KU KONKUK UNIVERSITY

Convolutional Neural Network

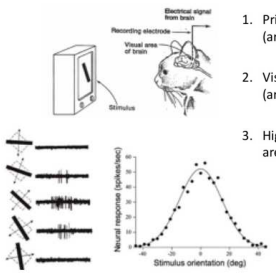
자연어처리연구실

PART-II

Convolutional Neural Network (CNN)

A bit of history:

Hubel & Wiesel,
1959
RECEPTIVE FIELDS OF SINGLE NEURONES IN THE CAT'S STRIATE CORTEX
1962
RECEPTIVE FIELDS, BINOCULAR INTERACTION AND FUNCTIONAL ARCHITECTURE IN THE CAT'S VISUAL CORTEX
1968...



1. Primary visual area (area17)
2. Visual association area (area 18 & 19)
3. Higher visual association area (area 39)

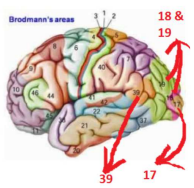


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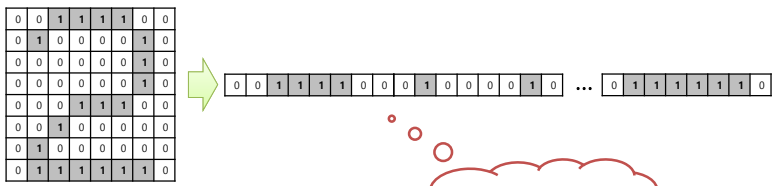
그림 출처: Fei-Fei Lee et al. 강의자료 (2016)

[실험]
고양이에게 시각자극을 제시하고 피질의 각기 다른 층에 있는 개별 신경세포의 활동을 기록
[목적]
각각의 신경세포가 무엇을 탐지하도록 전문화되어 있는 것인지를 찾아내려는 것
[발견]
고양이의 피질이 **위계적 세부 특징 탐색 회로망**으로 작동
피질의 하위층에 있는 신경세포는 단순한 세부 특징을 탐지하는 반면, 계속해서 상위층으로 올라갈수록 신경세포들은 보다 복잡한 세부 특징을 탐지함

