

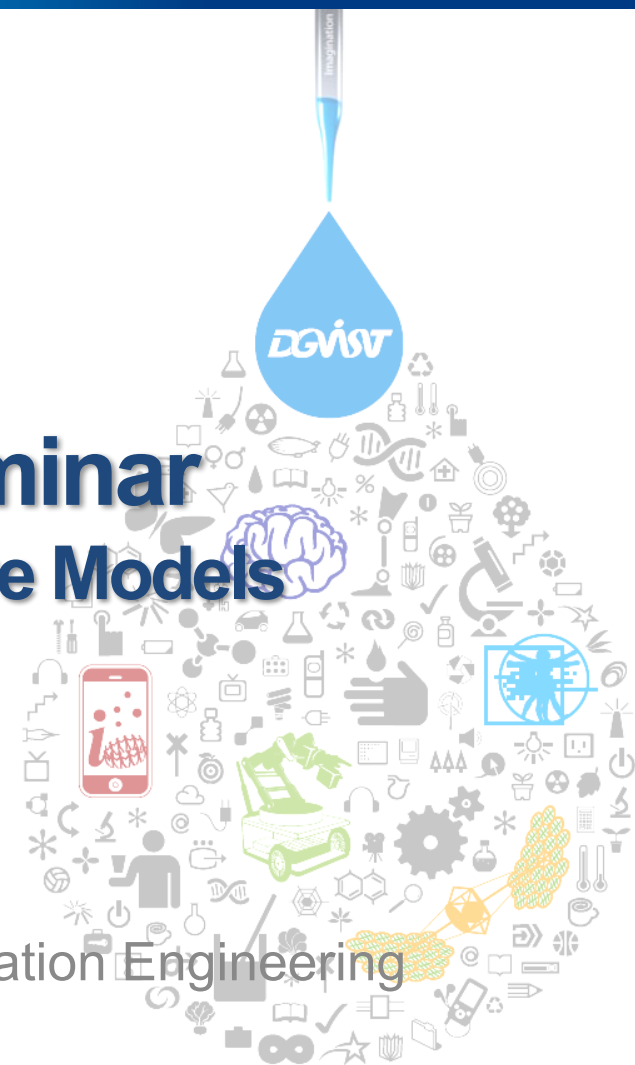
# Deep Learning Seminar

## Chapter 20. Deep Generative Models

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# Chapter 20. Deep Generative Models

- 20.1 Boltzmann Machines
- 20.2 Restricted Boltzmann Machines
- 20.3 Deep Belief Networks
- 20.4 Deep Boltzmann machines
- 20.5 Boltzmann Machines for Real-Valued Data
- 20.6 Convolutional Boltzmann Machines
- 20.7 Boltzmann Machines for Structured or Sequential Outputs
- 20.8 Other Boltzmann Machines

# Chapter 20. Deep Generative Models

- 20.9 Back-Propagation through Random Operations
- 20.10 Directed Generative Nets
- 20.11 Drawing Samples from Autoencoders
- 20.12 Generative Stochastic Networks
- 20.13 Other Generation Schemes
- 20.14 Evaluating Generative Models
- 20.15 Conclusion

# Chapter 20. Deep Generative Models

- **Generative models**
- **Boltzmann Machines**
- **Restricted Boltzmann Machines**
- **Deep Belief Networks**

# Generative models



# Generative V.S. Discriminative

## ● Generative

- To model the joint probability and to make a decision using the result of 'generate' the samples into the distribution
- E.g. Autoencoders, Restricted Boltzmann Machines

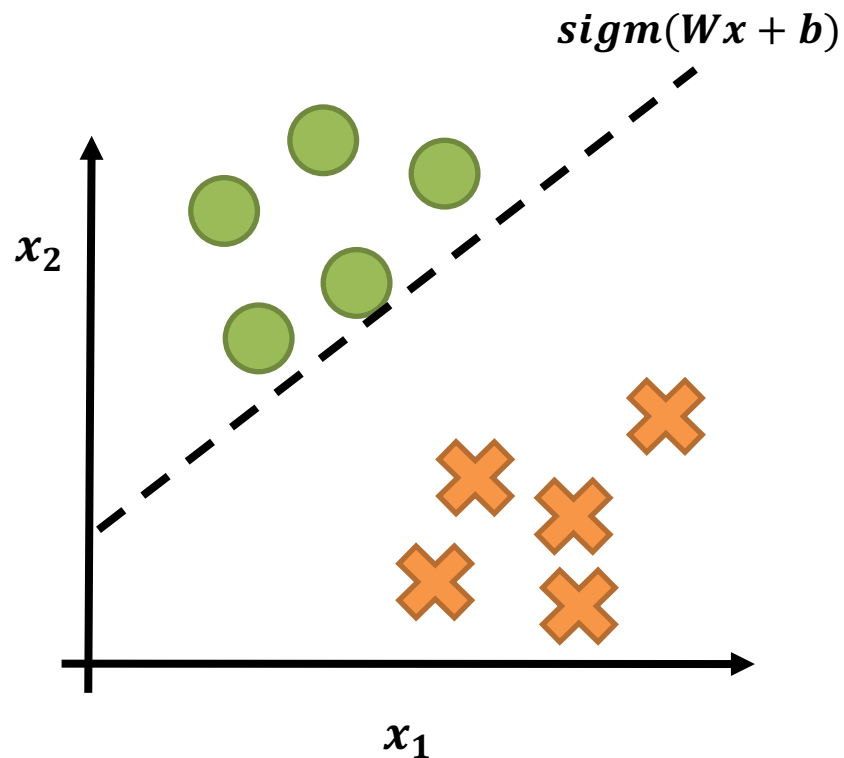
## ● Discriminative

- To directly compute the posterior class probability  $p(C|X)$  in the inference stage
- E.g. Logistic regression, SVM, Boosting, Neural networks

$$p(C|X) = \frac{p(X|C)p(C)}{p(X)}$$

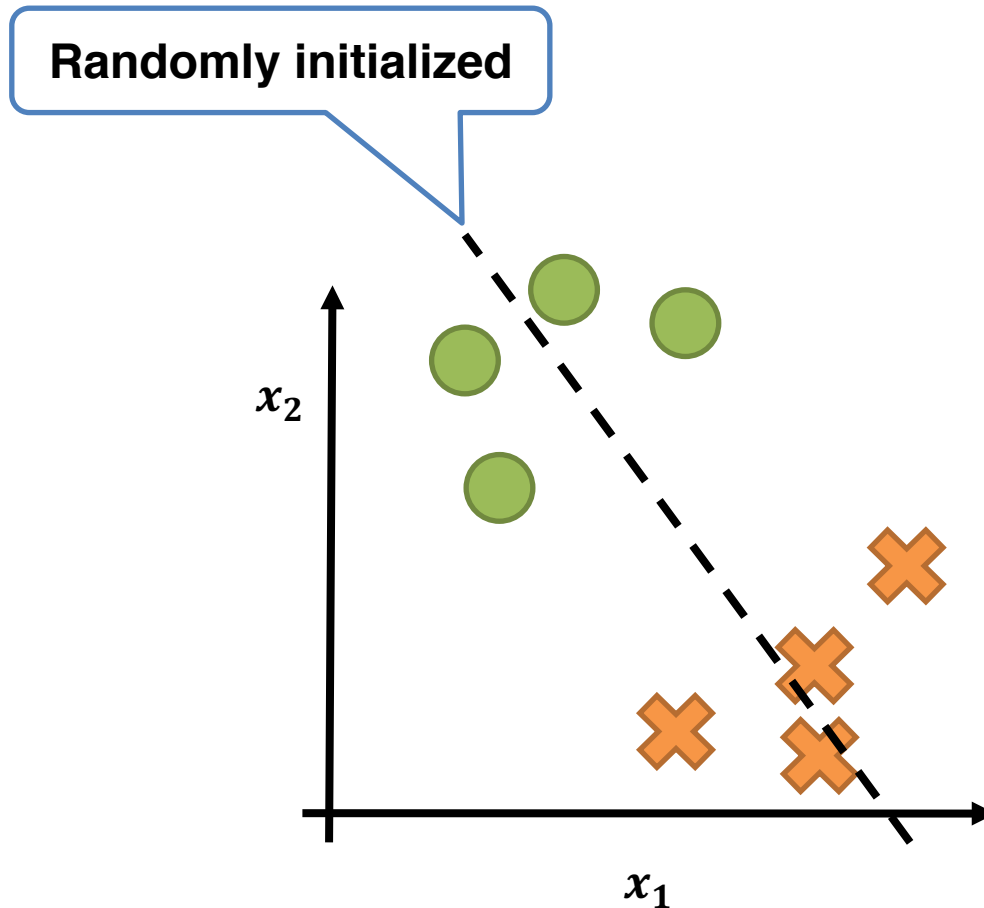
# Discriminative Model – Logistic Regression

