

Grundlagen der künstlichen Intelligenz – Logical Agents

Matthias Althoff

TU München

KI_11/7

November 07, 2019

KI_11/15

Organization

- 1 The Wumpus World
- 2 Logic
- 3 Propositional Logic
- 4 Propositional Theorem Proving
 - Proof by Resolution
 - Proof of Horn Clauses

The content is covered in the AI book by the section “Logical Agents”.

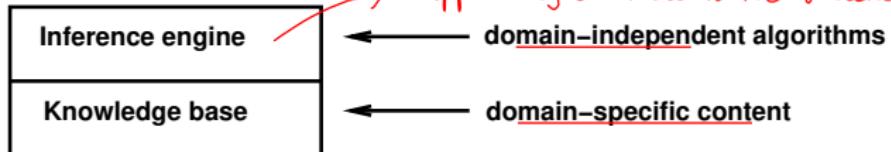
Learning Outcomes

Exam - related

- You understand the difference between a knowledge base and an inference engine.
- You understand the difference between syntax, semantics, and models.
- You understand the difference between satisfaction and entailment.
- You can create and evaluate sentences in propositional logic.
- You can create truth tables of sentences in propositional logic.
- You can apply inference by enumeration.
- You understand the concepts logical equivalence, validity, and satisfiability.
- You can systematically apply theorem proving given a set of inference rules.
- You can apply proof by resolution.
- You can convert a sentence in propositional logic into conjunctive normal form.
- You can prove correctness of Horn clauses by forward chaining and backward chaining.

Knowledge Base

A **knowledge base** is a set of sentences in a formal language.



* Possibilities to gain knowledge:

- **Inference**: Makes it possible to derive new knowledge from old knowledge.
- **Declarative approach**: New knowledge is added from “outside” by providing knowledge.
- **Perception**: New knowledge is added by the agent from its own perception.

Agents can be viewed at the

- **knowledge level**: what they know, regardless of how implemented;
- **implementation level**: data structures in the knowledge base and algorithms that manipulate them.

The Wumpus World

We introduce the Wumpus world to demonstrate the benefits of knowledge (note that the previous search algorithms do not need knowledge).

- Cave consisting of rooms connected by passageways.
- Lurking somewhere is the terrible Wumpus, who eats anyone who enters his room.
- You have one arrow to shoot him before finding a heap of gold.

4	Stench		Breeze	PIT
3	Wumpus	Breeze Stench Gold	PIT	Breeze
2	Stench		Breeze	
1	START	Breeze	PIT	Breeze
	1	2	3	4

Tweedback Questions

Does a pure search technique exist so that we arrive at the gold without getting killed by Wumpus? Under all circumstances

No, because you can not know for sure where Wumpus.

Wumpus World PEAS description

- **Performance measure:**

gold +1000, death -1000
 -1 per step, -10 for using the arrow

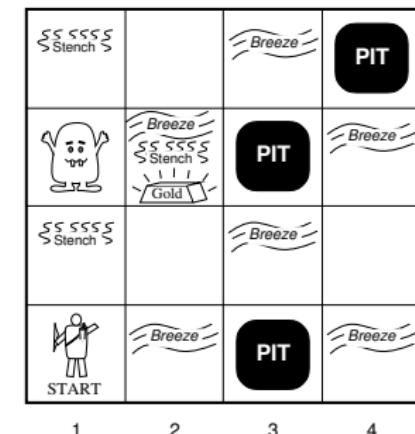
- **Environment:**

- Squares adjacent to Wumpus are smelly
- Squares adjacent to pits are breezy
- Glitter iff gold is in the same square
- Shooting kills Wumpus if you are facing it
- Shooting uses up the only arrow
- Grabbing picks up gold if in same square
- Releasing drops the gold in same square

- **Actuators:** left turn, right turn,

forward, grab, release, shoot

- **Sensors:** breeze, glitter, smell



Wumpus World Characterization

- **Observable:** No – only local perception.
we only see our current square
- **Deterministic:** Yes – outcomes are exactly specified.
- **Episodic:** No – sequential since actions change the environment.
- **Static:** Yes – Wumpus and pits do not move.
- **Discrete:** Yes.
- **Single-agent:** Yes – Wumpus is essentially a natural feature.

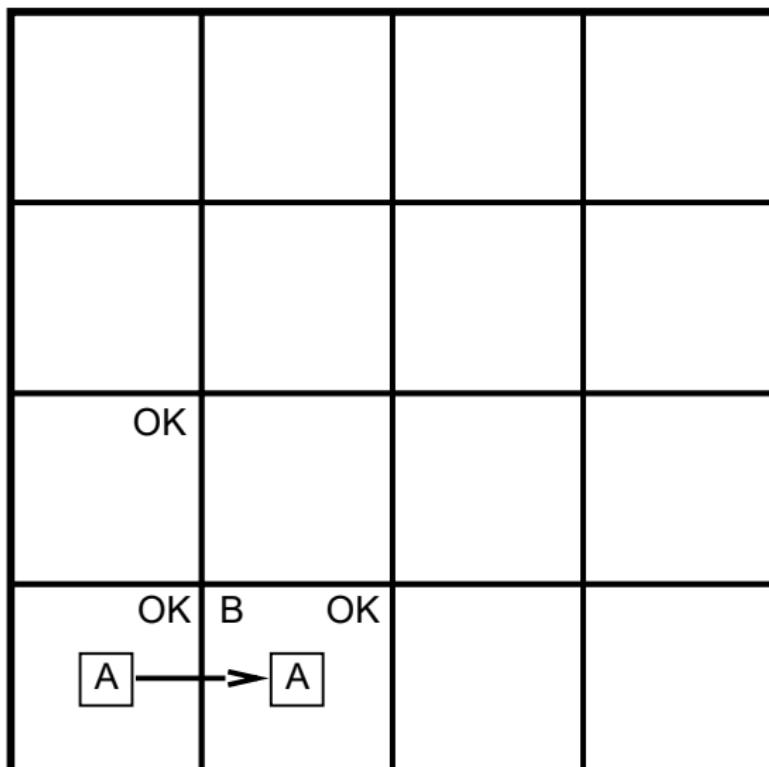
The main challenge is the initial ignorance of the environment; overcoming this ignorance seems to require logical reasoning.

Exploring a Wumpus World (1)

OK			
OK	OK		

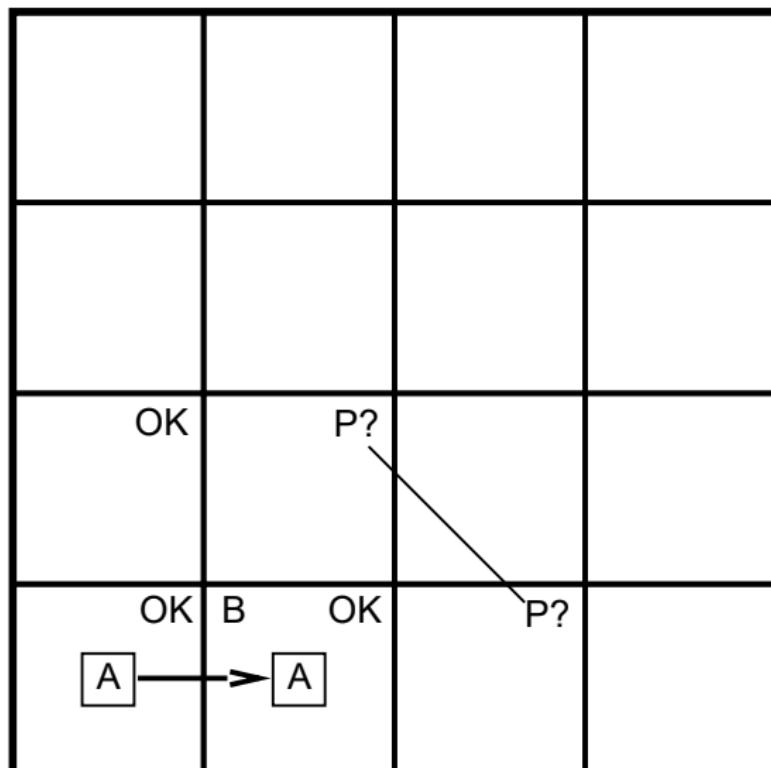
B: breeze,
S: stench,
G: glitter,
A: agent,
P: pit,
W: Wumpus,
OK: safe square.

Exploring a Wumpus World (2)



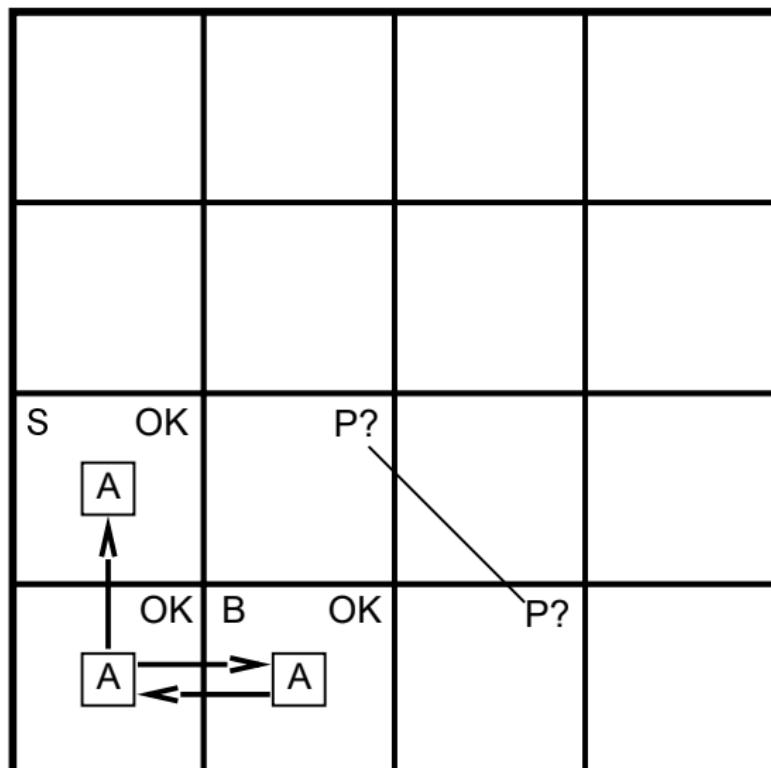
B: breeze,
S: stench,
G: glitter,
A: agent,
P: pit,
W: Wumpus,
OK: safe square.

