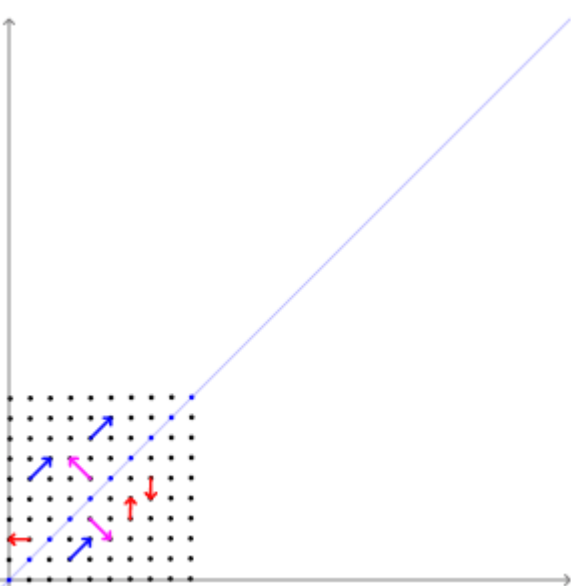


*
How to find the characteristics of a Transform?



```
float theta = Mathf.PI;
Quaternion rot = Quaternion.Euler(0, 0, -45.0f);
torque = Vector3.down * theta * 2.0f;
torque = rot * torque;
_rb.AddTorque(torque);
```



Formal definition [edit]

If *T* is a linear transformation from a vector space *V* over a field *F* into itself and **v** is a nonzero vector in *V*, then **v** is an eigenvector of *T* if *T*(**v**) is a scalar multiple of **v**. This can be written as

T(v) = λv,

where λ is a scalar in *F*, known as the **eigenvalue**, **characteristic value**, or **characteristic root** associated with **v**.

There is a direct correspondence between *n*-by-*n* square matrices and linear transformations from an *n*-dimensional vector space into itself, given any basis of the vector space. Hence, in a finite-dimensional vector space, it is equivalent to define eigenvalues and eigenvectors using either the language of matrices, or the language of linear transformations.^{[3][4]}

If *V* is finite-dimensional, the above equation is equivalent to^[5]

Au = λu.

where *A* is the matrix representation of *T* and **u** is the coordinate vector of **v**.

Eigenvalues and eigenvectors

From Wikipedia, the free encyclopedia
(Redirected from Eigen vector)

"Characteristic root" redirects here. For other uses, see Characteristic root (disambiguation).

In linear algebra, an **eigenvector** (ⁱ/ˈaɪɡənˈvɛktər/) or **characteristic vector** of a linear transformation is a nonzero vector that changes by a scalar factor when that linear transformation is applied to it. The corresponding **eigenvalue**, often denoted by λ,^[1] is the factor by which the eigenvector is scaled.

If it occurs that v and w are scalar multiples, that is if

Av = w = λv, (1)

then v is an **eigenvector** of the linear transformation *A* and the scale factor λ is the **eigenvalue** corresponding to that eigenvector. Equation (1) is the **eigenvalue equation** for the matrix *A*.

Equation (1) can be stated equivalently as

(A − λI)v = 0, (2)

where *I* is the *n* by *n* identity matrix and 0 is the zero vector.

Eigenvalues and the characteristic polynomial [edit]

Main article: Characteristic polynomial

Equation (2) has a nonzero solution v if and only if the determinant of the matrix (A − λI) is zero. Therefore, the eigenvalues of *A* are values of λ that satisfy the equation

|A − λI| = 0 (3)

Using Leibniz' rule for the determinant, the left-hand side of Equation (3) is a polynomial function of the variable λ and the degree of this polynomial is *n*, the order of the matrix *A*. Its coefficients depend on the entries of *A*, except that its term of degree *n* is always (−1)^{*n*}λ^{*n*}. This polynomial is called the *characteristic polynomial* of *A*. Equation (3) is called the *characteristic equation* or the *secular equation* of *A*.

The fundamental theorem of algebra implies that the characteristic polynomial of an *n*-by-*n* matrix *A*, being a polynomial of degree *n*, can be factored into the product of *n* linear terms,

|A − λI| = (λ₁ − λ)(λ₂ − λ) ⋯ (λ_{*n*} − λ), (4)

where each λ_{*i*} may be real but in general is a complex number. The numbers λ₁, λ₂, ... λ_{*n*}, which may not all have distinct values, are roots of the polynomial and are the eigenvalues of *A*.

As a brief example, which is described in more detail in the examples section later, consider the matrix

A = [2 1; 1 2].

Taking the determinant of (A − λI), the characteristic polynomial of *A* is

|A − λI| = | 2 − λ 1; 1 2 − λ | = 3 − 4λ + λ².

Setting the characteristic polynomial equal to zero, it has roots at λ=1 and λ=3, which are the two eigenvalues of *A*. The eigenvectors corresponding to each eigenvalue can be found by solving for the components of v in the equation (A − λI)v = 0. In this example, the eigenvectors are any nonzero scalar multiples of

[1 1; 1 1] [x; y] = [0; 0]
x + y = 0 → x = −y → (1, −1)
w → 1w

[−1 1; 1 −1] [x; y] = [0; 0]
−x + y = 0 → x = y → (1, 1)
x − y = 0

A = [2 1; 1 2] v_{λ=1} = [1; −1], v_{λ=3} = [1; 1]