- Classification model
- Finding **decision boundary** that minimize error rate



# An Example of Logistic Regression

- Decision boundary is randomly initialized

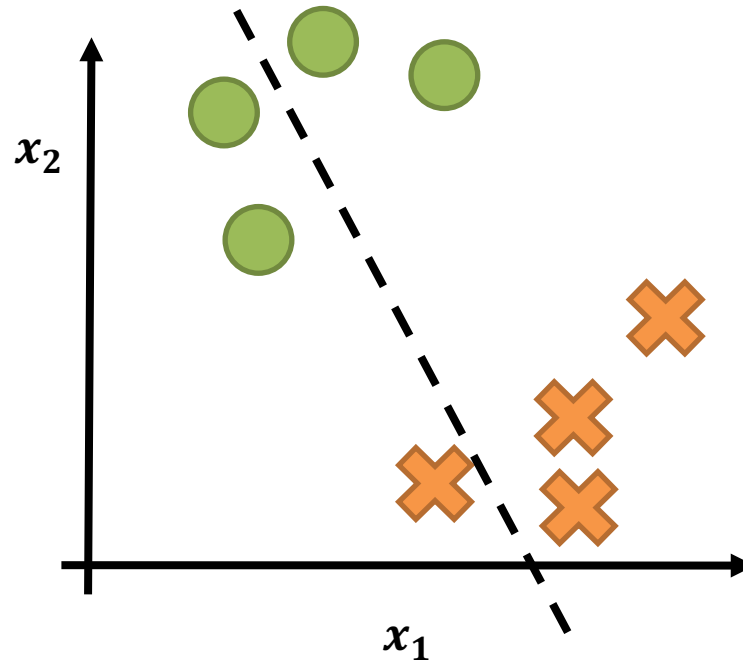




# An Example of Logistic Regression

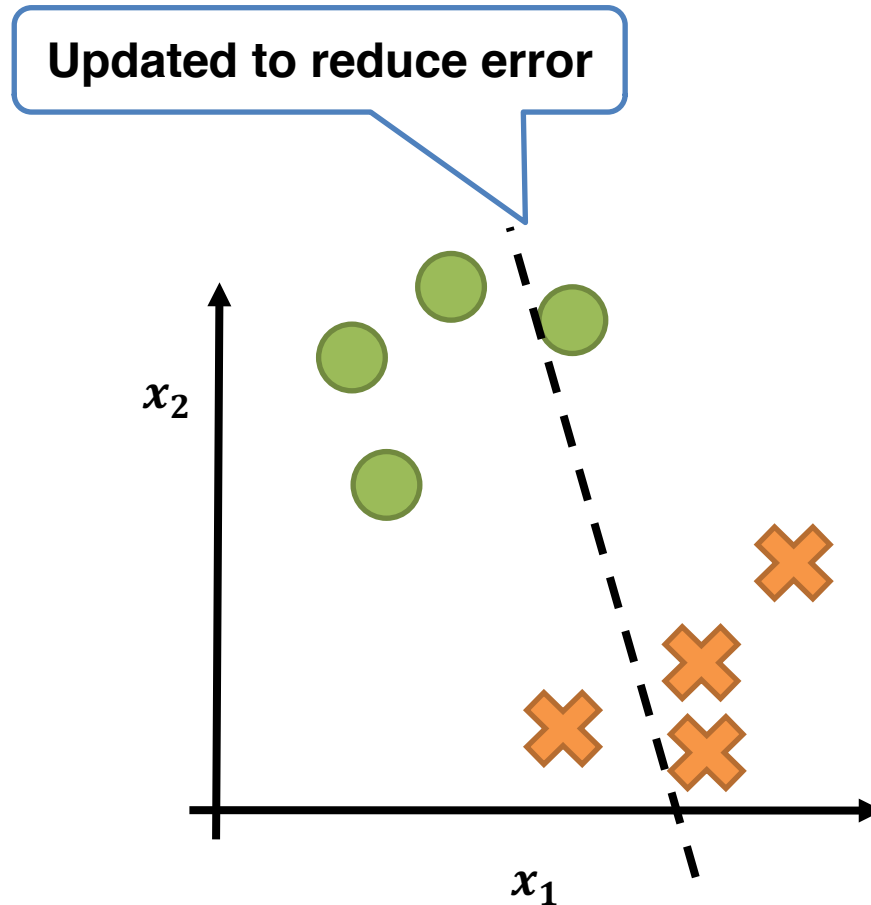
- Update parameters of decision boundary

Updated to reduce error



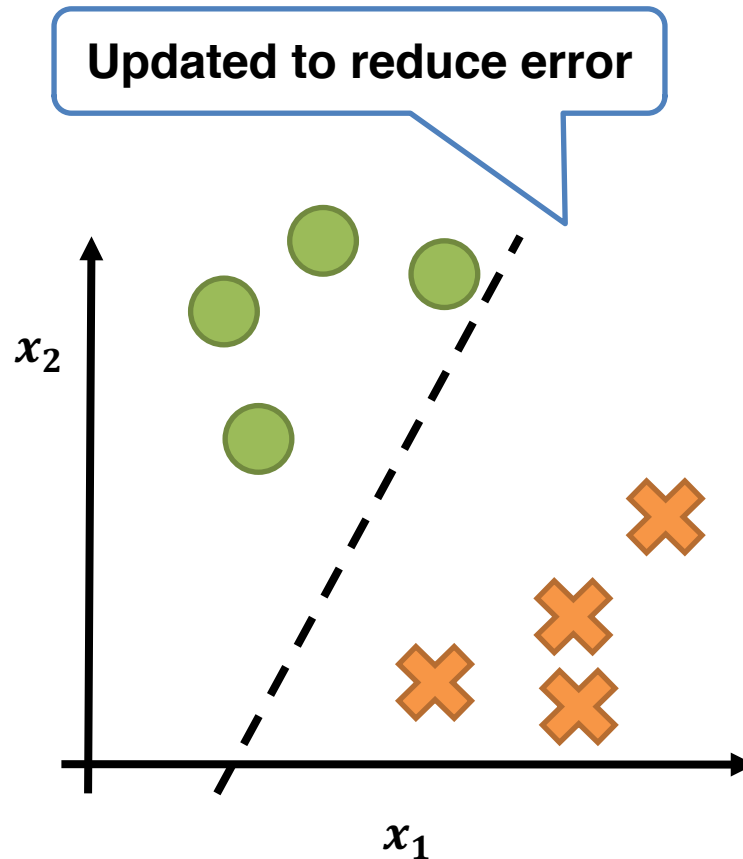
# An Example of Logistic Regression

- Update parameters of decision boundary



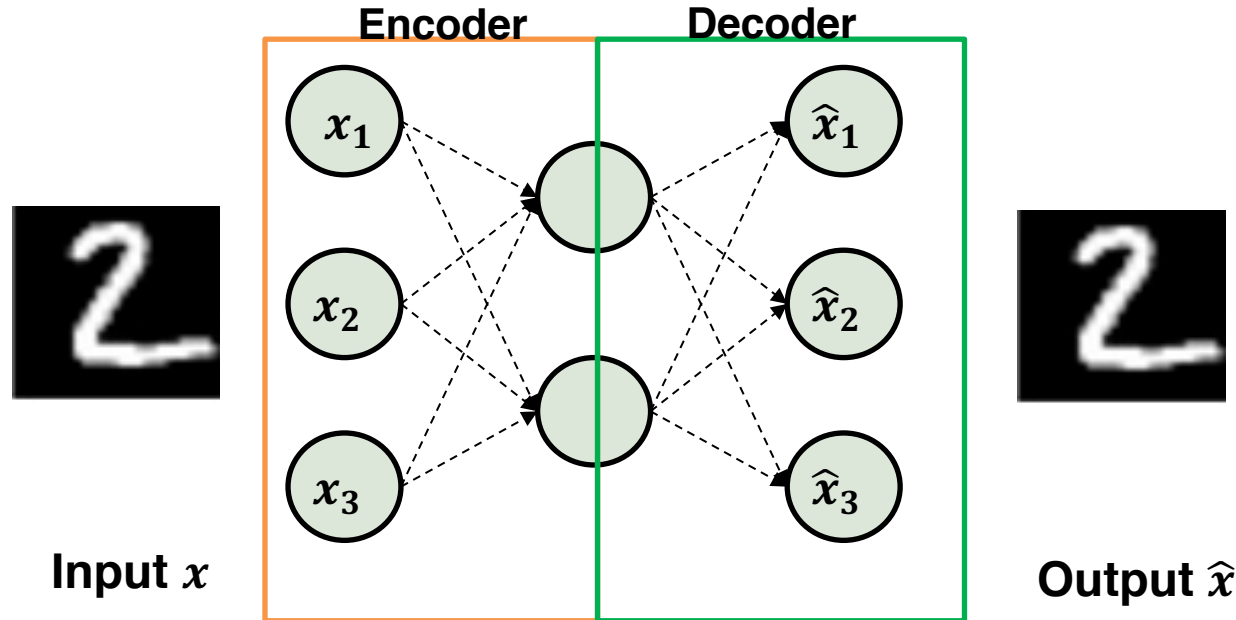
# An Example of Logistic Regression

- Update parameters of decision boundary



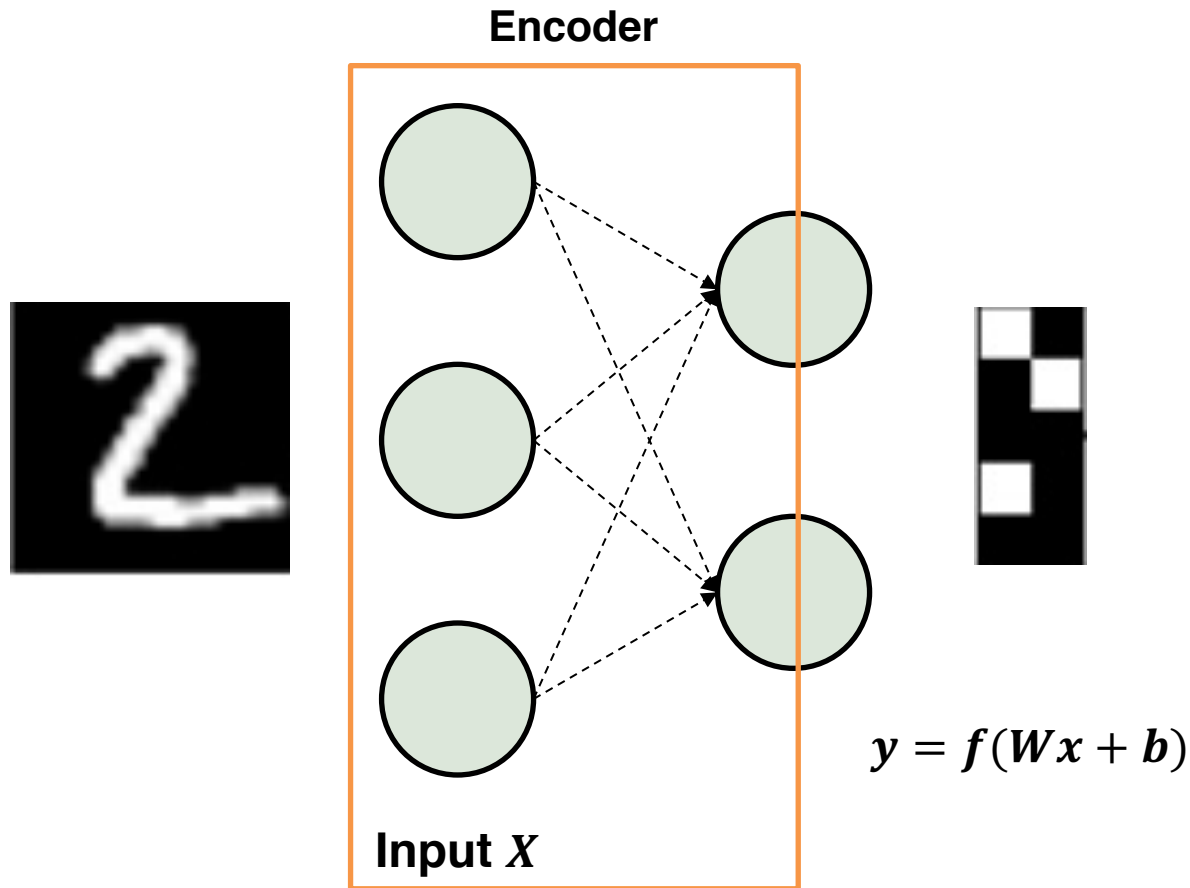
# Generative model – AutoEncoders (AE)