Exploring a Wumpus World (3)



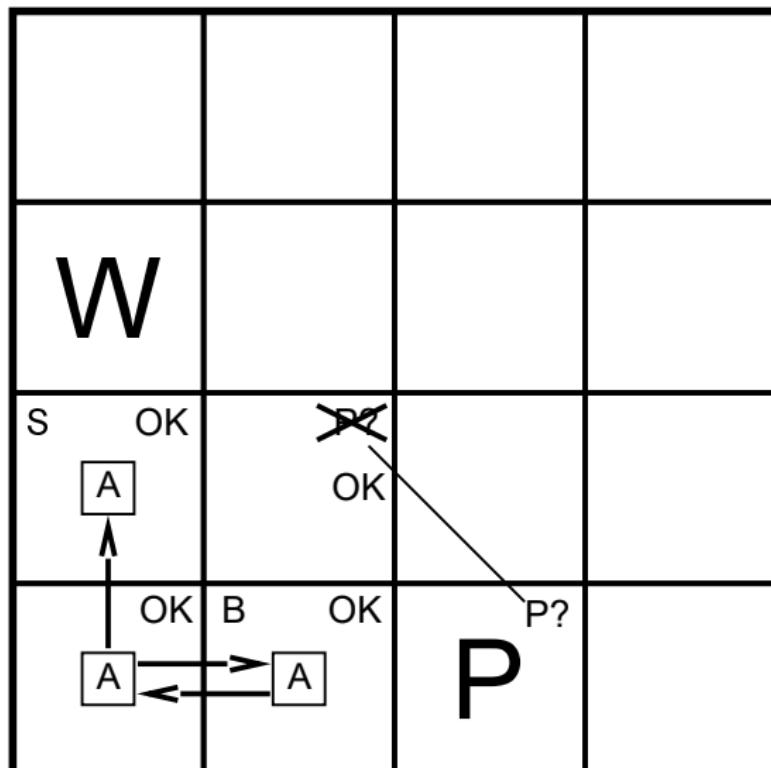
B: breeze,
S: stench,
G: glitter,
A: agent,
P: pit,
W: Wumpus,
OK: safe square.

Exploring a Wumpus World (4)



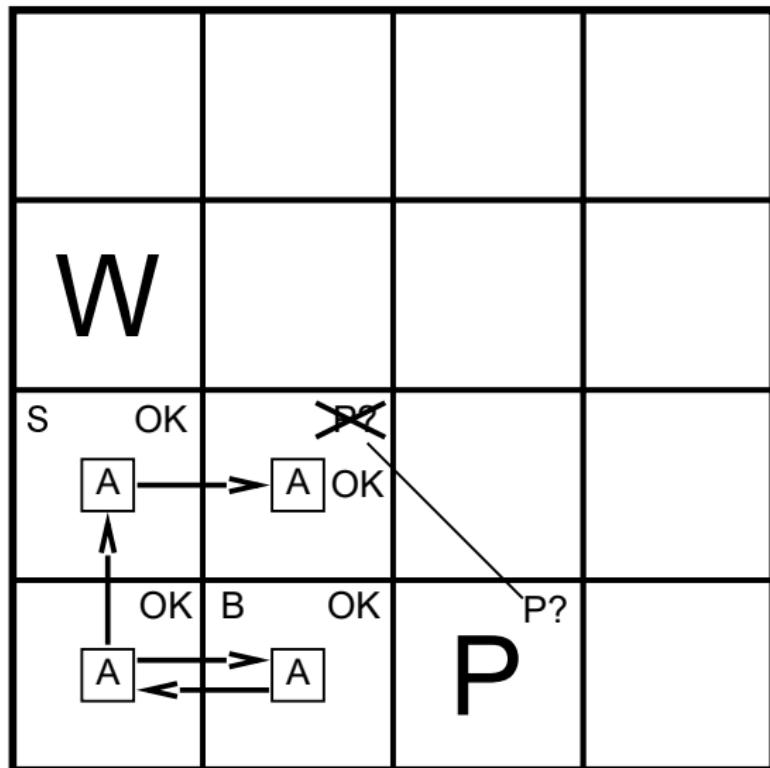
B: breeze,
S: stench,
G: glitter,
A: agent,
P: pit,
W: Wumpus,
OK: safe square.

Exploring a Wumpus World (5)



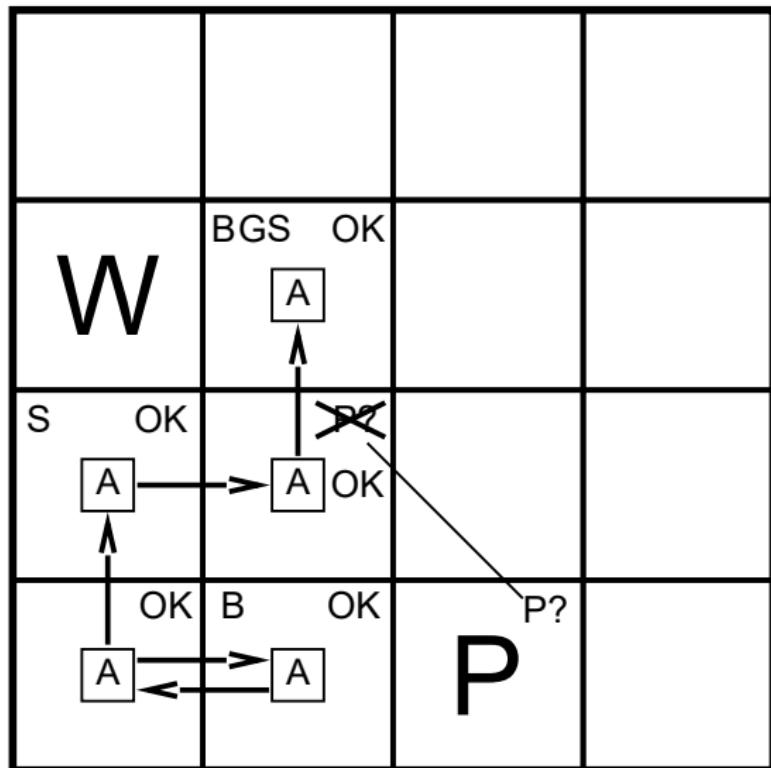
B: breeze,
S: stench,
G: glitter,
A: agent,
P: pit,
W: Wumpus,
OK: safe square.

Exploring a Wumpus World (6)



B: breeze,
S: stench,
G: glitter,
A: agent,
P: pit,
W: Wumpus,
OK: safe square.

Exploring a Wumpus World (7)



B: breeze,
S: stench,
G: glitter,
A: agent,
P: pit,
W: Wumpus,
OK: safe square.

Tweedback Questions

Search does not prevent us from getting killed.

Is it possible that even by using logic we get killed?

Yes, if Wumpus is in the first square

Basics of Logic (1)

Logic

The main concept of logic is explained based on ordinary arithmetic, which everybody is familiar with.

Syntax

Specifies how correct sentences are formed, e.g., $x + y = 4$ is well-formed, while $x4y+$ is not.

Semantics

The semantics defines the meaning of sentences, i.e., when a sentence is true. For instance, $x + y = 4$ is true for $x = y = 2$ and false for $x = y = 1$.

Model

Models are differently defined depending on the discipline. Here, models are instances which evaluate sentences to true or false. For instance, we have x men and y women playing a card game, then the sentence $x + y = 4$ is true for the models $x = 4, y = 0$; $x = 3, y = 1$; and so on.

Basics of Logic (2)

Satisfaction

If a sentence α is true in model m , we say that m **satisfies** α . We use the notation $M(\alpha)$ to mean the set of all models of α .

Entailment

Entailment is the relationship between two sentences where the truth of one sentence requires the truth of the other sentence, which is written as

$$\alpha \models \beta$$

Resolution Rule

if α entails β . Formally, entailment is defined as

to show $KB \models \alpha$, we show
that $KB \wedge \neg \alpha$ is not satisfiable

$$\alpha \models \beta \text{ if and only if } M(\alpha) \subseteq M(\beta),$$

For instance, the sentence $x = 0$ entails $xy = 0$.

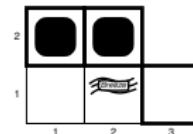
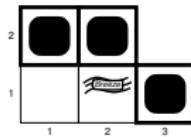
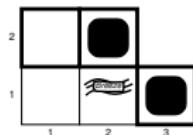
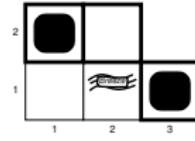
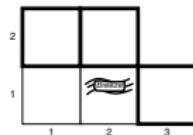
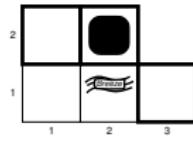
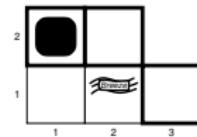
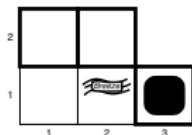
Logical Reasoning in the Wumpus World (1)

The agent in [2, 1] is interested (among other things) whether the adjacent squares contain pits. Each of those squares might have or not have a pit, resulting in $2^3 = 8$ models:

3: squares

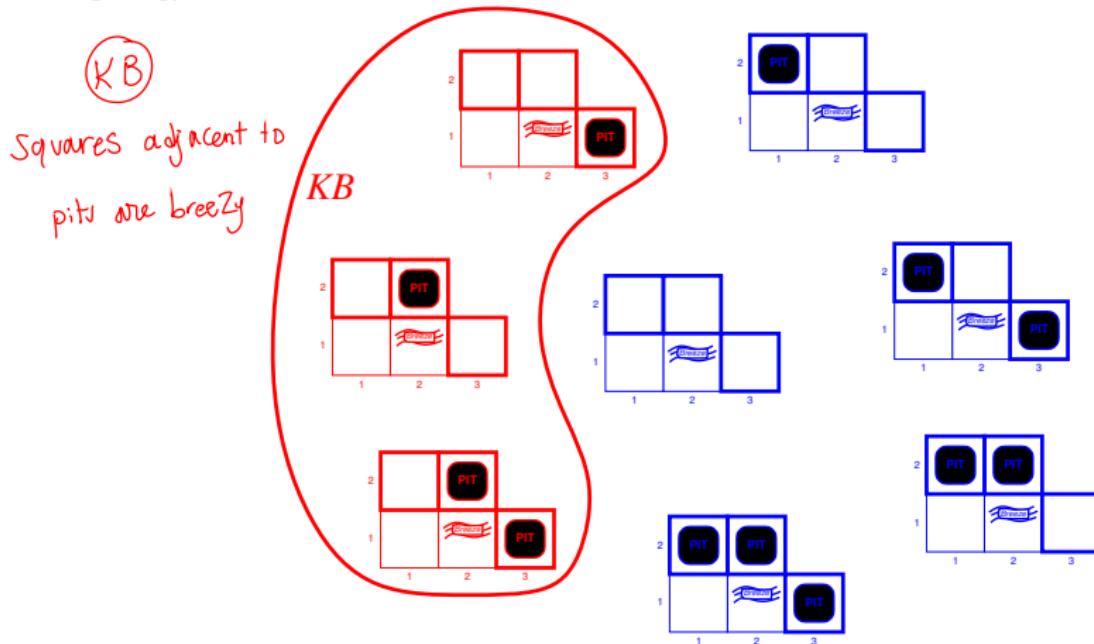
2: possibilities

pit
not a pit



Logical Reasoning in the Wumpus World (2)

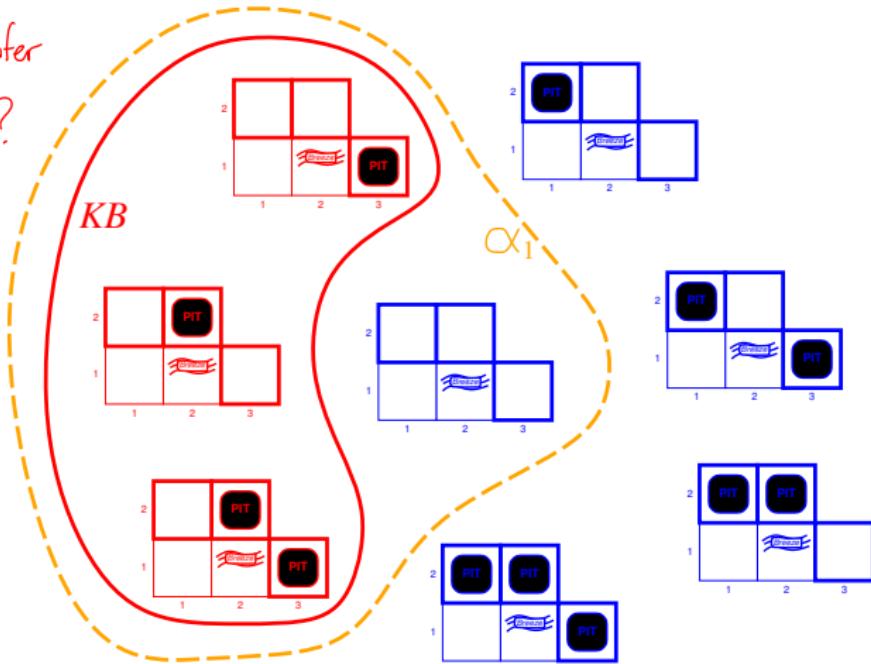
The knowledge base (KB) is a set of sentences. Models in which the knowledge base is true are shown below (the agent has only explored [1, 1] and [2, 1]):



Logical Reasoning in the Wumpus World (3)

For what models is the sentence $\alpha_1 = \text{"There is no pit in [1, 2]"}$ true?