Data Representation Problem

- Feed-Forward Neural Network (FFNN)
  - n차원 벡터를 1차원으로 변환하여 입력



Data Abstraction

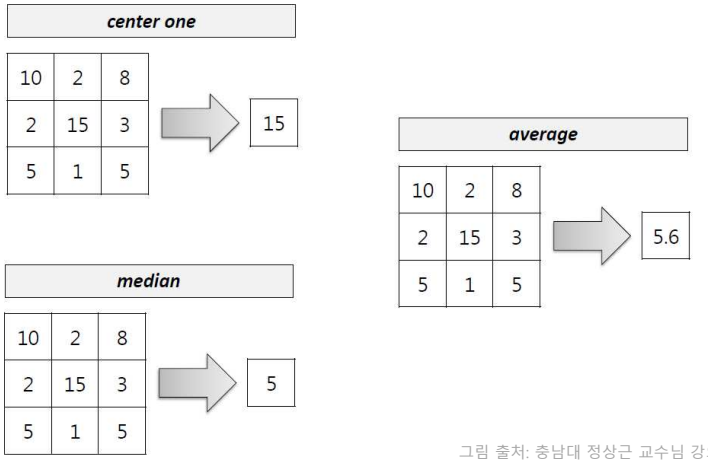


그림 출처: 충남대 정상근 교수님 강의자료

Data Abstraction

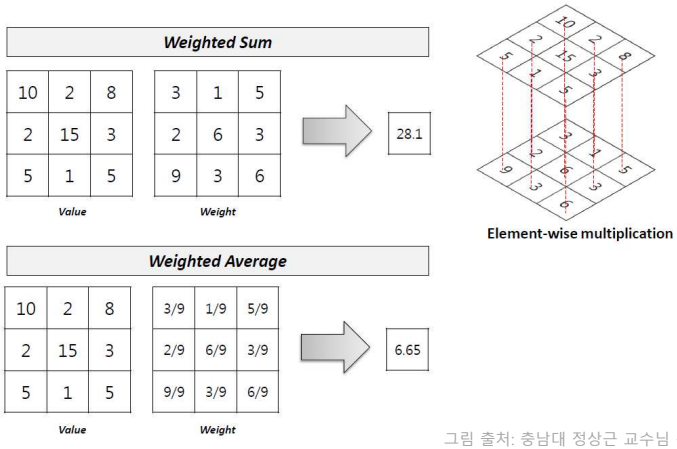
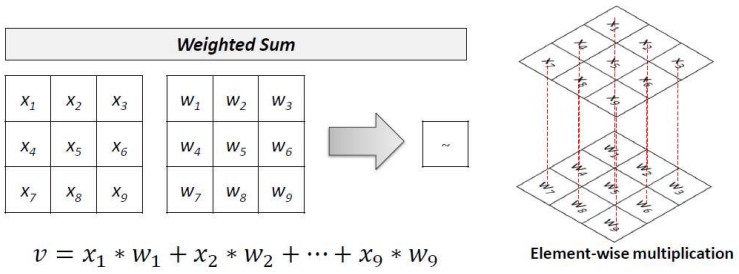


그림 출처: 충남대 정상근 교수님 강의자료

Data Abstraction



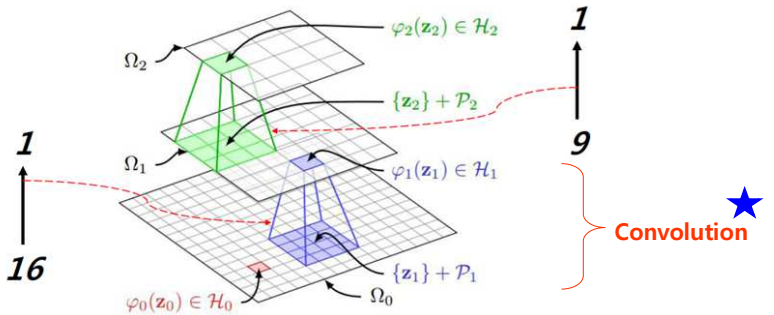
$$v = x_1 * w_1 + x_2 * w_2 + \cdots + x_9 * w_9$$

[1 x 9] matrix x [9x1] matrix = [1x1] matrix

$$\sum_i^9 x_i * w_i$$

그림 출처: 충남대 정상근 교수님 강의자료

Architecture of CNN



- Multi-layer feed-forward ANN
- Combinations of *convolutional* and fully connected layers
- Convolutional layers with *local* connectivity
- *Shared* weights across spatial positions
- Local or global pooling layers

What is Convolution?

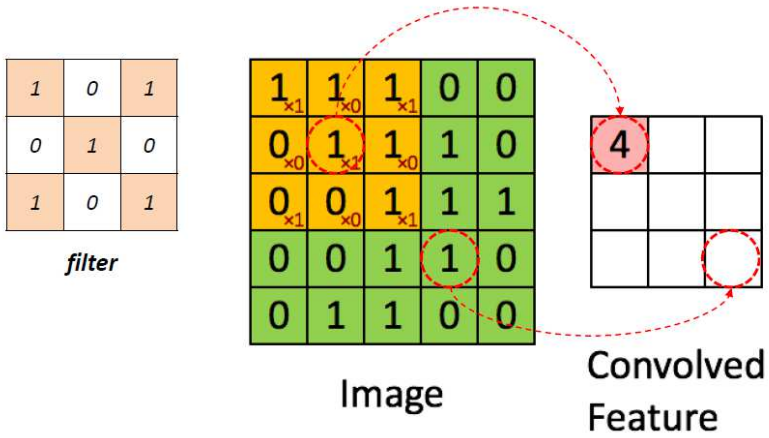


그림 출처: http://deeplearning.stanford.edu/wiki/index.php/Feature_extraction_using_convolution