- AE is neural network models that **‘generate’** the same data as the input data
- The main goal of AE is to train distribution of data
- AE with sigmoidal hidden units and linear reconstruction unit is equivalent to RBM



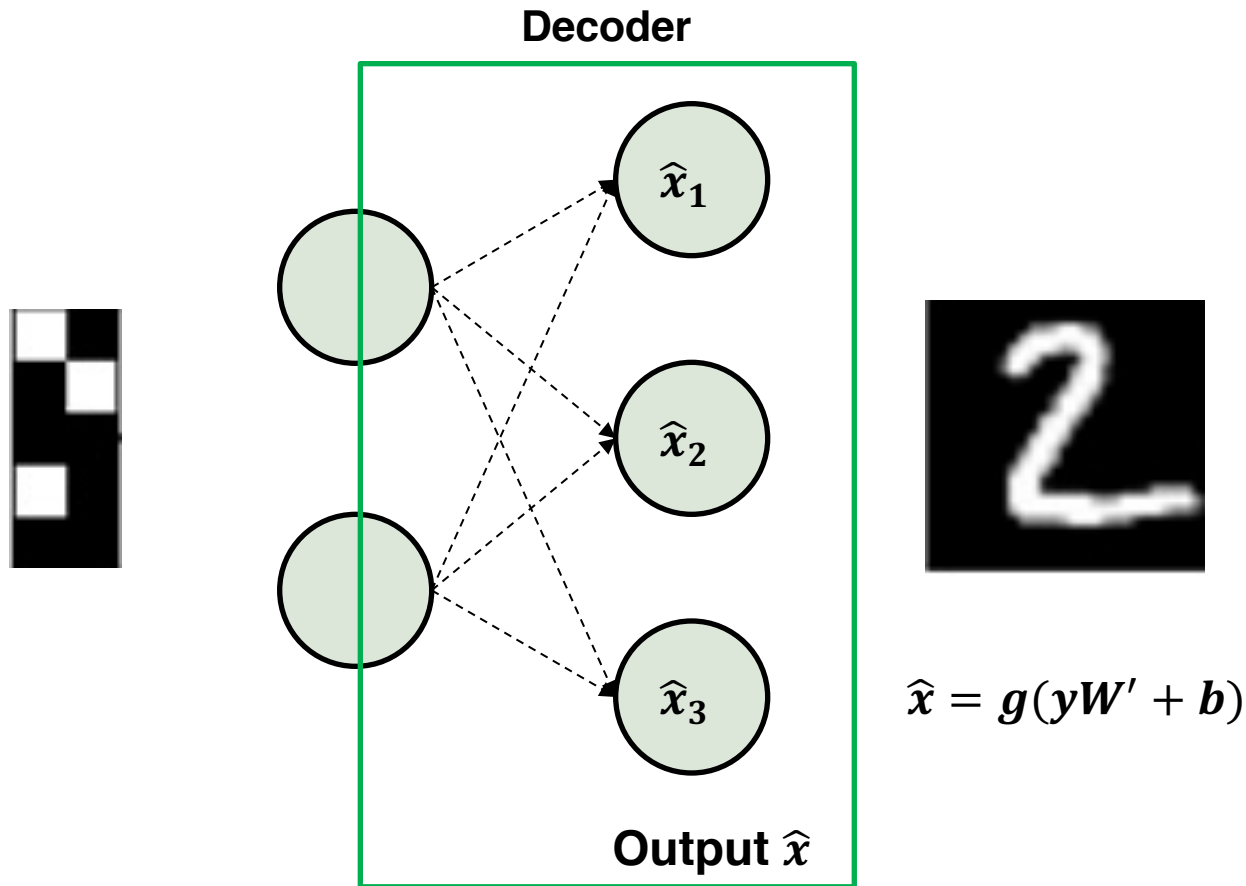
# An Example of AE – Encoder

- Encoder yields compression of input data



# An Example of AE – Decoder

- Decoder reconstructs input data

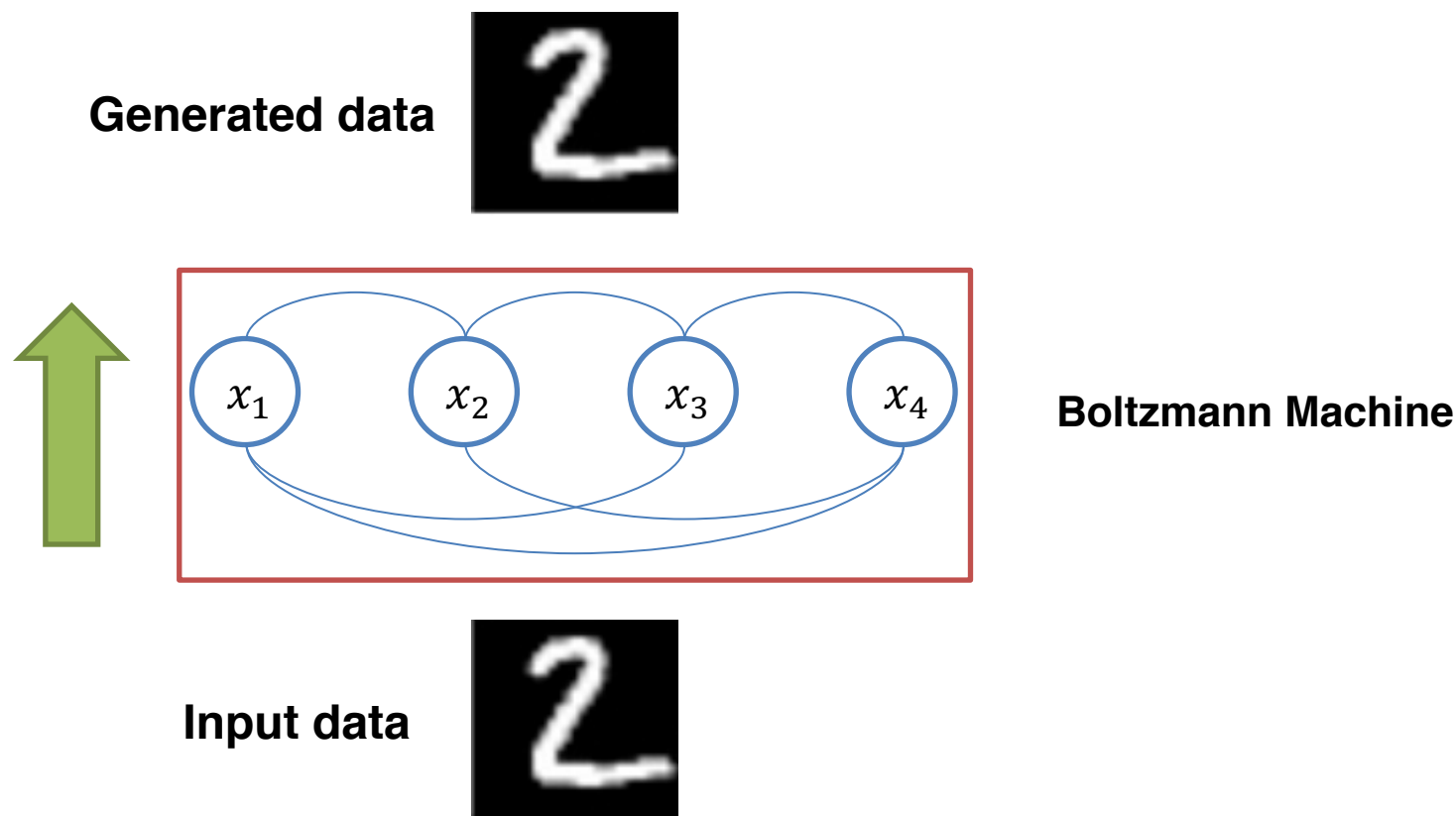


# Boltzmann Machines



# Boltzmann Machines (BM)

- BM is undirected graphical model and **energy based model**
- Each node is connected with all of other nodes

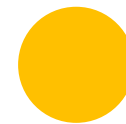
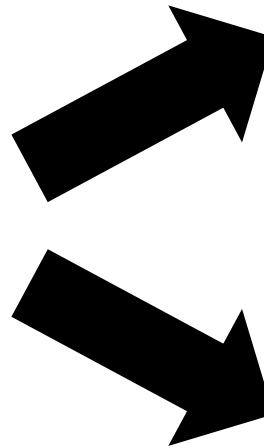
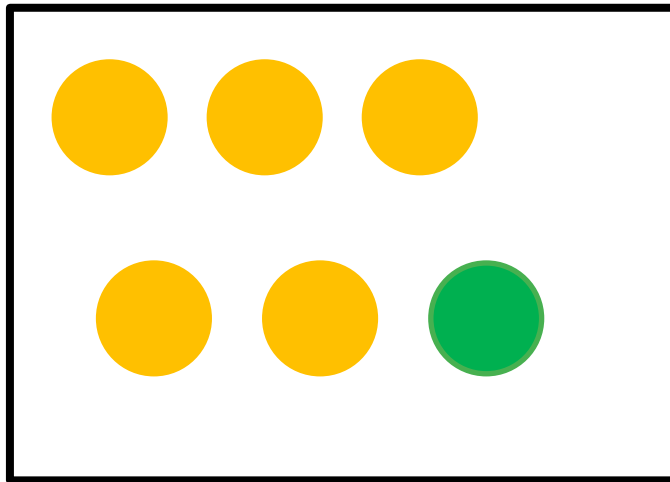