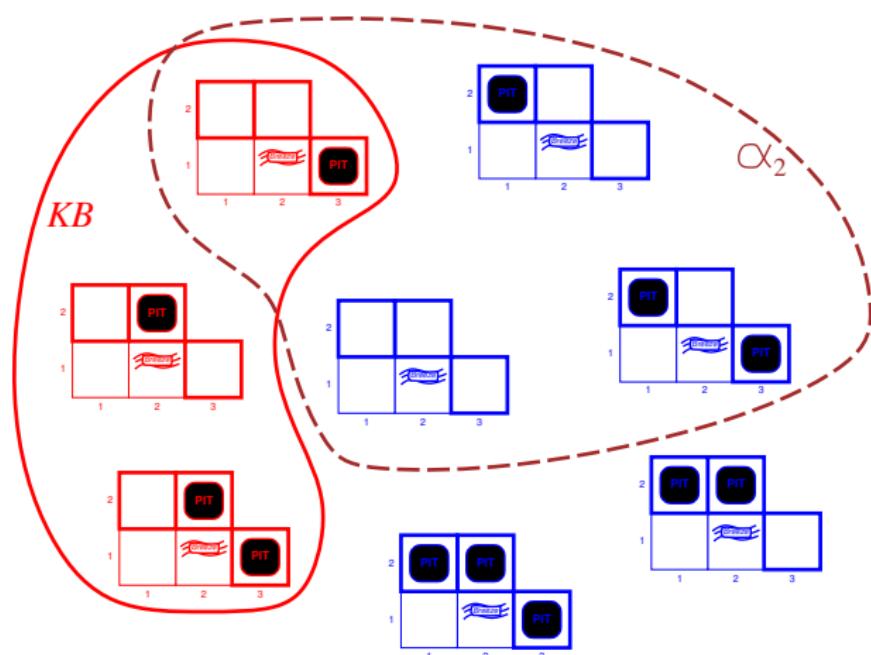
i.e. can we infer
 α_1 from KB?



In every model, in which KB is true, α_1 is also true. Thus, $KB \models \alpha_1$.

Logical Reasoning in the Wumpus World (4)

For what models is the sentence $\alpha_2 = \text{"There is no pit in [2, 2]"}$ true?



Not every model in which KB is true is α_2 also true. Thus, $KB \not\models \alpha_2$.

Syntax of Propositional Logic (SyntaxLogic.ipynb)

We apply the aforementioned techniques to a particular logic: propositional logic, which is the simplest commonly-used logic.

The proposition symbols S_1 , S_2 , etc, are sentences.

- If S is a sentence, $\neg S$ is a sentence (**negation**)
- If S_1 and S_2 are sentences, $S_1 \wedge S_2$ is a sentence (**conjunction**)
- If S_1 and S_2 are sentences, $S_1 \vee S_2$ is a sentence (**disjunction**)
- If S_1 and S_2 are sentences, $S_1 \Rightarrow S_2$ is a sentence (**implication**)
- If S_1 and S_2 are sentences, $S_1 \Leftrightarrow S_2$ is a sentence (**biconditional**)

Backus-Naur Form (AP: **atomic proposition**, e.g., **true**, **false**, A , B , etc.)

$$S ::= AP | \neg S | S_1 \wedge S_2 | S_1 \vee S_2 | S_1 \Rightarrow S_2 | S_1 \Leftrightarrow S_2 | (S)$$

Operator precedence (descending order): $\neg, \wedge, \vee, \Rightarrow, \Leftrightarrow$

Syntax of Propositional Logic: Examples

Reminder: Backus-Naur Form

$$S ::= AP | \neg S | S_1 \wedge S_2 | S_1 \vee S_2 | S_1 \Rightarrow S_2 | S_1 \Leftrightarrow S_2 | (S)$$

Operator precedence (descending order): $\neg, \wedge, \vee, \Rightarrow, \Leftrightarrow$

Q: is it a proper propositional logic?

- $true$ yes [true means for example S or $\neg S$]
- $true(\wedge S_1)$ no
- $S_1 \Rightarrow \Rightarrow S_2$ no
- $\neg\neg S$ yes
- $S_1 \Rightarrow (S_2 \Rightarrow S_3)$ yes
- $S_1 \neg \Rightarrow S_2$ no
- $S_1 \Rightarrow \neg S_2$ yes

Semantics of Propositional Logic

Each model specifies true/false for each proposition symbol,

e.g., $P_{1,2}$ $P_{2,2}$ $P_{3,1}$
 true false true

Rules for evaluating truth with respect to a model m :

$\neg S$	is true iff	S	is false		
$S_1 \wedge S_2$	is true iff	S_1	is true <i>and</i>	S_2	is true
$S_1 \vee S_2$	is true iff	S_1	is true <i>or</i>	S_2	is true
$\star S_1 \Rightarrow S_2$	is true iff	S_1	is false <i>or</i>	S_2	is true \Rightarrow follows S_2
i.e.,	is false iff	S_1	is true <i>and</i>	S_2	is false
$S_1 \Leftrightarrow S_2$	is true iff	$S_1 \Rightarrow S_2$	is true <i>and</i>	$S_2 \Rightarrow S_1$	is true

A simple recursive process evaluates an arbitrary sentence, e.g.,

$$P_{1,2} \wedge (P_{2,2} \vee P_{3,1}) = \text{true} \wedge (\text{false} \vee \text{true}) = \text{true} \wedge \text{true} = \text{true}$$

Truth Tables

The rules can also be expressed with a truth table that specifies the truth value for each possible assignment:

premise	P	false	false	true	true
Conclusion	Q	false	true	false	true
	$\neg P$	true	true	false	false
	$P \wedge Q$	false	false	false	true
	$P \vee Q$	false	true	true	true
*	$P \Rightarrow Q$	true	true	false	true \Rightarrow almost always true
*	$P \Leftrightarrow Q$	true	false	false	true

All assignments are intuitive, except the implication. The sentence

“5 is even implies Tokyo is the capital of Germany”

is true. Think of an implication $P \Rightarrow Q$ as saying

“If P is true, then I am claiming that Q is true.”

XOR		
0	0	0
0	1	1
1	0	1
1	1	0

Wumpus World Sentences

KB is usually entered by user

Symbols for each $[x, y]$ location

- $P_{x,y}$ is true if there is a pit in $[x, y]$.
- $W_{x,y}$ is true if there is a Wumpus in $[x, y]$, dead or alive.
- $B_{x,y}$ is true if the agent perceives a breeze in $[x, y]$.
- $S_{x,y}$ is true if the agent perceives stench in $[x, y]$.

To derive $\neg P_{1,2}$ in the previous example, we need the following sentences R_i :

- There is no pit in $[1, 1]$: $\neg P_{1,1}$ (R_1) ↙
resolvent
- A square is breezy if and only if there is an adjacent pit. This has to be stated for all squares; we just include the relevant ones:

$$B_{1,1} \Leftrightarrow (P_{1,2} \vee P_{2,1}) \quad (R_2) \quad \text{i.e. } F \Leftrightarrow F \vee F : R_2 \text{ is T}$$

$$B_{2,1} \Leftrightarrow (P_{1,1} \vee P_{2,2} \vee P_{3,1}) \quad (R_3)$$

- The previous sentences are true in all Wumpus worlds. Now we introduce the percepts (particular to this world): $\neg B_{1,1}$ (R_4), $B_{2,1}$ (R_5).

Inference by Enumeration (1)

Approach #1

A simple technique to decide whether $KB \models \alpha$ is to enumerate all models and check whether α is true in every model in which KB is true.

In our example, the relevant proposition symbols are $B_{1,1}$, $B_{2,1}$, $P_{1,1}$, $P_{1,2}$, $P_{2,1}$, $P_{2,2}$, and $P_{3,1}$, resulting in $2^7 = 128$ models; in 3 cases, KB is true:

given

evaluating resolvents

$B_{1,1}$	$B_{2,1}$	$P_{1,1}$	$P_{1,2}$	$P_{2,1}$	$P_{2,2}$	$P_{3,1}$	R_1	R_2	R_3	R_4	R_5	KB
false	true	true	true	true	false	false						
false	false	false	false	false	false	true	true	true	false	true	false	false
:	:	:	:	:	:	:	:	:	:	:	:	:
false	true	false	false	false	false	false	true	true	false	true	true	false
false	true	false	false	false	false	true	true	true	true	true	true	true
false	true	false	false	true	false	true	true	true	true	true	true	true
false	true	false	false	true	true	true	true	true	true	true	true	true
false	true	false	false	true	false	false	true	false	false	true	true	false
:	:	:	:	:	:	:	:	:	:	:	:	:
true	false	true	true	false	true	false						



In those 3 models, $\neg P_{1,2}$ is true, such that $KB \models \neg P_{1,2}$.

$P_{1,2}$ I want to know if there is no pit in (1,2)

Inference by Enumeration (2)

- If KB and α contain n symbols, there are 2^n models.
- Thus, the time complexity of enumeration is $\mathcal{O}(2^n)$.
- The space complexity is only $\mathcal{O}(n)$ because the enumeration is depth-first.
- Later we show algorithms that are more efficient on average.
However, propositional entailment is co-NP-complete, so every known inference algorithm is exponential in the size of the input.
- The proposed technique is a special case of **Model Checking** (see lecture by Prof. Jan Kretinsky).

Introduction to Theorem Proving (1)

Approach #2

- Instead of using enumeration, we apply rules of inference directly to sentences in theorem proving.
- Theorem proving does not require any models!
- ~~If the number of models is large, but the length of the proof is short, theorem proving can be more efficient than enumeration.~~

We require some concepts for theorem proving:

Logical equivalence

Two sentences α and β are logically equivalent if they are true in the same set of models, which is written as $\alpha \equiv \beta$. Alternative definition:

$\alpha \equiv \beta$ if and only if $\alpha \models \beta$ and $\beta \models \alpha$.

Introduction to Theorem Proving (2)

Validity

A sentence is valid if it is true in all models (e.g., $P \vee \neg P$). Valid sentences are also known as **tautologies**. *is a formula or assertion that is true in every possible interpretation*

Satisfiability *there exist a truth value assignment for the variables that makes the sentence true*

A sentence is satisfiable if it is true in some model, e.g., the expression $P_1 \wedge P_2$ is satisfiable for $P_1 = P_2 = \text{true}$, whereas $P_1 \wedge \neg P_1$ is not satisfiable.