Convolution Step

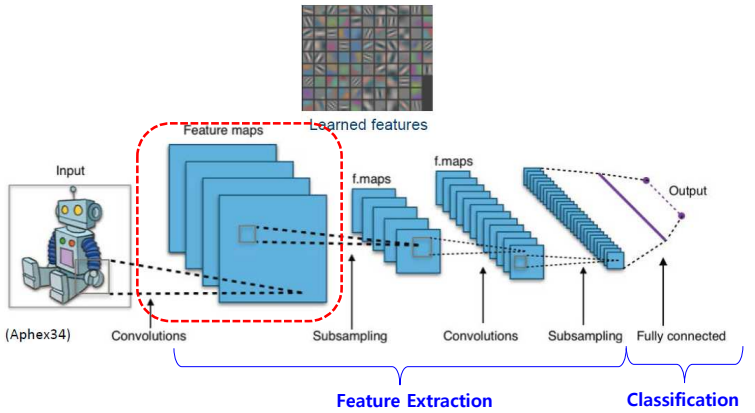


그림 출처: Nelson, Daniel. "What Are Convolutional Neural Networks?" Unite.AI, May 24, 2020. https://www.unite.ai/what-are-convolutional-neural-networks/.

Channel

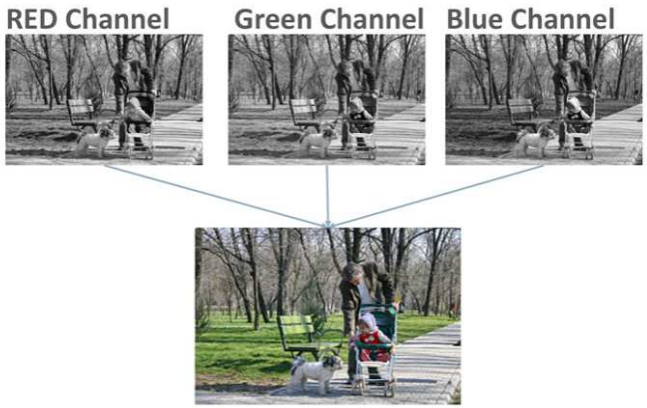
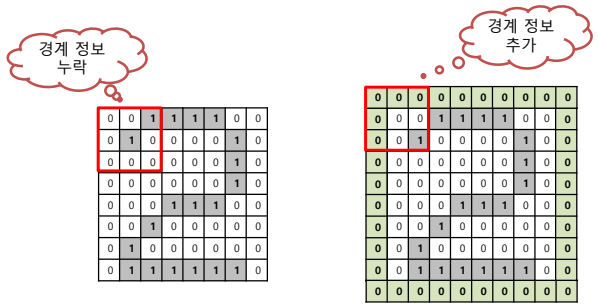


그림 출처: https://en.Wikipedia.org/wiki/Channel_(digital_image)

Padding

- 패딩
  - 경계(edge, boundary)에 대한 정보를 누락하지 않기 위해서 벡터 외부에 특정 정보를 추가하는 것



패딩 정보 추가 전 패딩 정보 추가 후

Filter (Kernel)

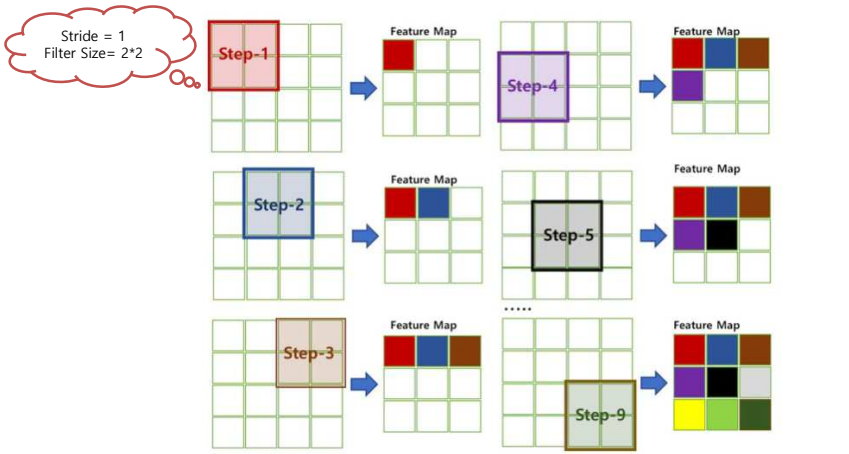


그림 출처: TAEWAN.KIM 블로그(http://taewan.kim/post/cnn/)