# Energy Based Model

- The meaning of energy

- a measure of the amount of information
- an example of high energy event – winning a lottery
- an example of low energy event – not winning a lottery



$\frac{5}{6}$

**High** probability  
**Low** energy



$\frac{1}{6}$

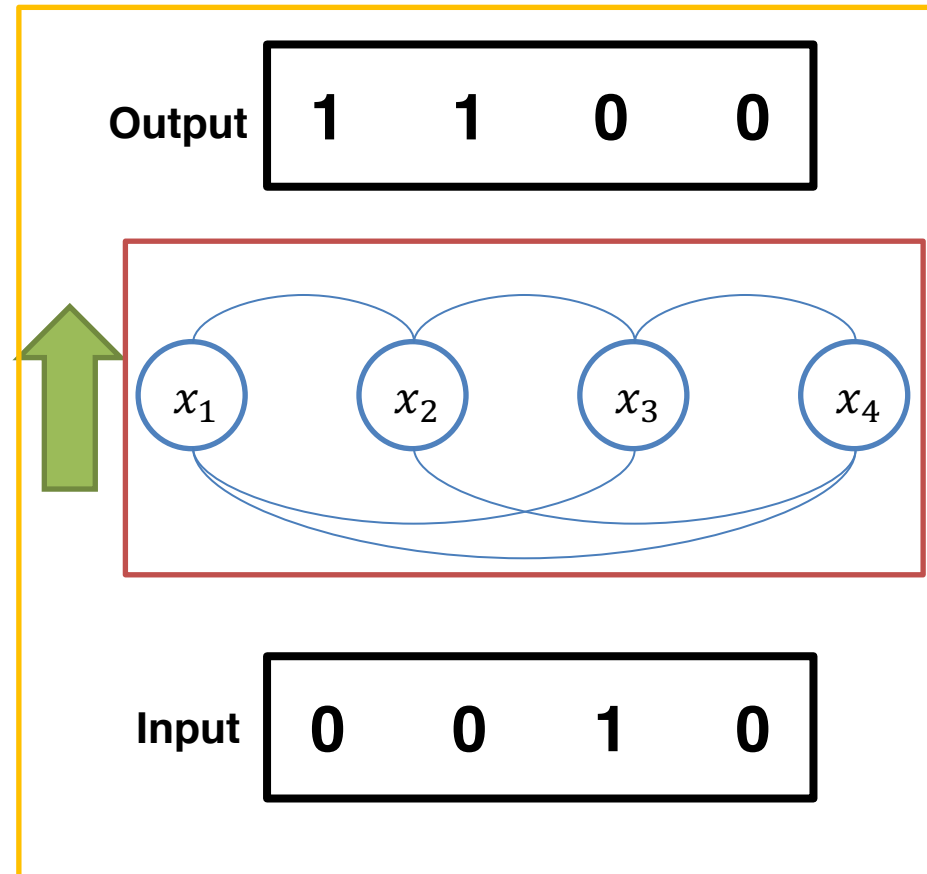
**Low** probability  
**High** energy

# Energy Based Model

- The goal is to **lower the energy** and **increase the probability** that the generated data actually exists

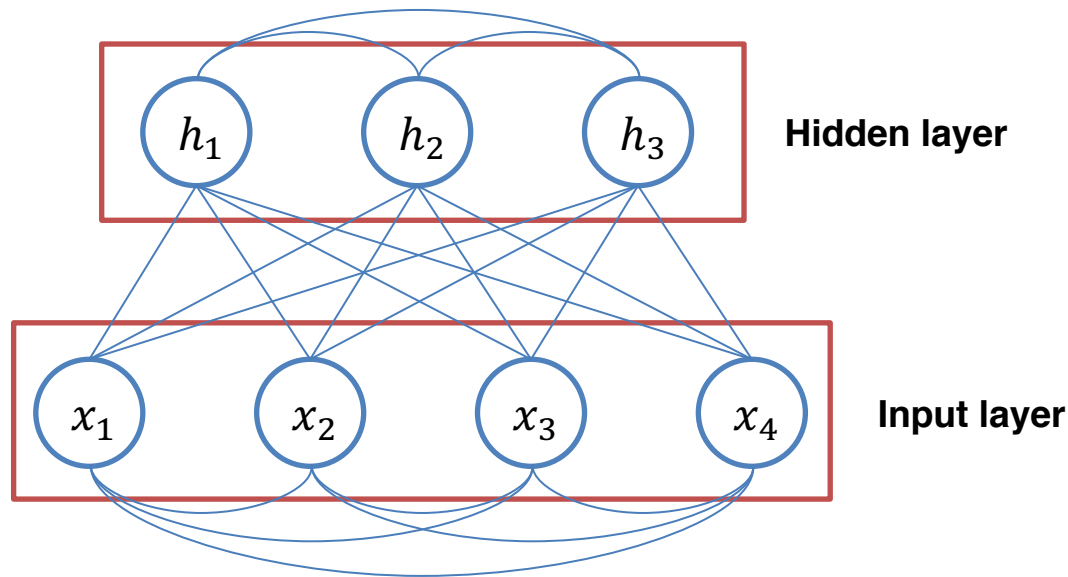
$$E(\mathbf{x}) = -\sum_i b_i x_i - \sum_i \sum_j w_{ij} x_i x_j$$
$$P(\mathbf{x}) = \frac{1}{Z} \exp(-E(\mathbf{x}))$$

$E$  : energy  
 $w$  : weight  
 $b$  : bias  
 $Z$  : partition function



# Multi Layer Boltzmann Machines

- Single layer BM can only generate linear data
- Multi layer BM can generate data with more complex distribution