- The problem of determining the satisfiability of sentences is also called a **SAT** problem, which is NP-complete.
- * Validity and satisfiability are connected: α is valid if $\neg\alpha$ is unsatisfiable.

Inference and Proofs

We discuss useful **inference rules** that can be applied to derive a **proof** – a chain of conclusions that lead to the desired goal.

① Modus Ponens

$$\frac{\text{only works } \alpha \Rightarrow \beta, \quad \alpha \text{ is true}}{\beta \text{ then, is true}}$$

not ↑

The notation means that when $\alpha \Rightarrow \beta$ and α are given, β can be inferred.

② And-Elimination

$$\frac{\alpha \wedge \beta}{\alpha \text{ then, is true}}, \quad \frac{\alpha \wedge \beta}{\beta \text{ is true}}$$

Further inference rules can be obtained by using well-known logical equivalences (see next slide).

Logical Equivalences

Important

③ Standard logical equivalences

works ↴ ↵

- $(\alpha \wedge \beta) \equiv (\beta \wedge \alpha)$ commutativity of \wedge brackets are not important
- $(\alpha \vee \beta) \equiv (\beta \vee \alpha)$ commutativity of \vee
- $((\alpha \wedge \beta) \wedge \gamma) \equiv (\alpha \wedge (\beta \wedge \gamma))$ associativity of \wedge
- $((\alpha \vee \beta) \vee \gamma) \equiv (\alpha \vee (\beta \vee \gamma))$ associativity of \vee
- $\neg(\neg\alpha) \equiv \alpha$ double-negation elimination
- $\boxed{(\alpha \Rightarrow \beta) \equiv (\neg\beta \Rightarrow \neg\alpha)}$ contraposition
- $\boxed{(\alpha \Rightarrow \beta) \equiv (\neg\alpha \vee \beta)}$ implication elimination
- $(\alpha \Leftrightarrow \beta) \equiv ((\alpha \Rightarrow \beta) \wedge (\beta \Rightarrow \alpha))$ biconditional elimination
- $\neg(\alpha \wedge \beta) \equiv (\neg\alpha \vee \neg\beta)$ De Morgan
- $\neg(\alpha \vee \beta) \equiv (\neg\alpha \wedge \neg\beta)$ De Morgan
- $(\alpha \wedge (\beta \vee \gamma)) \equiv ((\alpha \wedge \beta) \vee (\alpha \wedge \gamma))$ distributivity of \wedge over \vee
- $(\alpha \vee (\beta \wedge \gamma)) \equiv ((\alpha \vee \beta) \wedge (\alpha \vee \gamma))$ distributivity of \vee over \wedge

Tweedback Question

propositional Logic

How can we prove the above equivalences?

- A We can prove these equivalences by other yet-to-be proven equivalences of the list.
- B We can show the correctness by enumeration.

Inference from Equivalences

4

From the previous table, we can generate from bidirectional elimination the inference rules

$$\frac{\alpha \Leftrightarrow \beta}{(\alpha \Rightarrow \beta) \wedge (\beta \Rightarrow \alpha)}, \quad \frac{(\alpha \Rightarrow \beta) \wedge (\beta \Rightarrow \alpha)}{\alpha \Leftrightarrow \beta}.$$

* The inference rule works in both directions due to the equivalence. This is not possible in general, e.g., Modus Ponens does not work in the opposite direction to obtain $\alpha \Rightarrow \beta$ and α from β .

Proof for the Wumpus World Example

- ① We start with the sentence on slide 27:

$$R_2 : B_{1,1} \Leftrightarrow (P_{1,2} \vee P_{2,1})$$

- ② Bidirectional elimination (see slide 33):

$$R_6 : (B_{1,1} \Rightarrow (P_{1,2} \vee P_{2,1})) \wedge ((P_{1,2} \vee P_{2,1}) \Rightarrow B_{1,1})$$

- ③ And-Elimination (see slide 32):

$$R_7 : ((P_{1,2} \vee P_{2,1}) \Rightarrow B_{1,1})$$

- ④ Contraposition (see slide 33):

$$R_8 : (\neg B_{1,1} \Rightarrow \neg(P_{1,2} \vee P_{2,1}))$$

- ⑤ Modus Ponens (see slide 32) with R_8 and $R_4 = \neg B_{1,1}$:

$$R_9 : \neg(P_{1,2} \vee P_{2,1})$$

- ⑥ De Morgan (see slide 33):

$$R_{10} : \neg P_{1,2} \wedge \neg P_{2,1}$$

- ⑦ Thus, neither [1, 2] nor [2, 1] contains a pit.

Automated Theorem Proving

The previous method was done “by hand”. How can one automate this?

We can use the previously introduced search methods on the following problem:

- **Initial state**: the initial knowledge base.
- **Actions**: all the inference rules applied to all the sentences that match the top half of the inference rule.
- **Result**: the result of an action is to add the sentence in the bottom half of the inference rule.
- **Goal**: a state that contains the sentence to prove.

In practical cases, finding a proof can be more efficient than enumeration because not all possible models have to be generated.

Proof by Resolution



(InferencePropLogic.ipynb)

Important

- So far, we have not discussed completeness, i.e., does the algorithm find a proof if one exists? $KB \models \alpha ?$
 - For instance, the previous proof does not work without the resolution bidirectional elimination.
 - We introduce the inference rule **resolution**, which yields a complete inference algorithm when coupled with a complete search algorithm.
- No always leads to
Using resdn rule with PL, asln is always found*
- theorem - proving*

Robinson - 1965

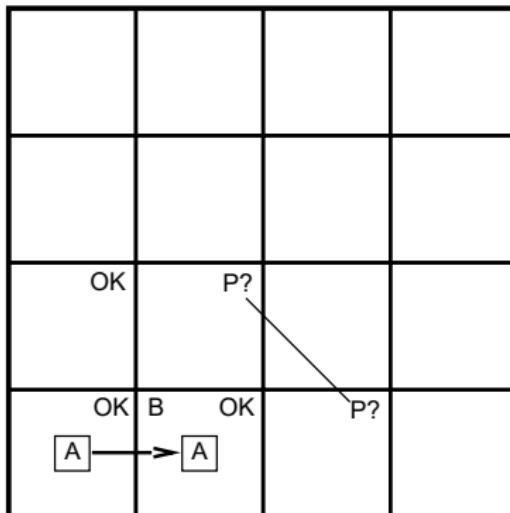
We begin with a

how it works

- ① Wumpus world example,
 - ② generalize it,
 - ③ and prove why resolution leads to a complete algorithm when using propositional logic.
- * The clause produced by a resolution rule, is sometimes called a resolvent.

Resolution in the Wumpus World (1)

We start with the following situation:



We add the following facts to the knowledge base:

$$R_{11} : \neg B_{1,2}$$

$$R_{12} : B_{1,2} \Leftrightarrow (P_{1,1} \vee P_{2,2} \vee P_{1,3})$$

Resolution in the Wumpus World (2)

$$\neg P_{1,2} \wedge \neg P_{2,1}$$

- ① By the same process that led to R_{10} on slide 36, we can derive the absence of pits in [2, 2] and [1, 3]:

$$R_{13} : \neg P_{2,2}$$

$$R_{14} : \neg P_{1,3}$$

- ② Bidirectional elimination to R_3 : $B_{2,1} \Leftrightarrow (P_{1,1} \vee P_{2,2} \vee P_{3,1})$ (slide 27), followed by Modus Ponens with R_5 : $B_{2,1}$ (slide 27) yields

$$R_{15} : P_{1,1} \vee P_{2,2} \vee P_{3,1}$$

• at least one in R_{15} must be true

- * ③ Now comes the first resolution rule: $\neg P_{2,2}$ in R_{13} resolves with $P_{2,2}$ in R_{15} to give the **resolvent**

• given $P_{2,2}$ is not true

$$R_{16} : P_{1,1} \vee P_{3,1}$$

- ④ Similarly, R_1 : $\neg P_{1,1}$ (slide 27) resolves with $P_{1,1}$ in R_{16} to

$$R_{17} : P_{3,1}$$

• again $P_{1,1}$ is not true

- ⑤ Now we know that the pit can only be in [3, 1]!

Resolution Inference Rules

literal : is a propositional variable or the negation of a propositional variable

Unit resolution rule

Given literals l_i (atomic proposition or its negation) we have that

$$\frac{l_1 \vee \dots \vee l_k, \quad m}{l_1 \vee \dots \vee l_{i-1} \vee l_{i+1} \vee \dots \vee l_k}, \text{ entails}$$

where l_i and m are **complementary literals** (i.e., $l_i \equiv \neg m$).

The unit resolution rule can be generalized:

One is the negation of the other

Full resolution rule

$$\frac{l_1 \vee \dots \vee l_k, \quad m_1 \vee \dots \vee m_n}{l_1 \vee \dots \vee l_{i-1} \vee l_{i+1} \vee \dots \vee l_k \vee m_1 \vee \dots \vee m_{j-1} \vee m_{j+1} \vee \dots \vee m_n},$$

where l_i and m_j are complementary literals.

Example: $\frac{P_{1,1} \vee P_{3,1}, \quad \neg P_{1,1} \vee \neg P_{2,2}}{P_{3,1} \vee \neg P_{2,2}}.$

Soundness of the Resolution Rule

We discuss the soundness of

$$\frac{l_1 \vee \dots \vee l_k, \quad m_1 \vee \dots \vee m_n}{l_1 \vee \dots \vee l_{i-1} \vee l_{i+1} \vee \dots \vee l_k \vee m_1 \vee \dots \vee m_{j-1} \vee m_{j+1} \vee \dots \vee m_n},$$

informally:

- **l_i is true and m_j is false:**

Hence, $m_1 \vee \dots \vee m_{j-1} \vee m_{j+1} \vee \dots \vee m_n$ must be true, because $m_1 \vee \dots \vee m_n$ is given.

- **m_j is true and l_i is false:**

Hence, $l_1 \vee \dots \vee l_{i-1} \vee l_{i+1} \vee \dots \vee l_k$ must be true, because $l_1 \vee \dots \vee l_k$ is given.

- **l_i is either true or false**, so one of these conclusions holds, as stated in the resolution rule.

Conjunctive Normal Form

- The resolution rule only applies to disjunction of literals, which are also called **clauses**. → is T, when at least one of literals forming it is T. Or
- Fortunately, every sentence of propositional logic can be reformulated as a conjunction of clauses, which is also referred to as **conjunctive normal form (CNF)**

when all literals

forming it are T

Conjunctive Normal Form

A sentence with literals x_{ij} of the form $\bigwedge_i \bigvee_j (\neg)x_{ij}$ is in conjunctive normal form. Otherwise put, it's an AND of ORs

Examples:

- $(A \vee B \vee C) \wedge (\neg A \vee B \vee C)$ yes
- $A \wedge B \wedge C \vee (\neg A \wedge B \vee C)$ no
- $A \wedge B \wedge C \wedge (\neg A \vee B \vee C)$ yes

↓ considered a clause

Conversion to CNF

Just follow as it is!

