

Sciences

Lab 11

(Operating Systems)

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Topic	Semaphores
Semester	Spring 2023 to onwards

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Semaphores

Header Files:

• #include <semaphores.h>

Datatype for Semaphore variables:

```
• sem t
```

Methods for handling semaphores:

```
int sem_init (sem_t *sem, int pshared, unsigned int value);
int sem_wait(sem_t *sem);
int sem_post(sem_t *sem);
```

Previous Knowledge:

Note: We use wait before signal when our semaphore variable (S) is initialed to 1. If it is initialized to 0 then we have to use signal before wait.

Usage:

```
sem_t S;

// 2<sup>nd</sup> Argument: 0 for thread sync. And Non Zero value for process sync
// 3<sup>rd</sup> Argument: Initial value for semaphore variable
sem init(&S, 0, 1);
```

Thread 1	Thread 2
worker1(){ sem_wait(&S); CRITICAL SECTION sem_post(&S) }	worker2(){ sem_wait(&S); CRITICAL SECTION sem_post(&S) }

Example Program with 2 Threads without synchronization:

```
#include <stdio.h>
#include <pthread.h>
#include <stdlib.h>
#include <unistd.h>
#include <semaphore.h>
void *worker1();
void *worker2();
int shared_variable = 10;
int main(int argc, char *argv[])
  pthread_t thread1, thread2;
  pthread_create(&thread1, NULL, worker1, NULL);
  pthread_create(&thread2, NULL, worker2, NULL);
  pthread_join(thread1, NULL);
  pthread_join(thread2, NULL);
  return 0;
void *worker1()
  int x = shared_variable;
  printf("WORKER1 - Before updation - Shared Variable: %d and x: %d\n", shared_variable, x);
  x++;
  shared_variable = x;
  printf("WORKER1 - After updation - Shared Variable: %d and x: %d\n", shared_variable, x);
void *worker2()
  int y = shared_variable;
  printf("WORKER2 - Before updation - Shared Variable: %d and y: %d\n", shared_variable, y);
  y += 10;
  shared_variable = y;
  printf("WORKER2 - After updation - Shared Variable: %d and y: %d\n", shared_variable, y);
```

Output:

```
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$ gcc main.c —o main —lpthread
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$ ./main
WORKER1 - Before updation - Shared Variable: 10 and x: 10
WORKER1 - After updation - Shared Variable: 11 and x: 11
WORKER2 - Before updation - Shared Variable: 11 and y: 11
WORKER2 - After updation - Shared Variable: 21 and y: 21
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$ ./main
WORKER1 - Before updation - Shared Variable: 10 and x: 10
WORKER1 - After updation - Shared Variable: 11 and x: 11
WORKER2 - Before updation - Shared Variable: 10 and y: 10
WORKER2 - After updation - Shared Variable: 20 and y: 20
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$ ./main
WORKER1 - Before updation - Shared Variable: 10 and x: 10
WORKER1 - After updation - Shared Variable: 11 and x: 11
WORKER2 - Before updation - Shared Variable: 10 and y: 10
WORKER2 - After updation - Shared Variable: 20 and y: 20
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$ ./main
WORKER1 - Before updation - Shared Variable: 10 and x: 10
WORKER1 - After updation - Shared Variable: 10 and x: 10
WORKER2 - Before updation - Shared Variable: 10 and y: 10
WORKER2 - After updation - Shared Variable: 20 and y: 20
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WORKER1 - Before updation - Shared Variable: 10 and x: 10
WORKER1 - After updation - Shared Variable: 11 and x: 11
WORKER2 - Before updation - Shared Variable: 10 and y: 10
WORKER2 - After updation - Shared Variable: 20 and y: 20
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WORKER1 - Before updation - Shared Variable: 10 and x: 10
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WORKER2 - Before updation - Shared Variable: 11 and y: 11
WORKER2 - After updation - Shared Variable: 21 and y: 21
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$ ./main
WORKER1 - Before updation - Shared Variable: 10 and x: 10
WORKER1 - After updation - Shared Variable: 11 and x: 11
WORKER2 - Before updation - Shared Variable: 11 and y: 11
WORKER2 - After updation - Shared Variable: 21 and y: 21
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$ ./main
```

You can see how we get non-consistent results each time we run the program, without synchronization. Our program's threads are suffering from race condition.

Example Program with 2 Threads with synchronization:

```
#include <stdio.h>
#include <pthread.h>
#include <stdlib.h>
#include <unistd.h>
#include <semaphore.h>

void *worker1();
void *worker2();

int shared_variable = 10;
sem_t semaphore_variable;

int main(int argc, char *argv[])
```

```
sem_init(&semaphore_variable, 0, 1);
  pthread_t thread1, thread2;
  pthread_create(&thread1, NULL, worker1, NULL);
  pthread_create(&thread2, NULL, worker2, NULL);
  pthread_join(thread1, NULL);
  pthread_join(thread2, NULL);
  return 0;
void *worker1()
  sem_wait(&semaphore_variable);
  int x = shared_variable;
  printf("WORKER1 - Before updation - Shared Variable: %d and x: %d\n", shared_variable, x);
  X++;
  shared_variable = x;
  printf("WORKER1 - After updation - Shared Variable: %d and x: %d\n", shared_variable, x);
  sem_post(&semaphore_variable);
void *worker2()
  sem_wait(&semaphore_variable);
  int y = shared_variable;
  printf("WORKER2 - Before updation - Shared Variable: %d and y: %d\n", shared_variable, y);
  y += 10;
  shared_variable = y;
  printf("WORKER2 - After updation - Shared Variable: %d and y: %d\n", shared_variable, y);
  sem_post(&semaphore_variable);
```

Output:

```
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$ gcc main.c -o main -lpthread
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$ ./main
WORKER1 - Before updation - Shared Variable: 10 and x: 10
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WORKER1 - After updation - Shared Variable: 11 and x: 11
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WORKER2 - After updation - Shared Variable: 21 and y: 21
irtiza@Irtiza:/mnt/c/Users/m7irt/OneDrive/Desktop$
```

Now each time we run the program, we get consistent results.

Question # 1 (10 Marks) Take X, Y, Z, W from the user. Use semaphore to implement the

following Program:

```
      Thread T1
      Thread T2

      Input (X,Y):
      Input (W,Z):

      X1= Z+2;
      Z1= X1*2;

      Y1=Z1*5;
      W1=Y1+5;

      S1=X1+Y1;
      S2=Z1+W1;

      Printf("x=%d",S1);
      Printf("x=%d",S2);
```