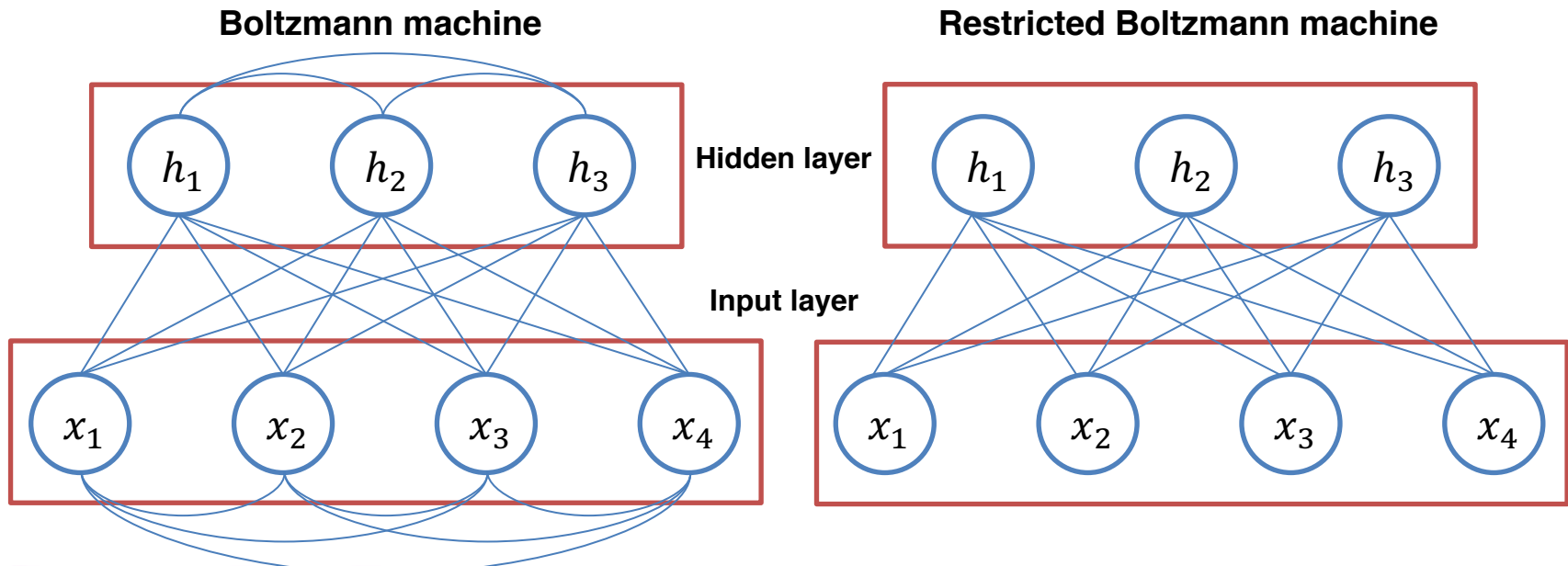
# Restricted Boltzmann Machines



# Restricted Boltzmann Machines (RBM)

- **Characteristics of RBM**

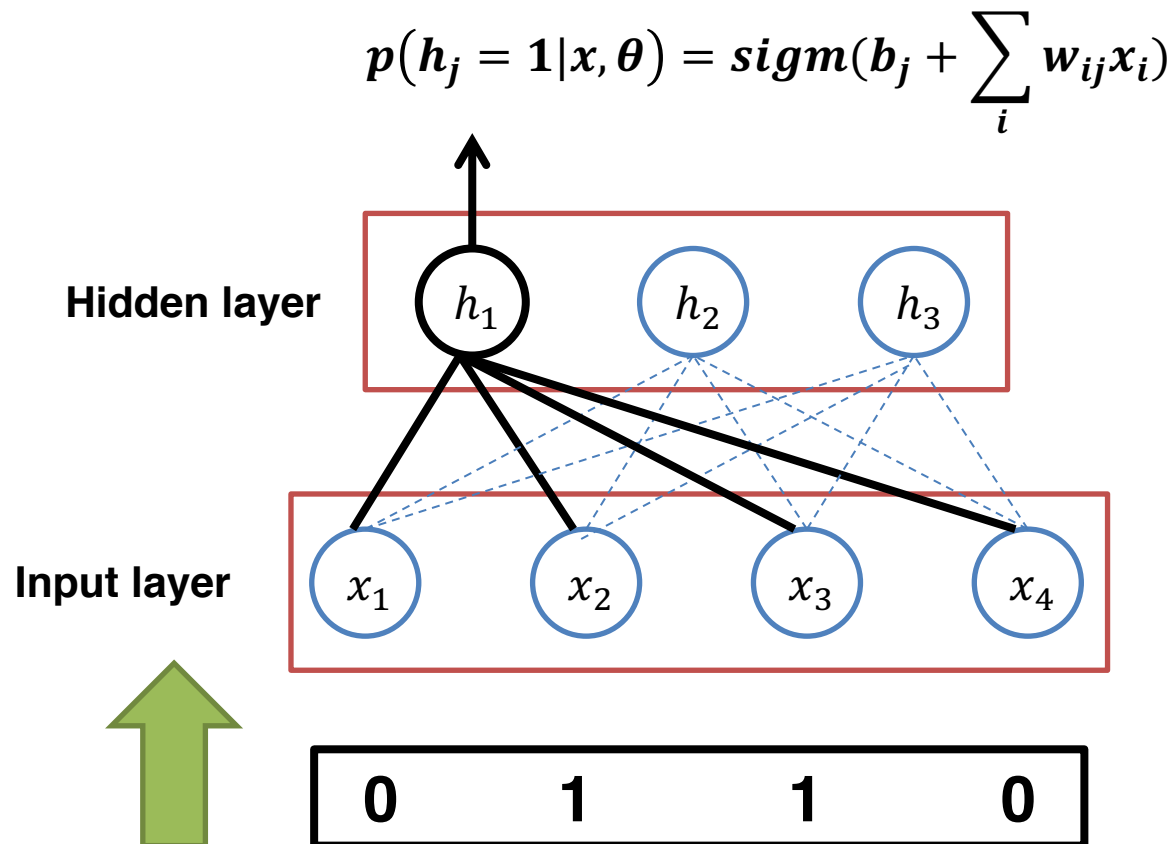
- no connection among same layer
- training procedure is much simpler than BM



# Data Generation of RBM

- Calculate latent variables

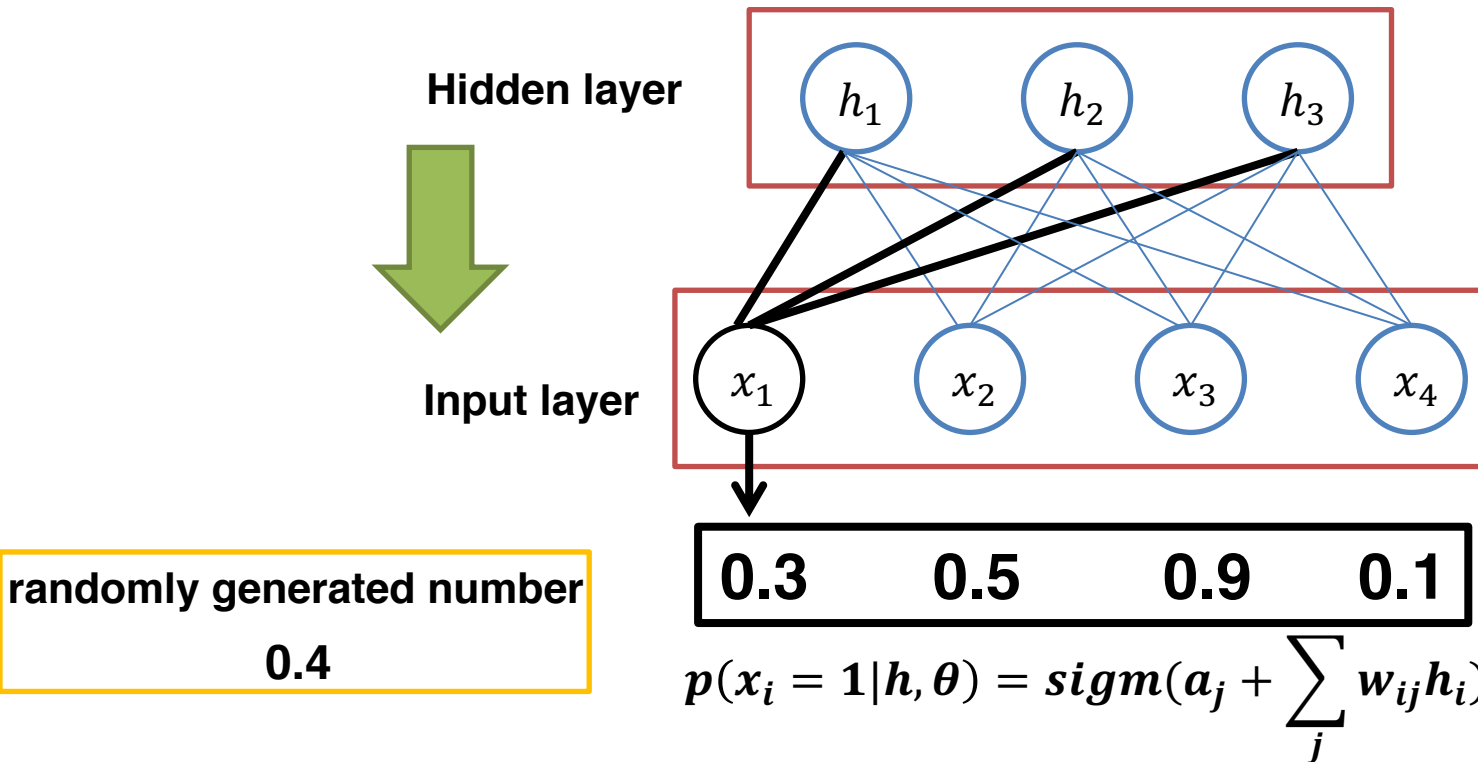
$a$  : bias of input layer  
 $b$  : bias of hidden layer  
 $w$  : weight  
 $\text{sigm}$  : sigmoid function



# Data Generation of RBM

- Calculate reconstruction value

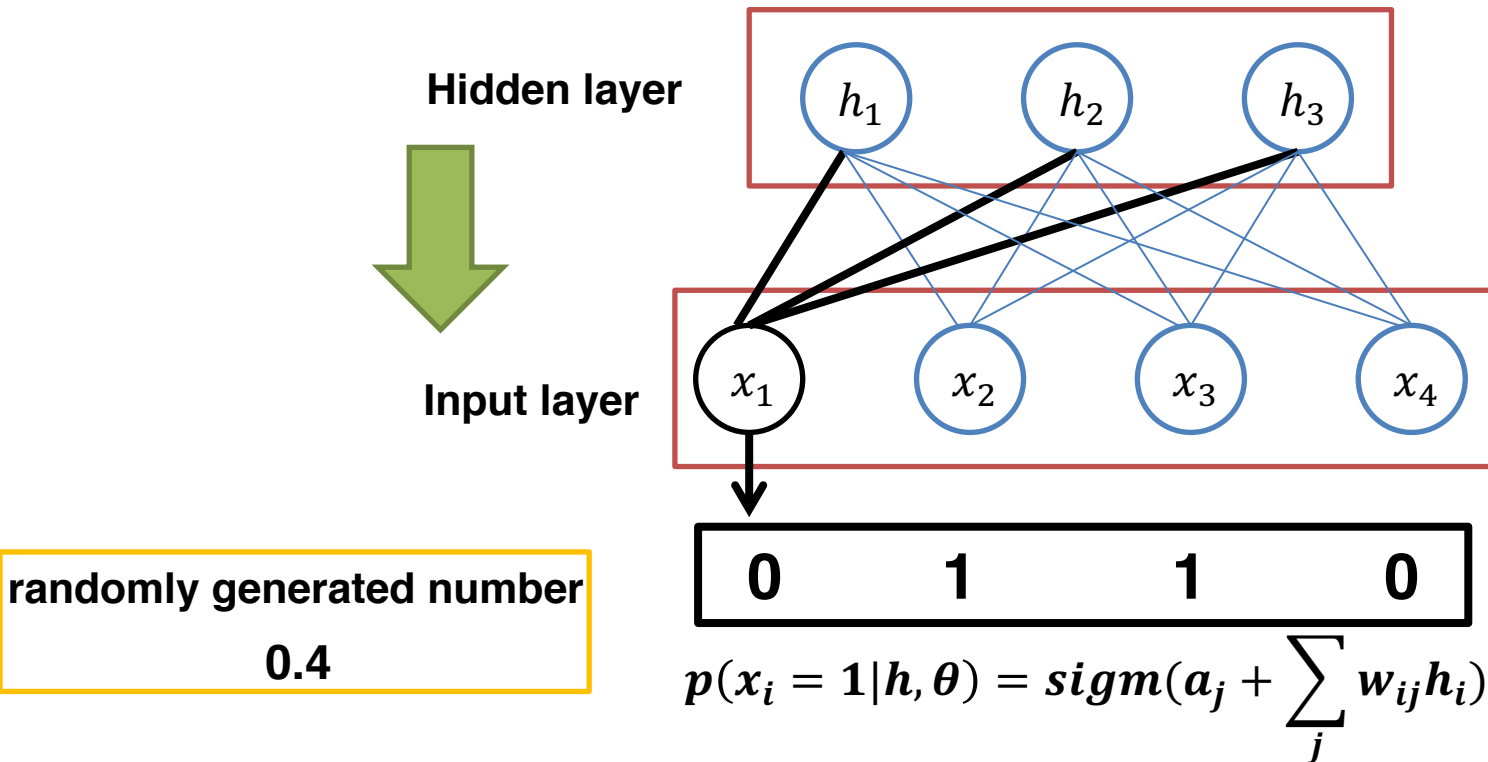
$a$  : bias of input layer  
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 $w$  : weight  
 $\text{sigm}$  : sigmoid function



# Data Generation of RBM

- Calculate reconstruction value

$a$  : bias of input layer  
 $b$  : bias of hidden layer  
 $w$  : weight  
 $\text{sigm}$  : sigmoid function