Feature Map

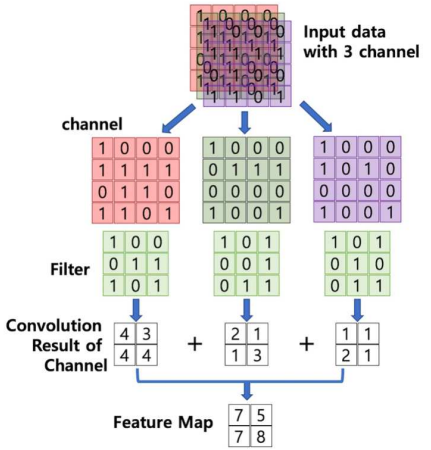


그림 출처: TAEWAN.KIM 블로그(http://taewan.kim/post/cnn/)

Subsampling (Pooling) Step

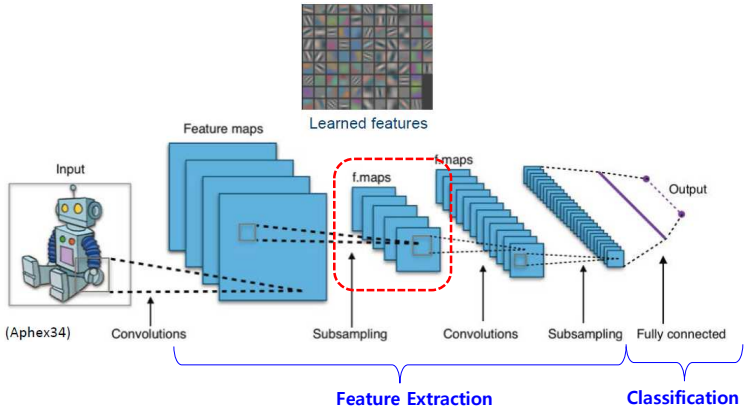
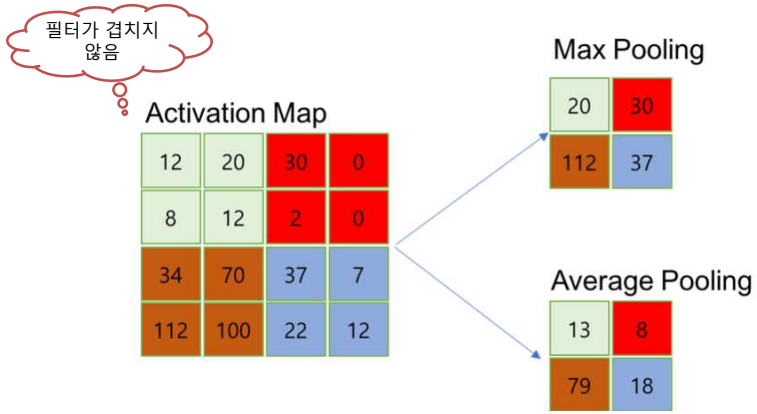


그림 출처: Nelson, Daniel. "What Are Convolutional Neural Networks?" Unite.AI, May 24, 2020. https://www.unite.ai/what-are-convolutional-neural-networks/.

Subsampling (Pooling)



참고: TAEWAN.KIM 블로그(http://taewan.kim/post/cnn/)

FNN Step

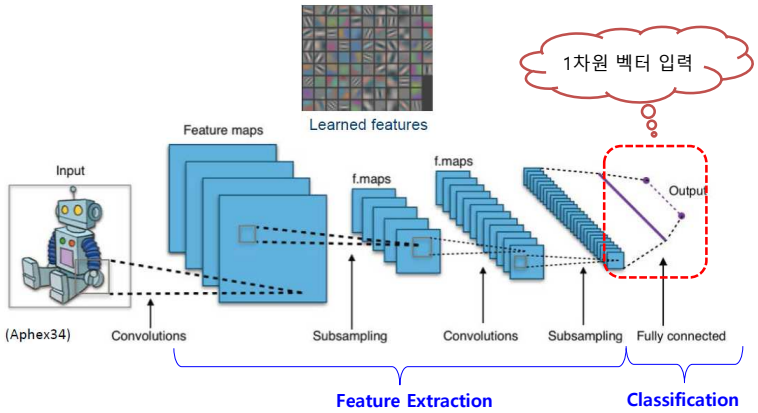
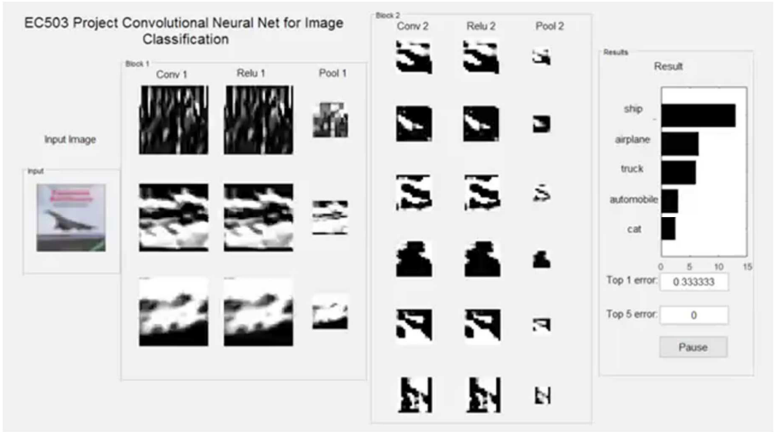


