





# Lecture 0: Lesson Plan

Robotics

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#### Outlines

- Introduction
- Spatial Descriptions and Transformations
- Kinematics; Forward & Inverse
- Jacobians: Velocities and Static Forces
- Dynamics

### References

1	Introduction to Robotics: Mechanics and Control	J.J. Craig	INTRODUCTION TO ROBOTICS MEGILINICS AND CONTROL PHIND EXTENN  JOHN J. CRAIG.
2	Robot Modeling and Control	M.W. Spong, S. Hutchinson, M. Vidyasagar	ROBOT MODELING AND CONTROL  Mark W. Spong   Seth Hatchinson   M. Vidyasagar
3	Modelling and Control of Robot Manipulators	L. Sciavicco B. Siciliano	Bruno Siciliano Lorenzo Sciavicco Lugi Villari Giuseppe Oriolo  Robotics  Modelling, Planning and Control

### Evaluation

1	Midterm Exam	30 %	6 Points
2	Final Exam	35 %	7 Points
3	Projects	20 %	4 Points
4	Homework	10 %	2 Points
5	Quiz	5 %	1 Point

## The END

• References:

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