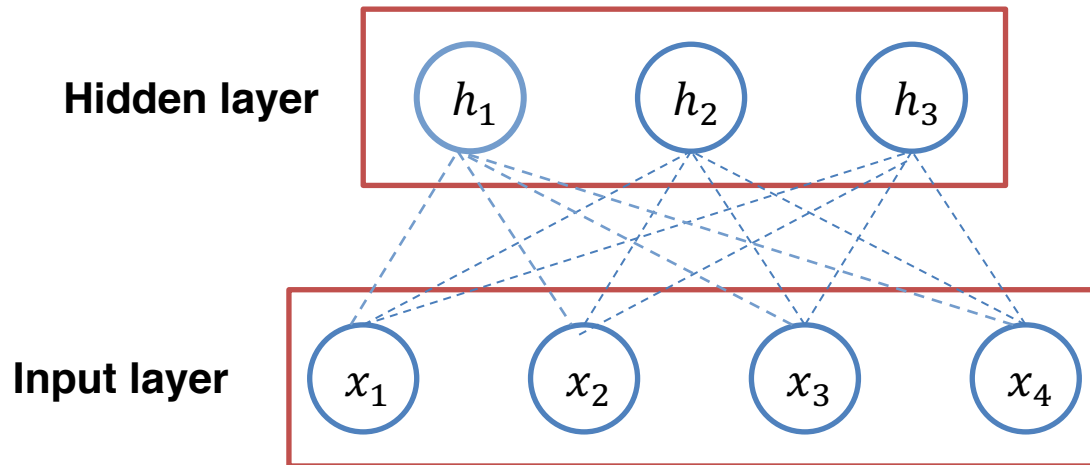


# Probability of RBM

$a$  : bias of input layer  
 $b$  : bias of hidden layer  
 $E$  : energy function  
 $Z$  : partition function

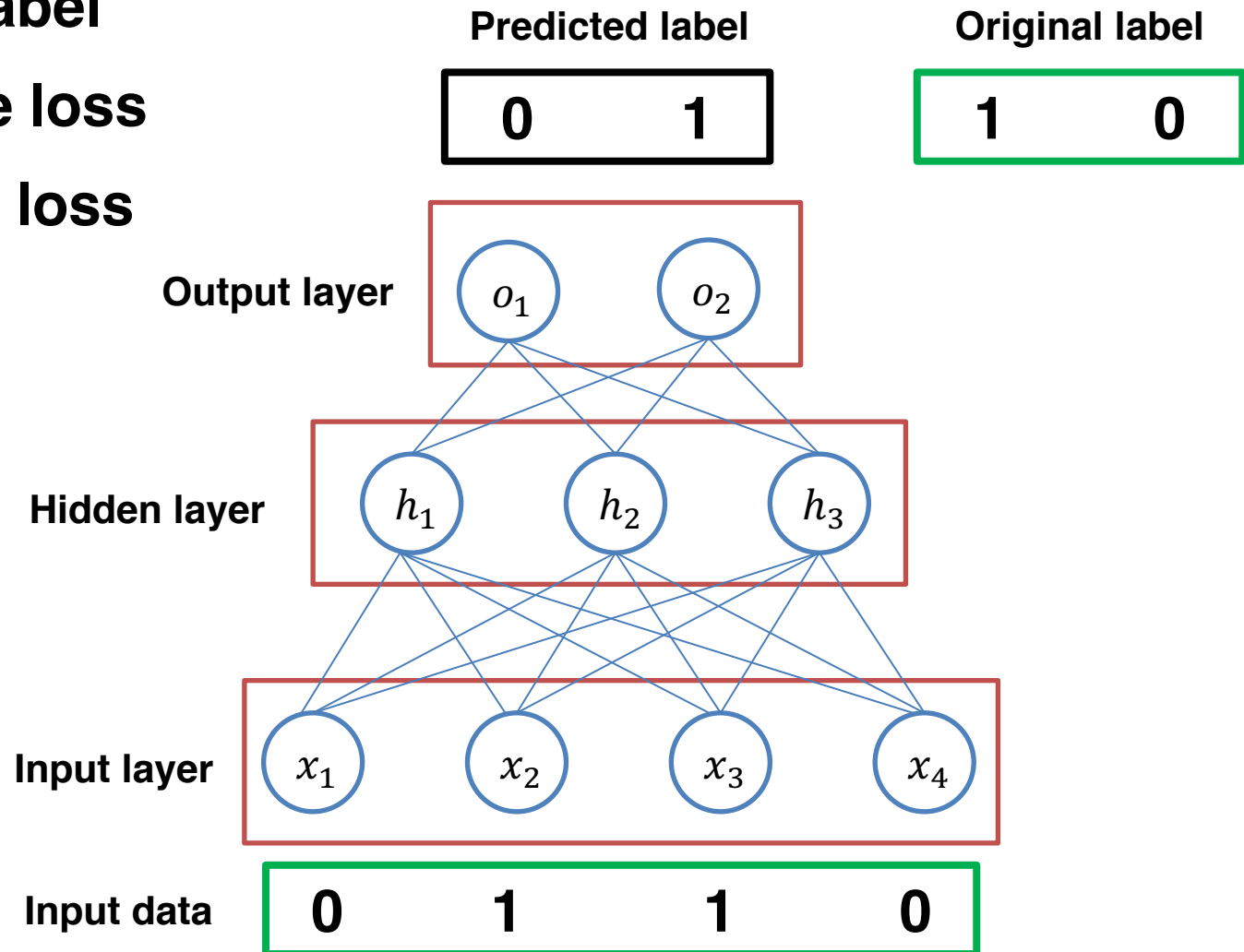
$$E = - \sum_i a_i v_i - \sum_j b_j h_j - \sum_i \sum_j w_{ij} v_i h_j$$

$$P(x) = \frac{1}{Z} \exp(-E(x))$$



# Training of Multi Layer Perceptron (MLP)

1. Predict label
2. Calculate loss
3. **Minimize** loss



# Training of Multi Layer Perceptron (MLP)

1. Predict label
2. Calculate loss
3. **Minimize** loss

$\alpha$  : *learning rate*  
 $\Delta w$  : *gradient*

- Parameter update with gradient decent

$$\Delta w_{ij} = \frac{\delta loss}{\delta w_{ij}}$$

$$w_{ij} \leftarrow w_{ij} - \alpha \cdot \Delta w_{ij}$$

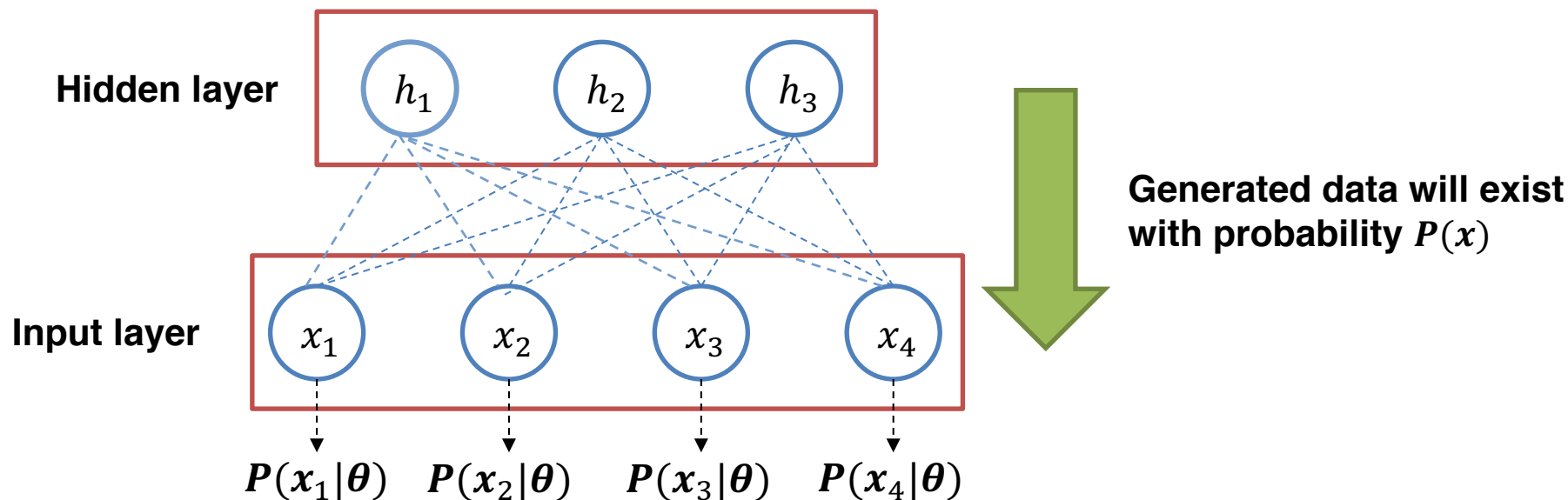
# Likelihood of RBM

$L$  : likelihood  
 $E$  : energy function  
 $Z$  : partition function

- RBM learns distribution of data by **maximizing likelihood**

$$P(x) = \frac{1}{Z} \exp(-E(x))$$

$$L(\theta) = \prod_{n=1}^N P(x_n | \theta)$$



# Training of RBM

$\alpha$  : learning rate  
 $L$  : likelihood  
 $E$  : energy function  
 $Z$  : partition function

- Probability

Difficult to calculate

$$P(x) = \frac{1}{Z} \exp(-E(x))$$

- Likelihood

$$L(\theta) = \prod_{n=1}^N P(x_n | \theta)$$

- Log likelihood

$$\log(L(\theta)) = \sum_{n=1}^N \log(P(x_n | \theta)) = \sum_{n=1}^N \{-E - \log(Z)\}$$