그림 출처: Nelson, Daniel. "What Are Convolutional Neural Networks?" Unite.AI, May 24, 2020. https://www.unite.ai/what-are-convolutional-neural-networks/.

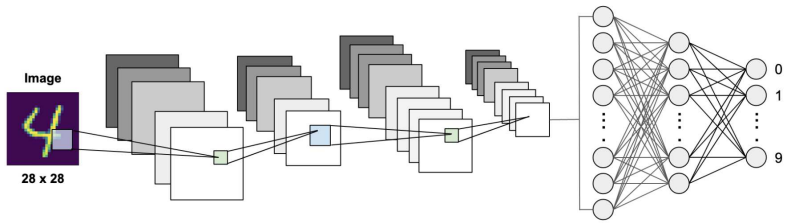
CNN 시연 영상



영상 출처: https://www.youtube.com/watch?v=bEzS-kFSi5k

MNIST by CNN

실습 코드 다운로드: https://github.com/KUNLP/Lecture



Convolution
Channel: 32
Filter: (3,3)
Stride: (1,1)
Padding: (1,1)
+
ReLU

Max Pooling
Filter: (2,2)
Stride: (2,2)

Convolution
Channel: 64
Filter: (3,3)
Stride: (1,1)
Padding: (1,1)
+
ReLU

Max Pooling
Filter: (2,2)
Stride: (2,2)

Fully-Connected NN
Input: 7*7*64
Output: 10

Shape

(28,28,1) → (28,28,32) → (14,14,32) → (14,14,64) → (7,7,64) → (10)

MNIST by CNN

```
class MNIST_CNN(nn.Module):

  def __init__(self, config):

    super(MNIST_CNN, self).__init__()

    # 첫번째 층 설계: Convolutional NN
    # (batch, 28, 28, 1) -> (batch, 28, 28, 32) -> (batch, 14, 14, 32)
    self.conv1 = nn.Sequential()
    self.conv1.add_module("conv1", nn.Conv2d(1,32,kernel_size=(3,3), stride=(1,1), padding=(1,1)))
    self.conv1.add_module("relu1", nn.ReLU())
    self.conv1.add_module("maxpool1", nn.MaxPool2d(kernel_size=(2,2), stride=(2,2)))

    # 두번째 층 설계: Convolutional NN
    # (batch, 14, 14, 32) -> (batch, 14, 14, 64) -> (batch, 7, 7, 64)
    ?

    # 세번째 층 설계: Fully-Connected NN
    # (batch, 7, 7, 64) -> (batch, 10)
    ?
    # FNN 가중치 초기화
    nn.init.xavier_uniform_(self.fnn.weight)
```

다양한 초기화 함수 존재

$$W \sim U\left(-\sqrt{\frac{6}{n_{in}+n_{out}}}, +\sqrt{\frac{6}{n_{in}+n_{out}}}\right)$$

MNIST by CNN

```python
def forward(self, input_features):

  # 첫번째 Convolution
  output = self.conv1(input_features)

  # 두번째 Convolution
  output = self.conv2(output)

  # 텐서를 1차원으로 펼치기: (batch, -1)
  # output.size(0): 배치 차원의 크기, -1: 해당 차원은 파이토치가 알아서 설정
  output = output.view(output.size(0), -1)
  hypothesis = self.fnn(output)

  return hypothesis
```