Important

We demonstrate the conversion to CNF by converting $B_{1,1} \Leftrightarrow (P_{1,2} \vee P_{2,1})$:

- ① Eliminate $\alpha \Leftrightarrow \beta$ with $(\alpha \Rightarrow \beta) \wedge (\beta \Rightarrow \alpha)$:

$$\left(B_{1,1} \Rightarrow (P_{1,2} \vee P_{2,1}) \right) \wedge \left((P_{1,2} \vee P_{2,1}) \Rightarrow B_{1,1} \right)$$

- ② Eliminate $\alpha \Rightarrow \beta$ with $\neg\alpha \vee \beta$:

$$\left(\neg B_{1,1} \vee P_{1,2} \vee P_{2,1} \right) \wedge \left(\neg(P_{1,2} \vee P_{2,1}) \vee B_{1,1} \right)$$

- ③ “Moving \neg inwards” by application of the following equivalences (see slide 33)

$$\neg(\neg\alpha) \equiv \alpha \quad (\text{double-negation elimination})$$

$$\neg(\alpha \wedge \beta) \equiv (\neg\alpha \vee \neg\beta) \quad (\text{De Morgan})$$

$$\neg(\alpha \vee \beta) \equiv (\neg\alpha \wedge \neg\beta) \quad (\text{De Morgan})$$

We only require the last rule in the example:

$$\left(\neg B_{1,1} \vee P_{1,2} \vee P_{2,1} \right) \wedge \left((\neg P_{1,2} \wedge \neg P_{2,1}) \vee B_{1,1} \right)$$

- ④ Now we only have nested \wedge and \vee operators applied to literals. It remains to swap \wedge and \vee using the distributivity law:

$$(\neg B_{1,1} \vee P_{1,2} \vee P_{2,1}) \wedge (\neg P_{1,2} \vee B_{1,1}) \wedge (\neg P_{2,1} \vee B_{1,1})$$

A Resolution Algorithm

Important

Inference procedures based on resolution use the principle of proof by contradiction:

To show that $KB \models \alpha$, we show that $KB \wedge \neg\alpha$ is unsatisfiable.

Basic procedure

- ① $KB \wedge \neg\alpha$ is converted into CNF
- ② The resolution rule is applied to the resulting clauses:
each pair that contains complementary literals is resolved to produce
a new clause, which is added to the others (if not already present)
- ③ The process continues until
 - there are no new clauses to be added $\Rightarrow KB \not\models \alpha$;
 - two clauses resolve to yield the empty clause $\Rightarrow KB \models \alpha$.

Example of the Resolution Algorithm (1)

Wumpus World: the agent is in [1,1] and there is no breeze, so there can be no pits in the neighboring squares. The knowledge base is

$$KB = R_2 \wedge R_4 = (B_{1,1} \Leftrightarrow (P_{1,2} \vee P_{2,1})) \wedge \neg B_{1,1},$$

and we would like to prove $\alpha = \neg P_{1,2}$

OK			
OK	A	OK	

Example of the Resolution Algorithm (2)

We start with the conversion of $KB \wedge \neg\alpha = (B_{1,1} \Leftrightarrow (P_{1,2} \vee P_{2,1})) \wedge \neg B_{1,1} \wedge P_{1,2}$ into CNF:

- ① Eliminate $\alpha \Leftrightarrow \beta$ with $(\alpha \Rightarrow \beta) \wedge (\beta \Rightarrow \alpha)$:

$$\left(B_{1,1} \Rightarrow (P_{1,2} \vee P_{2,1}) \right) \wedge \left((P_{1,2} \vee P_{2,1}) \Rightarrow B_{1,1} \right) \wedge \neg B_{1,1} \wedge P_{1,2}$$

- ② Eliminate $\alpha \Rightarrow \beta$ with $\neg\alpha \vee \beta$:

$$\left(\neg B_{1,1} \vee P_{1,2} \vee P_{2,1} \right) \wedge \left(\neg(P_{1,2} \vee P_{2,1}) \vee B_{1,1} \right) \wedge \neg B_{1,1} \wedge P_{1,2}$$

- ③ “Moving \neg inwards” (see slide 33):

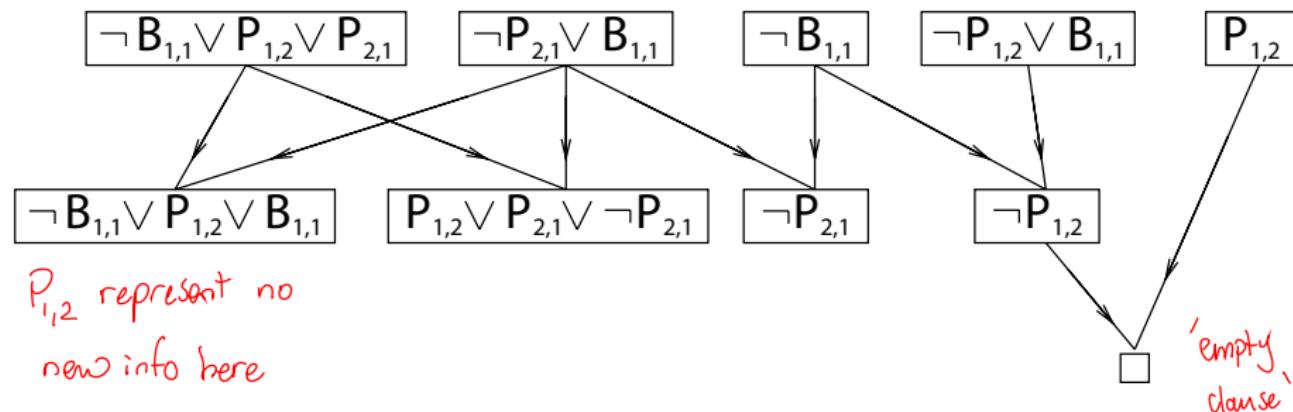
$$\left(\neg B_{1,1} \vee P_{1,2} \vee P_{2,1} \right) \wedge \left((\neg P_{1,2} \wedge \neg P_{2,1}) \vee B_{1,1} \right) \wedge \neg B_{1,1} \wedge P_{1,2}$$

- ④ Now we only have nested \wedge and \vee operators applied to literals. It remains to swap \wedge and \vee using the distributivity law:

$$(\neg B_{1,1} \vee P_{1,2} \vee P_{2,1}) \wedge (\neg P_{1,2} \vee B_{1,1}) \wedge (\neg P_{2,1} \vee B_{1,1}) \wedge \neg B_{1,1} \wedge P_{1,2}$$

Example of the Resolution Algorithm (3)

When we convert $KB \wedge \neg\alpha$ into CNF, we obtain the clauses on the top:



The second row of the figure shows clauses obtained by resolving pairs.

We obtain the empty clause by resolving $P_{1,2}$ with $\neg P_{1,2}$, so that $KB \models \alpha$

since $\alpha = \top P_{1,2}$, this means no pit is [1,2]

Resolution Algorithm

function PL-Resolution (KB, α) **returns** true, or false

$c\text{lauses} \leftarrow$ the set of clauses in the CNF representation of $KB \wedge \neg\alpha$

$new \leftarrow \{\}$

loop do

for each pair of clauses C_i, C_j **in** $c\text{lauses}$ **do**

$resolvents \leftarrow$ PL-Resolve(C_i, C_j)

if $resolvents$ contains the empty clause **then return** true

$new \leftarrow new \cup resolvents$

if $new \subseteq c\text{lauses}$ **then return** false

$c\text{lauses} \leftarrow c\text{lauses} \cup new$

Completeness of Resolution

→ always finds a soln

It remains to show why resolution is complete for propositional logic.

Resolution closure

The **resolution closure** $RC(S)$ of a set of clauses S is the set of all clauses derivable by repeated application of the resolution rule to S and its derivatives.

- $RC(S)$ is finite, because there are only finitely many distinct clauses that can be constructed out of the symbols P_1, \dots, P_k .
- Hence, PL-resolution always terminates.

Ground resolution theorem

→ $KB \models \alpha, KB \wedge \neg \alpha$

If a set of clauses is unsatisfiable, then the resolution closure of those clauses contains the empty clause.

Proof of the Ground Resolution Theorem (1)

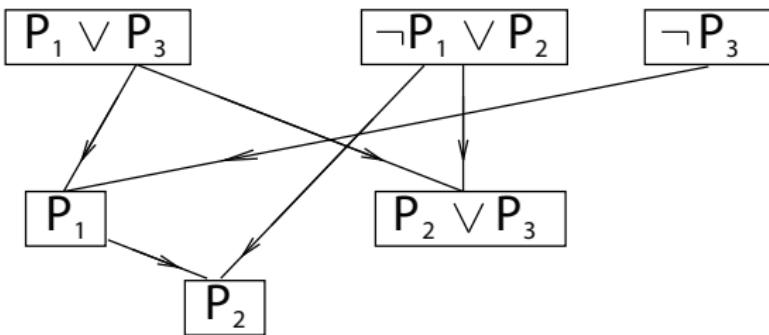
Understand

The theorem is proven by its contrapositive ($\alpha \Rightarrow \beta \equiv \neg\beta \Rightarrow \neg\alpha$): if the closure $RC(S)$ does **not** contain the empty clause, then S is satisfiable.

We can construct a model for S with suitable truth values for P_1, \dots, P_k :

For i from 1 to k :

- If a clause in $RC(S)$ contains the literal $\neg P_i$ and all its other literals are false under the assignment chosen for P_1, \dots, P_{i-1} , then assign *false* to P_i .
- Otherwise assign *true* to P_i .



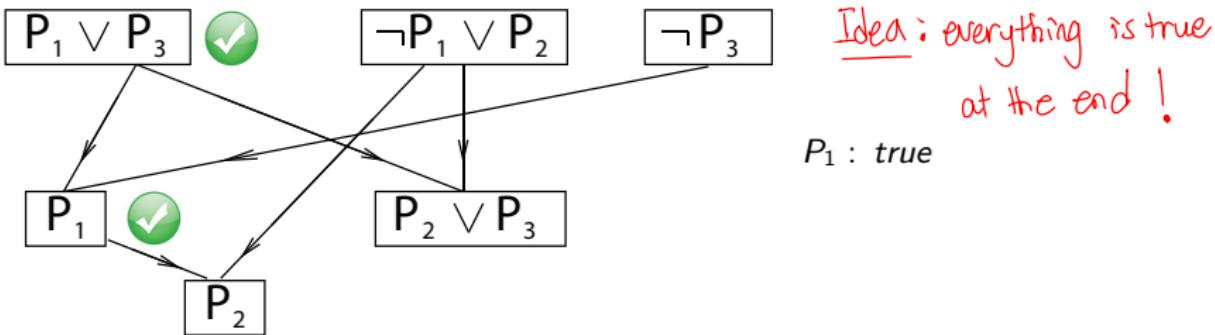
Proof of the Ground Resolution Theorem (2)

The theorem is proven by its contrapositive: if the closure $RC(S)$ does **not** contain the empty clause, then S is satisfiable.