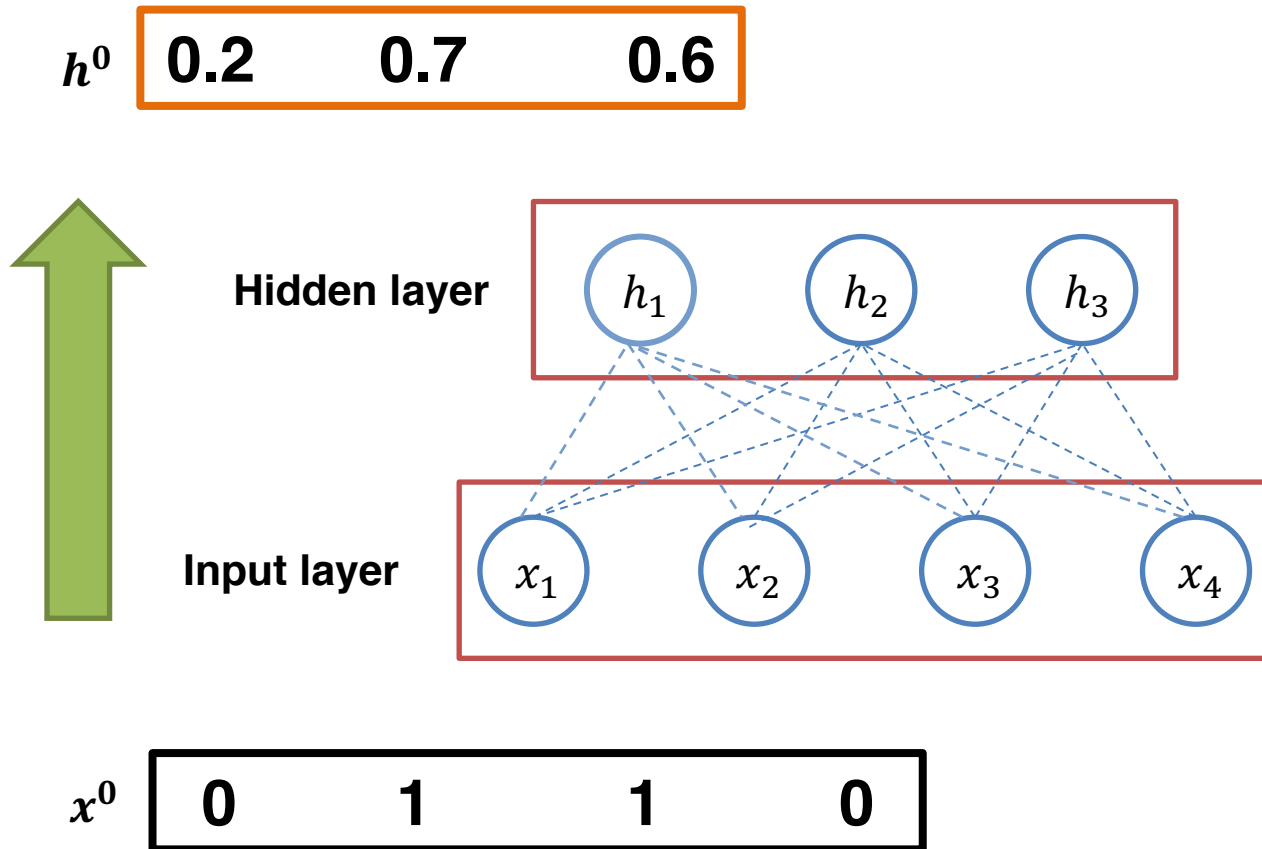
- Weight update formula

$$w_{ij} \leftarrow w_{ij} + \alpha \frac{\delta \log(L(\theta))}{\delta w_{ij}}$$