Hypothesis 만들기

MNIST by CNN

MLP 1차원 입력 (batch, 28*28)

```python
# 데이터 읽기 함수
def load_dataset():

  (train_X, train_y), (test_X, test_y) = mnist.load_data()
  print(train_X.shape) # (60000, 28, 28)
  print(train_y.shape) # (60000,10)
  print(test_X.shape) # (10000, 28, 28)
  print(test_y.shape) # (10000,10)

  train_X = train_X.reshape(-1, 28*28)
  print(train_X.shape)
  test_X  = test_X.reshape(-1, 28*28)

  train_X = torch.tensor(train_X, dtype=torch.float)
  train_y = torch.tensor(train_y, dtype=torch.long)
  test_X = torch.tensor(test_X, dtype=torch.float)
  test_y = torch.tensor(test_y, dtype=torch.long)

  return (train_X, train_y), (test_X, test_y)
```

CNN 3차원 입력 (batch, 1, 28, 28)

```python
# 데이터 읽기 함수
def load_dataset():

  (train_X, train_y), (test_X, test_y) = mnist.load_data()
  print(train_X.shape) # (60000, 28, 28)
  print(train_y.shape) # (60000,10)
  print(test_X.shape) # (10000, 28, 28)
  print(test_y.shape) # (10000,10)

  # 채널 추가
  train_X = train_X.reshape(-1, 1, 28, 28)
  test_X  = test_X.reshape(-1, 1, 28, 28)
  print(train_X.shape)
  print(test_X.shape)

  train_X = torch.tensor(train_X, dtype=torch.float)
  train_y = torch.tensor(train_y, dtype=torch.long)
  test_X = torch.tensor(test_X, dtype=torch.float)
  test_y = torch.tensor(test_y, dtype=torch.long)

  return (train_X, train_y), (test_X, test_y)
```

채널 1개 추가

MNIST by CNN

```python
# 모델 평가 함수
def test(config):
  ?
  # 저장된 모델 가중치 로드
  model.load_state_dict(torch.load(os.path.join(config["output_dir"], config["model_name"])))
```

```python
# 모델 학습 함수
def train(config):
  ?

  # 데이터 읽기
  (input_features, labels), (_, _) = load_dataset()

  # TensorDataset/DataLoader를 통해 배치(batch) 단위로 데이터를 나누고 셔플(shuffle)
  train_features = TensorDataset(input_features, labels)
  train_dataloader = DataLoader(train_features, shuffle=True, batch_size=config["batch_size"])
```


MNIST by CNN

```python
if(__name__=="__main__"):

    root_dir = "/gdrive/My Drive/colab/cnn/mnist"
    output_dir = os.path.join(root_dir, "output")
    if not os.path.exists(output_dir):
        os.makedirs(output_dir)

    config = {"mode": "train",
              "model_name":"epoch_{0:d}.pt".format(10),
              "output_dir":output_dir,
              "learn_rate":0.001,
              "batch_size":32,
              "epoch":10,
              }

    if(config["mode"] == "train"):
        train(config)
    else:
        test(config)
```

학습

```
(60000, 28, 28)
(60000,)
(10000, 28, 28)
(10000,)
(60000, 1, 28, 28)
(10000, 1, 28, 28)
Average Loss= 0.425261
PRED= [3, 2, 7, 0, 8, 4, 6, 8, 1, 6, 7
GOLD= [3, 2, 7, 0, 8, 4, 9, 8, 1, 6, 7
Accuracy= 0.972583

Average Loss= 0.093104
PRED= [2, 2, 1, 0, 4, 5, 7, 7, 1, 4, 1
GOLD= [2, 2, 1, 0, 4, 5, 7, 7, 1, 4, 1
Accuracy= 0.977567
```

평가

```
(60000, 28, 28)
(60000,)
(10000, 28, 28)
(10000,)
(60000, 1, 28, 28)
(10000, 1, 28, 28)
PRED= [1, 6, 1, 6, 4, 4, 7, 5, 2, 8,
GOLD= [1, 6, 1, 6, 4, 4, 7, 5, 2, 8,
Accuracy= 0.983900
```

질의응답

Q&A

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