We can construct a model for S with suitable truth values for P_1, \dots, P_k :

For i from 1 to k :

- If a clause in $RC(S)$ contains the literal $\neg P_i$ and all its other literals are false under the assignment chosen for P_1, \dots, P_{i-1} , then assign *false* to P_i .
- Otherwise assign *true* to P_i . ↓
start



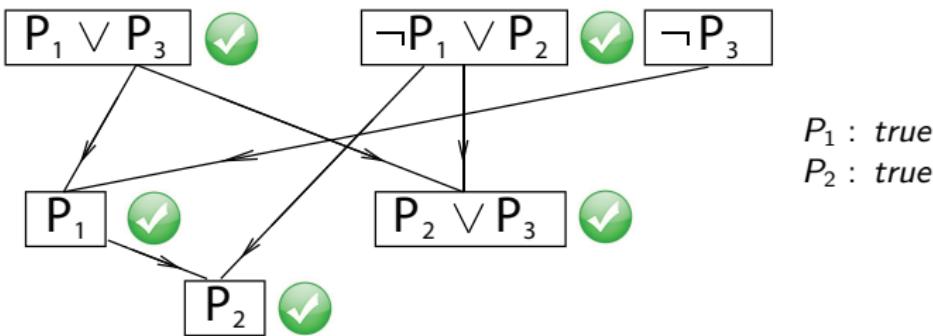
Proof of the Ground Resolution Theorem (3)

The theorem is proven by its contrapositive: if the closure $RC(S)$ does **not** contain the empty clause, then S is satisfiable.

We can construct a model for S with suitable truth values for P_1, \dots, P_k :

For i from 1 to k :

- If a clause in $RC(S)$ contains the literal $\neg P_i$ and all its other literals are false under the assignment chosen for P_1, \dots, P_{i-1} , then assign *false* to P_i .
- Otherwise assign *true* to P_i .



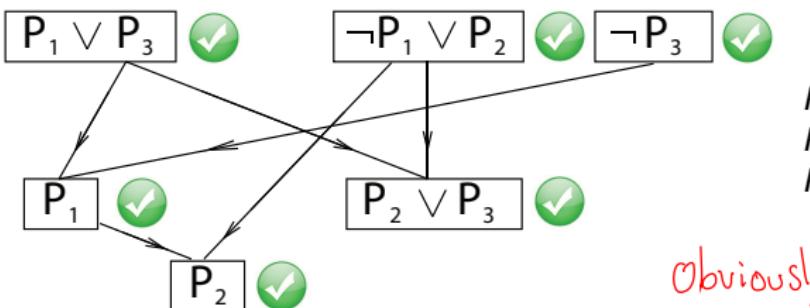
Proof of the Ground Resolution Theorem (4)

The theorem is proven by its contrapositive: if the closure $RC(S)$ does **not** contain the empty clause, then S is satisfiable.

We can construct a model for S with suitable truth values for P_1, \dots, P_k :

For i from 1 to k :

- If a clause in $RC(S)$ contains the literal $\neg P_i$ and all its other literals are false under the assignment chosen for P_1, \dots, P_{i-1} , then assign *false* to P_i .
- Otherwise assign *true* to P_i .



$P_1 : \text{true}$
 $P_2 : \text{true}$
 $P_3 : \text{false}$

Obviously, this satisfiable

Proof of the Ground Resolution Theorem (5)

The theorem is proven by its contrapositive: if the closure $RC(S)$ does **not** contain the empty clause, then S is satisfiable.

We can construct a model for S with suitable truth values for P_1, \dots, P_k :

For i from 1 to k :

- If a clause in $RC(S)$ contains the literal $\neg P_i$ and all its other literals are false under the assignment chosen for P_1, \dots, P_{i-1} , then assign *false* to P_i .
- Otherwise assign *true* to P_i .

 This assignment is a model of S . To see this, assume the opposite – a clause becomes false at stage i when all its literals are false:

$$(false \vee false \vee \dots \vee P_i) \text{ or } (false \vee false \vee \dots \vee \neg P_i).$$

The model construction will choose the truth value for P_i such that the clause is true. The clause can only be falsified if **both** clauses are in $RC(S)$. Since $RC(S)$ is closed under resolution, it will contain the resolvent, whose literals P_1, \dots, P_{i-1} are all false by assignment.

- This contradicts the assumption that the first falsified clause appears at stage i .
- Hence, we have proven that the construction never falsifies a clause in $RC(S)$.

Horn Clauses

Some simple forms of sentences do not require proof by resolution. We introduce Horn clauses for which very efficient inference algorithms exist.

Horn clause is a clause (a disjunction of literals) with at most one positive,
 i.e. unnegated literal.

- * proposition symbol; or
- * (conjunction of symbols) \Rightarrow symbol

Which are Horn clauses?

- $(L_{1,1} \wedge \text{Breeze}) \Rightarrow B_{1,1}$ yes
- $L_{1,1}$ yes ($\equiv \text{true} \Rightarrow L_{1,1}$)
- $(L_{1,1} \vee \text{Breeze}) \Rightarrow B_{1,1}$ no

A knowledge base consisting of Horn clauses only requires Modus Ponens as an inference method:

$$\frac{\alpha_1, \dots, \alpha_n, \quad \alpha_1 \wedge \dots \wedge \alpha_n \Rightarrow \beta}{\beta}$$

AND-OR Graph

Showing Horn clause graphically

Forward chaining is best illustrated by an **AND-OR** graph.

AND-OR graph

- Links joined by an arc indicate a conjunction: every link must be proven
- Links joined without an arc indicate a disjunction: only one link has to be proven

The knowledge base and the corresponding AND-OR graph (here: only AND nodes):

$$P \Rightarrow Q$$

$$L \wedge M \Rightarrow P$$

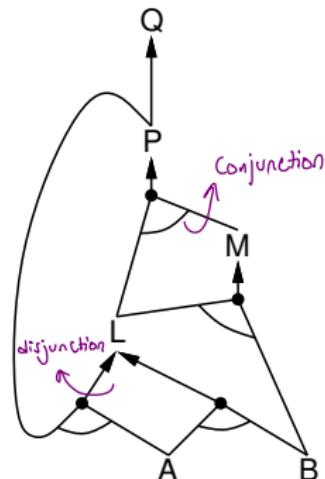
$$B \wedge L \Rightarrow M$$

$$A \wedge P \Rightarrow L$$

$$A \wedge B \Rightarrow L$$

$$A$$

$$B$$



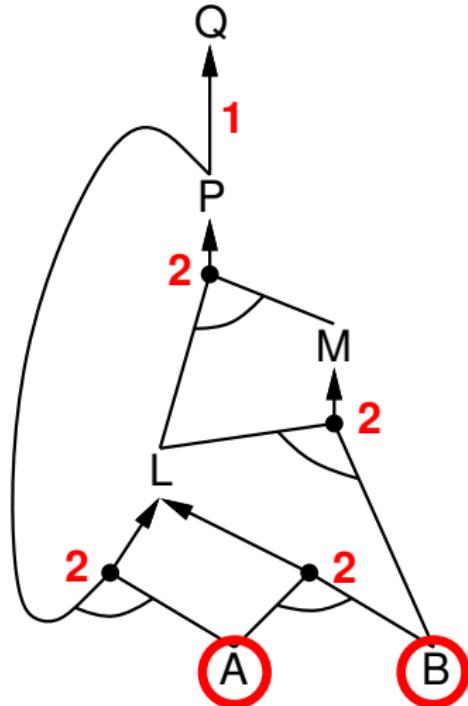
Forward Chaining (1)

Doing inference
 forward
 backward

- ➊ Fire any rule whose premises are satisfied in the KB ,
- ➋ add its conclusion to the KB ,
- ➌ until query is found. → true/false

Forward chaining time complexity is only linear!

(red circle: frontier; red filling: explored)

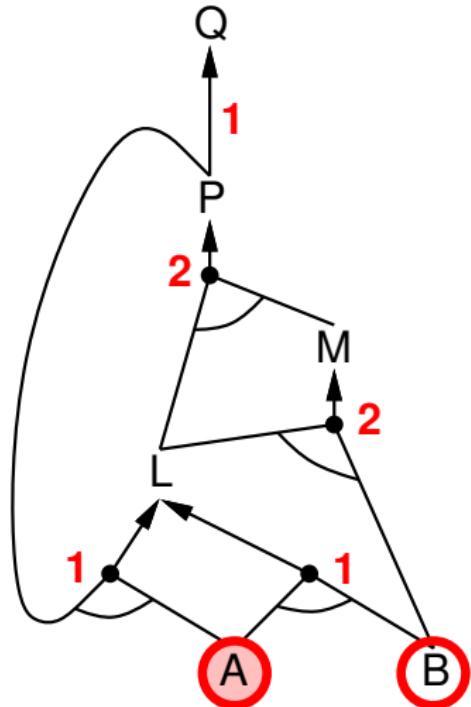


Forward Chaining (2)

- ① Fire any rule whose premises are satisfied in the KB ,
- ② add its conclusion to the KB ,
- ③ until query is found.

Forward chaining time complexity is only linear!

(red circle: frontier; red filling: explored)

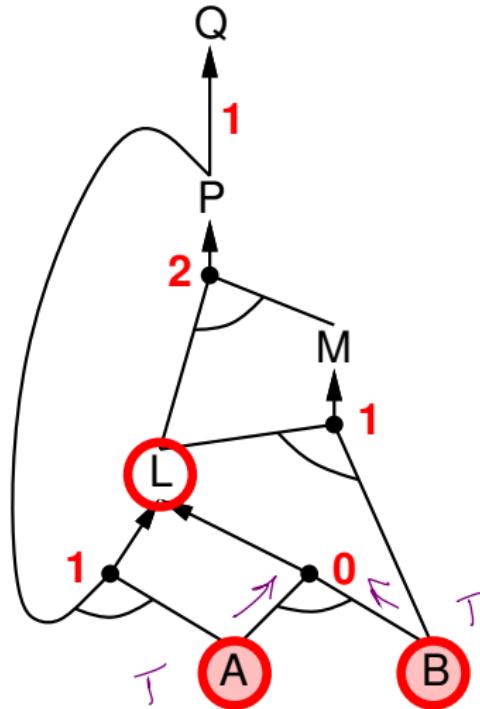


Forward Chaining (3)

- ① Fire any rule whose premises are satisfied in the KB ,
- ② add its conclusion to the KB ,
- ③ until query is found.

Forward chaining time complexity is only linear!

(red circle: frontier; red filling: explored)

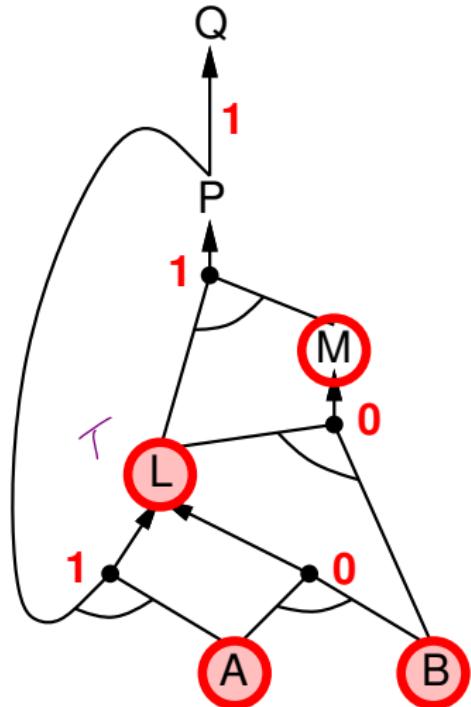


Forward Chaining (4)

- ① Fire any rule whose premises are satisfied in the KB ,
- ② add its conclusion to the KB ,
- ③ until query is found.

Forward chaining time complexity is only linear!