Differentiate

# Contrastive Divergence (CD)

- Approximate algorithm of training of RBM

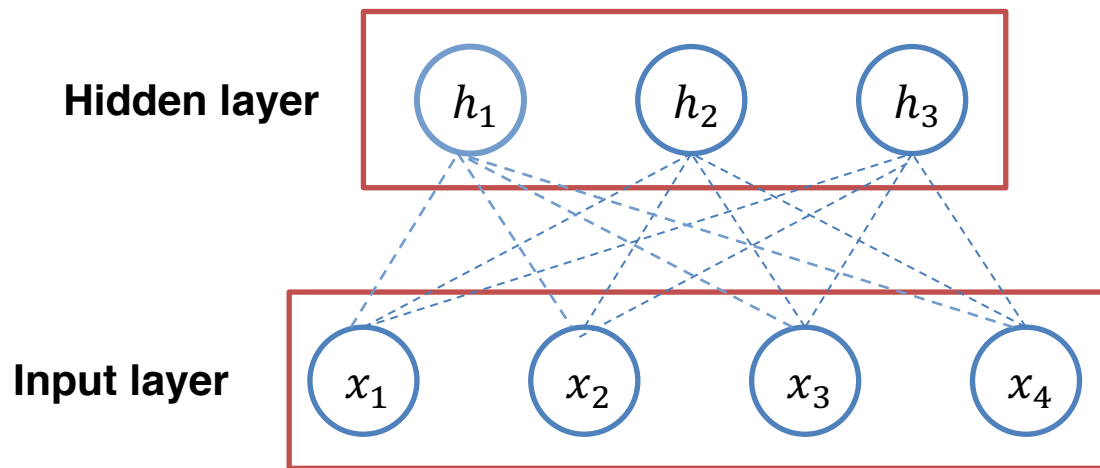


# Contrastive Divergence (CD)

- Approximate algorithm of training of RBM

$h^0$ 

0.2	0.7	0.6
-----	-----	-----



$x^0$ 

0	1	1	0
---	---	---	---

$p^1$ 

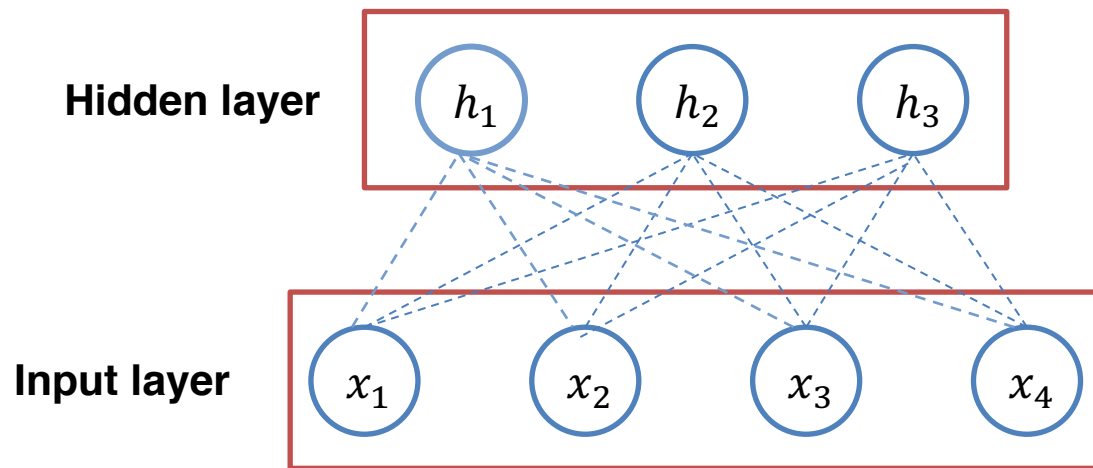
0.1	0.5	0.9	0.3
-----	-----	-----	-----

# Contrastive Divergence (CD)

- Approximate algorithm of training of RBM

$h^0$ 

0.2	0.7	0.6
-----	-----	-----



$x^0$ 

0	1	1	0
---	---	---	---

$x^1$ 

0	1	1	0
---	---	---	---



# Contrastive Divergence (CD)

- Approximate algorithm of training of RBM

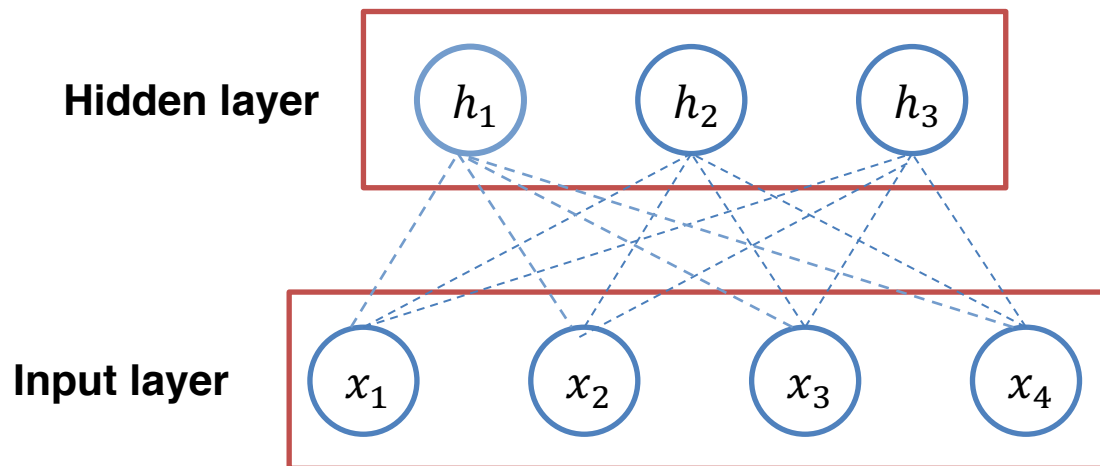
Iterate  $k$  time

$h^0$ 

0.2	0.7	0.6
-----	-----	-----

$h^1$ 

0.8	0.2	0.3
-----	-----	-----

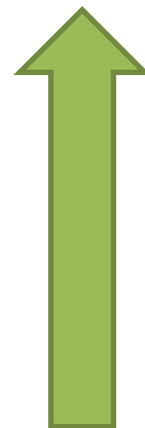


$x^0$ 

0	1	1	0
---	---	---	---

$x^1$ 

0	1	1	0
---	---	---	---



# Weight Update with CD

- Gradient of weight

$$\Delta w_{ij} = x_i^0 h_j^0 - x_i^k h_j^k$$

- Gradient of bias of input layer

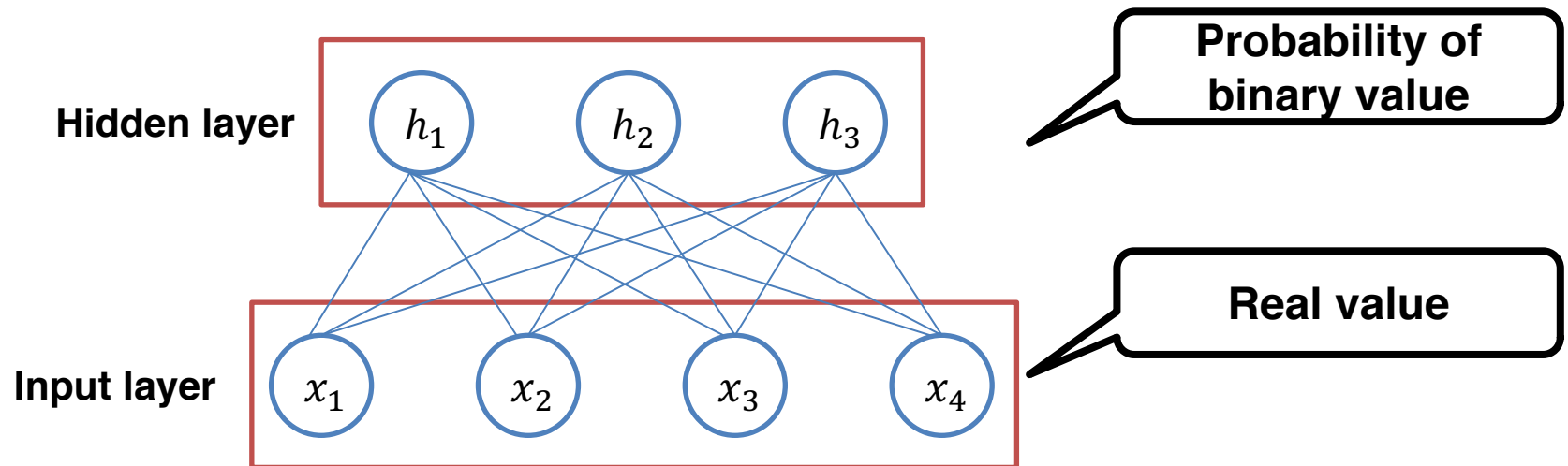
$$\Delta a_i = x_i^0 - x_i^k$$

- Gradient of bias of hidden layer

$$\Delta b_j = h_j^0 - h_j^k$$

# Boltzmann Machines for Real-Valued Data

- Gaussian-Bernoulli RBM



# Boltzmann Machines for Real-Valued Data

$\sigma$  : standard deviation

- Energy function

$$E = - \sum_i \frac{(v_i - a_i)^2}{2\sigma_i^2} - \sum_j b_j h_j - \sum_i \sum_j w_{ij} \frac{v_i}{\sigma_i} h_j$$

- Probability

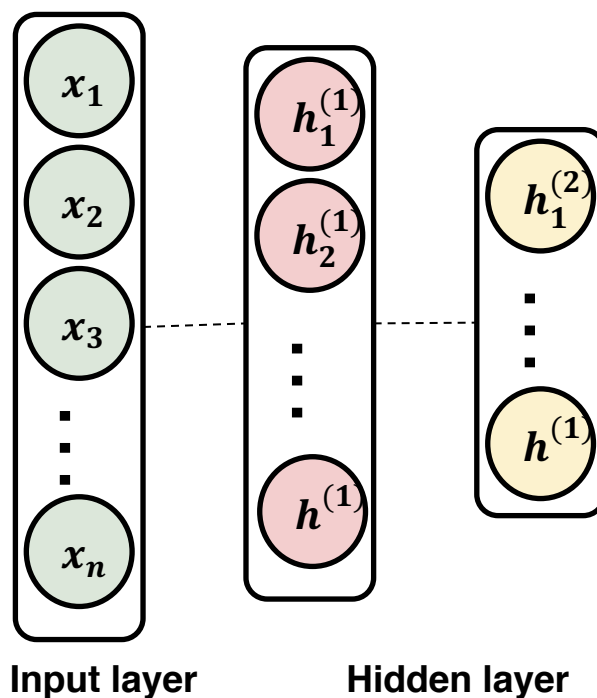
$$P(x_i|h) \propto \exp\left(-\frac{(v_i - a_i - \sum_j w_{ij} h_j)^2}{2\sigma_i^2}\right)$$

# Deep Belief Networks



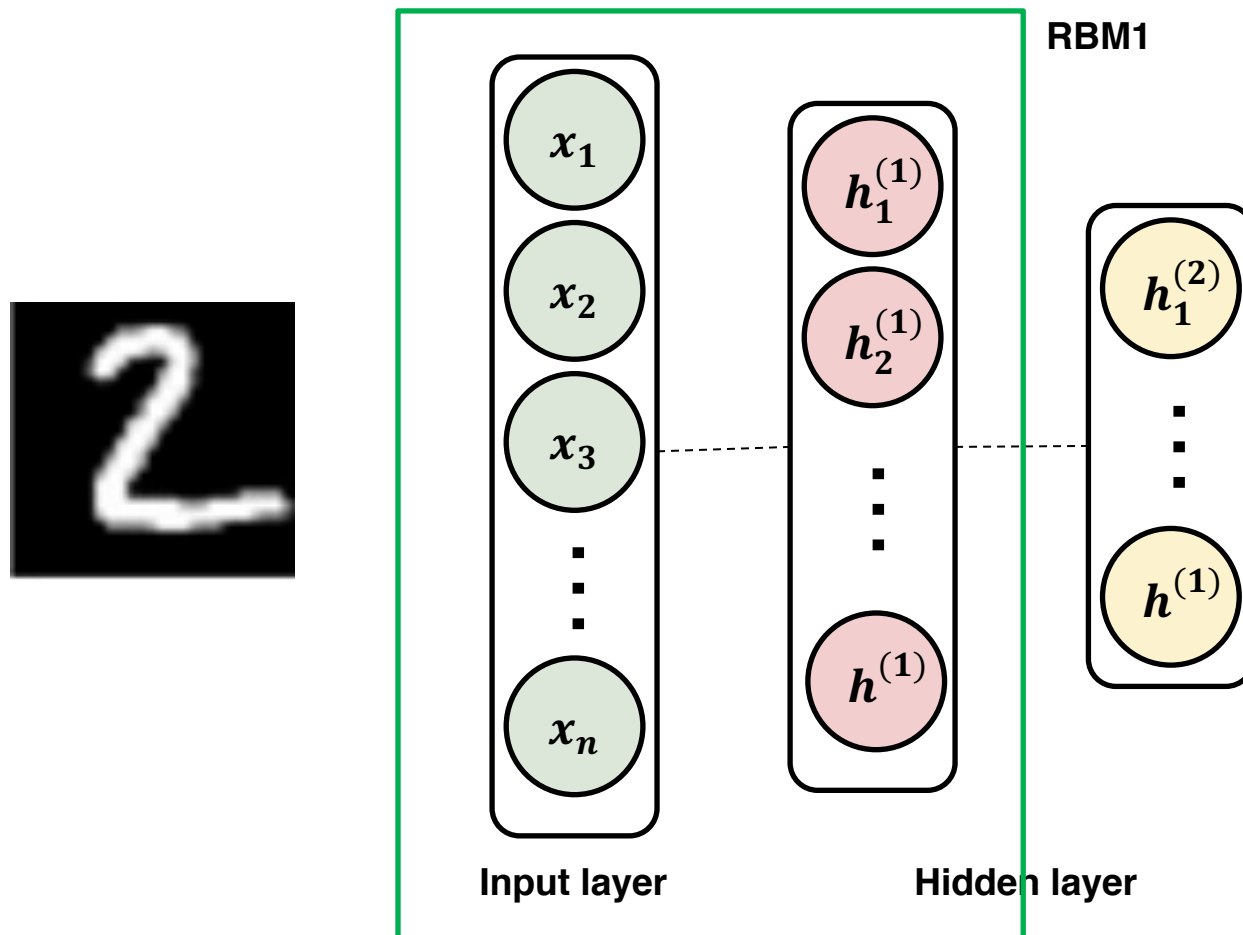
# Deep Belief Networks (DBN)

- The first non-convolutional models to successfully admit training of deep architectures (Hinton et al, 2006)



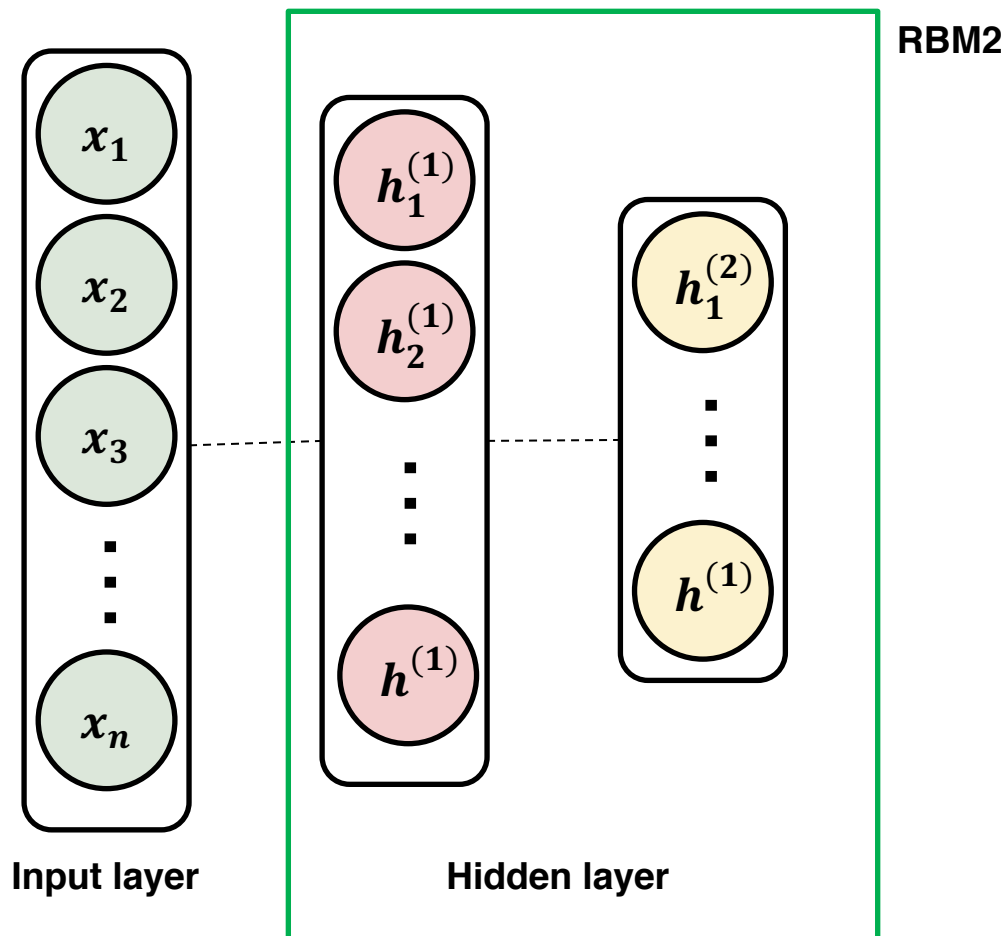
# DBN for Classification

- Layer-wise pre-training (unsupervised)



# DBN for Classification

- Layer-wise pre-training (unsupervised)





# DBN for Classification

- Fine tuning (supervised)