(red circle: frontier; red filling: explored)

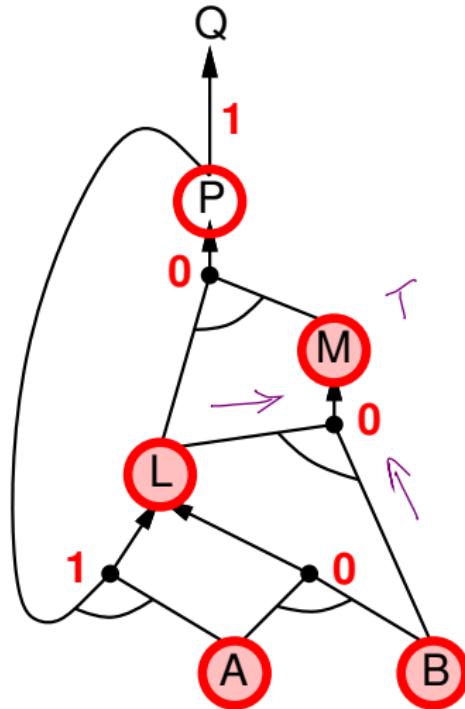


Forward Chaining (5)

- ① Fire any rule whose premises are satisfied in the KB ,
- ② add its conclusion to the KB ,
- ③ until query is found.

Forward chaining time complexity is only linear!

(red circle: frontier; red filling: explored)

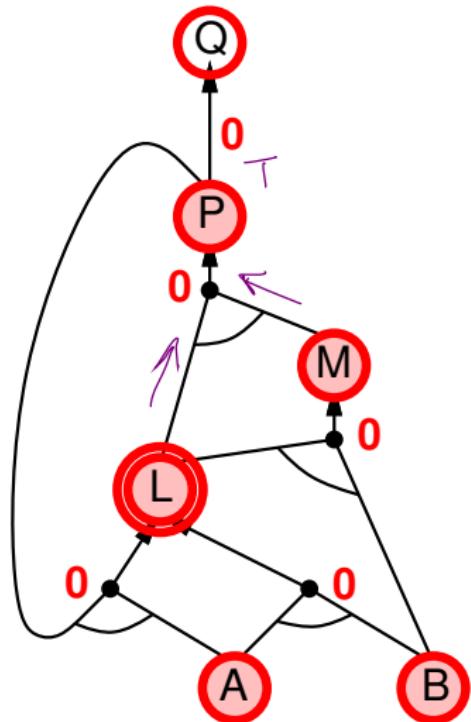


Forward Chaining (6)

- ① Fire any rule whose premises are satisfied in the KB ,
- ② add its conclusion to the KB ,
- ③ until query is found.

Forward chaining time complexity is only linear!

(red circle: frontier; red filling: explored)

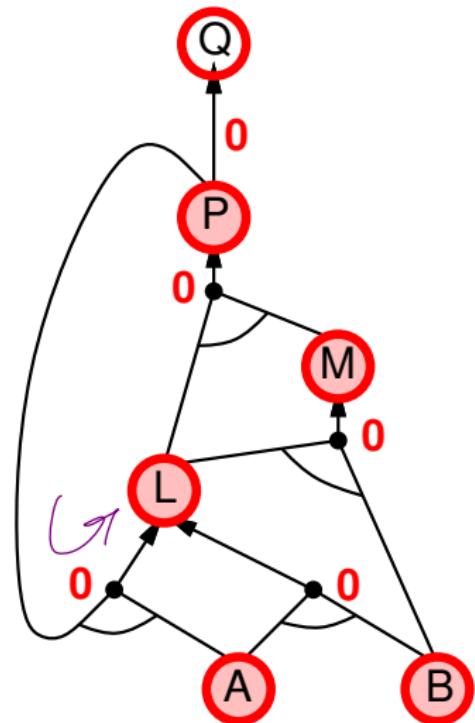


Forward Chaining (7)

- ① Fire any rule whose premises are satisfied in the KB ,
- ② add its conclusion to the KB ,
- ③ until query is found.

Forward chaining time complexity is only linear!

(red circle: frontier; red filling: explored)

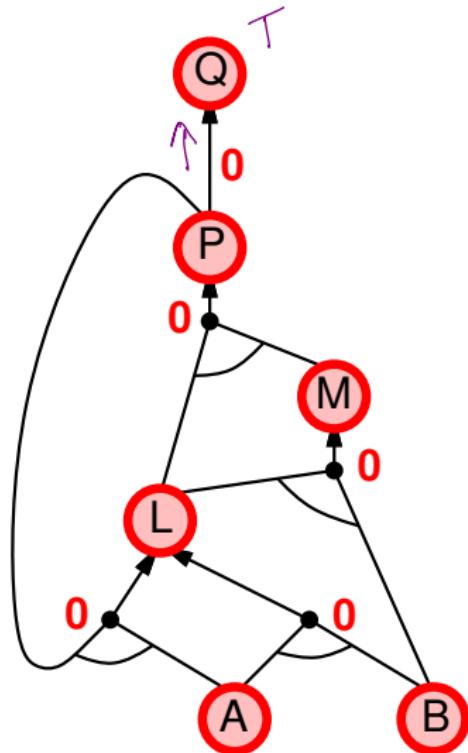


Forward Chaining (8)

- ① Fire any rule whose premises are satisfied in the KB ,
- ② add its conclusion to the KB ,
- ③ until query is found.

Forward chaining time complexity is only linear!

(red circle: frontier; red filling: explored)



Backward Chaining

Idea: work backwards from the query q :
to prove q by backward chaining,

- check if q is known already, or
- prove by backward chaining all premises of some rule concluding q .

Avoid loops: check if new subgoal is already on the goal stack.

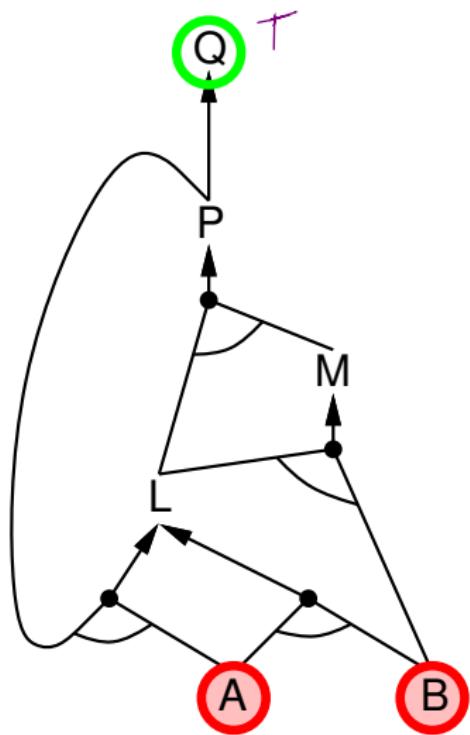
Avoid repeated work: check if new subgoal

- has already been proven true, or
- has already failed.

Backward Chaining: Example (1)

Backward chaining time complexity is also only linear!

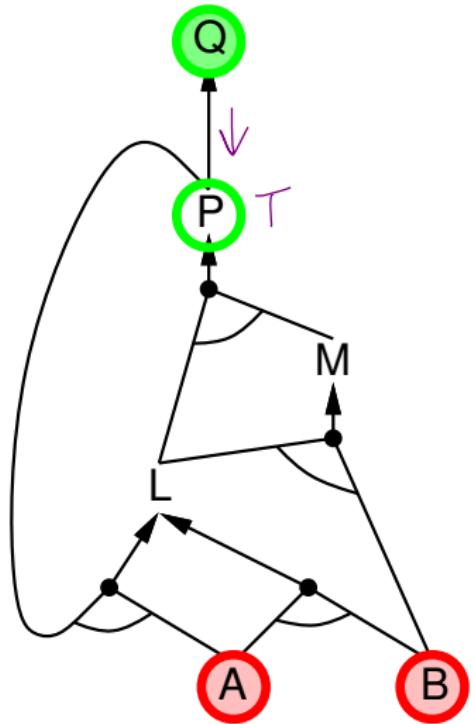
(green circle: frontier;
green filling: explored;
red filling: inferred, known as true)



Backward Chaining: Example (2)

Backward chaining time complexity is also only linear!

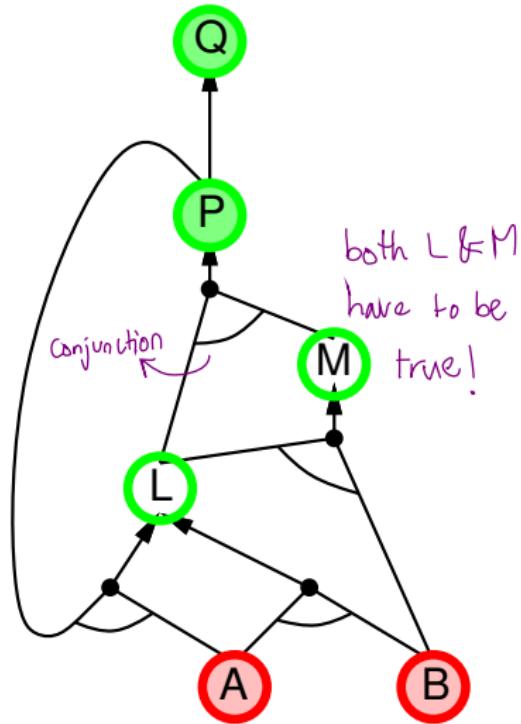
(green circle: frontier;
green filling: explored;
red filling: inferred, known as true)



Backward Chaining: Example (3)

Backward chaining time complexity is also only linear!

(green circle: frontier;
green filling: explored;
red filling: inferred, known as true)

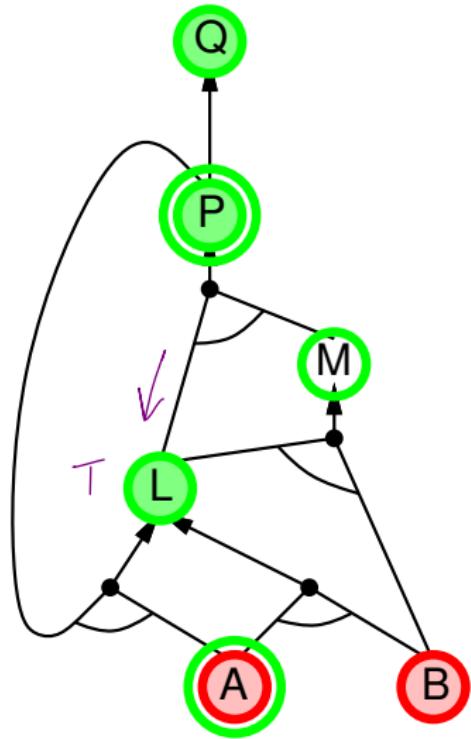


Backward Chaining: Example (4)

Backward chaining time complexity is also only linear!

(green circle: frontier;
 green filling: explored;
 red filling: inferred, known as true)

either $P \wedge A$
 has to be true OR $A \wedge B$
 has to be true



Backward Chaining: Example (5)

we could examine

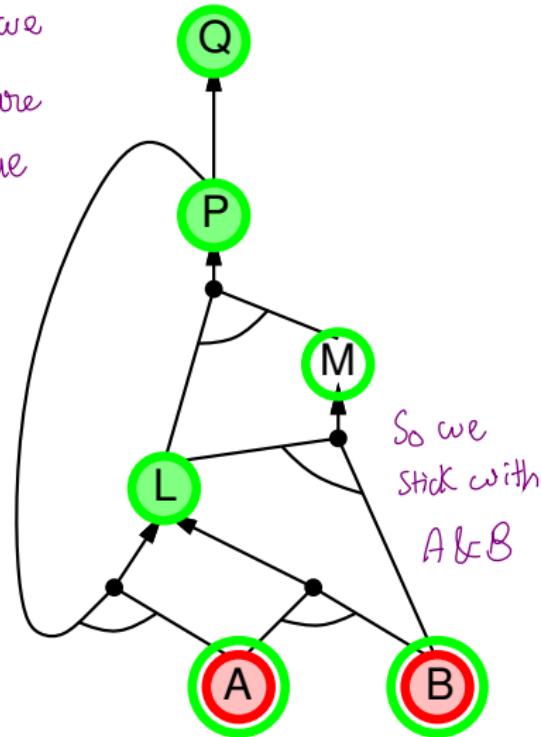
$P \& A$; since we

are still not sure

that P is true

Backward chaining time complexity is
also only linear!

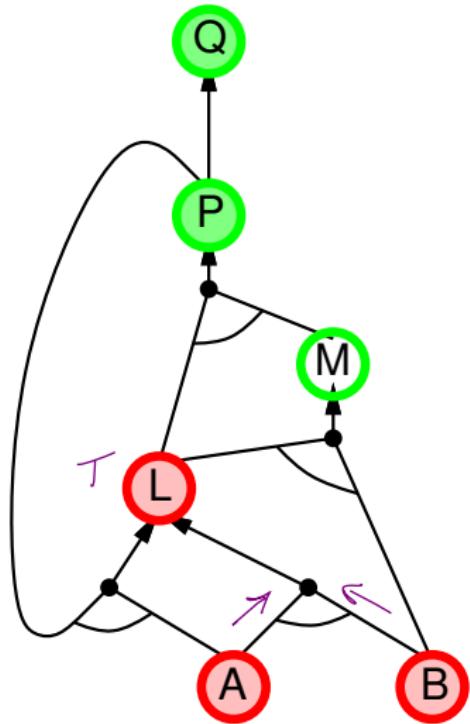
(green circle: frontier;
green filling: explored;
red filling: inferred, known as true)



Backward Chaining: Example (6)

Backward chaining time complexity is also only linear!

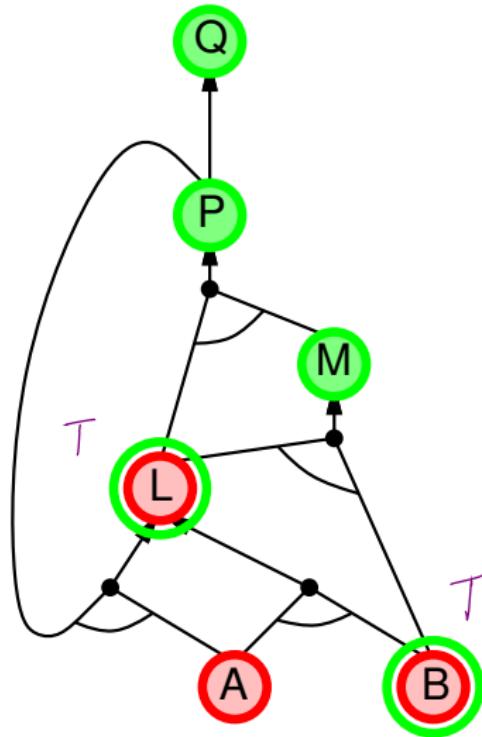
(green circle: frontier;
green filling: explored;
red filling: inferred, known as true)



Backward Chaining: Example (7)

Backward chaining time complexity is also only linear!

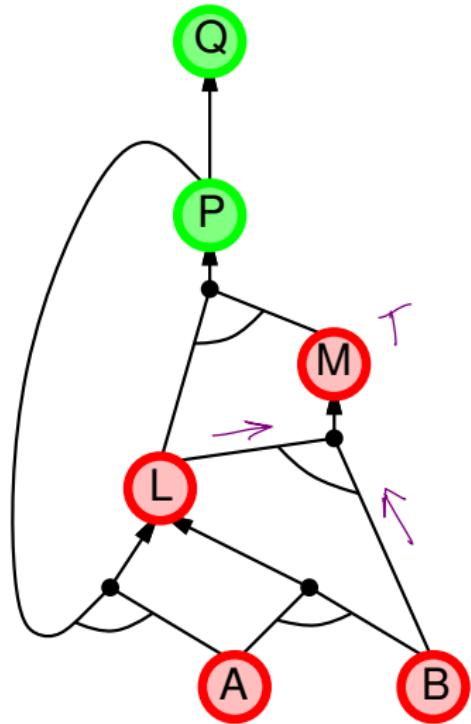
(green circle: frontier;
green filling: explored;
red filling: inferred, known as true)



Backward Chaining: Example (8)

Backward chaining time complexity is also only linear!

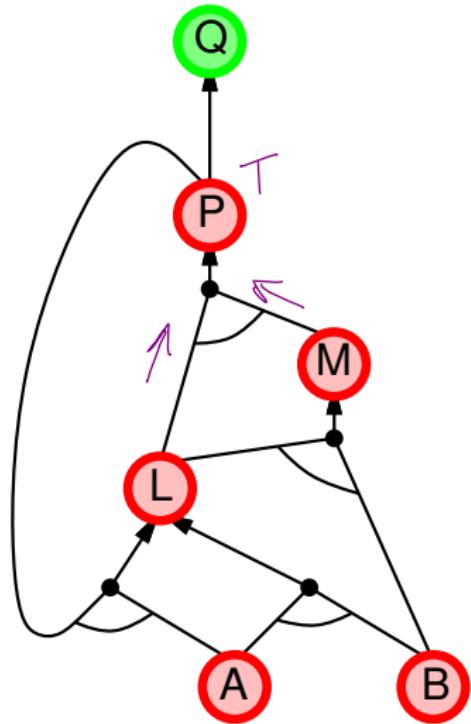
(green circle: frontier;
green filling: explored;
red filling: inferred, known as true)



Backward Chaining: Example (9)

Backward chaining time complexity is also only linear!

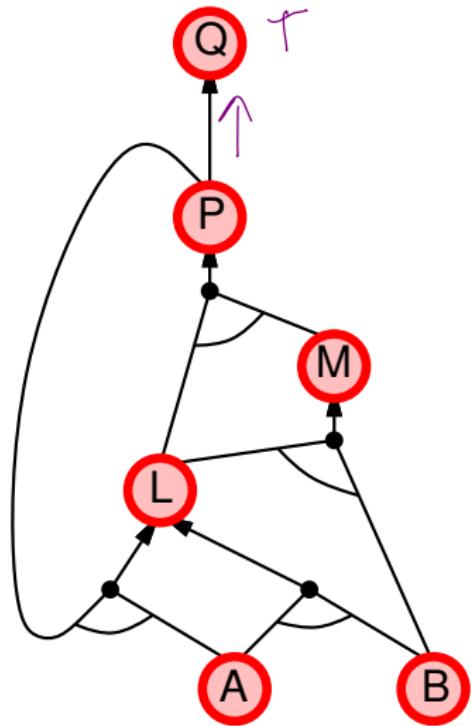
(green circle: frontier;
green filling: explored;
red filling: inferred, known as true)



Backward Chaining: Example (10)

Backward chaining time complexity is also only linear!

(green circle: frontier;
green filling: explored;
red filling: inferred, known as true)



Forward vs. Backward Chaining

Forward chaining

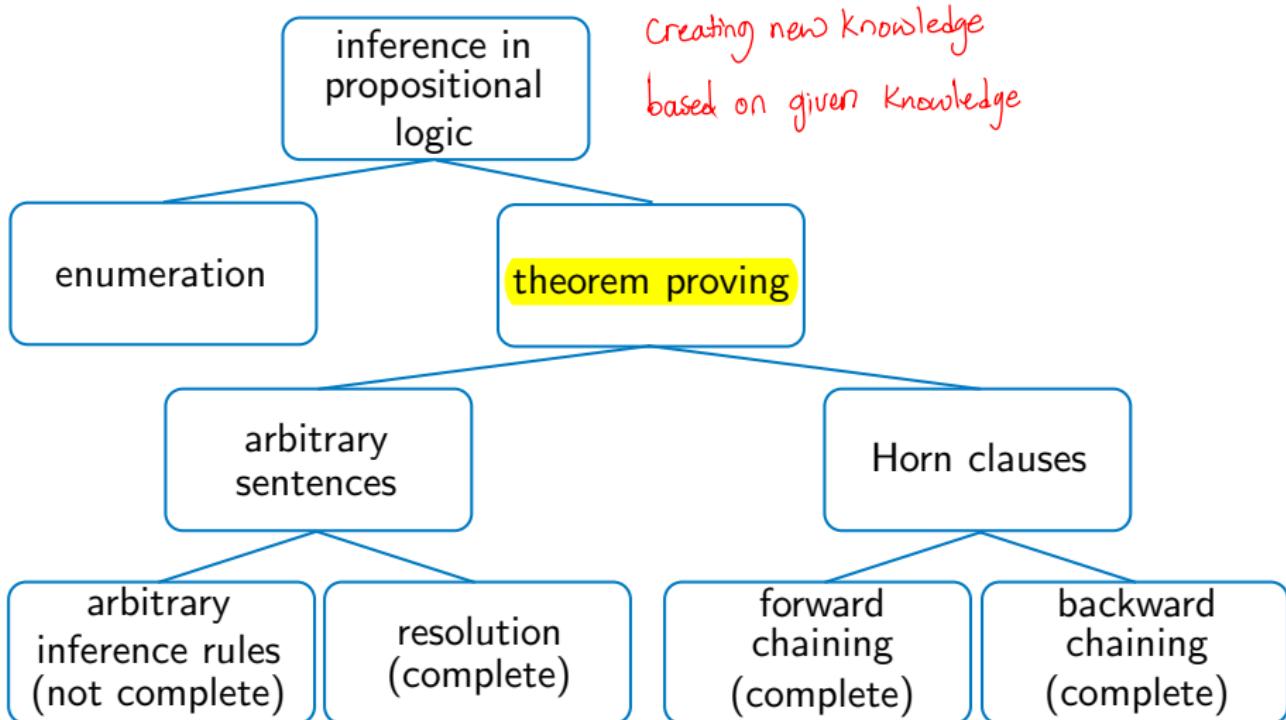
- Forward chaining is **data-driven**, automatic, and unconsciously processing.
exploring unnecessary nodes
- It is popular in e.g., object recognition and routine decisions.
- Forward chaining may do **lots of work** that is irrelevant to the goal.

Backward chaining

- Backward chaining is **goal-driven** and appropriate for problem-solving.
- It is a good choice for problems, such as e.g., Where are my keys?
How do I cook a meal?
- **Computational effort** of backward chaining can be much less than linear in time and space. *"pruning trees"*

Overview of Inference Methods

Summary



Summary

- Intelligent agents need knowledge about the world in order to reach good solutions.
 - Knowledge is contained in agents in the form of **sentences** in a **knowledge representation language** that are stored in a **knowledge base**.
- * A knowledge-based agent is composed of a knowledge base and an inference mechanism, which infers new sentences for decision making.
- The set of possible models for propositional logic is finite, so entailment can be checked by enumerating models.
- * **Inference rules** are patterns of sound inference to find proofs. The **resolution** rule yields a complete inference algorithm for knowledge bases in conjunctive normal form. **Forward and backward chaining** are natural reasoning algorithms for **Horn clauses**.